

Probability and non-probability sampling

Matthew J. Salganik
Department of Sociology
Princeton University

Summer Institute in Computational Social Science
June 21, 2018

The Summer Institute in Computational Social Science is supported by grants from the Russell Sage Foundation and the Alfred P. Sloan Foundation.



	Sampling	Interviews	Data environment
1st era	Area probability	Face-to-face	Stand-alone
2nd era	Random digital dial probability	Telephone	Stand-alone
3rd era	Non-probability	Computer-administered	Linked

Probability Samples

$$P(u_i) = \frac{p_i}{(N-1) \cdots (N-n+1)} \binom{N-1}{n-1} (n-1)! \\ + \sum_{j \neq i}^N \frac{p_j}{(N-1) \cdots (N-n+1)} \binom{N-1}{n-1} (n-1)! \frac{n-1}{N-1},$$

which upon simplification becomes

$$(19) \quad P(u_i) = \frac{N-n}{N-1} p_i + \frac{n-1}{N-1}, \quad (i = 1, 2, \dots, N).$$

Similarly, it may be shown that for this case

$$(20) \quad P(u_i u_j) = \frac{n-1}{N-1} \left[\frac{N-n}{N-2} (p_i + p_j) + \frac{n-2}{N-2} \right], \\ (i \neq j: i, j = 1, 2, \dots, N).$$

Non-Probability Samples



Probability Samples

unknown sampling process
weighting based on unverifiable assumptions

Non-Probability Samples

unknown sampling process
weighting based on unverifiable assumptions

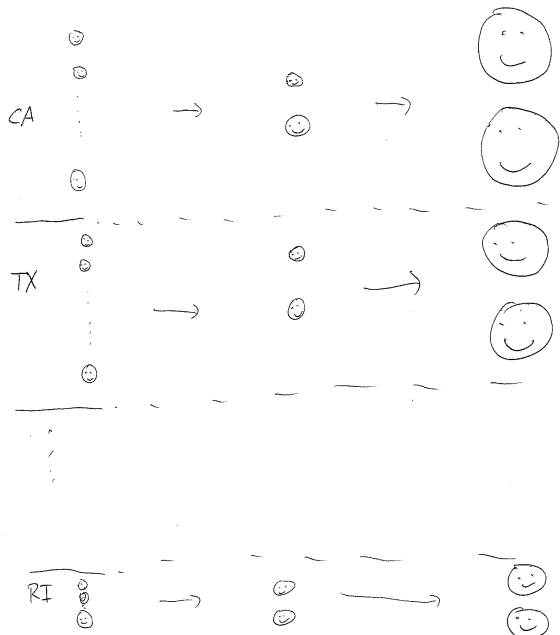
- ▶ Probability sample (roughly): every unit from a frame population has a known and non-zero probability of inclusion

- ▶ Probability sample (roughly): every unit from a frame population has a known and non-zero probability of inclusion
- ▶ Not all probability samples look like miniature versions of the population

- ▶ Probability sample (roughly): every unit from a frame population has a known and non-zero probability of inclusion
- ▶ Not all probability samples look like miniature versions of the population
- ▶ But, with appropriate weighting, probability samples can yield unbiased estimates of the frame population

Main insight from probability samples:

- ▶ How you collect your data impacts how you make inference
- ▶ Focus on properties of estimators not properties samples



$$\hat{y} = \frac{\sum_{i \in s} y_i / \pi_i}{N}$$

where π_i is person i 's probability of inclusion

Sometimes called:

- ▶ Horvitz-Thompson estimator
- ▶ π estimator

Inference from probability samples in theory

respondents } estimates
known information about sampling }

Inference from probability samples in theory

respondents } estimates
known information about sampling }

Inference from probability samples in practice

respondents } estimates
estimated information about sampling }
auxiliary information + assumptions }

Inference from probability samples in theory

$$\left. \begin{array}{l} \text{respondents} \\ \text{known information about sampling} \end{array} \right\} \text{estimates}$$

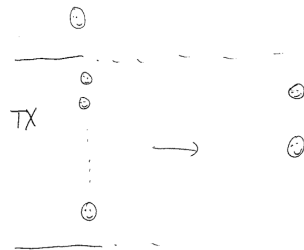
Inference from probability samples in practice

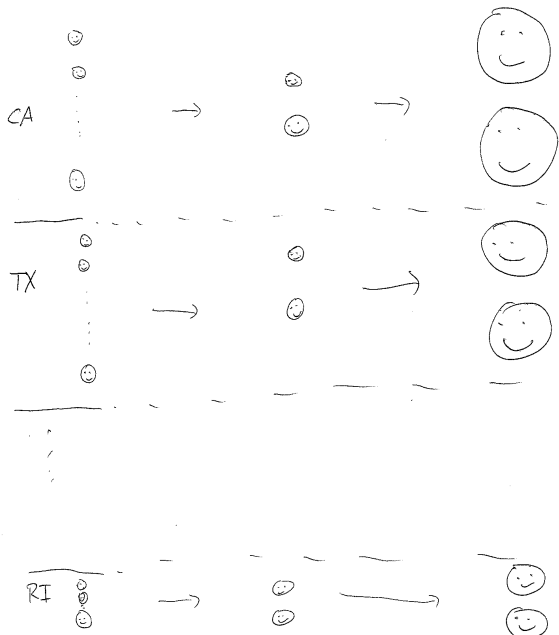
$$\left. \begin{array}{l} \text{respondents} \\ \underbrace{\text{estimated information about sampling}}_{\text{auxiliary information} + \text{assumptions}} \end{array} \right\} \text{estimates}$$

Inference from non-probability samples

$$\left. \begin{array}{l} \text{respondents} \\ \underbrace{\text{estimated information about sampling}}_{\text{auxiliary information} + \text{assumptions}} \end{array} \right\} \text{estimates}$$





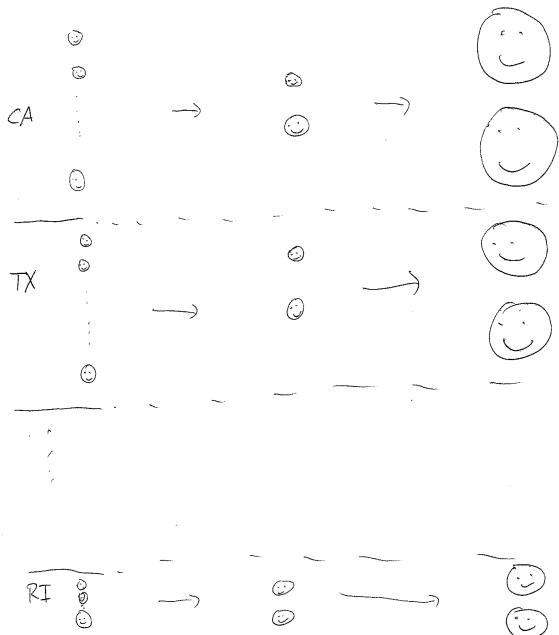


$$\hat{y} = \frac{\sum_{i \in s} y_i / \hat{\pi}_i}{N}$$

where $\hat{\pi}_i = \frac{n_g}{N_g} \quad \forall \quad i \in g$ (estimated probability of inclusion)

Requires:

- ▶ auxiliary information (N_g)
- ▶ ability to place respondents in groups
- ▶ assumptions



- ▶ Key to many adjustment methods is to use external information

- ▶ Key to many adjustment methods is to use external information
- ▶ If external information is incorrect or used improperly then you can make things worse (but it usually seems to make things better)

Imagine that you want to estimate the average height of Duke students.

- ▶ Assume 50% are male and 50% are female
- ▶ You stand outside the Brodhead Center and recruit 60 Duke students
- ▶ Males ($n=20$): Average height: 180cm
- ▶ Females ($n=40$): Average height: 170cm

What is your estimate of the average height? (think-pair-share)

► sample mean = 173.3cm ($\frac{180*20+170*40}{20+40}$)

- ▶ sample mean = 173.3cm ($\frac{180*20+170*40}{20+40}$)
- ▶ weighted estimate = 175cm ($180 * 0.5 + 170 * 0.5$)

- ▶ sample mean = 173.3cm ($\frac{180*20+170*40}{20+40}$)
- ▶ weighted estimate = 175cm ($180 * 0.5 + 170 * 0.5$)

How could this go wrong?

Forecasting elections with non-representative polls

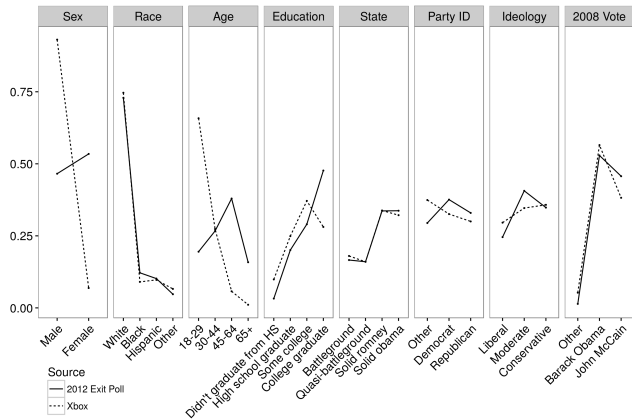
Wei Wang^{a,*}, David Rothschild^b, Sharad Goel^b, Andrew Gelman^{a,c}

^a *Department of Statistics, Columbia University, New York, NY, USA*

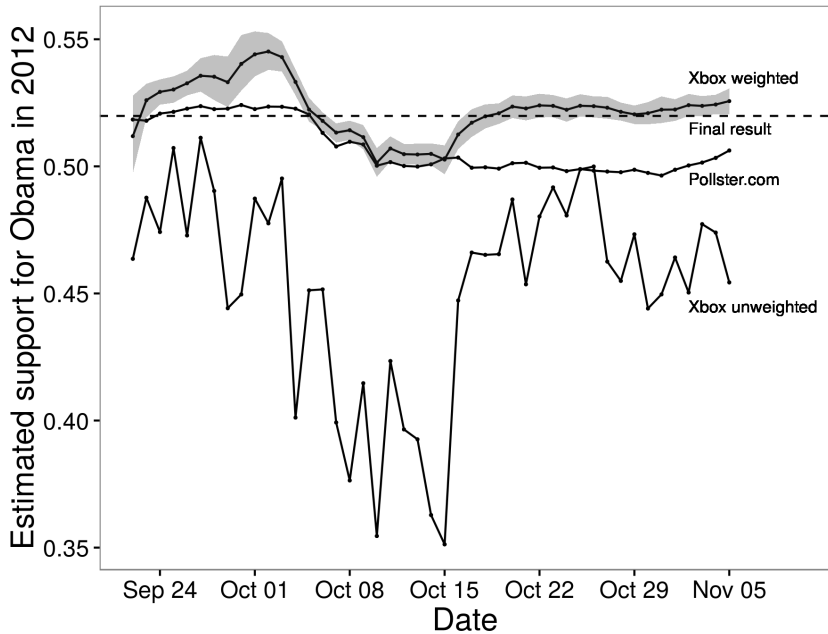
^b *Microsoft Research, New York, NY, USA*

^c *Department of Political Science, Columbia University, New York, NY, USA*





- ▶ about 750,000 interviews
- ▶ about 350,000 unique respondents



Statistical Modeling, Causal Inference, and Social Science

[HOME](#)[BOOKS](#)[BLOGROLL](#)[SPONSORS](#)[« Scientific communication by press release](#)[Nate Silver's website »](#)

President of American Association of Buggy-Whip Manufacturers takes a strong stand against internal combustion engine, argues that the so-called “automobile” has “little grounding in theory” and that “results can vary widely based on the particular fuel that is used”

Posted by [Andrew](#) on 6 August 2014, 2:45 pm



<http://andrewgelman.com/2014/08/06/president-american-association-buggy-whip-manufacturers-takes-strong-stand-internal-combustion-engine-argues-called-automobile-little-grounding-theory/>

Online, Opt-in Surveys: Fast and Cheap, but are they Accurate?

Sharad Goel
Stanford University
scgoel@stanford.edu

Adam Obeng
Columbia University
adam.obeng@columbia.edu

David Rothschild
Microsoft Research
davidmr@microsoft.com

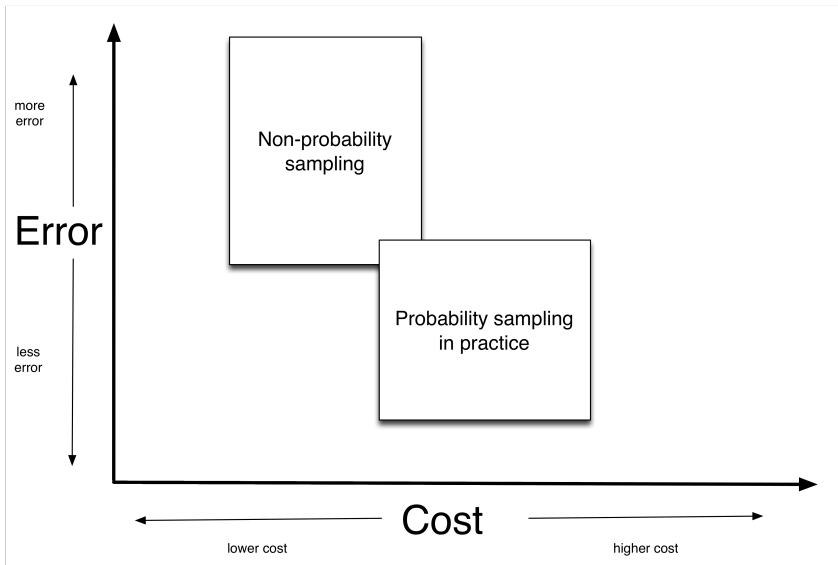
- ▶ Mr. P. is just one of the many ways to post-stratify non-probability samples

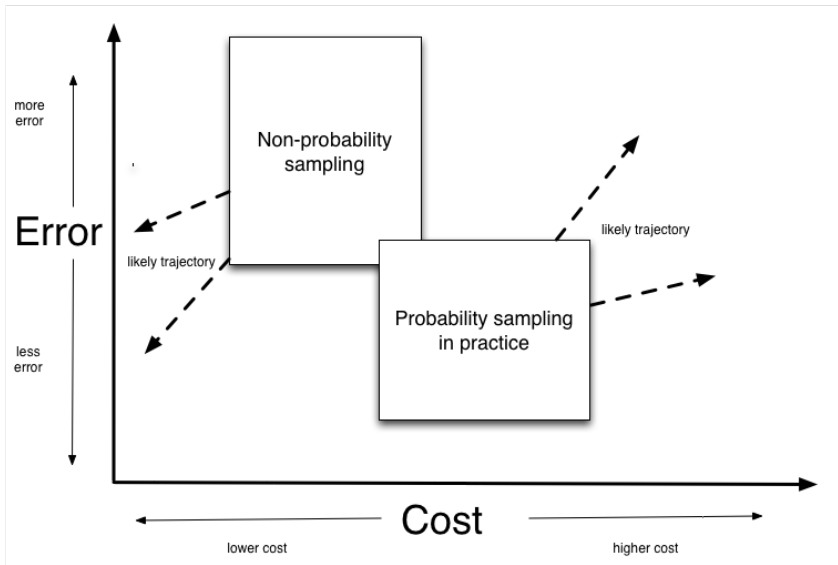
- ▶ Mr. P. is just one of the many ways to post-stratify non-probability samples
- ▶ the performance of Mr. P. (and related methods) is an empirical question

- ▶ Mr. P. is just one of the many ways to post-stratify non-probability samples
- ▶ the performance of Mr. P. (and related methods) is an empirical question
- ▶ related methods can be applied to big data and experiments

- ▶ Mr. P. is just one of the many ways to post-stratify non-probability samples
- ▶ the performance of Mr. P. (and related methods) is an empirical question
- ▶ related methods can be applied to big data and experiments
- ▶ there are also non-probability sampling methods that focus on sampling rather than weighting (e.g., quota-sampling, sample matching)

- ▶ Mr. P. is just one of the many ways to post-stratify non-probability samples
- ▶ the performance of Mr. P. (and related methods) is an empirical question
- ▶ related methods can be applied to big data and experiments
- ▶ there are also non-probability sampling methods that focus on sampling rather than weighting (e.g., quota-sampling, sample matching)
- ▶ we should not let what happened in 1948 prevent us from trying new things today





Wrap-up:

- ▶ Samples don't need to look like mini-populations

Wrap-up:

- ▶ Samples don't need to look like mini-populations
- ▶ Key to making good estimates is for estimation process to account for the sampling process

Wrap-up:

- ▶ Samples don't need to look like mini-populations
- ▶ Key to making good estimates is for estimation process to account for the sampling process
- ▶ There is not a bright-line difference between probability sampling in practice and non-probability sampling

Wrap-up:

- ▶ Samples don't need to look like mini-populations
- ▶ Key to making good estimates is for estimation process to account for the sampling process
- ▶ There is not a bright-line difference between probability sampling in practice and non-probability sampling
- ▶ To learn more: Lohr (2009) or Sandal et al (2013)