



STAT 215A Fall 2017

Week 9

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10/20/2017



The Expectation-Maximization (EM) algorithm





The intuition behind the EM algorithm

The Expectation-Maximization algorithm

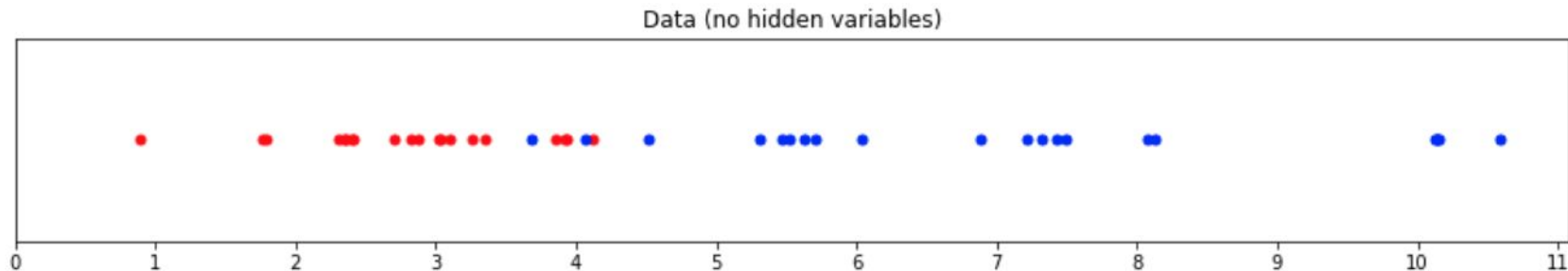
The material for this section came from this discussion on Stack Overflow (primarily the first answer by Alex Riley):

<https://stackoverflow.com/questions/11808074/what-is-an-intuitive-explanation-of-the-expectation-maximization-technique>

The Expectation-Maximization algorithm

Suppose that we have some data sampled from a mixture of two Gaussians

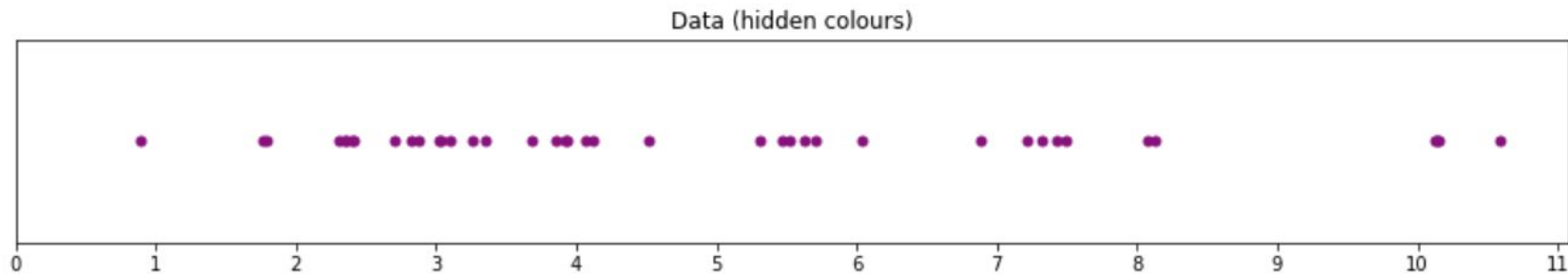
We want to know the mean and standard deviation of these Gaussians



The Expectation-Maximization algorithm

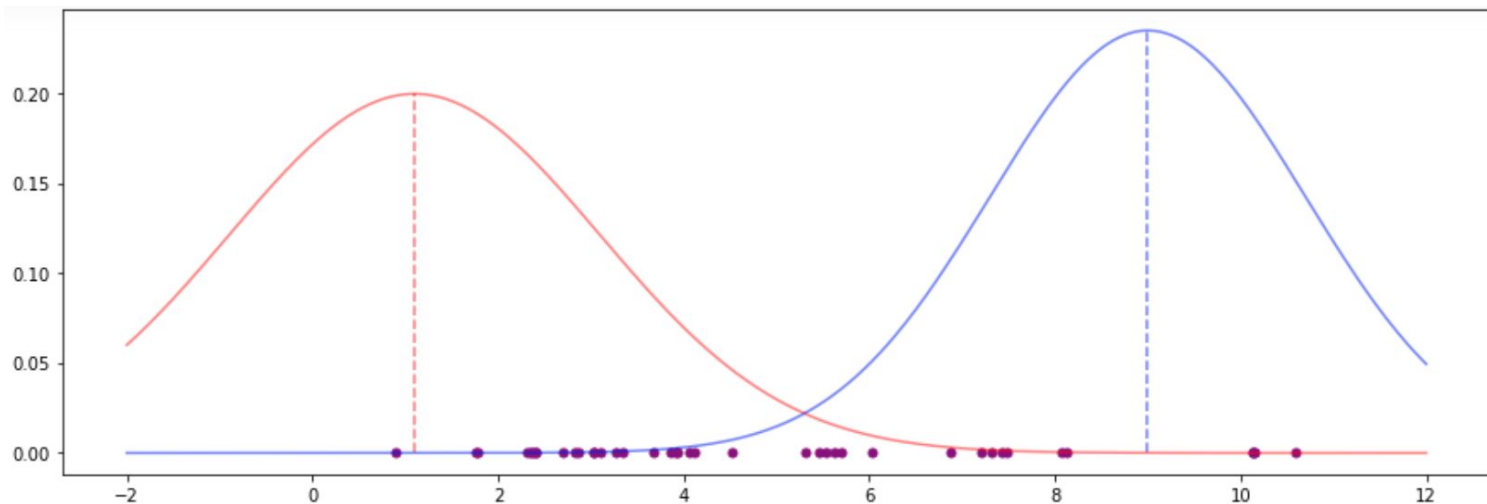
The problem: we don't actually know which data point came from which Gaussian.

If we knew that the problem would be easy!



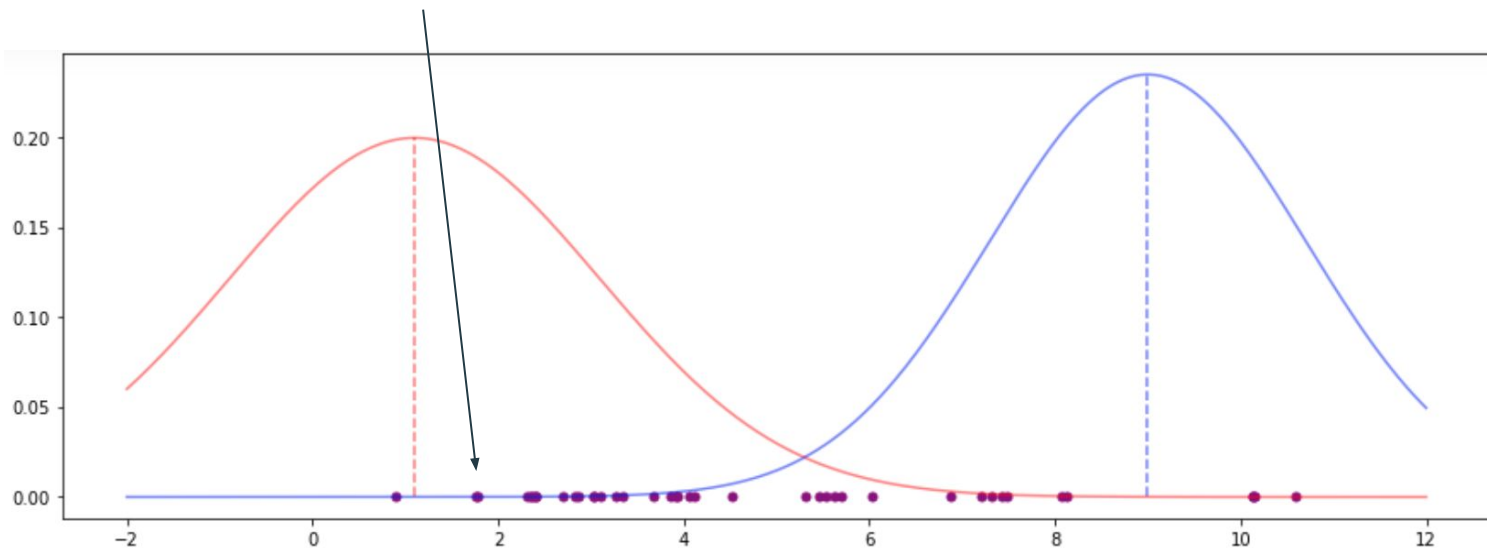
The Expectation-Maximization algorithm

1. Start with initial estimates of the mean and standard deviation for each Gaussian



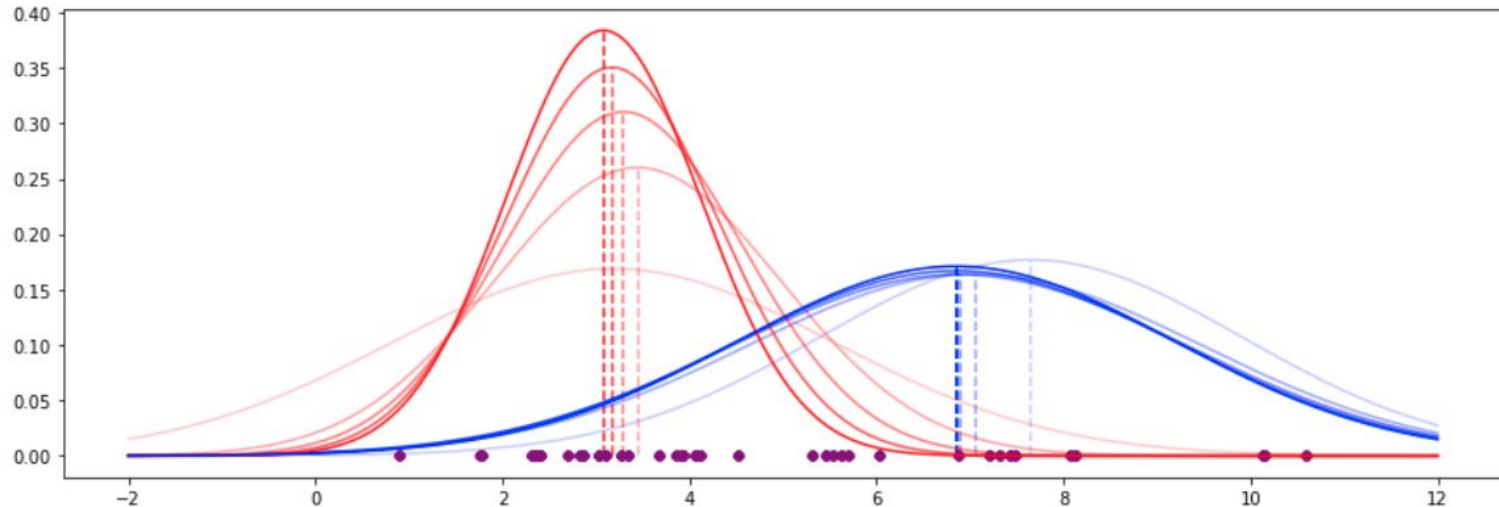
The Expectation-Maximization algorithm


2. Compute the likelihood of each data point appearing under the current parameter guesses (using the density for each estimated Gaussian)
 - the data point at 1.761 is more likely to be red ($p=0.189$) than blue ($p=0.00003$)




The Expectation-Maximization algorithm

3. Turn these two likelihood values into weights so that they sum to 1
4. Use these weights to re-estimate the mean and SD for each Gaussian
5. Repeat stages 2-4





The mathematical formulation of the EM algorithm



The Expectation-Maximization algorithm

The material for this section came from the following summary paper (by Alexis Roche 2003):

<https://arxiv.org/pdf/1105.1476.pdf>

The Expectation-Maximization algorithm

EM is a general theory for calculating maximum likelihood estimates (**MLE**)

Let Y be a random variable with density $p(y|\theta)$

- θ is an unknown parameter vector

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$$p(y|\theta) \text{ wrt } \theta$$

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Except in basic situations, there is no closed form solution to this problem.

EM provides a numerical approximation to the MLE.

The Expectation-Maximization algorithm

EM is a likelihood maximizer.

It iteratively maximizes successive local approximations of the likelihood function.

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There are two steps:

1. The **E-step**: approximate the likelihood function
2. The **M-step**: maximize this approximation with respect to θ

The Expectation-Maximization algorithm

In EM, we have a “latent” variable, Z , whose density depends on θ

In a mixture model, we assume that we first sample z and then we sample the observables y from a distribution that depends on z :

$$p(z, y|\theta) = p(z|\theta)p(y|z)$$

EM as a consequence of Jensen's inequality

Let's define $L(\theta) \equiv \log p(y|\theta)$

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$$L(\theta) - L(\theta') = \log \frac{p(y|\theta)}{p(y|\theta')} \quad (\text{by definition of } L)$$

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$$= \log \int \frac{p(z, y|\theta)}{p(y|\theta')} dz \quad (\text{since the marginal density of } y \text{ is the integral of the joint density of } z \text{ and } y)$$

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EM as a consequence of Jensen's inequality

$$L(\theta) - L(\theta') \geq \underbrace{\int \log \frac{p(z|\theta)}{p(z|\theta')} p(z|y, \theta') dz}_{\text{Call this } Q(\theta, \theta')}$$

$Q(\theta, \theta')$ is thus an auxiliary function for the log-likelihood $L(\theta)$ in that

1. The increase in likelihood when moving from θ to θ' is always greater than $Q(\theta, \theta')$
2. $Q(\theta', \theta') = 0$

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Iterating such a process defines the EM algorithm

EM as a consequence of Jensen's inequality

$$L(\theta) \equiv \log p(y|\theta)$$

$$Q(\theta, \theta') \equiv \int \log \frac{p(z|\theta)}{p(z|\theta')} p(z|y, \theta') dz$$

Using EM, we will maximize $Q(\theta^{t+1}, \theta^t)$ instead of the difference in likelihood functions $L(\theta^{t+1}) - L(\theta^t)$

EM as expectation-maximization

We can decompose Q into the following difference:

$$Q(\theta, \theta') = Q(\theta|\theta') - Q(\theta'|\theta')$$

where

$$Q(\theta|\theta') \equiv \int \log p(z|\theta) p(z|y, \theta') dx \equiv \mathbb{E}[\log p(Z|\theta)|y, \theta']$$

EM as expectation-maximization

We can decompose Q into the following difference:

$$Q(\theta, \theta') = Q(\theta | \theta') - Q(\theta' | \theta')$$

where

$$Q(\theta | \theta') \equiv \int \log p(z | \theta) p(z | y, \theta') dx \equiv E[\log p(Z | \theta) | y, \theta']$$

For a fixed θ' :

Maximizing $Q(\theta, \theta')$ wrt θ is equivalent to maximizing $Q(\theta | \theta')$

(i.e. we can ignore the second term in the equation above)

EM as expectation-maximization



Given a current parameter estimate θ_n

E-step: form the auxiliary function $Q(\theta|\theta_n)$ which involves computing the posterior distribution of the unobserved variable

$$Q(\theta|\theta_n) \equiv \int \log p(z|\theta) p(z|y, \theta_n) dx \equiv E[\log p(Z|\theta)|y, \theta_n]$$

M-step: update the parameter estimate by maximizing the auxiliary function

$$\theta_{n+1} = \arg \max_{\theta} Q(\theta|\theta_n)$$

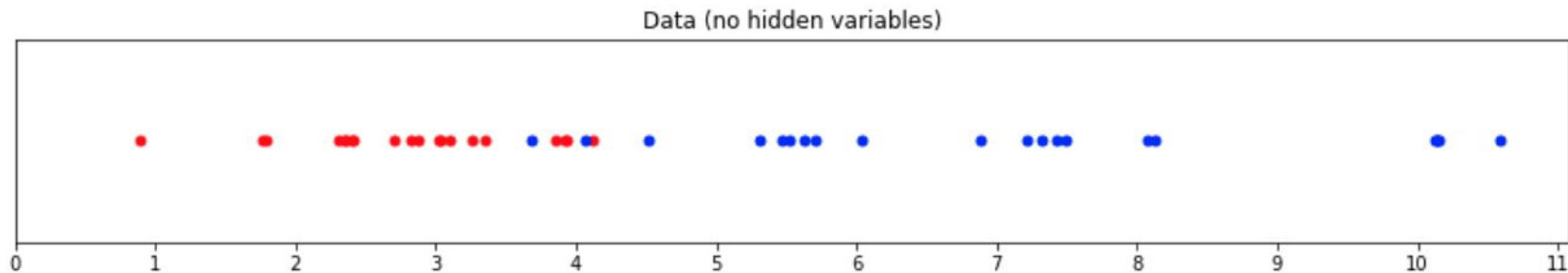


A worked example: Gaussian mixtures

Returning back to our Gaussian Mixture example

The materials for this section can be found mostly on the wikipedia page

https://en.wikipedia.org/wiki/Expectation%E2%80%93maximization_algorithm#Gaussian_mixture



Gaussian Mixture example

Consider the mixture model

$$\begin{aligned} X_i | (Z_i = 1) &\sim \mathcal{N}_d(\boldsymbol{\mu}_1, \Sigma_1) \text{ and} \\ X_i | (Z_i = 2) &\sim \mathcal{N}_d(\boldsymbol{\mu}_2, \Sigma_2) \end{aligned}$$

Let Z_i be the indicator that observation i comes from group 1:

$$\begin{aligned} P(Z_i = 1) &= \tau_1 \text{ and} \\ P(Z_i = 2) &= \tau_2 = 1 - \tau_1 \end{aligned}$$

Z_i is unobserved...

Gaussian Mixture example

The aim is to estimate the unknown parameters

$$\theta = (\tau, \mu_1, \mu_2, \Sigma_1, \Sigma_2)$$

To do this, we will use the EM algorithm

1. **E-step:** given the current estimate of the parameters, calculate the following conditional expectation:

$$Q(\theta|\theta^{(t)}) = \mathbb{E}_{\mathbf{Z}|\mathbf{X},\theta^{(t)}} [\log L(\theta; \mathbf{x}, \mathbf{Z})]$$

2. **M-step:** find the argmax of $Q(\theta|\theta^{(t)})$ for each component of θ

Gaussian Mixture example: the E-step

The E-step involves performing the following calculation:

Given our current estimate of the parameters, the **conditional distribution** of Z_i is determined by Bayes theorem to be the proportional height of the normal density weighted by τ

$$T_{j,i}^{(t)} := P(Z_i = j | X_i = \mathbf{x}_i; \theta^{(t)}) = \frac{\tau_j^{(t)} f(\mathbf{x}_i; \boldsymbol{\mu}_j^{(t)}, \Sigma_j^{(t)})}{\tau_1^{(t)} f(\mathbf{x}_i; \boldsymbol{\mu}_1^{(t)}, \Sigma_1^{(t)}) + \tau_2^{(t)} f(\mathbf{x}_i; \boldsymbol{\mu}_2^{(t)}, \Sigma_2^{(t)})}$$

Gaussian Mixture example: the E-step

The E-step involves performing the following calculation:

$$\begin{aligned} Q(\theta|\theta^{(t)}) &= \mathbb{E}_{\mathbf{Z}|\mathbf{X},\theta^{(t)}} [\log L(\theta; \mathbf{x}, \mathbf{Z})] \\ &= \mathbb{E}_{\mathbf{Z}|\mathbf{X},\theta^{(t)}} \left[\log \prod_{i=1}^n L(\theta; \mathbf{x}_i, \mathbf{z}_i) \right] \\ &= \mathbb{E}_{\mathbf{Z}|\mathbf{X},\theta^{(t)}} \left[\sum_{i=1}^n \log L(\theta; \mathbf{x}_i, \mathbf{z}_i) \right] \\ &= \sum_{i=1}^n \mathbb{E}_{\mathbf{Z}|\mathbf{X};\theta^{(t)}} [\log L(\theta; \mathbf{x}_i, \mathbf{z}_i)] \\ &= \sum_{i=1}^n \sum_{j=1}^2 P(Z_i = j | X_i = \mathbf{x}_i; \theta^{(t)}) \log L(\theta_j; \mathbf{x}_i, \mathbf{z}_i) \\ &= \sum_{i=1}^n \sum_{j=1}^2 T_{j,i}^{(t)} \left[\log \tau_j - \frac{1}{2} \log |\Sigma_j| - \frac{1}{2} (\mathbf{x}_i - \boldsymbol{\mu}_j)^\top \Sigma_j^{-1} (\mathbf{x}_i - \boldsymbol{\mu}_j) - \frac{d}{2} \log(2\pi) \right] \end{aligned}$$

Gaussian Mixture example: the M-step

The M-step involves performing the following optimizations:

$$\begin{aligned}\tau^{(t+1)} &= \arg \max_{\tau} Q(\theta | \theta^{(t)}) \\ &= \arg \max_{\tau} \left\{ \left[\sum_{i=1}^n T_{1,i}^{(t)} \right] \log \tau_1 + \left[\sum_{i=1}^n T_{2,i}^{(t)} \right] \log \tau_2 \right\}\end{aligned}$$

Which can be shown to yield

$$\tau_j^{(t+1)} = \frac{\sum_{i=1}^n T_{j,i}^{(t)}}{\sum_{i=1}^n (T_{1,i}^{(t)} + T_{2,i}^{(t)})} = \frac{1}{n} \sum_{i=1}^n T_{j,i}^{(t)}$$

Gaussian Mixture example: the M-step

The M-step involves performing the following optimizations:

$$\begin{aligned}(\boldsymbol{\mu}_1^{(t+1)}, \Sigma_1^{(t+1)}) &= \arg \max_{\boldsymbol{\mu}_1, \Sigma_1} Q(\theta | \theta^{(t)}) \\ &= \arg \max_{\boldsymbol{\mu}_1, \Sigma_1} \sum_{i=1}^n T_{1,i}^{(t)} \left\{ -\frac{1}{2} \log |\Sigma_1| - \frac{1}{2} (\mathbf{x}_i - \boldsymbol{\mu}_1)^\top \Sigma_1^{-1} (\mathbf{x}_i - \boldsymbol{\mu}_1) \right\}\end{aligned}$$

Which can be shown to yield

$$\boldsymbol{\mu}_1^{(t+1)} = \frac{\sum_{i=1}^n T_{1,i}^{(t)} \mathbf{x}_i}{\sum_{i=1}^n T_{1,i}^{(t)}} \text{ and } \Sigma_1^{(t+1)} = \frac{\sum_{i=1}^n T_{1,i}^{(t)} (\mathbf{x}_i - \boldsymbol{\mu}_1^{(t+1)}) (\mathbf{x}_i - \boldsymbol{\mu}_1^{(t+1)})^\top}{\sum_{i=1}^n T_{1,i}^{(t)}}$$

Gaussian Mixture example: the M-step

The M-step involves performing the following optimizations:

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And by symmetry

$$\boldsymbol{\mu}_2^{(t+1)} = \frac{\sum_{i=1}^n T_{2,i}^{(t)} \mathbf{x}_i}{\sum_{i=1}^n T_{2,i}^{(t)}} \text{ and } \Sigma_2^{(t+1)} = \frac{\sum_{i=1}^n T_{2,i}^{(t)} (\mathbf{x}_i - \boldsymbol{\mu}_2^{(t+1)}) (\mathbf{x}_i - \boldsymbol{\mu}_2^{(t+1)})^\top}{\sum_{i=1}^n T_{2,i}^{(t)}}$$