

CS 188 Discussion 9:

Bayes Net Sampling, Decision Networks, VPI

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Slides based on Sashrika + Joy

Administrivia

- Project 4 due on Mon, Nov 6
- Homework is due on Tuesdays
- We have office hours pretty much all day every weekday (12-7), come to Soda 341B! (my hours are 1-3 PM on Mondays)
- Discussion slides are on Ed
- **No discussion last week - Bayes Nets discussion worksheet + solns posted**

Today's Topics

- Bayes Net Sampling
 - Prior Sampling
 - Rejection Sampling
 - Likelihood Weighting
 - Gibbs Sampling
- Decision Networks
- Value of Perfect Information (VPI)

Sampling

- Want some probability, for example $P(A)$ or $P(A \mid +b)$
- Calculating exact probability (for example, with variable elimination) can be horribly expensive
- Take random samples and infer the probability with reasonable accuracy

Prior Sampling

- Algorithm:

- Generate samples

- For $i=1, 2, \dots, n$ (in topological order)
 - Sample X_i from $P(X_i \mid \text{parents}(X_i))$
- Return (x_1, x_2, \dots, x_n)

- Discard samples inconsistent with evidence
- Calculate probability of the query

- Pros:

- Easy!

- Cons:

- Requires a large number of samples, especially when we condition on unlikely scenarios

Rejection Sampling

Worksheet Q1a

- Algorithm:

- Generate samples

- Input: evidence e_1, \dots, e_k
- For $i=1, 2, \dots, n$
 - Sample x_i from $P(x_i \mid \text{parents}(x_i))$
 - If x_i not consistent with evidence
 - Reject: Return, and no sample is generated in this cycle
- Return (x_1, x_2, \dots, x_n)

- Calculate probability of the query

- Pros:

- Bad samples take less time to create, so more efficient than Prior Sampling

- Cons:

- Still requires a large number of samples, especially when we condition on unlikely scenarios

Likelihood Weighting

Worksheet Q1b-d

- Idea: Set all your variables to agree with evidence, then sample
 - **Weight** all samples by the probability of the evidence given the sampled variables
- Pros:
 - Never generate a bad sample!
- Cons:
 - Evidence influences the choice of downstream variables, but not upstream ones. Samples could have low weight!

```
▪ Input: evidence  $e_1, \dots, e_k$ 
▪  $w = 1.0$ 
▪ for  $i=1, 2, \dots, n$ 
  ▪ if  $X_i$  is an evidence variable
    ▪  $x_i =$  observed value $i$  for  $X_i$ 
    ▪ Set  $w = w * P(x_i \mid \text{parents}(X_i))$ 
  ▪ else
    ▪ Sample  $x_i$  from  $P(X_i \mid \text{parents}(X_i))$ 
▪ return  $(x_1, x_2, \dots, x_n), w$ 
```

- A bit less intuitive
- Algorithm:
 - Step 1: Fix all evidence variables
 - Step 2: Assign all other variables randomly
 - Keep looping through non-evidence variables:
 - Resample this variable \mathbf{X} from $\mathbf{P}(\mathbf{X} \mid \text{all other variables})$
 - New state of variables with the new \mathbf{X} is new sample
 - As the number of iterations grows large, the samples converge to coming from the right distribution
- Pros:
 - Both upstream and downstream variables condition on evidence

Decision Networks

- MDP Sampling
- **Decision Networks**
- Value of Perfect Information (VPI)

Decision Networks



Chance nodes: associated with a probability (like Bayes nets), ovals

- Ex: 80% chance of rain forecasted

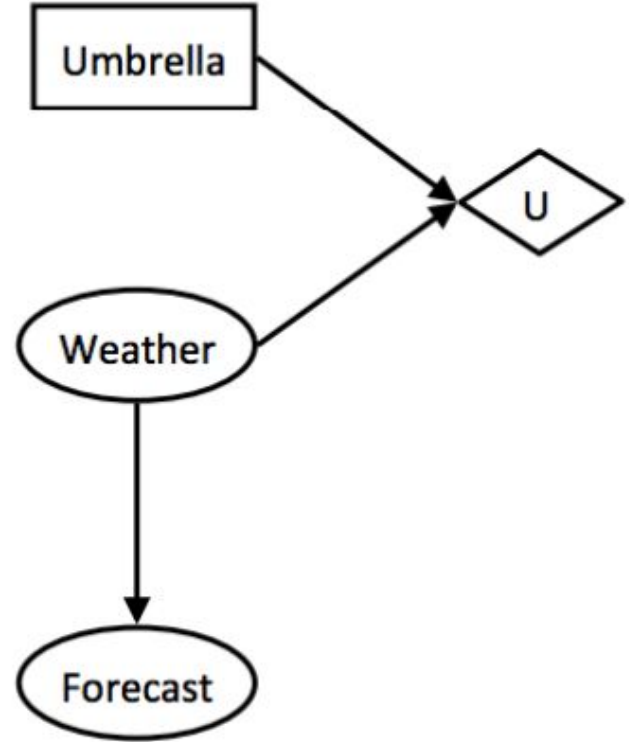


Action nodes: represent choice from a number of actions, rectangles

- Ex: do I take my umbrella?



Utility nodes: combination of action + chance, utility determined from parents' values, diamonds



Utility

- Expected utility (EU) of taking action a given evidence e with n chance nodes

$$EU(a|e) = \sum_{x_1, \dots, x_n} P(x_1, \dots, x_n|e)U(a, x_1, \dots, x_n)$$

- Maximum expected utility (MEU): choose the action that maximizes EU

$$MEU(E = e) = \max_a EU(A = a|E = e)$$

Value of Perfect Information (VPI)

- MDP Sampling
- Decision Networks
- **Value of Perfect Information (VPI)**

VPI

- Observing evidence may have a cost (time, money) → let's quantify how much it's worth
 - Current max utility with evidence e is

$$MEU(e) = \max_a \sum_s P(s|e)U(s, a)$$

- If we observed some evidence e' , MEU becomes

$$MEU(e, e') = \max_a \sum_s P(s|e, e')U(s, a)$$

- But we don't know what e' is → replace with random variable E' . Represent new MEU with expected value of MEU (our best estimate)

$$MEU(e, E') = \sum_{e'} P(e'|e)MEU(e, e')$$

- How much is MEU expected to increase? Find the difference!

$$VPI(E'|e) = MEU(e, E') - MEU(e)$$

- Nonnegativity

- Observing new evidence cannot hurt you

$$\forall E', e \ VPI(E'|e) \geq 0$$

- Nonadditivity

- The VPI of observing two pieces of evidence isn't necessarily the sum of their individual VPI'

$$VPI(E_j, E_k|e) \neq VPI(E_j|e) + VPI(E_k|e) \text{ in general}$$

- Order Independence

- Order of observing evidence doesn't matter since we only take an action after observing new evidence

$$VPI(E_j, E_k|e) = VPI(E_j|e) + VPI(E_k|e, E_j) = VPI(E_k|e) + VPI(E_j|e, E_k)$$

Rest of the Worksheet

Thank you for attending!

Attendance link:

- <https://tinyurl.com/cs188fa23>

Discussion No: 9

Remember my name is Kenny

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