

<u>Lecture 17: Introduction to</u>

<u>Course</u> > <u>Unit 5 Bayesian statistics</u> > <u>Bayesian Statistics</u>

7. The Posterior Distribution, Bayes'

> Formula

7. The Posterior Distribution, Bayes' Formula Clinical Trial Examples, Source of Priors



I COUID IIIAAIIIIIZE IL.

I could take its expectation.

I could do whatever I want but that's a different thing.

But really, if you did not have this guy right here

that would just be frequentist estimation.

You're just slapping on by multiplying your posterior.

So yeah, you don't need to understand that to actually learn it.

11:09 / 11:09

▶ 1.0x

) **X**

₹ 000

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Prior Implications to Posterior: True or False

0/1 point (graded)

Consider the case of a binary parameter $\theta \in \{0,1\}$. We have the prior distribution $\pi(\theta)$ that satisfies $\pi(0) = p$ and $\pi(1) = 1 - p$, for some $0 \le p \le 1$. Then, we observe X_1, \ldots, X_n with corresponding conditional likelihood function $L(X_1, \ldots, X_n | \theta)$ that is positive for both $\theta = 0$ and $\theta = 1$. Which of the following statements about the posterior distribution $\pi(\theta | X_1, \ldots, X_n)$ is true? (Choose all that apply.)

 $ule{1}$ If p=0, then the posterior distribution will be identical to the prior distribution. \checkmark

riangle If $p<rac{1}{2}$, then in the posterior distribution, $\pi\left(heta=0|X_1,\ldots,X_n
ight)\leq\pi\left(heta=1|X_1,\ldots,X_n
ight)$ will necessarily be true.

 $ext{ If } p>rac{1}{2}$, then in the posterior distribution, $\pi\left(heta=0|X_1,\ldots,X_n
ight)\geq\pi\left(heta=1|X_1,\ldots,X_n
ight)$ will necessarily be true.

×

Solution:

In the cases where p=0 or p=1, the prior distribution would have one of $\pi(0)$ or $\pi(1)$ as 1 and the other as zero. As Bayes' rule gives that the posterior distribution $\pi(\theta|X_1,\ldots,X_n)$ is the likelihood function $L(X_1,\ldots,X_n)$ multiplied by the prior distribution, this means that if the prior is 0 for a certain θ , the product will still be zero in the (un-normalized) posterior.

Furthermore, as we've assumed the likelihood to be positive for any θ , the product will be positive in the (un-normalized) posterior. Hence, after normalization, we will get a posterior probability of 1 for the θ that has a probability of 1 in the prior, and a 0 for the other, making the posterior identical to the prior. Thus the choices "If p=0, then the posterior distribution will be identical to the prior distribution." and "If p=1, then the posterior distribution will be identical to the prior distribution."

The third and fourth choices are incorrect because it is possible for the likelihood function to skew the posterior probability in the other direction. For example, consider a prior with $\pi(0)=0.3$, $\pi(1)=0.7$, as well as likelihoods $L(X_1,\ldots,X_n|\theta=0)=0.9$ and $L(X_1,\ldots,X_n|\theta=0)=0.1$. Then Bayes' rule gives $\pi(\theta=0|X_1,\ldots,X_n)=\frac{(0.3)(0.9)}{(0.3)(0.9)+(0.7)(0.1)}=\frac{27}{33}$ and $\pi(\theta=1|X_1,\ldots,X_n)=\frac{(0.7)(0.1)}{(0.3)(0.9)+(0.7)(0.1)}=\frac{7}{33}$ so we get $\pi(\theta=0|X_1,\ldots,X_n)>\pi(\theta=1|X_1,\ldots,X_n)$, contrary to the third statement

A similar example where the roles of $\theta=0$ and $\theta=1$ are reversed would disprove the fourth choice.

Submit

You have used 2 of 2 attempts

1 Answers are displayed within the problem

Updating Prior (Belief Propagation)

1/1 point (graded)

In this problem, we will explore how to update the belief successively, having observed data. The model is as follows:

- $\theta \in \Theta$, the parameter space; and $\pi(\cdot)$ is the prior distribution of θ .
- We observe i.i.d. (conditional on the parameter) data X_1, \ldots, X_n and calculate the likelihood function $L_n(X_1, \ldots, X_n | \theta)$ (as in the setting of maximum likelihood estimation)
- Write $\phi(X_1, \ldots, X_n)$ as a placeholder function that depends on X_1, \ldots, X_n , but not on the parameter θ . (ϕ could stand for different functions in different equations. It's simply a placeholder whenever we want to collect terms that only depend on X_1, \ldots, X_n .)

In this context, we add observations one by one, computing the likelihood $L_i(X_1,\ldots,X_i|\theta)$ and posterior $\pi(\theta|X_1,\ldots,X_i)$ after each observation i. Which of the following identities are true? (Choose all that apply.)

$$otag$$
 $\pi\left(heta|X_{1},\ldots,X_{n}
ight)=\pi\left(heta
ight)\cdot L_{n}\left(X_{1},\ldots,X_{n}| heta
ight)\cdot\phi\left(X_{1},\ldots,X_{n}
ight)$

$$olimits L_n\left(X_1,\ldots,X_n| heta
ight) = L_{n-1}\left(X_1,\ldots,X_{n-1}| heta
ight) \cdot L_1\left(X_n| heta
ight) \checkmark$$

$$igwedge L_n\left(X_1,\ldots,X_n| heta
ight)=rac{\pi(heta|X_1,\ldots,X_n)}{\pi(heta)}\phi\left(X_1,\ldots,X_n
ight)$$

~

Solution:

All the choices are correct. To see this, we proceed as follows. For brevity of notation, let $\alpha_n = \pi(\theta|X_1,\ldots,X_n)$; $\beta_n = L_n(X_1,X_2,\ldots,X_n|\theta)$. We also use X as a compact notation to represent X_1,X_2,\ldots,X_n , so that $\phi(X)$ corresponds to $\phi(X_1,\ldots,X_N)$.

• Note that, using Bayes' rule,

$$egin{aligned} lpha_n\left(heta
ight) &= \pi\left(heta|X_1,\ldots,X_n
ight) = rac{p_n\left(X_1,\ldots,X_n| heta
ight)\pi\left(heta
ight)}{\int_{\Theta}p_n\left(X_1,\ldots,X_n|t
ight)\pi\left(t
ight)\,dt} \ &= \pi\left(heta
ight)eta_n\left(heta
ight)\phi\left(X
ight), \end{aligned}$$

where, $\phi\left(X
ight)$ captures the term in the denominator. This does not depend on heta as we have already integrated over the variable.

• Similarly, using the independence of X_1,\ldots,X_n conditional on heta,

$$eta_{n}\left(heta
ight)=p_{n}\left(X_{1},\ldots,X_{n}| heta
ight)=p_{n-1}\left(X_{1},\ldots,X_{n-1}| heta
ight)\cdot p\left(X_{n}| heta
ight)=eta_{n-1}\left(heta
ight)\cdot p\left(X_{n}| heta
ight).$$

• For this part, note that,

$$egin{aligned} lpha_n\left(heta
ight) &= \pi\left(heta|X_1,\ldots,X_n
ight) \ &= rac{p_n\left(X_1,\ldots,X_n| heta
ight)\pi\left(heta
ight)}{\widetilde{\phi}\left(X
ight)} \ &= rac{p_{n-1}\left(X_1,\ldots,X_{n-1}| heta
ight)\pi\left(heta
ight)p\left(X_n| heta
ight)}{\phi\left(X
ight)} \ &\propto p\left(X_n| heta
ight)\underbrace{p_{n-1}\left(X_1,\ldots,X_{n-1}| heta
ight)\pi\left(heta
ight)}_{\proptolpha_{n-1}(heta)} \ &\propto lpha_{n-1}\left(heta
ight)p\left(X_n| heta
ight). \end{aligned}$$

• This follows by rearranging the first identity and taking the reciprocal of ϕ .

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You have used 1 of 2 attempts

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Discussion

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