

1 Kurz (2018) SSM with lagged states

SSM

Kurz's SSM is:

$$\text{Observation : } Z_t = D_1 X_t + D_2 X_{t-1} + R \varepsilon_t \quad (1a) \quad \text{ssm1}$$

$$\text{State : } X_t = A X_{t-1} + C \varepsilon_t, \quad (1b) \quad \text{ssm2}$$

and $\varepsilon_t \sim MN(0, I_m)$, where R and C are covariance matrices.

1.1 LW (2003)

$$\alpha(L) \tilde{y}_t = \alpha_r(L)(r_t - r_t^*) + \sigma_1 \varepsilon_{1t} \quad (2) \quad \text{lw1}$$

$$B(L) \pi_t = b_l(\pi_t^l - \pi_t) + b_o(\pi_{t-1}^o - \pi_{t-1}) + b_y(y_{t-1} - y_{t-1}^*) + \sigma_2 \varepsilon_{2t} \quad (3) \quad \text{lw2}$$

$$\Delta z_t = \sigma_3 \varepsilon_{3t} \quad (4) \quad \text{lw3}$$

$$\Delta y_t^* = g_{t-1} + \sigma_4 \varepsilon_{4t} \quad (5) \quad \text{lw4}$$

$$\Delta g_t = \sigma_5 \varepsilon_{5t} \quad (6) \quad \text{lw5}$$

$$r_t^* = c g_t + z_t \quad (7) \quad \text{lw6}$$

where $\tilde{y}_t = (y_t - y_t^*)$.

Express LW model in SSF with all observables in Z_t and remaining latent states in the state vector X_t , where the observables Z_t are:

$$Z_{1t} = y_t - \alpha_1 y_{t-1} - \alpha_2 y_{t-2} + \frac{a_r}{2}(r_{t-1} + r_{t-2})$$

$$Z_{2t} = B(L) \pi_t - b_l(\pi_t^l - \pi_t) - b_o(\pi_{t-1}^o - \pi_{t-1}) - b_y y_{t-1}$$

Then the measurement equations is:

$$Z_{1t} = y_t^* - \alpha_1 y_{t-1}^* - \alpha_2 y_{t-2}^* - \frac{a_r}{2}(r_{t-1}^* + r_{t-2}^*) + \sigma_1 \varepsilon_{1t}, \quad (8) \quad \text{z1}$$

$$Z_{2t} = b_y y_{t-1}^* + \sigma_2 \varepsilon_{2t} \quad (9) \quad \text{z2}$$

The state equation is:

$$\Delta y_t^* = g_{t-1} + \sigma_4 \varepsilon_{4t} \quad (10) \quad \text{x1}$$

$$\Delta g_t = \sigma_5 \varepsilon_{5t} \quad (11) \quad \text{x2}$$

$$\Delta r_t^* = c \sigma_5 \varepsilon_{5t} + \sigma_3 \varepsilon_{3t}. \quad (12) \quad \text{x3}$$

and state vector is $X_t = \begin{bmatrix} y_t^* & y_{t-1}^* & g_t & r_t^* & r_{t-1}^* & \varepsilon_t & \varepsilon_{2t} & \varepsilon_{3t} & \varepsilon_{4t} & \varepsilon_{5t} \end{bmatrix}'$.

Written out, the full SSM is:

$$\underbrace{\begin{bmatrix} Z_{1t} \\ Z_{2t} \end{bmatrix}}_{Z_t} = \underbrace{\begin{bmatrix} 1 & -\alpha_1 & 0 & 0 & -\frac{a_r}{2} & \sigma_1 & 0 & 0 & 0 & 0 \\ 0 & b_y & 0 & 0 & 0 & 0 & \sigma_2 & 0 & 0 & 0 \end{bmatrix}}_{D_1} \underbrace{\begin{bmatrix} y_t^* \\ y_{t-1}^* \\ g_t \\ r_t^* \\ r_{t-1}^* \\ \varepsilon_{1t} \\ \varepsilon_{2t} \\ \varepsilon_{3t} \\ \varepsilon_{4t} \\ \varepsilon_{5t} \end{bmatrix}}_{X_t} + \underbrace{\begin{bmatrix} 0 & -\alpha_2 & 0 & 0 & -\frac{a_r}{2} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}}_{D_2} \underbrace{\begin{bmatrix} y_{t-1}^* \\ y_{t-2}^* \\ g_{t-1} \\ r_{t-1}^* \\ r_{t-2}^* \\ \varepsilon_{1t-1} \\ \varepsilon_{2t-1} \\ \varepsilon_{3t-1} \\ \varepsilon_{4t-1} \\ \varepsilon_{5t-1} \end{bmatrix}}_{X_{t-1}} + \underbrace{\begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}}_R \underbrace{\begin{bmatrix} \varepsilon_{1t} \\ \varepsilon_{2t} \\ \varepsilon_{3t} \\ \varepsilon_{4t} \\ \varepsilon_{5t} \end{bmatrix}}_{\varepsilon_t}$$

$$\underbrace{\begin{bmatrix} y_t^* \\ y_{t-1}^* \\ g_t \\ r_t^* \\ r_{t-1}^* \\ \varepsilon_{1t} \\ \varepsilon_{2t} \\ \varepsilon_{3t} \\ \varepsilon_{4t} \\ \varepsilon_{5t} \end{bmatrix}}_{X_t} = \underbrace{\begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}}_A \underbrace{\begin{bmatrix} y_{t-1}^* \\ y_{t-2}^* \\ g_{t-1} \\ r_{t-1}^* \\ r_{t-2}^* \\ \varepsilon_{1t-1} \\ \varepsilon_{2t-1} \\ \varepsilon_{3t-1} \\ \varepsilon_{4t-1} \\ \varepsilon_{5t-1} \end{bmatrix}}_{X_{t-1}} + \underbrace{\begin{bmatrix} 0 & 0 & 0 & \sigma_4 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \sigma_5 \\ 0 & 0 & \sigma_3 & 0 & c\sigma_5 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}}_C \underbrace{\begin{bmatrix} \varepsilon_{1t} \\ \varepsilon_{2t} \\ \varepsilon_{3t} \\ \varepsilon_{4t} \\ \varepsilon_{5t} \end{bmatrix}}_{\varepsilon_t}$$

The parameter values from LW(2003) are:

$$\sigma_1 = 0.387, \sigma_2 = 0.731, \sigma_3 = 0.323, \sigma_4 = 0.605, \sigma_5 = 0.102$$

$$\alpha_1 = 1.51, \alpha_2 = -0.57, b_y = 0.043, \alpha_r = -0.098, c = 1.068.$$