



APPLICATION IN DESIGNING ALGORITHMS: GRAPH ALGORITHMS

GROUP 12

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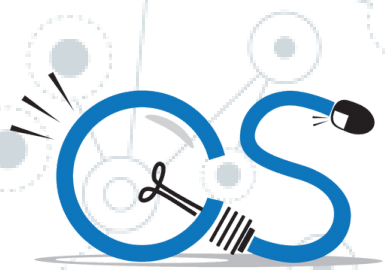


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Graph's Algorithms

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Part 1: OVERVIEW



Part 1: OVERVIEW

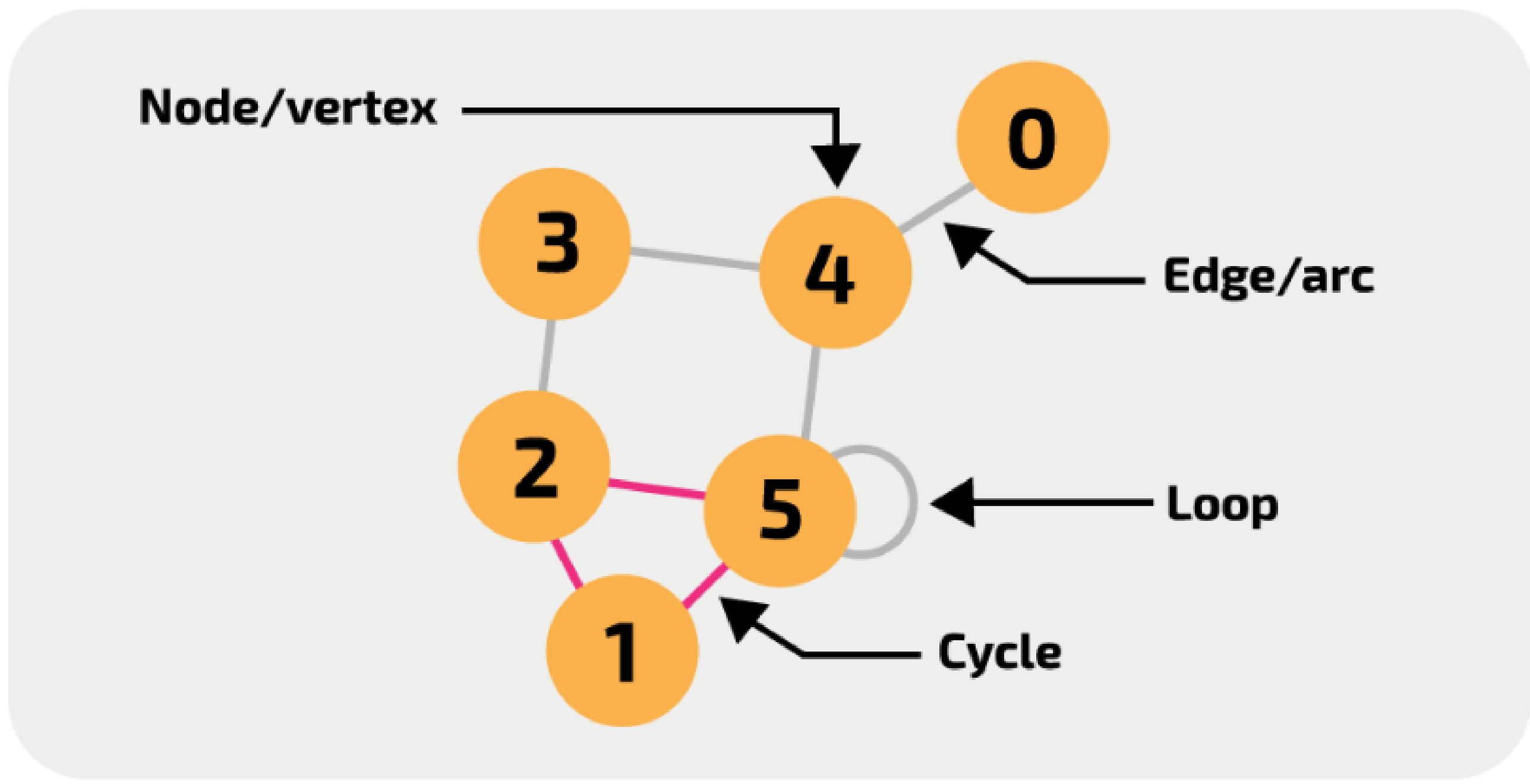


What is a GRAPH?



Part 1: OVERVIEW

What is a GRAPH?





Part 1: OVERVIEW

 **What are differences between geometry and graph?**



Part 1: OVERVIEW

Traversing Algorithm

DFS

BFS



Part 1: OVERVIEW

DFS

BFS

Order

- explores as deeply as possible along a branch before backtracking
- processes from farther to nearer

- explores vertices level by level
- processes from nearer to farther

Approach

Backtracking

???

Data structure

stack

queue

Specific use cases

- ???

- finding shortest path (in a map, a network, a puzzle,...)

Common use cases

Better if the graph is wide

Better if solutions are shallow

Time complexity

$O(|V| + |E|)$
 $|V|$: numbers of vertices
 $|E|$: numbers of edges



Part 2: GRAPH'S ALGORITHMS





Part 2: GRAPH'S ALGORITHMS

Topological Sort

Problem Statement

Technical Definition

Algorithm

Part 2: GRAPH'S ALGORITHMS

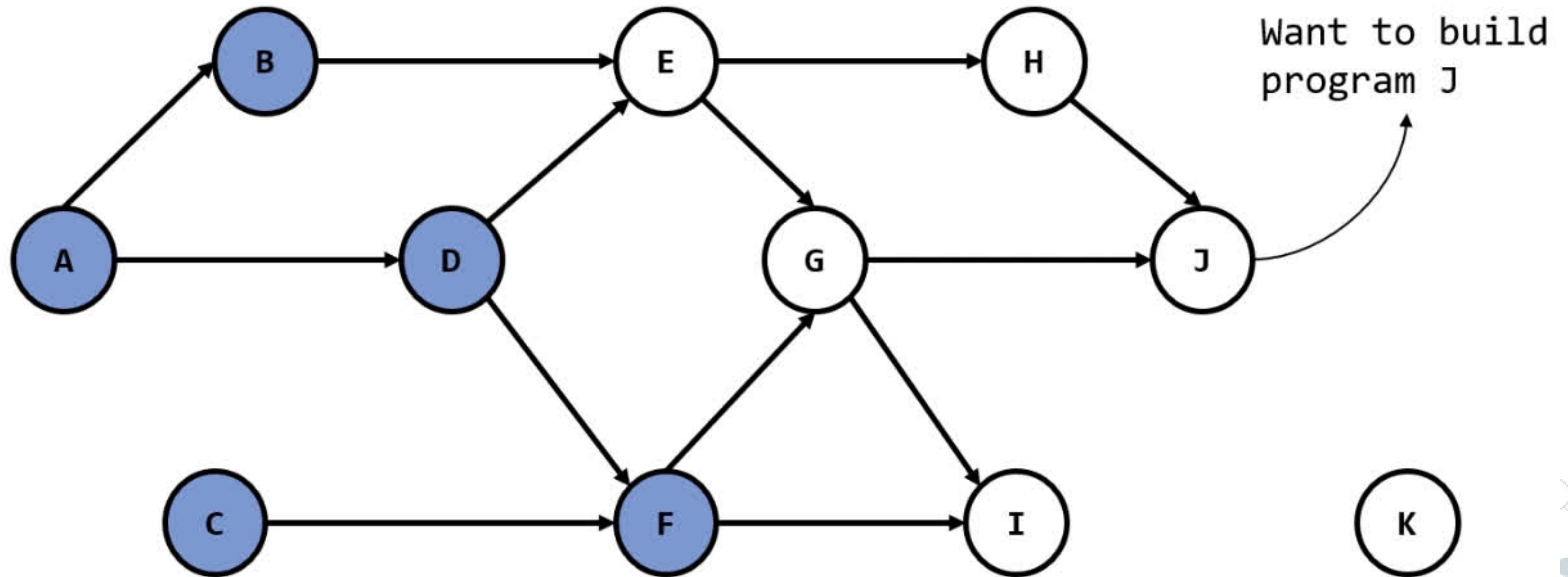
Topological Sort

Problem
Statement

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Definition

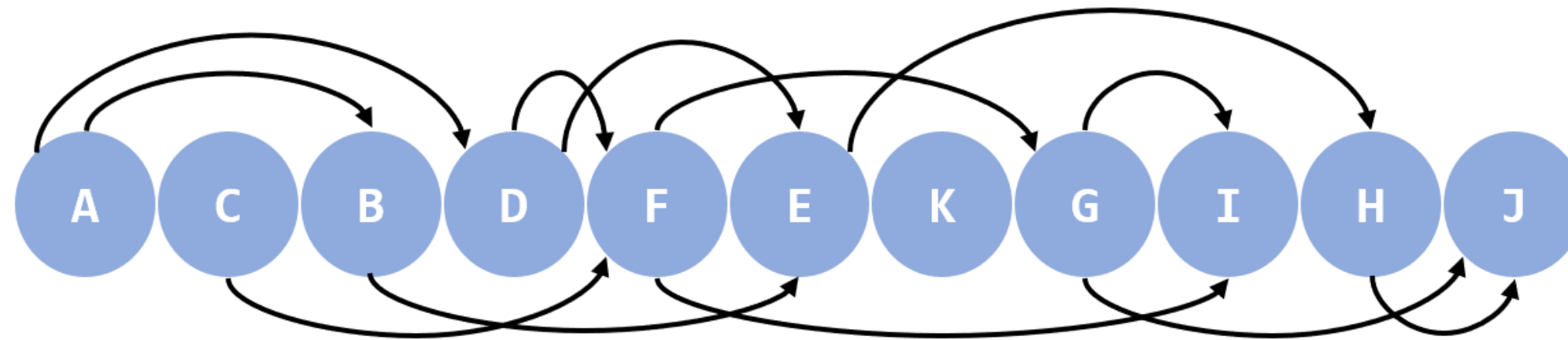
Algorithm

Program build dependencies: a program cannot be built unless its dependencies are built first.



Part 2: GRAPH'S ALGORITHMS

Topological Sort



A **topological ordering** of a directed graph is a linear ordering of its vertices such that for every directed edge (u,v) from vertex u to vertex v , u comes before v in the ordering.

The **topological sort** algorithm can find a topological ordering in $O(V + E)$ time!

NOTE: Topological orderings are not unique!



Problem
Statement

Technical
Definition

Algorithm

Part 2: GRAPH'S ALGORITHMS

Topological Sort

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Does every graphs have topological order?



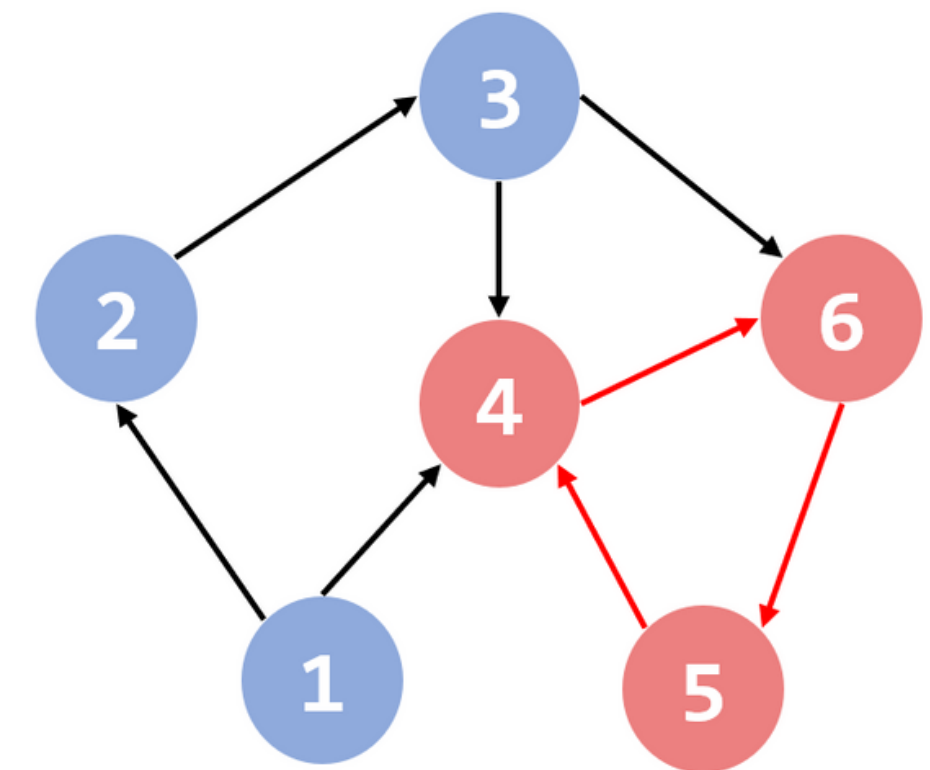
No!

The only type of graph which has valid topological order is a **Directed Acyclic Graph (DAG)** - directed edges and no cycle!

Q: How do I verify if my graph has a cycle?

A:
Tarjan's Algorithm strongly connected components
Kahn's Algorithm

...





Part 2: GRAPH'S ALGORITHMS

Topological Sort

Problem
Statement

Technical
Definition

Algorithm

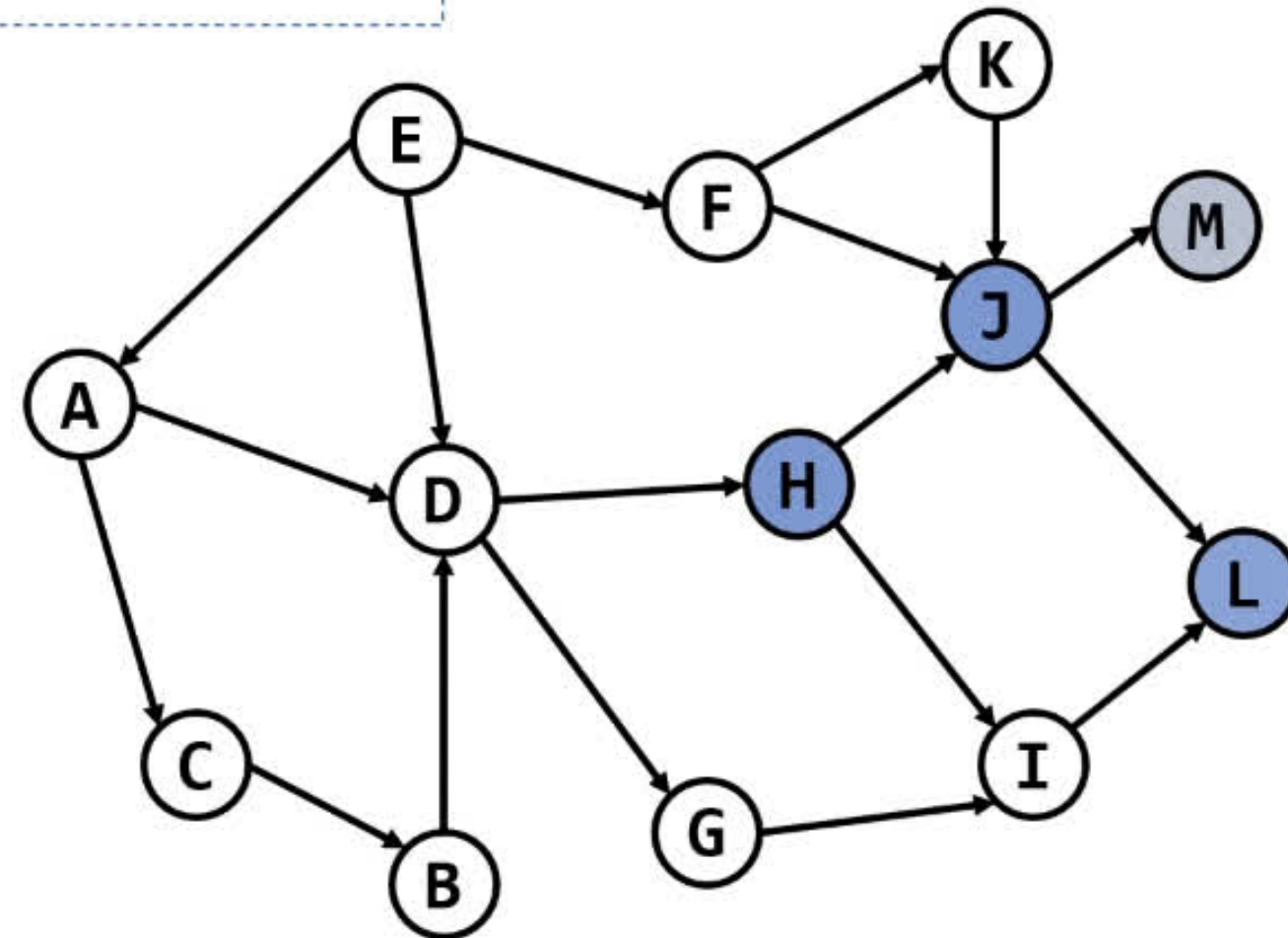
1. **Pick an unvisited node.**
2. **Beginning with the selected node, start a DFS on only unvisited nodes.**
3. **On the recursive callback of the DFS, add the current node to the topological ordering in reverse order.**

Part 2: GRAPH'S ALGORITHMS

Topological Sort

Topological Sort Visualization

Stack



Topological ordering:

M



Problem
Statement

Technical
Definition

Algorithm



Part 2: GRAPH'S ALGORITHMS

Topological Sort

Problem
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Technical
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Algorithm

```
function topo_sort():  
    visited <- a list of size |V| with all 0  
    result <- an empty list  
    for each vertex v in the graph:  
        if not visited[v]:  
            topo_sort_helper(v)
```

```
function topo_sort_helper(v):  
    visited[v] <- 1  
    for u in adjacent vertices of v:  
        if not visited[u]:  
            topo_sort_helper(v)  
    add v to the beginning of result
```

```
return result in reverse
```




Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm

**Directed Graph -
Strongly connected components**

**Undirected Graph -
Bridges and Articulation Points**



Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in directed graph

Some Definations

Problem Statement

Algorithm

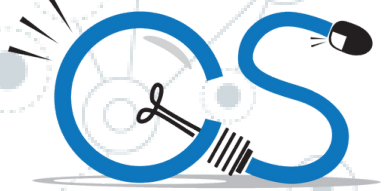
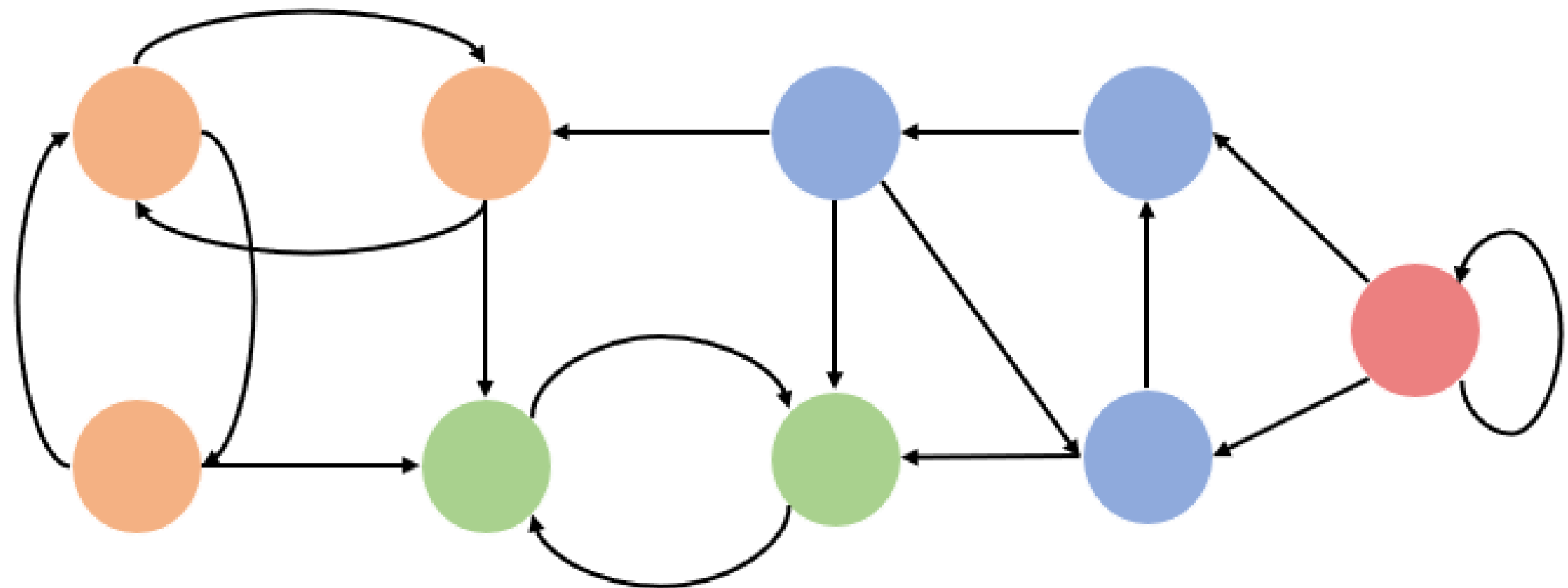
- **The Stack Invariant**
- **New low-link update condition**
- **Overview**
- **Visualization**
- **Pseudocode**

Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in directed graph

? What are **Strongly Connected Components (SCCs)**?

SCCs can be thought of as self - contained cycle within a directed graph where every vertex in a given cycle can reach every other vertex in the same cycle.



Some
Definitions

Problem
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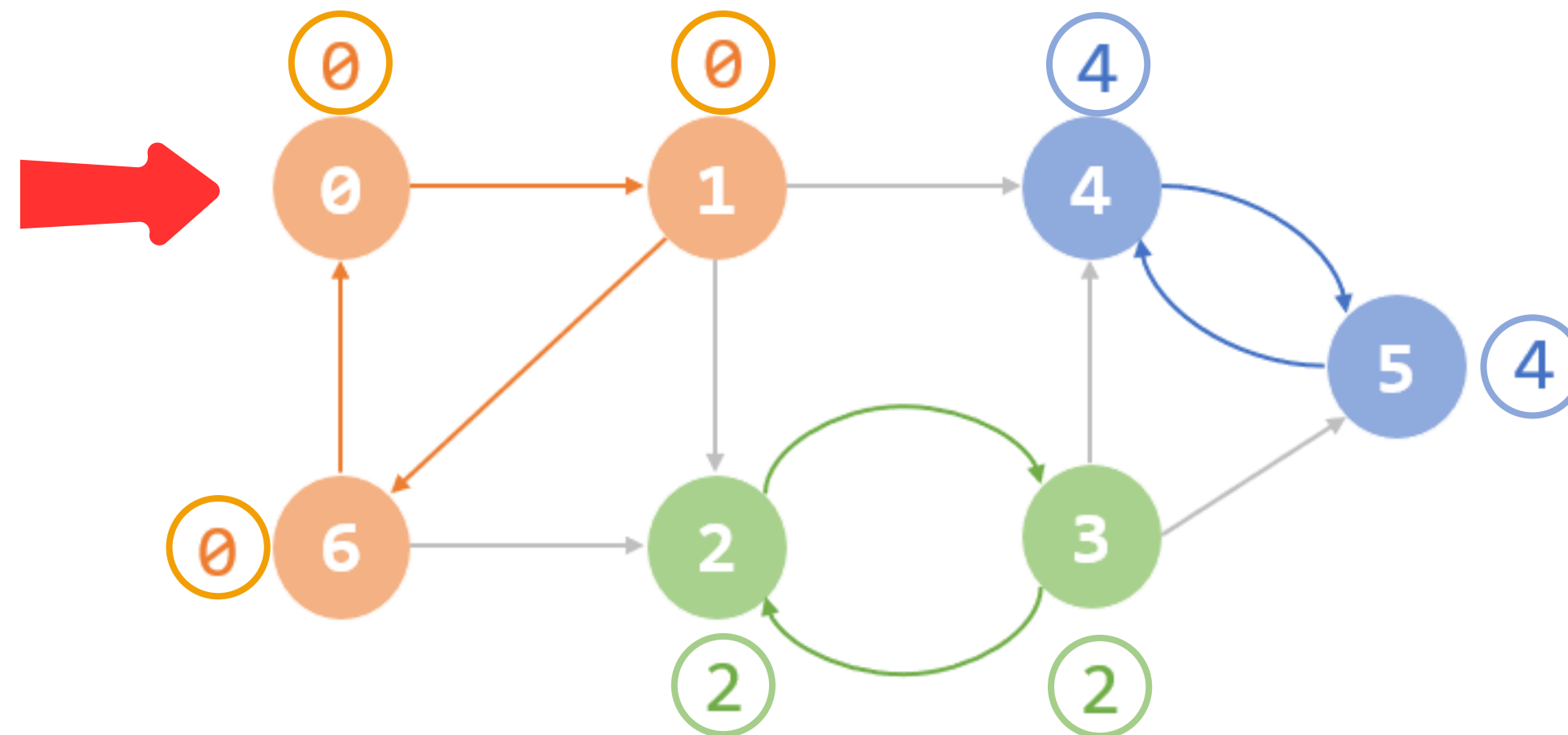
Algorithm

Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in directed graph

Low - link values

The **low - link value** of a node is the smallest [lowest] node id **reachable** from that node when doing a DFS (including itself).



Some
Definitions

Problem
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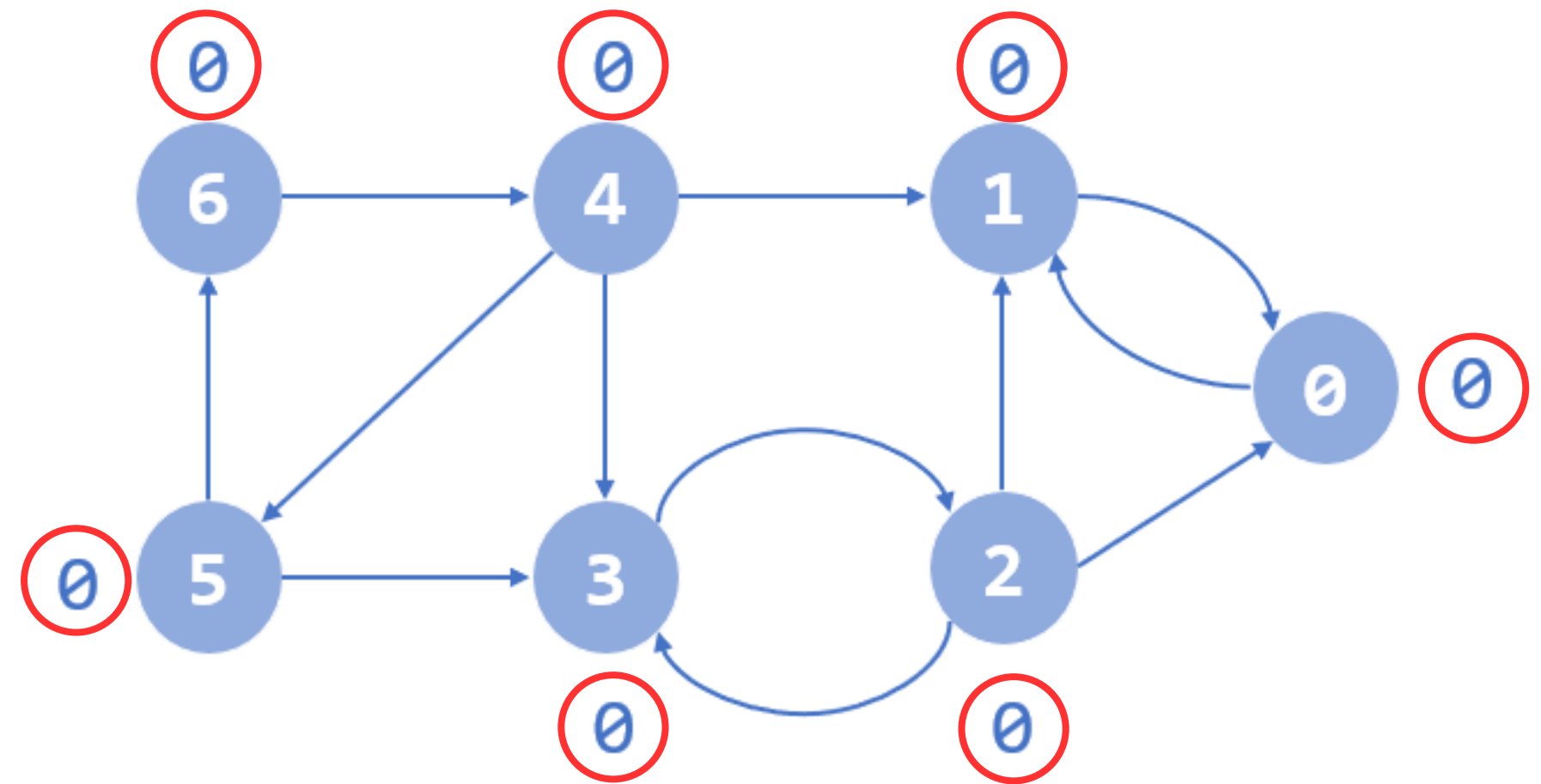
Algorithm

Part 2: GRAPH'S ALGORITHMS

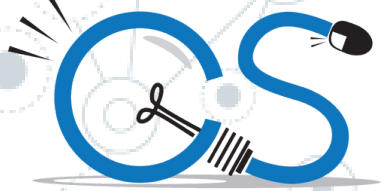
Tarjan's Algorithm in directed graph

Low - link values

The **low - link value** of a node is the smallest [lowest] node id **reachable** from that node when doing a DFS (including itself).



All low link values are the same but there are multiple SCCs!



Some
Definitions

Problem
Statement

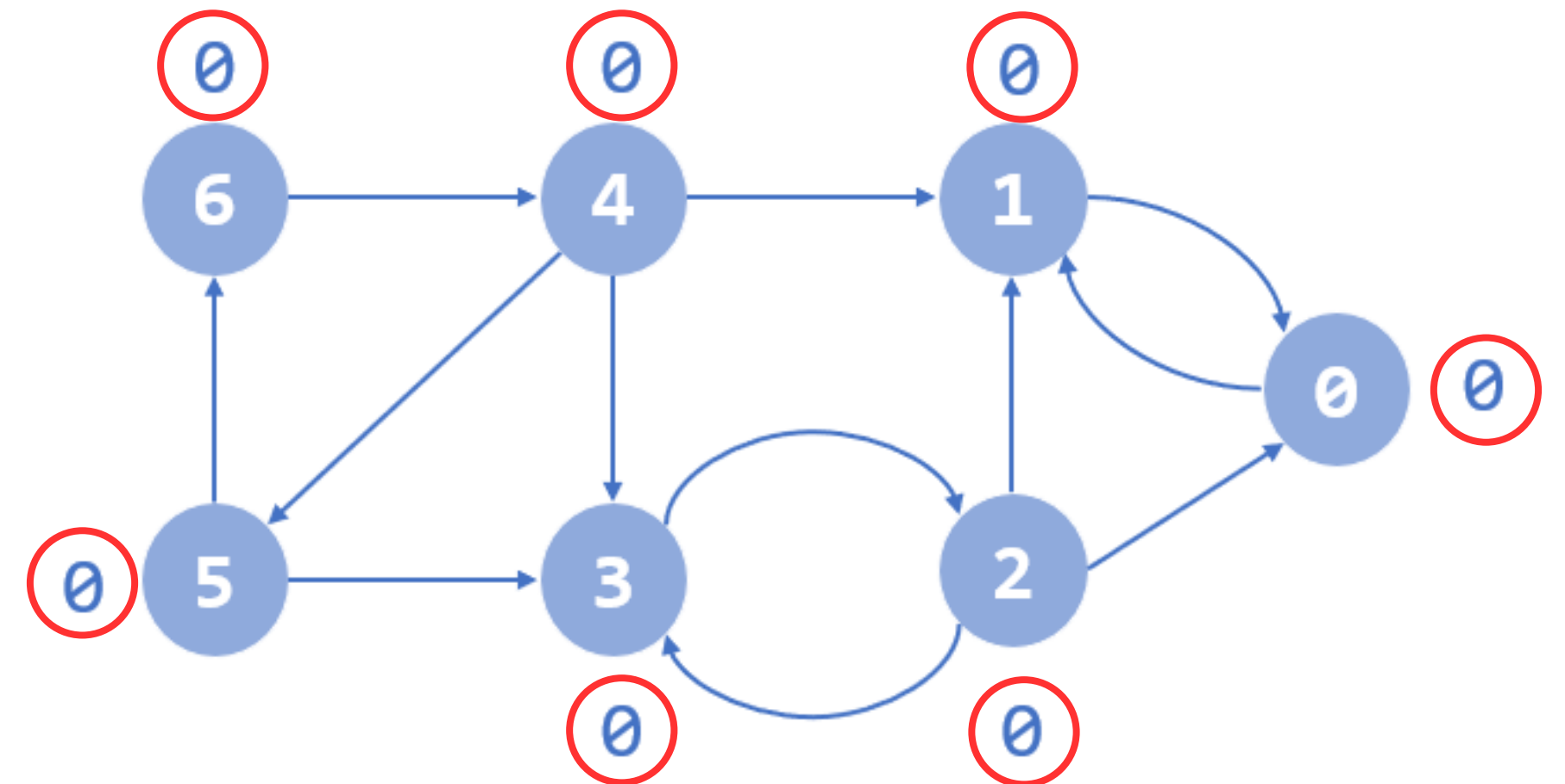
Algorithm

Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in directed graph

Low - link values

The **low - link value** of a node is the smallest [lowest] node id **reachable** from that node when doing a DFS (including itself).



Depending on where the DFS starts, and the order in which nodes/edges are visited, the low-link values for identifying SCCs could be **wrong**.

→ **Tarjan's Algorithm**



Some
Definitions

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Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in directed graph

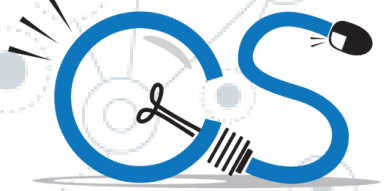
The Stack Invariant

To cope with the random traversal order of the DFS, Tarjan's Algorithm maintains **a set** (often as **a stack**) of valid nodes from which to update low-link values from.

STACK/SET

nodes are **added** as they're explored for the first time

nodes are **removed** each time a SCC is found



Some
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Algorithm

New low-link update condition

Overview

Visualization

Pseudocode



Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in directed graph

New low-link update condition

- **u and v are nodes in a graph**
- **currently exploring u**

To update u's low-link value to node v's low-link value:

- **there has to be a path of edges from u to v**
- **node v must be on the stack**

Some
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Algorithm

• The Stack Invariant

• Overview

• Visualization

• Pseudocode

Part 2: GRAPH'S ALGORITHMS

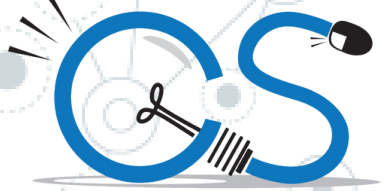
Tarjan's Algorithm in directed graph

Overview

- Mark all nodes as unvisited.
- Start DFS.
- Upon visiting a node assign it an id and a low-link value, also mark current nodes as visited and add them to stack.
- On DFS backtrack, if the previous node is on the stack $\Rightarrow \min(\text{current node's low-link value, last node's low-link value})^*$
- After visiting all neighbors, if the current node started a connected component $**$
 \Rightarrow pop nodes off stack until current node is reached.

*: this allows low-link values are maintained throughout cycles.

** : if its id == its low-link value



Some
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• Pseudocode



Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in directed graph

Visualization

Tarjan's Algorithm Visualization



Unvisited

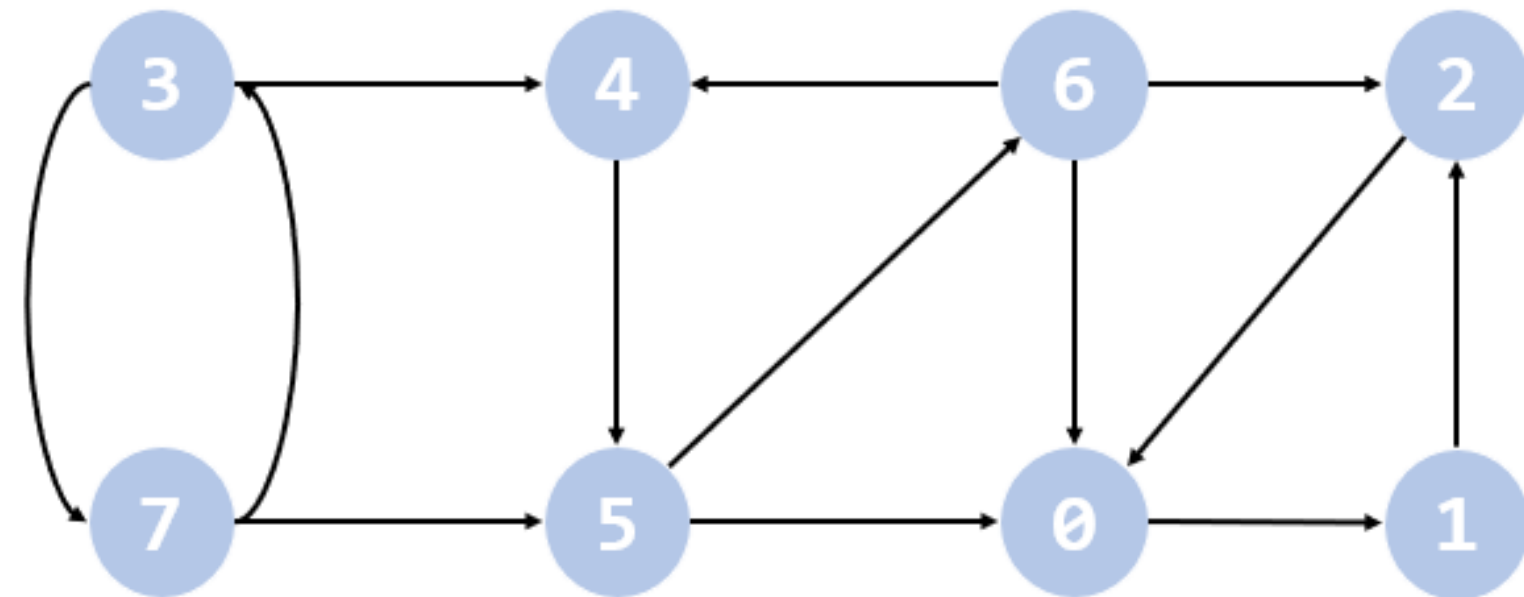


Visiting neighbors



Visiting all neighbors

Stack



If a node is **green** or **gray**
=> it is on the stack
=> can update its low-link value

Some
Definations

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Part 2: GRAPH'S ALGORITHMS

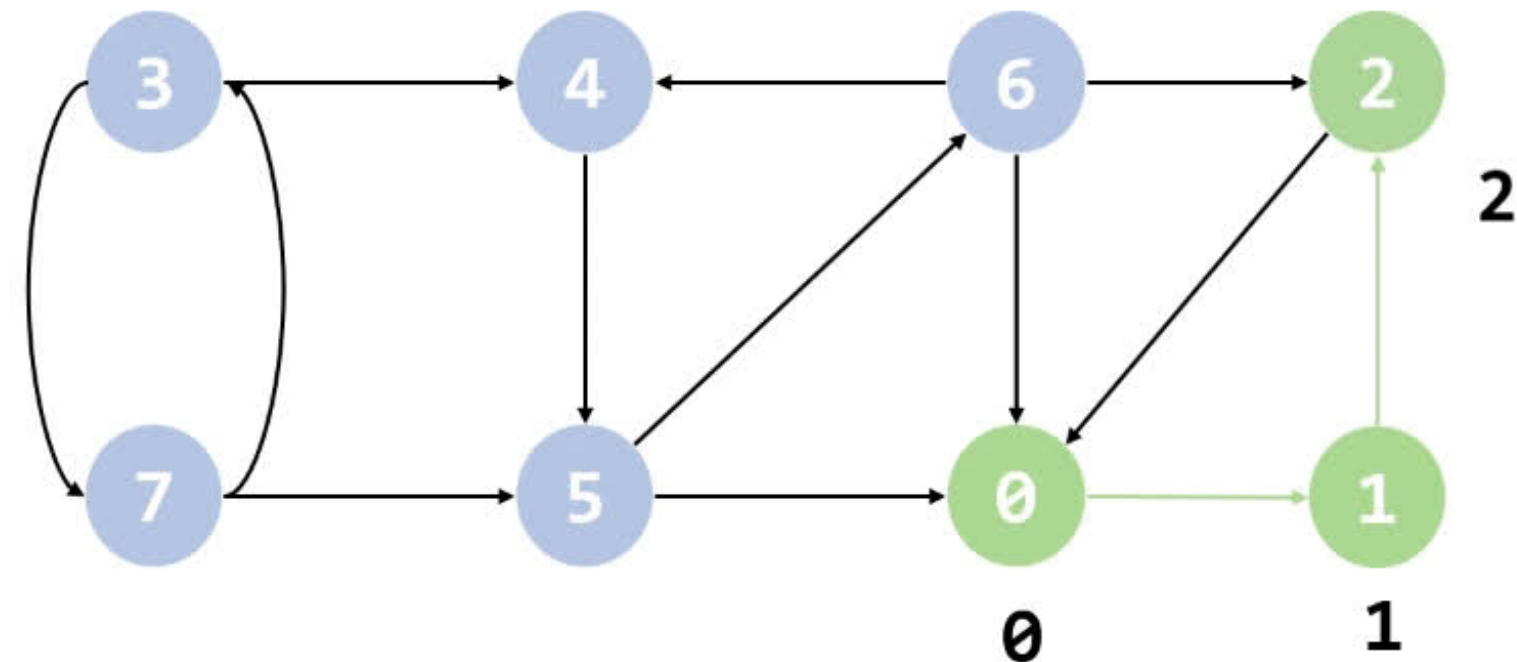
Tarjan's Algorithm in directed graph Visualization

Tarjan's Algorithm Visualization

Unvisited Visiting neighbors Visiting all neighbors

Stack

0
1
2



Some
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• Pseudocode

Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in directed graph

Pseudocode

```
function scc():  
    visited <- a list of size |V| with all 0  
    order <- a list of size |V| with all -1  
    low_link <- a list of size |V| with all -1  
    current <- 0  
    st <- an empty stack  
    on_st <- a list of size |V| with all 0  
    scc_count <- 0  
    for each vertex v in the graph:  
        if not visited[v]:  
            scc_helper(v)  
    return scc_count
```

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- New low-link update condition

- Overview

- Visualization

Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in directed graph

Some
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- The Stack Invariant
- New low-link update condition
- Overview
- Visualization
-

Pseudocode

```
function scc_helper(v):
    add v into st
    visited[v] <- 1
    on_st[v] <- 1
    order[v] <- current
    low_link[v] <- current
    current <- current + 1
    for each adjacent vertex u of v:
        if not visited[u]:
            scc_helper(u)
            low_link[v] <- min(low_link[v], low_link[u])
        else if on_st[u]:
            low_link[v] <- min(low_link[v], order[u])
    if low_link[v] = order[v]:
        repeat:
            u <- extract top from st
            on_st[u] <- 0
        until u = v
    scc_count <- scc_count + 1
```



Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in undirected graph

Some Definations

Conditions

Algorithm

- **Overview**
- **Visualization**
- **Pseudocode**

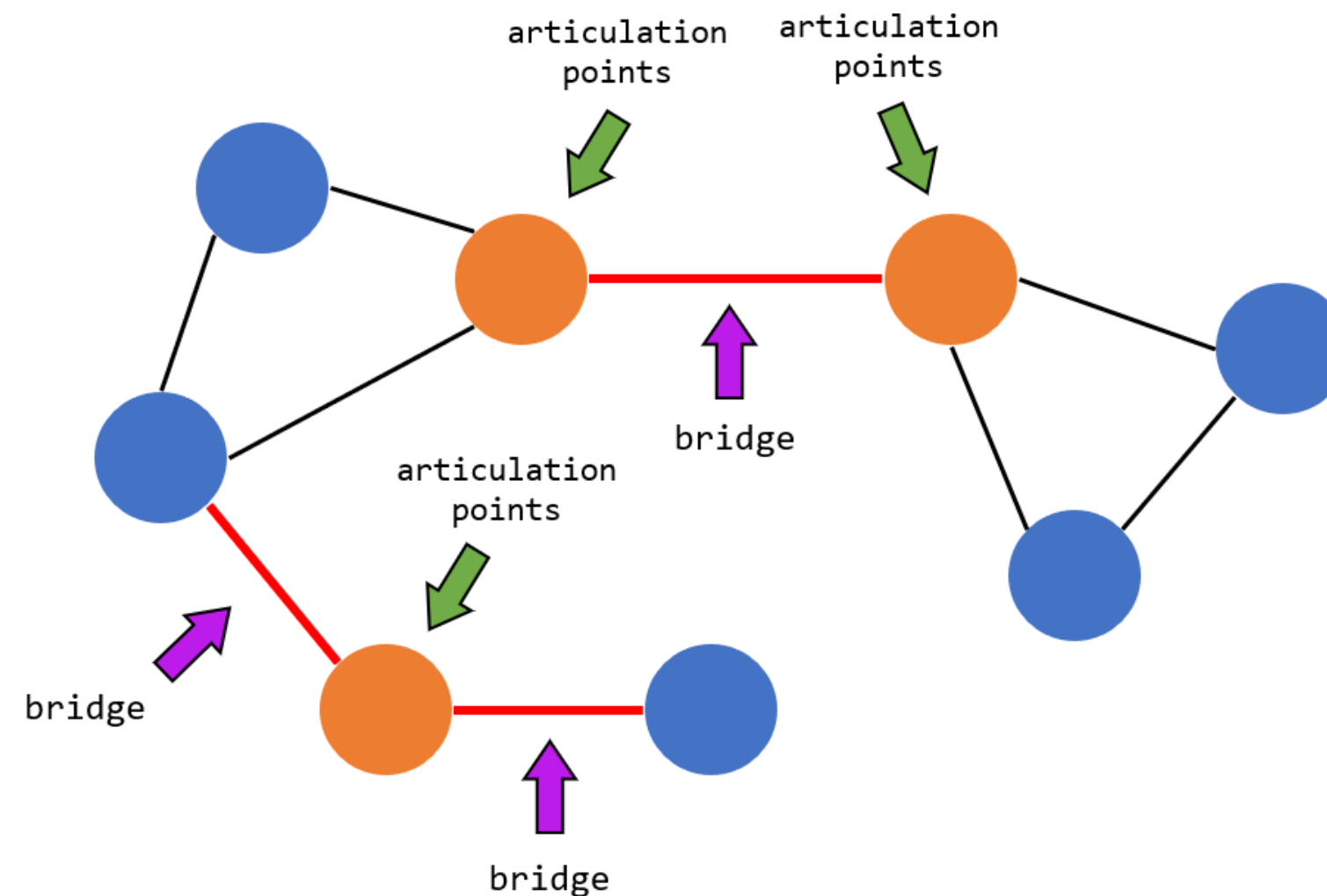
Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in undirected graph



What are **Bridges** and **Articulation points**?

A **Bridge** / an **Articulation point** is an edge / a vertex which, when removed, increases the number of connected components in the graph.



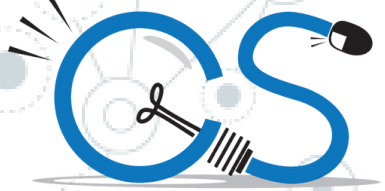
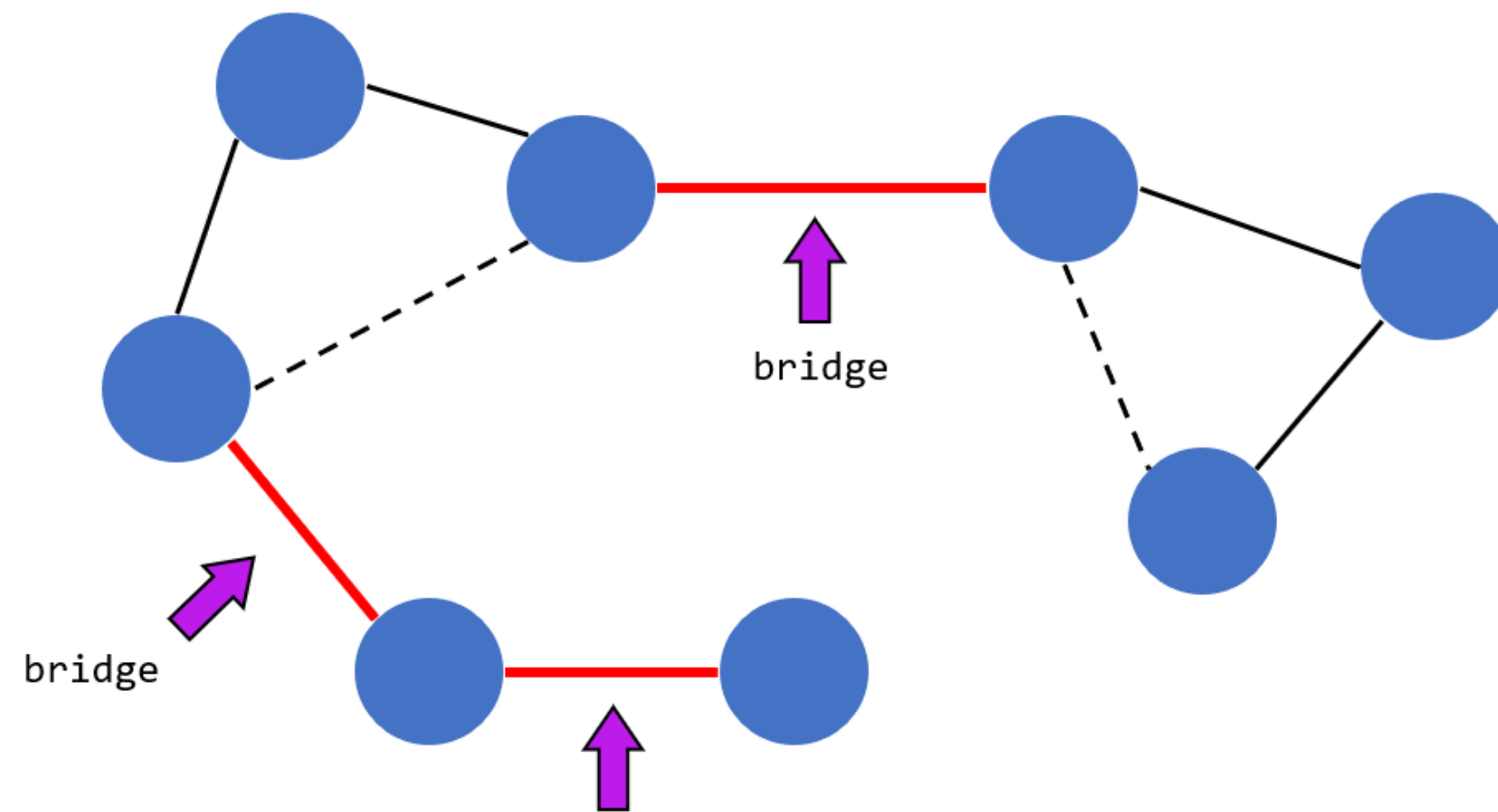
Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in undirected graph



How do we know if an edge is a **bridge**?

If on the DFS tree, vertex v is the parent of vertex u , the edge connecting u and v is **a bridge** if and only if u doesn't have any other links to v or any ancestors of v .



Some
Definitions

Conditions

Algorithm

Part 2: GRAPH'S ALGORITHMS

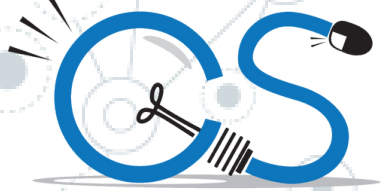
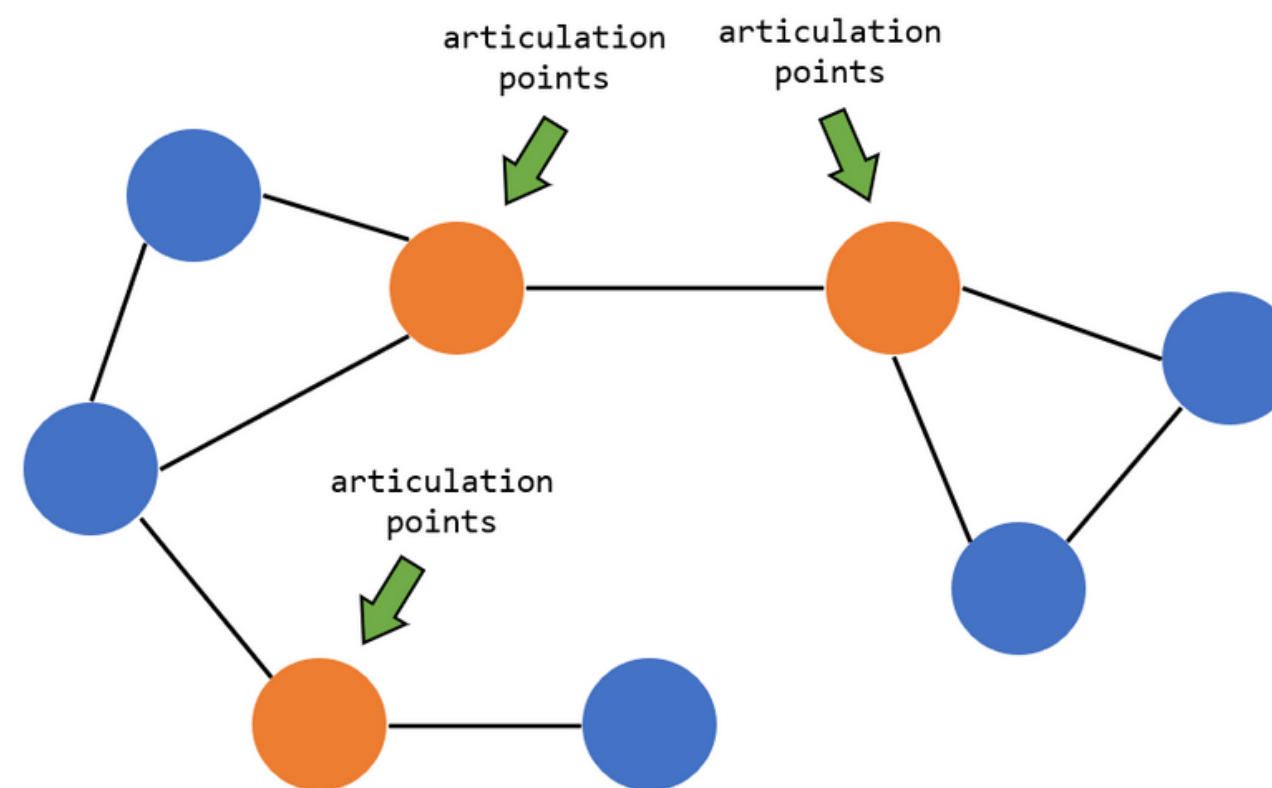
Tarjan's Algorithm in undirected graph



How do we know if a vertex is an **articulation point**?

A vertex v of the DFS tree is an **articulation point** if and only if one of the followings happens:

- v is the root and have more than 1 child
- v is not the root and a child of v does not have any other links to any ancestors of v



Some
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Algorithm



Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in undirected graph

Overview

- If we consider the DFS tree as a DAG, we can use the same approach except that now we want to find the lowest link possible so the **stack is not needed**.
- We will use an array to keep track of the parent of each vertex.

Some
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Conditions

Algorithm

Visualization

Pseudocode

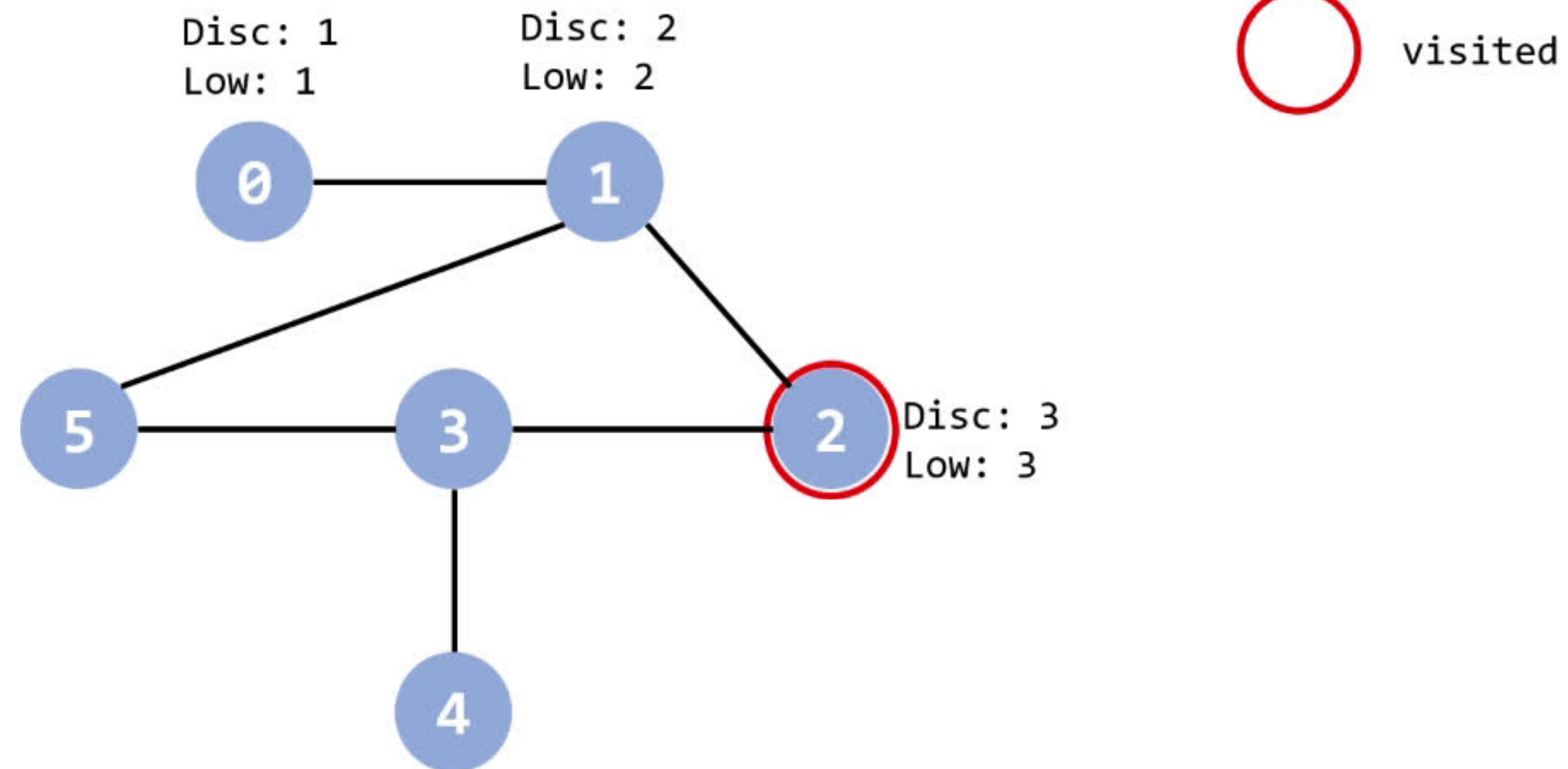


Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in undirected graph

Visualization

Tarjan's Algorithm in undirected graph



Some
Definations

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Pseudocode



Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in undirected graph

Pseudocode

```
function bridges():  
    visited <- a list of size |V| with all 0  
    order <- a list of size |V| with all -1  
    low_link <- a list of size |V| with all -1  
    parent <- a list of size |V| with all -1  
    current <- 0  
    bridge_count <- 0  
    for each vertex v in the graph:  
        if not visited[v]:  
            bridge_helper(v)  
    return bridge_count
```

Some
Definitions

Conditions

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• Visualization



Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in undirected graph

Some
Definitions

Conditions

Algorithm

- Overview

- Visualization

```
function bridge_helper(v):  
    visited[v] <- 1  
    order[v] <- current  
    low_link[v] <- current  
    current <- current + 1  
    for each adjacent vertex u of v:  
        if not visited[u]:  
            parent[u] <- v  
            bridge_helper(u)  
            low_link[v] <- min(low_link[v], low_link[u])  
            if low_link[u] > order[v]:  
                bridge_count <- bridge_count + 1  
        else if parent[v] != u  
            low_link[v] <- min(low_link[v], order[u])
```

Pseudocode



Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in undirected graph

Pseudocode

Some
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• Overview

• Visualization

```
function ap():  
    visited <- a list of size |V| with all 0  
    order <- a list of size |V| with all -1  
    low_link <- a list of size |V| with all -1  
    parent <- a list of size |V| with all -1  
    current <- 0  
    ap_count <- 0  
    branches <- 0  
    root <- -1  
    for each vertex v in the graph:  
        if not visited[v]:  
            branches <- 0  
            root <- v  
            ap_helper(v)  
    return ap_count
```


Part 2: GRAPH'S ALGORITHMS

Tarjan's Algorithm in undirected graph

Some
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- Visualization

Pseudocode

```
function ap_helper(v):
    visited[v] <- 1
    order[v] <- current
    low_link[v] <- current
    current <- current + 1
    is_ap <- 0
    for each adjacent vertex u of v:
        if not visited[u]:
            parent[u] <- v
            ap_helper(u)
            if v = root:
                branches <- branches + 1
                if branches > 1:
                    is_ap = 1
            else:
                low_link[v] <- min(low_link[v], low_link[u])
                if low_link[u] >= order[v]:
                    is_ap = 1
            else if parent[v] != u
                low_link[v] <- min(low_link[v], order[u])
    ap_count <- ap_count + is_ap
```



Part 2: GRAPH'S ALGORITHMS

Ford - Fulkerson's Algorithm

Some Definations

- **Capacity, Source, Sink and Flow**
- **Augmenting path**
- **Residual Graph**

Algorithm

- **Updating capacity**
- **Finding augmenting paths**
- **Overview**
- **Visualization**
- **Pseudocode**

Part 2: GRAPH'S ALGORITHMS

Ford - Fulkerson's Algorithm

Some Definitions

- Capacity, Source, Sink and Flow
- Augmenting path
- Residual Graph

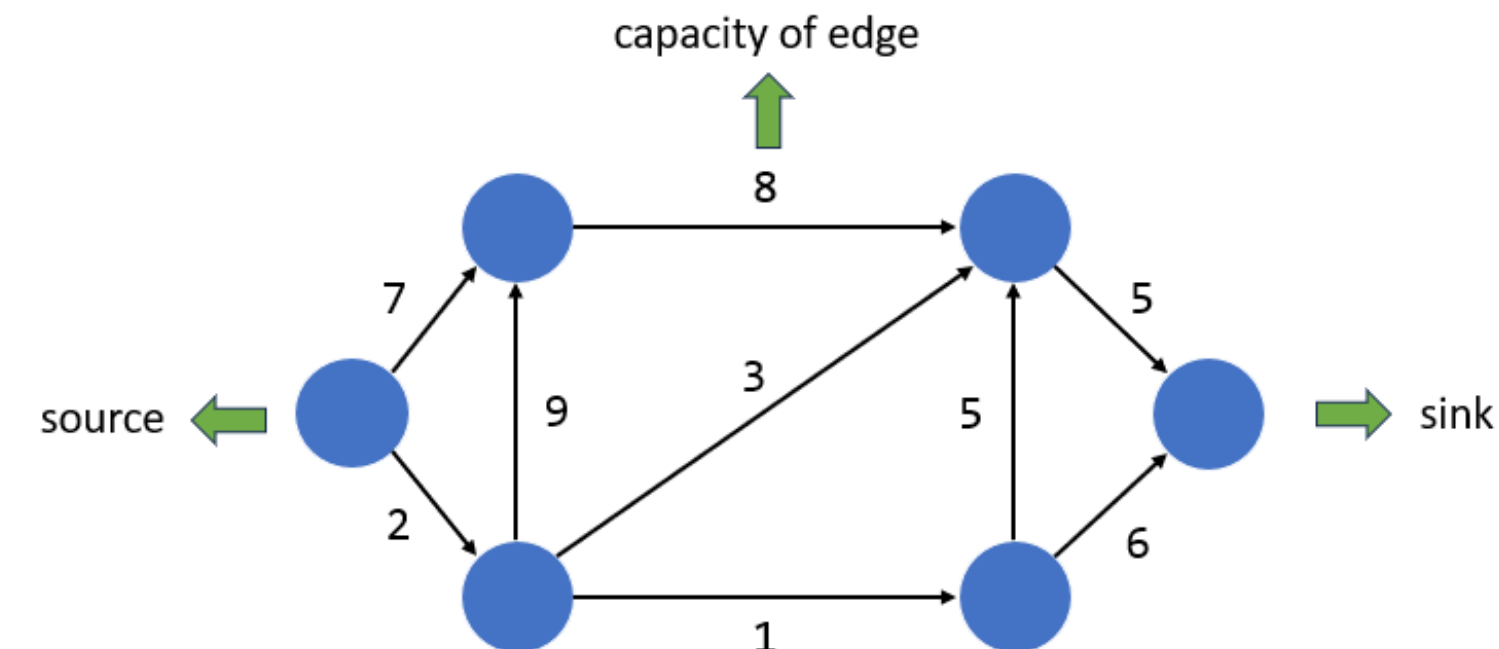
Algorithm

Capacity: the maximum amount of substance that can pass through a certain edge

Source / sink: sender / receiver of substance

Flow: a way by which substance flowing from source to sink, satisfying the following constraints:

- total substance from source = total substance to sink
- total substance to v = total substance from v (v is not **source** or **sink**) substance through an edge \leq **capacity** of that edge



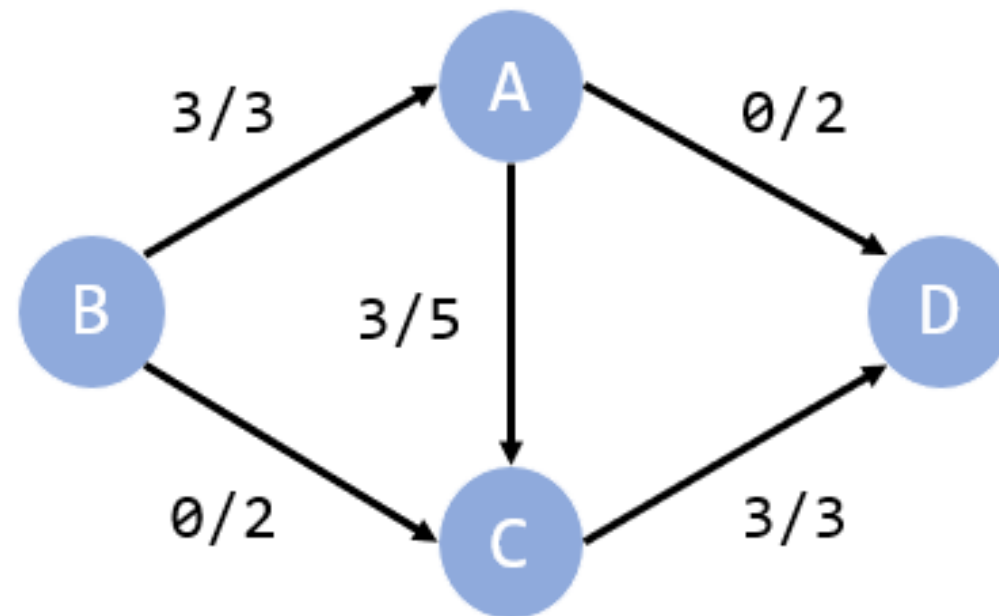
Part 2: GRAPH'S ALGORITHMS

Ford - Fulkerson's Algorithm

Some Definitions

- Capacity, Source, Sink and Flow
- Augmenting path
- Residual Graph

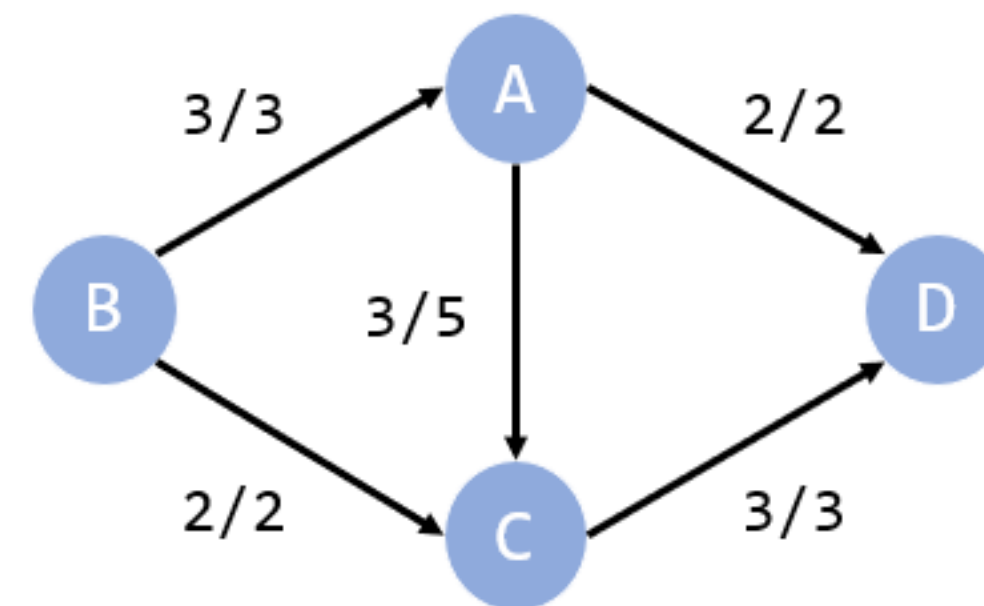
Algorithm



flow value = 3

Flow value: the total amount of substance flowing from source to sink

Maximum flow: the flow which maximizes flow value



flow value = 5

Part 2: GRAPH'S ALGORITHMS

Ford - Fulkerson's Algorithm

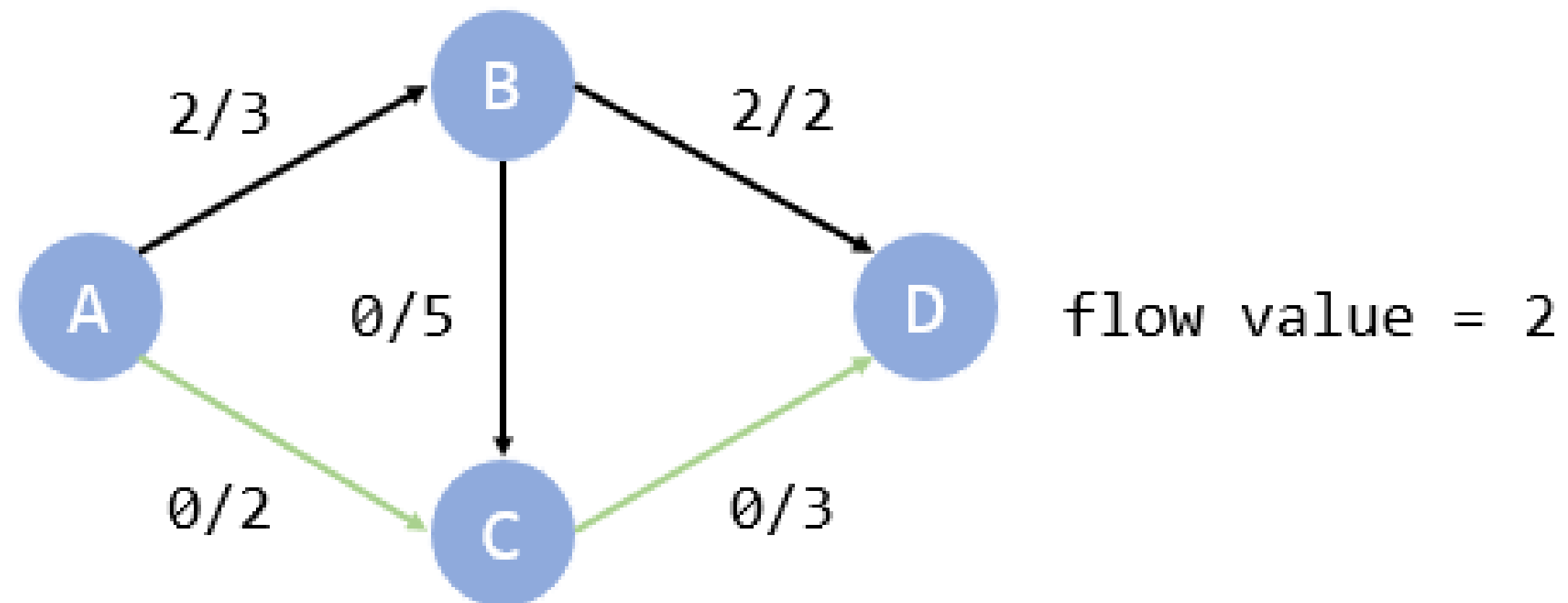
Some Definitions

- Capacity, Source, Sink and Flow
- **Augmenting path**
- Residual Graph

Algorithm

Augmenting path

Augmenting path is a path from source to sink where more substance can be sent. The amount of substance must not be greater than the bottleneck of the path.



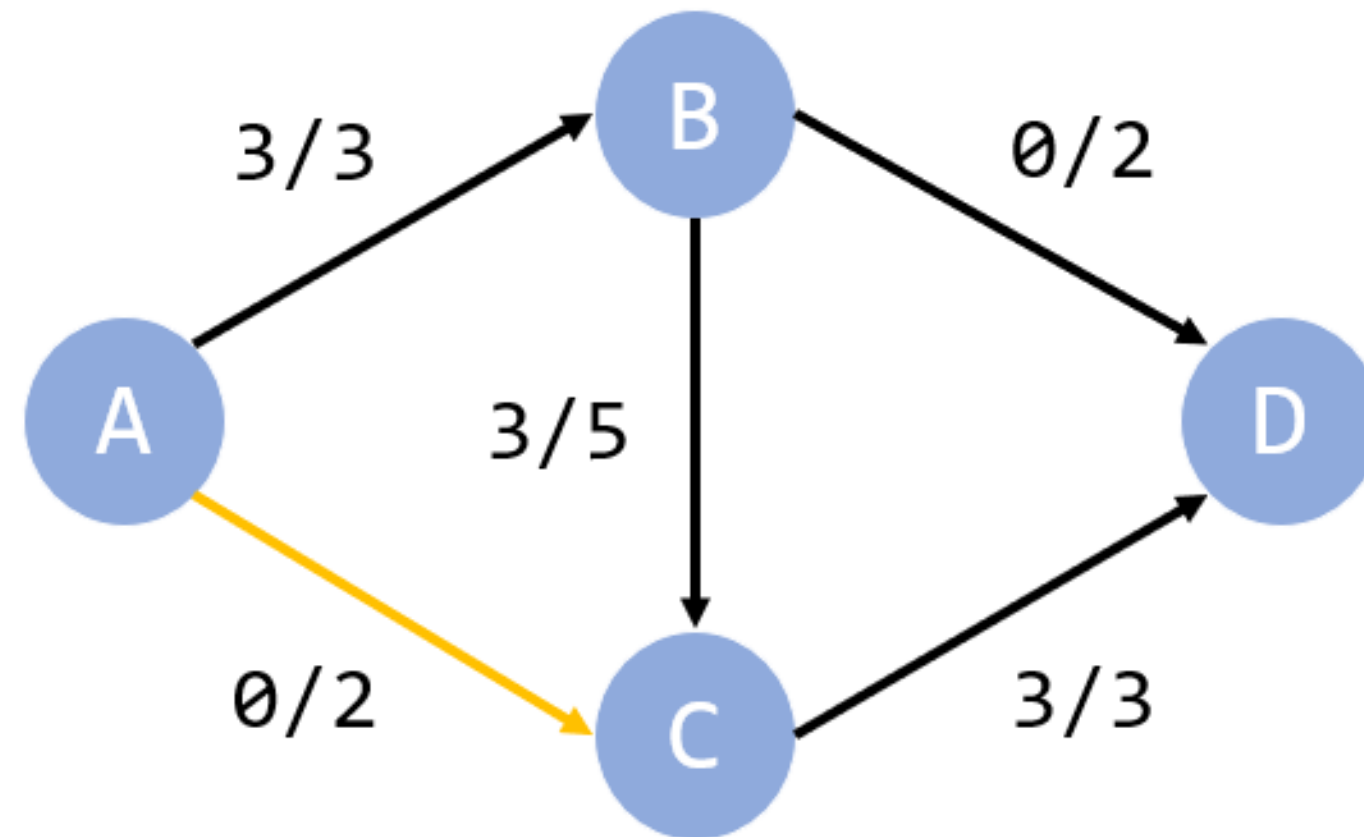
Part 2: GRAPH'S ALGORITHMS

Ford - Fulkerson's Algorithm

Residual graph



Assuming that the current flow **blocks all augmenting path** when we haven't yet found the maximum flow value. How do we cope with this?



flow value = 3

Some Definitions

- Capacity, Source, Sink and Flow
- Augmenting path
- Residual Graph

Algorithm

Part 2: GRAPH'S ALGORITHMS

Ford - Fulkerson's Algorithm

Some Definitions

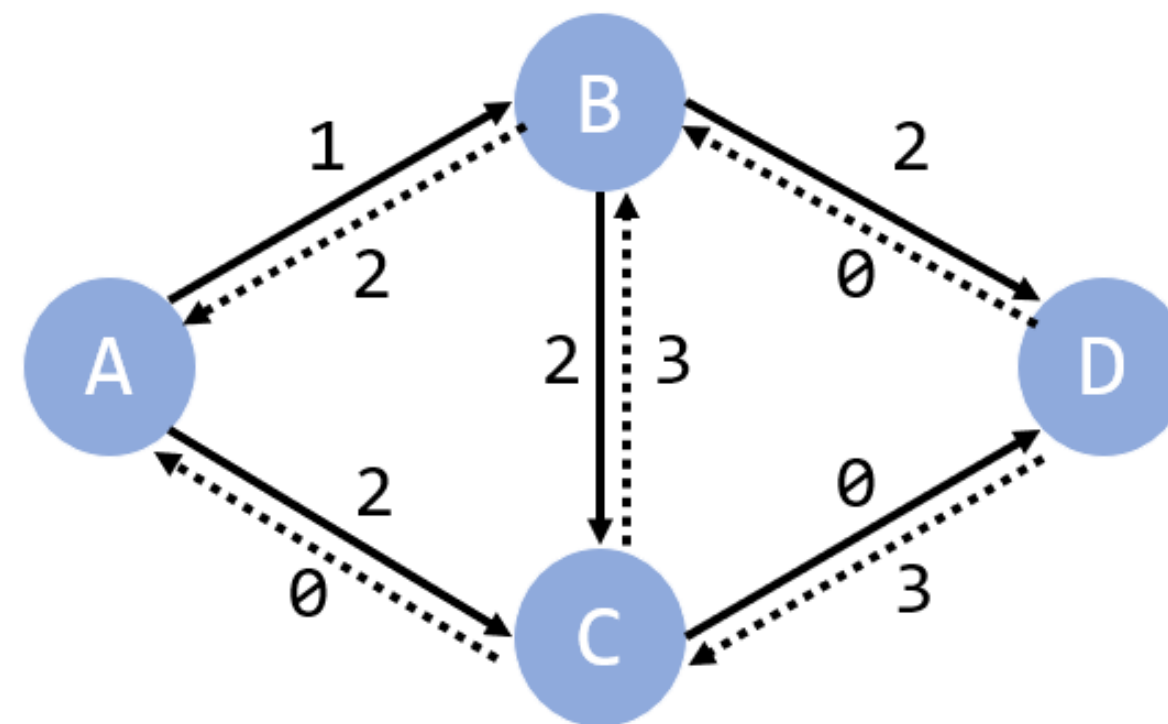
- Capacity, Source, Sink and Flow
- Augmenting path
- Residual Graph

Algorithm

Residual graph

? Assuming that the current flow **blocks all augmenting path** when we haven't yet found the maximum flow value. How do we cope with this?

By adding reverse edges. The reverse edges allow us to "undo" bad path choices by "forcing" the substance to flow on other paths.



flow value = 2

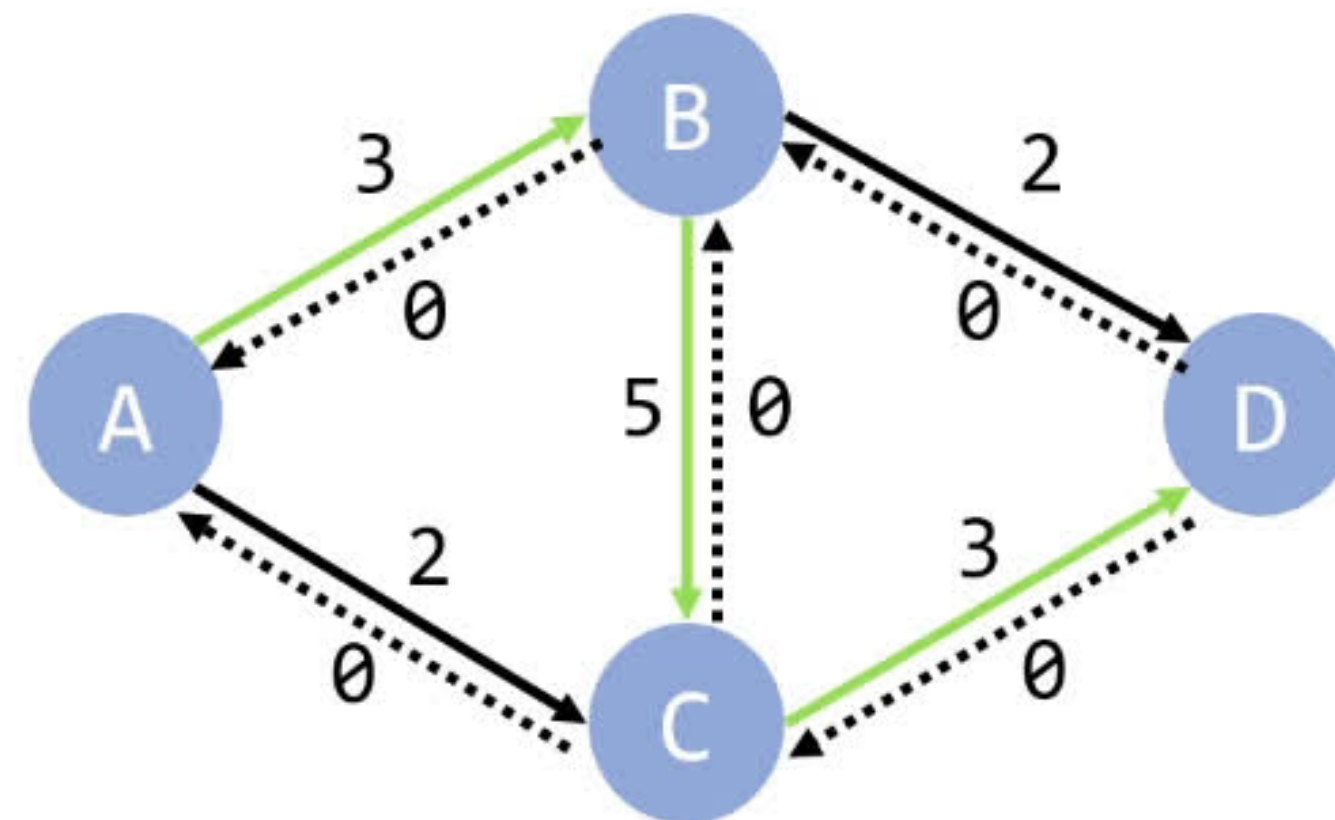
Part 2: GRAPH'S ALGORITHMS

Ford - Fulkerson's Algorithm

Updating capacity

Letting substance passing through an edge reduce its capacity but allow more substance to be forced out.

=> **decrease capacity** of the **edge** and **increase capacity** of the **reverse edge**.



flow value = 3

Some
Definitions

Algorithm

Finding augmenting paths

Overview

Visualization

Pseudocode

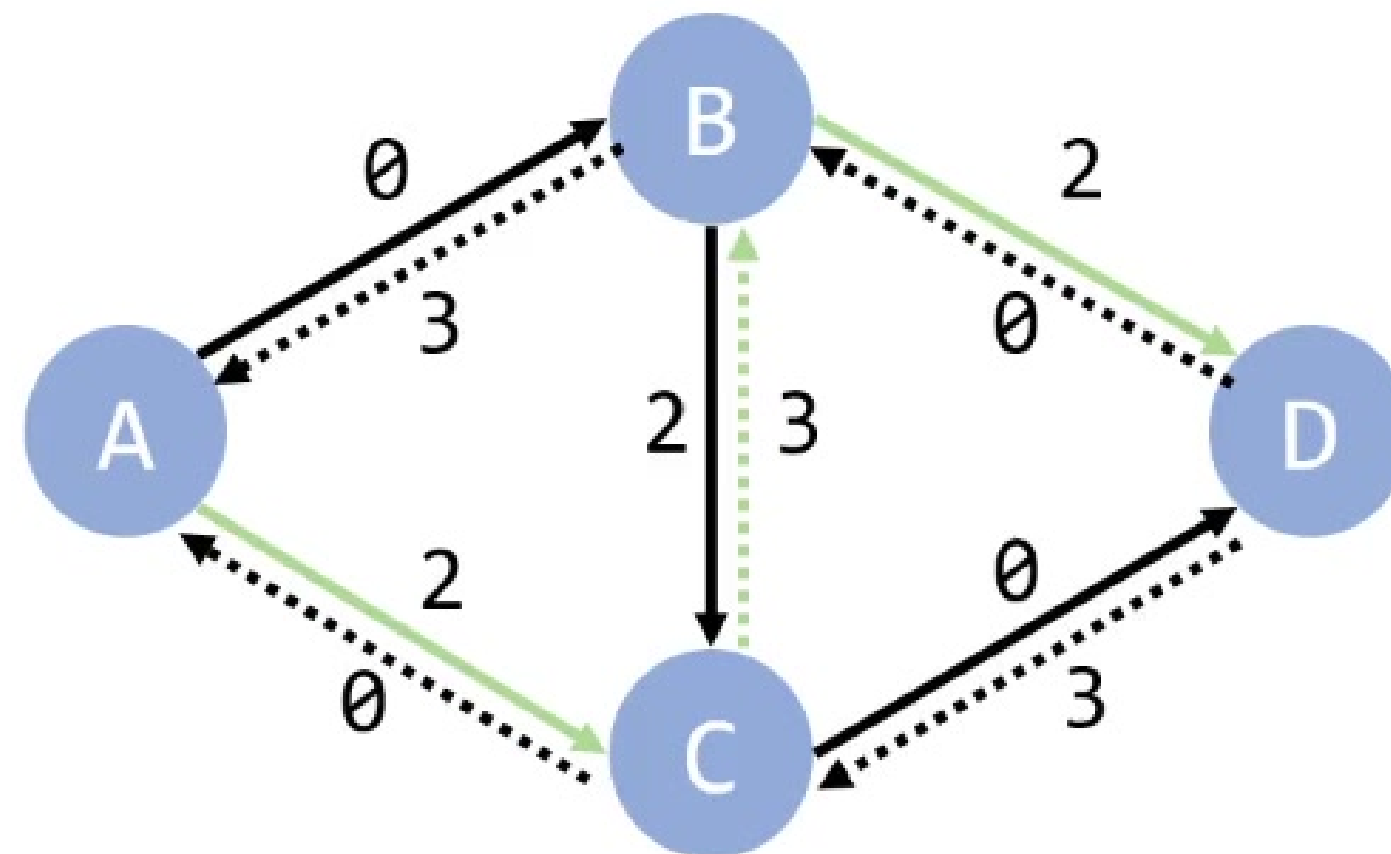
Part 2: GRAPH'S ALGORITHMS

Ford - Fulkerson's Algorithm

Updating capacity

By contrast, force some substance out of an edge increase its capacity but leave the edges with less substance.

=> update capacity the **opposite way**.



flow value = 3

Some
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Finding augmenting paths

Overview

Visualization

Pseudocode



Part 2: GRAPH'S ALGORITHMS

Ford - Fulkerson's Algorithm

Finding augmenting paths

- Find a path from source to sink which does not have any edges with capacity 0. Here we use DFS.
- Other methods of finding paths can also be used. If we use BFS, we have Edmond - Karp's algorithm.

Some
Definations

Algorithm

• Updating capacity

• Overview

• Visualization

• Pseudocode



Part 2: GRAPH'S ALGORITHMS

Ford Fulkerson's Algorithm

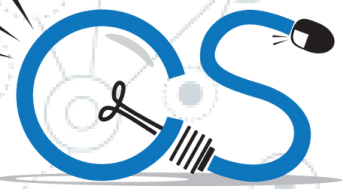
Overview

Ford - Fulkerson's Algorithm repeatedly **finds augmenting paths** using DFS and **sends flow** along the paths. When no more augmenting paths can be found, the algorithm ends.

Some
Definations

Algorithm

- Updating capacity
- Finding augmenting paths
- Visualization
- Pseudocode



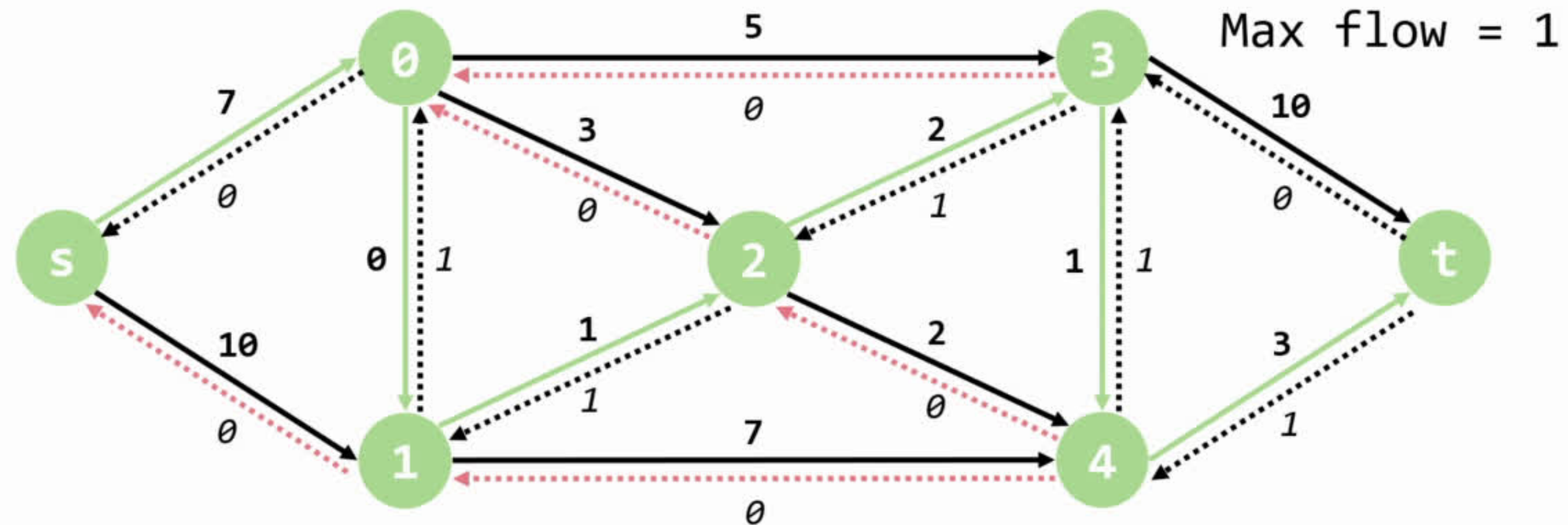
Part 2: GRAPH'S ALGORITHMS

Ford Fulkerson's Algorithm Visualization

Some
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Ford-Fulkerson Algorithm Visualization



Augmenting path found, bottleneck = 1

Updating capacity

Finding augmenting paths

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Part 2: GRAPH'S ALGORITHMS

Ford Fulkerson's Algorithm

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Definitions

Algorithm

- Updating capacity
- Finding augmenting paths
- Overview
- Visualization

pre-condition:

for each edge (u, v) of the graph:

add edge (v, u) of capacity \emptyset to the graph

function ford_fulkerson():

flow_value $\leftarrow \emptyset$

visited \leftarrow a list of size $|V|$ with all \emptyset

parent \leftarrow a list of size $|V|$ with all -1

bottleneck \leftarrow infinity

while find_aug_path(source):

s \leftarrow sink

while s \neq source:

graph[parent[s]][s] \leftarrow graph[parent[s]][s] - bottleneck

graph[s][parent[s]] \leftarrow graph[s][parent[s]] + bottleneck

s \leftarrow parent[s]

flow_value += bottleneck

visited \leftarrow a list of size $|V|$ with all \emptyset

parent \leftarrow a list of size $|V|$ with all -1

return max_flow

Pseudocode



Part 2: GRAPH'S ALGORITHMS

Ford Fulkerson's Algorithm

Pseudocode

Some
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```
function find_aug_path(v)
  visited[v] <- 1
  for each adjacent vertex u of v and capacity c of connecting
  edge:
    if not visited[u] and c > 0:
      parent[u] <- v
      if u = sink or find_aug_path(u):
        bottleneck <- min(bottleneck, c)
      return True
  return False
```



THANK YOU FOR LISTENING!