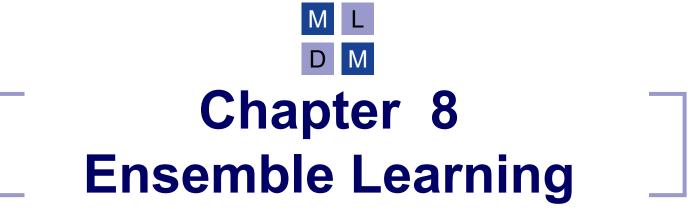
## MIMA Group



#### Content

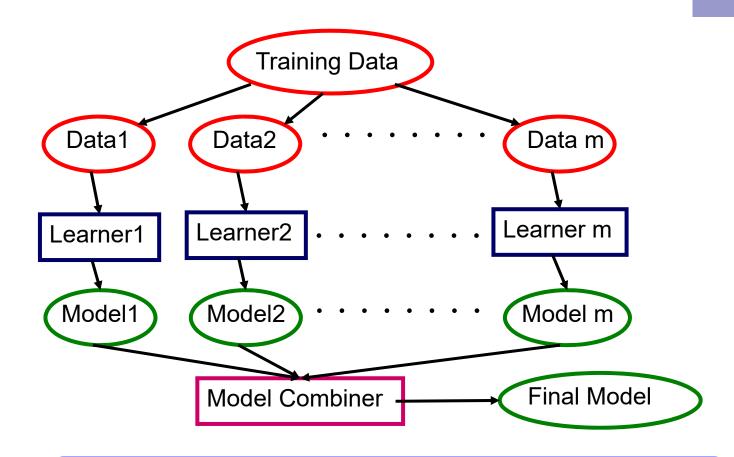


- Introduction
- Bagging
- Boosting
  - Adaboost



- What is ensemble learning
  - Learn multiple alternative definitions of a concept using different training data or different learning algorithms.
- Example 1
  - Generate 100 different decision trees from the same or different training set and have them vote on the best classification for a new example.





Key motivation: reduce the error rate.

#### **Different Learners**



- Different learning algorithms
- Algorithms with different choice for parameters
- Data set with different features
- Data set = different subsets

## Homogenous Ensembles



- Use a single, arbitrary learning algorithm but manipulate training data to make it learn multiple models.
  - Data1 ≠ Data2 ≠ ... ≠ Data m
  - Learner1 = Learner2 = ... = Learner m
- Different methods for changing training data:
  - Bagging: Resample training data
  - Boosting: Reweight training data

## **Bagging**



- Introduced by Breiman (1996)
  - *L. Breiman. Bagging predictors*. Machine Learning, 24(2): 123 140, 1996 (citations 16529)
  - Create ensembles by repeatedly randomly resampling the training data
- "Bagging" stands for "bootstrap aggregating".
  - Given a training set of size n, create m samples of size n by drawing n examples from the original data, with replacement.
  - Each bootstrap sample will on average contain 63.2% of the unique training examples, the rest are replicates.
  - Combine the m resulting models using simple majority vote.



#### Example

- What's the average price of house prices?
- From F, get a sample L= $(x_1, x_2, ..., x_n)$ , and calculate the average u.
- Question: how reliable is u? What's the standard error of u? what's the confidence interval?



- One possibility: get several samples like F.
- Problem: it is impossible (or too expensive) to get multiple samples.
- Solution: bootstrap



Let the original samples be  $L=(x_1,x_2,...,x_n)$ 

- Repeat B time:
  - Generate a sample L<sub>k</sub> of size n from L by sampling with replacement.
  - Compute  $\hat{\theta}^*$  for  $x^*$ .
  - → Now we end up with bootstrap values

$$\hat{\theta}^* = (\hat{\theta}_1^*, ..., \hat{\theta}_B^*)$$

 Use these values for calculating all the quantities of interest (e.g., standard deviation, confidence intervals)



An example

X=(3.12, 0, 1.57, 19.67, 0.22, 2.20)

Mean=4.46

X1=(1.57,0.22,19.67, 0,0,2.2,3.12)

Mean=4.13

X2=(0, 2.20, 2.20, 2.20, 19.67, 1.57) Mean=4.64

X3=(0.22, 3.12,1.57, 3.12, 2.20, 0.22)
Mean=1.74



Original	1	2	3	4	5	6	7	8
Training set 1	2	7	8	3	7	6	3	1
Training set 2	7	8	5	6	4	2	7	1
Training set 3	3	6	2	7	5	6	2	2
Training set 4	4	5	1	4	6	4	3	8



- Cases where bootstrap does not apply
  - Small data sets: the original sample is not a good approximation of the population
  - Dirty data: outliers add variability in our estimates.
  - Dependence structures (e.g., time series, spatial problems): Bootstrap is based on the assumption of independence.

## **Bagging**



#### Let the original training data be L

- Repeat B times:
  - Get a <u>bootstrap sample</u> L<sub>k</sub> from L.
  - Train a predictor using L<sub>k</sub>.
- Combine B predictors by
  - Voting (for classification problem)
  - Averaging (for estimation problem)
- Bagging works well for "unstable" learning algorithms.
- Bagging can slightly degrade the performance of "stable" learning algorithms.

## **Bagging**



- Unstable learning algorithms: small changes in the training set result in large changes in predictions.
  - Neural network
  - Decision tree
  - Regression tree
  - Subset selection in linear regression
- Stable learning algorithms:
  - K-nearest neighbors

## **Bagging-Summary**



- Bootstrap is a resampling method.
- Bagging is directly related to bootstrap.
  - It uses bootstrap samples to train multiple predictors.
  - Output of predictors are combined by voting or other methods.
- Experiment results:
  - It is effective for unstable learning methods.
  - It does not help stable learning methods.

## **Boosting**

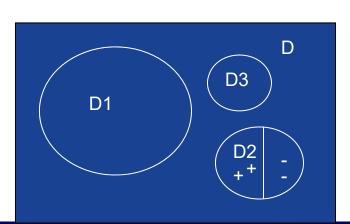


- A family of methods
- Sequential production of classifiers
- Each classifier is dependent on the previous one, and focuses on the previous one's errors
- Examples that are incorrectly predicted in previous classifiers are chosen more often or weighted more heavily

## **Boosting**



- Robert E. Schapire, The strength of weak learnability. Machine Learning, 5(2):197-227, 1990. (citations 4600+)
- Consider creating three component classifiers for a twocategory problem through boosting.
  - Randomly select  $n_1 < n$  samples from D without replacement to obtain  $D_1$
  - Train weak learner C<sub>1</sub>
  - Select  $n_2 < n$  samples from D with half of the samples misclassified by  $C_1$  to obtain  $D_2$
  - Train weak learner C₂
  - Select all remaining samples from D that C<sub>1</sub>
     and C<sub>2</sub> disagree on
  - Train weak learner C<sub>3</sub>
  - Final classifier is vote of weak learners



#### **AdaBoost**



- Yoav Freund, Robert E. Schapire. A decision-theoretic generalization of on-line learning and an application to boosting, EuroCOLT '95 Proceedings of the Second European Conference on Computational Learning Theory (citations 15000+)
- Instead of resampling, uses training set re-weighting
  - Each training sample uses a weight to determine the probability of being selected for a training set.
- AdaBoost is an algorithm for constructing a "strong" classifier as linear combination of "simple" "weak" classifier
- Final classification based on weighted vote of weak classifiers



What is AdaBoost?

# AdaBoost

Adaptive Boosting

A learning algorithm

Building a strong classifier from a lot of weaker ones



$$h_1(x) \in \{-1, +1\}$$
 $h_2(x) \in \{-1, +1\}$ 

$$h_2(x) \in \{-1, +1\}$$

$$h_T(x) \in \{-1, +1\}$$

$$H_T(x) = sign\left(\sum_{t=1}^T \alpha_t h_t(x)\right)$$

weak classifiers

strong classifier

slightly better than random



$$h_1(x) \in \{-1, +1\}$$
 $h_2(x) \in \{-1, +1\}$ 

$$\vdots$$

$$h_T(x) \in \{-1, +1\}$$

#### weak classifiers

slightly better than random

- Each weak classifier learns by considering one simple feature
- T most beneficial features for classification should be selected
- How to
  - define features?
  - select beneficial features?
  - train weak classifiers?
  - manage (weight) training samples?
  - associate weight to each weak classifier?



$$h_1(x) \in \{-1, +1\}$$

$$h_2(x) \in \{-1, +1\}$$

•

$$h_T(x) \in \{-1, +1\}$$

How good the strong one will be?

$$H_T(x) = sign\left(\sum_{t=1}^T \alpha_t h_t(x)\right)$$

weak classifiers

strong classifier

slightly better than random



Given:  $(x_1, y_1), K, (x_m, y_m)$  where  $x_i \in X, y_i \in \{-1, +1\}$ 

Initialization:  $D_1(i) = \frac{1}{m}, i = 1, K, m$  |  $D_t(i)$ :probability distribution of  $x_i$ 's at time t

For t = 1, K, T:

• Find classifier  $h_t: X \to \{-1, +1\}$  which minimizes error wrt  $D_t$ , i.e.,

$$h_t = \arg\min_{h_j} \varepsilon_j$$
 where  $\varepsilon_j = \sum_{i=1}^m D_t(i)[y_i \neq h_j(x_i)]$  minimize weighted error

• Weight classifier:  $\alpha_t = \frac{1}{2} \ln \frac{1 - \varepsilon_t}{\varepsilon}$  for minimize exponential loss

 $D_{t+1}(i) = \frac{D_t(i) \exp[-\alpha_t y_i h_t(x_i)]}{Z_t}, Z_t \text{ is for normalization}$ Update distribution:

Give error classified patterns more chance for learning.



Given:  $(x_1, y_1), K, (x_m, y_m)$  where  $x_i \in X, y_i \in \{-1, +1\}$ 

Initialization:  $D_1(i) = \frac{1}{m}, i = 1, K, m$ 

For t = 1, K, T:

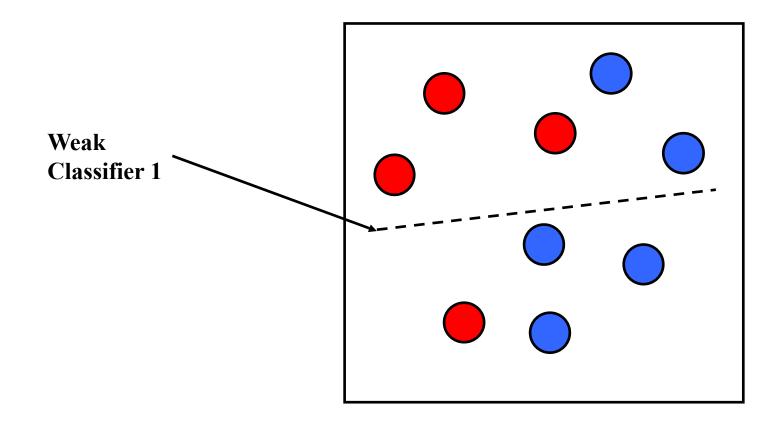
• Find classifier  $h_t: X \to \{-1, +1\}$  which minimizes error wrt  $D_t$ , i.e.,

$$h_t = \arg\min_{h_j} \varepsilon_j$$
 where  $\varepsilon_j = \sum_{i=1}^m D_t(i)[y_i \neq h_j(x_i)]$ 

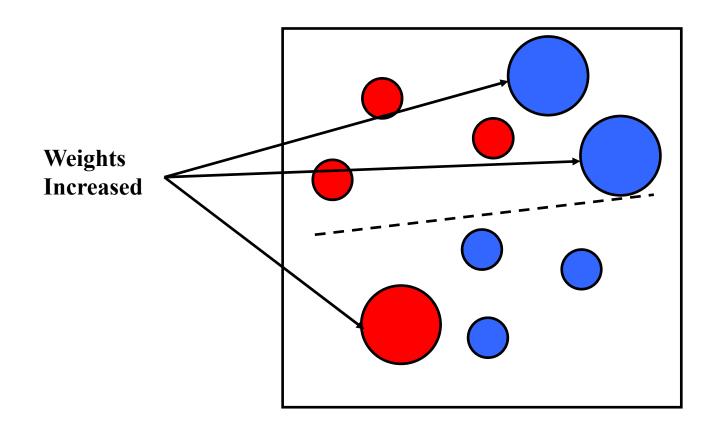
- Weight classifier:  $\alpha_t = \frac{1}{2} \ln \frac{1 \varepsilon_t}{\varepsilon_t}$
- Update distribution:  $D_{t+1}(i) = \frac{D_t(i) \exp[-\alpha_t y_i h_t(x_i)]}{Z_t}$ ,  $Z_t$  is for normalization

Output final classifier:  $sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$ 

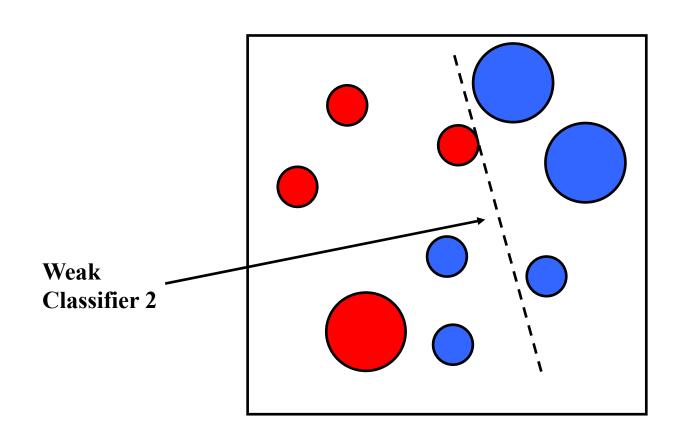




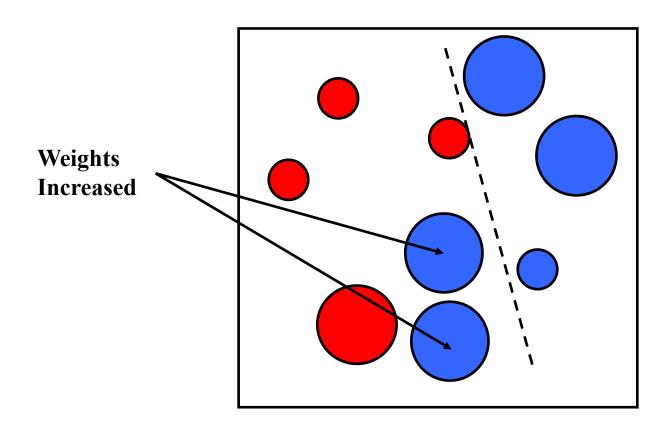




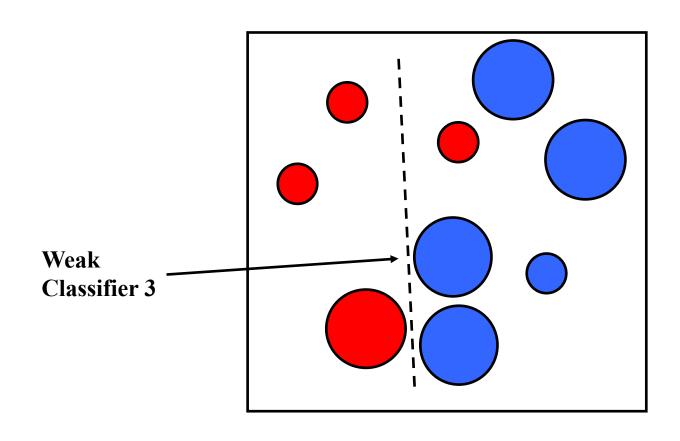






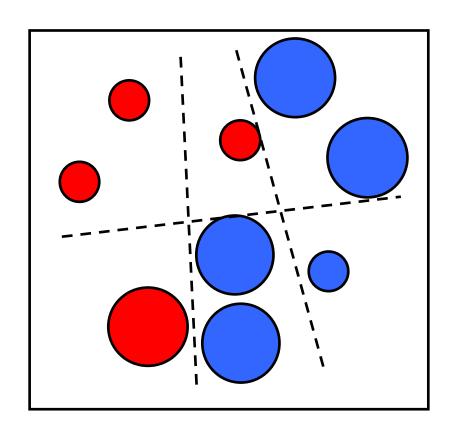








Final classifier is a combination of weak classifiers





Given:  $(x_1, y_1), K, (x_m, y_m)$  where  $x_i \in X, y_i \in \{-1, +1\}$ 

Initialization:  $D_1(i) = \frac{1}{m}, i = 1, K, m$ 

For t = 1, K, T:

# How and why AdaBoost works?

• Weight classifier:  $\alpha_t = \frac{1}{2} \ln \frac{1 - \varepsilon_t}{\varepsilon_t}$ 

• Update distribution:  $D_{t+1}(i) = \frac{D_t(i) \exp[-\alpha_t y_i h_t(x_i)]}{Z_t}$ ,  $Z_t$  is for normalization

Output final classifier:  $sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$ 



Given:  $(x_1, y_1), K, (x_m, y_m)$  where  $x_i \in X, y_i \in \{-1, +1\}$ 

Initialization:  $D_1(i) = \frac{1}{m}, i = 1, K, m$ 

For t = 1, K, T:

# What goal the AdaBoost wants to reach?

• Weight classifier:  $\alpha_t = \frac{1}{2} \ln \frac{1 - \varepsilon_t}{\varepsilon_t}$ 

• Update distribution:  $D_{t+1}(i) = \frac{D_t(i) \exp[-\alpha_t y_i h_t(x_i)]}{Z_t}$ ,  $Z_t$  is for normalization

Output final classifier:  $sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$ 



Given: 
$$(x_1, y_1), K, (x_m, y_m)$$

Initialization: 
$$D_1(i) \neq$$

For t = 1, K, T:

They are goal dependent.

• Find classifier  $h_{i}$ 

$$h_t = \arg\min_{h_j} \varepsilon_j$$
 where  $\varepsilon_j = \sum_{t=0}^{\infty} (i) [y_t \neq h_j(x_t)]$ 

- Weight classifier:
- Update distribution

$$D_{t+1}(i) = \frac{D_t(i) \exp[-\alpha_t y_i h_t(x_i)]}{Z}$$

 $\frac{Z_{t}}{Z_{t}}$ ,  $Z_{t}$  for normalization

$$sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$$

Goal



Final classifier: 
$$sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$$

## Minimize exponential loss

$$loss_{exp}[H(x)] = E_{x,y}[e^{-yH(x)}]$$

## Maximize the margin yH(x)

#### Goal



Final classifier: 
$$sign \left( H(x) = \sum_{t=1}^{T} \alpha_t h_t(x) \right)$$
Minimize  $loss_{exp} \left[ H(x) \right] = E_{x,y} \left[ e^{-yH(x)} \right]$ 
Define  $H_t(x) = H_{t-1}(x) + \alpha_t h_t(x)$  with  $H_0(x) = 0$ 
Then,  $H(x) = H_T(x)$ 

$$E_{x,y} \left[ e^{-yH_t(x)} \right] = E_x \left[ E_y \left[ e^{-yH_t(x)} \mid x \right] \right]$$

$$= E_x \left[ E_y \left[ e^{-yH_{t-1}(x) + \alpha_t h_t(x)} \mid x \right] \right]$$

$$= E_x \left[ E_y \left[ e^{-yH_{t-1}(x)} e^{-y\alpha_t h_t(x)} \mid x \right] \right]$$

 $=E_{x}\left[e^{-yH_{t-1}(x)}\left[e^{-\alpha_{t}}P(y=h_{t}(x))+e^{\alpha_{t}}P(y\neq h_{t}(x))\right]\right]$ 



Final classifier: 
$$sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$$
  
Minimize  $loss_{exp}\left[H(x)\right] = E_{x,y}\left[e^{-yH(x)}\right]$ 

Minimize 
$$loss_{exp}[H(x)] = E_{x,y}[e^{-yH(x)}]$$

Define 
$$H_t(x) = H_{t-1}(x) + \alpha_t h_t(x)$$
 with  $H_0(x) = 0$ 

Then,  $H(x) = H_T(x)$ 

$$E_{x,y} \left[ e^{-yH_t(x)} \right] = E_x \left[ e^{-yH_{t-1}(x)} \left[ e^{-\alpha_t} P(y = h_t(x)) + e^{\alpha_t} P(y \neq h_t(x)) \right] \right]$$

Set 
$$\frac{\partial}{\partial \alpha_t} E_{x,y} \left[ e^{-yH_t(x)} \right] = 0$$

$$\Rightarrow E_x \left[ e^{-yH_{t-1}(x)} \left[ -e^{-\alpha_t} P(y = h_t(x)) + e^{\alpha_t} P(y \neq h_t(x)) \right] \right] = 0$$

 $\alpha_t = ?$ 

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Final classifier: 
$$sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$$
  
Minimize  $loss_{exp}\left[H(x)\right] = E_{x,y}\left[e^{-yH(x)}\right]$ 

Define 
$$H_t(x) = H_{t-1}(x) + \alpha_t h_t(x)$$
 with  $H_0(x) = 0$ 

Then,  $H(x) = H_T(x)$ 

$$\Rightarrow \alpha_t = \frac{1}{2} \ln \frac{P(y = h_t(x))}{P(y \neq h_t(x))} \Rightarrow \alpha_t = \frac{1}{2} \ln \frac{1 - \varepsilon_t}{\varepsilon_t} \qquad P(x_i, y_i) = D_t(i)$$

$$\varepsilon_t = P(\text{error}) \approx \sum_{i=1}^m D_t(i) [y_i \neq h_j(x_i)]$$

$$\Rightarrow E_x \left[ e^{-yH_{t-1}(x)} \left[ -e^{-\alpha_t} P(y = h_t(x)) + e^{\alpha_t} P(y \neq h_t(x)) \right] \right] = 0$$

#### Final classifier

Define 
$$H_t(x) =$$

Then, 
$$H(x) = H$$

Given:  $(x_1, y_1), K, (x_m, y_m)$  where  $x_i \in X, y_i \in \{-1, +1\}$ 

Initialization:  $D_1(i) = \frac{1}{m}, i = 1, K, m$ 

For t = 1, K, T:

• Find classifier  $h_t: X \to \{-1, +1\}$  which minimizes error wrt  $D_t$ , i.e.,

$$h_t = \arg\min_{h_t} \varepsilon_j$$
 where  $\varepsilon_j = \sum_{i=1}^m D_t(i)[y_i \neq h_j(x_i)]$ 

Minimize los • Weight classifier:  $\alpha_t = \frac{1}{2} \ln \frac{1 - \varepsilon_t}{\varepsilon_t}$ 

Define  $H_t(x) = \int$  Update distribution:  $D_{t+1}(i) = \frac{D_t(i) \exp[-\alpha_t y_i h_t(x_i)]}{Z_t}$ ,  $Z_t$  is for normalization

Then, H(x) = H Output final classifier:  $sign\left(H(x) = \sum_{i=1}^{T} \alpha_{i} h_{i}(x)\right)$ 

$$\Rightarrow \alpha_{t} = \frac{1}{2} \ln \frac{P(y = h_{t}(x))}{P(y \neq h_{t}(x))} \Rightarrow \alpha_{t} = \frac{1}{2} \ln \frac{1 - \varepsilon_{t}}{\varepsilon_{t}} \qquad P(x_{i}, y_{i}) = D_{t}(i)$$

$$\varepsilon_{t} = P(\text{error}) \approx \sum_{i=1}^{m} D_{t}(i) [y_{i} \neq h_{j}(x_{i})]$$

$$\Rightarrow E_x \left[ e^{-yH_{t-1}(x)} \left[ -e^{-\alpha_t} P(y = h_t(x)) + e^{\alpha_t} P(y \neq h_t(x)) \right] \right] = 0$$

$$D_{t+1} = ?$$

Final classifier

Given:  $(x_1, y_1), K, (x_m, y_m)$  where  $x_i \in X, y_i \in \{-1, +1\}$ 

Initialization:  $D_1(i) = \frac{1}{m}, i = 1, K, m$ 

For t = 1, K, T:

• Find classifier  $h_t: X \to \{-1, +1\}$  which minimizes error wrt  $D_t$  , i.e.,

$$h_t = \arg\min_{h_j} \varepsilon_j$$
 where  $\varepsilon_j = \sum_{i=1}^m D_t(i)[y_i \neq h_j(x_i)]$ 

Minimize los · Weight classifier:  $\alpha_t = \frac{1}{2} \ln \frac{1 - \varepsilon_t}{\varepsilon_t}$ 

Define  $H_t(x) = \underbrace{\begin{array}{c} \text{Update distribution:} \\ D_{t+1}(i) = \frac{D_t(i) \exp[-\alpha_t y_i h_t(x_i)]}{Z_t} \end{array}}_{D_{t+1}(i) = \frac{D_t(i) \exp[-\alpha_t y_i h_t(x_i)]}{Z_t}$  is for normalization Then, H(x) = H Output final classifier:  $sign\left(H(x) = \sum_{i=1}^{T} \alpha_i h_t(x)\right)$ 

$$\Rightarrow \alpha_t = \frac{1}{2} \ln \frac{P(y = h_t(x))}{P(y \neq h_t(x))} \Rightarrow \alpha_t = \frac{1}{2} \ln \frac{1 - \varepsilon_t}{\varepsilon_t} \qquad P(x_i, y_i) = D_t(i)$$

$$\varepsilon_t = P(\text{error}) \approx \sum_{i=1}^m D_t(i) [y_i \neq h_j(x_i)]$$

$$\Rightarrow E_x \left[ e^{-yH_{t-1}(x)} \left[ -e^{-\alpha_t} P(y = h_t(x)) + e^{\alpha_t} P(y \neq h_t(x)) \right] \right] = 0$$

Final classifier: 
$$sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$$
  
Minimize  $loss_{exp}\left[H(x)\right] = E_{x,y}\left[e^{-yH(x)}\right]$ 

Minimize 
$$loss_{exp}[H(x)] = E_{x,y}[e^{-yH(x)}]$$

Define 
$$H_t(x) = H_{t-1}(x) + \alpha_t h_t(x)$$
 with  $H_0(x) = 0$ 

Then, 
$$H(x) = H_T(x)$$

$$E_{x,y} \left[ e^{-yH_t} \right] = E_{x,y} \left[ e^{-yH_{t-1}} e^{-y\alpha_t h_t} \right] \approx E_{x,y} \left[ e^{-yH_{t-1}} \left( 1 - y\alpha_t h_t + \frac{1}{2} \alpha_t^2 y^2 h_t^2 \right) \right]$$

$$\Rightarrow h_t = \arg\min_{h} E_{x,y} \left[ e^{-yH_{t-1}} \left( 1 - y\alpha_t h + \frac{1}{2}\alpha_t^2 y^2 h^2 \right) \right] \qquad y^2 h^2 = 1$$

$$\Rightarrow h_t = \arg\min_{h} E_{x,y} \left[ e^{-yH_{t-1}} \left( 1 - y\alpha_t h + \frac{1}{2}\alpha_t^2 \right) \right]$$

$$\Rightarrow h_{t} = \arg\min_{h} E_{x} \left[ E_{y} \left[ e^{-yH_{t-1}} \left( 1 - y\alpha_{t}h + \frac{1}{2}\alpha_{t}^{2} \right) \right] | x \right]$$

Final classifier: 
$$sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$$
  
Minimize  $loss_{exp}\left[H(x)\right] = E_{x,y}\left[e^{-yH(x)}\right]$ 

Minimize 
$$loss_{exp}[H(x)] = E_{x,y}[e^{-yH(x)}]$$

Define 
$$H_t(x) = H_{t-1}(x) + \alpha_t h_t(x)$$
 with  $H_0(x) = 0$ 

Then, 
$$H(x) = H_T(x)$$

$$\Rightarrow h_{t} = \arg\max_{h} E_{x} \left[ 1 \cdot h(x) e^{-H_{t-1}(x)} \cdot P(y = 1 \mid x) + (-1) \cdot h(x) e^{H_{t-1}(x)} \cdot P(y = -1 \mid x) \right]$$

$$\Rightarrow h_{t} = \arg\max_{h} E_{x} \left[ E_{y} \left[ e^{-yH_{t-1}} \left( yh \right) \right] | x \right]$$

$$\Rightarrow h_{t} = \arg\min_{h} E_{x} \left[ E_{y} \left[ e^{-yH_{t-1}} \left( -y\alpha_{t}h \right) \right] | x \right]$$

$$\Rightarrow h_t = \arg\min_{h} E_x \left[ E_y \left[ e^{-yH_{t-1}} \left( 1 - y\alpha_t h + \frac{1}{2}\alpha_t^2 \right) \right] | x \right]$$

# $D_{t+1} = ?$

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Final classifier: 
$$sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$$
  
Minimize  $loss_{exp}\left[H(x)\right] = E_{x,y}\left[e^{-yH(x)}\right]$   
Define  $H_t(x) = H_{t-1}(x) + \alpha_t h_t(x)$  with  $H_0(x) = 0$ 

Then,  $H(x) = H_T(x)$ 

$$\Rightarrow h_{t} = \arg\max_{h} E_{x} \left[ 1 \cdot h(x) e^{-H_{t-1}(x)} \cdot P(y=1 \mid x) + (-1) \cdot h(x) e^{H_{t-1}(x)} \cdot P(y=-1 \mid x) \right]$$

$$\Rightarrow h_t = \arg\max_h E_{x, y \sim e^{-yH_{t-1}(x)}P(y|x)} \left[ yh(x) \right] \qquad \text{maximized when } y = h(x) \quad \forall x$$

$$\Rightarrow h_t(x) = sign\left(E_{x, y \sim e^{-yH_{t-1}(x)}P(y|x)}[y \mid x]\right)$$

$$\Rightarrow h_t(x) = sign\left(P_{x, y \sim e^{-yH_{t-1}(x)}P(y|x)}(y=1 \mid x) - P_{x, y \sim e^{-yH_{t-1}(x)}P(y|x)}(y=-1 \mid x)\right)$$

$$D_{t+1} = ?$$

Then,  $H(x) = H_T(x)$ 

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Final classifier: 
$$sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$$
  
Minimize  $loss_{exp}\left[H(x)\right] = E_{x,y}\left[e^{-yH(x)}\right]$   
Define  $H_t(x) = H_{t-1}(x) + \alpha_t h_t(x)$  with  $H_0(x) = 0$ 

At time 
$$t$$
  $x, y \sim e^{-yH_{t-1}(x)}P(y \mid x)$ 

$$\Rightarrow h_t(x) = sign\left(P_{x, y \sim e^{-yH_{t-1}(x)}P(y|x)}(y = 1 \mid x) - P_{x, y \sim e^{-yH_{t-1}(x)}P(y|x)}(y = -1 \mid x)\right)$$

$$D_{t+1} = ?$$

Final classifier

Given:  $(x_1, y_1), K, (x_m, y_m)$  where  $x_i \in X, y_i \in \{-1, +1\}$ 

Initialization  $D_1(i) = \frac{1}{m}, i = 1, K, m$ 

For t = 1, K, T:

• Find classifier  $h_t: X \to \{-1, +1\}$  which minimizes error wrt  $D_t$ , i.e.,

$$h_t = \arg\min_{h_i} \varepsilon_j$$
 where  $\varepsilon_j = \sum_{i=1}^m D_t(i)[y_i \neq h_j(x_i)]$ 

- Minimize los · Weight classifier:  $\alpha_t = \frac{1}{2} \ln \frac{1 \varepsilon_t}{\varepsilon}$
- Define  $H_t(x) = \int_{t+1}^{t} (t) \exp[-\alpha_t y_i h_t(x_i)] Z_t$  is for normalization Then, H(x) = H Output final classifier:  $sign\left(H(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\right)$

At time t  $x, y \sim e^{-yH_{t-1}(x)}P(y|x)$ 

At time 1  $x, y \sim P(y \mid x)$   $P(y_i \mid x_i) = 1 \Rightarrow D_1(1) = \frac{1}{Z_1} = \frac{1}{m}$ 

At time t+1  $x, y \sim e^{-yH_t(x)}P(y|x) \equiv D_{t}e^{-\alpha_t yh_t(x)}$ 

 $\Rightarrow D_{t+1}(i) = \frac{D_t(i) \exp[-\alpha_t y_i h_t(x_i)]}{Z_t}, Z_t \text{ is for normalization}$ 

### Successful applications of ensembles

Netflix prize





Users rate movies (1,2,3,4,5 stars); Netflix makes suggestions to users based on previous rated movies.





"The Netflix Prize seeks to substantially improve the accuracy of predictions about how much someone is going to love a movie based on their movie preferences. Improve it enough and you win one (or more) Prizes. Winning the Netflix Prize improves our ability to connect people to the movies they love."



- Supervised learning task
  - Training data is a set of users and ratings (1,2,3,4,5 stars) those users have given to movies.
  - Construct a classifier that given a user and an unrated movie, correctly classifies that movie as either 1, 2, 3, 4, or 5 stars

\$1 million prize for a 10% improvement over Netflix's current movie recommender/classifier



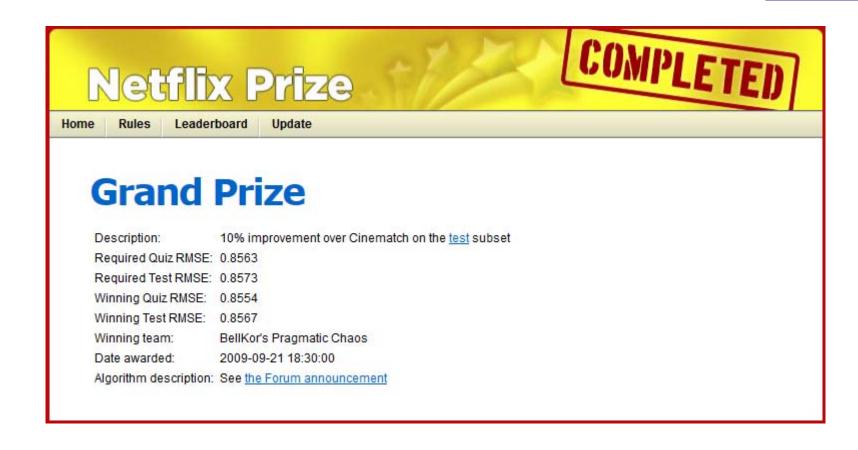






■ The final solution consists of blending 107 individual results.







#### Leaderboard

Showing Test Score. Click here to show quiz score

Display top 20 ▼ leaders.

Rank	Team Name	Best Test Score	% Improvement	Best Submit Time
Grand Prize - RMSE = 0.8567 - Winning Team: BellKor's Pragmatic Chaos				
1	BellKor's Pragmatic Chaos	0.8567	10.06	2009-07-26 18:18:28
2	The Ensemble	0.8567	10.06	2009-07-26 18:38:22
3	Grand Prize Team	0.8582	9.90	2009-07-10 21:24:40
4	Opera Solutions and Vandelay United	0.8588	9.84	2009-07-10 01:12:31
5	Vandelay Industries!	0.8591	9.81	2009-07-10 00:32:20
6	<u>PragmaticTheory</u>	0.8594	9.77	2009-06-24 12:06:56
7	BellKor in BigChaos	0.8601	9.70	2009-05-13 08:14:09
8	<u>Dace</u>	0.8612	9.59	2009-07-24 17:18:43
9	Feeds2	0.8622	9.48	2009-07-12 13:11:51
10	<u>BiqChaos</u>	0.8623	9.47	2009-04-07 12:33:59
11	Opera Solutions	0.8623	9.47	2009-07-24 00:34:07
12	BellKor	0.8624	9.46	2009-07-26 17:19:11

## MIMA Group

# Thank You!

**Any Question?**