

2. Passive-aggressive algorithm

In this problem, we will try to understand the loss in Passive-Aggressive (PA) Perceptron algorithm.

The passive-aggressive (PA) algorithm (without offset) responds to a labeled training example (x, y) by finding θ that minimizes

$$\frac{\lambda}{2} \|\theta - \theta^{(k)}\|^2 + \text{Loss}_h(y\theta \cdot x) \quad (3.5)$$

where $\theta^{(k)}$ is the current setting of the parameters prior to encountering (x, y) and

$$\text{Loss}_h(y\theta \cdot x) = \max\{0, 1 - y\theta \cdot x\}$$

is the hinge loss. We could replace the loss function with something else (e.g., the zero-one loss). The form of the update is similar to the perceptron algorithm, i.e.,

$$\theta^{(k+1)} = \theta^{(k)} + \eta yx \quad (3.6)$$

but the real-valued step-size parameter η is no longer equal to one; it now depends on both $\theta^{(k)}$ and the training example (x, y) .

Update equation

1/1 point (graded)

Consider minimizing the above defined loss function with the hinge loss component.

What happens to the step size at large values of λ ? Please choose one from the options below:

☐ If λ is large, the step-size of the algorithm (η) would be large

☒ If λ is large, the step-size of the algorithm (η) would be small ✓

Solution:

As λ increases, the passive-aggressive algorithm is dissuaded from updating very far from the previous θ . This is because λ serves as the weight for the regularization term (the portion that prevents overfitting: $\|\theta - \theta^{(k)}\|$) of the minimizing function.

Thus, as λ increases, we expect the step size between updates to decrease, so η should be smaller.

Submit

You have used 1 of 3 attempts

i Answers are displayed within the problem

Calculating the Step size

1/1 point (graded)

Suppose $\text{Loss}_h(y\theta^{(k+1)} \cdot x) > 0$ after the update. Express the value of η in terms of λ in this case. (Hint: you can simplify the loss function in this case).

1/lambda

✓ Answer: 1/lambda

$\frac{1}{\lambda}$

Solution:

When $\text{Loss}_h(y\theta^{(k+1)} \cdot x) > 0$, the hinge loss,

$$\max\{0, 1 - y\theta \cdot x\}$$

can be simply rewritten as $1 - y\theta \cdot x$. Thus, our minimizing function simplifies as follows:

$$\begin{aligned} f(\theta) &= \frac{\lambda}{2} \|\theta - \theta^{(k)}\|^2 + \text{Loss}_h(y\theta \cdot x) \\ &= \frac{\lambda}{2} \|\theta - \theta^{(k)}\|^2 + 1 - y\theta \cdot x \end{aligned}$$

We compute the minimum by setting gradient of $f(\theta)$ w.r.t. θ to 0:

$$\begin{aligned} \nabla_{\theta} f &= \lambda(\theta - \theta^{(k)}) - yx = 0 \\ (\theta - \theta^{(k)}) &= \frac{1}{\lambda} yx \\ \theta &= \theta^{(k)} + \frac{1}{\lambda} yx \end{aligned}$$

where $\frac{1}{\lambda}$ is just the step size.

Thus, $\eta = \frac{1}{\lambda}$ when $\text{Loss}_h(y\theta^{(k+1)} \cdot x) > 0$.

Submit

You have used 1 of 3 attempts

i Answers are displayed within the problem

Loss functions and decision boundaries

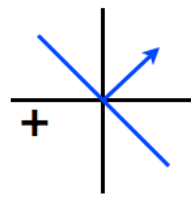
1.0/1.0 point (graded)

Consider minimizing the above defined loss function and the setting of our decision boundary plotted below. We ran our PA algorithm on the next data point in our sequence - a positively-labeled vector (indicated with a $+$). We plotted the results of our algorithm after the update, by trying out a few different variations of loss function and λ as follows:

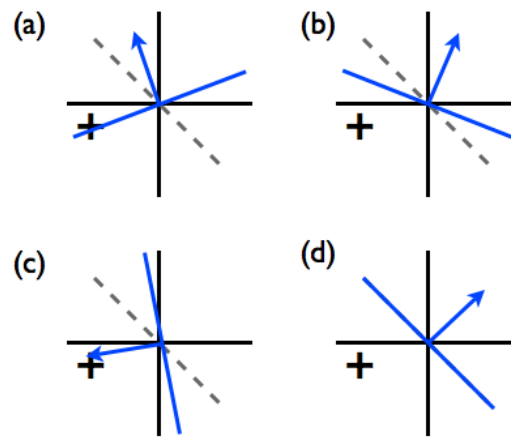
1. hinge loss and a large λ
2. hinge loss and a small λ
3. 0-1 loss and a large λ
4. 0-1 loss and a small λ

Each of the options below provides a matching between the 4 variations above with a decision boundary plotted in a-d below. Please choose the options that match them correctly. Note that the dotted lines correspond to the previous decision boundary, and the solid blue lines correspond to the new decision boundary; also, note that these are just sketches which ignore any changes to the magnitude of θ .

setting before update:



possible settings after update:



- (a) ✓ Answer: 0-1 loss, small lambda
- (b) ✓ Answer: Hinge loss, large lambda
- (c) ✓ Answer: Hinge loss, small lambda
- (d) ✓ Answer: 0-1 loss, large lambda

Solution:

- 1 - b hinge loss and a large λ . For hinge loss, loss can be improved by moving the θ vector towards the example. However, since λ is large, the change in θ term dominates, so θ only rotates slightly.
- 2 - c hinge loss and a small λ . For hinge loss, loss can be improved by moving the θ vector towards the example. Since λ is small, the loss term dominates, so the loss is minimized when the example is correctly classified. The difference between hinge loss and 0-1 loss with small λ is that hinge loss will correctly classify the example with a margin from the boundary. This is because hinge loss is minimized when $y\theta \cdot x \geq 1$ while 0-1 is when $y\theta \cdot x \geq 0$.
- 3 - d 0-1 loss and a large λ . Since the loss function is zero-one, it can only take on two values whether its classified correctly or not. With λ large, the change in θ term dominates. In order to minimize the change in θ , θ simply stays the same after the update and does not improve the loss at all.
- 4 - a 0-1 loss and a small λ . Since λ is small, the zero-one loss term dominates. Since the loss function can only improve when it is classified correctly, the example must be on the positive side. Because all correctly classified examples show the same loss, the secondary goal of minimizing the change in θ will cause the point to be immediately on the positive side of the decision boundary.

Submit

You have used 3 of 3 attempts

❗ Answers are displayed within the problem

Discussion

Show Discussion

Topic: Unit 1 Linear Classifiers and Generalizations (2 weeks):Homework 2 / 2. Passive-aggressive algorithm