

## 6. Image Corrupted with noise

### Problem 5. Image Corrupted with noise

3/3 points (graded)

Consider an image, in which every pixel takes a value of **1**, with probability  $q$ , and a value **0**, with probability  $1 - q$ , where  $q$  is the realized value of a random variable  $Q$  which is distributed uniformly over the interval  $[0, 1]$ . The realized value  $q$  is the same for every pixel.

Let  $X_i$  be the value of pixel  $i$ . We observe, for each pixel the value of  $Y_i = X_i + N$ , where  $N$  is normal with mean **2** and unit variance. (Note that we have the same noise at each pixel.) Assume that, conditional on  $Q$ , the  $X_i$ 's are independent, and that the noise  $N$  is independent of  $Q$  and the  $X_i$ 's.

1. Find  $\mathbf{E}[Y_i]$ . (Give a numerical answer.)

$$\mathbf{E}[Y_i] = \boxed{5/2} \quad \checkmark \text{ Answer: 2.5}$$

2. Find  $\mathbf{Var}[Y_i]$ . (Give a numerical answer.)

$$\mathbf{Var}[Y_i] = \boxed{5/4} \quad \checkmark \text{ Answer: 1.25}$$

3. Let  $A$  be the event that the actual values  $X_1$  and  $X_2$  of pixels **1** and **2**, respectively, are zero. Find the conditional probability of  $Q$  given  $A$ .  
(Enter your answer in terms of  $q$  in standard notation.)

For  $0 \leq q \leq 1$ :

$$f_{Q|A}(q) = \boxed{3 \cdot (1-q)^2} \quad \checkmark \text{ Answer: } 3 \cdot (1-q)^2$$

STANDARD NOTATION

#### Solution:

1. Notice that

$$\mathbf{E}[Y_i] = \mathbf{E}[X_i + N] = \mathbf{E}[X_i] + \mathbf{E}[N] = \mathbf{E}[X_i] + 2.$$

In order to find  $\mathbf{E}[X_i]$ , we will use the law of iterated expectations.

$$\mathbf{E}[X_i] = \mathbf{E}[\mathbf{E}[X_i | Q]] = \mathbf{E}[Q] = 0.5.$$

Hence,  $\mathbf{E}[Y_i] = 2.5$ .

2. Since  $X_i$  and  $N$  are independent,

$$\mathbf{Var}(X_i + N) = \mathbf{Var}(X_i) + \mathbf{Var}(N) = \mathbf{Var}(X_i) + 1.$$

In order to compute  $\mathbf{Var}(X_i)$ , we use the law of total variance as follows:

$$\begin{aligned} \mathbf{Var}(X_i) &= \mathbf{E}[\mathbf{Var}(X_i | Q)] + \mathbf{Var}(\mathbf{E}[X_i | Q]) \\ &= \mathbf{E}[Q(1-Q)] + \mathbf{Var}(Q) \end{aligned}$$

$$\begin{aligned}
 &= \mathbf{E}[Q] - \mathbf{E}[Q^2] + \mathbf{E}[Q^2] - (\mathbf{E}[Q])^2 \\
 &= \mathbf{E}[Q] - \mathbf{E}[Q]^2 \\
 &= 0.5 - 0.25 \\
 &= 0.25.
 \end{aligned}$$

A shorter derivation uses the fact  $\mathbf{X}_i = \mathbf{X}_i^2$  and proceeds as follows.

$$\begin{aligned}
 \mathbf{Var}(\mathbf{X}_i) &= \mathbf{E}[\mathbf{X}_i^2] - (\mathbf{E}[\mathbf{X}_i])^2 \\
 &= \mathbf{E}[\mathbf{X}_i] - (\mathbf{E}[\mathbf{X}_i])^2 \\
 &= 0.5 - 0.25 \\
 &= 0.25.
 \end{aligned}$$

Given  $\mathbf{Var}(\mathbf{X}_i) = 0,25$ ,

$$\mathbf{Var}(\mathbf{Y}_i) = \mathbf{Var}(\mathbf{X}_i + \mathbf{N}) = \mathbf{Var}(\mathbf{X}_i) + \mathbf{Var}(\mathbf{N}) = 1 + \frac{1}{4} = \frac{5}{4}.$$

3. Using Bayes' rule, we have for  $0 \leq q \leq 1$ ,

$$\begin{aligned}
 f_{Q|A}(q) &= \frac{f_Q(q)\mathbf{P}(A \mid Q = q)}{\mathbf{P}(A)} \\
 &= \frac{f_Q(q)\mathbf{P}(A \mid Q = q)}{\int_0^1 f_Q(q')\mathbf{P}(A \mid Q = q') \, dq'} \\
 &= \frac{1 \cdot (1 - q)^2}{\int_0^1 (1 - q')^2 \, dq'} \\
 &= 3(1 - q)^2.
 \end{aligned}$$

提交

You have used 1 of 3 attempts

**i** Answers are displayed within the problem

### Error and Bug Reports/Technical Issues

**Topic:** Exam 2 / 6. Image Corrupted with noise

显示讨论