

## 5. Exercise: Normal unknown and additive noise

### Exercise: Normal unknown and additive noise

3/4 points (graded)

As in the last video, let  $\mathbf{X} = \boldsymbol{\Theta} + \mathbf{W}$ , where  $\boldsymbol{\Theta}$  and  $\mathbf{W}$  are independent normal random variables and  $\mathbf{W}$  has mean zero.

a) Assume that  $\mathbf{W}$  has positive variance. Are  $\mathbf{X}$  and  $\mathbf{W}$  independent?

No ▼

✓ Answer: No

b) Find the MAP estimator of  $\boldsymbol{\Theta}$  based on  $\mathbf{X}$  if  $\boldsymbol{\Theta} \sim N(1, 1)$  and  $\mathbf{W} \sim N(0, 1)$ , and evaluate the corresponding estimate if  $\mathbf{X} = 2$ .

$\hat{\boldsymbol{\theta}} =$

✓ Answer: 1.5

c) Find the MAP estimator of  $\boldsymbol{\Theta}$  based on  $\mathbf{X}$  if  $\boldsymbol{\Theta} \sim N(0, 1)$  and  $\mathbf{W} \sim N(0, 4)$ , and evaluate the corresponding estimate if  $\mathbf{X} = 2$ .

$\hat{\boldsymbol{\theta}} =$

✓ Answer: 0.4

d) For this part of the problem, suppose instead that  $\mathbf{X} = 2\boldsymbol{\Theta} + 3\mathbf{W}$ , where  $\boldsymbol{\Theta}$  and  $\mathbf{W}$  are standard normal random variables. Find the MAP estimator of  $\boldsymbol{\Theta}$  based on  $\mathbf{X}$  under this model and evaluate the corresponding estimate if  $\mathbf{X} = 2$ .

$\hat{\boldsymbol{\theta}} =$

✗ Answer: 0.30769

#### Solution:

a) They are not independent. This is intuitively clear because  $\mathbf{W}$  has an effect on  $\mathbf{X}$ . Another way to see it is that we have (by independence of  $\boldsymbol{\Theta}$  and  $\mathbf{W}$ ) that  $\mathbf{E}[\boldsymbol{\Theta}\mathbf{W}] = \mathbf{E}[\boldsymbol{\Theta}] \mathbf{E}[\mathbf{W}] = \mathbf{0}$ , which leads to

$$\mathbf{E}[\mathbf{X}\mathbf{W}] = \mathbf{E}[(\boldsymbol{\Theta} + \mathbf{W})\mathbf{W}] = \mathbf{E}[\mathbf{W}^2] \neq \mathbf{0} = \mathbf{E}[\mathbf{X}] \mathbf{E}[\mathbf{W}],$$

which in turn implies that  $\mathbf{X}$  and  $\mathbf{W}$  are not independent.

b) If we focus on the terms that involve  $\theta$ , the posterior is of the form

$$c(x)e^{-(\theta-1)^2/2}e^{-(x-\theta)^2/2}.$$

To find the MAP estimate, we set the derivative with respect to  $\theta$  of the exponent to zero, so that  $(\hat{\theta} - 1) + (\hat{\theta} - x) = 0$ , or  $\hat{\theta} = (1 + x)/2$ , which, when  $x = 2$ , evaluates to  $3/2$ .

c) If we focus on the terms that involve  $\theta$ , the posterior is of the form

$$c(x)e^{-\theta^2/2}e^{-(x-\theta)^2/(2 \cdot 4)}.$$

To find the MAP estimate, we set the derivative with respect to  $\theta$  of the exponent to zero, so that  $\hat{\theta} + (\hat{\theta} - x)/4 = 0$ , or  $\hat{\theta} = x/5$ , which, when  $x = 2$ , evaluates to  $2/5$ .

d) Note that conditional on  $\Theta = \theta$ , the random variable  $\mathbf{X}$  is normal with mean  $2\theta$  and variance  $9$ . If we focus on the terms that involve  $\theta$ , the posterior is of the form

$$c(x)e^{-\theta^2/2}e^{-(x-2\theta)^2/(2 \cdot 9)}.$$

To find the MAP estimate, we set the derivative with respect to  $\theta$  of the exponent to zero, so that  $\hat{\theta} + 2(2\hat{\theta} - x)/9 = 0$ , or  $\hat{\theta} = 2x/13$ , which, when  $x = 2$ , evaluates to  $4/13$ .

提交

You have used 3 of 3 attempts

**i** Answers are displayed within the problem

讨论

显示讨论

**Topic:** Unit 7 / Lec. 15 / 5. Exercise: Normal unknown and additive noise