
Chapter 2

Processes and Threads

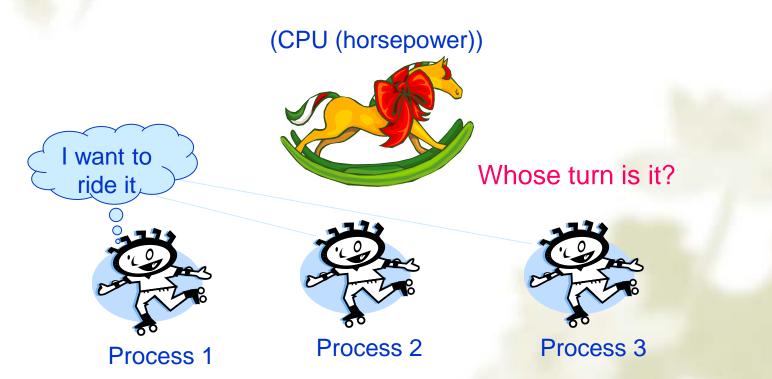
- 2.1 Processes
- 2.2 Threads
- 2.3 Inter-process communication
- 2.4 Classical IPC problems
- 2.5 Scheduling

Content of this lecture

- What is scheduling?
- When to Schedule?
- Basic Scheduling Algorithm
 - Batch systems
 - First-Come First-Served
 - Shortest job first
 - Interactive systems
 - Round-robin
 - Priority scheduling
 - Multi Queue & Multi-level Feedback
 - Guaranteed Scheduling, Lottery Scheduling, and Fair Sharing Scheduling
- Summary

What is scheduling

Deciding which process/thread should occupy the resource (CPU) to run next.



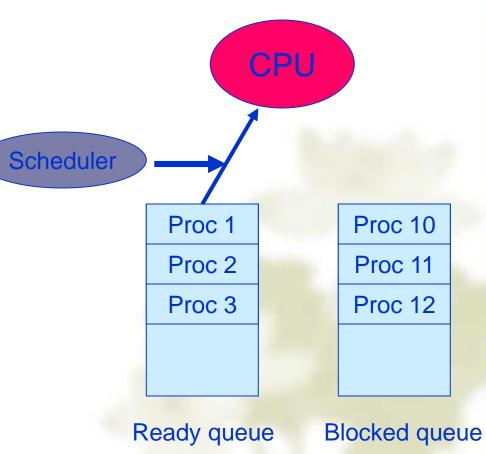
Process Scheduler

Proc1: 20 time units

Proc2: 3 time units

Proc3: 4 time units

Preemptive vs. non-preemptive



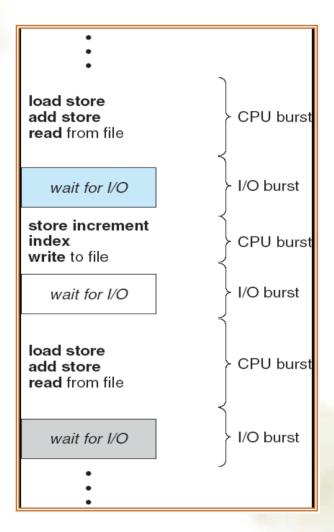
Processes typically consist of

CPU bursts

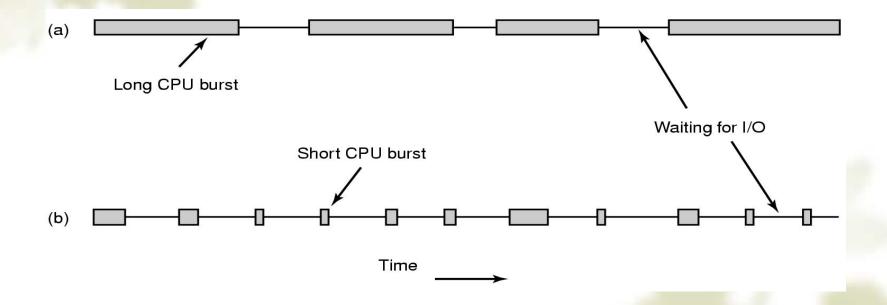
❖A period of time when a process needs the CPU is called a CPU burst.

√I/O bursts

❖A period of time when a process needs I/O is called a I/O burst.



- Duration and frequency of bursts vary greatly from process to process.
 - **CPU-bound Process**
 - ❖Long CPU bursts, infrequent I/O waits.
 - ❖ E.g. Number crunching tasks, image processing.
 - √I/O-bound Process
 - Short CPU bursts, frequent I/O waits.
 - ❖ E.g. A task that processes data from disk, for example, counting the number of lines in a file is likely to be I/O bound.
- As CPU get faster, processes tend to get more I/O bound.



- Bursts of CPU usage alternate with periods of I/O wait
 - a) a CPU-bound process
 - b) an I/O bound process

CPU Scheduling

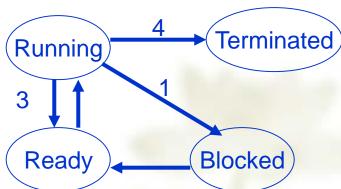
- Problem to solve
 - When (scheduling opportunity)
 when to allocate CPU to process?
 - What (scheduling algorithm)
 what is the principle of allocation?
 - How to allocate CPU? scheduling- process?

When to schedule?

- A new process is created
- The running process exits
- The running process is blocked
- I/O interrupt (some processes will be ready)
- Clock interrupt (every 10 milliseconds)

Preemptive vs. Non-preemptive

- Non-preemptive scheduling
 - The running process keeps the CPU until it voluntarily gives up the CPU
 - process exits
 - switches to blocked state
 - 1and 4 only (no 3)
 - Disadvantage?
- Preemptive scheduling
 - The running process can be interrupted and must release the CPU (can be forced to give up CPU)
 - Preemptive principles?



Categories of Scheduling Algorithms

- Batch System
 - Non-preemptive algorithms
 - Preemptive algorithms with long time periods for each process
- Interactive System
 - Preemption is essential
- Real-Time System
 - Preemption is sometimes not needed

Scheduling Algorithm

Properties of a GOOD Scheduling Algorithm:

- Fair (nobody cries)
- Priority (lady first)
- Efficiency (make best use of equipment)
- Encourage good behavior (good boy/girl)
- Support heavy loads (degrade gracefully)
- Adapt to different environments (interactive, realtime...)

Performance Criteria

- Different Systems, Different Focuses
- For All Systems
 - **←** Fairness
 - No process should suffer starvation
 - Efficiency
 - Keep resources as busy as possible
 - Policy Enforcement
 - Seeing that stated policy is carried out

Performance Criteria

Batch Systems

Throughput

Number of processes that completes in unit time

Turnaround Time (also called elapse time)

Amount of time to execute a particular process from the time its entered

Waiting Time

amount of time process has been waiting in ready queue

Processor Utilization

Percent of time CPU is busy

Performance Criteria

- Interactive Systems
 - Response Time
 - amount of time from when a request was first submitted until first response is produced.
 - Proportionality
 - ❖meet users' expectation
- Real-Time Systems
 - Meeting Deadlines
 - avoid losing data
 - Predictability
 - Same time/cost regardless of load on the system

Single Processor Scheduling Algorithms

- Batch systems
 - ← First Come First Served (FCFS)
 - Shortest Job First
- Interactive Systems
 - Round Robin
 - Priority Scheduling
 - Multi Queue & Multi-level Feedback
 - Guaranteed Scheduling

(1) First Come First Served (FCFS)

- Also called FIFO. Process that requests the CPU FIRST is allocated the CPU FIRST.
- Non-preemptive
- Used in Batch Systems
- Implementation: FIFO queues

 - The scheduler selects from the head of the queue.
- Performance Metric: Average Waiting Time.
- Given Parameters:
 - → Burst Time (in ms), Arrival Time and Order

FCFS Example

Process	Burst Time	Order	Arrival Time
P1	24	1	0
P2	3	2	0
P3	4	3	0

The final schedule:



P1 waiting time: 0

P2 waiting time: 24

P3 waiting time: 27

The average waiting time:

(0+24+27)/3 = 17

FCFS Example (cont.)

Suppose that the processes arrive in the order

$$P_2, P_3, P_1$$

The Gantt chart for the schedule is:



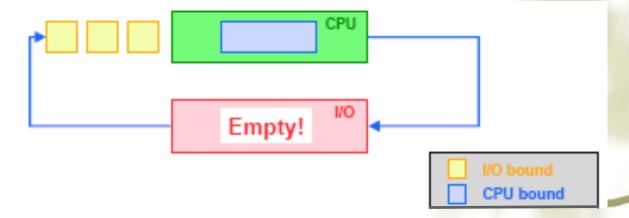
- Waiting time for $P_1 = 7$; $P_2 = 0$; $P_3 = 3$
- Average waiting time: (7 + 0 + 3)/3 = 3.3
- Much better than previous case.
- Convoy effect: short process behind long process

Problems with FCFS

- Non-preemptive
- Not optimal AWT (Average Waiting Time)
- Cannot utilize resources in parallel:
 - Assume 1 process CPU bounded and many I/O bounded processes
 - result: Convoy effect, low CPU and I/O Device utilization
 - ≪Why?

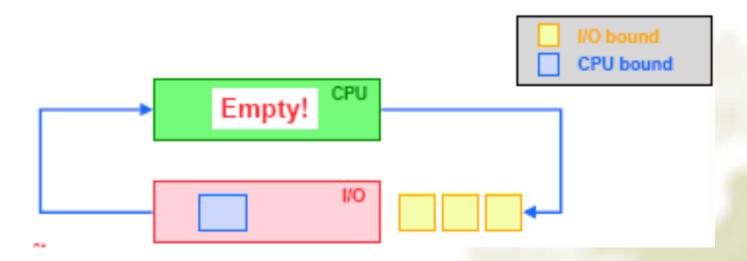
Why Convoy Effects?

- Consider n-1 jobs in system that are I/O bound and 1 job that is CPU bound.
- I/O bound jobs pass quickly through the ready queue and suspend themselves waiting for I/O.
- CPU bound job arrives at head of queue and executes until complete.
- I/O bound jobs rejoin ready queue and wait for CPU bound job to complete.
- I/O devices idle until CPU bound job completes.



Why Convoy Effects?

- When CPU bound job complete, other processes rush to wait on I/O again.
- CPU becomes idle.



(2) Shortest Job First (SJF)

- Schedule the job with the shortest elapse time first
- Scheduling in Batch Systems
- Two types:
 - Non-preemptive
 - Preemptive
- Requirement: the elapse time needs to know in advance
- Optimal if all the jobs are available simultaneously (provable)
 - Gives the best possible AWT (average waiting time)

Non-preemptive SJF: Example

Process	Burst Time	Order	Arrival Time
P1	6	2	0
P2	8	4	0
P3	7	3	0
P4	3	1	0



P4 waiting time: 0

P1 waiting time: 3

P3 waiting time: 9

P2 waiting time: 16

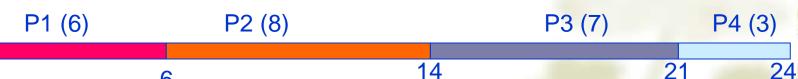
The total time is: 24

The average waiting time (AWT):

(0+3+9+16)/4 = 7

Comparing to FCFS

Process	Burst Time	Order	Arrival Time
P1	6	1	0
P2	8	2	0
P3	7	3	0
P4	3	4	0



P1 waiting time: 0

6

P2 waiting time: 6

P3 waiting time: 14

P4 waiting time: 21

The total time is the same.

The average waiting time (AWT):

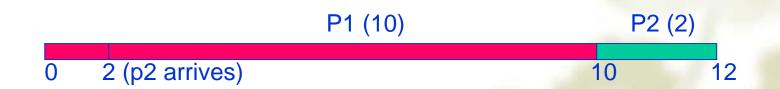
(0+6+14+21)/4 = 10.25

(comparing to 7)

SJF is not always optimal

Is SJF optimal if all the jobs are not available simultaneously?

Process	Burst Time	Order	Arrival Time
P1	10	1	0
P2	2	2	2



P1 waiting time: 0

P2 waiting time: 8

The average waiting time (AWT):

$$(0+8)/2 = 4$$

What if the scheduler waits for 2 time units? (Do it yourself)

Process	Burst Time	Order	Arrival Time
P1	10	2	0
P2	2	1	2



P1 waiting time: 4

P2 waiting time: 0

The average waiting time (AWT):

(0+4)/2 = 2

However: waste 2 time units of CPU

Preemptive SJF

- Also called Shortest Remaining Time First
 - Schedule the job with the shortest remaining time required to complete
- Requirement: the elapse time needs to be known in advance

Preemptive SJF: Same Example

Process	Burst Time	Order	Arrival Time
P1	10	1	0
P2	2	2	2



P1 waiting time: 4-2=2

P2 waiting time: 0

The average waiting time (AWT):

(0+2)/2 = 1

No CPU waste!!!

A Problem with SJF

Starvation

- In some condition, a job is waiting for ever
- Example: SJF
 - Process A with elapse time of 1 hour arrives at time 0
 - ❖But ever 1 minute from time 0, a short process with elapse time of 2 minutes arrive
 - ❖ Result of SJF: A never gets to run

Interactive Scheduling Algorithms

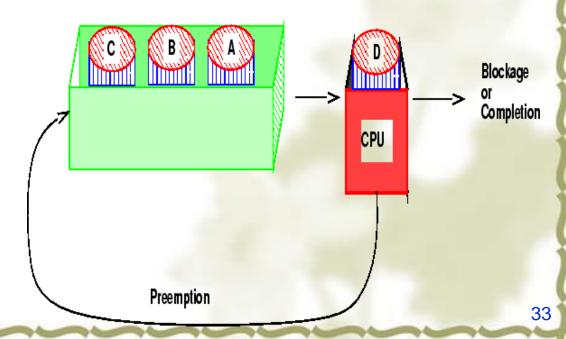
- Usually preemptive
 - Time is sliced into quantum (time intervals)
 - Scheduling decision is also made at the beginning of each quantum
- Performance Criteria
 - Min Response Time
 - best proportionality
- Representative algorithms:
 - Round-robin
 - Priority-based
 - Multi Queue & Multi-level Feedback
 - Guaranteed Scheduling
 - Lottery Scheduling
 - Fair Sharing Scheduling

(3) Round-robin

- One of the oldest, simplest, most commonly used scheduling algorithm
- Select process/thread from ready queue in a round-robin fashion (take turns)

Problem:

- Do not consider priority
- Context switch overhead



Round-robin: Example

Process	Duration	Order	Arrival Time
P1	3	1	0
P2	4	2	0
P3	3	3	0

Suppose time quantum is: 1 unit, P1, P2 & P3 never block



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- P1 waiting time: 4
- P2 waiting time: 6
- P3 waiting time: 6

The average waiting time (AWT):

$$(4+6+6)/3 = 5.33$$

Time Quantum

- Time slice too large
 - FCFS behavior
 - Poor response time
- Time slice too small
 - Too many context switches (overheads)
 - Inefficient CPU utilization
- Heuristic: 70-80% of jobs block within timeslice
- Typical time-slice 10 to 100 ms

(4) Priority Scheduling

- Each job is assigned a priority.
- FCFS within each priority level.
- Select highest priority job over lower ones.
- Rational: higher priority jobs are more mission-critical
 - Example: display a video film in real time vs. send email

Problems:

- May not give the best AWT
- indefinite blocking or starving a process

Set Priority

- Two approaches
 - Static (for system with well known and regular application behaviors)
 - Dynamic (otherwise)
- Priority may be based on:
 - Cost to user
 - Importance of user
 - Process type
 - Requirement to resource

 - Percentage of CPU time used in last X hours.

Priority Scheduling: Example

Process	Duration	Priority	Arrival Time
P1	6	4	0
P2	8	1	0
P3	7	3	0
P4	3	2	0

P2 (8) P4 (3) P3 (7) P1 (6)

0 8 11 18 24

P2 waiting time: 0

P4 waiting time: 8

P3 waiting time: 11

P1 waiting time: 18

The average waiting time (AWT):

(0+8+11+18)/4 = 9.25

(worse than SJF:7)

Priority in Unix

```
yyzhou|csil-linux1|~|[73]% ps -1
   FS UID PID PPID C PRI NI ADDR SZ WCHAN TTY TIME CMD
100 S 14828 2047 2045 0 79 4 - 822 rt_sig pts/l 00:00:00 csh
000 R 14828 23001 2047 0 80 4 - 791 - pts/l 00:00:00 ps
yyzhou|csil-linux1|~|[74]%
yyzhou|csil-linux1|~|[74]%
```

Nobody wants to

Be "nice" in Unix

NICE(1) NICE(1) NTAIME: nice - run a program with modified scheduling priority SYNOPSIS nice [OPTION] [COMMAND [ARG]...] DESCRIPTION Run COMMAND with an adjusted scheduling priority. COMMAND, print the current scheduling priority. ADJUST is 10 by default. Range goes from -20 (highest priority) to 19 (lowest). -ADJIIST increment priority by ADJUST first -n, --adjustment=ADJUST same as -ADJUST --help display this help and exit

14maa 1 95

--version

(5) Multi-Queue Scheduling

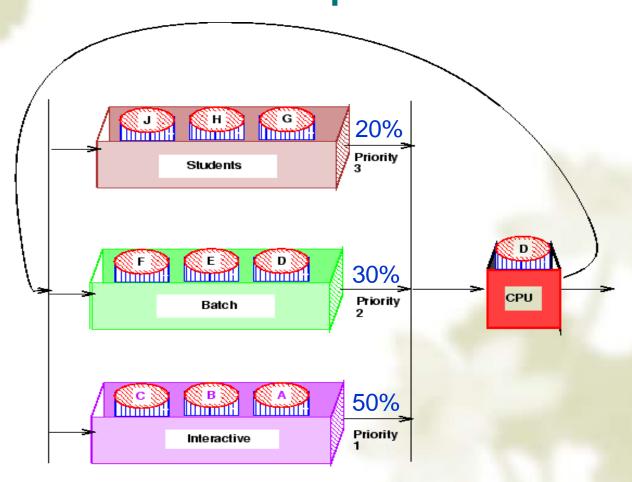
- Hybrid between priority and round-robin
- Used in scenarios where the processes can be classified into groups based on property like process type, CPU time, IO access, memory size, etc.
- Split the Ready Queue in several queues, processes assigned to one queue permanently
- Each queue with its own scheduling algorithm
 - E.g. interactive processes: RR, background processes: FCFS/SRTF

Multi-Queue Scheduling

- Example
 - System processes (highest priority)
 - Interactive programs (Round Robin)

 - Student Processes
- Scheduling between queues
 - Fixed Priorities (Possibility of starvation)
 - ≪ CPU spent on queue

Multi-Queue Scheduling: Example



Real Life Analogy

- Tasks (to-do list) for poor Bob
 - Class 1 priority (highest): tasks given by his boss
 - ❖ Finish the project (50%)
 - Class 2 priority: tasks for his wife
 - ❖Buy a valentine present (30%)
 - Class 3 priority (lowest): Bob's tasks
 - ❖Watch TV (20%)

(6)A Variation: Multi-level Feedback Algorithm

- Multi-Level Queue with priorities
- Processes move between queues
 - Start each process in a high-priority queue; as it finishes each CPU burst, move it to a lower- priority queue.
- Each queue represents jobs with similar CPU usage
- Jobs in a given queue are executed with a given time-slice
- Rational:
 - Once an I/O process completes an I/O request, it should have higher CPU priority.

Multi-level Feedback Algorithm (Details)

- ❖ Example (CTSS): Queue, has time-slice t 2ⁱ
 - If a job in $Queue_i$ doesn't block by end of time-slice, it is moved to $Queue_{i+1}$
 - Lowest priority Queue is FCFS

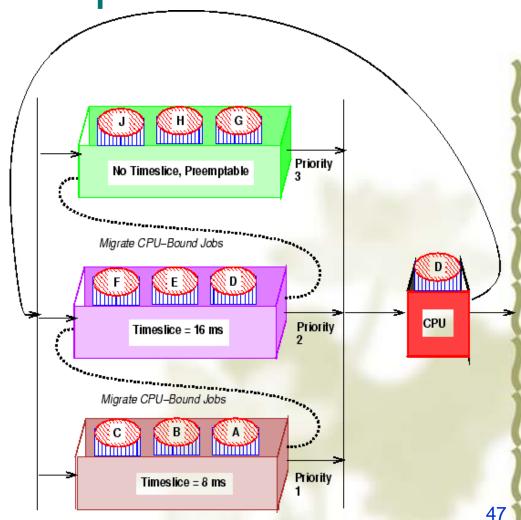
Multi-level Feedback Algorithm: Example

Three Queues

 \triangleleft Q₀: time slice 8ms

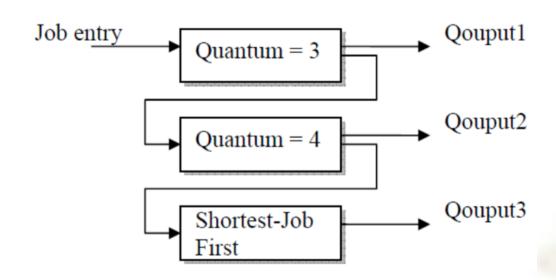
⋄ Q₁: time slice 16ms

⋄ Q₂: FCFS



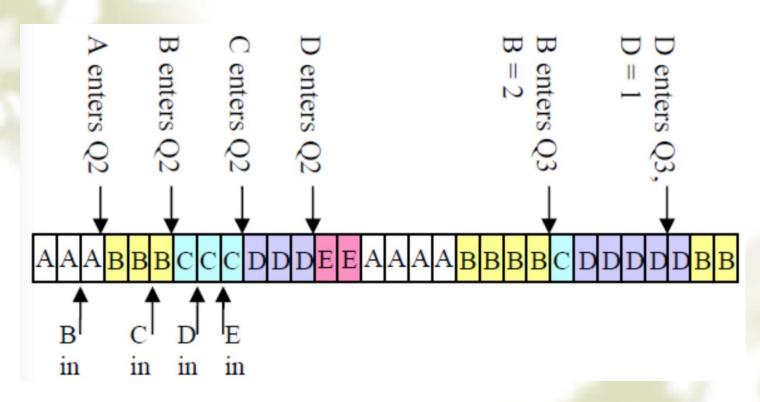
Quiz

Show your schedule with timeline and calculate the average turnaround time when use multi-level feedback queue as below (Please take arrival time into account). Note that the priority of the top 2 queues is based on arrival times.



Process ID	Arrival Time	Burst Time	
А	0	7	
В	2	9	
С	5	4	
D	7	8	
Е	8	2	

Solution



Turnaround time:

A=18, B=30-2=28, C=23-5=18, D=28-7=21, E=14-8=6

Average turnaround time:

$$(18 + 28 + 18 + 21 + 6)/5 = 91/5 = 18.2$$

Review: Scheduling Algorithms

- Batch systems
 - First come first served
 - Shortest job first
- Interactive systems

 - Priority scheduling
 - Multi-Queue & Multi-level feedback

(7) Guaranteed Scheduling (QoS)

- Make real promises to the users about performance and then live up to them.
- Example:
 - with *n* processes running, the scheduler makes sure that each one gets 1/*n* of the CPU cycles.
- Scheduling:
 - compute the ratio of actual CPU time consumed to CPU time entitled
 - Select the one with the lowest ratio

(8) Lottery Scheduling

- More commonly used
- Probability-based
 - Give processes lottery tickets. At scheduling time, a lottery ticket is chosen at random, and the process holding that ticket gets that resource.
- Give more tickets for higher priority processes (approximate Priority), or give short jobs more tickets (approximate SJF)
- Advantages
 - Simple
 - Highly responsive
 - Can support cooperation between processes
 - Easy to support priority and proportion requirement

(9) Fair-Share Scheduling

- Is Round-robin fair?
 - Yes, it is (from process point of view)
 - No, it may be not (from user point view)
- User-based fair share scheduling
 - Each user gets fair share
- Example:
 - Alice has 4 processes: A1, A2, A3, A4

 - Then A1, A2, A3, A4 are entitled only to 50% CPU, while B1 alone is entitled to 50%
 - Show Possible scheduling sequence: A1,B1,A2,B1,A3,B1,A4,B1,.....

Scheduling in Real-Time Systems

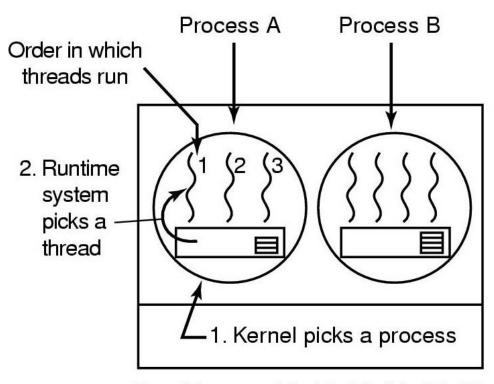
- The scheduler makes real promises to the user in terms of deadlines or CPU utilization.
- Schedulable real-time system
 - - ❖ m periodic events
 - ◆event i occurs within period P_i and requires C_i seconds
 - Then the load can only be handled if

$$\sum_{i=1}^{m} \frac{C_i}{P_i} \le 1$$

User-level Thread Scheduling

Possible Scheduling

- 50-msec quantum
- run 5 msec/CPU burst

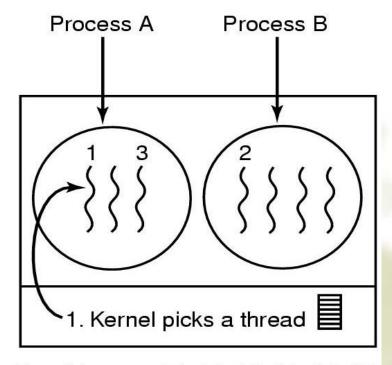


Possible: A1, A2, A3, A1, A2, A3 Not possible: A1, B1, A2, B2, A3, B3

Kernel-level Thread Scheduling

Possible scheduling

- 50-msec quantum
- threads run 5 msec/CPU burst



Possible: A1, A2, A3, A1, A2, A3 Also possible: A1, B1, A2, B2, A3, B3

Summary

- What is scheduling
- Scheduling objectives
- CPU Scheduling
- * FCFS
- Shortest job first (SJF)
- Priority
- Round-robin
- Multi-Queue
- Multi-level Feedback

Scheduling algorithms

- -Guaranteed Scheduling
- -Lottery Scheduling
- -Fair Sharing Scheduling
- Scheduling for
 - -Real-time systems
 - -Threads

Homework

- ***** 45、50
- Reading assignment: 10.3