



# Pattern recognition Advanced decision methods

Multiclass SVM

- Chapitre 5 -

## **Outline**

- Introduction
- Decomposition methods
- Main models
- 4 Conclusion

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- 2 Decomposition methods
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#### Motivations

- Discrimination multihypothèse
- Many practical cases item theoretical difficulty: non-trivial extension of the results of learning theory to two classes
- Still an open topic

#### Multiclass Decision

#### General case:

A classification problem is defined by three elements:

- decision options that are hypothetically assumed all known
- the risk term to optimize
- performance constraints to satisfy.

## **Decision options:**

$$\Psi = \{\psi_0, \psi_1, \dots, \psi_{I-1}\}$$

 $\mathcal{D}(\mathbf{x}) = k$  If  $\mathbf{x}$  is assigned to the set of classes member of  $\psi_k$ .

#### Multiclass Decision

## Risk term

$$r(\mathcal{D}) = \sum_{i=0}^{I-1} \sum_{i=0}^{nc-1} r_{ij} P_j P(\mathcal{D}(X) = i | \omega_j)$$

where  $r_{ij}$  the cost of assigning an observation of class  $\omega_j$  to the subset of classes  $\psi_i$ .

#### Performance constrains:

Each constraint is defined by a cost function  $c_k$  with k = 1..K and its associated bound  $\gamma_k$ :

$$\begin{array}{rcl} c_{k}\left(\mathcal{D}\right) & \leq & \gamma_{k} \\ \text{with: } c_{k}\left(\mathcal{D}\right) & = & \sum_{i=0}^{I-1} \sum_{j=0}^{nc-1} c_{ij,k} P_{j} P\left(\mathcal{D}\left(X\right) = i \middle| \omega_{j}\right) \end{array}$$

whire  $c_{ii,k}$  is a real and k = 1..K.

#### Multiclass Decision

### **Problem**

$$\begin{cases} \min_{\mathcal{D}} R(\mathcal{D}) \\ \text{with: } c_k(\mathcal{D}) \leq \gamma_k \quad \forall k = 1..K \end{cases}$$

#### **Dual Problem**

$$\begin{split} \max_{\boldsymbol{\mu} \geq 0} \left( \inf_{\mathcal{D}} \mathrm{E} \left( \mathcal{D}, \boldsymbol{\mu} \right) \right) \\ \text{avec} \quad \mathrm{E} \left( \mathcal{D}, \boldsymbol{\mu} \right) = R \left( \mathcal{D} \right) + \sum_{k=1}^K \mu_k \left( c_k \left( \mathcal{D} \right) - \gamma_k \right) \end{split}$$

where  $\boldsymbol{\mu} = [\mu_1, \mu_2, \dots, \mu_K]^T \in \mathbb{R}^{+K}$  is the vector of Lagrange multipliers;  $\mathcal{D}$ , the decision function which defines the partition  $\mathcal{Z}$  de  $\mathcal{X}$ .

## Optimal solution

## Optimal rule

 $\inf_{\mathcal{D}} \mathbb{E}(\mathcal{D}, \boldsymbol{\mu})$  is given by the rule  $\mathcal{D}_{\inf}$ :

$$\mathcal{D}_{\inf}\left(\mathbf{x}, \boldsymbol{\mu}\right) = \underset{i, i=0..I-1}{\operatorname{indicemin}} \ g_i\left(\mathbf{x}, \boldsymbol{\mu}\right)$$

with:

$$g_i(\mathbf{x}, \boldsymbol{\mu}) = \sum_{j=0}^{nc-1} P_j P(\mathbf{x}|\omega_j) \left( r_{ij} + \sum_{k=1}^K \mu_k c_{ij,k} \right)$$

# Concluding remarks

## Identical rule

Bayes rule: solving the unconstrained problem of risk R' minimization:

$$R'(\mathcal{D}) = \sum_{i=0}^{I-1} \int_{\mathcal{D}(\mathbf{x})=i} P(\mathbf{x}) \sum_{j=0}^{nc-1} r'_{ij} P(\omega_j | \mathbf{x}) d\mathbf{x}$$

with:

$$r'_{ij} = r_{ij} + \sum_{k=1}^K \mu_k^* c_{ij,k}$$

and  $R'_i(\mathbf{x}) = g_i(\mathbf{x}, \boldsymbol{\mu}^*)$ .

## Bayes rule

## **Decision options:**

$$\psi_{\mathbf{k}} = H_{\mathbf{k}}$$

for k from 1 to nc

## Unconstrained rule

Bayes rule that is solution of the unconstrained minimization of risk  $R_B$ 

$$R_{B}(\mathcal{D}) = \sum_{i=1}^{nc} \int_{\mathcal{D}(\mathbf{x})=i} \sum_{i=1}^{nc} r_{ij} P(\omega_{j}|\mathbf{x}) P(\mathbf{x}) d\mathbf{x}$$

with  $\mathcal{D}_i$  the set of  $\mathbf{x}$  such that  $\mathcal{D}(\mathbf{x}) = i$  is defined by:

$$\mathcal{D}_{i} = \{x | \sum_{j=1}^{nc} r_{ij} P(\mathbf{x} | \omega_{j}) P_{j}\} \leq \sum_{j=1}^{nc} r_{kj} P(\mathbf{x} | \omega_{j}) P_{j}\} \forall k$$

# Training - first solution

- Estimate  $P(\mathbf{x}|\omega_i)$
- Estimate  $P_i$
- Apply the Bayes rule by plugging the estimators

# **Principle**

Not solve a more complex problem than the original problem, if the initial problem can be addressed directly.

## Observation

Estimating densities is difficult (especially in large dimensional space).

## Consequence

Try to define a partition.

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#### Introduction

# Principle:

• Decompose a multiclass problem into several 2 classes problems

## Approaches:

- One against all
- One against one
- Error correcting codes
- Graphs

# One against all

- A classifier per class: class k against the others
- The decision is made by selecting the rule for which f(x) is the largest
- Problem: class size very unbalanced when learning . . .
- Performance often good enough

## One against one

- A classifier for each pair of classes
- We need  $C_K^2$  classifiers for K classes
- Final decision based on majority vote (possibly weighted by f(x))
- Outputs post-processing to estimate  $P(\omega_i|f(x))$ Platt proposes  $\frac{1}{1+e^{Af(x)+B}}$

# One against one - variation

- ullet Basic classifier provide answers  $\{-1,0,1\}$
- 0 for the other classes

# **Error correcting codes**

## Principle:

- Each class is characterized by a binary word of given size N
- Each 0, 1 is the result of a classification
- Each classification relates to a separation between groups of classes
- Each observation is classified N times
- Decision is taken according to the distances of the code word formed the codewords representing the classes

#### Remark:

• Effective if the bit errors are uncorrelated

# Graphs and decision

# Principle:

- Path between nodes
- Each node removes a class

#### Remarks:

- Learning as complex as 1 against 1
- sensitive to the order of nodes

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#### Contexte:

- K classes
- A training set  $A_n = \{(x_i, y_i)\} \in (\mathcal{X} \times \{1 : K\})^n$

#### Goal:

• Find the hyperplane separators that minimize an objective function

$$J(f) = \lambda ||f||_{\mathcal{H}}^2 + \sum_{i=1}^n L(y_i, f(x_i))$$
With:  $\sum_{i=1}^K f_i = 0$ 

Consequence of representor theorem:

$$f_k(x) = \sum_{i=1}^n \alpha_{ik} K(x_i, x) + b_k$$

## Weston and Watkins Model

## Primal problem:

$$\min_{f} \left\{ \frac{1}{2} \sum_{j=1}^{K} \|w_{j}\|^{2} + C \sum_{i=1}^{n} \sum_{j=1, j \neq y_{i}}^{K} \xi_{ij} \right\}$$
Avec  $\langle w_{y_{i}} - w_{j}, \phi(x_{i}) \rangle + b_{y_{i}} - b_{j} \geq 1 - \xi_{ij} \quad i = 1 : n, j = 1 : K, j \neq y_{i}$ 

$$\xi_{ij} \geq 0$$

The constraint  $\sum_k w_k = 0$  is implicitly satisfied by the solution

#### Weston and Watkins Model

#### **Dual Problem:**

With 
$$0 \le \alpha_{i,k} \le C$$
 
$$\sum_{i|y_i=k}^K \sum_{l=1}^K \alpha_{il} - \sum_{i=1}^m \alpha_{ik} = 0$$
 With  $H = (h_{ik,il})$  such that  $h_{ik,il} = K(x_i, x_i)(\delta_{v_i,v_i} - \delta_{v_i,l} - \delta_{v_i,k} + \delta_{k,l})$ 

 $\min_{\alpha} \left\{ \frac{1}{2} \alpha^T H \alpha - 1^T \alpha \right\}$ 

# Cramer and Singer Model

## Primal problem:

$$\begin{aligned} \min_f \left\{ \frac{1}{2} \sum_{j=1}^K \|w_j\|^2 + C \sum_{i=1}^m \xi_i \right\} \\ \text{With} \quad \langle w_{y_i} - w_j, \phi(x_i) \rangle + \delta_{y_i,k} \geq 1 - \xi_i \quad i = 1: m, j = 1: K, j \neq y_i \\ \xi_i > 0 \end{aligned}$$

Training is focused on the most violated constraint for each sample. Leads to a more "compact" dual problem which enables a more effective implementation (by decomposition on the same principle as SMO)

#### Lee and al. Model

Both previous M-SVM does not converge to the Bayes classifier when the number of samples tends to  $\infty$ .

Lee and al. propose a universally convergent formulation.

## Primal problem:

$$\begin{aligned} \min_{f} \left\{ \frac{1}{2} \sum_{j=1}^{K} \|w_{j}\|^{2} + C \sum_{i=1}^{n} \sum_{j=1, j \neq y_{i}}^{K} \xi_{ij} \right\} \\ \text{With} \quad \left\langle w_{j}, \phi(x_{i}) \right\rangle + b_{j} \leq -\frac{1}{K-1} + \xi_{ij} \quad i = 1 : n, j = 1 : K, j \neq y_{i} \\ \xi_{ij} \geq 0 \\ \sum_{i=1}^{K} w_{j} = 0, \sum_{i=1}^{K} b_{j} = 0 \end{aligned}$$

Consistency if cost converges in probability to Bayes risk Strong consistency if convergence is ps (almost sure) Universal Convergence: whatever *P* 

# On class SVM based solutions

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