



# Advanced method for decision Pattern recognition

One class SVM

- Chapitre 4 -

## **Outline**

- Introduction
- 2 Methods and properties
  - 1C-SVM
  - 1C-SVM Variantes
- Optimization
  - SMO approach
  - Regularization path
- Other approach
  - PCA
  - KPCA
- Conclusion

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# Motivations

# **Motivations**

- Novelty detection
- Quantile estimation

# **Situations**

- Only one kind of observations are available
- Classes without samples
- Sensor failures
- **a** . . .

## **Problem**

- A representation space  $\mathcal{X}_I \subseteq \mathbb{R}^I$
- A data set of iid observations  $A_n = \{x_{1:n}\}$
- A random variable X follows an unknown probability distribution P.

# Aim:

Estimate a "simple" subset  $S \subset \mathcal{X}_I$  such that  $P(X \ni S) = 1 - \mu$  with  $\mu$  a predefined value.

# Main elements of solutions

- ullet Approximate the solution using a function f
- f(x) > 0 if  $x \in S$
- f is a linear combination of kernels expressed in a transformed space
- f is determined by solving a quadratic problem

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# **Support and Quantiles**

- ullet A data set of iid observations  $A_n = \{x_{1:n}\}$  with  $x_i \in \mathcal{X}_m$
- The RV X follows an unknown probability distribution P
- $\bullet$  C is the class of the measurable subsets  $\mathcal{X}_m$
- ullet  $\lambda$  a measurement function defined on  ${\cal C}$

#### Definition:

•  $U(\mu)$  is a quantile if :

$$U(\mu) = \inf\{\lambda(C)|P(C) \ge \mu, C \in \mathcal{C}\}\$$

Intepretation:

The smallest subset containing a probability mass  $\mu$ .

Remark:

U(1) is the support of P

# Estimation of a quantile

Empirical estimator :

$$P_{emp}^{n}(C) = \frac{1}{n} \sum_{i=1}^{n} I_{C}(x_{i})$$

•  $C_{\lambda}(\mu)$ ,  $C_{\lambda}^{n}(\mu)$ : the C which reach the infimum (greatest lower bound).

Standard measure : the "volume" of C (Lebesgue measure) We seek C with "minimal" volume Determine an estimate of minimum volume  $C_{\lambda}^{n}(\mu)$  is insuffisant : Ensure ability to generalize.

## Quantile estimation

# Consequences

- tradeoff between quality of learning complexity of the learner (VC dimension).
- Restrict or control the set of subsets C eligible.
- ullet With kernel methods : implicit definition of  ${\mathcal C}$  via  ${\mathcal K}$
- Minimize a quadratic form in the Hilbert space which allows to control the complexity of the function defining C
- We use  $\lambda(C_{w,\rho}) = ||w||^2$  (small VC dimension) with  $C_{w,\rho} = \{x | f_w(x) \ge \rho\}$

## aim:

- Find the best hyperplane that separates the data from the origin
- Maximize the margin
- The value of f(x) depends on the position x with respect to the hyperplane

To find f we solve :

$$\begin{array}{ll} \underset{w \in \mathcal{H}, \xi, \rho}{\text{minimize}} & \frac{1}{2} \|w\|^2 - \rho + \frac{1}{n\nu} \sum_{i=1}^n \xi_i \\ \text{with} & \langle w, \Phi(x_i) \rangle \geq \rho - \xi_i \\ \text{and} & \xi_i \geq 0 \quad \forall i = 1: n \end{array}$$

with 
$$\nu \in ]0,1]$$
.  
 $f(x) = signe(\langle w, \Phi(x) \rangle - \rho)$ 

#### Resolution:

$$\mathfrak{L}(w,\xi,\rho,\alpha,\beta) = \frac{1}{2} \|w\|^2 + \frac{1}{n\nu} \sum_{i=1}^n \xi_i$$

$$-\sum_i \alpha_i (\langle w, \Phi(x_i) \rangle - \rho + \xi_i) - \sum_i \beta_i \xi_i - \rho$$
avec  $\alpha_i \ge 0 \quad \beta_i \ge 0$ 

Cancelling derivatives with respect to variables of the primal problem :

• 
$$w = \sum_{i} \alpha_{i} \Phi(x_{i})$$

• 
$$0 \le \alpha_i \le \frac{1}{\nu n}$$

• 
$$\sum_i \alpha_i = 1$$

#### **Dual Problem:**

$$\begin{array}{ll} \underset{\alpha}{\text{minimize}} & \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j \mathcal{K}(x_i,x_j) \\ \\ \text{with} & 0 \leq \alpha_i \leq \frac{1}{\nu n} \text{and} & \sum_i \alpha_i = 1 \end{array}$$

and

$$\rho = \sum_{j} (\alpha_{j} K(x_{j}, x_{i})) \text{ quand } \alpha_{i} \in ]0, \frac{1}{\nu n}[$$

due to KKT conditions.

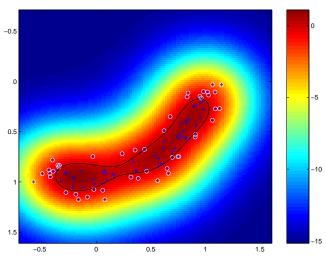


Figure: nu\_1svm

# Link with Parzen windows:

- Knormalized as a density (Gaussian case)
- $\nu = 1$

## Consequence:

- $\alpha_{1:n} = \frac{1}{n}$
- This is the Parzen estimator of a probability density function

#### Remark:

If K is normalized,  $\sum_i \alpha_i K(x_i, x)$  is a probability density that is based solely on the SV.

# Property 1:

If the data  $\{\Phi(x_{1:n})\}$  are separable then there is only one hyperplane :

- separating all the data from the origin
- maximizing the distance from the origin

This hyperplane is the solution of problem  $\rho > 0$ :

$$\begin{array}{ll} \underset{w}{\text{minimize}} & \frac{1}{2}\|w\|^2 \\ & \text{with} & \langle w, \phi(x_i) \rangle \geq \rho \end{array}$$

# Property 2:

- Consider the separating hyperplane defined by  $(w, \rho)$  for the data  $\{(\Phi(x_{1:n}), 1)\}$  then this hyperplane (w, 0) is the optimal hyperplane of the data set  $\{(\Phi(x_{1:n}), 1), (-\Phi(x_{1:n}), -1)\}$ .
- Consider (w,0) the optimal hyperplane separating a set of labeled data :  $\{(\Phi(x_{1:n}),y_{1:n})\}$  defined such that  $\langle w,\phi(x_i)\rangle>0$  if  $y_i=1$ . Moreover, if  $\frac{\rho}{\|w\|}$  is the margin of this hyperplane, then  $(w,\rho)$  define the support hyperplane for the data set  $\{(\Phi(x_{1:n}),1)\}$ .

**Property 3 :** If the solution of the 1C-SVM problem is such that  $\rho \neq 0$ , then

- ullet u is an upper bound of the proportion of outliers
- ullet  $\nu$  is a lower bound of the proportion of SV

$$PropExclus \le \nu \le PropSVs$$

• If the data are iid according to a continuous distribution function P and the kernel is non-constant then  $\nu$  is asymptotically equal to the fraction of SVs and excluded.

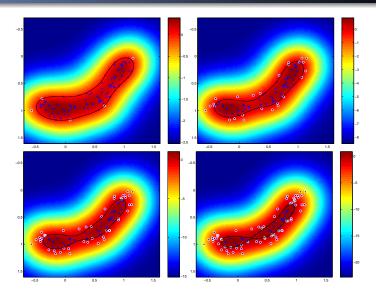


Figure: Examples of  $\nu$ -1sym with  $\nu = 0.1, 0.3, 0.5, 0.7$ 

#### **SVDD**

#### Aim:

- $\bullet$  Find the hypersphere with minimum volume that contains all observations excepted a fraction  $\nu$
- The hypersphere is defined by the position of its center a and its radius R

## Problem formulation:

minimize 
$$R^{2} + \frac{1}{n\nu} \sum_{i} \xi_{i}$$
with 
$$\|a - \Phi(x_{i})\|^{2} \le R^{2} + \xi_{i}$$
and 
$$\xi_{i} \ge 0 \quad \forall i = 1: n$$

#### Resolution:

$$\mathfrak{L}(R, a, \xi) = R^2 + \frac{1}{n\nu} \sum_{i} \xi_i - \sum_{i} (\alpha_i (R^2 + \xi_i - \|a - \Phi(x_i)\|^2)) - \sum_{i} \beta_i \xi_i$$
with
$$\xi_i \ge 0 \quad \alpha_i \ge 0 \quad \beta_i \ge 0 \quad \forall i = 1 : n$$

#### **Dual Problem:**

$$\begin{array}{ll} \underset{\alpha}{\text{minimize}} & \sum_{i,j} \alpha_i \alpha_j K(x_i, x_j) - \sum_i \alpha_i K(x_i, x_i) \\ & \text{with} & 0 \leq \alpha_i \leq \frac{1}{\nu n} \quad \forall i = 1: n \text{and} & \sum_i \alpha_i = 1 \end{array}$$

# Equivalence:

- If  $K(x_i, x_i) = Cte$  then SVDD  $\Leftrightarrow \nu$ -1SVM
- If K(x, x') depends only on x x' SVDD  $\Leftrightarrow \nu$ -1SVM

Faire figure

#### Discriminant 1CSVM

**Contexte:** It is assumed that we have observations that do not belong to the target class

#### Problem formulation:

Let  $n_1$  be the number of samples that belong to class  $\omega_1$  and  $n_2$  the number of other observations,

$$\begin{split} \min_{w \in \mathcal{H}, \xi, \zeta, \rho} \quad & \frac{1}{2} \|w\|^2 - \rho + \frac{1}{n_1 \nu_1} \sum_{i=1}^{n_1} \xi_i + \frac{1}{n_2 \nu_2} \sum_{k=1}^{n_2} \zeta_k \\ \text{with} \qquad & \langle w, \Phi(x_i) \rangle \geq \rho - \xi_i \quad \forall i = 1: n_1 \\ \text{with} \qquad & \langle w, \Phi(x_k) \rangle < \rho - \zeta_k \quad \forall k = 1: n_2 \\ \text{and} \qquad & \xi_i \geq 0 \quad \forall i = 1: n_1 \\ \text{and} \qquad & \zeta_k \geq 0 \quad \forall k = 1: n_2 \end{split}$$

## Discriminant 1CSVM

#### **Dual Problem:**

$$\begin{aligned} & \underset{\alpha}{\min} & & \sum_{i,j=1}^{n_1} \alpha_i \alpha_j K(x_i, x_j) \\ & & -2 \sum_{i=1}^{n_1} \sum_{k=1}^{n_2} \alpha_i \alpha_k K(x_i, x_k) \\ & & + \sum_{k,p=1}^{n_2} \alpha_k \alpha_p K(x_k, x_p) \end{aligned}$$
 with 
$$& \sum_{i=1}^{n_1} \alpha_i - \sum_{k=1}^{n_2} \alpha_k = 1 \\ \text{and} & 0 \leq \alpha_i \leq \frac{1}{n_1 \nu_1} \quad \forall i = 1: n_1 \\ \text{and} & 0 \leq \alpha_k \leq \frac{1}{n_2 \nu_2} \quad \forall k = 1: n_2 \end{aligned}$$

#### Comments

Conclusion

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#### **SMO Method**

# Principle:

Divide the primal problem into a sequence of small problems.

Due to equality constraint on  $\sum_i \alpha_i \Rightarrow$  it is not possible to change a single value.

At least consider pairs of values.

**basic problem :** Consider  $\alpha_i$  and  $\alpha_i$  :

$$\begin{array}{ll} \min\limits_{\alpha_i,\alpha_j} & \frac{1}{2} \left( \alpha_i^2 \textit{K}_{ii} + \alpha_j^2 \textit{K}_{jj} + 2 \alpha_i \alpha_j \textit{K}_{ij} \right) + c_i \alpha_i + c_j \alpha_j \\ \text{with} & \alpha_i + \alpha_j = \gamma \\ \text{and} & 0 \leq \alpha_i, \alpha_j \leq \frac{1}{n\nu} \end{array}$$

and

$$\gamma = 1 - \sum_{k \neq i,j} \alpha_k = \alpha_i^{old} + \alpha_j^{old}$$

$$c_i = \sum_{k \neq i,j} \alpha_k K_{ik} \qquad c_j = \sum_{k \neq i,j} \alpha_k K_{jk}$$

decompose in 4 sub-matrix

#### SMO Method

# **Resolution**: Substituting $\alpha_j$ :

$$\begin{aligned} & \min_{\alpha_i} & & \frac{1}{2}\alpha_i^2\chi + \alpha_i(c_i - c_j + \gamma(K_{ij} - K_{jj})) \\ & \text{with} & & \chi = K_{ii} - 2K_{ij} + K_{jj} \\ & \text{and} & & & L \leq \alpha_i, \alpha_j \leq H \end{aligned}$$

and

$$L = \max(0, \gamma - \frac{1}{\nu n})$$

$$H = \min(\frac{1}{\nu n}, \gamma)$$

where

$$\alpha_i = \min(\max(L, \tilde{\alpha_i}), H)$$

#### SMO Method

#### Resolution:

$$\tilde{\alpha_i} = \alpha_i^{old} + \frac{c_j - c_i + \alpha_j^{old} K_{jj} - \alpha_i^{old} K_{ii} + K_{ij} (\alpha_i^{old} - \alpha_j^{old})}{\chi}$$

$$= \alpha_i^{old} + \frac{f^{old}(x_j) - f^{old}(x_i)}{\chi}$$

#### Initialization:

Draw  $n\nu$  observations and fix values  $\alpha_i = \frac{1}{n\nu}$ . If  $n\nu$  is not an integer, give the supplement to the last.

Conclusion

#### SVs Choice:

• We seek a sample that violates the KKT conditions

$$f(x_i)\alpha_i > 0$$

case  $f(x_i) > 0$  and  $\alpha_i \neq 0$  or

$$-f(x_i)(\frac{1}{n\nu}-\alpha_i)>0$$

case 
$$f(x_i) < 0$$
 and  $\alpha_i \neq \frac{1}{n\nu}$ 

• Find the sample  $x_j$  which maximizes on  $k | f(x_i) - f(x_k) |$  for  $x_k \in SV$  with  $SV = \{x_k | \alpha_k \in ]0, \frac{1}{n\nu}[\}$ 

In practice this operation is repeated on all the data and then several times only on SVs.

If no violation of KKT conditions remains on  $A_n$  then it is finished!

# Simple algorithm:

- Initialize  $\alpha$  and  $\rho = \max_i f(x_i)$
- ② While the KKT conditions are not satisfied for all  $x_i$ 
  - Choose  $\alpha_i$  and  $\alpha_i$
  - 2 Initialize  $\alpha_i^{old}$  and  $\alpha_i^{old}$
  - **6** Calculate  $\tilde{\alpha}_i$
  - ① Determine  $\alpha_i = \min(\max(L, \tilde{\alpha_i}), H)$
  - **o** Deduce  $\alpha_i$
  - **o** Calculate  $\rho$  using the fact that  $\rho = f(SV|border)$
- **1** Return  $\alpha$  and  $\rho$

## Problem formulation:

$$\begin{aligned} & \min_{w,\rho,\xi} & & \frac{n\nu}{2} \|w\|^2 - n\nu\rho + \sum_{i=1}^n \xi_i \\ & \text{with} & & \langle w, \Phi(x_i) \rangle \geq \rho - \xi_i & \forall i = 1:n \\ & \text{and} & & \xi_i \geq 0 & \forall i = 1:n \end{aligned}$$

#### **Dual Problem:**

$$\begin{array}{ll} \underset{\alpha}{\text{minimize}} & \frac{1}{2n\nu} \sum_{i,j} \alpha_i \alpha_j K(x_i,x_j) \\ \text{with} & 0 \leq \alpha_i \leq 1 \quad \forall i=1:n \\ \text{with} & w = \frac{1}{n\nu} \sum_i \alpha_i \Phi(x_i) \\ \text{and} & \sum_i \alpha_i = n\nu \\ \end{array}$$

## Observation 1:

For a given value  $\nu$  there is a solution  $\alpha^{\nu}$ ,

The function  $f^{\nu}(x)$  divides  $A_n$  in 3 groups :

• 
$$C = \{i | f^{\nu}(x_i) > 0 \text{ et } \alpha_i^{\nu} = 0\}$$

• 
$$\mathcal{M} = \{i | f^{\nu}(x_i) = 0 \text{ et } \alpha_i^{\nu} \in ]0, 1[\}$$

• 
$$\mathcal{E} = \{i | f^{\nu}(x_i) < 0 \text{ et } \alpha_i^{\nu} = 1\}$$

## Observation 2:

When  $\nu$  changes without change of the groups composition, only the  $\alpha_i$ associated with the elements of  $\mathcal{M}$  change.

## Observation 3:

When  $\nu$  changes while the composition of the groups stay the same, values of the  $\alpha_i$  associated with the elements of  $\mathcal{M}$  change linearly with  $\nu$ .

## Proof:

Given  $\nu^m$  and  $\nu^M$  such that the groups stay the same for any  $\nu \in [\nu^m, \nu^M]$ 

Consequence:

$$\sum_{k \in \mathcal{M}} \alpha_k^{\nu^{M}} - \sum_{k \in \mathcal{M}} \alpha_k^{\nu} = n(\nu^{M} - \nu)$$

We define 
$$g^{\nu}(x)=\langle w^{\nu},\Phi(x)\rangle-\frac{\alpha_0^{\nu}}{n\nu}$$
 with  $\rho^{\nu}=\frac{\alpha_0^{\nu}}{n\nu}$ 

$$g^{\nu}(x) = \frac{1}{n\nu} \left( \sum_{i} \alpha_{i}^{\nu} K(x, x_{i}) - \alpha_{0}^{\nu} \right)$$

$$g^{\nu}(x) = g^{\nu}(x) - \frac{\nu^{M}}{\nu} g^{\nu^{M}}(x) + \frac{\nu^{M}}{\nu} g^{\nu^{M}}(x)$$

$$= \frac{1}{n\nu} \left( \sum_{i} (\alpha_{i}^{\nu} - \alpha_{i}^{\nu^{M}}) K(x, x_{i}) - (\alpha_{0}^{\nu} - \alpha_{0}^{\nu^{M}}) + n\nu^{M} g^{\nu^{M}}(x) \right)$$

For any observation  $x_k \in \mathcal{M}$  we have :

$$g^{\nu^{\mathbf{M}}}(x_{k}) = g^{\nu}(x_{k}) = 0$$

$$\sum_{I \in \mathcal{M}} (\alpha_{I}^{\nu} - \alpha_{I}^{\nu^{\mathbf{M}}}) K(x_{k}, x_{I}) - (\alpha_{0}^{\nu} - \alpha_{0}^{\nu^{\mathbf{M}}}) = 0$$

$$\begin{cases} K\left(\alpha^{\nu} - \alpha^{\nu^{\mathbf{M}}}\right) - \left(\alpha_{0}^{\nu} - \alpha_{0}^{\nu^{\mathbf{M}}}\right) \mathbf{1} &= \mathbf{0} \\ \mathbf{1}^{T}\left(\alpha^{\nu} - \alpha^{\nu^{\mathbf{M}}}\right) &= n\nu - n\nu^{\mathbf{M}} \end{cases}$$

Let:

$$A = \begin{pmatrix} K & -1 \\ \mathbf{1}^T & 0 \end{pmatrix}$$
$$c^T = [0...0, 1]$$

Thus:

$$A\left(\left(\begin{array}{c} \alpha^{\nu} \\ \alpha_{0}^{\nu} \end{array}\right) - \left(\begin{array}{c} \alpha^{\nu^{M}} \\ \alpha_{0}^{\nu^{M}} \end{array}\right)\right) = (n\nu - n\nu^{M})c \tag{1}$$

Thus:

$$\begin{pmatrix} \alpha^{\nu} \\ \alpha_{0}^{\nu} \end{pmatrix} = \begin{pmatrix} \alpha^{\nu M} \\ \alpha_{0}^{\nu M} \end{pmatrix} + (n\nu - n\nu^{M})A^{-1}c$$
 (2)

# Group change :

•  $x_k$  de  $\mathcal{M}$  vers  $\mathcal{E}$   $(\alpha_k \to 1)$ 

$$\nu = \frac{1 - \alpha_k^{\nu M}}{n(A^{-1}c)_k} + \nu^M$$

•  $x_k$  de  $\mathcal{M}$  vers  $\mathcal{C}$   $(\alpha_k \to 0)$ 

$$\nu = \frac{-\alpha_k^{\nu M}}{n(A^{-1}c)_k} + \nu^M$$

•  $x_k$  vers  $\mathcal{M}$  (eq 2)

$$\nu = \nu^{M} \left( \frac{[K(x_{k},.),-1](A^{-1}c) - g^{\nu^{M}}(x_{k})}{[K(x_{k},.),-1](A^{-1}c)} \right)$$

# Group change case 3:

$$g^{\nu}(x_k) = \frac{1}{n\nu} \left( \sum_i (\alpha_i^{\nu} - \alpha_i^{\nu^{\mathbf{M}}}) K(x_k, x_i) - (\alpha_0^{\nu} - \alpha_0^{\nu^{\mathbf{M}}}) + n\nu^{\mathbf{M}} g^{\nu^{\mathbf{M}}}(x_k) \right) = 0$$

Thus:

$$\sum_{i} (\alpha_{i}^{\nu} - \alpha_{i}^{\nu^{\mathbf{M}}}) K(x_{k}, x_{i}) - (\alpha_{0}^{\nu} - \alpha_{0}^{\nu^{\mathbf{M}}}) = -n \nu^{\mathbf{M}} g^{\nu^{\mathbf{M}}}(x_{k})$$

Thus:

$$[K(\mathbf{x}_k,.),-1](\begin{pmatrix} \alpha^{\nu} \\ \alpha_0^{\nu} \end{pmatrix} - \begin{pmatrix} \alpha^{\nu}^{\mathbf{M}} \\ \alpha_0^{\nu}^{\mathbf{M}} \end{pmatrix}) = -n\nu^{\mathbf{M}} g^{\nu^{\mathbf{M}}}(\mathbf{x}_k)$$

Using eq. 2:

$$n[K(x_k,.),-1]A^{-1}c(\nu-\nu^M)=-n\nu^Mg^{\nu^M}(x_k)$$

# Regularization path

## Step:

 $u^m = \max(\nu_{changement})$ Replace  $u^M$  by the value  $u^m$ progression by decreasing value of u

# Stop:

When  $\mathcal{E}$  is empty!

## Regularization path

#### **Initialization:**

Start with  $\nu = 1 - \frac{\epsilon}{n}$ 

A single  $x_k$  is in the margin, the others are outliers  $(lpha_i=1$  et

$$(\alpha_k = 1 - \epsilon). \ \rho = f(x_k)$$

To find k:

$$\min_{k} \frac{1}{2n\nu} \sum_{i,j} \alpha_{i} \alpha_{j} K_{ij} - \frac{\epsilon}{n\nu} \sum_{i} \alpha_{i} K_{ik} + \frac{\epsilon^{2}}{2n\nu} K_{kk}$$

Thus:

$$\min_{k} \frac{1}{2n\nu} \sum_{i,j} K_{ij} - \frac{\epsilon}{n\nu} \sum_{i} K_{ik} + \frac{\epsilon^2}{2n\nu} K_{kk}$$

Which means choosing the closest  $x_k$  to the barycenter in the Hilbert space :

$$\max_{k} \sum_{i \neq k} K_{ik}$$

If several  $x_k$  enter simultaneously the margin (P=0): solve the optimisation problem with  $\nu$  close to 1.

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#### **PCA**

## **Principle**

Projection from  $\mathbb{R}^l$  to  $\mathbb{R}^d$ 

Minimizing the deformation of the sample cloud

Retain most of the variance

Decision based on reconstruction error.

#### **PCA** Method

We search u such that ||u|| = 1 and the projection of X on the axis carried by u captures the most variance.

$$\max_{u} \quad u^{t} X^{t} X u$$
 avec 
$$u^{t} u = 1$$

Dual Problem:

$$\max_{\lambda} \min_{u} -u^{t}X^{t}Xu + \lambda(u^{t}u - 1)$$

#### Method - continuation

We search v such that ||v|| = 1 and  $v \perp u$  and the projection of X on the axis carried by v captures the most variance in the subspace.

$$\max_{v} \quad v^{t} X^{t} X v$$
 avec 
$$v^{t} v = 1 \text{ et } v^{t} u = 0$$

Dual problem:

$$\max_{\lambda,\beta} \min_{\mathbf{v}} -\mathbf{v}^t X^t X \mathbf{v} + \lambda (\mathbf{v}^t \mathbf{v} - 1) + \beta \mathbf{v}^t \mathbf{u}$$

## Solution

Eigenvectors

Eigenvalues

## **Principle**

Perform a PCA in a transformed space  ${\cal H}$ 

Given  $\Phi$  a transformation such that :

$$\Phi : \mathbb{R}^I \to \mathcal{H}$$
$$x \mapsto \Phi(x)$$

Hypothesis :  $\sum_{i} \tilde{\Phi}(x_{i}) = 0$ One defines  $\tilde{S}_{f} = \frac{1}{n} \sum_{i} \tilde{\Phi}(x_{i}) \tilde{\Phi}(x_{i})^{t}$ 

We search  $\lambda$  and V such that :

$$\tilde{S}_f V = \lambda V$$

### Solution

V a vector of the space  $\{\tilde{\Phi}(x_1),\ldots,\tilde{\Phi}(x_n)\}\Rightarrow$ 

$$\exists \alpha \text{ st. } V = \sum_{i} \alpha_{i} \tilde{\Phi}(x_{i})$$

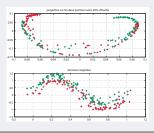
with  $\tilde{K}_{i,j} = < \tilde{\Phi}(x_i), \tilde{\Phi}(x_j) >$  Consequences :

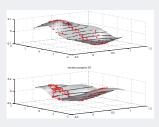
$$K\alpha = n\lambda\alpha$$

 $\alpha$  are the eigenvectors of K $KPCA_d(x) = \sum_i \alpha_i^d \tilde{K}(x_i, x)$ 

### Interpretation

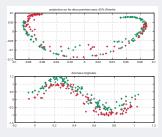
- Maximize the variance in  $\mathcal{H}$
- ullet Minimize the reconstruction error in  ${\cal H}$
- Minimize the representation entropy
- Maximize mutual information in relation with the data
- ullet If  $\Phi$  is a polynomial, relation with high order moments

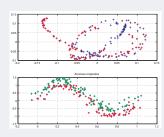




### Interpretation

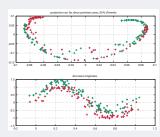
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- Maximize mutual information in relation with the data
- $\bullet$  If  $\Phi$  is a polynomial, relation with high order moments

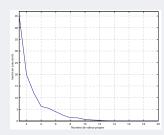




### Interpretation

- ullet Maximize the variance in  ${\cal H}$
- ullet Minimize the reconstruction error in  ${\cal H}$
- Minimize the representation entropy
- Maximize mutual information in relation with the data
- $\bullet$  If  $\Phi$  is a polynomial, relation with high order moments





#### Outline

- Introduction
- 2 Methods and properties
  - 1C-SVM
  - 1C-SVM Variantes
- Optimization
  - SMO approach
  - Regularization path
- Other approach
  - PCA
  - KPCA
- Conclusion

## Conclusion

### Contributions

- Detection
- Classification