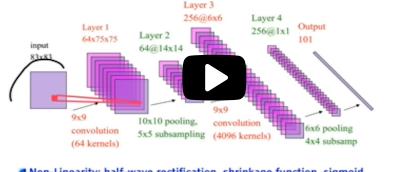
# 2. CNN - Continued Convolution Neural Networks (Continued)

## Convolutional Neural Network

Start of transcript. Skip to the end.



- Non-Linearity: half-wave rectification, shrinkage function, sigmoid
- Pooling: average, L1, L2, max

(Caption will be displayed when you start playing the video.)

All right.

So let's look at how to then actually construct

a convolutional neural network.

I will take input image here.

And now, since each convolution corresponds

to some weight matrix here associated with the little paths that I'm looking at, it corresponds to looking for a particular type of features

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#### CNN - Numerical Example

1/1 point (graded)

In this problem, we are going to work out the outputs of a tiny toy example of CNN that is made up of just one conv layer consisting of just one filter F of shape  $2 \times 2$  followed by a max-pooling layer of shape  $2 \times 2$ . The input image is of shape  $3 \times 3$ 

The output of the CNN is calculated as  $\operatorname{Pool}\left(\operatorname{ReLU}\left(\operatorname{Conv}\left(I\right)\right)\right)$  where ReLU is the rectified linear activation function given by:

$$\operatorname{ReLU}(x) = \max(0, x)$$

Also assume that the stride for the convolution and pool layers is  ${\bf 1}$ 

For the following values of the image I and filter weights F enter below the value of the output of the CNN (hint - it will be a single integer):

$$I = egin{bmatrix} 1 & 0 & 2 \ 3 & 1 & 0 \ 0 & 0 & 4 \end{bmatrix}$$

$$F = egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix}$$

#### **Solution:**

First let's calculate the output of the convolutional layer

$$I = egin{bmatrix} 1 & 0 & 2 \ 3 & 1 & 0 \ 0 & 0 & 4 \end{bmatrix}$$

$$F = egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix}$$

$$\operatorname{Conv}\left(I
ight) = egin{bmatrix} 1 & 0 & 2 \ 3 & 1 & 0 \ 0 & 0 & 4 \end{bmatrix} . egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix}$$

$$\operatorname{Conv}\left(I
ight) = egin{bmatrix} 2 & 0 \ 3 & 5 \end{bmatrix}$$

$$\operatorname{ReLU}\left(\operatorname{Conv}\left(I
ight)
ight)=\operatorname{ReLU}\left(egin{bmatrix}2&0\3&5\end{bmatrix}
ight)$$

$$\operatorname{ReLU}\left(\operatorname{Conv}\left(I
ight)
ight) = egin{bmatrix} 2 & 0 \ 3 & 5 \end{bmatrix}$$

$$\operatorname{Pool}\left(\operatorname{ReLU}\left(\operatorname{Conv}\left(I
ight)
ight)
ight)=\operatorname{Pool}\left(egin{bmatrix}2 & 0 \ 3 & 5\end{bmatrix}
ight)$$

$$\operatorname{Pool}\left(\operatorname{ReLU}\left(\operatorname{Conv}\left(I\right)\right)\right)=5$$

Submit

You have used 1 of 3 attempts

Answers are displayed within the problem

### **CNN Meaning**

1/1 point (graded)

If you are trying to recognize a large number of features, you should have a small number of filters.

true

false

Each filter represents a distinct set of weights, which corresponds to searching for a particular feature in the image. If you have a large number of features, you want many filters.	
Submit You have used 1 of 2 attempts	
Answers are displayed within the problem	
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