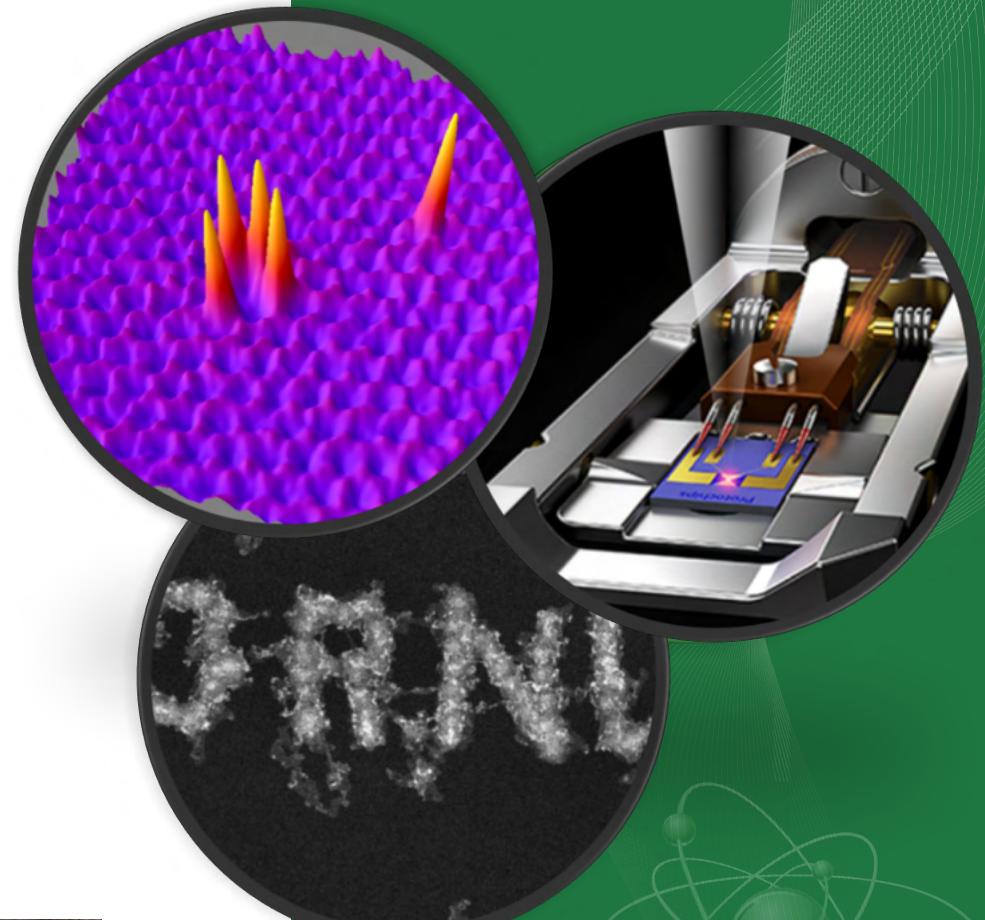


Machine Learning for Scanning Probe and Electron Microscopy for Materials Discovery

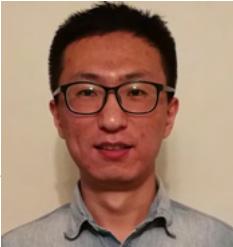
Sergei V. Kalinin

The Center for Nanophase Materials Sciences (CNMS),
Oak Ridge National Laboratory

January 24, 2022



Mahshid
Ahmadi



Yongtao Liu



Rama
Vasudevan



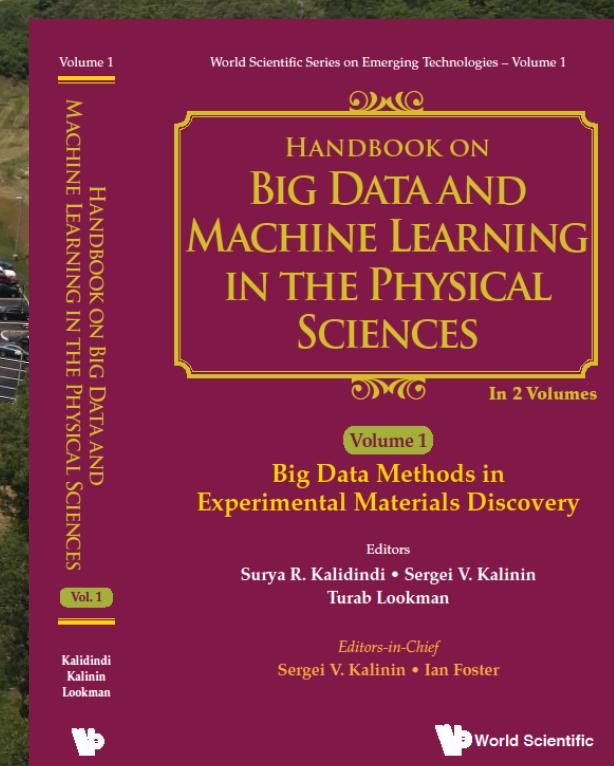
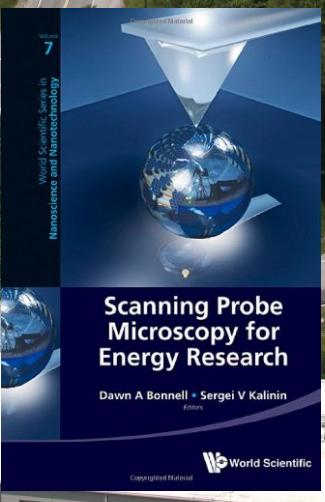
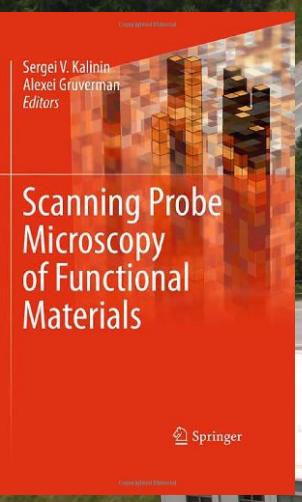
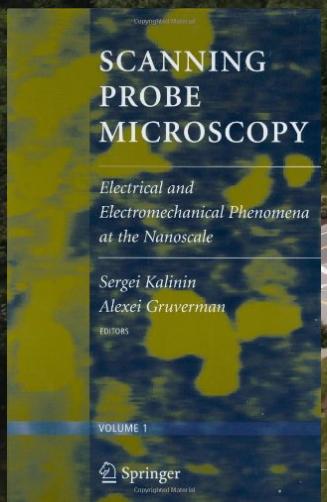
Maxim
Ziatdinov



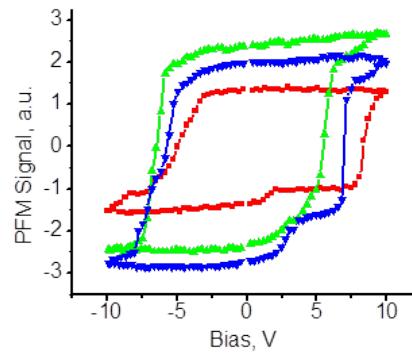
Kyle Kelley



Ondrej
Dyck



Multidimensional SPM modes



We realized we
are doing big
data

- What do we learn from the data?
- How much can we believe in results?
- Can we perform experiments better?

Physics perspective:

1. Local stimulus: spectroscopic (3D) SPM modes
2. Phase transitions are hysteretic: First Order Reversal Curves
3. Phase transitions can be rate-controlled

SPM Perspective:

4. SPM requires resonance enhancement

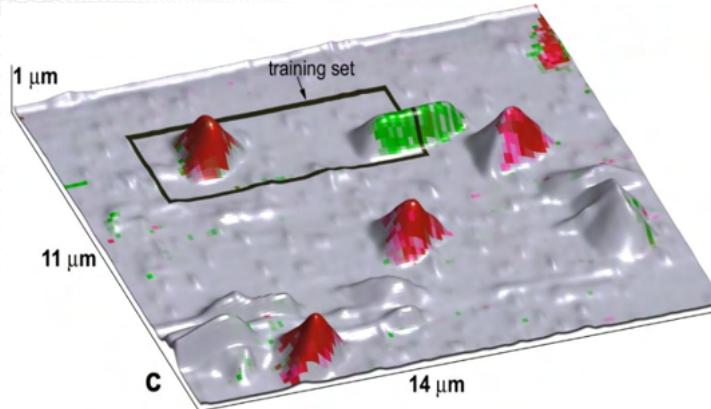
Instrumental limit: photodetector bandwidth (~ 10 MHz) x DAQ performance (32 Bit)

- **Single frequency/heterodyne:** compression to ~ 1 kHz
- **Band excitation:** 10^2 bins at ~ 1 kHz = 100 kHz
- **G-mode:** full streaming at ~ 10 MHz

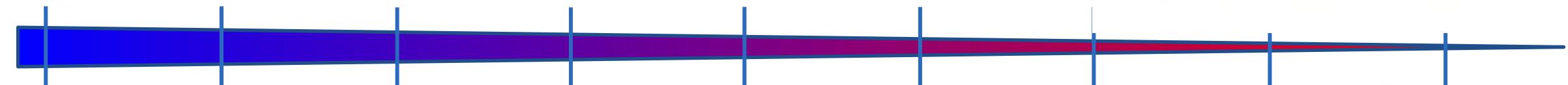
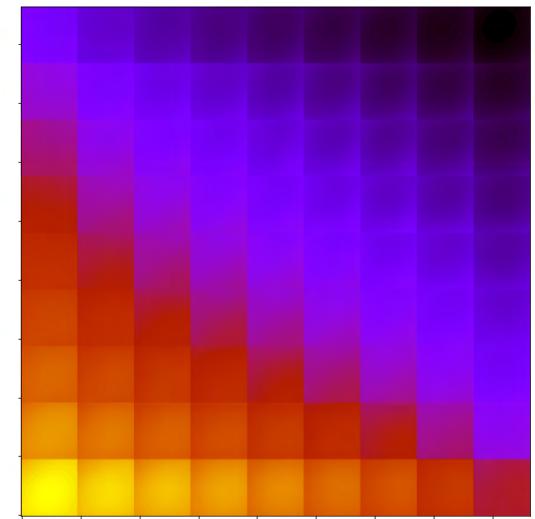
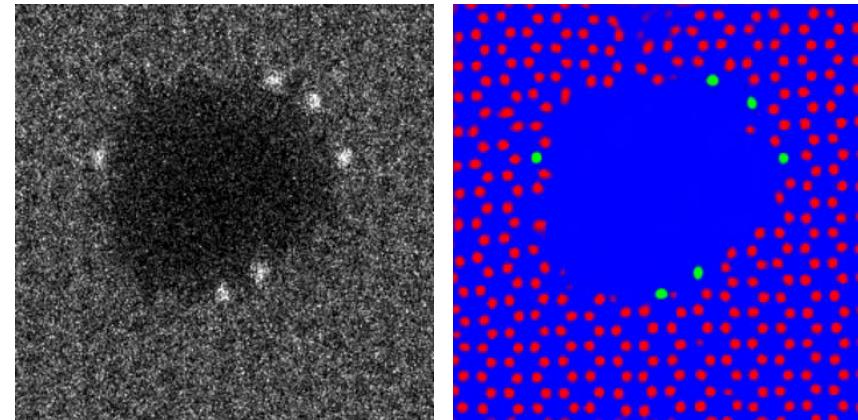
History at ORNL: Machine learning

Deep networks for learning physics

Shallow networks for data analysis



Deep networks for data analysis

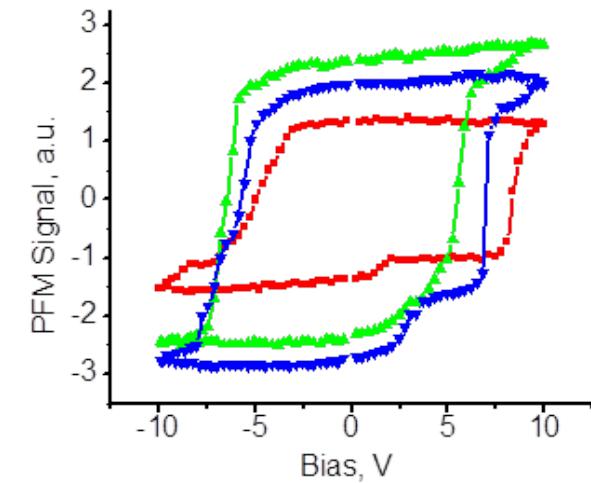
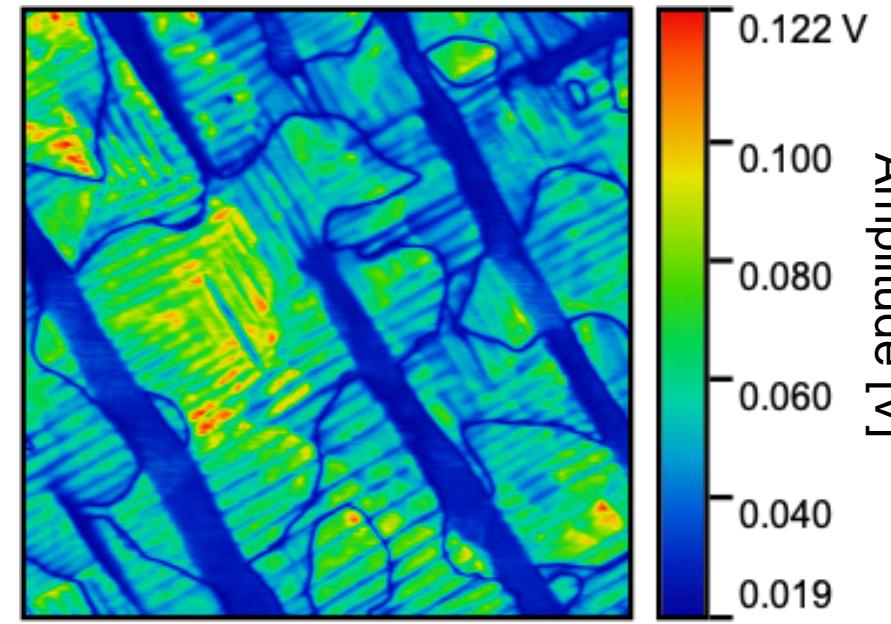
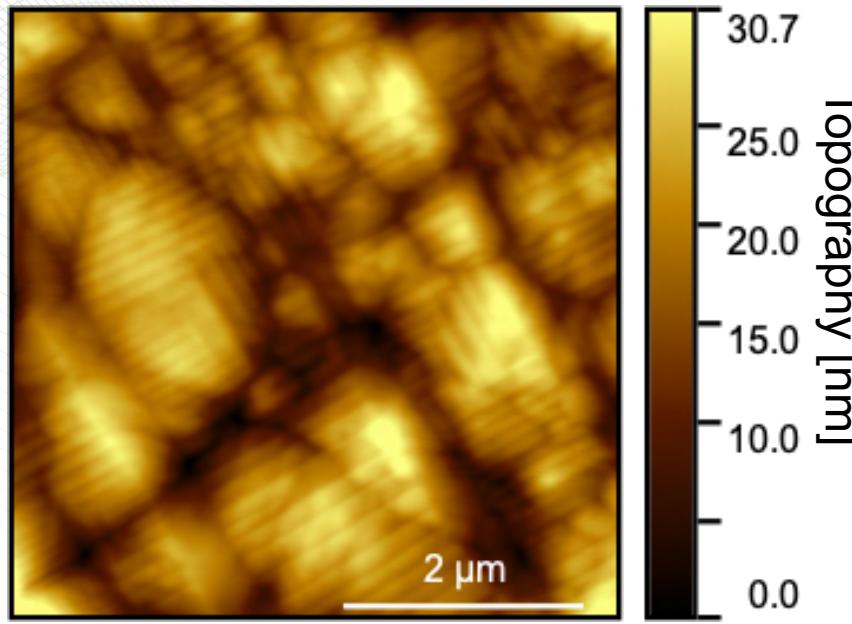


2006	Principal component analysis	Neural network recognition	NN-based theory-experiment marching	Physics-based ML	Deep learning	• ELIT ML • Invariant autoencoders
------	------------------------------	----------------------------	-------------------------------------	------------------	---------------	---------------------------------------

M.P. NIKIFOROV, A.A. VERTEGEL, V.V. REUKOV, G.L. THOMPSON, S.V. KALININ, and S. JESSE, *Functional recognition imaging using artificial neural networks: Applications to rapid cellular identification by broadband electromechanical response*, Nanotechnology **20**, 405708 (2009).

O.S. OVCHINNIKOV, S. JESSE, P. BINTACCHIT, S. TROLIERMcKINSTY, and S.V. KALININ, *Disorder identification in hysteresis data: recognition analysis of random-bond random-field Ising model*, Phys. Rev. Lett. **103**, 157203 (2009).

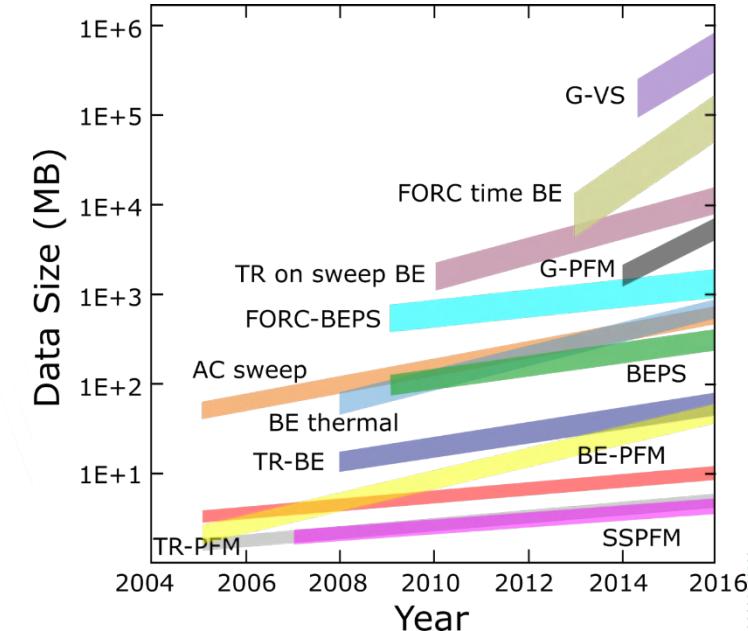
Not all regions are equally interesting!



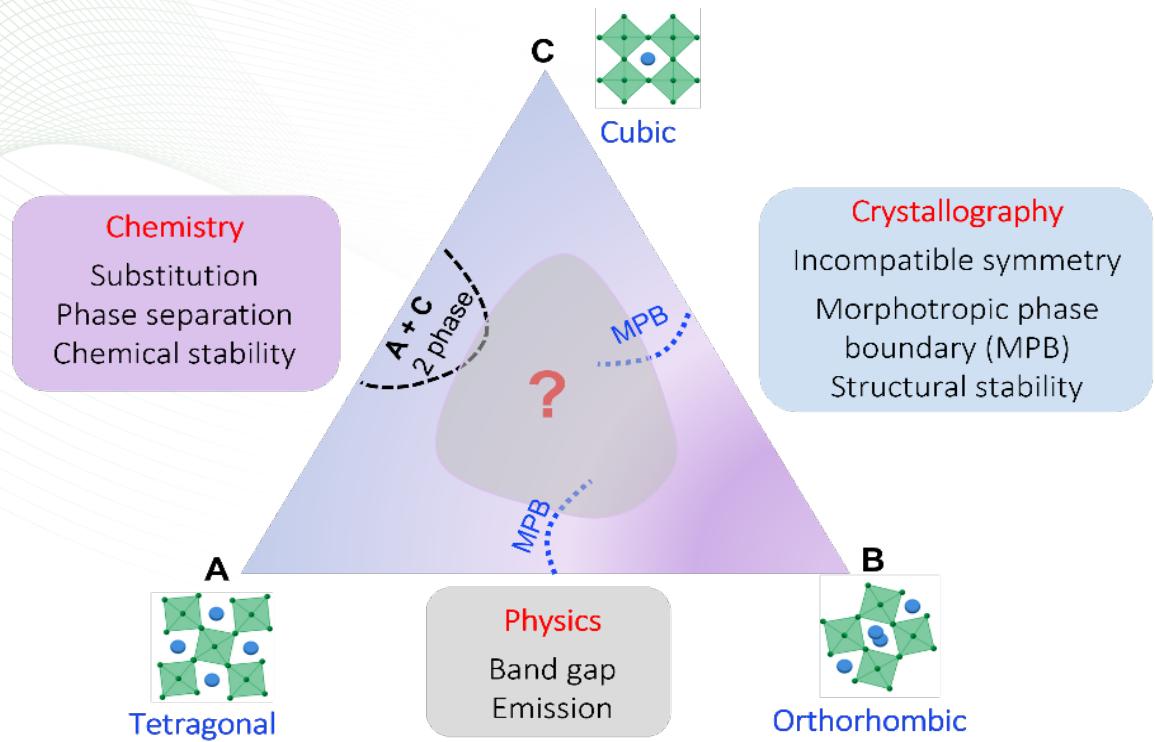
- Interesting functionalities are expected at the certain elements of domain structure
- We can guess some; we have to discover others
- Can we run PFM so that we either explore only selected regions, or discover new functionalities?

Automated experiment in PFM

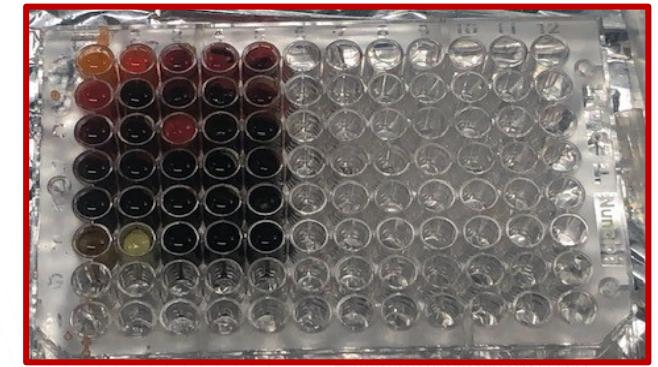
- Non-rectangular scans
- Image-reconstruction based on non-rectangular scans
- Decision making



Why synthesis?



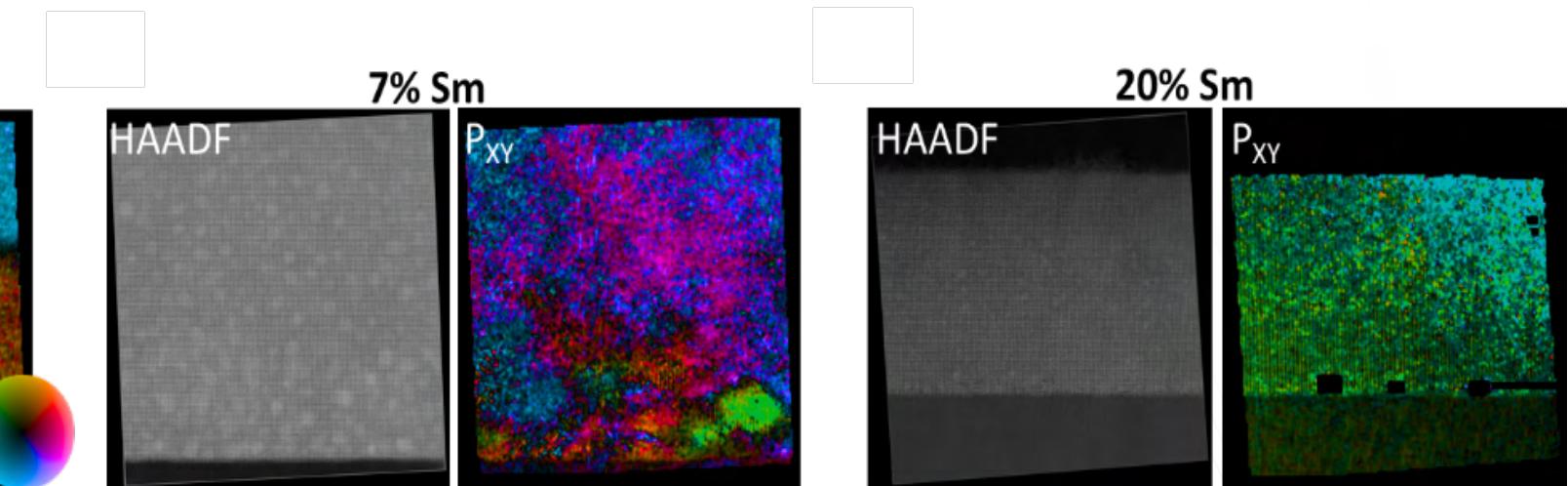
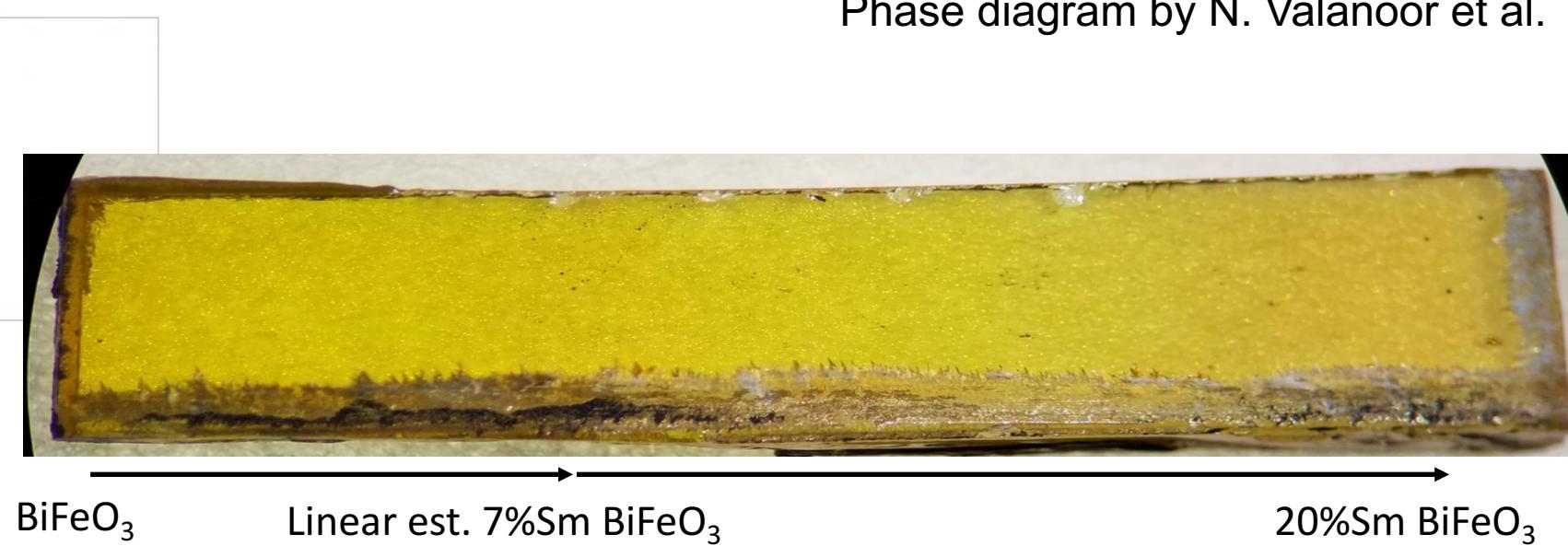
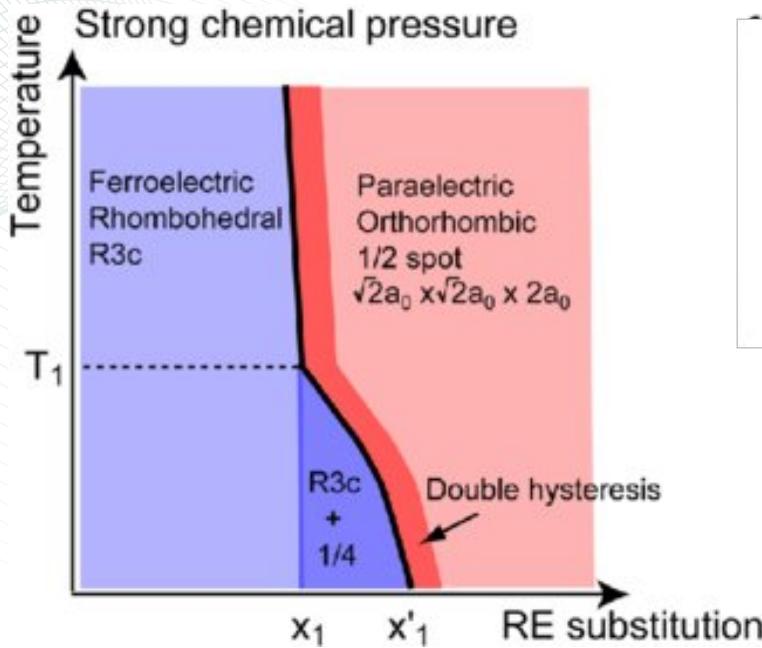
- Automated synthesis in its simplest form requires some way to navigate phase diagrams
- ... in more complex form, processing space.
- Ideally, incorporate physical knowledge and modelling



M. Ahmadi

Combinatorial library

Sample by I. Takeuchi, UMD
Phase diagram by N. Valanoor et al.

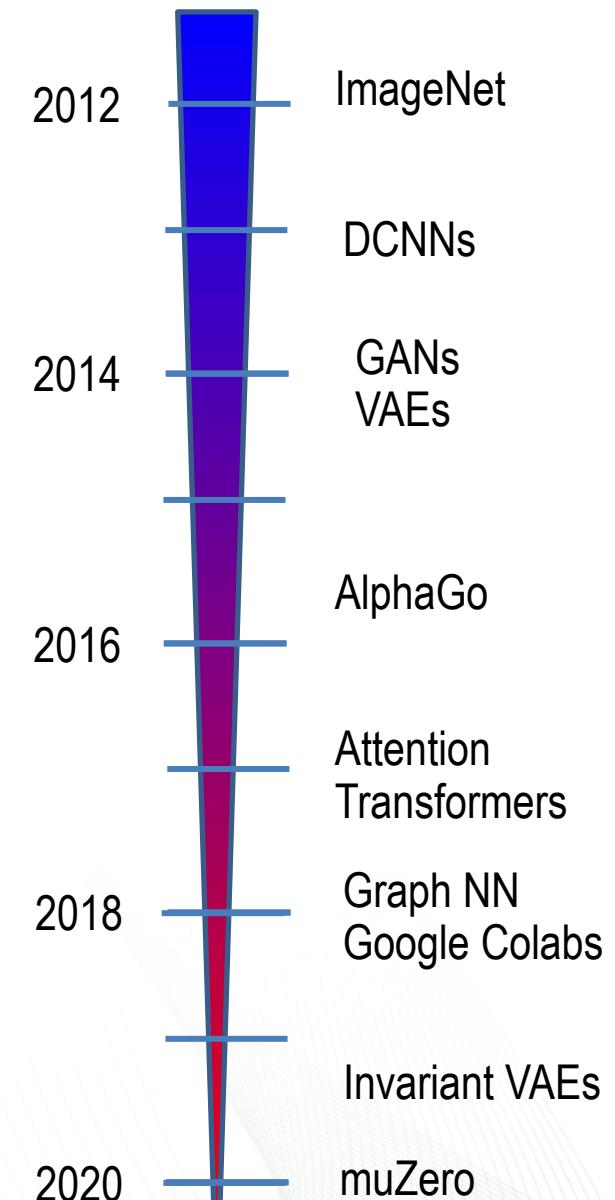


Why Machine Learning (in Imaging)?

- Last decade has experienced an explosive growth of machine learning and artificial intelligence applications
- These developments have spanned areas from computer vision to medicine to autonomous systems and games
- However, the progress and impact as applied to experimental physical sciences has been minimal....

Why is it difficult?

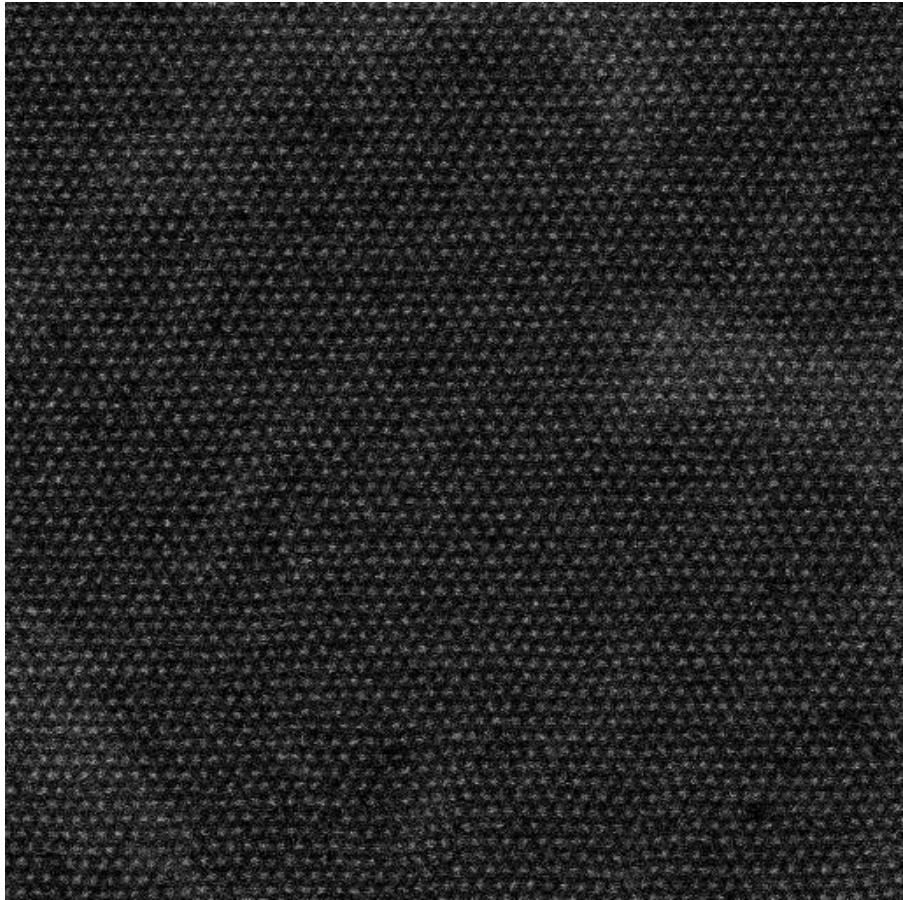
- Requires domain expertise and domain-specific goals
- Deeply causal and hypothesis drive nature of domain sciences
- No single answer: culture, not a method
- Infrastructure, open code, open data



Supervised learning:
know what thy look for....
... and simplify it

Learning the defect evolution

Experimental

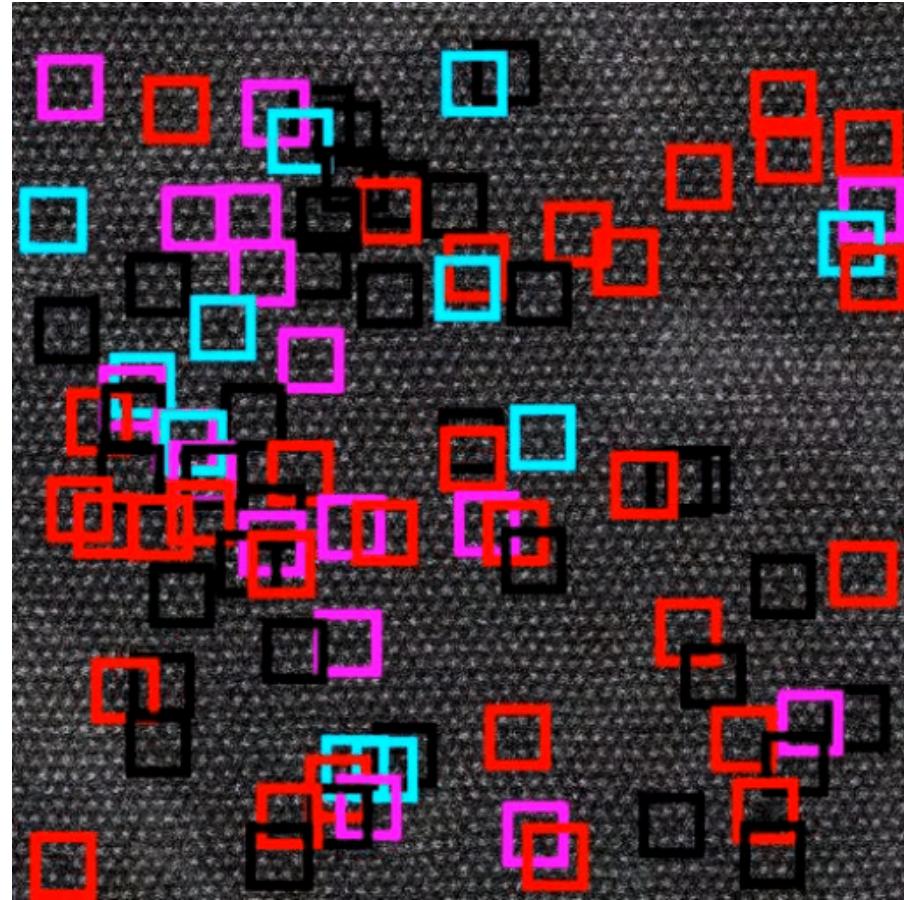


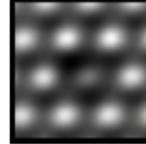
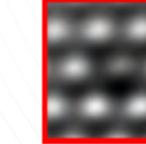
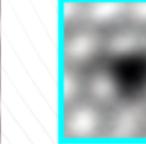
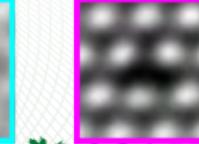
Sample: WS₂
E-beam energy: 60 kV

10

Data collected by Ondrej Dyck (CNMS/ORNL)

Decoded



Class 1 Count: 2078	Class 2 Count: 1055	Class 3 Count: 1687	Class 4 Count: 2123	Class 5 Count: 1166
				

(Mo_w + V_s)-I

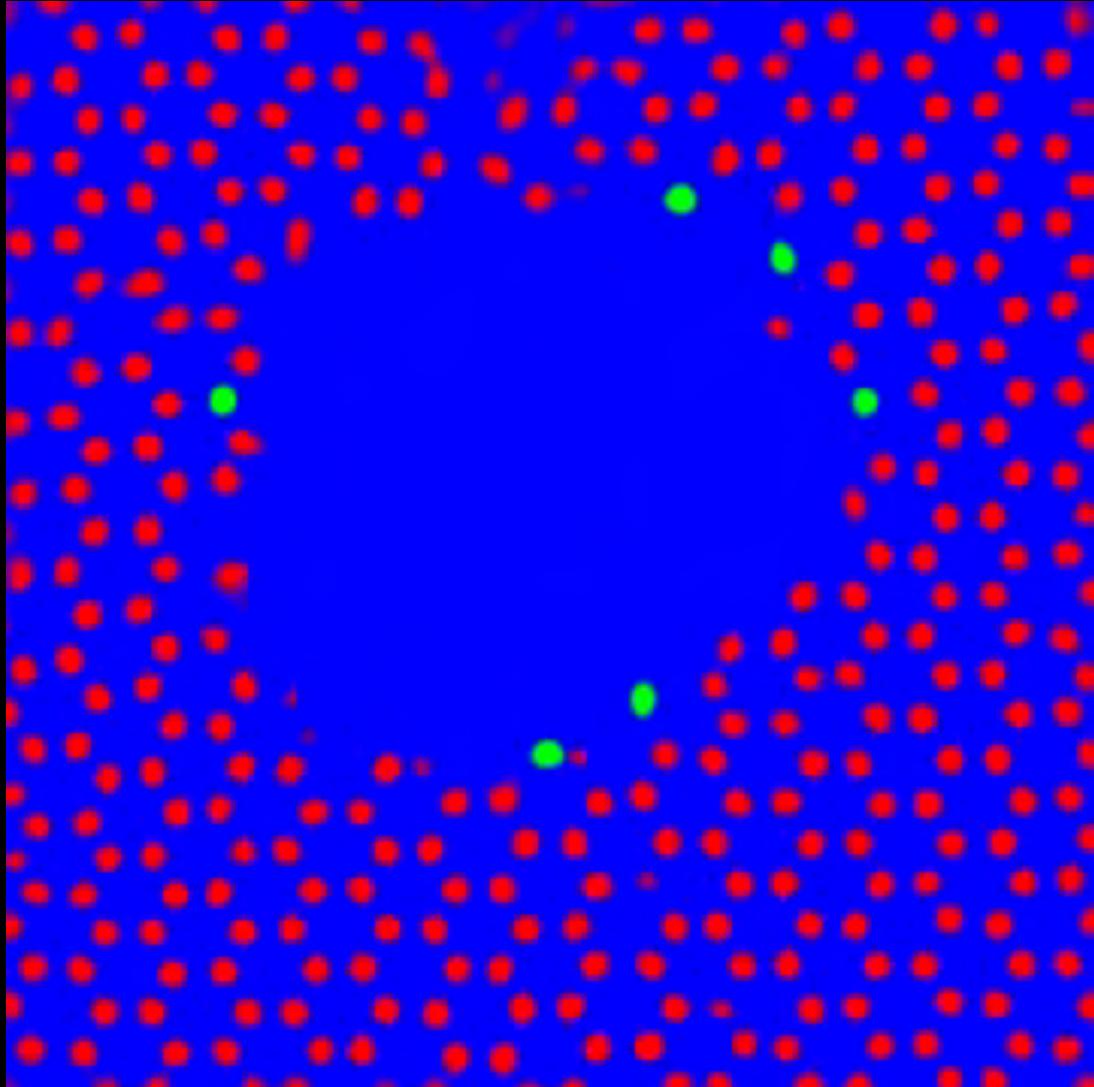
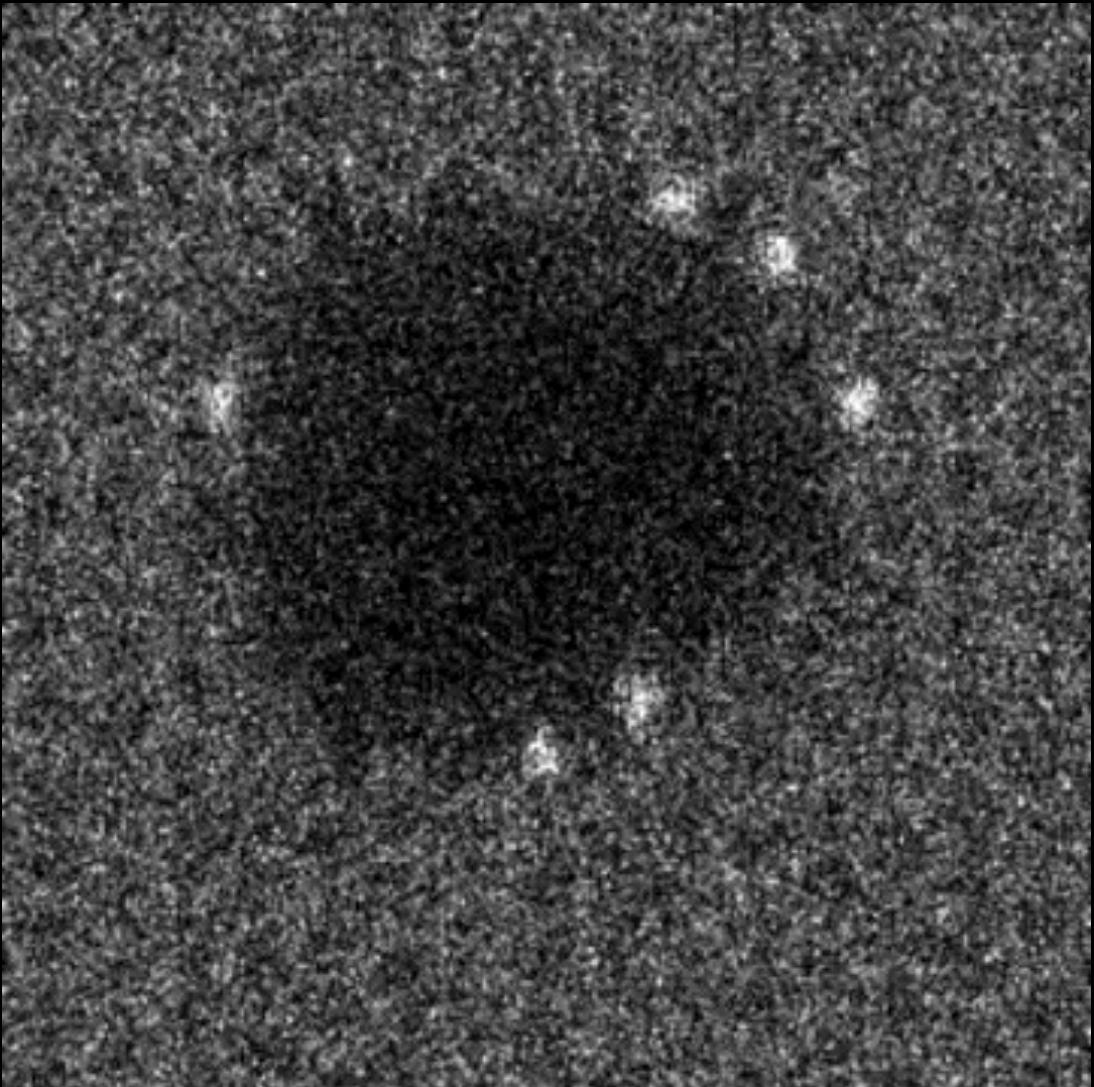
Adatom

(Mo_w + V_s)-II

V_w

Deep learning works like a charm for:

- Drift correction
- Denoising
- Data processing/dimensionality reduction
- Feature finding (physics is in the training set)



Autoencoders: variational, rotational, conditional

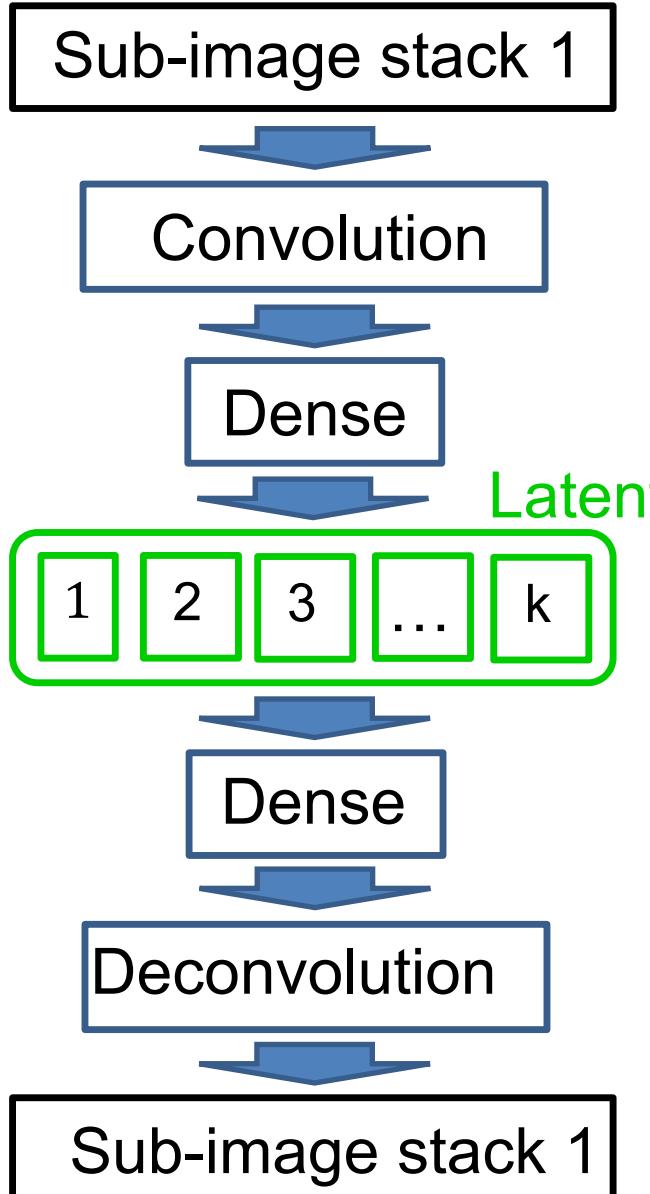
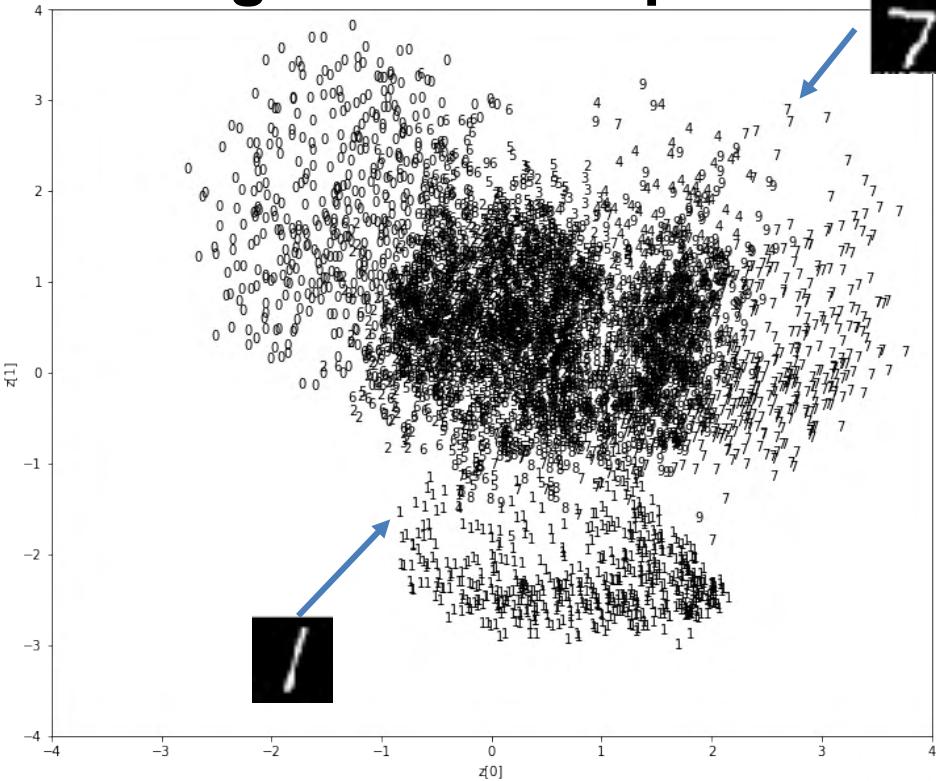
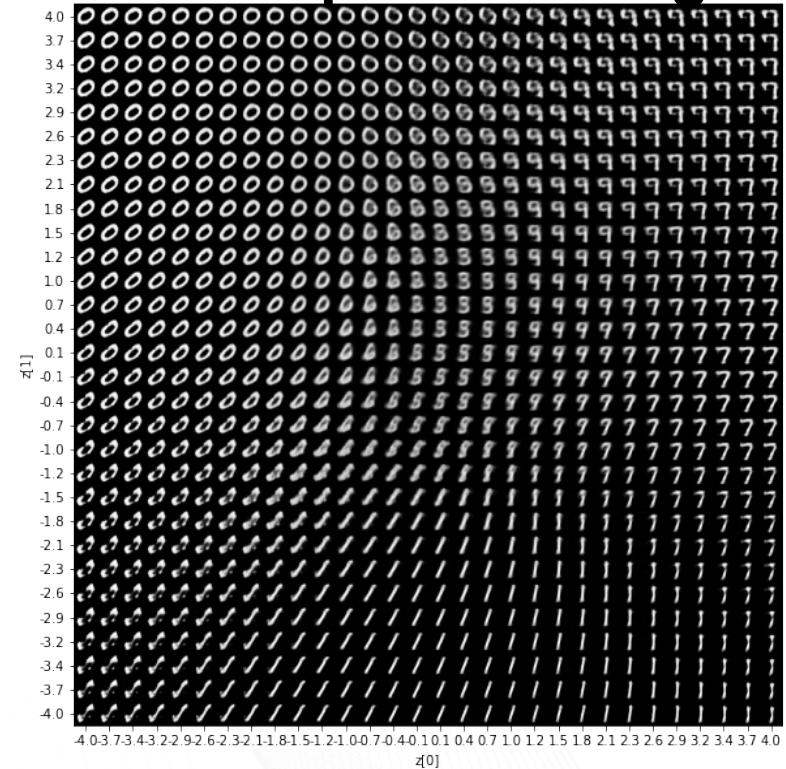


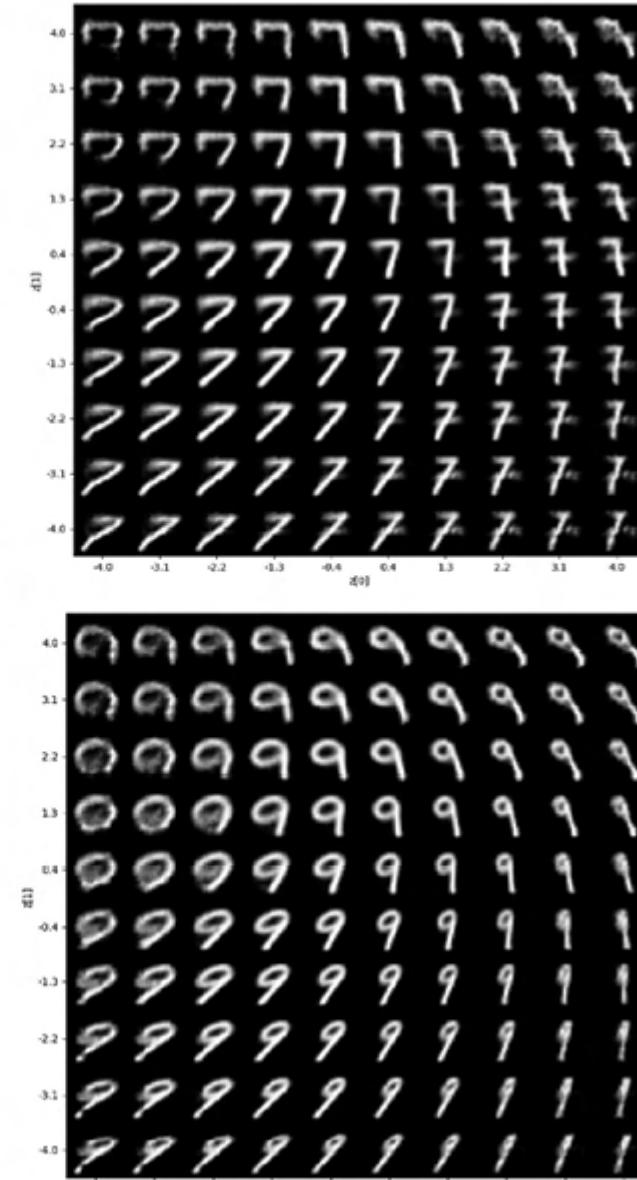
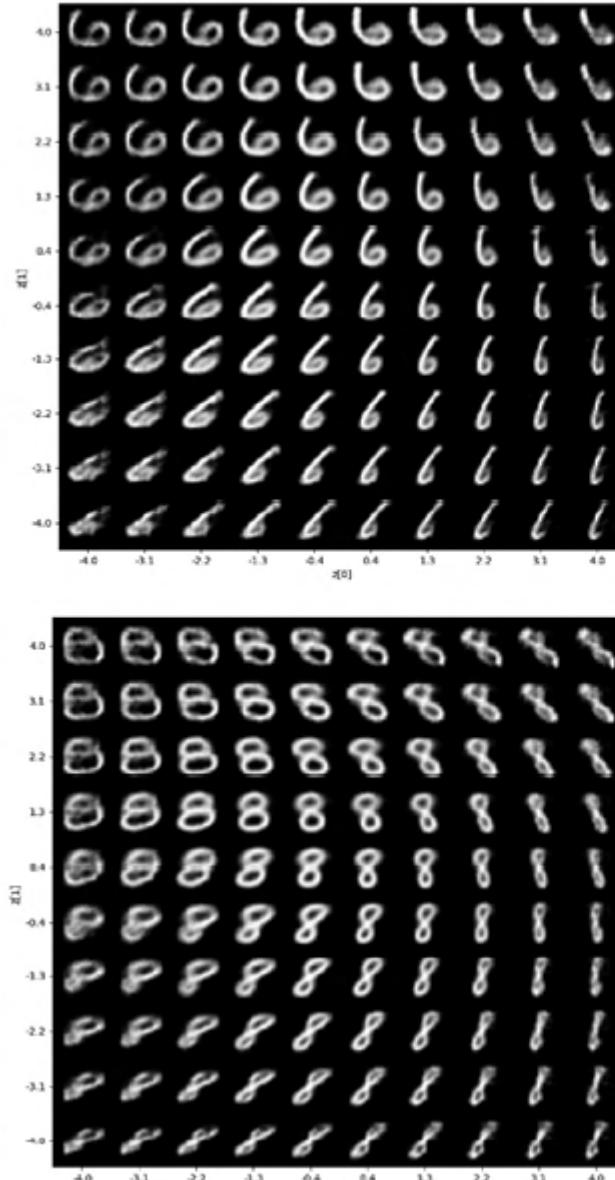
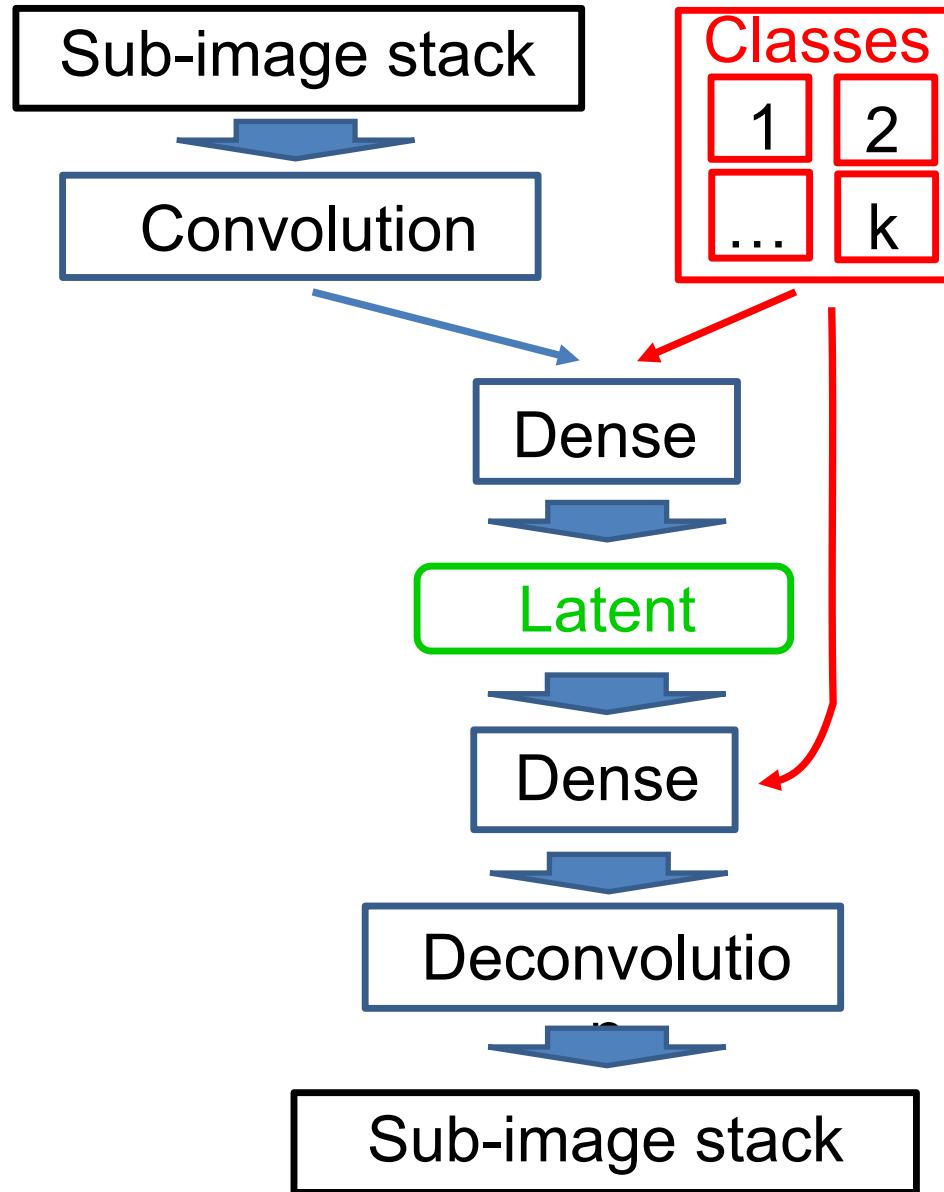
Image -> Latent space



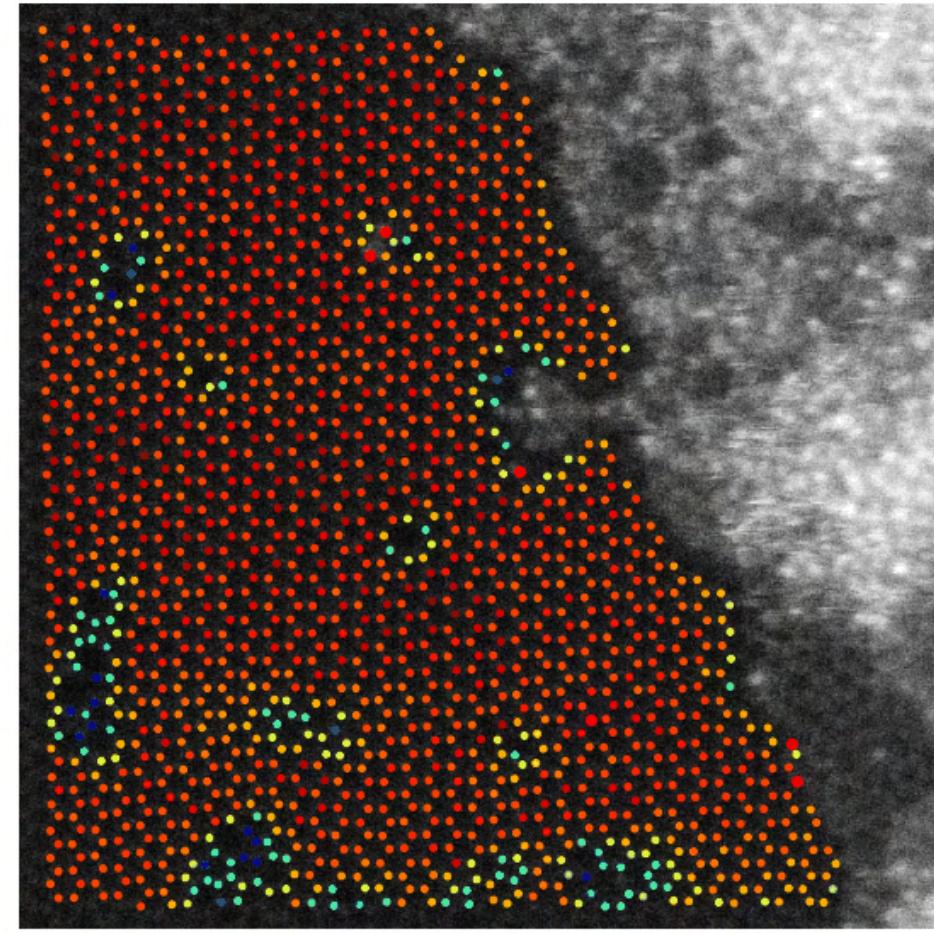
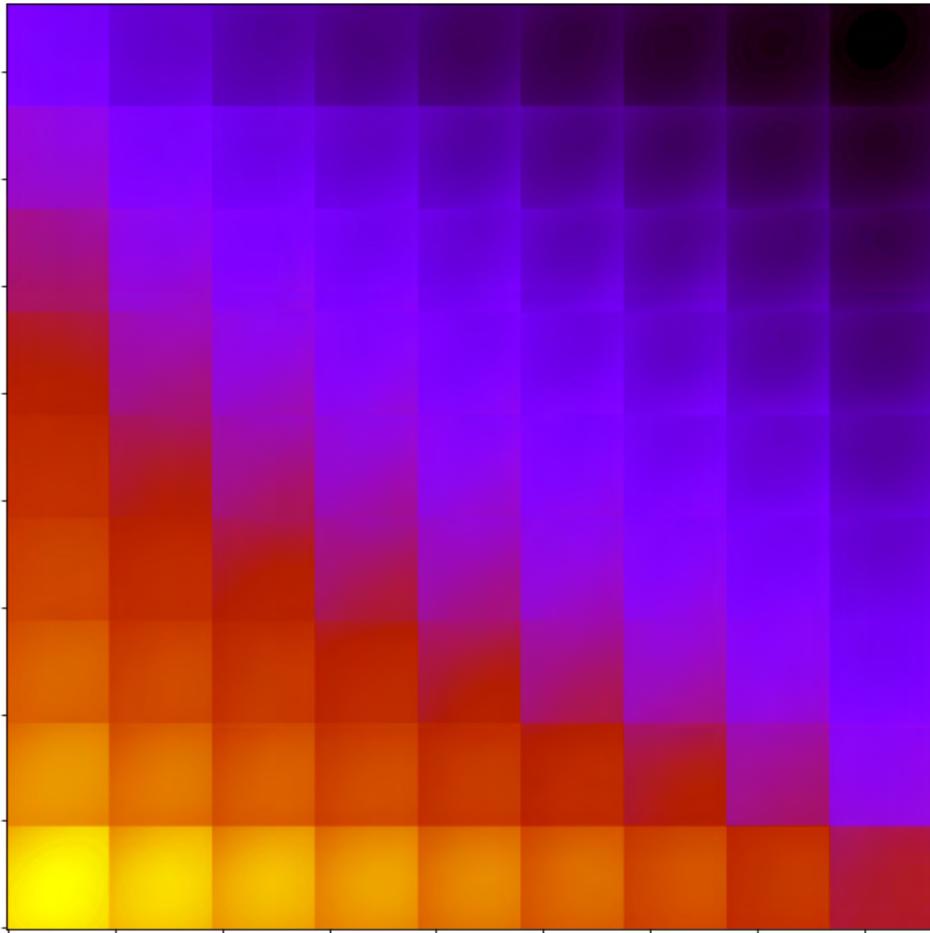
Latent space -> Image



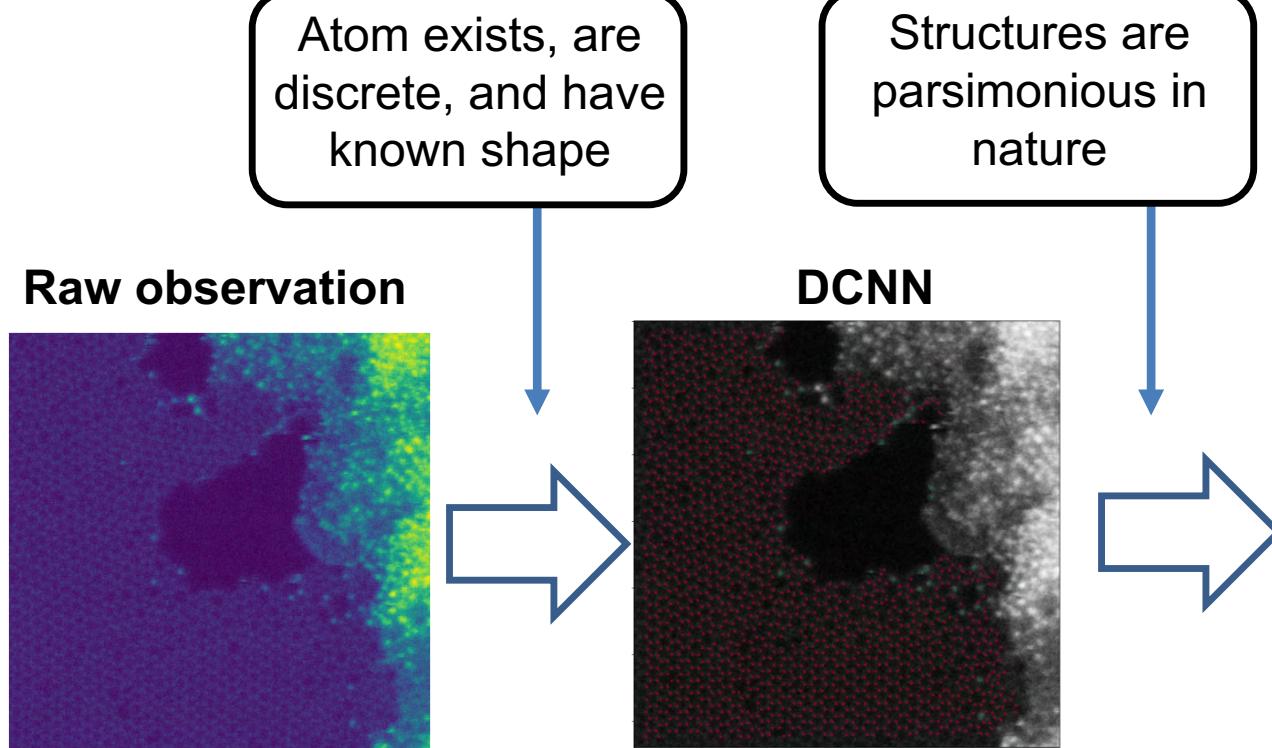
Conditional variational autoencoder



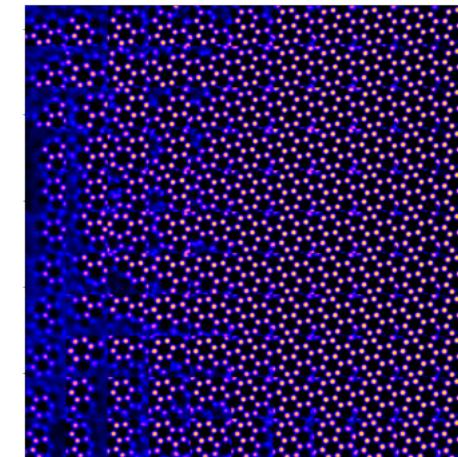
Rotational Variational Autoencoders



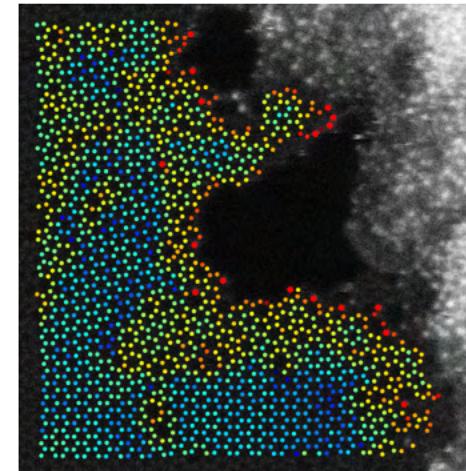
Discovering Molecular Fragments



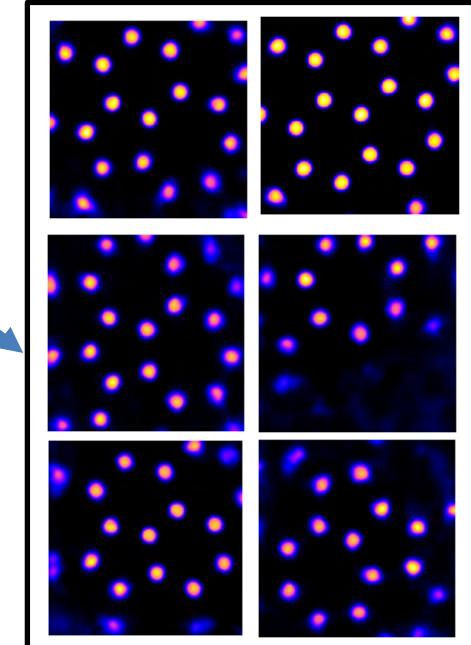
Latent space of srVAE



Latent labels



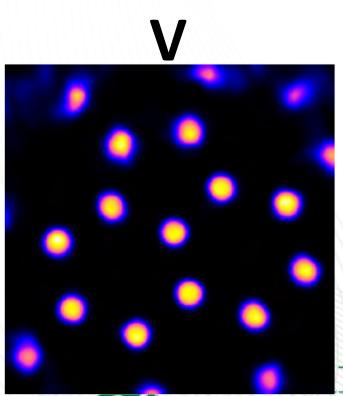
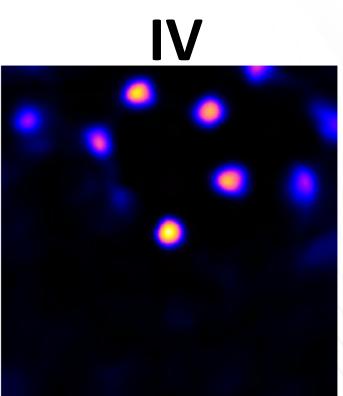
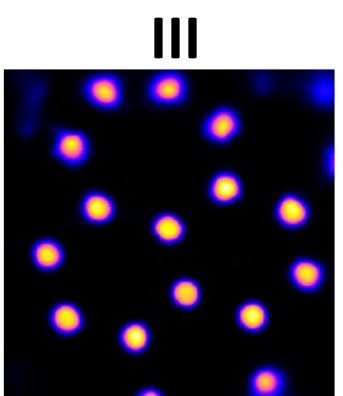
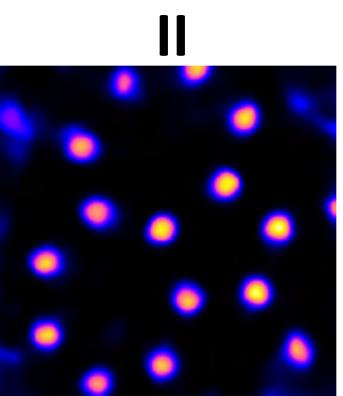
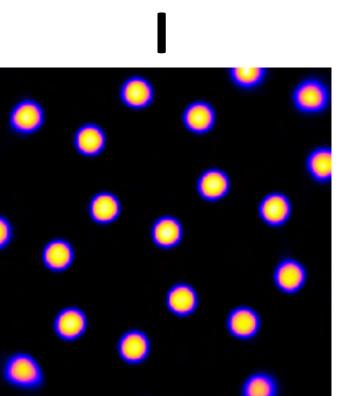
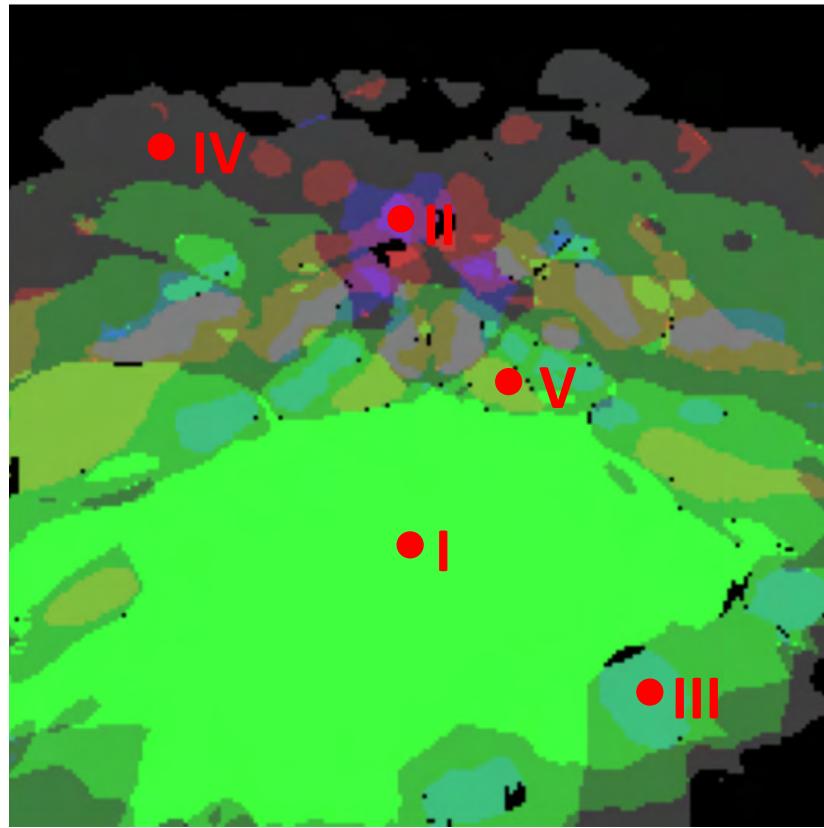
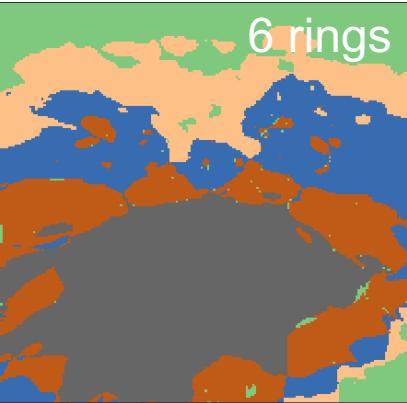
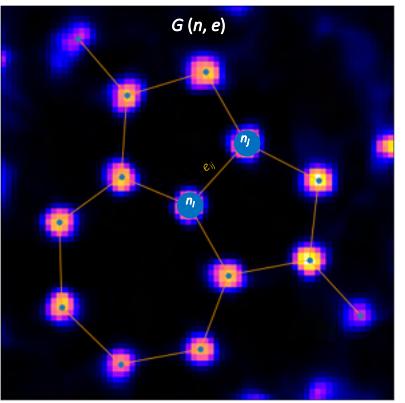
I. Molecules



II. Reaction

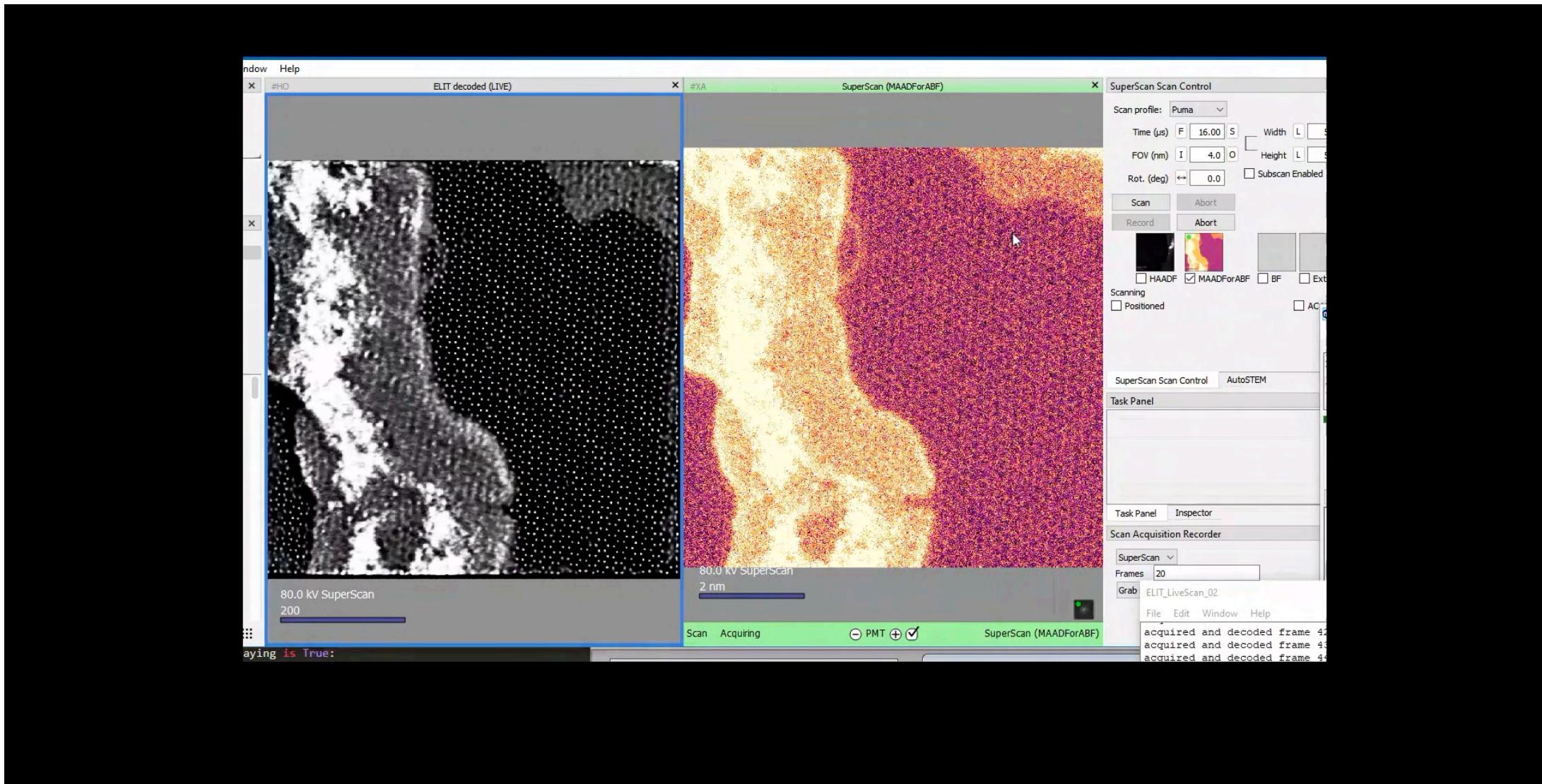
$A \rightarrow B \rightarrow C$

Discovering Molecular Fragments: Chemical Space Map

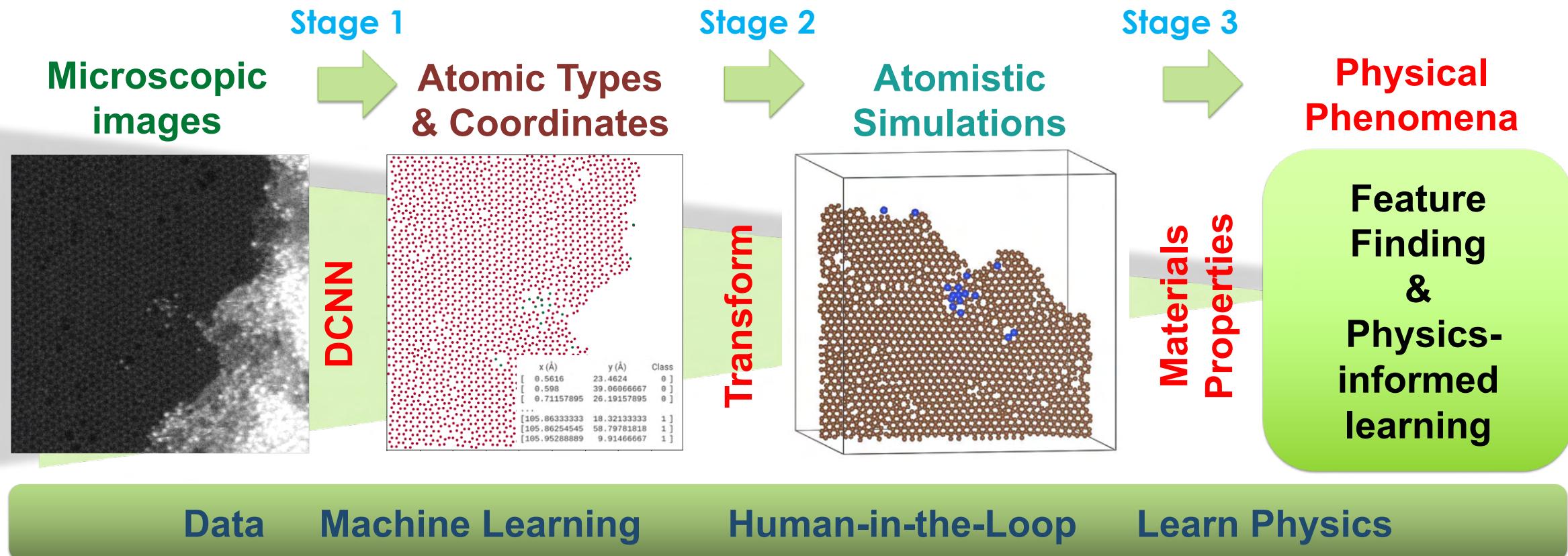


On-the-fly implementation

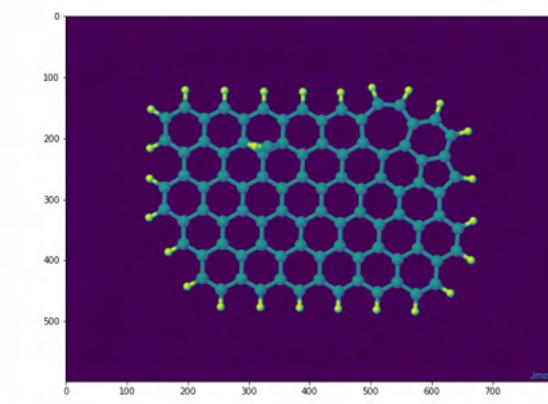
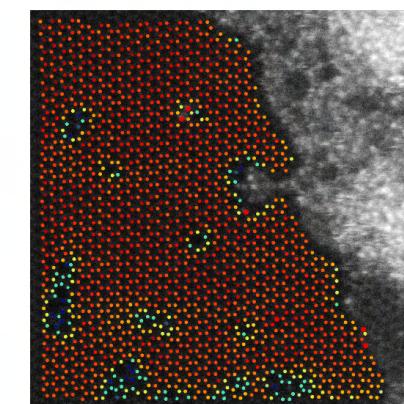
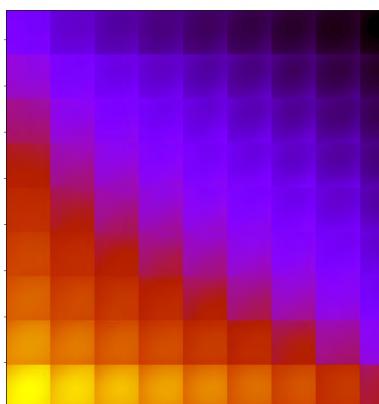
Implementation: Kevin Roccapriore, Ayana Ghosh, Sergei V. Kalinin & Maxim Ziatdinov



From Microscope to MD



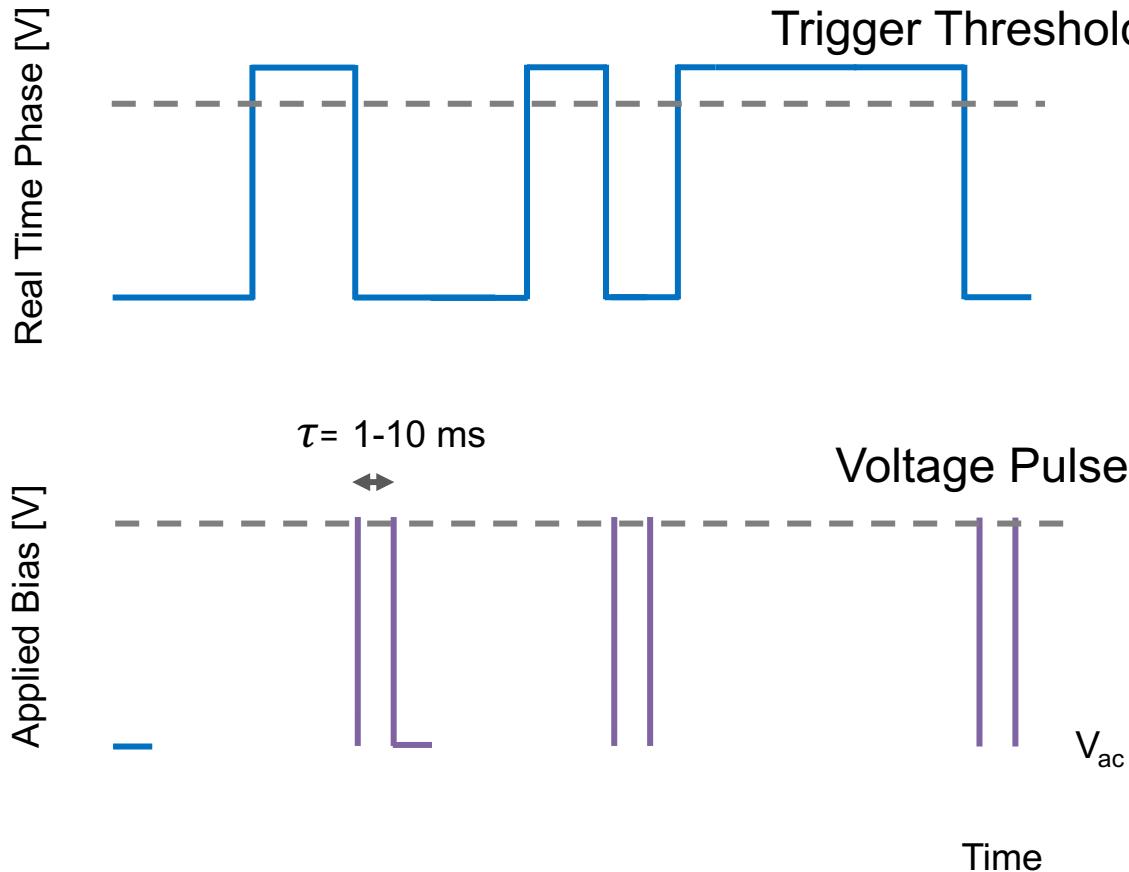
- DCNNs for atom finding
- Invariant VAEs for physics discovery
- Conditional VAEs
- GP reconstructions
- Piping data in DFT/MD environment



Automated Experiment:
almost easy.... If you know what you are looking for

FerroBOT: Image-based feedback

Real-time Feedback



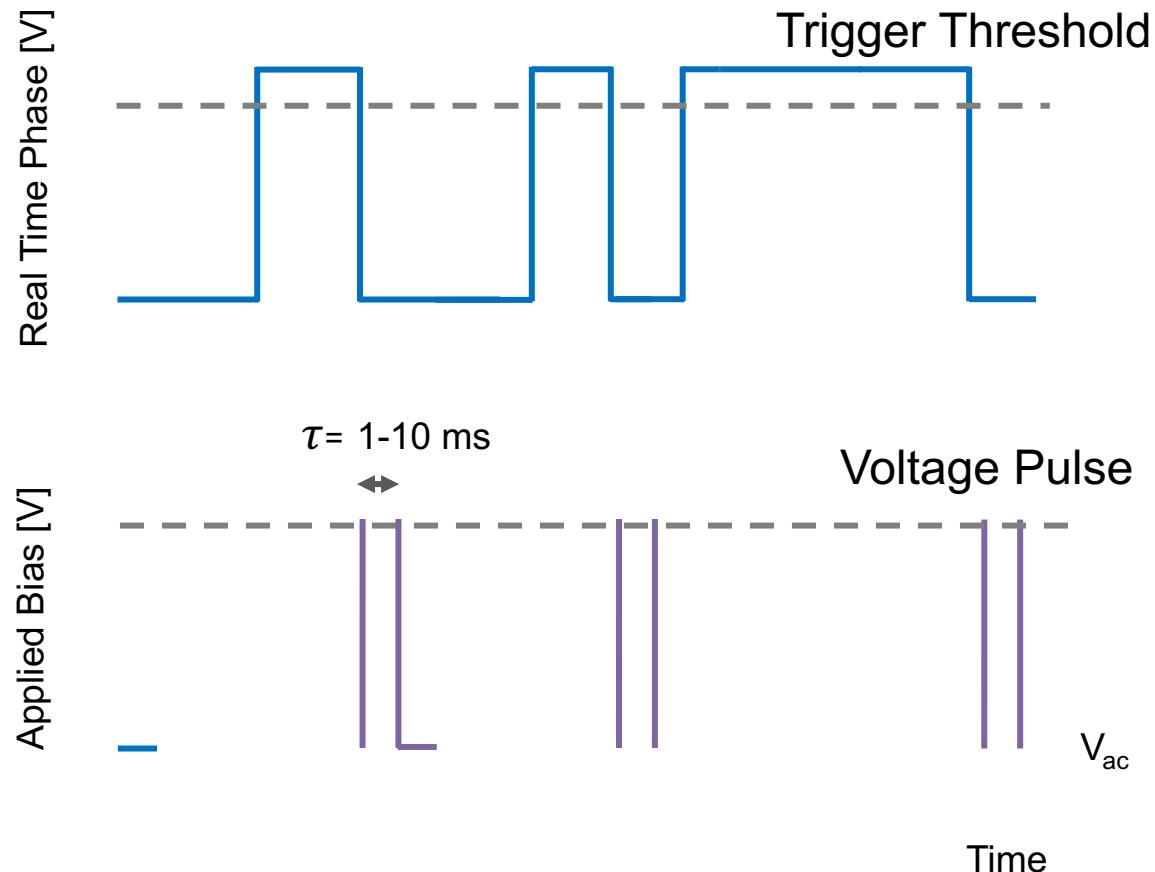
Example PFM Phase

- FPGA – Labview – Matlab framework
 - Driving with AFM

Reduction of "purple" domain

FerroBOT: single action table

Real-time Feedback



Real-time Manipulation

- FPGA – Labview – Matlab framework
 - Driving with AFM
- BiFeO₃: map DW energy landscape
 - Pulsing 5 ms, 1.5V, vacuum, domain wall growth

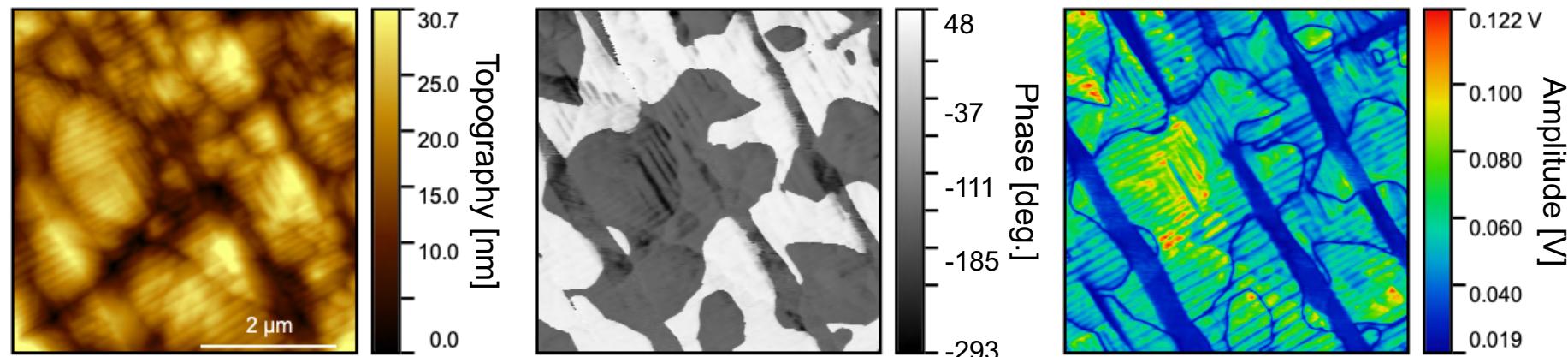
Amplitude

Phase

Realtime Feature Finding: PbTiO_3

- Cypher microscope
 - Ethernet connection for transmitting locations
- Skimage corner finding
 - Thresholded image feed
- Python – LabView framework
- Outlook
 - IV curves on domain walls
 - Ferroelastic domain wall probing

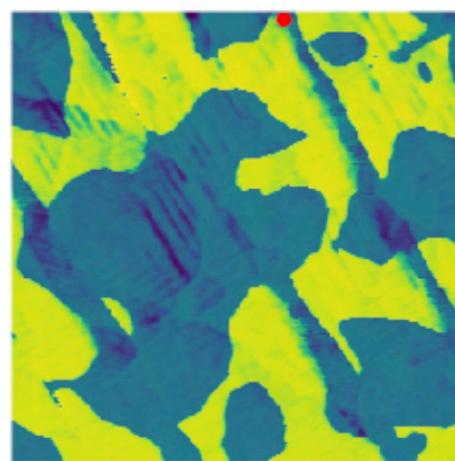
Initial State via Vertical Piezoresponse Force Microscopy



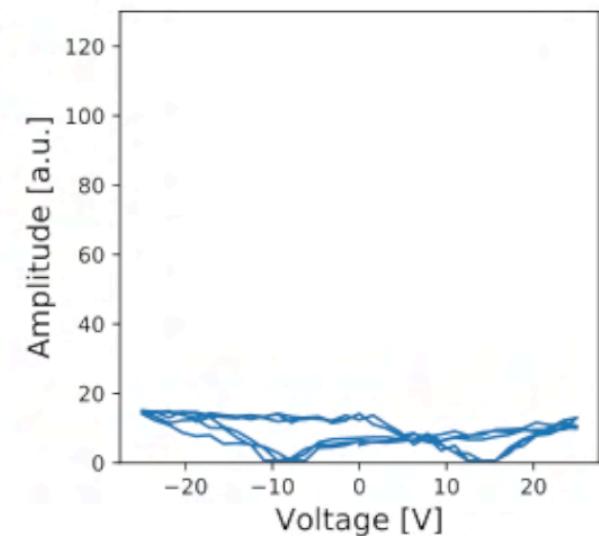
Feature Recognition



Tip Location



BEPS at Features

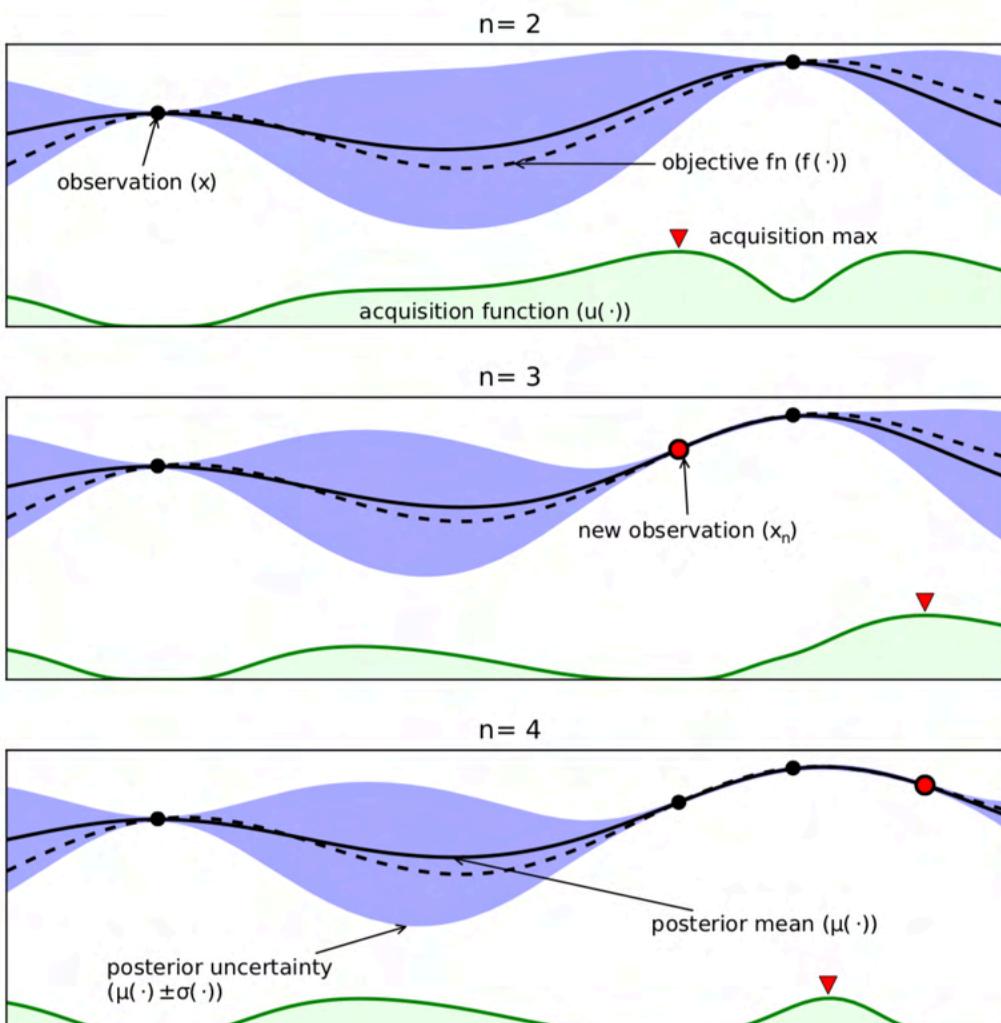


Here, we use simple computer vision algorithms to explore polarization switching in the regions predefined by operator based on prior knowledge

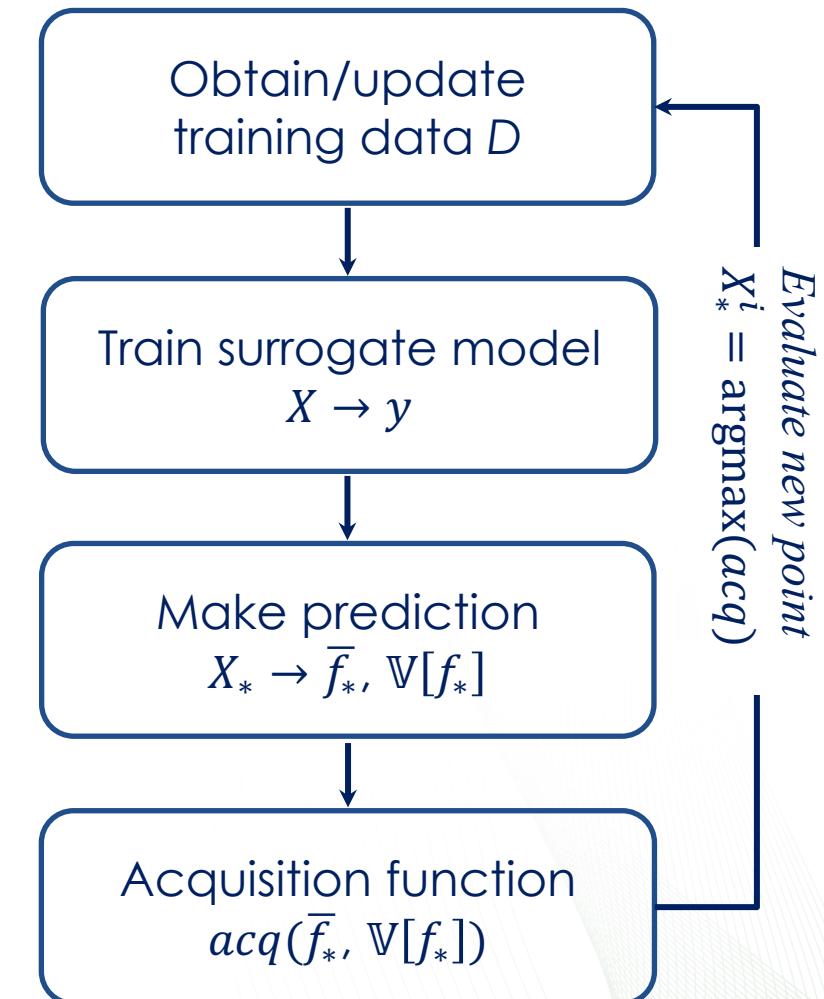
Automated Experiment:

... with John Snow priors...

The basics: Bayesian Optimization

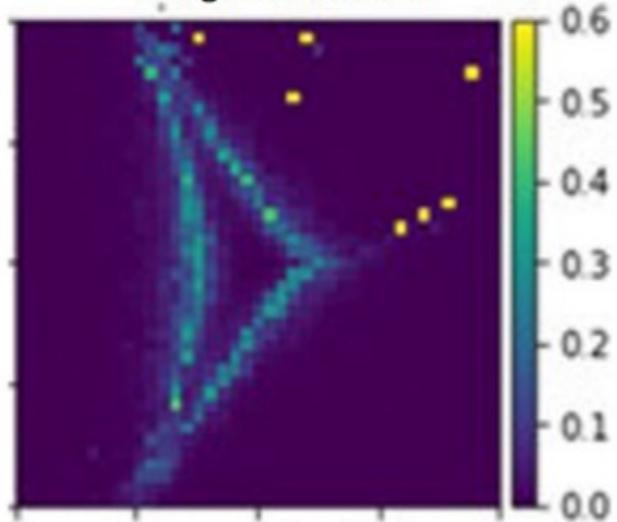


X, y : (sparse) Training data
 X_* : New (not yet evaluated) points



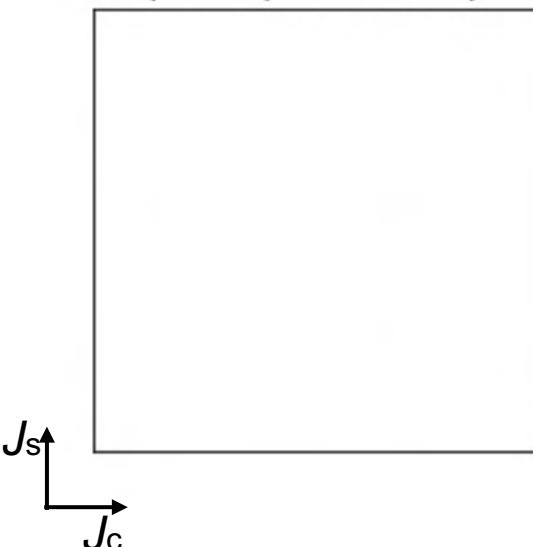
Bayesian Optimization for physical discovery

Full grid simulation

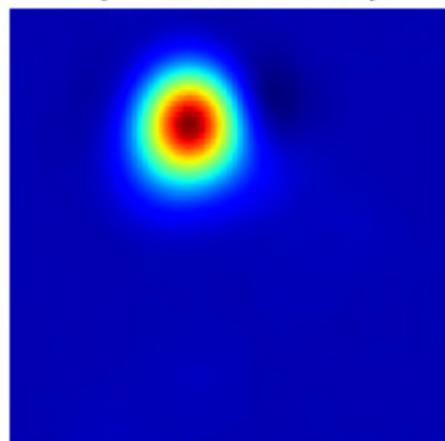


Discovering regions where heat capacity is maximized in NNN Ising model

Explored points at step 0



GP prediction at step 0



- Started to work in August 2019
- First, we planned to apply BO for autonomous experimentation at CNMS. Then, COVID happened...
- “So what if we use BO to explore the parameter spaces of theoretical models?”

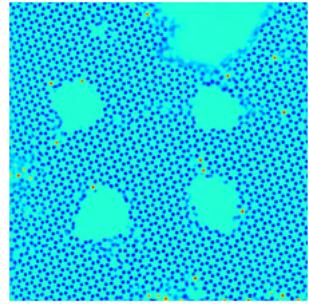
Implementation in GPim

```
1 def acquisition_function(gpmodel, X_full, X_sparse):  
2     mean, sd = gpmodel.predict(X_full, verbose=0) # leave it as is  
3     acq = 5 * sd + 10 * mean # Good for heat capacity  
4     return acq, (mean, sd) # leave it as is
```

```
1 # Initialize Bayesian optimizer with a custom acquisition function  
2 boptim = gpim.boptimizer(  
3     X_sparse, Z_sparse, X_full,  
4     J2_to_S_func, acquisition_function=acquisition_function,  
5     batch_size=1000, lengthscale=[1., 40.], dscale=4, exit_strategy=1,  
6     exploration_steps=650, use_gpu=True, verbose=1, save_checkpoints=True,  
7     filename='/content/drive/My Drive/research/Ising_BO/bo_ising_heat_acq1_e')  
8 # Run Bayesian optimization  
9 boptim.run()
```

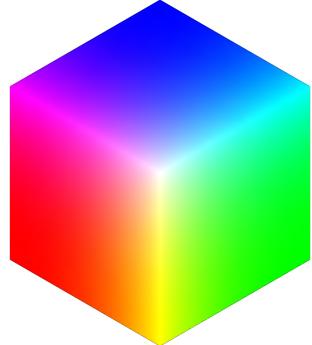
Automated experiment workflows

SPM or STEM image



- Sliding window/linear transform
- Keras DCNN
- rVAE (rotational invariance)
- rcVAE (plus classification)

EELS or SPM datacube



- Integrated intensity
- Keras DCNN
- Spec2im autoencoder
- $(\text{im}, \text{spec}) \rightarrow (\text{spec}, \text{im})$
- CycleGAN

Descriptor

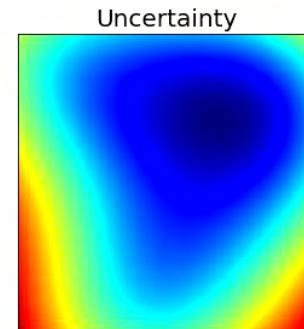
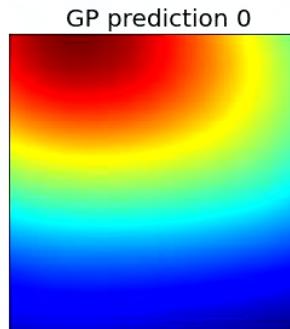
Gaussian processing

- Acquisition functions
- Pathfinder functions
- Kernel control

GPim library
(M. Ziatdinov)

Input data

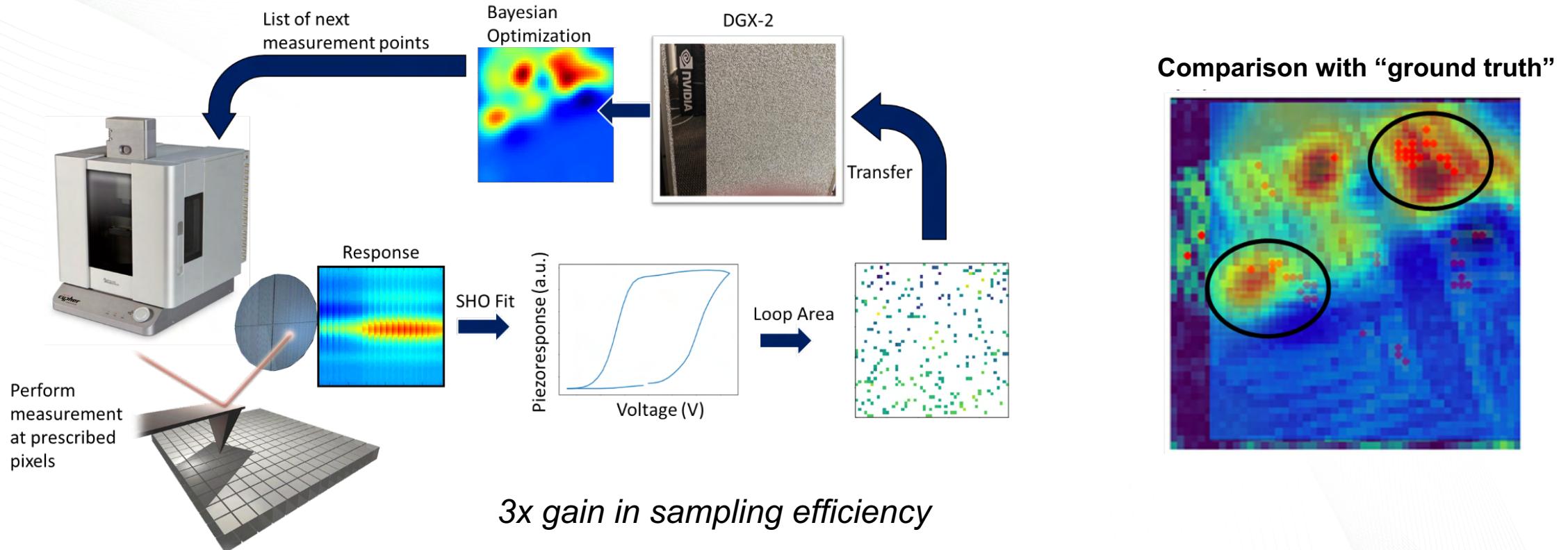
x



- AE based on structural analysis for STEM data
- AE based on spectral data in PFM
- AE based on DL for EELS data
- Feature of interest finding for mesoscopic images

Bayesian Optimization for Self-Driving Microscopy

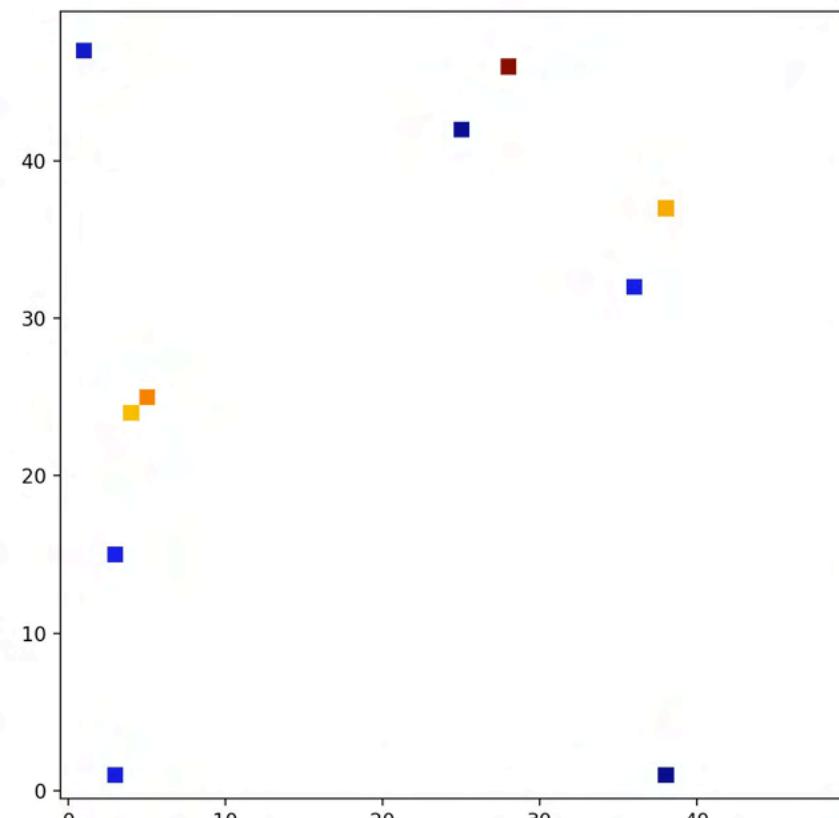
Then, COVID restrictions got relaxed and Rama Vasudevan realized a “self-driving” PFM



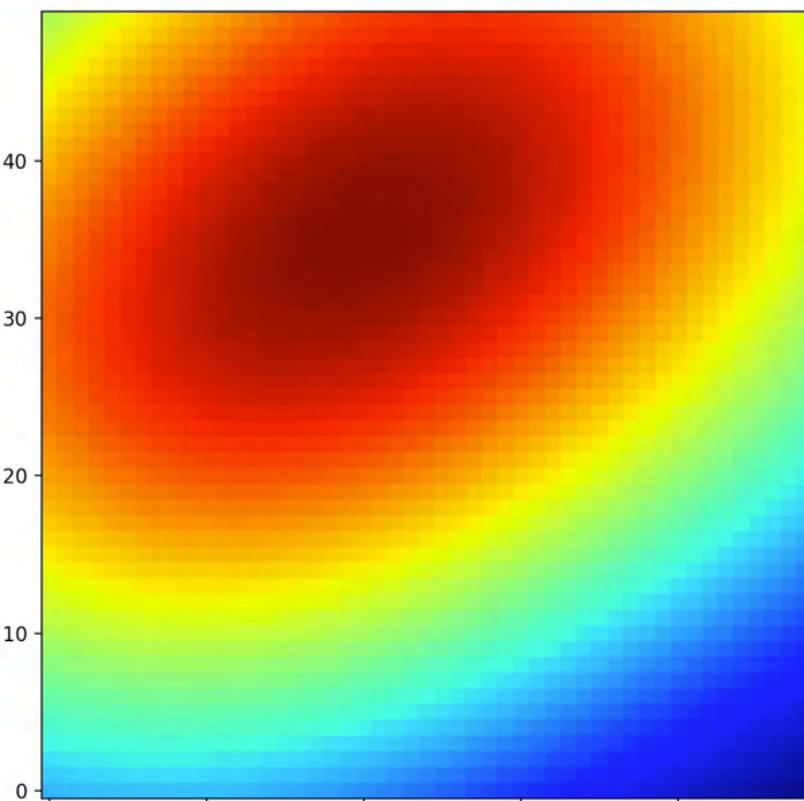
R. K. Vasudevan, K. Kelley, H. Funakubo, S. Jesse, S. V. Kalinin, M. Ziatdinov, **ACS Nano** (2021) <https://doi.org/10.1021/acsnano.0c10239>

Putting it together: GP optimized experiments

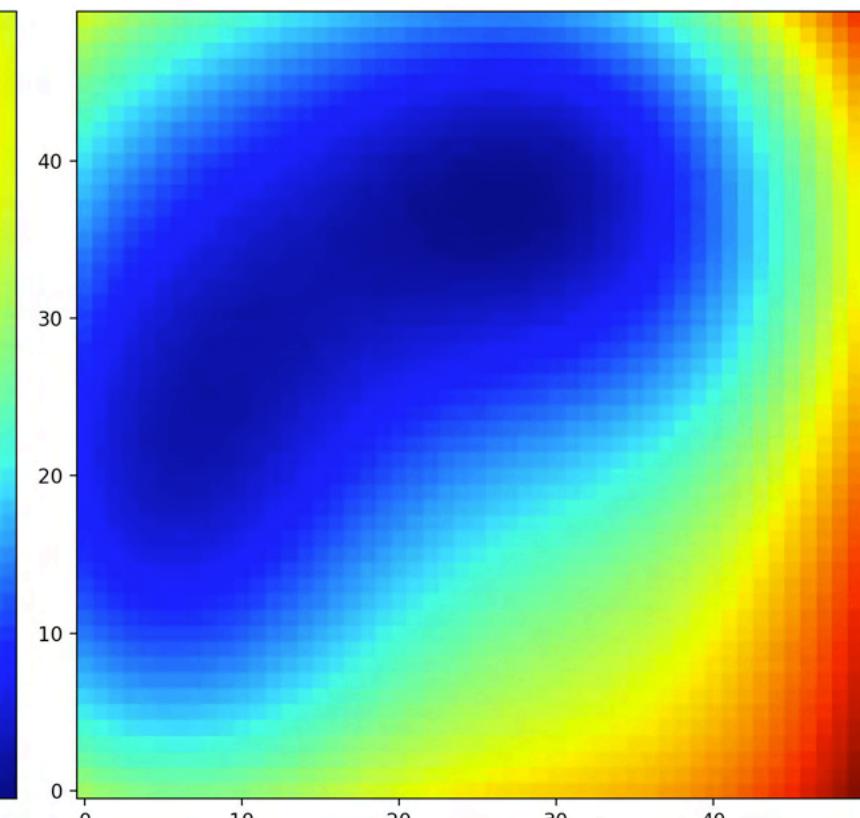
Measured Loop Area



GP Prediction



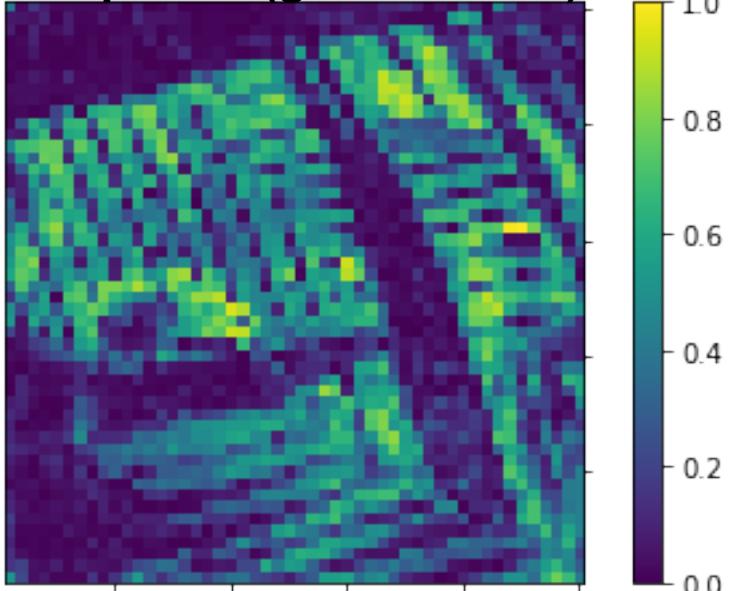
GP Uncertainty



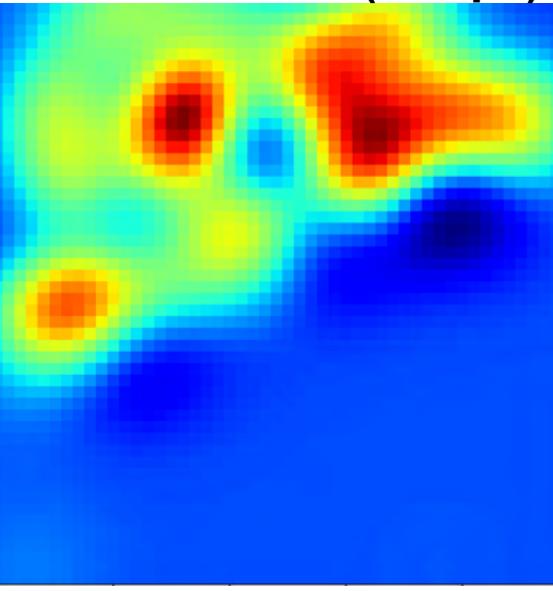
But what if we do not know a priori what elements of domain structure are we interested in?

- First step – Gaussian Processing towards exploration of specific behavior
- Here, we explore regions with maximal area under hysteresis loop
- For N measured points, the GP reconstructs the loop area map and uncertainties of the reconstruction
- Based on these, next locations for measurements are selected

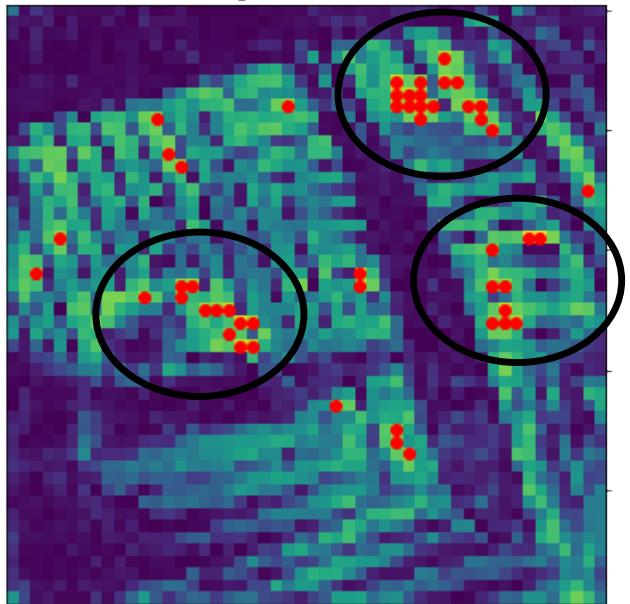
Loop Area (ground truth)



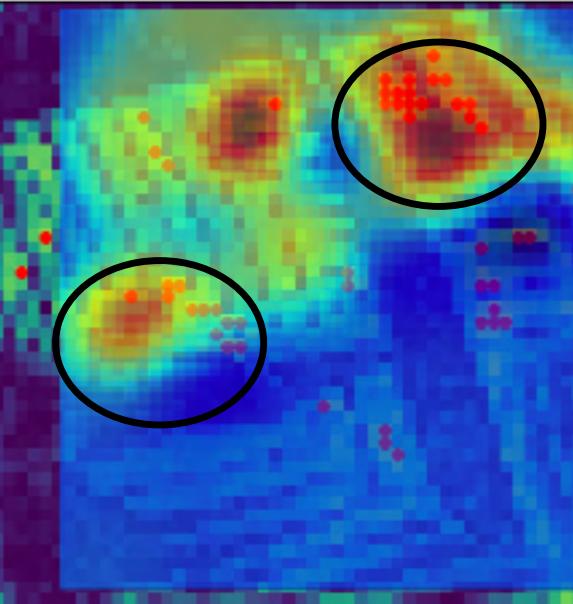
GP Prediction (400 px)



Loop Area >0.8



Overlaid



[arXiv:2103.12165](https://arxiv.org/abs/2103.12165)

[arXiv:2011.13050](https://arxiv.org/abs/2011.13050)

Next steps:

- Incorporate prior knowledge of domain structure
- Factor in generative physics of ferroelectric domain structures
- These are complex ML problems

But: the bridge is built!

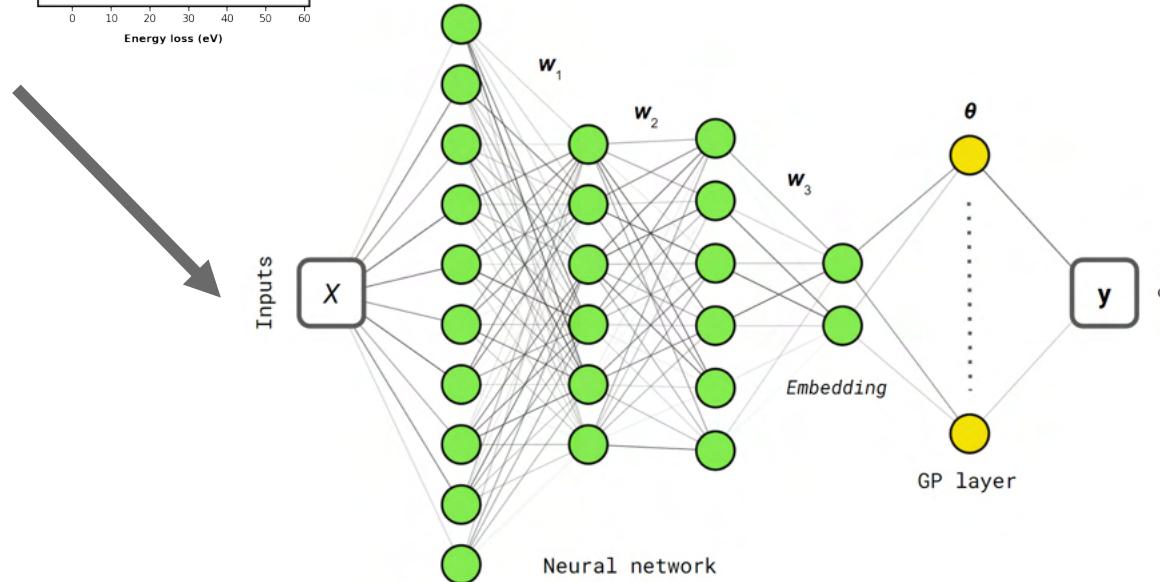
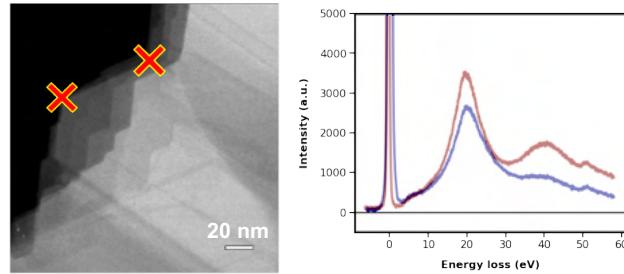
Automated Experiment:

... as a scientist...

Physics-based feature engineering: Deep kernel learning – Bayesian optimization

Specify physics criteria

Active learning



Acquire
structural data

Measure a
spectrum

Train DKL
model with new
data

Decide next
position (optimize
physics criteria)

Allows navigation of the system to search for physics

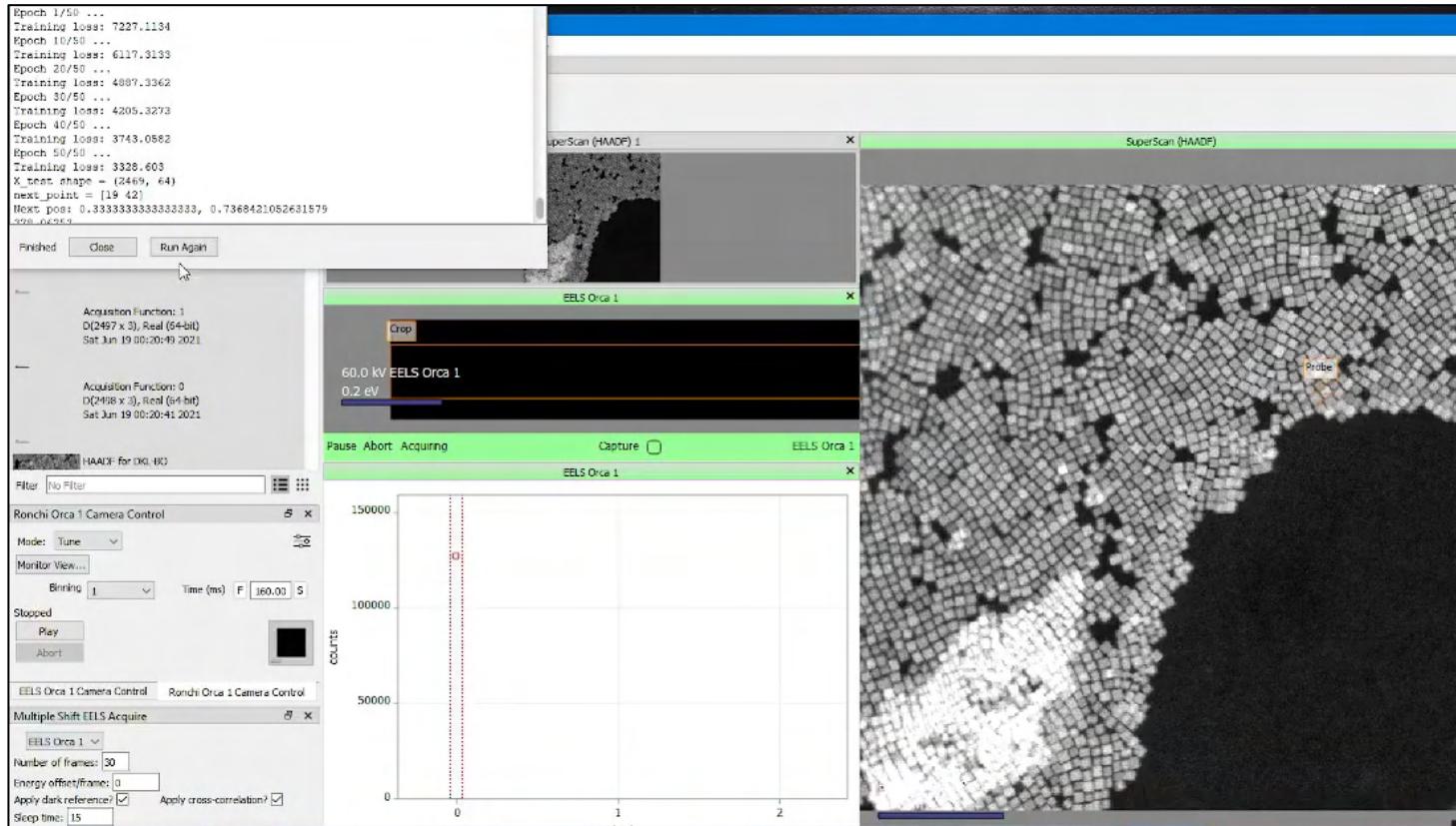
Physics-based feature engineering:

Microscope Operation

Structural
image



Set of
spectra



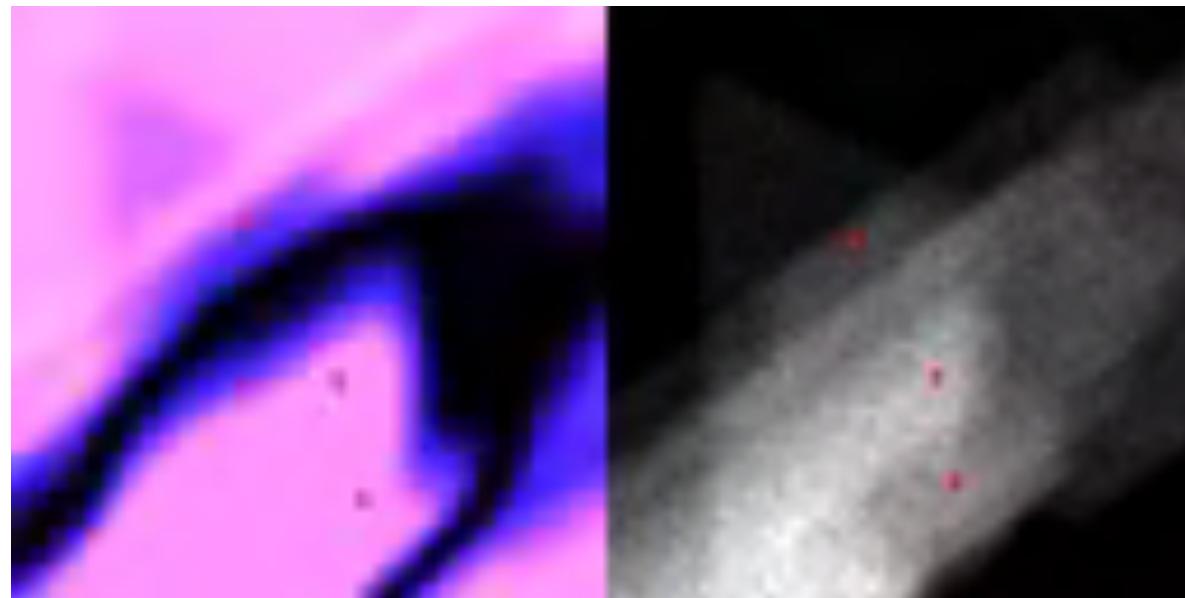
Opportunity alert

- Between measurements, the beam is optionally blanked or placed in a safe position.
- This is an **excellent** opportunity for “smart EELS” with **beam sensitive materials**

Physics-based feature engineering: MnPS₃

- Discovering physics in a “new” material MnPS₃
- Curve fitting to help enforce physical processes

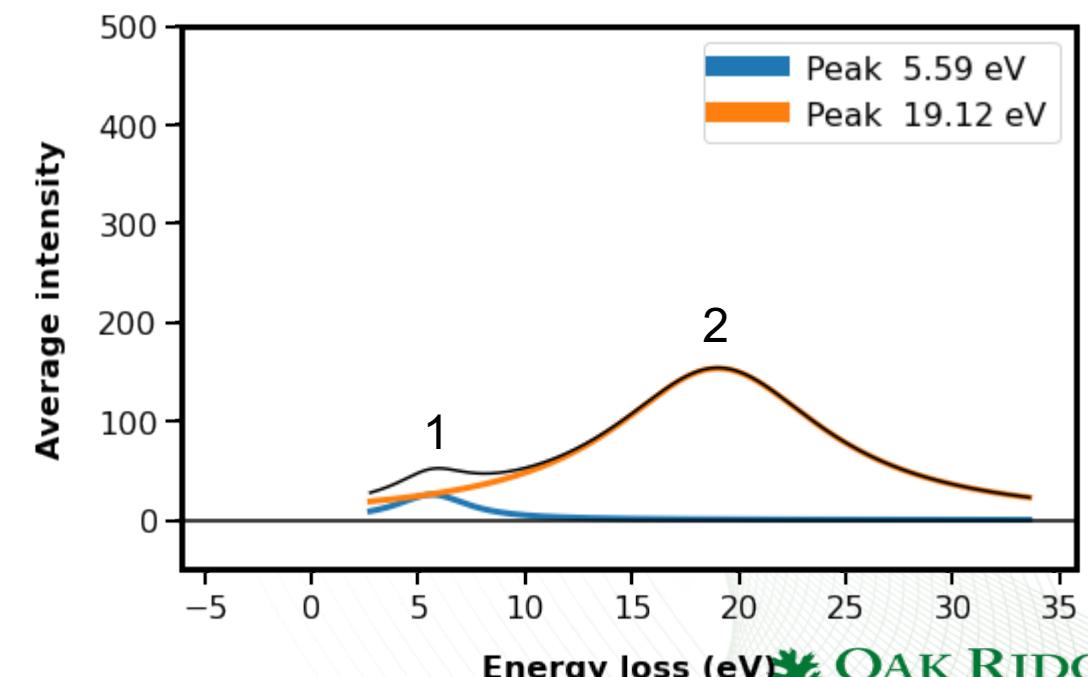
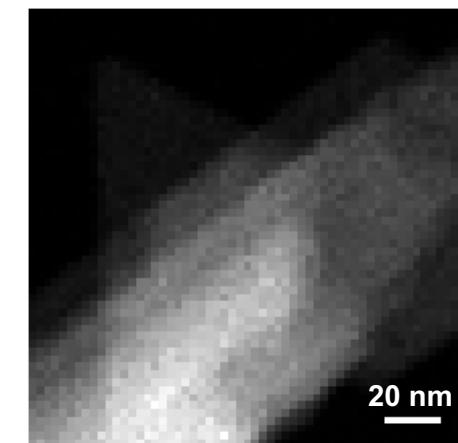
“Acquisition function”



HAADF-STEM

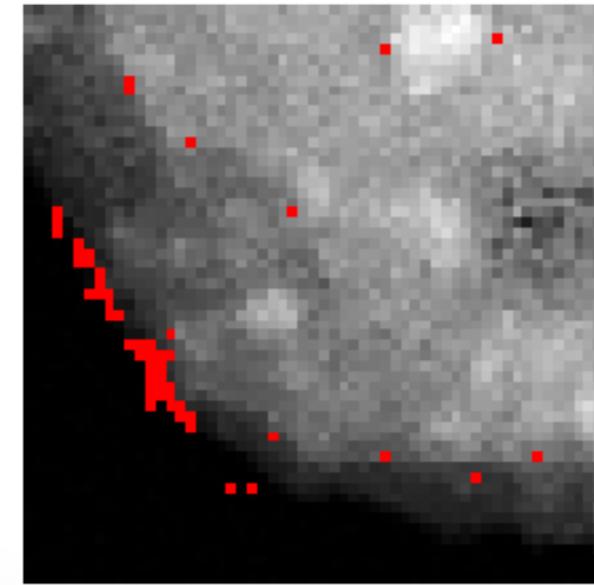
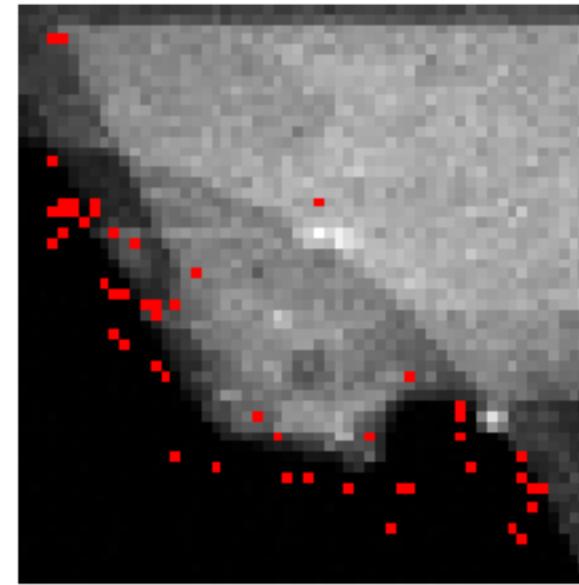
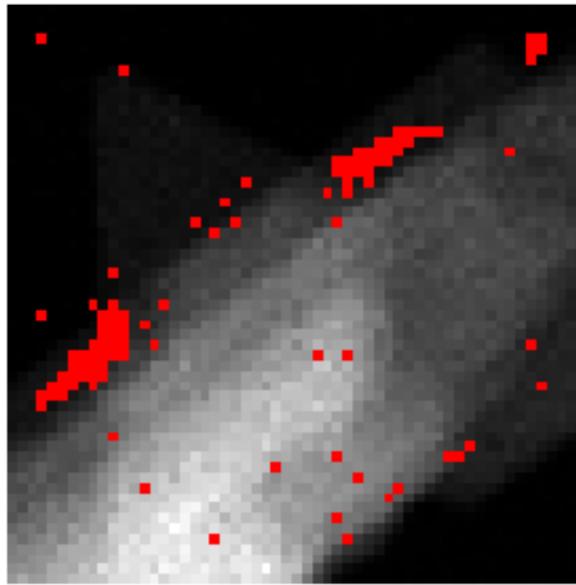
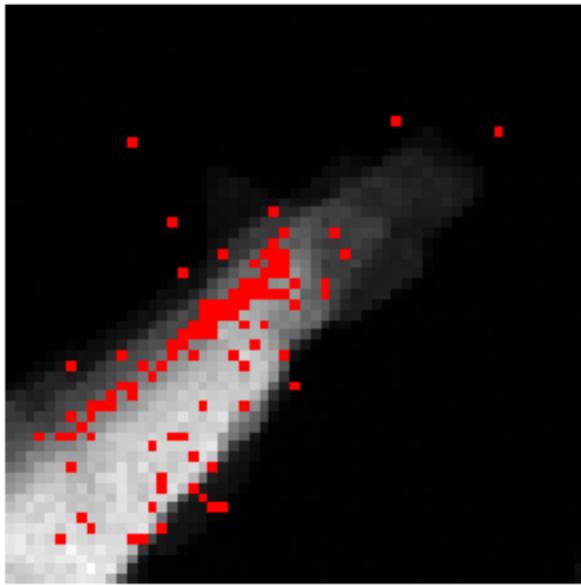
Physics search criteria:

$$\textit{Ratio} = \textit{Peak 1} / \textit{peak 2}$$



More examples of physics discovery

- Very similar behavior when searching for the same criteria!
- Success!

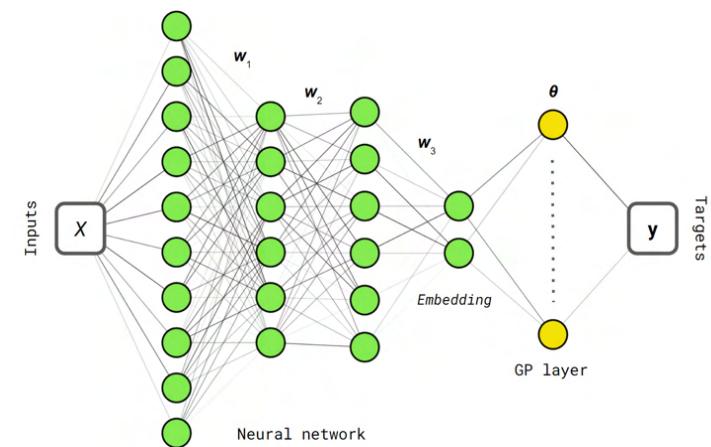


Automated Experiments in 4D STEM

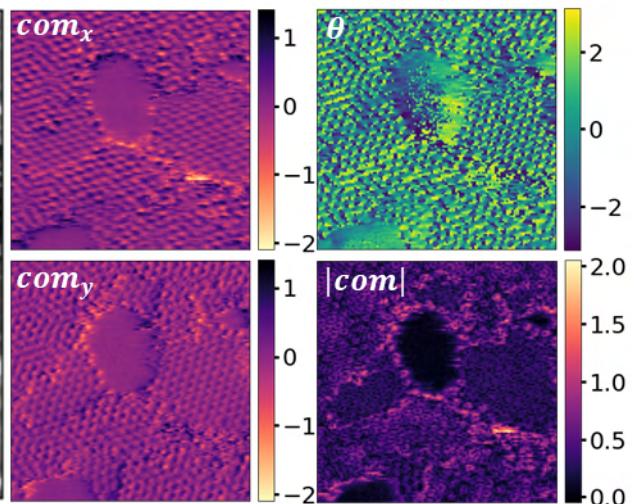
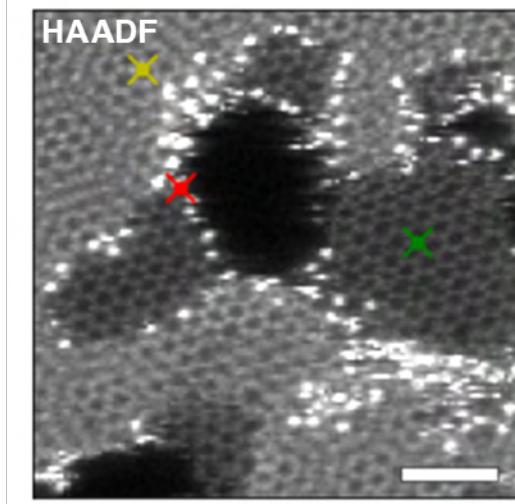
Quantities to explore

- Electric field
- Potential
- Charge density
- Strain

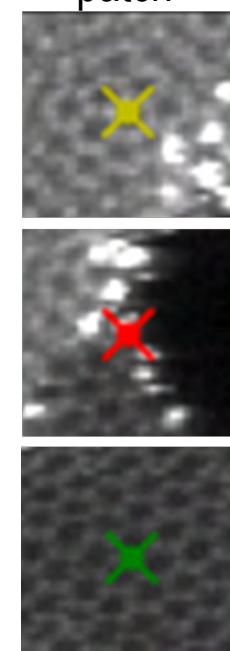
Choose explorable quantity



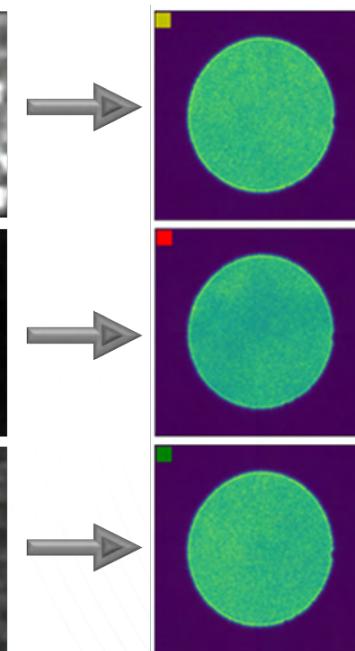
Traditional 4D STEM: graphene “DPC”



Local image patch



D.P.



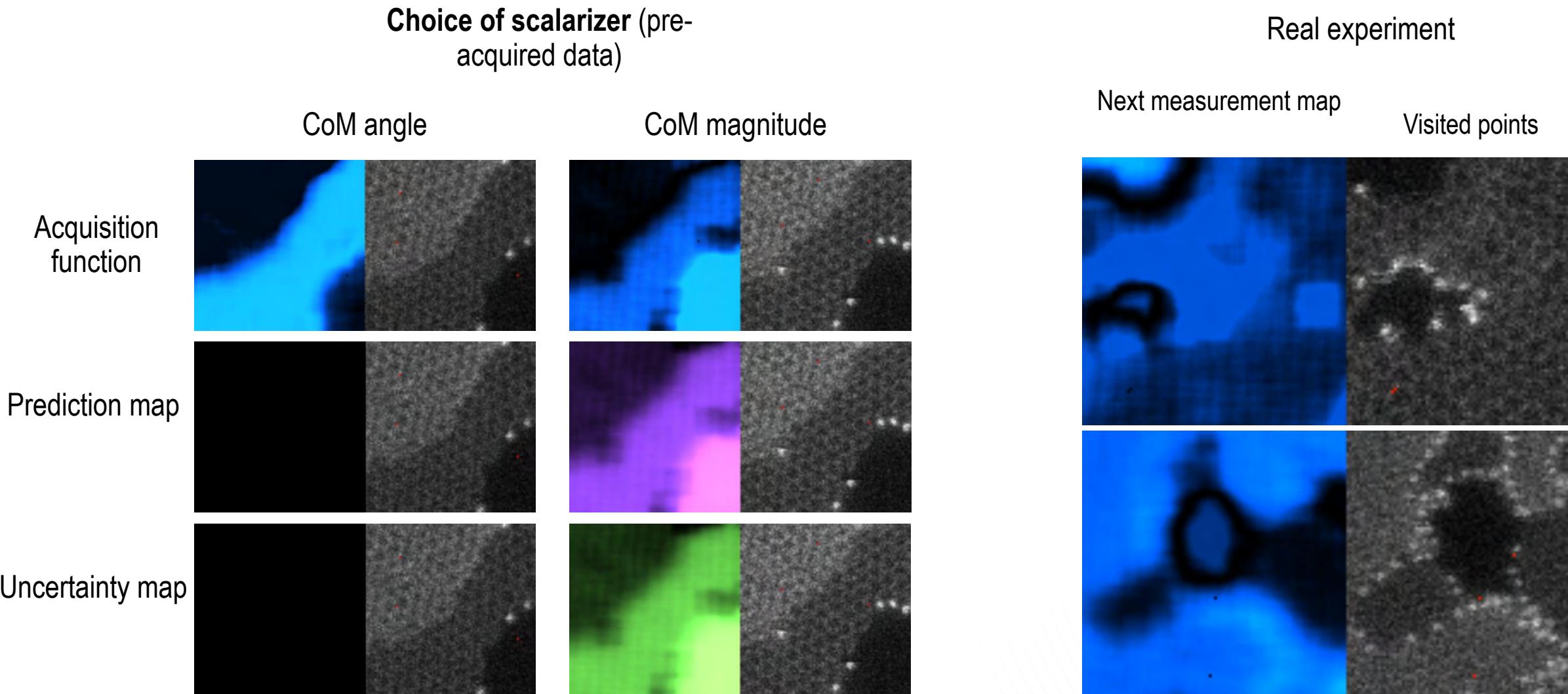
Scalarize
 $|com|$

1 px

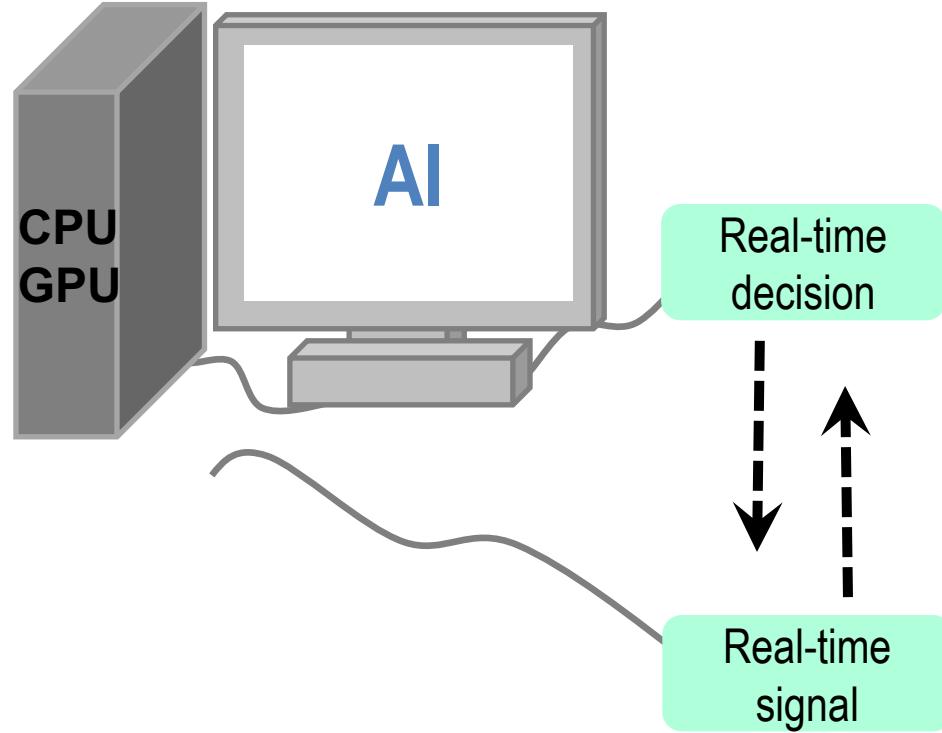
2 px

0.2 px

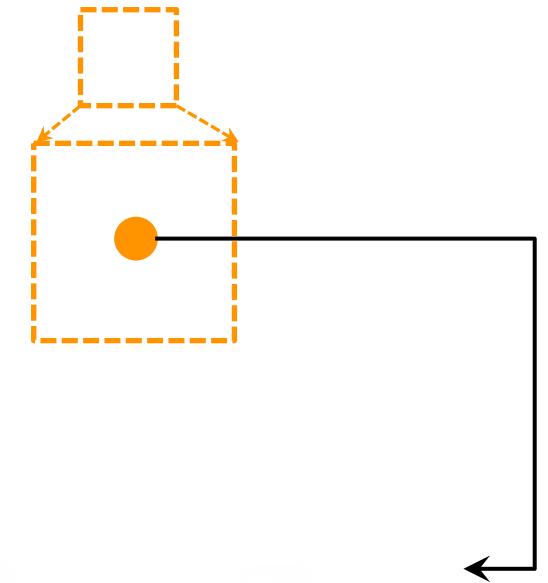
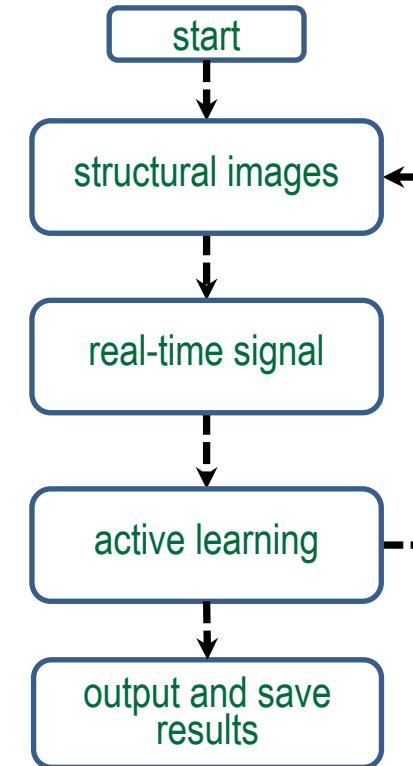
Automated Experiments in 4D STEM DPC example



Deep Kernel Learning for PFM

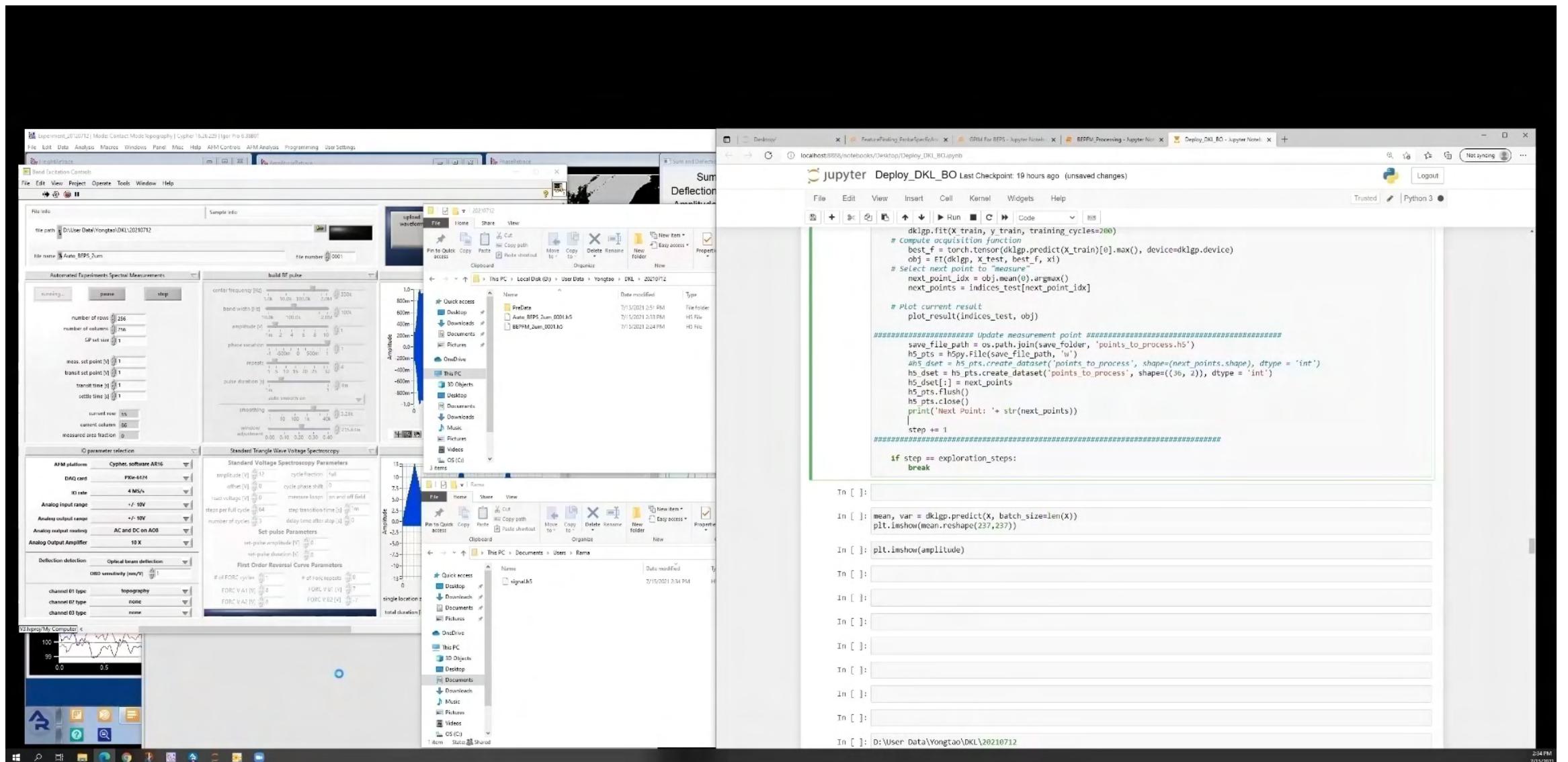


Active Learning

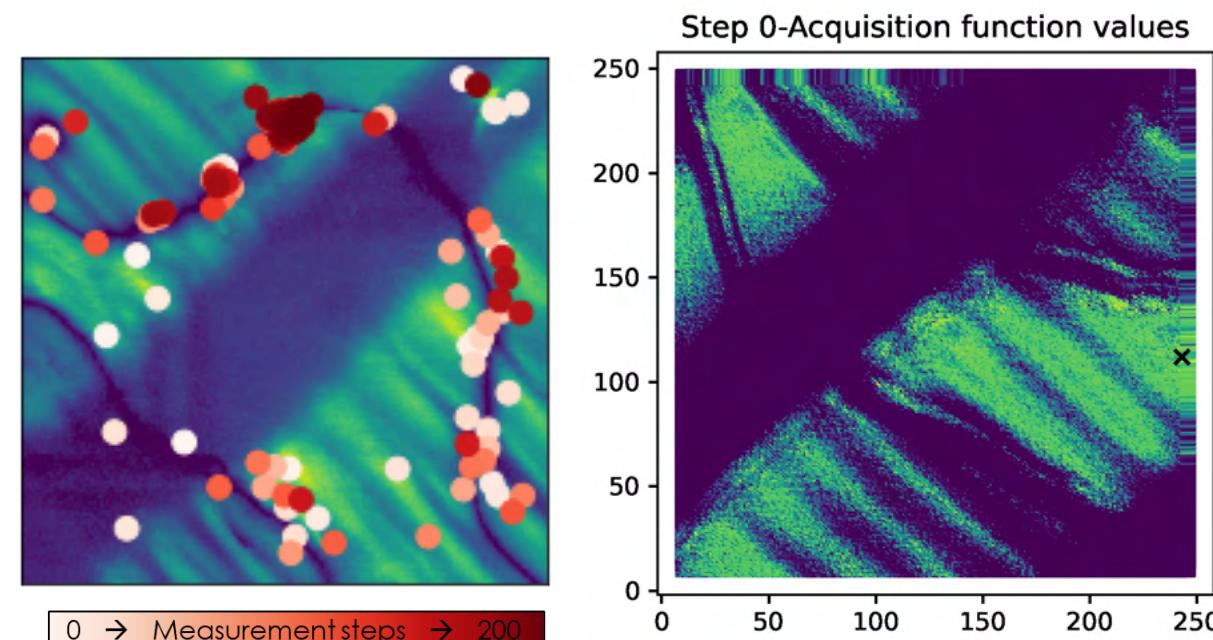


- (Deep Kernel Learning) Active learning of structure-property correlation.

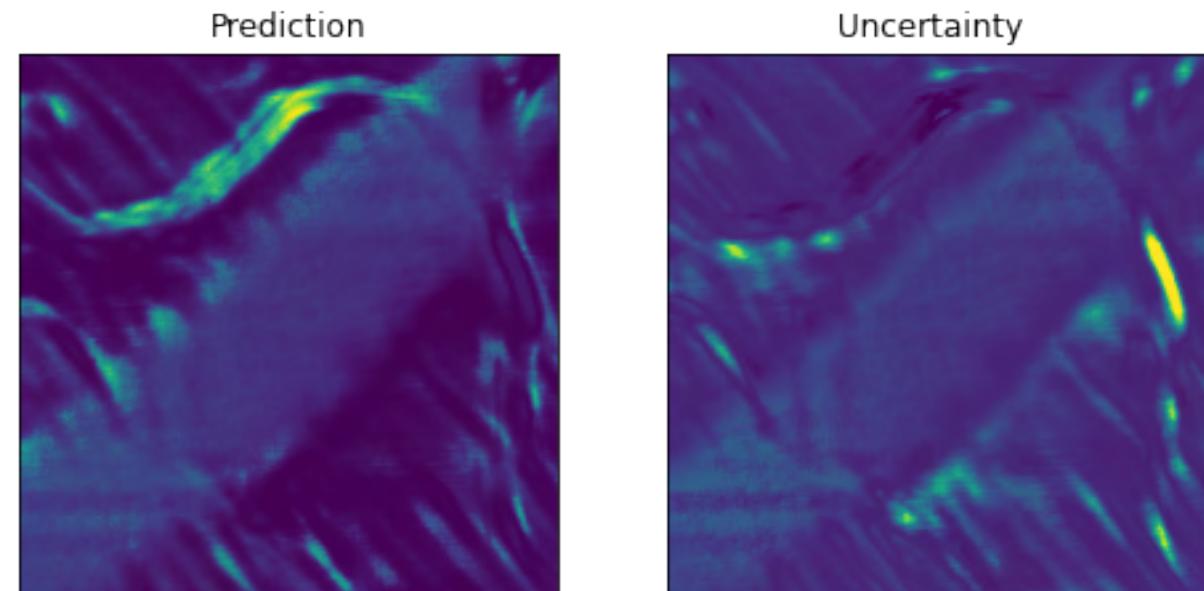
Deep Kernel Learning AE



Guided by: Off field loop area



Results: DKL predicted loop area map



- Large loop opening corresponding 180° domain walls probably due to the large polarization mobility of 180° walls.
- Future work: DKL-nonlinearity study of HZO; CIPS domain walls.

Automated Experiment:

... as a scientist...

Bayesian optimization:

1. Works only in low-dimensional spaces
2. The correlations are defined by the kernel function (very limiting)
3. We do not use any knowledge about physics of the system
4. We do not use cheap information available during the experiment (proxies)

GP Augmented with Structural model

Define a probabilistic model:

$$\mathbf{y} \sim MVNormal(\mathbf{m}, \mathbf{K})$$

$$K_{ij} = \sigma^2 \exp(0.5(x_i - x_j)^2 / l^2)$$

$$\sigma \sim LogNormal(0, s_1)$$

$$l \sim LogNormal(0, s_2)$$

Prediction on new data X_* :

$$\mathbf{f}_*^i \sim MVNormal\left(\mu_{\boldsymbol{\theta}^i}^{\text{post}}, \Sigma_{\boldsymbol{\theta}^i}^{\text{post}}\right)$$

$$\mu_{\boldsymbol{\theta}^i}^{\text{post}} = \mathbf{m}(X_*) + \mathbf{K}(X_*, X | \boldsymbol{\theta}^i) \mathbf{K}(X, X | \boldsymbol{\theta}^i)^{-1} (\mathbf{y} - \mathbf{m}(X)) \rightarrow \mu_{\boldsymbol{\Omega}^i}^{\text{post}} = \mathbf{m}(X_* | \phi^i) + \mathbf{K}(X_*, X | \boldsymbol{\theta}^i) \mathbf{K}(X, X | \boldsymbol{\theta}^i)^{-1} (\mathbf{y} - \mathbf{m}(X | \phi^i))$$

$$\Sigma_{\boldsymbol{\theta}^i}^{\text{post}} = \mathbf{K}(X_*, X_* | \boldsymbol{\theta}^i) - \mathbf{K}(X_*, X | \boldsymbol{\theta}^i) \mathbf{K}(X, X | \boldsymbol{\theta}^i)^{-1} \mathbf{K}(X, X_* | \boldsymbol{\theta}^i)$$

$\boldsymbol{\Omega}^i = \{\phi^i, \boldsymbol{\theta}^i\}$ is a single HMC posterior sample with the kernel and prob model parameters

GP Augmented with Structural model

Probabilistic model

$$m = y_0 - \sum_{n=1}^N L_n \quad (N=2)$$

$$y_0 \sim Uniform(-10, 10)$$

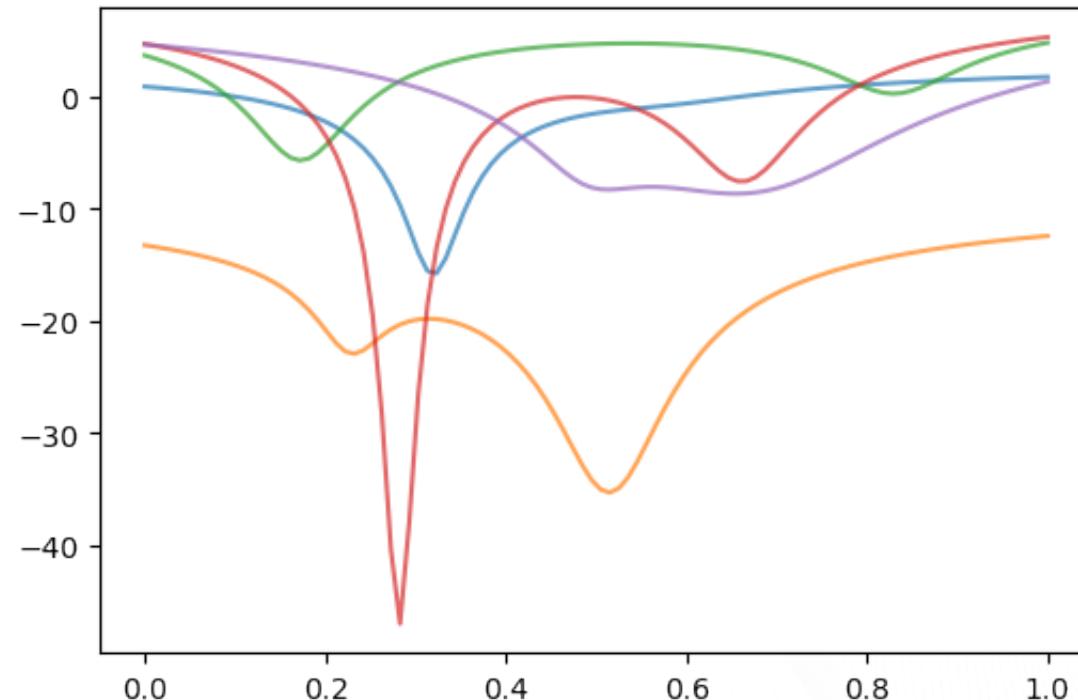
$$L_n \sim \frac{A_n}{\sqrt{(x-x_n^0)^2+w_n^2}}$$

$$A_n \sim LogNormal(0, 1)$$

$$w_n \sim HalfNormal(.1)$$

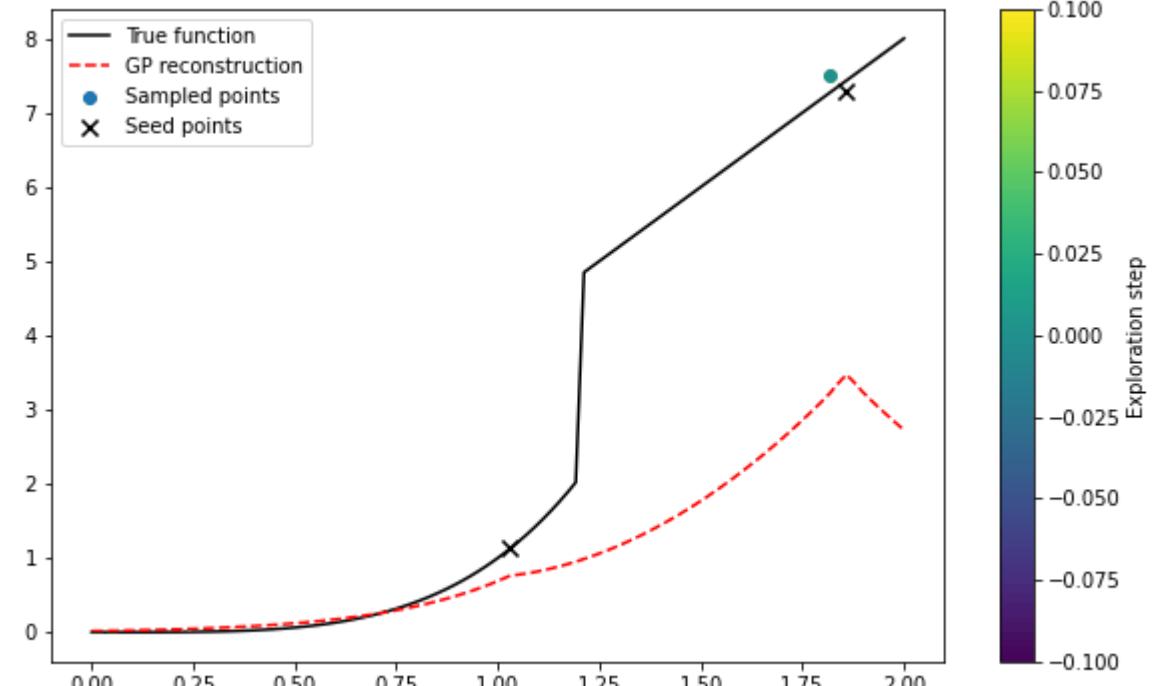
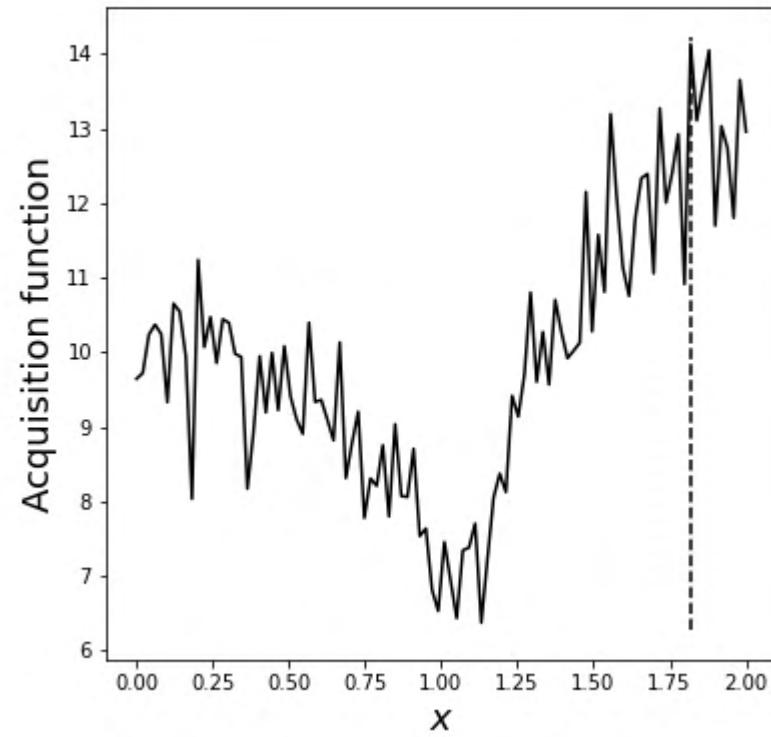
$$x_n^0 \sim Uniform(0, 1)$$

Prior predictive distribution

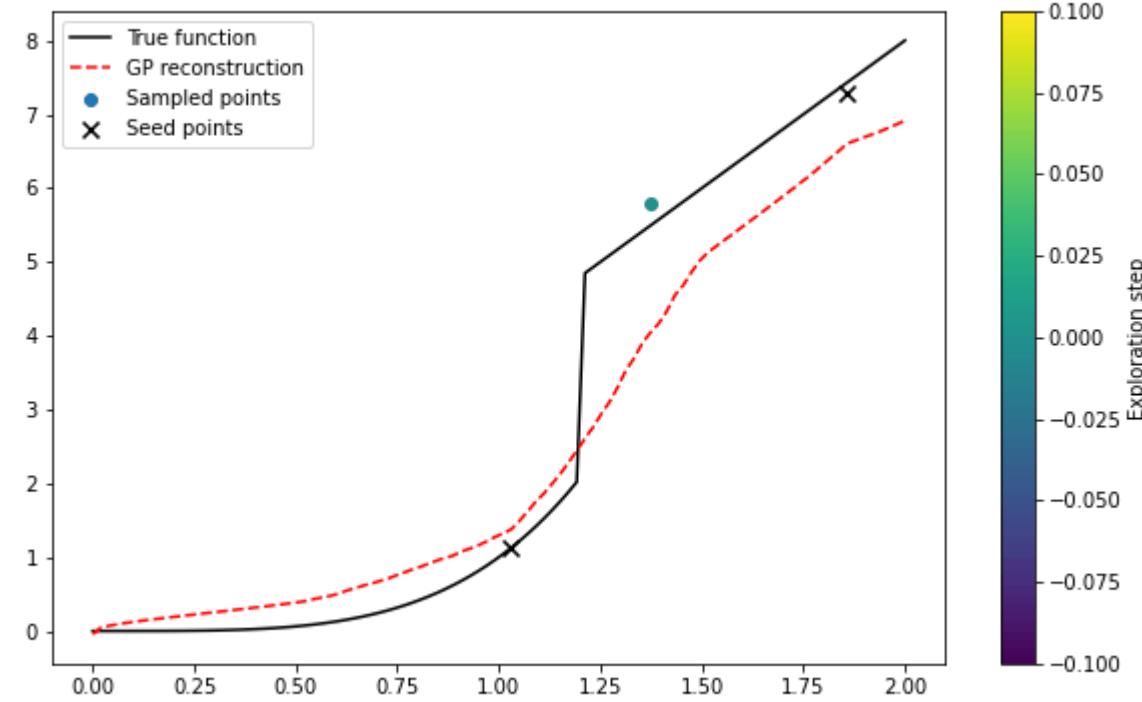
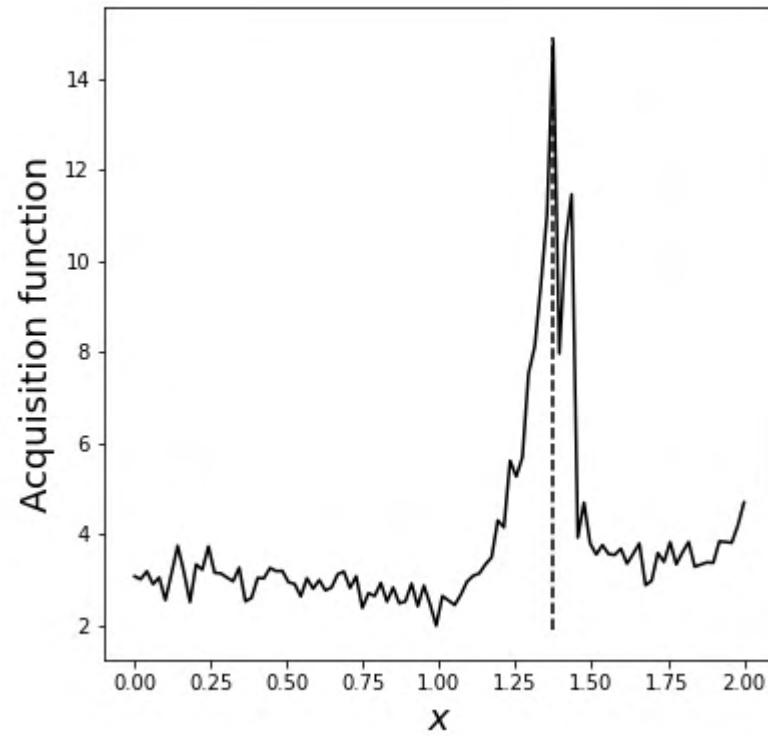


This model simply tells us that there are two minima in our data but does not assume to have any prior knowledge about their relative depth, width, or distance

Simple GP search



Structured GP search

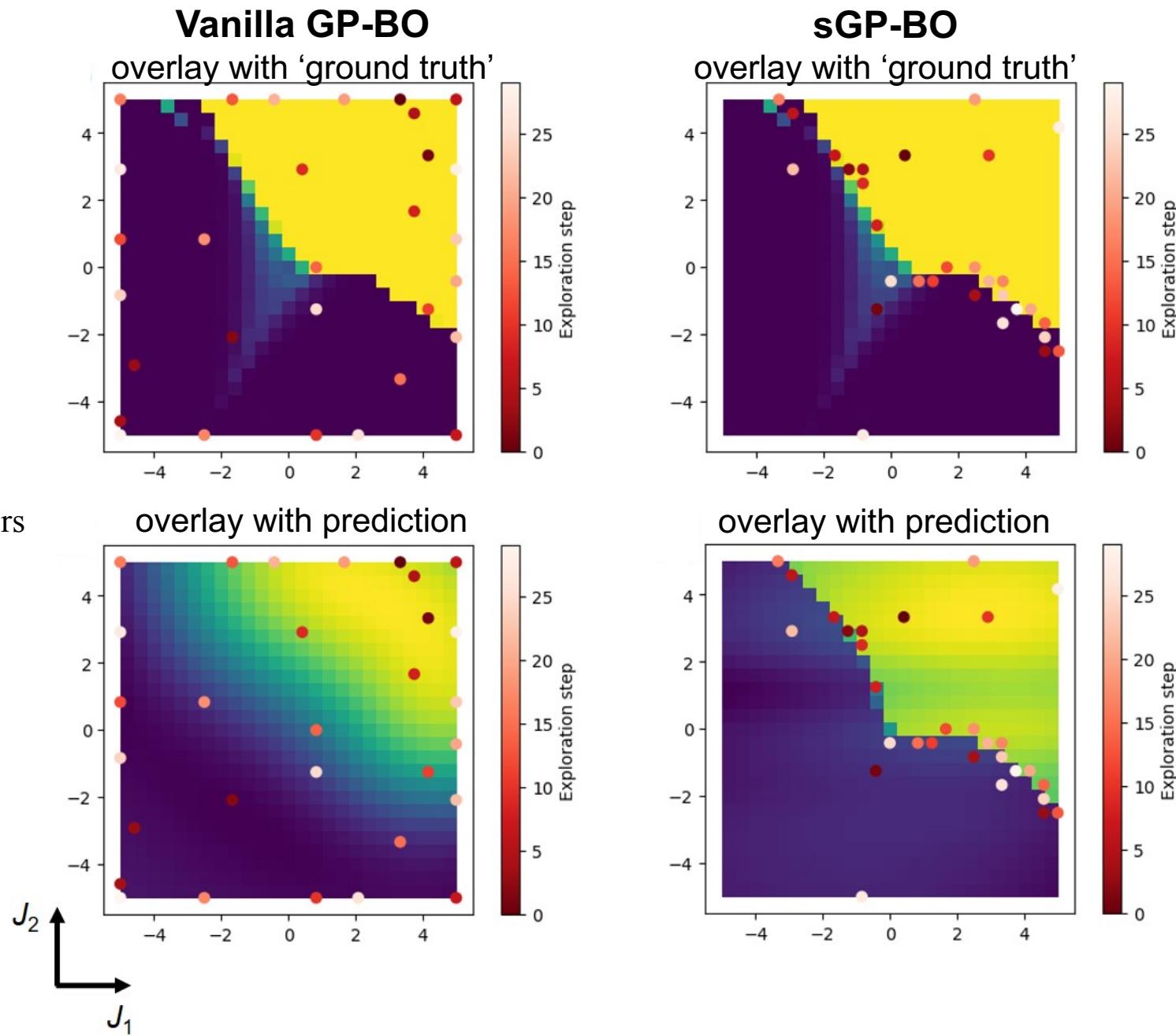


Application to Ising model

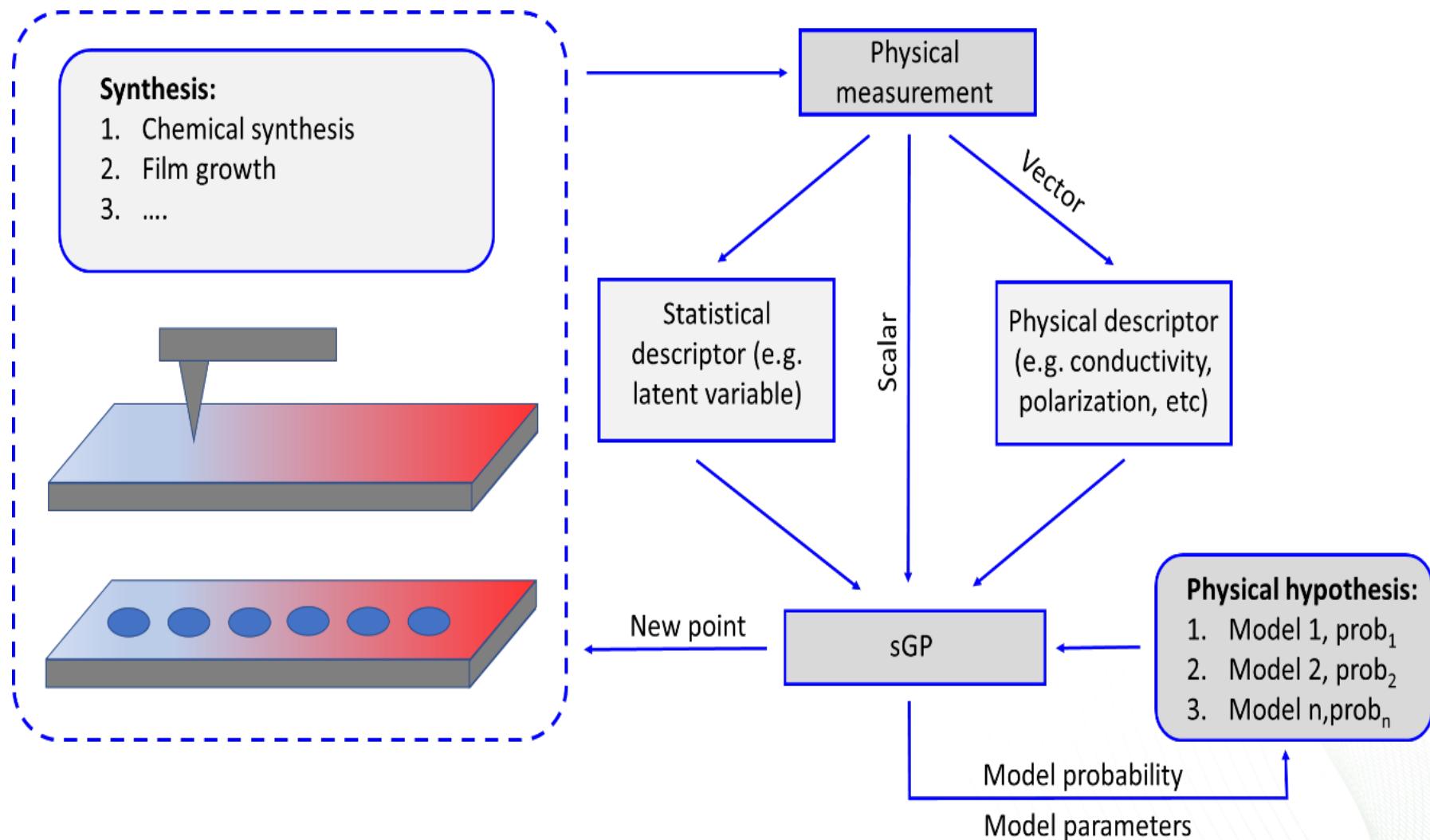
Probabilistic model

$$A/\tanh\left(\frac{f(J_1)+f(J_2)}{w}\right)$$

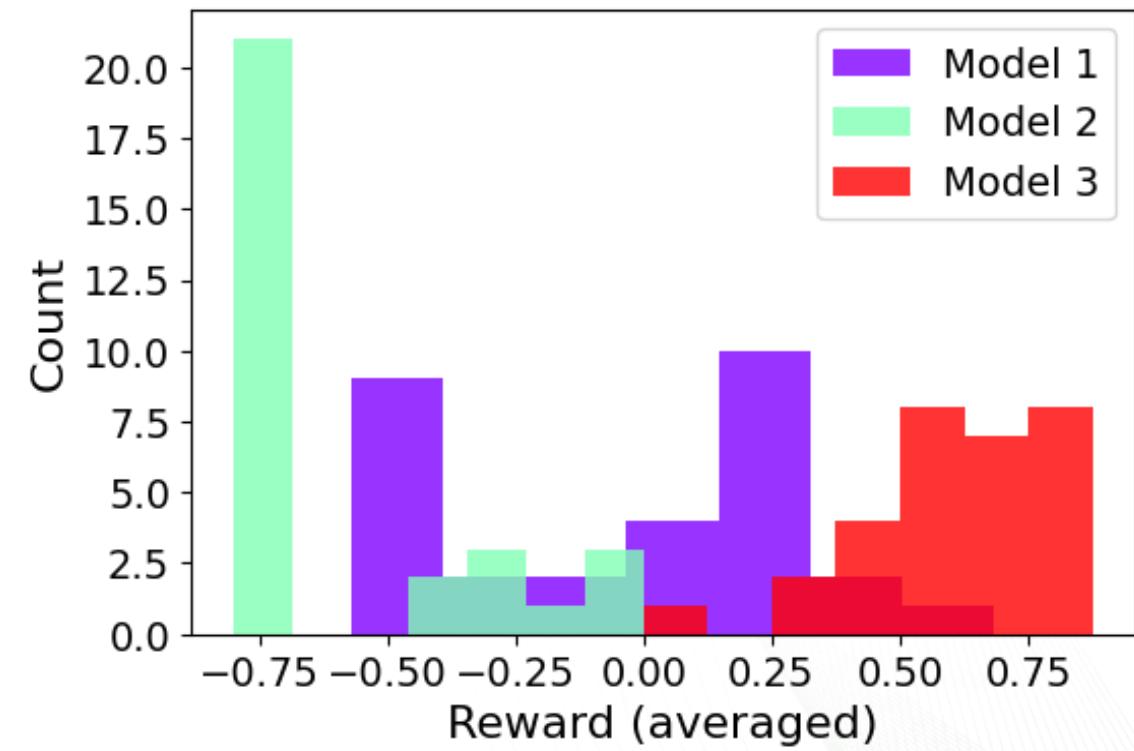
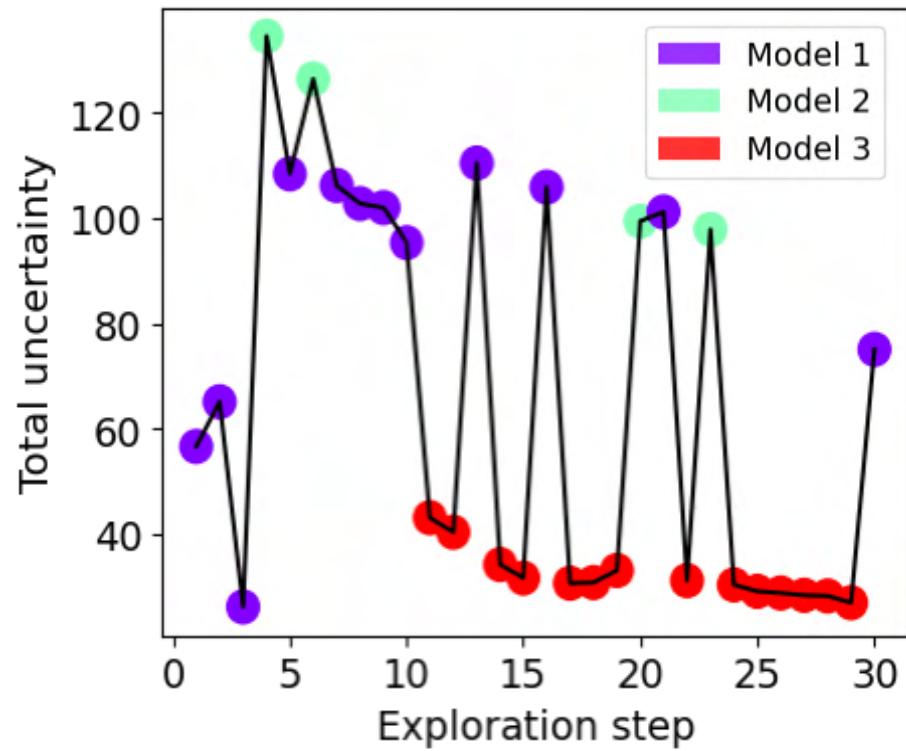
where $f(J)$ is a third-degree polynomial with normal priors on its parameters



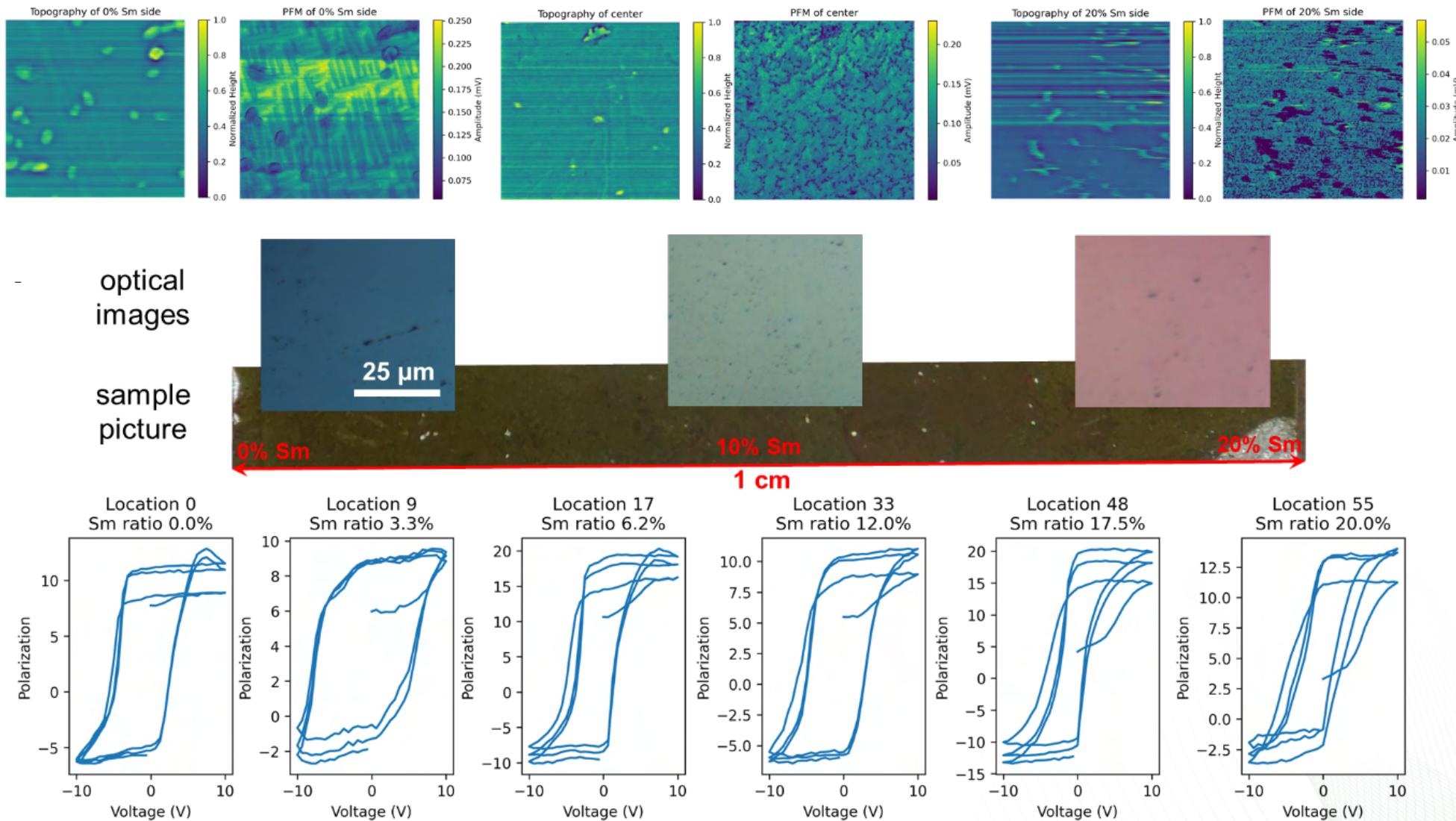
Hypothesis active learning: hypoAL



Next step: active model selection



Back to combinatorial libraries:



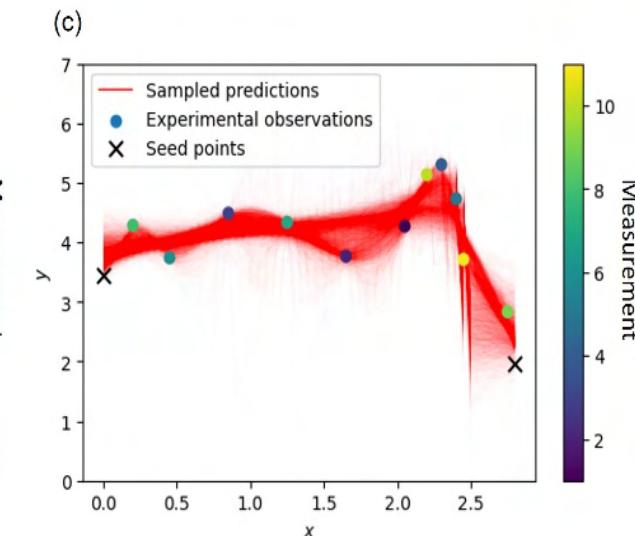
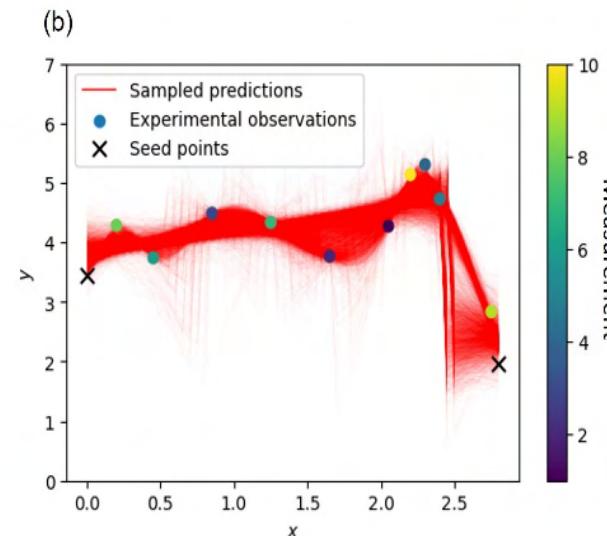
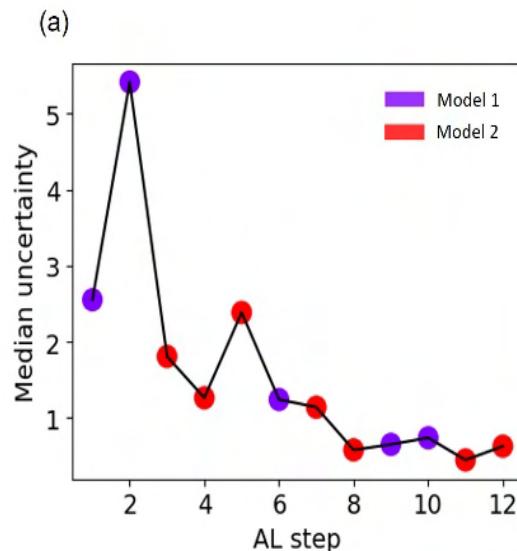
Hypothesis selection for ferroelectric response

Model 1 (second order phase transition):

$$S = \begin{cases} S_0 \left(1 - \frac{x}{x_0}\right)^2 + C, & x \leq x_c, \\ C, & x > x_c \end{cases}$$

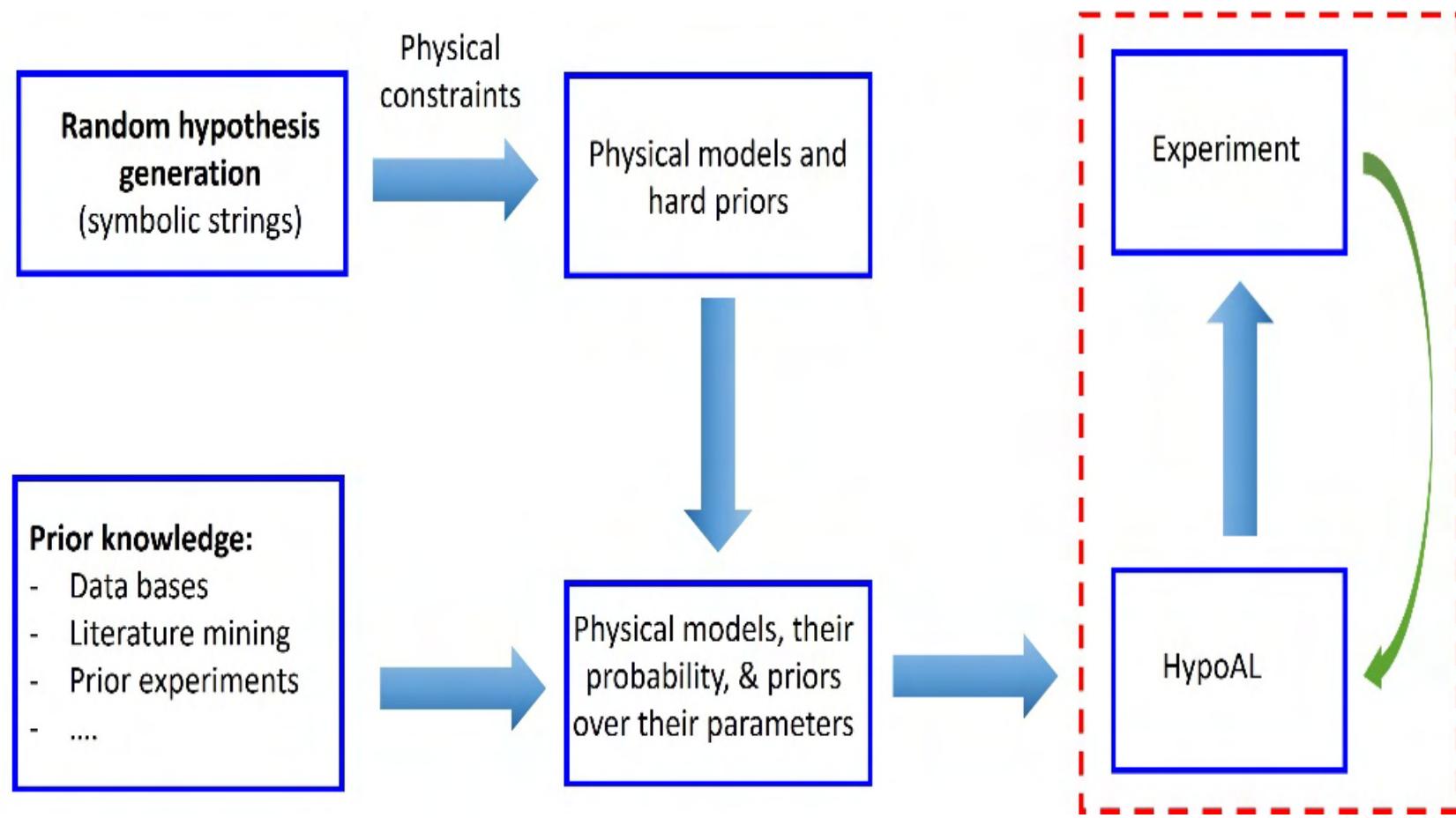
Model 2 (first order phase transition):

$$S = \begin{cases} S_0 \left(1 - \frac{x}{x_0}\right)^{\frac{5}{4}} + C_0, & x \leq x_c, \\ C_1, & x > x_c \end{cases}$$



Towards hypothesis learning

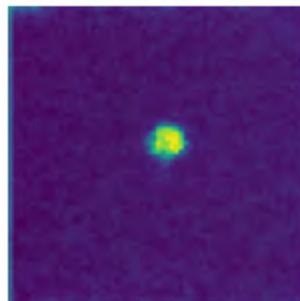
- Data already exists: Eureka, SISSO, SinDY, etc.
- What if we make hypothesis learning a part of active experiment?
- Need policies for hypothesis generation



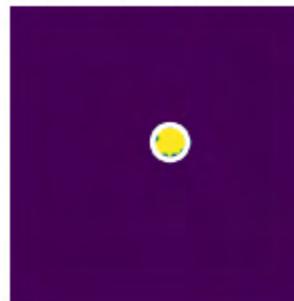
Hypothesis learning in experiment

Step 1, Random Write Parameters
Write Bias: -5.2V, Write Time: 0.428S

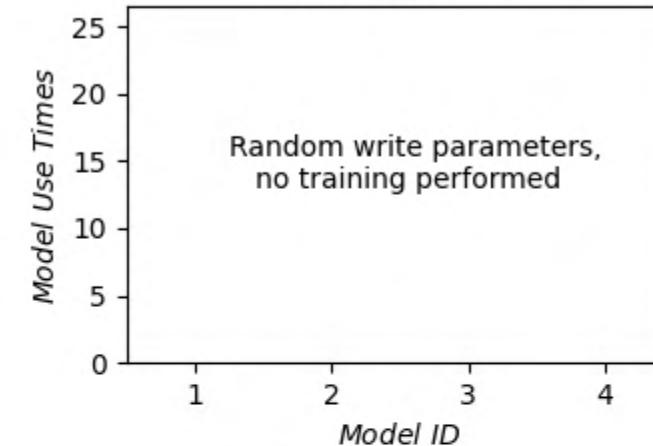
BEPFM Phase



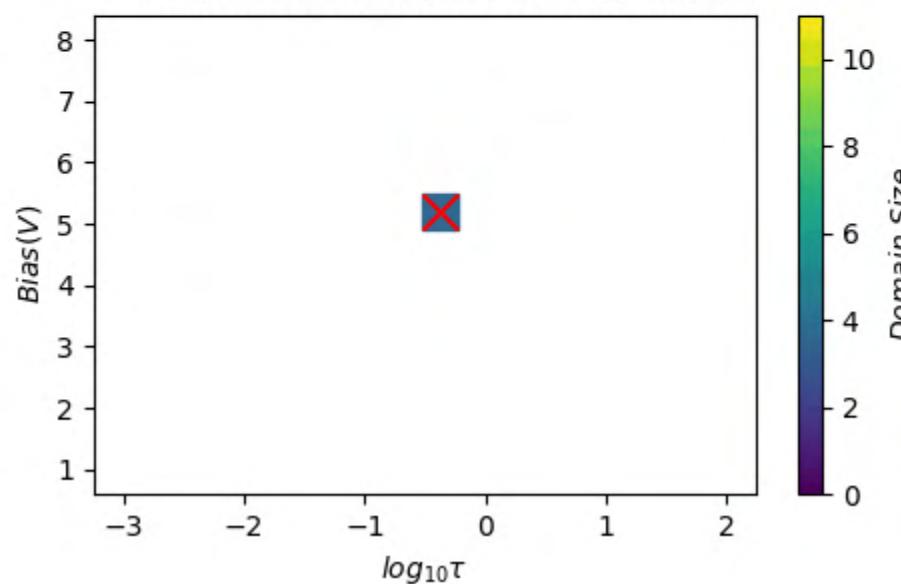
Domain Size: 3.79



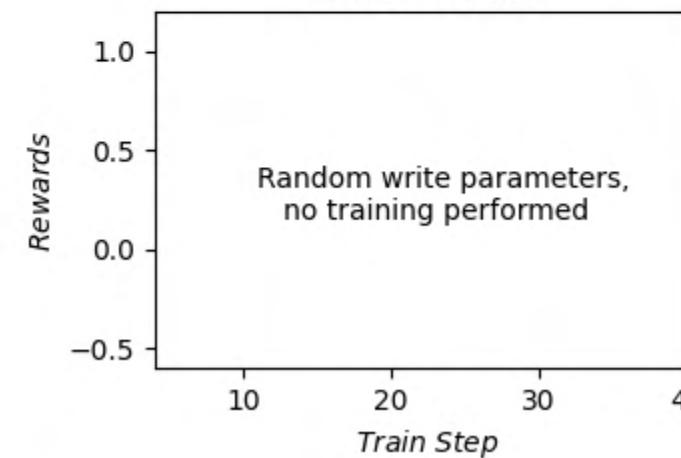
Model Selection



Domain size vs write bias and time



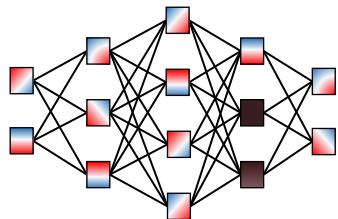
Model Reward



More than ML: Human in the Loop

Prior knowledge

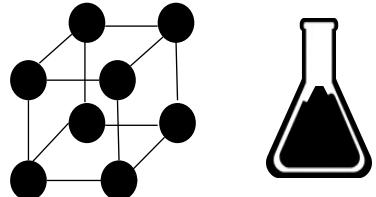
- Weights
- Inductive biases



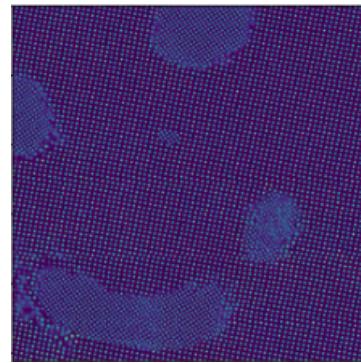
Reward Function



Material Parameters

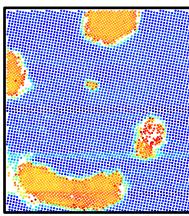


Human

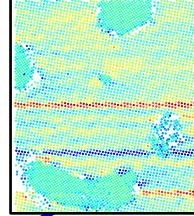
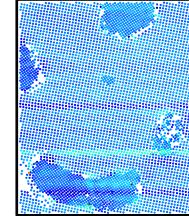


Experiment

Select analysis method



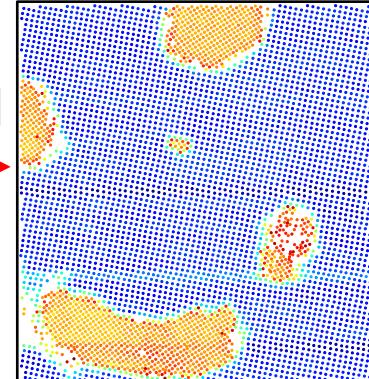
Select component



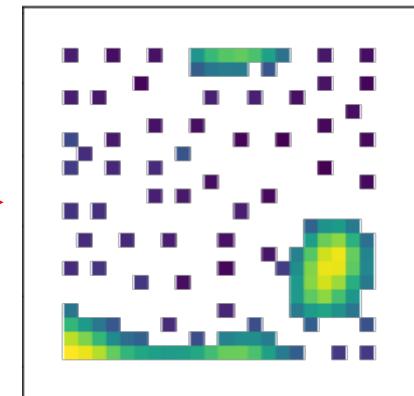
AI



DCNN

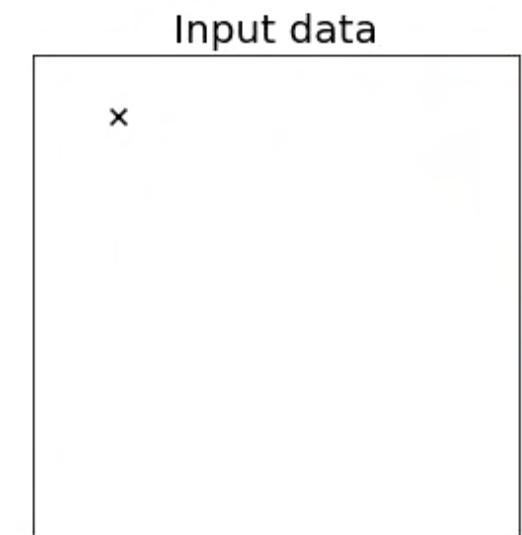
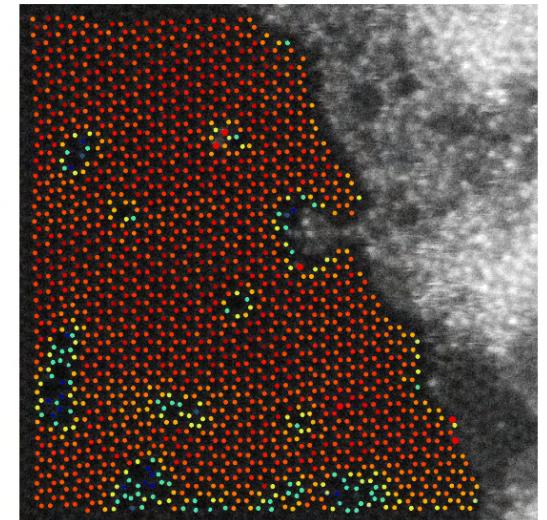


rVAE BO



What if I want to do it myself?

- **AtomAI**: comprehensive toolbox for DCNN-based supervised exploration of STEM and SPM Data:
- **PyroVED**: building structure-property correlations and unsupervised and semi-supervised physical discovery
- **GPim**: Gaussian processing toolbox for image analytics and automated experiment
- **gpax**: hypothesis-driven structured Gaussian Processes
- **PyCroscopy**: General data formats, workflows, and image analytics



YouTube: M*N: Microscopy, Machine Learning, Materials

Medium: <https://ziatdinovmax.medium.com/>

Concluding:

- **Machine learning is great, but**
 - Requires domain expertise
 - Ease of use for deployment
 - Some ML knowledge
- **Microscope is a laboratory:**
 - Engineering controls
 - Algorithms
 - Connection to domain expertise

Sergei V. Kalinin
sergei2@ornl.gov



Connect!

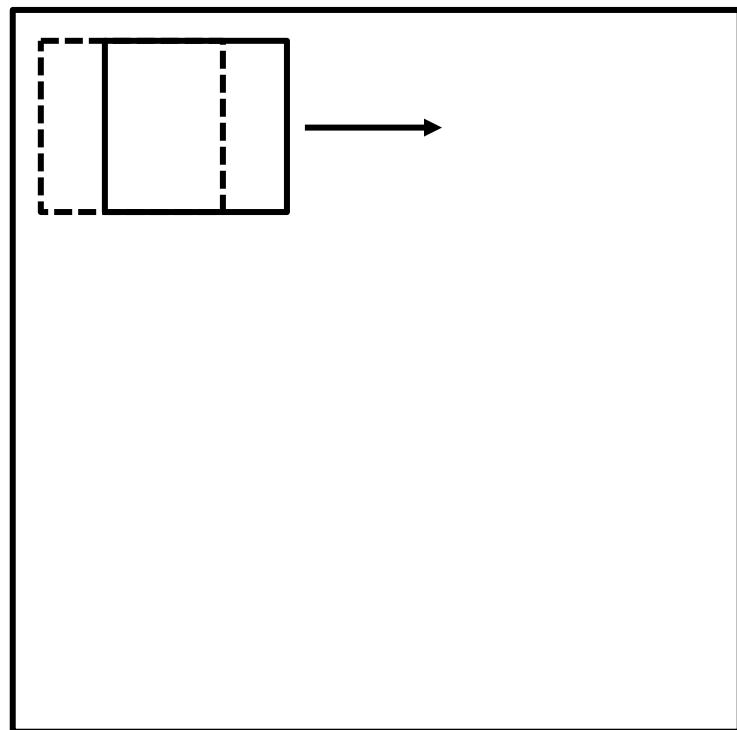


YouTube

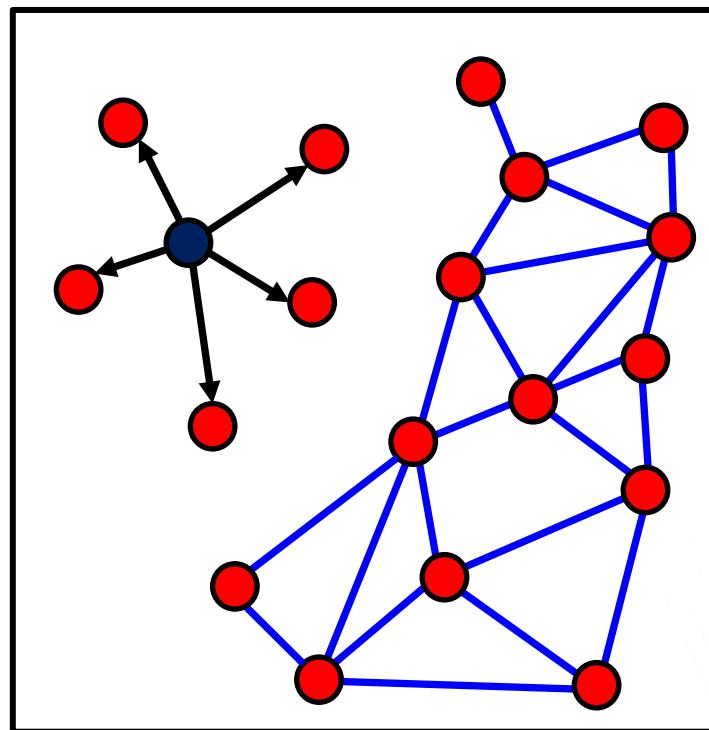
Describing the building blocks

- The classical physical descriptions (symmetry, etc) can be defined locally only in Bayesian sense
- We can argue that local descriptors are simple, if not necessarily known
- And the rules that guide their emergence are also simple, if not known

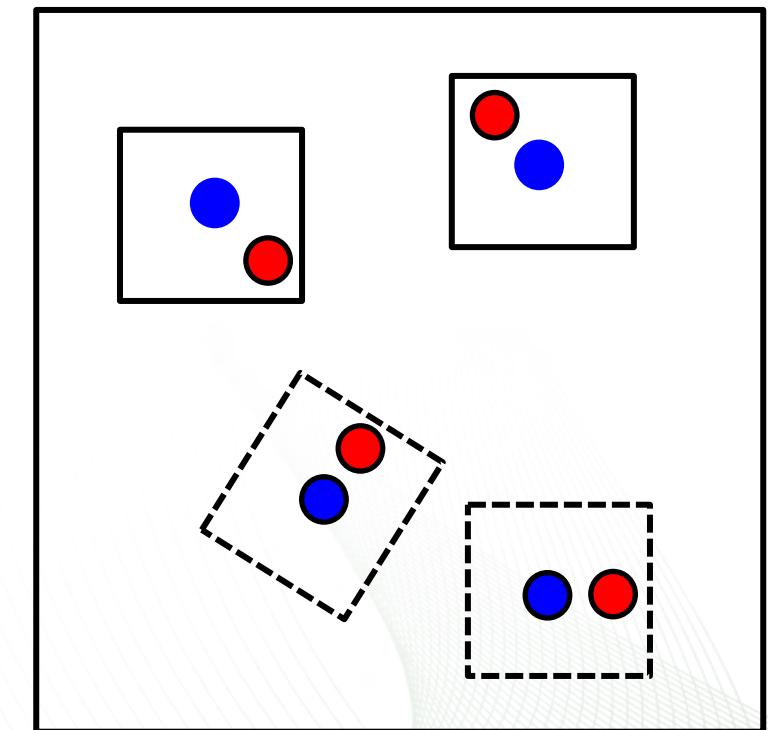
Continuous translational symmetry

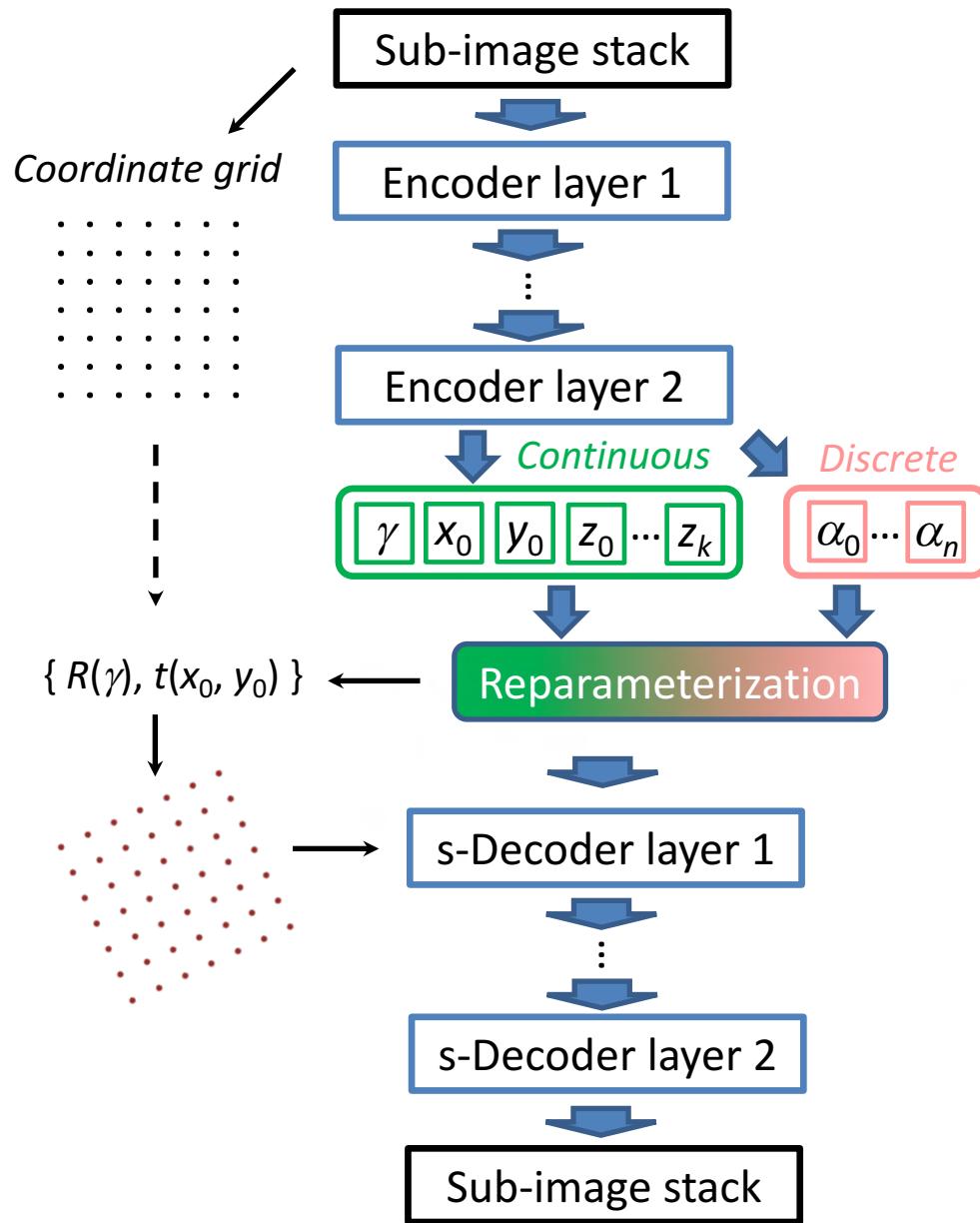


Atom based descriptions



Localized sub-images





- Generative model is a function of spatial coordinate (e.g., via spatial broadcasting)
- 3 additional latent variables to absorb rotations and shifts
- Disentangles rotations and translations from image content
- Learns discrete classes in unsupervised fashion
- Well-suited for analyzing microscopy (sub-)images on atomic and molecular levels

ELBO =

$$\begin{aligned}
 & - \text{Reconstruction Loss} \\
 & - \beta_c(t) |(D_{KL}(q(z|x) \parallel p(z)) + D_{KL}(q(\gamma|x) \parallel p(\gamma)) - C_z| \quad \text{Continuous} \\
 & - \beta_d(t) |D_{KL}(q(\alpha|x) \parallel p(\alpha)) - C_\alpha| \quad \text{Discrete} \\
 & + \text{physics-based "loss" ?}
 \end{aligned}$$

Theory in the loop



- Theory provides a “map” of the physical phenomena with the level of detail dependent on complexity and veracity of the theory. However, unless the map is very good, we cannot drive by the map
- Experiment gives us immediate feedback, but it may be unclear which direction to choose
- Theory experiment matching allows to combine general direction and local details
- We aim to implement automated experiment, both fully correlative (self-driving car), and model based (theory “map” is updated when driving)

Enter the Scientific Workflows

"One of the things that is not understood at all by the conventional forces in society, if you will, is that America benefits enormously from these global platforms—global platforms that are built in America, whether it's the Internet itself, email, Android, the iPhone, et cetera."

Schmidt says. If a company, or indeed a country, controlled the platform, it controlled what ran on top of it. A creation like Google's TensorFlow was the latest example.

"It's a global platform competition, and it is extremely important that the platforms be invented in America. Platforms establish a base by which innovation occurs in the future."

"One of the most surprising and important stories of our time."
—Ashlee Vance, author of *Elon Musk*

Genius Makers



The Mavericks Who Brought AI
to Google, Facebook, and the World

CADE METZ

What do we hope to achieve?

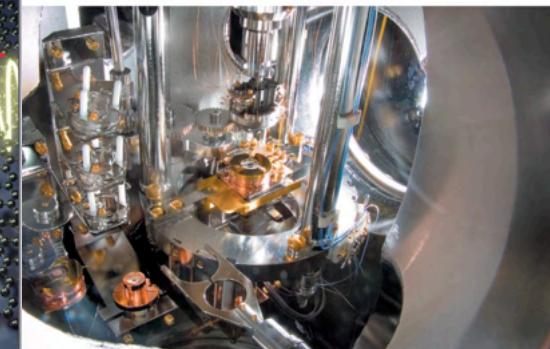
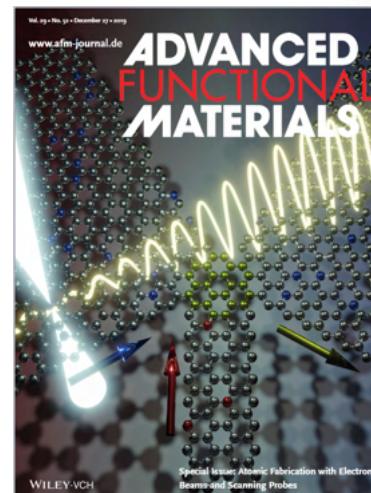
Microscopy today:

- Primary component of research in materials science, physics and biology
- 1000s of high-end (S)TEM platforms, ~10,000 overall
- 1000s of high-end UHV SPMs, >50,000 ambient
- Chemical and mass-spectrometric imaging

What do microscopists do?

- Most of the time - sit alone in the dark room and turn knobs 😊
- Limited amount of collected data
- Case for automation: CryoEM

Unsurprisingly, inspired by autonomous cars, etc. – multiple proposals to make automated microscopes!



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TECHNOLOGY FEATURE THE ATOMIC-FORCE REVOLUTION

Atomic force microscopy is revealing molecular structures with startling clarity. Artificial intelligence and automation could expand its potential.

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