

OS02 - Written Exam 2 - Theory of Estimation - Solutions

Problem 1 (≈ 6 points). *The covariance between two jointly distributed (under $P_{\xi,\eta}$) random variables ξ and η is defined as follows*

$$\gamma = \mathbb{E}[(\xi - \mathbb{E}\xi)(\eta - \mathbb{E}\eta)].$$

The independent random vectors

$$\begin{pmatrix} \xi_1 \\ \eta_1 \end{pmatrix}, \begin{pmatrix} \xi_2 \\ \eta_2 \end{pmatrix}, \dots, \begin{pmatrix} \xi_n \\ \eta_n \end{pmatrix}$$

are assumed to come from the distribution $P_{\xi,\eta}$. It is also assumed that $\mathbb{E}|\xi| < \infty$, $\mathbb{E}|\eta| < \infty$ and $\mathbb{E}|\xi\eta| < \infty$. The sampling covariance is defined as follows

$$\hat{\gamma} = \frac{1}{n} \sum_{i=1}^n (\xi_i - \bar{\xi})(\eta_i - \bar{\eta}), \quad \bar{\xi} = \frac{1}{n} \sum_{i=1}^n \xi_i, \quad \bar{\eta} = \frac{1}{n} \sum_{i=1}^n \eta_i.$$

1. *Prove that $\hat{\gamma}$ is a consistent estimator of γ (by using theorems and definitions).*

1. Solution : First of all, let us re-write the theoretical covariance γ and sampling covariance $\hat{\gamma}$ in the following manner

$$\begin{aligned} \gamma &= \mathbb{E}[(\xi - \mathbb{E}\xi)(\eta - \mathbb{E}\eta)] = \mathbb{E}(\xi\eta) - \mathbb{E}(\xi) \cdot \mathbb{E}(\eta), \\ \hat{\gamma} &= \frac{1}{n} \sum_{i=1}^n (\xi_i - \bar{\xi})(\eta_i - \bar{\eta}) = \frac{1}{n} \sum_{i=1}^n \xi_i \eta_i - \bar{\xi} \cdot \bar{\eta} = \frac{1}{n} \sum_{i=1}^n \xi_i \eta_i - \frac{1}{n} \sum_{i=1}^n \xi_i \cdot \frac{1}{n} \sum_{i=1}^n \eta_i. \end{aligned}$$

Second, as it follows from the law of large numbers (assuming that $\mathbb{E}|\xi| < \infty$, $\mathbb{E}|\eta| < \infty$ and $\mathbb{E}|\xi\eta| < \infty$), if $n \rightarrow \infty$, then

$$\frac{1}{n} \sum_{i=1}^n \xi_i \xrightarrow[\mathbb{P}]{} \mathbb{E}(\xi), \quad \frac{1}{n} \sum_{i=1}^n \eta_i \xrightarrow[\mathbb{P}]{} \mathbb{E}(\eta), \quad \text{and} \quad \frac{1}{n} \sum_{i=1}^n \xi_i \eta_i \xrightarrow[\mathbb{P}]{} \mathbb{E}(\xi \cdot \eta).$$

Third, let us define the following continuous real function f of three real variables :

$$(x, y, z) \mapsto f(x, y, z) = x - y \cdot z.$$

Finally, by using the continuity theorem, we get (when $n \rightarrow \infty$)

$$\hat{\gamma} = \frac{1}{n} \sum_{i=1}^n (\xi_i - \bar{\xi})(\eta_i - \bar{\eta}) = f\left(\frac{1}{n} \sum_{i=1}^n \xi_i \eta_i, \frac{1}{n} \sum_{i=1}^n \xi_i, \frac{1}{n} \sum_{i=1}^n \eta_i\right) \xrightarrow[\mathbb{P}]{} f(\mathbb{E}(\xi\eta), \mathbb{E}(\xi), \mathbb{E}(\eta)) = \gamma.$$

Hence, as it follows from the definition, $\hat{\gamma}$ is a consistent estimator of γ .

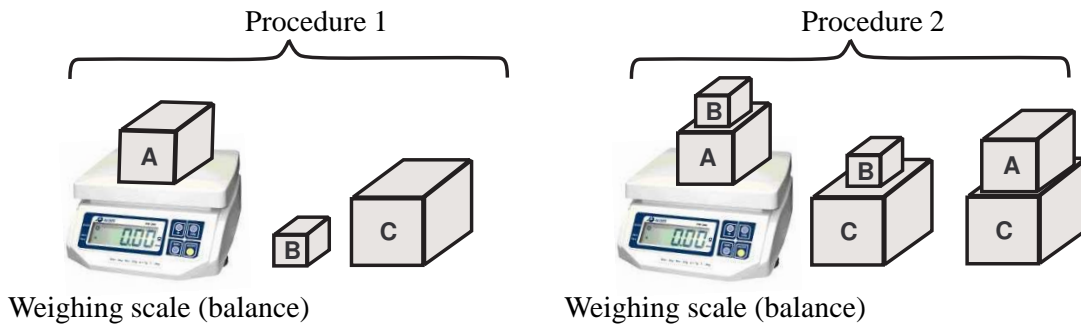


FIGURE 1 – Two different weighing procedures.

Problem 2 (≈ 7 points). Let us consider three objects A, B and C. The true masses of these objects are denoted by α , β and γ , respectively. We have a weighing scale (balance), see Figure 1. We wish to compare two different weighing procedures to estimate the unknown masses α , β and γ :

1. individual weighing : we repeat this procedure 3 times (for A, B and C). Only one object (A or B or C) is installed on the balance at once.
2. pair weighing : we repeat this procedure 3 times (for A+B, B+C and A+C). Two objects (A+B or B+C or A+C) are installed on the balance at once.

These procedures are illustrated in Figure 1. Let us consider the following additive measurement model of balance :

$$y = x + \xi, \quad \xi \sim \mathcal{N}(0, \sigma^2),$$

where x is the true mass of object, y is the measured (estimated) value of x and ξ is measurement noise. It is assumed that the variance of noise σ^2 is constant (and independent of the true mass).

1. Write down the measurement models for both weighing procedures.
2. Find the estimators $\hat{\alpha}$, $\hat{\beta}$ and $\hat{\gamma}$ for the unknown masses α , β and γ , respectively, by the method of moments for both weighing procedures. The first order moment can be used (see the hint on page 3).
3. Calculate the variances of the estimators $\hat{\alpha}$, $\hat{\beta}$ and $\hat{\gamma}$ for each procedure.
4. Compare the variances of the first procedure with the variances of the second procedure. Which procedure is more precise (i.e. which variances are smaller) ?

Solution :

1. (1 point) The measurement model of procedure 1 :

$$\begin{cases} y_1 = \alpha + \xi_1 \\ y_2 = \beta + \xi_2 \\ y_3 = \gamma + \xi_3 \end{cases}, \quad \xi_i \sim \mathcal{N}(0, \sigma^2).$$

The measurement model of procedure 2 :

$$\begin{cases} y_1 = \alpha + \beta + \xi_1 \\ y_2 = \beta + \gamma + \xi_2 \\ y_3 = \alpha + \gamma + \xi_3 \end{cases}, \quad \xi_i \sim \mathcal{N}(0, \sigma^2).$$

2. (2.5 points) The method of moments estimator for procedure 1 :

$$\begin{cases} \mathbb{E}(y_1) = \alpha \\ \mathbb{E}(y_2) = \beta \\ \mathbb{E}(y_3) = \gamma \end{cases} \Rightarrow \begin{cases} \hat{\alpha} = y_1 \\ \hat{\beta} = y_2 \\ \hat{\gamma} = y_3 \end{cases}.$$

The method of moments estimator for procedure 2 :

$$\begin{cases} \mathbb{E}(y_1) = \alpha + \beta \\ \mathbb{E}(y_2) = \beta + \gamma \\ \mathbb{E}(y_3) = \alpha + \gamma \end{cases} \Rightarrow \begin{cases} \hat{\alpha} + \hat{\beta} = y_1 \\ \hat{\beta} + \hat{\gamma} = y_2 \\ \hat{\alpha} + \hat{\gamma} = y_3 \end{cases}$$

or

$$\hat{\theta} = B^{-1}Y \Leftrightarrow \begin{pmatrix} \hat{\alpha} \\ \hat{\beta} \\ \hat{\gamma} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix}^{-1} \cdot \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} \cdot \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}.$$

3. (2.5 points) The variances of the estimators for procedure 1 are :

$$\begin{cases} \hat{\alpha} = \alpha + \xi_1 \\ \hat{\beta} = \beta + \xi_2 \\ \hat{\gamma} = \gamma + \xi_3 \end{cases}, \quad \xi_i \sim \mathcal{N}(0, \sigma^2) \Rightarrow \text{var}(\hat{\alpha}) = \text{var}(\hat{\beta}) = \text{var}(\hat{\gamma}) = \sigma^2.$$

The expectation of the estimator for procedure 2 is

$$\mathbb{E}(\hat{\theta}) = \mathbb{E}[B^{-1}(B\theta + \xi)] = \theta + \mathbb{E}[B^{-1}\xi] = \theta$$

and the variance-covariance matrix of the estimator is

$$\begin{aligned} \text{cov}(\hat{\theta}) &= \mathbb{E}\left[(\hat{\theta} - \theta)(\hat{\theta} - \theta)^T\right] = \mathbb{E}[B^{-1}\xi\xi^T B^{-T}] = \sigma^2 B^{-1} B^{-T} \\ &= \sigma^2 \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} \cdot \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \end{pmatrix} = \sigma^2 \begin{pmatrix} \frac{3}{4} & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & \frac{3}{4} & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & \frac{3}{4} \end{pmatrix}. \end{aligned}$$

Hence, the variances of the estimators for procedure 2 are

$$\text{var}(\hat{\alpha}) = \text{var}(\hat{\beta}) = \text{var}(\hat{\gamma}) = \frac{3\sigma^2}{4}.$$

4. (1 point) The variances of procedure 2 are smaller : $\frac{3\sigma^2}{4} < \sigma^2$.

Problem 3 (≈ 7 points). The independent observations (ξ_1, \dots, ξ_n) are assumed to come from the Poisson distribution $\Pi(\lambda)$, where $\lambda > 0$ is a parameter. But we wish to estimate another parameter θ , which is defined as the following function of λ :

$$\theta = \theta(\lambda) = \lambda e^{-\lambda},$$

by using the same observations (ξ_1, \dots, ξ_n) . Let us consider the two following heuristic estimators :

$$\hat{\theta}_1 = \bar{\xi} e^{-\bar{\xi}}, \text{ where } \bar{\xi} = \frac{1}{n} \sum_{i=1}^n \xi_i,$$

$$\hat{\theta}_2 = \frac{1}{n} \sum_{j=1}^n \mathbb{I}_{\{\xi_j=1\}}, \text{ where } \mathbb{I}_{\{\xi_j=1\}} = \begin{cases} 1 & \text{si } \xi_j = 1 \\ 0 & \text{si } \xi_j \neq 1 \end{cases} \text{ is the indicator function of the event } \{\xi_j = 1\}.$$

1. Is the estimator $\hat{\theta}_1$ biased? If the answer is “yes”, then calculate the mean error $\lambda \rightarrow b_1(\lambda)$. Is the estimator $\hat{\theta}_1$ asymptotically biased?
2. Is the estimator $\hat{\theta}_2$ biased? If the answer is “yes”, then calculate the mean error $\lambda \rightarrow b_2(\lambda)$. Is the estimator $\hat{\theta}_2$ asymptotically biased?
3. Can $\hat{\theta}_2$ be interpreted as a method of moments estimator? If the answer is “yes”, how to choose the function $x \mapsto g(x)$?
4. Are the estimators $\hat{\theta}_1$ and $\hat{\theta}_2$ consistent?

Hint. If $\xi_i \sim \Pi(\lambda)$, then $\sum_{i=1}^n \xi_i \sim \Pi(n\lambda)$.

Hint.

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} \text{ for } |x| < \infty.$$

Solution :

1. (3 points) Calculate the expectation of $\hat{\theta}_1 = \bar{\xi} e^{-\bar{\xi}}$:

$$\mathbb{E}(\hat{\theta}_1) = \mathbb{E}(\bar{\xi} e^{-\bar{\xi}}) = \mathbb{E}\left(\frac{\zeta}{n} e^{-\frac{\zeta}{n}}\right),$$

where $\zeta = n\bar{\xi}$. If $\xi_i \sim \Pi(\lambda)$, then $\zeta = n\bar{\xi} = \sum_{i=1}^n \xi_i \sim \Pi(n\lambda)$. Therefore (taking into account the hints)

$$\begin{aligned} \mathbb{E}(\hat{\theta}_1) &= \sum_{k=0}^{\infty} \frac{k}{n} e^{-\frac{k}{n}} \mathbb{P}(\zeta = k) = \sum_{k=0}^{\infty} \frac{k}{n} e^{-\frac{k}{n}} \frac{(n\lambda)^k}{k!} e^{-n\lambda} = \frac{e^{-n\lambda}}{n} \sum_{k=1}^{\infty} \frac{(n\lambda e^{-\frac{1}{n}})^k}{(k-1)!} \\ &= (n\lambda e^{-\frac{1}{n}}) \frac{e^{-n\lambda}}{n} \sum_{k=1}^{\infty} \frac{(n\lambda e^{-\frac{1}{n}})^{k-1}}{(k-1)!} = (n\lambda e^{-\frac{1}{n}}) \frac{e^{-n\lambda}}{n} e^{(n\lambda e^{-\frac{1}{n}})} = \lambda e^{n\lambda(e^{-\frac{1}{n}}-1)-\frac{1}{n}}. \end{aligned}$$

Finally, we get

$$\mathbb{E}(\hat{\theta}_1) = \lambda e^{n\lambda(e^{-\frac{1}{n}}-1)-\frac{1}{n}} \neq \theta(\lambda) = \lambda e^{-\lambda},$$

hence, the estimator $\hat{\theta}_1$ is biased and the mean error is $\lambda \rightarrow b_1(\lambda) = \lambda e^{n\lambda(e^{-\frac{1}{n}}-1)-\frac{1}{n}} - \lambda e^{-\lambda}$. By using the hint, we get after simple algebra that

$$\lim_{n \rightarrow \infty} \lambda e^{n\lambda\left(\sum_{k=0}^{\infty} \frac{(-1/n)^k}{k!} - 1\right) - \frac{1}{n}} = \lambda e^{-\lambda}.$$

It implies that the estimator $\hat{\theta}_1$ is asymptotically unbiased.

2. (1 point) Calculate the expectation of $\hat{\theta}_2 = \frac{1}{n} \sum_{j=1}^n \mathbb{I}_{\{\xi_j=1\}}$:

$$\mathbb{E}(\hat{\theta}_2) = \mathbb{E}\left(\frac{1}{n} \sum_{j=1}^n \mathbb{I}_{\{\xi_j=1\}}\right) = n \frac{1}{n} \mathbb{E}(\mathbb{I}_{\{\xi_1=1\}}) = \mathbb{P}(\xi_1 = 1) = \lambda e^{-\lambda} = \theta(\lambda).$$

Hence, the estimator $\hat{\theta}_2$ is unbiased.

3. (1 point) Yes, the estimator $\hat{\theta}_2$ can be interpreted as a method of moments estimator. The function g is defined as follows $x \mapsto g(x) = \mathbb{I}_{\{x=1\}}$.

4. (2 points) As it follows from the law of large numbers, if $n \rightarrow \infty$, then $\bar{\xi} = \frac{1}{n} \sum_{i=1}^n \xi_i \xrightarrow{\mathbb{P}} \mathbb{E}(\xi) = \lambda$. Taking into account the continuity theorem with the continuous function $f(x) = xe^{-x}$, we get

$$\hat{\theta}_1 = \frac{1}{n} \sum_{i=1}^n \xi_i e^{-\frac{1}{n} \sum_{i=1}^n \xi_i} \xrightarrow{\mathbb{P}} \lambda e^{-\lambda} = \theta(\lambda).$$

The estimator $\hat{\theta}_1$ is consistent.

Let us define a sequence of independent binary random variables $\mathbb{I}_{\{\xi_1=1\}}, \mathbb{I}_{\{\xi_2=1\}}, \dots, \mathbb{I}_{\{\xi_n=1\}}$ ($\mathbb{I}_{\{\xi_i=1\}}$ obeys a Bernoulli distribution). As it follows from the law of large numbers, if $n \rightarrow \infty$, then

$$\hat{\theta}_2 = \frac{1}{n} \sum_{j=1}^n \mathbb{I}_{\{\xi_j=1\}} \xrightarrow{\mathbb{P}} \mathbb{E}(\mathbb{I}_{\{\xi_1=1\}}) = \lambda e^{-\lambda} = \theta(\lambda).$$

The estimator $\hat{\theta}_2$ is consistent.