

robot_land

- + robot_land()
- + set_time()
- + advanceTime()
- + get_current_time()
- + get_num_robots()
- + get_robot_pos()
- + get_robot_vel()
- + get_robot_radius()
- + get_robot_sensor_angle()
- + get_robot_sensor_distance()
- + get_num_obstacles()
- + get_obstacle_pos()
- + get_obstacle_radius()