Answer for 1th question

ANSII We could use an EDGE LOCK PROTOCOL to improve the concurrency of tree based protocol.

Transforming a Graph Protocol to Edge Protocol:

Consider a free T on which transaction Ti operates only through exclusive locks (X-locks), through following protocol

Ti can request a lock on item A only when,

- 1 A is the first item locked by Ti or the parent of A is locked in X-mode by T:
- 2) A is not yet locked by Ti
- 3 A vertex can be unlocked at any time.

The edge lock protocol for the above tree protocol is

Ti can lock edge (A,B) in exclusive (EX-mode) lock only when, ((A,B) is the first edge to be locked by T: or Ti has locked perent of (A,B)

(A,B) has not been previously locked by Ti Ti can lock item A in X-mode if it holds a lock on the incoming edge (9, A) where Q is parent of A.

Example Schedule: Tree Protocol

	T	-	-	A
		T ₂	T ₃	
	Lock-X(A)			(B)
		Lock- X(B)		
		Unlock(B)		
			Lock-X(C)	\bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc
			Urlock(C)	
1	Lock-X(B)			
1	Lock-X(D)			
-	Lock-X(c)			
	Lock-X(F)	1		
	Unlock(F)			
	+		Lock-X(F)	
		ſ	Unlock(F)	
	Unlock(c)			
	Unlock(D)			
1	Unlock(B)			

Transaction T₁ needs to work with only D and F. For that purpose, it not only needs to lock D, F but also B, C as per tree protocol. But B, C have been locked by T₂, T₃ respectively. Hence T₁ has to wait for B, C though it doesn't necessarily need them. This increases the waiting time and hence decreases concurrency. This drawback of Tree protocol is overcome in Edge Lock Protocol.

Example Schedule: Edge Lock Protocol						
Τ	T ₂	T3	= (0,A)			
EX(O,A)	EX(A,B)		(A,C)			
X(A)	X(B) UE(A,B)	EX(A,C) X(C)	(C,F) (B,E) (C,F) (C,F)			
EX(A,B) EX(B,D) X(D) EX(A,C)		UE(A,C)				
EX(C ₁ F) X(F) UE(C ₁ F) U(F)		X(F) U(F)	X → exclusive lock EX → edge exclusive lock U → unlock UE → unlock edge			
U(A) U(A) U(O,A)	V(B)	J(C)				

In this profocol, To doesn't require to lock B, C to work with D, F. The constraints are actually on Edges (A,B) and (B,D) in case of D; (A,C) and (C,F) in case of F. Notice that, no matter how long T2 locks B and T3 locks C, they release the locks on (A,B) and (A,C) edges just in time for T1 to take over.

The edges are basically acting like dummy data items, here.

Since, T1, T2, T3 can be performed without any dependence, concurrency has improved.

This is the strategy I propose to improve the concurrency degree of tree based protocol.

Ans 13

Answer for 1st question in EndTermQuiz

Justification in quiz was brief. This is more detailed justification.

Average Time needed to find the block

= Access Time of Block Transfer Time

Access Time = Seek Time + Rotational Latercy Time

Given, Seek Time = 5m8

Rotational Latercy Time = Time taken to position head at sight sector

= Time required to traverse half of track.

Given, Speed of rotation of disk = 10,000 rotations per minute

... Time for half revolution = $\frac{1}{2}$ minute 10,000

 $= \frac{1}{20000} \times 8000 = 3m8$

.. Rotational Latercy Time = 3ms

Block Transfer Time

- = Time for transferring block of data
 - = Time to transfer 2 sectors of data

Time taken for 1 rotation = $\frac{1}{10,000}$ minutes = $\frac{60}{10,000}$ 8

Time taken for rotation $7 = \frac{60}{10000}$ 8 through 120 sectors $J = \frac{60}{10000}$

- Time taken for rotation $\frac{1}{10,000}$ = 0.1 ms through 2 sectors $\int \frac{1}{10,000}$ = 0.1 ms
- =) Block Transfer Time = 0.1 ms

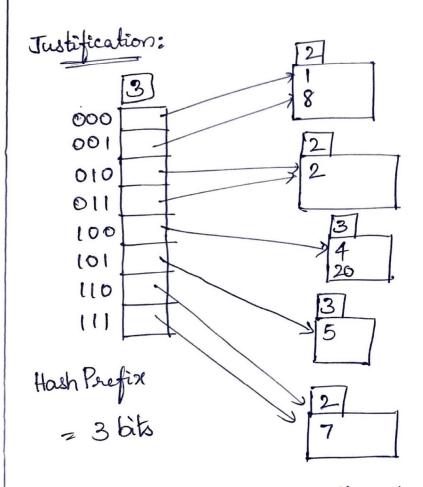
Hence, Average Time needed to find a block given the block address is 5+3+0.1 ms = 18.1 ms

which is (38 and < 10) ms (B)

Ans 5:

Answer for 5th question in EndTermQuiz

Justification given in Quiz Schematic attached along with 11th question



These are the buckets after the final insertion.

: There are 5 buckets — option (E)