

Paper Title

September 15, 2015

Abstract

Our abstract.

1 Introduction

Introduction here.

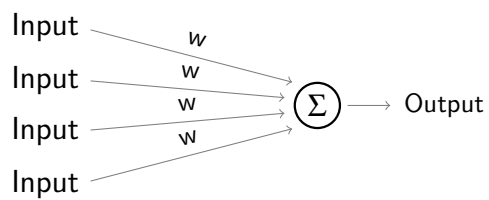


Figure 1: Single Neuron Diagram

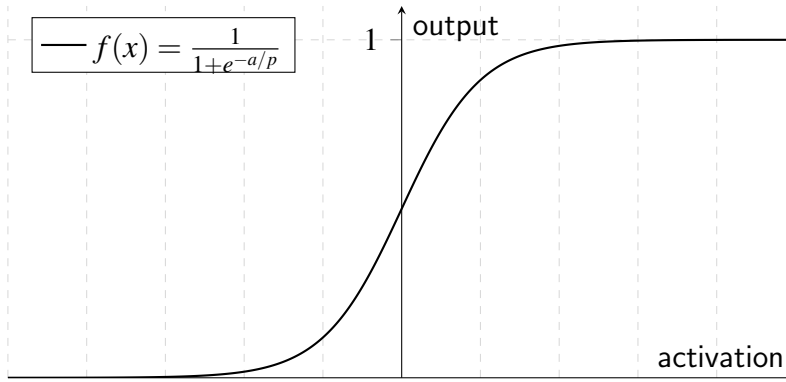


Figure 2: Sigmoid Function Graph

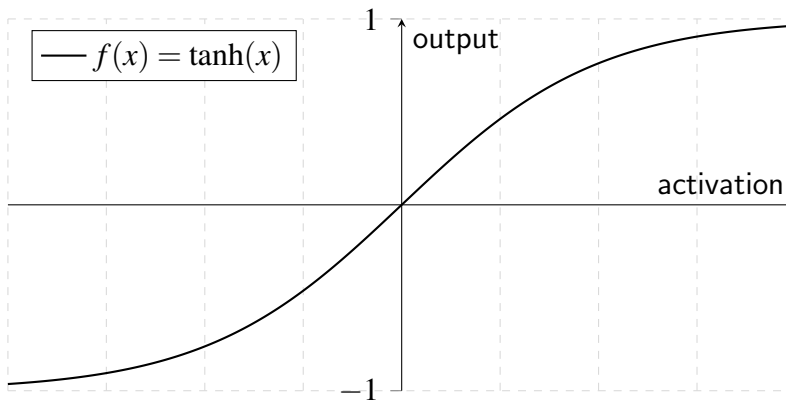


Figure 3: Hyperbolic Tangent Function Graph

2 Neural Network Background

2.1 Neuron Architecture

2.2 Feedforward Neural Network

3 Learning Implementation

4 Simulation

4.1 Sensor Choice and Layout

4.2 Kinematics

5 Results

2

Results, testing, and applications go here.

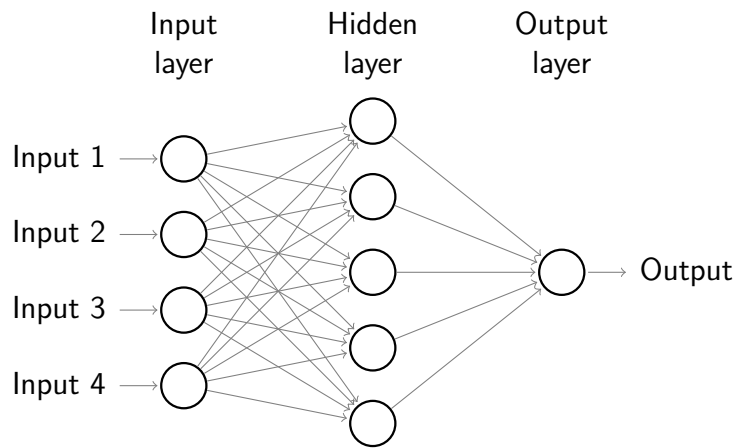


Figure 4: Single Output Feedforward Network

5.1 Training Methods

5.2 Findings

5.3 Further Applications

6 Discussion

7 Conclusion

Restate, discuss further study, improving experimentation, etc.

References

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- Dudek, G., & Jenkin, M. (2000). *Computational principles of mobile robotics*. New York, NY, USA: Cambridge University Press.
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