# Anjali Padmanaban

anjali.jax@gmail.com | \$904.208.8560

Enthusiastic engineering graduate seeking challenging opportunities in electronic design and automation.

#### EDUCATION

**University of Central Florida** BS in Electrical Engineering **Mathematics Minor** Art Studio Minor May 2022 | Orlando, FL Cum. GPA: 3.36

## COURSEWORK

Ordinary Differential Equations II Matrix and Linear Algebra Linear Control Systems Analog Filter Design Satellite Communications Introduction to Robotic Systems **Embedded Systems** Computer Architecture

## SKILLS

MATLAB • Multisim • EAGLE • AutoCAD Python • Java • C, Assembly Language Next.js • LATEX • OpenCV • NumPy Code Composer Studio • Arduino • MARS • Vivado

Components: Arduino, Raspberry Pi, MSP430 microcontrollers, LoRa REYAX Module, TPS61178 Boost Converter, AKK TS832+RC832, LF351D OpAmp, ARTIX-7FPGA

Lab testing equipment: Multimeter,

Oscilloscope, Power Supplies
Microsoft Office: Word, Excel, PowerPoint Satellite Communications: Uplink,

Downlink Calculations

## **ACHIEVEMENTS**

2022 Selected for FAR-51025 Launch Contest & Senior Design Showcase Semi Finalist

2021 Dean's List

2019 Tableaux Vivant Exhibit

2017 Dean's List

2015 32nd/64 in FIRST Robotics Competition

2014 FLL: State 1st in Robot Game 1st in Robot Design

# PRESENTATIONS

Real Time Finger Detection

Rover Payload Final Presentation

Rover Payload Final Demo

#### **EXPERIENCE**

#### Capacitech Energy | Electrical Engineering Intern

August 2021 - December 2021 | Orlando, FL

- Created MATLAB simulations to test the effects of supercapacitors in parallel with solar panels in small scale and large 100kW powered grid.
- Wrote captivating articles highlighting the company's innovation in creating flexible supercapacitors.

#### University of Central Florida | Undergraduate Research Assistant January 2019 - May 2019 | Orlando, FL

- Collaborated with a mentor to develop a research question related to multi robot systems.
- Independently researched methods of mapping and navigation.
- Utilized MATLAB to create a mathematical model to demonstrate how a multi robot system works to cover as much area as possible.

#### FIRST | Participant & Coach

Jan 2013 - May 2017 | Jacksonville, FL

- Actively participated in FIRST competitions as Team Captain for FIRST Lego League (FLL), FIRST Robotics Competition (FRC), FIRST Tech Challenge (FTC) and coached FLL teams.
- Designed, built, and programmed robots to compete in the FIRST competitions and won several awards.

## **Kumon Math and Reading Center** | Tutor

July 2013 - June 2020 | Jacksonville, FL

- Instructed students ages 4-18 in math and reading.
- Focused on guiding student in higher level math like trigonometry and calulus.
- Assisted students in developing critical reading skills.

## **PROJECTS**

#### Aerojet Rocketdyne Radio Controlled Rover | Spring 2022

Developed a radio controlled rover payload that was chosen out of 6 competing designs for entry into the FAR-51025 Rocket Launch Contest. The custom built rover and capsule meet strict requirements of weight, size, and durability set by the rocket team to be deployed at 10,000 ft, and is controllable over 2km with live video feedback. Managed complete development life cycle from component selection, schematic capture, PCB design, firmware development and field testing of a modular 3 part system consisting of a capsule with an automated landing system, radio controlled rover, and control station with video monitoring.

#### **Transistor Amplifier** | Fall 2020

Designed a three-stage amplifier to meet design specifications using Multisim and Excel.

#### Real Time Finger Detection | Fall 2020

Made with OpenCV Python, this program will count the number of fingers displayed within the camera frame.

#### IEEE Southeastcon 2020 | Fall 2019 - Spring 2020

Collaborated with a group of engineering students to build a robot to compete in SOUTHEASTCON 2020 where the robot must retrieve and stack color coded blocks in the order of pi.

#### Mazebot | Fall 2017

Built using the mBot and programmed with mBlock, this robot can navigate any maze by utilizing ultrasonic sensors and a light sensor.