# Μοριοδότηση 2018

### Ενδεικτικές απαντήσεις και από γραπτά μαθητών

Θέμα Α

A1- 7

A2-8

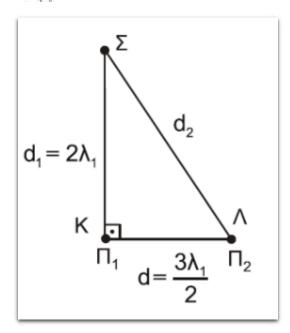
A3-0

A4 - 8

A5: 
$$\Lambda - \Sigma - \Lambda - \Sigma - \Lambda$$

Ožum B

# BI-(i)



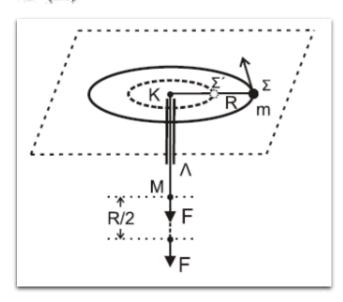
$$d_2 = \sqrt{d_1^2 + d^2} = \sqrt{4 \cdot \lambda_1^2 + rac{9}{4} \cdot \lambda_1^2} = rac{5 \cdot \lambda_1}{2}$$

Ίδιο υλικό

$$v_\delta = \lambda_1 \cdot f_1 = \lambda_2 \cdot f_2 \overset{f_2=2 \cdot f_1}{\Longrightarrow} \lambda_2 = \frac{\lambda_1}{2}$$
 $α) τρόπος$ 

$$|A_\Sigma|=|2A\cdot\sigma v
urac{2\pi(d_1-d_2)}{2\lambda_2}|=|2A\cdot\sigma v
urac{\pi(rac{3\lambda_1}{2}-rac{5\lambda_1}{2})}{rac{\lambda_1}{2}}|=|2A|$$
  $egin{aligned} eta) au
ho\delta\pi oarepsilon \ d_1-d_2=rac{3\lambda_1}{2}-rac{5\lambda_1}{2}=-\lambda_1=-2\lambda_2 \ d_1-d_2=N\cdot\lambda_2 \end{aligned} 
ight\} N=-2 \quad ext{emscans}$ 

## B2-(uu)



$$m: \quad \Sigma au_{arepsilon arepsilon (\mathbf{K})} = \vec{0} \Rightarrow \Delta \vec{L} = \vec{0} \Rightarrow \overrightarrow{L}_1 = \overrightarrow{L}_2$$

Η τάση του νήματος διέρχεται από τον άξονα περιστροφής

$$\begin{split} \alpha) \overline{\rho \phi \pi o \varsigma} \\ \lambda \rho \alpha & m \cdot v_1 \cdot R = m \cdot v_2 \cdot \frac{R}{2} \Rightarrow v_2 = 2 v_1 \\ \Theta \mathsf{MKE}_m(\Sigma \to \Sigma') & \mathsf{K}_{\Sigma'} - \mathsf{K}_{\Sigma} = W_F \Rightarrow \frac{1}{2} \cdot m \cdot v_2^2 - \frac{1}{2} \cdot m \cdot v_1^2 = W_F \\ W_F &= \frac{3}{2} \cdot m \cdot v_1^2 \\ v_1 &= \omega \cdot R \end{split} \right\} W_F &= \frac{3}{2} \cdot m \cdot \omega^2 \cdot R^2 \\ v_1 &= \omega \cdot R \end{split}$$
 
$$\begin{split} \beta) \underline{\tau \rho \phi \pi o \varsigma} \\ I_1 \cdot \omega &= I_2 \cdot \omega' \Rightarrow m \cdot R^2 \cdot \omega = m \cdot \frac{R^2}{4} \cdot \omega' \Rightarrow \omega' = 4 \omega \\ \Theta \mathsf{MKE}_m(\Sigma \to \Sigma') & \mathsf{K}_{\Sigma'} - \mathsf{K}_{\Sigma} = W_F \Rightarrow \frac{1}{2} \cdot I_2 \cdot \omega'^2 - \frac{1}{2} \cdot I_1 \cdot \omega^2 = W_F \\ W_F &= \frac{1}{2} m \frac{R^2}{4} 16 \omega^2 - \frac{1}{2} m \cdot R^2 \omega^2 \Rightarrow W_F = \frac{3}{2} \cdot m \cdot \omega^2 \cdot R^2 \end{split}$$

Εξίσωση Bernoulli για μια ρευματική γραμμή  $(\Gamma o \Delta)$ 

$$P_{\Gamma} + rac{1}{2}
ho\cdot v_{\Gamma}^2 = P_{\Delta} + rac{1}{2}
ho\cdot v_{\Delta}^2 + 
ho\cdot g\cdot h$$

Εξίσωση συνέχειας  $(\Gamma o \Delta)$ 

$$\Pi_{\Gamma} = \Pi_{\Delta} \Rightarrow A_{\Gamma} \cdot v_{\Gamma} = A_{\Delta} \cdot v_{\Delta} \stackrel{A_{\Gamma} = 2A_{\Delta}}{\Longrightarrow} v_{\Delta} = 2v_{\Gamma}$$

Οριζόντια βολή  $(\Delta o K)$ 

$$\left. \begin{array}{l} h = \frac{1}{2}g \cdot t^2 \\ 4h = v_\Delta \cdot \sqrt{\frac{2h}{g}} \Rightarrow v_\Delta^2 = 8g \cdot h \stackrel{v_\Delta = 2v_\Gamma}{\Longrightarrow} 4v_\Gamma^2 = 8g \cdot h \Rightarrow v_\Gamma^2 = 2g \cdot h \\ 4h = v_\Delta \cdot t \end{array} \right\}$$

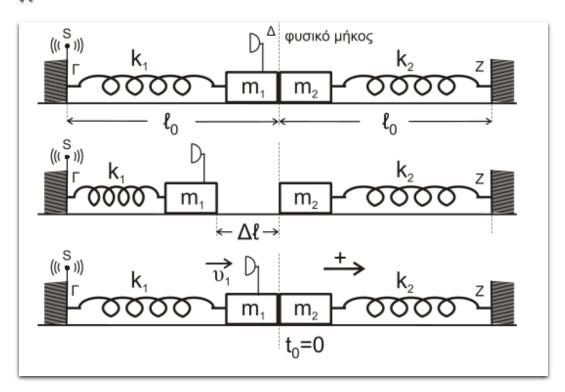
$$g \cdot h = \frac{v_\Gamma^2}{2}$$

Άρα η εξίσωση Bernoulli γράφεται

$$P_{\Gamma}-P_{\Delta}=rac{1}{2}
ho\cdot v_{\Delta}^2+
ho\cdot g\cdot h-rac{1}{2}
ho\cdot v_{\Gamma}^2=rac{1}{2}
ho\cdot 4v_{\Gamma}^2+
ho\cdot rac{v_{\Gamma}^2}{2}-rac{1}{2}
ho\cdot v_{\Gamma}^2=2
ho\cdot v_{\Gamma}^2$$

OEHO F

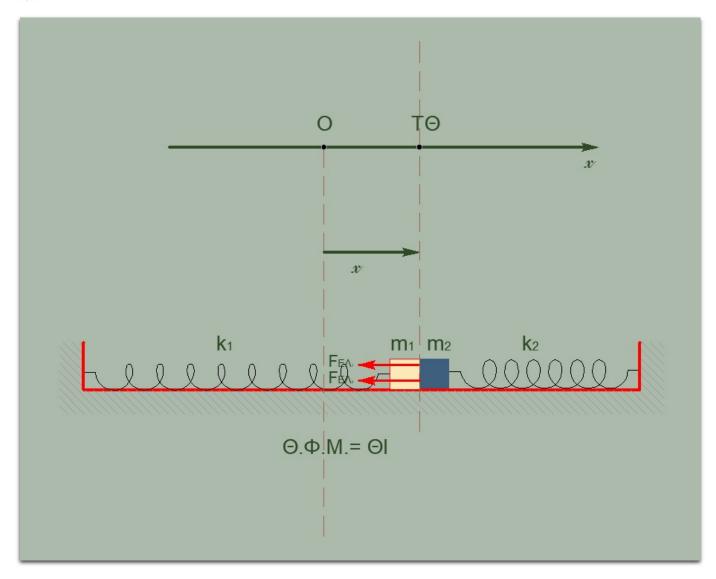
n



$$k_1 = k_2 = k$$
$$m_1 = m_2 = m$$

$$\Delta l = 0.4m = A_1$$
 $K_1 - m$ ,  $AAT: D_1 = k_1 = m_1 \cdot \omega_1^2 \Rightarrow \omega_1 = \sqrt{\frac{k}{m}} = 5 \frac{rad}{sec}$ 
 $v_{max1} = \omega_1 \cdot A_1 = \sqrt{\frac{k}{m}} \cdot \Delta l = 2 \frac{m}{sec}$ 
 $f_1 = \frac{v_{\eta\chi} - v_{max1}}{v_{\eta\chi}} \cdot f_s$ 
 $A\Delta O m_1, m_2 \quad (\Theta. \text{ I.}) \quad m_1 \cdot v_{max1} = (m_1 + m_2) \cdot V \Rightarrow V = 1 \frac{m}{sec}$ 
 $f_2 = \frac{v_{\eta\chi} - V}{v_{\eta\chi}} \cdot f_s$ 
 $\frac{f_1}{f_2} = \frac{v_{\eta\chi} - v_{max1}}{v_{\eta\chi} - V} = \frac{338}{339}$ 

**L**2



 $(m_1 + m_2)$ :

T. 
$$\Theta_1 : \Sigma F = -F_{EA1} - F_{EA2} = -k_1 \cdot x - k_2 \cdot x = -(2k)x$$

Για να εκτελεί ένα σώμα ΑΑΤ πρέπει να ισχύει

$$\Sigma F = -D \cdot x, D = 2k = (m_1 + m_2)\omega^2 \Rightarrow \omega = \sqrt{\frac{2k}{2m}} = \sqrt{\frac{k}{m}} = 5 \frac{rad}{sec}$$
 $\Theta.1.: V = v_{max} \stackrel{v_{max} = \omega \cdot A}{\Longrightarrow} 1 = 5 \cdot A \Rightarrow A = 0.2m$ 

**L3** 

$$\left. egin{aligned} f_{\Delta ext{EKTH}} &= f_s \ & \ f_{\Delta ext{EKTH}} &= rac{v_{v_N} \pm v_{\Sigma T \Sigma}}{v_{v_N}} \cdot f_s \end{aligned} 
ight\} v_{\Sigma T \Sigma} = 0$$

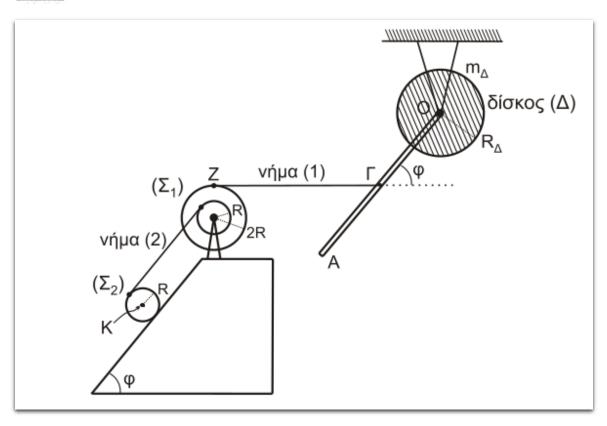
Για πρώτη φορά, δηλαδή ακραία θέση, οπότε

$$T=rac{2\pi}{\omega}=rac{2\pi}{5}sec$$
 
$$\Delta t=rac{T}{4}=rac{\pi}{10}sec$$

Г4

$$|rac{dp}{dt}|_{m_1+m_2(max)} = \Sigma F_{max} = D \cdot A \stackrel{D=100}{\Longrightarrow} \Sigma F_{max} = 20N, \quad \dot{\eta} \quad rac{kg \cdot m}{sec^2}$$

Θέμα Δ



Ράβδος (ρ)

$$M = 8kg$$

$$l=3m$$

Δίσκος (Δ)

$$m_{\Delta}=4kg$$

$$R_{\Delta}=rac{\sqrt{2}}{2}m$$

Τροχαλία (τροχ)

$$R = 0.2m$$

$$I_{\pi po\chi} = 1.95 kg \cdot m^2$$

Κύλινδρος

$$m = 30kg$$

$$R = 0.2m$$

$$\eta\mu\varphi=0.8$$

$$\sigma v u \varphi = 0.6$$

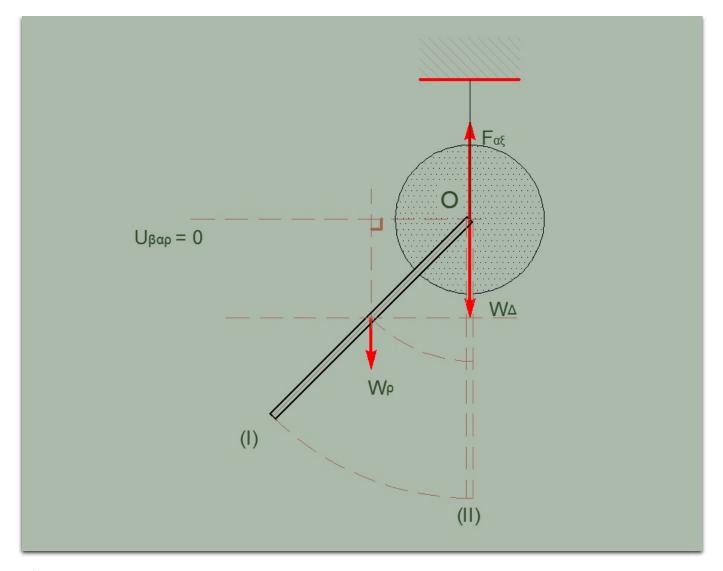
$$g = 10 \frac{m}{sec^2}$$

81

$$I_{
ho=\Delta}=(rac{1}{12}\cdot M\cdot l^2+Mrac{l^2}{4})+rac{1}{2}\cdot m_\Delta\cdot R_\Delta^2=25kg\cdot m^2$$

82

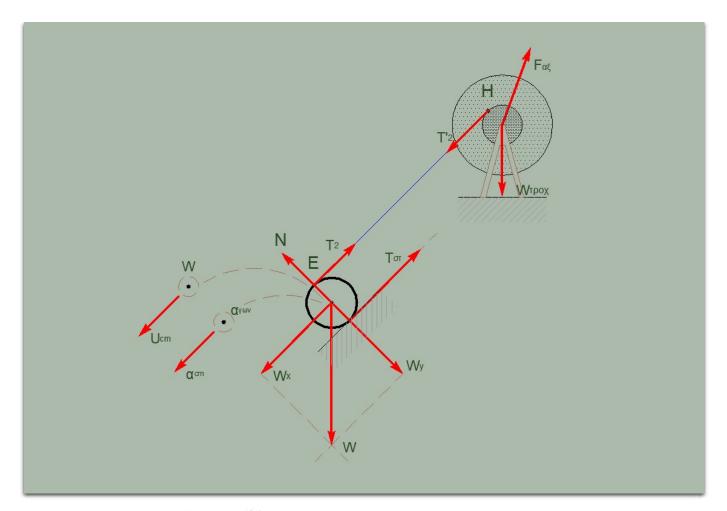
$$|\frac{dL}{dt}|_{\rho-\Delta} = \Sigma \tau_{(0)} = W_\rho \cdot \frac{l}{2} \cdot \text{sung} = 72 \frac{kg \cdot m^2}{sec^2} \quad \text{ff} \quad N \cdot m$$



**A**3

$$egin{aligned} \mathbf{A} \Delta \mathbf{M} \mathbf{E}_{
ho - \Delta} (\mathbf{I} o II) : K_I + U_1 &= K_{II} + U_{II} \ 0 + (-M \cdot g \cdot rac{l}{2} \cdot \eta \mu arphi + U_{eta lpha 
ho (\Delta)(I))}) &= \mathbf{K}_{\mathrm{II}} + (-\mathbf{M} \cdot g \cdot rac{l}{2} + U_{eta lpha 
ho (\Delta)(II))}) \ K_{II} &= M \cdot g \cdot rac{l}{2} \cdot (1 - \eta \mu arphi) \Rightarrow K_{II} &= 24J \end{aligned}$$

4



νήμα(2) αβαρές, μη εκτατό  $({f T}_2={f T}_2')$ 

KXO:

$$egin{aligned} v_{
m B} = 2 \cdot v_{
m cm} &= 2 \cdot \omega \cdot R \Rightarrow lpha_{
m B} = 2 \cdot lpha_{
m cm} = 2 \cdot lpha_{
m \gamma \omega \nu} \cdot R \ \end{aligned}$$
 $egin{aligned} v_{
m B} = v_H &= \omega_{
m \gamma 
m pox} \cdot R \Rightarrow lpha_{
m B} = lpha_{
m H} = lpha_{
m \gamma \omega 
u_{
m pox}} \cdot R \end{aligned}$ 

m: MET.

$$\Sigma F_x = m \cdot \alpha_x \Rightarrow W_x - T_{\sigma\tau} - T_2 = m \cdot \alpha_{cm} \quad (1)$$

m: TTPOO.

$$\Sigma \tau = \mathbf{I} \cdot \alpha_{\gamma \omega \nu} \Rightarrow T_{\sigma \tau} \cdot R - T_2 \cdot R = \frac{1}{2} \cdot m \cdot R^2 \cdot \alpha_{\gamma \omega \nu} \stackrel{\alpha_{cm} = \alpha_{\gamma \omega \nu} R}{\Longrightarrow} T_{\sigma \tau} - T_2 = \frac{1}{2} \cdot m \cdot \alpha_{cm}$$
(2)
$$(1)\Lambda(2) \Rightarrow W_x - 2T_2 = \frac{3}{2} \cdot m \cdot \alpha_{cm}$$
(3)
$$\tau \rho o \chi : \quad \Sigma \tau = \mathbf{I} \cdot \alpha_{\gamma \omega \nu} \Rightarrow T_2' \cdot R = 1.95 \cdot \alpha_{\gamma \omega \nu} \underbrace{\alpha_{\gamma \omega \nu} (\tau \rho o \chi)}_{(3)} \stackrel{\alpha_{\gamma \omega \nu} (\tau \rho o \chi)}{\Longrightarrow}$$
(3)
$$W_x - 2 \cdot \frac{1.95 \cdot \frac{2\alpha_{cm}}{R}}{R} = \frac{3}{2} \cdot m \cdot \alpha_{cm}$$

κύλινδρος:

Μπορείτε να εκτυπώσετε τις λύσεις σε μορφή pdf από εδώ

- Previous Archive Next -