# 6.6: Beyond Linearity

\$ echo "Data Science Institute"

#### Introduction

In section 6.5 we saw how we can improve upon linear models by reducing their complexity and therefore the resulting variance of the estimates.

In this section we will look at extension of the linear model that do not require linearity.

- Polynomial Regression
- Step Functions
- Regression Splines
- Local Regression
- Generalized Additive Models

## **Polynomial Regression**

The extension from linear regression to polynomial regression replaces the linear model

$$y_i=eta_0+eta_1x_i+\epsilon_i$$
 with a polynomial model of degree  $d$   $y_i=eta_0+eta_1x_i+eta_2x_i^2+eta_3x_i^3+\cdots+eta_dx_i^d+\epsilon_i$ . The coefficient are easily \alert{estimated using least squares regression} with predictors  $x_i,x_i^2,\ldots,x_i^d$ .

• We do not often fit polynomials with degrees higher than 4 since they can be overly flexible and result in overfitting.

## **Exercises: Polynomial Regression**

- Go over the "Getting Started" section together as a class.
- Go over the "Polynomial Regression" section together as a class.
- 5 minutes for students to complete the questions.
- Questions should be completed at home if time does not allow.

## **Step Functions**

Step functions involve breaking the range of the predictor X into sections with specified cut points  $c_1, c_2, \ldots c_K$ , called **knots**. Each section is then fit with a constant so our model becomes

$$y_i = f(x_i) = egin{cases} eta_0 + eta_1, & ext{if} & x_i \leq c_1 \ eta_0 + eta_2, & ext{if} & c_1 \leq x_i \leq c_2 \ dots & dots \ eta_0 + eta_K, & ext{if} & c_K \leq x_i \end{cases}$$

We can use least squares to fit the coefficients.

## **Exercises: Step Functions**

- Go over the "Step Functions" section together as a class.
- 5 minutes for students to complete the questions.
- Questions should be completed at home if time does not allow.

## **Regression Splines**

**Piecewise polynomial regression** is a combination of the previous two methods we have seen. We fit each of the K predictor sections with a polynomial of degree d.

$$y_i = f(x_i) = egin{cases} eta_{01} + eta_{11} x_i + eta_{21} x_i^2 + \cdots + eta_{d1} x_i^d, & ext{if} \quad x_i \leq c_1 \ eta_{02} + eta_{12} x_i + eta_{22} x_i^2 + \cdots + eta_{d2} x_i^d, & ext{if} \quad c_1 \leq x_i \leq c_2 \ dots & dots \ eta_{0K} + eta_{1K} x_i + eta_{2K} x_i^2 + \cdots + eta_{dK} x_i^d, & ext{if} \quad c_K \leq x_i \end{cases}$$

Again, the coefficients can be fit using least squares.

The degrees of freedom of a model is a measure of how flexible it is.

- The higher the degree of the polynomial and the more knots we have, the higher the degree of freedom.
- The higher the degrees of freedom the more flexible the model is.

#### **Location and Number of Knot**

#### Where to place knots?

- Regression splines are most stable in regions with a lot of knots.
- Place knots in places where function might vary the fastest.
- Although often knots are placed at uniform intervals for simplicity.

#### How many knots?

- Try out different numbers and see which looks best.
- Use cross-validation to find the value of K with the smallest RSS.

## **Constraints for Regression Splines**

There are several useful constraints that can be used with regression splines to reduce their degrees of freedom, thereby reducing their flexibility and making the fit more stable.

- \alert{Continuity}: the fitted curve must be continuous.
- \alert{Continuous derivatives}: the first or second derivative must be continuous (this
  has the effect of requiring the curve to be smooth... no corners etc.)
- $\arrowvert Albert {Natural spline}: the function must be linear in the region on the boundary (i.e. where <math>X$  is smaller than the smallest knot or larger than the largest knot).

### **Exercises: Splines**

Open the Beyond Linearity Exercises Jupyter Notebook file.

• Go over the "Splines" section together as a class.

# **Local Regression**

Local regression involves fitting a function at a target point  $x_0$  using only the nearby training observations.

- 1. Find the k training observations with  $x_i$  closest to  $x_0$ .
- 2. Assign weights  $K_{i0}$  to each of these points so that the farthest point has weight zero and the closest has the highest weight.
- 3. Fit a weighted least squares regression by finding  $\hat{eta}_0$  and  $\hat{eta}_1$  that minimize

$$\sum_{i=1}^{n} K_{i0}(y_i - eta_0 - eta_1 x_i)^2$$
.

4. The fitted function is then  $y_i = \hat{eta_0} + \hat{eta_1} x_i$ .

## **Choices for Local Regression**

The most important choice is the \alert{span s=k/n which is the fraction of points that are used to perform the local regression}.

- Controls the flexibility of the fit
  - $\circ$  small s results in a local, more wiggly fit
  - $\circ$  large s provides a global fit.
- Cross-validation can be used to choose s or it can be chosen directly.

There are other less important choices that can be made.

- How to define the weighting function K.
- What type of model to use such as constant, linear, or quadratic regression.

### **Exercises: Local Regression**

- Go over the "Local Regression" section together as a class.
- 10 minutes for students to complete the questions.
- Questions should be completed at home if time does not allow.

#### **Generalized Additive Models**

We have seen how we can extend simple linear regression beyond linearity. Now we will look at extensions for multiple linear regression. In the case of a  $\altert quantitative response$  our linear regression model is

$$y_i = eta_0 + eta_1 x_{i1} + eta_2 x_{i2} + \cdots + eta_p x_{ip} + \epsilon_i$$

We can replace the linear  $eta_j x_{ij}$  with a non linear function  $f_j\left(x_{ij}
ight)$  to aquire the model

$$y_i = eta_0 + f_1\left(x_{i1}
ight) + f_2\left(x_{i2}
ight) + \cdots + f_p\left(x_{ip}
ight) + \epsilon_i$$

The functions  $f_j(x_{ij})$  can all have different forms including natural splines, polynomial regression, local regression etc. We can fit the model using least squares.

#### **Generalized Additive Models**

GAMs can also be used for qualitative Y. We will assume that Y is zero or one and  $p(X) = \Pr(Y = 1|X)$ . The logistic regression model is

$$\log\left(rac{p(X)}{1-p(X)}
ight)=eta_0+eta_1X_1+eta_2X_2+\cdots+eta_pX_p$$

We can incorporate non-linear relationships with functions  $f_j(X_j)$ 

$$\log\left(rac{p(X)}{1-p(X)}
ight)=eta_0+f_1\left(X_1
ight)+f_2\left(X_2
ight)+\cdots+f_p\left(X_p
ight)$$

#### **Pros and Cons of GAMs**

#### Pros

- We can model different non-linear relationships for each variable.
- Non-linear fits could provide more accurate predictions.
- The additive model allows for the examination of the effect of a single predictor while holding the rest constant.

#### Cons

• The interactions between variables are missed with the additive assumption. However, we can add additional predictors in the form of  $X_i imes X_j$ .

#### **Exercises: GAMs**

- Go over the start of the "Generalized Linear Models" section together as a class.
- 10 minutes for students to complete the questions.
- Go over the rest of the "Generalized Linear Models" section together as a class.
- Questions should be completed at home if time does not allow.

#### References

Chapter 7 of the ISLR2 and ISLP books:

James, Gareth, et al. "Moving Beyond Linearity." An Introduction to Statistical Learning: with Applications in R, 2nd ed., Springer, 2021.

James, Gareth, et al. "Moving Beyond Linearity." An Introduction to Statistical Learning: with Applications in Python, Springer, 2023.