## **CS564 ML**

# **Assignment-3**

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#### In this assignment, the following has been done:

**Implementation of a HMM model for PoS tagging on the Brown dataset** using PoS tags as Hidden States and Tokens/Words as the observed variable.

**Implementation of Viterbi algorithm** for the Decoding Problem and to obtain the POS for the test data. We also report the f1 score, the precision and recall for all the POS tags.

### **Code for Emission Probabilities**

### **Code for Transition Probabilities**

```
def create_transition_prob(data_seq, states):
                                                                                                               def create_emission_prob(data_obs, data_seq, states, corpus):
    transit_prob = {}
                                                                                                                   emiss_prob = {}
                                                                                                                   for state in states.keys():
     for row in states.keys():
                                                                                                                       emiss_prob[state] = {}
for obs in corpus.keys():
    emiss_prob[state][obs] = 0
         transit_prob[row] = {}
         for col in states.keys():
              transit_prob[row][col] = 0
                                                                                                                   for t in range(len(data_seq)):
     for sample_seq in data_seq:
                                                                                                                       for w in range(len(data_seq[t])):
    emiss_prob[data_seq[t][w]][data_obs[t][w]] += 1
         for i in range(len(sample_seq)-1):
             transit_prob[sample_seq[i]][sample_seq[i+1]] += 1
                                                                                                                   for state in states.keys():
   for obs in corpus.keys():
     for row in states.keys():
                                                                                                                           emiss_prob[state][obs] = (emiss_prob[state][obs]+1)/(states[state]+len(corpus))
         for col in states.keys()
             transit_prob[row][col] = (transit_prob[row][col]+1)/(states[row]+len(states))
                                                                                                                   return emiss_prob
    return transit_prob
```

#### Precision, Recall and F1 Score for each Tag:

	Precision	Recall	F1 Score
PRON	0.74056072	0.6679715	0.70239565
VERB	0.94985435	0.56122449	0.70556414
DET	0.98251266	0.59026818	0.73747841
NOUN	0.97167022	0.65400984	0.78180437
•	0.90753425	0.6339239	0.74644602
ADJ	0.87960856	0.51273547	0.64783775
ADP	0.98903344	0.63594884	0.77413111
PRT	0.94654641	0.78521898	0.85836824
ADV	0.90529032	0.62609316	0.74024056
NUM	0.92633606	0.61215399	0.73716475
CONJ	0.99560117	0.48258706	0.6500718
Х	0.00273186	0.8220339	0.00544561

## **Overall Accuracy**:

Bigram Model for HMM	60%	<u>Conclusion</u> : The <u>Trigram model performs better</u> than the Bigram HMM model for PoS tagging, because the transition
Trigram Model for HMM	90%	probabilities are calculated for more words.