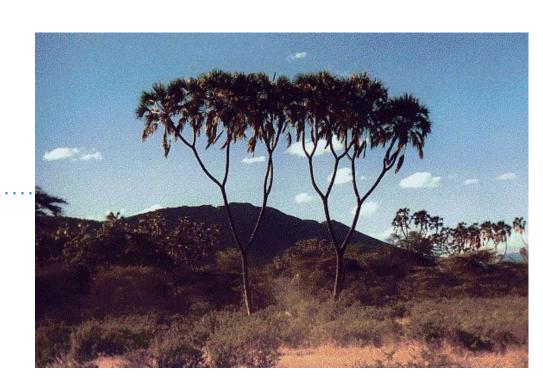
CS61B, 2019

Lecture 16: ADTs and BSTs

- Abstract Data Types
- Binary Search Tree (intro)
- BST Definitions
- BST Operations
- Sets vs. Maps, Summary





Abstract Data Types



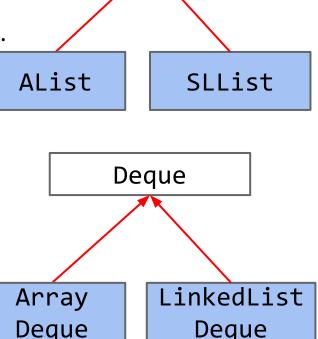
Interfaces vs. Implementation

In class:

- Developed ALists and SLLists.
- Created an interface List61B.
 - Modified AList and SLList to implement List61B.
 - List61B provided default methods.

In projects:

- Developed ArrayDeque and LinkedListDeque.
- Created an interface Deque.
 - Modified AD and LLD to implement Deque.

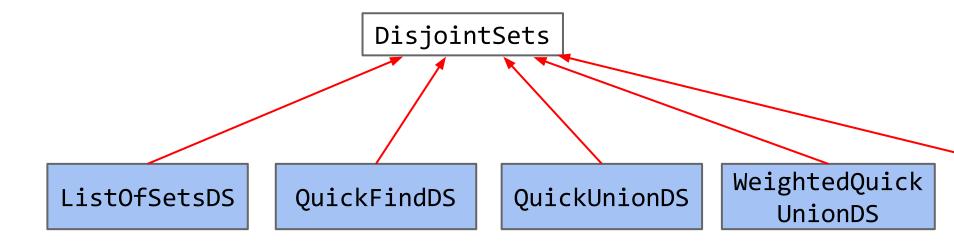


List61B



Interfaces vs. Implementation

With DisjointSets, we saw a much richer set of possible implementations.



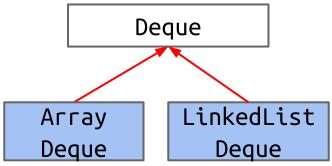


Abstract Data Types

An **Abstract Data Type (ADT)** is defined only by its operations, not by its implementation.

Deque ADT:

- addFirst(Item x);
- addLast(Item x);
- boolean isEmpty();
- int size();
- printDeque();
- Item removeFirst();
- Item removeLast();
- Item get(int index);



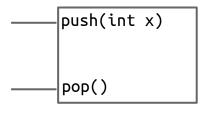
ArrayDeque and LinkedList Deque are implementations of the Deque ADT.



Another example of an ADT: The Stack

The Stack <u>ADT</u> supports the following operations:

- push(int x): Puts x on top of the stack.
- int pop(): Removes and returns the top item from the stack.



2 6 4



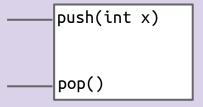
The Stack ADT: yellkey.com/?

The Stack <u>ADT</u> supports the following operations:

- push(int x): Puts x on top of the stack.
- int pop(): Removes and returns the top item from the stack.

Which implementation do you think would result in faster overall performance?

- A. Linked List
- B. Array



+



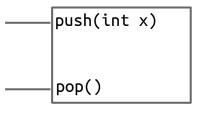
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- B. Array



4

Both are about the same. No resizing for linked lists, so probably a lil faster.



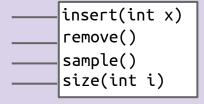
The GrabBag ADT: yellkey.com/?

The GrabBag <u>ADT</u> supports the following operations:

- insert(int x): Inserts x into the grab bag.
- int remove(): Removes a random item from the bag.
- int sample(): Samples a random item from the bag (without removing!)
- int size(): Number of items in the bag.

Which <u>implementation</u> do you think would result in faster overall performance?

- A. Linked List
- B. Array





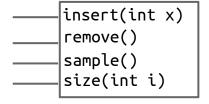
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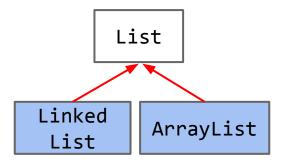


Abstract Data Types in Java

One thing I particularly like about Java is the syntax differentiation between abstract data types and implementations.

 Note: Interfaces in Java aren't purely abstract as they can contain some implementation details, e.g. default methods.

Example: List<Integer> L = new ArrayList<>();

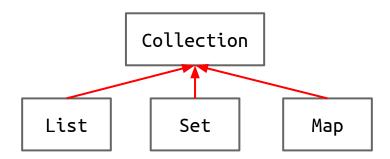




Collections

Among the most important interfaces in the java.util library are those that extend the Collection interface (btw interfaces can extend other interfaces).

- Lists of things.
- Sets of things.
- Mappings between items, e.g. jhug's grade is 88.4, or Creature c's north neighbor is a Plip.
 - Maps also known as associative arrays, associative lists (in Lisp), symbol tables, dictionaries (in Python).





Map Example

Maps are very handy tools for all sorts of tasks. Example: Counting words.

```
sumomo 1
mo 2
momo 2
no 1
uchi 1
```

Python equivalent

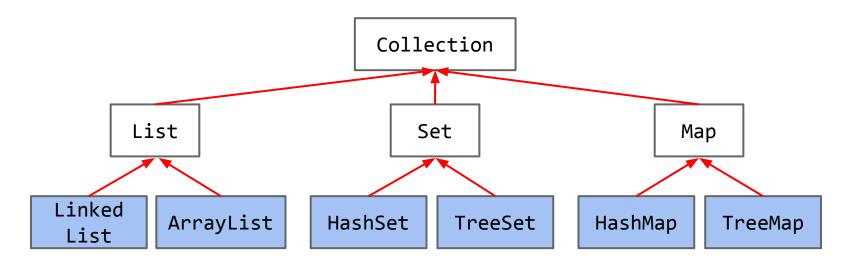


Java Libraries

The built-in java.util package provides a number of useful:

- Interfaces: ADTs (lists, sets, maps, priority queues, etc.) and other stuff.
- Implementations: Concrete classes you can use.

Today, we'll learn the basic ideas behind the TreeSet and TreeMap.

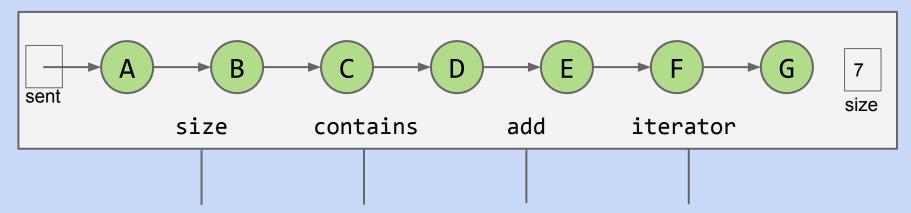


Binary Search Trees



Analysis of an OrderedLinkedListSet<Character>

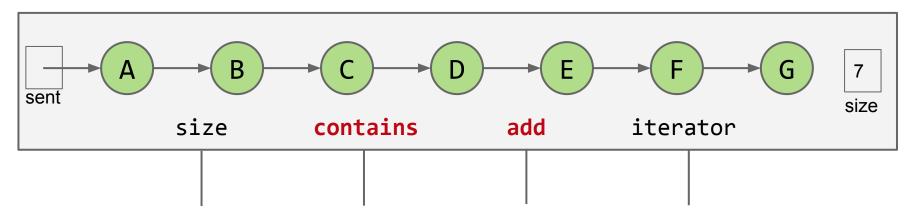
In an earlier lecture, we implemented a set based on <u>unordered arrays</u>. For the **order linked list** set implementation below, name an operation that takes worst case linear time, i.e. $\Theta(N)$.





Analysis of an OrderedLinkedListSet<Character>

In an earlier lecture, we implemented a set based on <u>unordered arrays</u>. For the **order linked list** set implementation below, name an operation that takes worst case linear time, i.e. $\Theta(N)$.

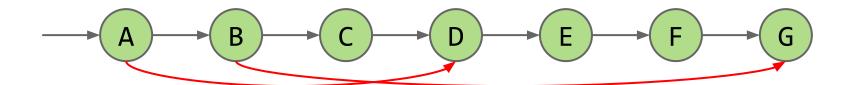




Optimization: Extra Links

Fundamental Problem: Slow search, even though it's in order.

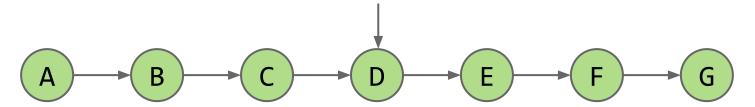
• Add (random) express lanes. Skip List (won't discuss in 61B)



Optimization: Change the Entry Point

Fundamental Problem: Slow search, even though it's in order.

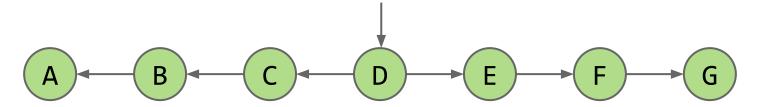
Move pointer to middle.



Optimization: Change the Entry Point, Flip Links

Fundamental Problem: Slow search, even though it's in order.

Move pointer to middle and flip left links. Halved search time!



Optimization: Change the Entry Point, Flip Links

Fundamental Problem: Slow search, even though it's in order.

How do we do even better?

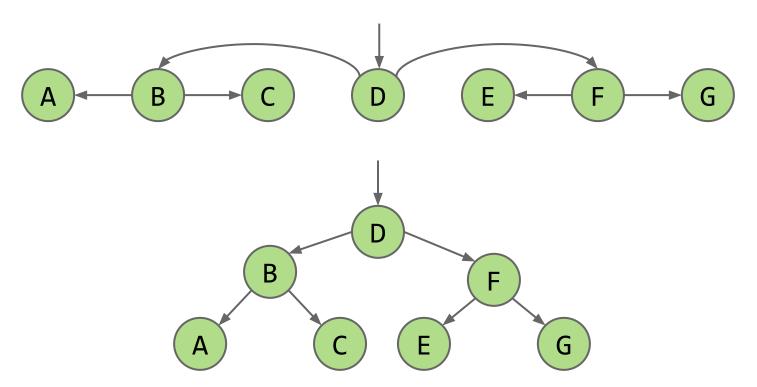




Optimization: Change Entry Point, Flip Links, Allow Big Jumps

Fundamental Problem: Slow search, even though it's in order.

How do we do better?





BST Definitions

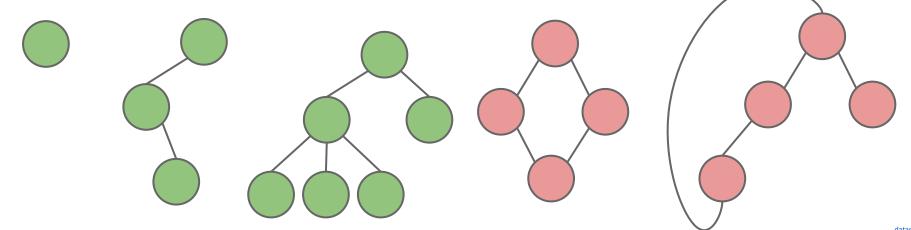


Tree

A tree consists of:

- A set of nodes.
- A set of edges that connect those nodes.
 - Constraint: There is exactly one path between any two nodes.

Green structures below are trees. Pink ones are not.



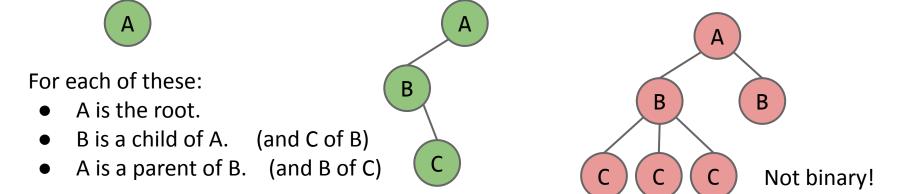


Rooted Trees and Rooted Binary Trees

In a rooted tree, we call one node the root.

- Every node N except the root has exactly one parent, defined as the first node on the path from N to the root.
- Unlike (most) real trees, the root is usually depicted at the top of the tree.
- A node with no child is called a leaf.

In a rooted binary tree, every node has either 0, 1, or 2 children (subtrees).



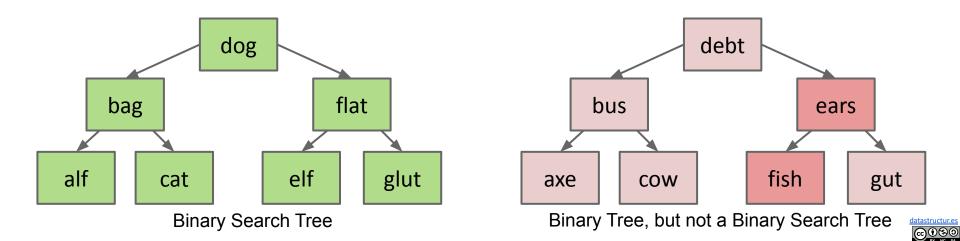


Binary Search Trees

A binary search tree is a rooted binary tree with the BST property.

BST Property. For every node X in the tree:

- Every key in the **left** subtree is **less** than X's key.
- Every key in the **right** subtree is **greater** than X's key.



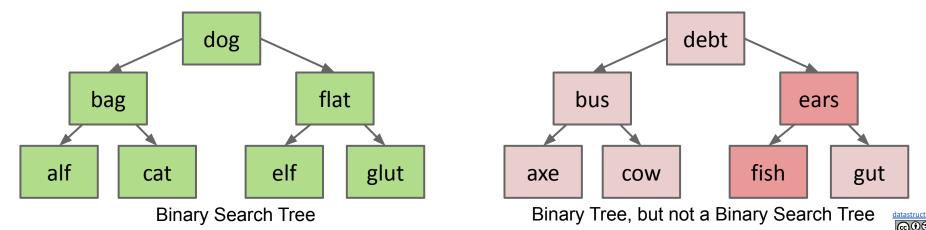
Binary Search Trees

Ordering must be complete, transitive, and antisymmetric. Given keys p and q:

- Exactly one of p < q and q < p are true.
- p < q and q < r imply p < r.

One consequence of these rules: No duplicate keys allowed!

Keeps things simple. Most real world implementations follow this rule.



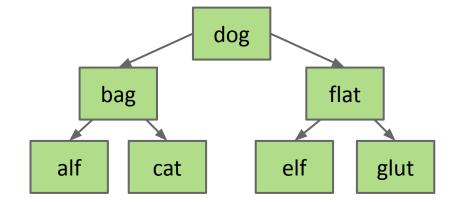
BST Operations: Search



Finding a searchKey in a BST (come back to this for the BST lab)

If searchKey equals T.key, return.

- If searchKey < T.key, search T.left.
- If searchKey > T.key, search T.right.



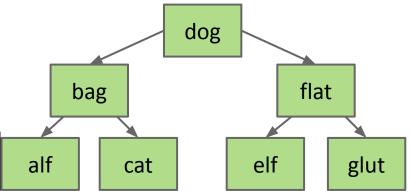


Finding a searchKey in a BST

If searchKey equals T.key, return.

- If searchKey < T.key, search T.left.
- If searchKey > T.key, search T.right.

```
static BST find(BST T, Key sk) {
   if (T == null)
      return null;
   if (sk.equals(T.key))
      return T;
   else if (sk < T.key)</pre>
      return find(T.left, sk);
   else
      return find(T.right, sk);
```



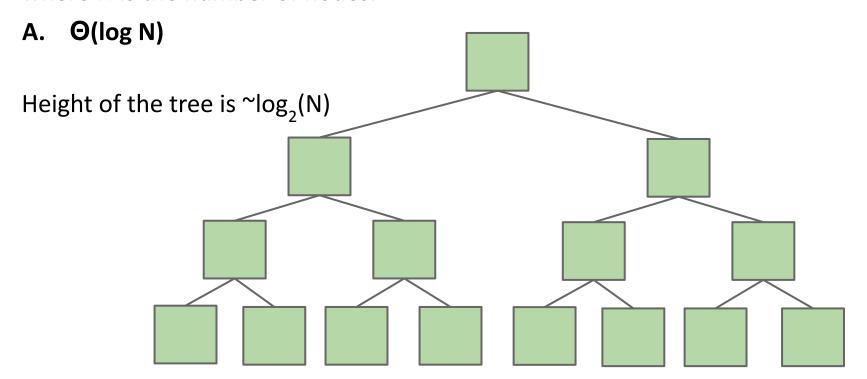
BST Search: http://yellkey.com/?

What is the runtime to complete a search on a "bushy" BST in the worst case, where N is the number of nodes. "bushiness" is an intuitive concept $\Theta(\log N)$ that we haven't defined. $\Theta(N)$ $\Theta(N \log N)$ $\Theta(N^2)$ $\Theta(2^N)$



BST Search

What is the runtime to complete a search on a "bushy" BST in the worst case, where N is the number of nodes.





BSTs

Bushy BSTs are extremely fast.

 At 1 microsecond per operation, can find something from a tree of size 10³⁰⁰⁰⁰⁰ in one second.

Much (perhaps most?) computation is dedicated towards finding things in response to queries.

It's a good thing that we can do such queries almost for free.



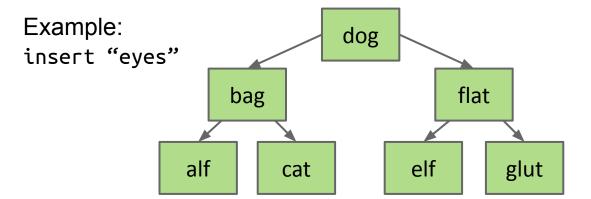
BST Operations: Insert



Inserting a New Key into a BST

Search for key.

- If found, do nothing.
- If not found:
 - Create new node.
 - Set appropriate link.





Inserting a New Key into a BST

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- If found, do nothing.
- If not found:
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```
static BST insert(BST T, Key ik) {
  if (T == null)
    return new BST(ik);
  if (ik < T.key)</pre>
    T.left = insert(T.left, ik);
  else if (ik > T.key)
    T.right = insert(T.right, ik);
  return T;
```

```
dog
    bag
                            flat
alf
                       elf
          cat
                                 glut
  ARMS LENGTH
                           eyes
  RECURSION!!!! No good.
```

A common rookie bad habit to avoid:

```
if (T.left == null)
  T.left = new BST(ik);
else if (T.right == null)
  T.right = new BST(ik);
```

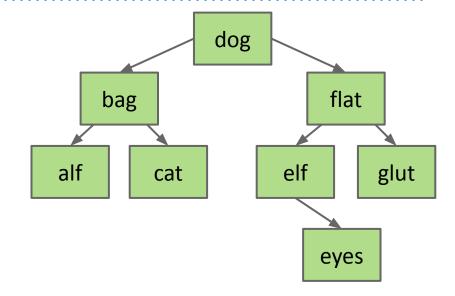
BST Operations: Delete



Deleting from a BST

3 Cases:

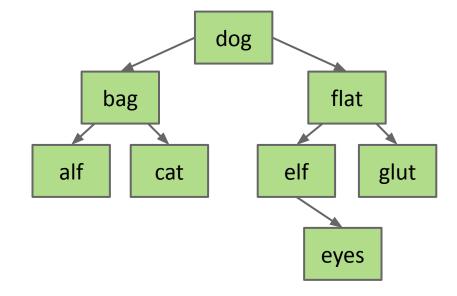
- Deletion key has no children.
- Deletion key has one child.
- Deletion key has two children.



Case 1: Deleting from a BST: Key with no Children

Deletion key has no children ("glut"):

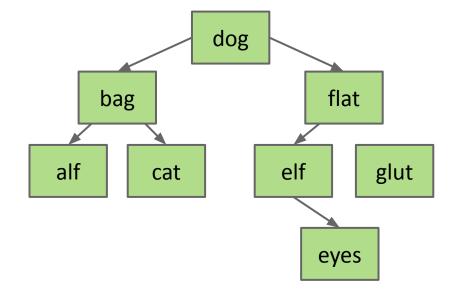
- Just sever the parent's link.
- What happens to "glut" node?



Case 1: Deleting from a BST: Key with no Children

Deletion key has no children ("glut"):

- Just sever the parent's link.
- What happens to "glut" node?
 - Garbage collected.



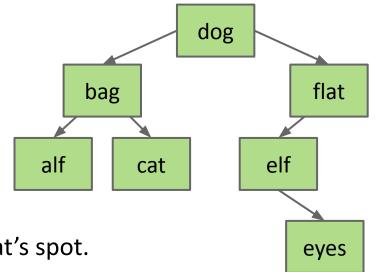
Case 2: Deleting from a BST: Key with one Child

Example: delete("flat"):

Goal:

- Maintain BST property.
- Flat's child definitely larger than dog.
 - Safe to just move that child into flat's spot.

Thus: Move flat's parent's pointer to flat's child.



Case 2: Deleting from a BST: Key with one Child

Example: delete("flat"):

Goal:

- Maintain BST property.
- Flat's child definitely larger than dog.
 - Safe to just move that child into flat's spot.

bag flat
alf cat elf
at's spot.
eyes

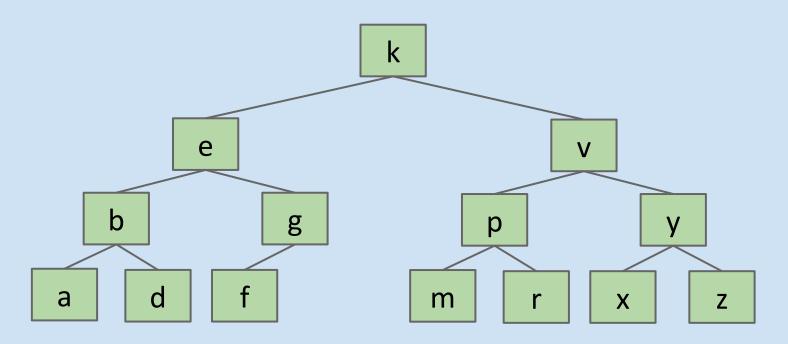
Thus: Move flat's parent's pointer to flat's child.

Flat will be garbage collected (along with its instance variables).



Hard Challenge

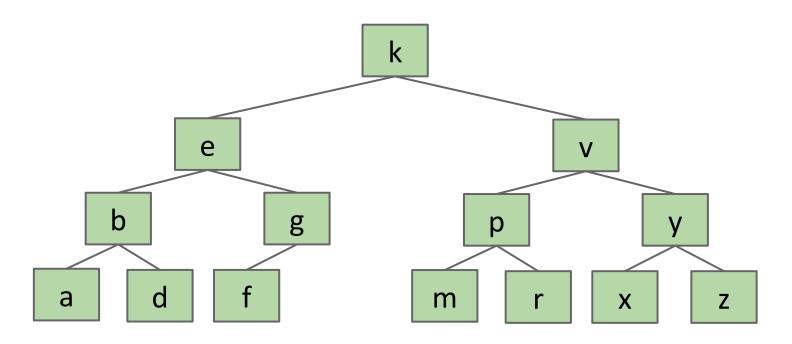
Delete k.





Hard Challenge

Delete k.





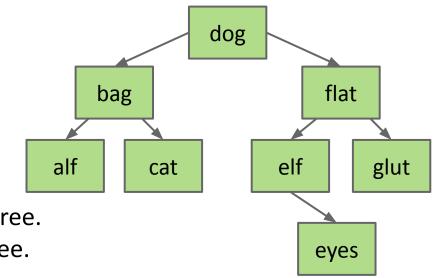
Case 3: Deleting from a BST: Deletion with two Children (Hibbard)

Example: delete("dog")

Goal:

- Find a new root node.
- Must be > than everything in left subtree.
- Must be < than everything right subtree.

Would bag work?



Case 3: Deleting from a BST: Deletion with two Children (Hibbard)

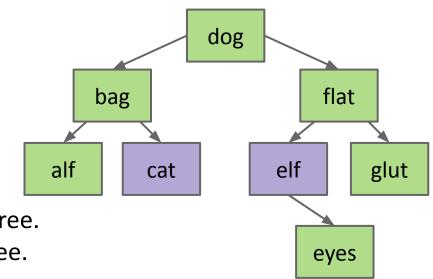
Example: delete("dog")

Goal:

- Find a new root node.
- Must be > than everything in left subtree.
- Must be < than everything right subtree.

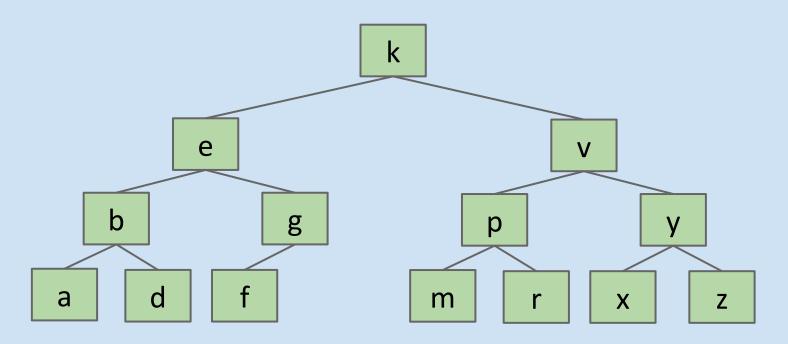
Choose either predecessor ("cat") or successor ("elf").

- Delete "cat" or "elf", and stick new copy in the root position:
 - This deletion guaranteed to be either case 1 or 2. Why?
- This strategy is sometimes known as "Hibbard deletion".



Hard Challenge (Hopefully Now Easy)

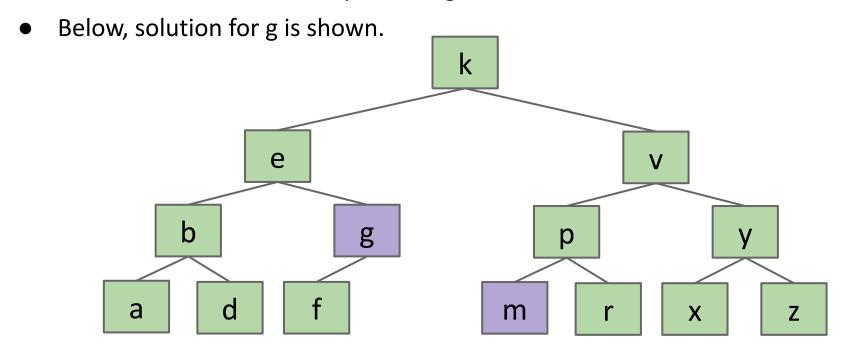
Delete k.





Hard Challenge (Hopefully Now Easy)

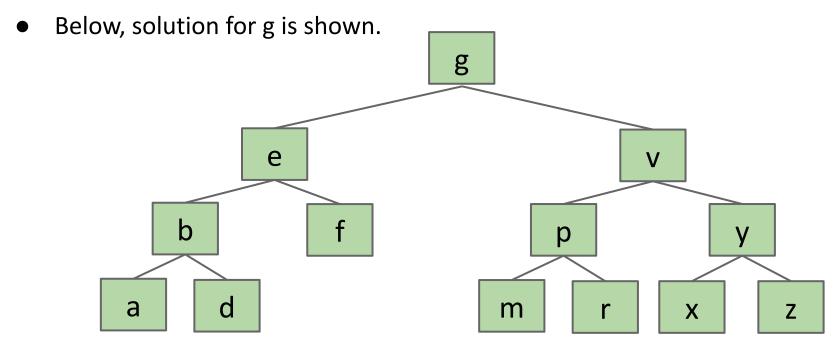
Delete k. Two solutions: Either promote g or m to be in the root.





Hard Challenge (Hopefully Now Easy)

Two solutions: Either promote g or m to be in the root.

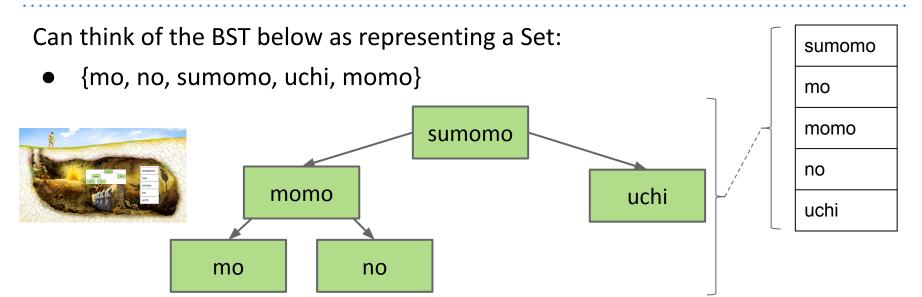




Sets vs. Maps, Summary

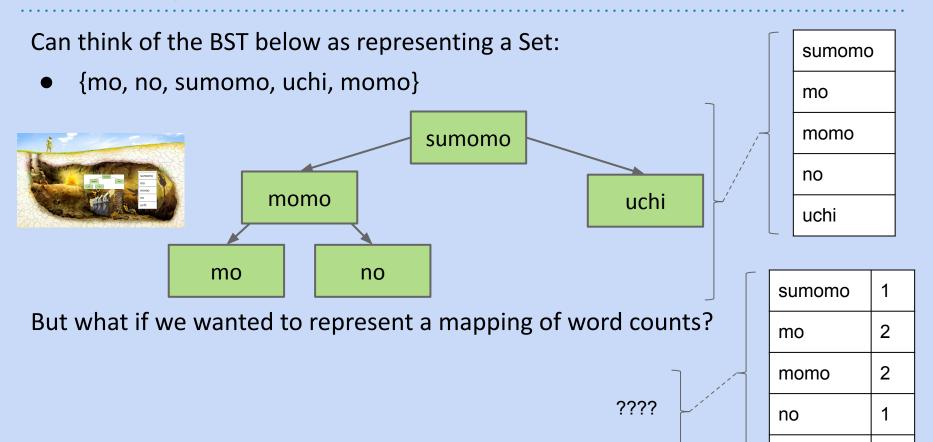


Sets vs. Maps





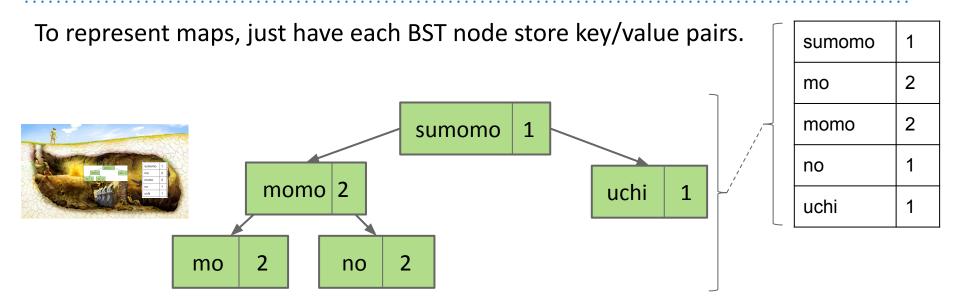
Sets vs. Maps



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Sets vs. Maps



Note: No efficient way to look up by value.

 Example: Cannot find all the keys with value = 1 without iterating over ALL nodes. This is fine.



Summary

Abstract data types (ADTs) are defined in terms of operations, not implementation.

Several useful ADTs: Disjoint Sets, Map, Set, List.

Java provides Map, Set, List interfaces, along with several implementations.

We've seen two ways to implement a Set (or Map): ArraySet and using a BST.

- ArraySet: $\Theta(N)$ operations in the worst case.
- BST: Θ(log N) operations in the worst case if tree is balanced.

BST Implementations:

- Search and insert are straightforward (but insert is a little tricky).
- Deletion is more challenging. Typical approach is "Hibbard deletion".



BST Implementation Tips



Tips for BST Lab

- Code from class was "naked recursion". Your BSTMap will not be.
- For each public method, e.g. put(K key, V value), create a private recursive method, e.g. put(K key, V value, Node n)
- When inserting, always set left/right pointers, even if nothing is actually changing.
- Avoid "arms length base cases". Don't check if left or right is null!

```
static BST insert(BST T, Key ik) {
  if (T == null)
    return new BST(ik);
  if (ik < T.label()))
    T.left = insert(T.left, ik);
  else if (ik > T.label())
    T.right = insert(T.right, ik);
  return T;
    Always set, even if
    nothing changes!
```

Avoid "arms length base cases".

```
if (T.left == null)
   T.left = new BST(ik);
else if (T.right == null)
   T.right = new BST(ik);
```

Citations

Probably photoshopped binary tree: http://cs.au.dk/~danvy/binaries.html

