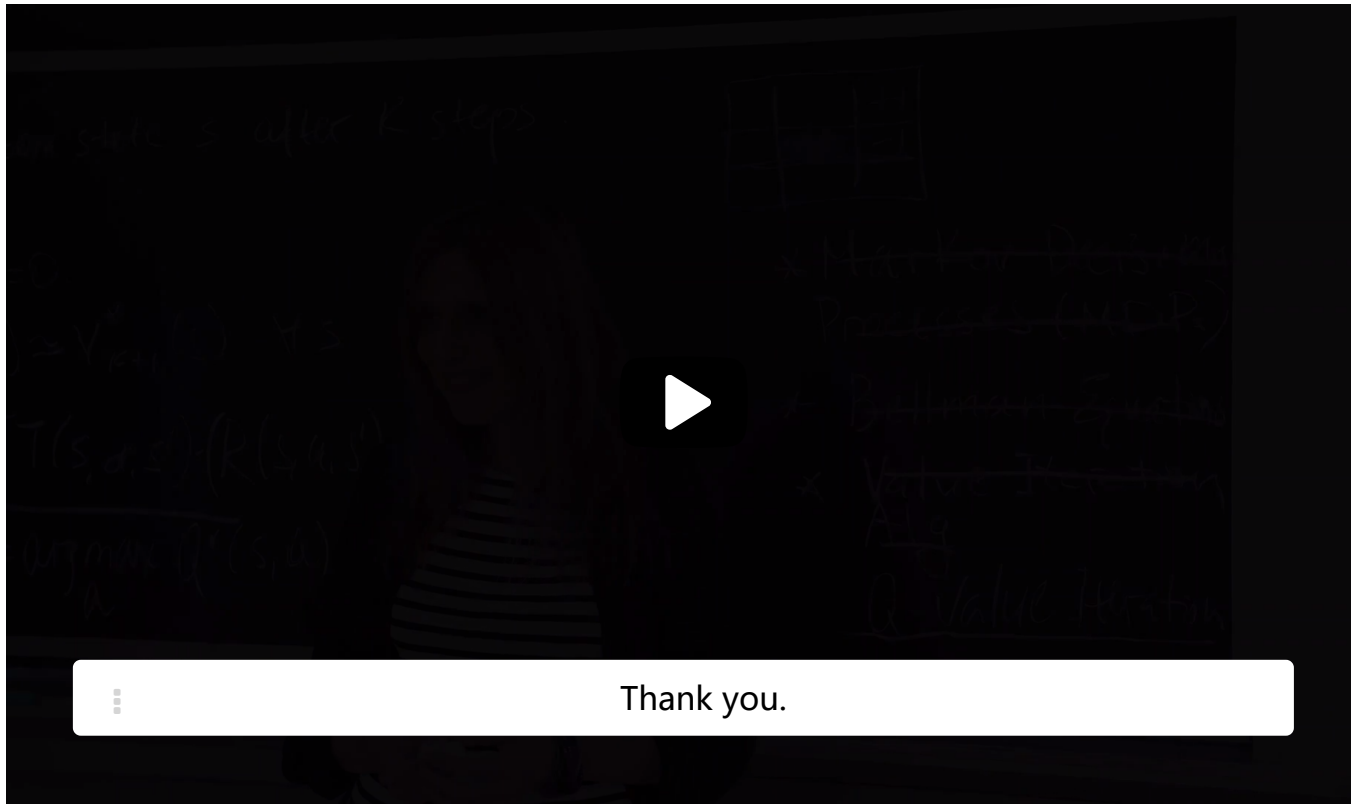


8. Q-value Iteration

Q-value Iteration



and directly get Q^* .

And that's exactly what you will do in your exercise.

You will reformulate this algorithm

and get a new algorithm which is called Q value iterations.

But the idea-- exactly the same.

And we will use this algorithm in our discussion

about reinforcement learning next time.

Thank you.



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The derivation of the Q-value iteration update rule from the equation above is similar to the derivation of the value iteration update rule.

First, recall the Bellman equations:

$$V^*(s) = \max_a Q^*(s, a)$$

$$Q^*(s, a) = \sum_{s'} T(s, a, s') (R(s, a, s') + \gamma V^*(s')).$$

Plugging first equation into the second, we get:

$$Q^*(s, a) = \sum_{s'} T(s, a, s') \left(R(s, a, s') + \gamma \max_{a'} Q^*(s', a') \right).$$

Now, let $Q_k^*(s, a)$ be the expected rewards from state s followed by action a , and then acting optimally for k steps afterwards. (Hence, $V_k^*(s) = \max_a Q_k^*(s, a)$.)

Q-value Iteration Update Rule

1/1 point (graded)

Referring to the equations above, what should the Q-value iteration update rule be?

☐ $Q_{k+1}^*(s, a) = \sum_{s'} T(s, a, s') (R(s, a, s') + \gamma \max_{s'} Q_k^*(s', a))$

☐ $Q_{k+1}^*(s, a) = \sum_{s'} T(s, a, s') (R(s, a, s') + \gamma V^*(s'))$

☒ $Q_{k+1}^*(s, a) = \sum_{s'} T(s, a, s') (R(s, a, s') + \gamma \max_{a'} Q_k^*(s', a')) \checkmark$

☐ $Q_{k+1}^*(s, a) = \sum_{s'} T(s, a, s') (R(s, a, s') + \gamma Q_k^*(s', a))$

Solution:

Q-value iteration would use the previous iteration of the Q-value on the right hand side of the equation

$$Q^*(s, a) = \sum_{s'} T(s, a, s') \left(R(s, a, s') + \gamma \max_{a'} Q^*(s', a') \right)$$

to update the Q value estimate of the current step. Hence, the Q value update for k^{th} step would look like:

$$Q_{k+1}^*(s, a) = \sum_{s'} T(s, a, s') (R(s, a, s') + \gamma \max_{a'} Q_k^*(s', a')) .$$

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You have used 1 of 2 attempts

i Answers are displayed within the problem

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