922 U0610 電腦視覺 Computer Vision

Homework 2

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I. INTRODUCTION

1.1. Descriptions of Problem

Part 1 of this homework is to binarize lena.bmp with threshold 128 (0-127, 128-255).

Part 2 of this homework is to draw the histogram of lena.bmp.

Part 3 of this homework is to find connected components with following rules:

- A. Draw bounding box of regions.
- B. Draw cross at centroid of regions.
- C. Omit regions that have a pixel count less than 500.

1.2. Programming Tools

- 1.2.1. Programming Language: Python3
- 1.2.2. Programming IDE: Visual Studio Code

II. METHOD

2.1. Algorithms

2.1.1. Binarize lena.bmp with threshold 128 (0-127, 128-255)

- Step 0. Define threshold of binary image.
- Step 1. Load image from file.
- Step 2. Get width and height of image.
- Step 3. New image with the same size and 'binary' format.
- Step 4. Process image pixel by pixel. (r: row, c: column)
- Step 4.1. Get pixel value from lena.bmp at (c, r).
- Step 4.2. If value bigger than or equal to threshold, set pixel as 1 to target at (c, r).
- Step 4.3. If value smaller than threshold, set pixel as 0 to target at (c, r).
- Step 5. Save image.

2.1.2. Draw the histogram of lena.bmp

- Step 1. Load image from file.
- Step 2. Get width and height of image.
- Step 3. Create histogram array with zeros.
- Step 4. Process image pixel by pixel. (r: row, c: column)
- Step 4.1. Get pixel from lena.bmp at (width 1 c, r).
- Step 4.2. Record count in histogram array.
- Step 5. Save histogram to csv file.
- Step 6. Plot, save and show the histogram.

2.1.3. Find connected components

- Step 0. Define threshold of region pixels.
- Step 1. Load image from file.
- Step 2. Get width and height of image.
- Step 3. Assign a unique ID to each region with <u>8-connected neighborhood detection</u>.
- Step 4. Only deal with region which has at least 500 pixels.
- Step 4.1. Push rectangle's information to stack.
- Step 5. New image with the same size and 'RGB' format.
- Step 6. Draw rectangles and crosses on image.
- Step 7. Save image.

2.2. Code Fragments

2.2.1. Part 1 of this homework

```
HW2.1.py X

■ binary.bmp

      from PIL import Image
      threshold = 128
      originalImage = Image.open('lena.bmp')
      width, height = originalImage.size
      # New image with the same size and 'binary' format.
      binaryImage = Image.new('1', originalImage.size)
      for c in range(width):
          for r in range(height):
              value = originalImage.getpixel((c, r))
              if (value >= threshold):
                  value = 1
              else:
                  value = 0
              binaryImage.putpixel((c, r), value)
      binaryImage.save('binary.bmp')
```

Figure 2.2.1. Code of part 1 of this homework.

2.2.2. Part 2 of this homework

```
HW2.2.py X
      from PIL import Image
      import matplotlib.pyplot as plt
      import numpy as np
      import csv
      originalImage = Image.open('lena.bmp')
      width, height = originalImage.size
      # Create histogram array with zeros.
      histogram = np.zeros(256)
      for c in range(width):
          for r in range(height):
              pixelValue = originalImage.getpixel((c, r))
              # Record count in histogram array.
              histogram[pixelValue] += 1
      # Save histogram to csv file.
     csvFile = open('histogram.csv', 'w')
      writer = csv.writer(csvFile)
      writer.writerow(histogram)
      plt.bar(range(len(histogram)), histogram)
     plt.savefig('histogram.png')
      plt.show()
```

Figure 2.2.2. Code of part 2 of this homework.

2.2.3. Part 3 of this homework

```
from PIL import Image, ImageDraw
import numpy as np
class Stack:
    "A container with a last-in-first-out (LIFO) queuing policy."
   def init (self):
       self.list = []
    def push(self,item):
        "Push 'item' onto the stack"
       self.list.append(item)
    def pop(self):
        "Pop the most recently pushed item from the stack"
        return self.list.pop()
    def isEmpty(self):
        "Returns true if the stack is empty"
        return len(self.list) == 0
thresholdRegionPixels = 500
originalImage = Image.open('lena.bmp')
binaryImage = Image.open('binary.bmp')
width, height = originalImage.size
# Record is this location visited or not.
visited = np.zeros((width, height))
labeledImageArray = np.zeros((width, height))
idCount = 1
numberLabel = np.zeros(width * height)
```

Figure 2.2.3.1. Code of part 3 of this homework.

```
for c in range(width):
    for r in range(height):
        if binaryImage.getpixel((c, r)) == 0:
            visited[c, r] = 1
        elif visited[c, r] == 0:
            stack = Stack()
            stack.push((c, r))
            while not stack.isEmpty():
                col, row = stack.pop()
                if visited[col, row] == 1:
                    continue
                visited[col, row] = 1
                labeledImageArray[col, row] = idCount
                numberLabel[idCount] = numberLabel[idCount] + 1
                for x in [col - 1, col, col + 1]:
                    for y in [row - 1, row, row + 1]:
                        if (0 \le x \le width) and (0 \le y \le height):
                            if (binaryImage.getpixel((x, y)) != 0) and (visited[x, y] == 0):
                                stack.push((x, y))
            idCount += 1
```

Figure 2.2.3.2. Code of part 3 of this homework.

```
rectangles = Stack()
# Look through each label.
for regionID, n in enumerate(numberLabel):
    if (n >= thresholdRegionPixels):
        # left position of rectangle.
        rectLeft = width
        rectRight = 0
        # top position of rectangle.
        rectTop = height
        rectBottom = 0
        for x in range(width):
            for y in range(height):
                 if (labeledImageArray[x, y] == regionID):
                    if (x < rectLeft):</pre>
                         rectLeft = x
                     if (x > rectRight):
                         rectRight = x
                     if (y < rectTop):</pre>
                         rectTop = y
                     if (y > rectBottom):
                         rectBottom = y
        rectangles.push((rectLeft, rectRight, rectTop, rectBottom))
```

Figure 2.2.3.3. Code of part 3 of this homework.

```
connectedImage = Image.new('RGB', originalImage.size)
connectedImageArray = connectedImage.load()
# Process image pixel by pixel.
for c in range(width):
    for r in range(height):
        # Convert binary image to 'RGB' format.
        if (binaryImage.getpixel((c, r)) == 0):
            connectedImageArray[c, r] = (0, 0, 0)
            connectedImageArray[c, r] = (255, 255, 255)
# Draw rectangles and crosses on image.
while not rectangles.isEmpty():
    rectLeft, rectRight, rectTop, rectBottom = rectangles.pop()
    # Object to draw image.
    draw = ImageDraw.Draw(connectedImage)
    draw.rectangle(((rectLeft, rectTop), (rectRight, rectBottom)), outline = 'red')
    # Center of rectangle.
    rectCenterX = (rectLeft + rectRight) / 2
    rectCenterY = (rectTop + rectBottom) / 2
    draw.line(((rectCenterX - 10, rectCenterY)), (rectCenterX + 10, rectCenterY)), \
    fill = 'red', width = 5)
    draw.line(((rectCenterX, rectCenterY - 10), (rectCenterX, rectCenterY + 10)), \
    fill = 'red', width = 5)
connectedImage.save('connectedImage.bmp')
```

Figure 2.2.3.4. Code of part 3 of this homework.

III. RESULTS

3.1. Original Image



Figure 3.1. Original lena.bmp.

3.2. Results of part 1 of this homework





Figure 3.2.1. Original lena.bmp.

Figure 3.2.2. Binary.bmp.

3.3. Results of part 2 of this homework



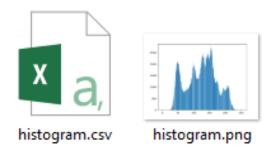


Figure 3.3.1. Original lena.bmp.

Figure 3.3.2. Output files of part 2.

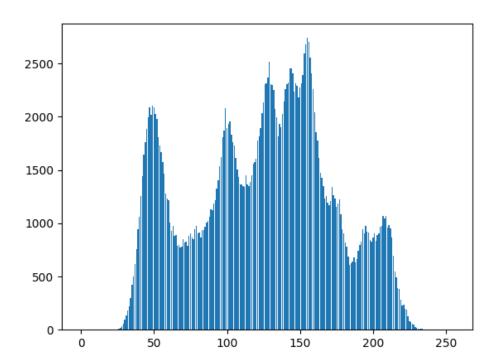


Figure 3.3.3. Histogram of lena.bmp.

3.4. Results of part 3 of this homework





Figure 3.4.1. Original lena.bmp.

Figure 3.4.2. Binary.bmp..



Figure 3.4.3. connectedImage.bmp.