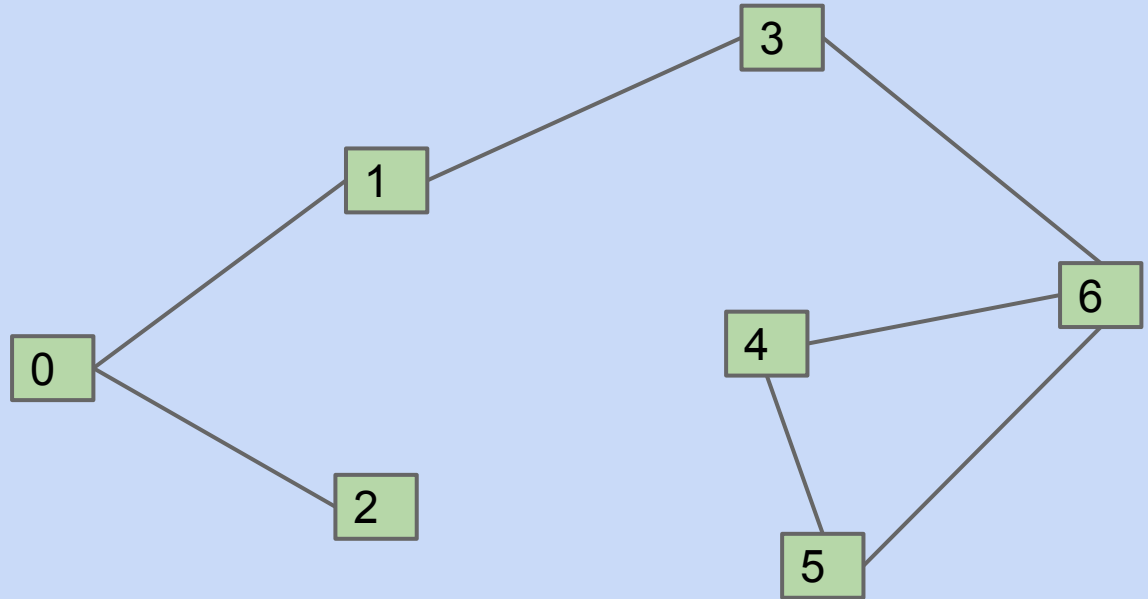


## Warm-up Problem

---

Given an undirected graph, determine if it contains any cycles.

- May use any data structure or algorithm from the course so far.

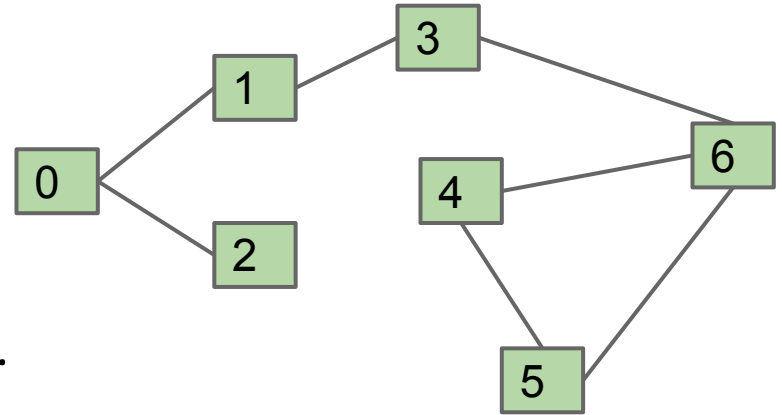


## Warm-up Problem

---

Given an undirected graph, determine if it contains any cycles.

- May use any data structure or algorithm from the course so far.



Approach 1: Do DFS from 0 (arbitrary vertex).

- Keep going until you see a marked vertex.
- Potential danger:
  - 1 looks back at 0 and sees marked.
  - Solution: Just don't count the node you came from.

Worst case runtime:  $O(V + E)$  -- do study guide problems to reinforce this.

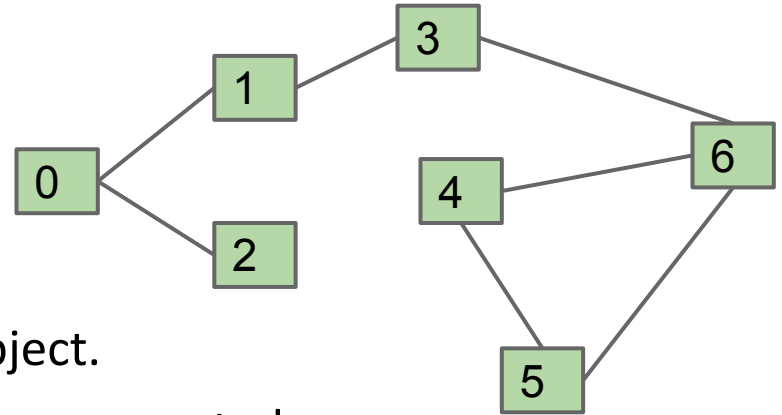
- With some cleverness, can give a tighter bound of  $O(V)$ .

## Warm-up Problem

---

Given an undirected graph, determine if it contains any cycles.

- May use any data structure or algorithm from the course so far.



Approach 2: Use a WeightedQuickUnionUF object.

- For each edge, check if the two vertices are connected.
  - If not, union them.
  - If so, there is a cycle.

Worst case runtime:  $O(V + E \alpha(V))$  if we have path compression.

- Here  $\alpha(V)$  is the [inverse Ackermann function](#) from [Disjoint Sets](#).

# CS61B, 2019

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## Lecture 26: Minimum Spanning Trees

- MST, Cut Property, Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm



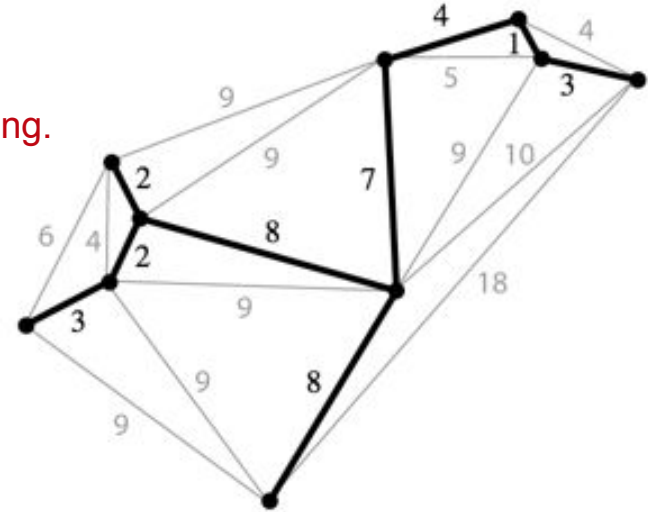
# Spanning Trees

Given an **undirected** graph, a **spanning tree**  $T$  is a subgraph of  $G$ , where  $T$ :

- Is connected.
  - Is acyclic.
  - Includes all of the vertices.
- These two properties make it a tree.
- This makes it spanning.

Example:

- Spanning tree is the black edges and vertices.

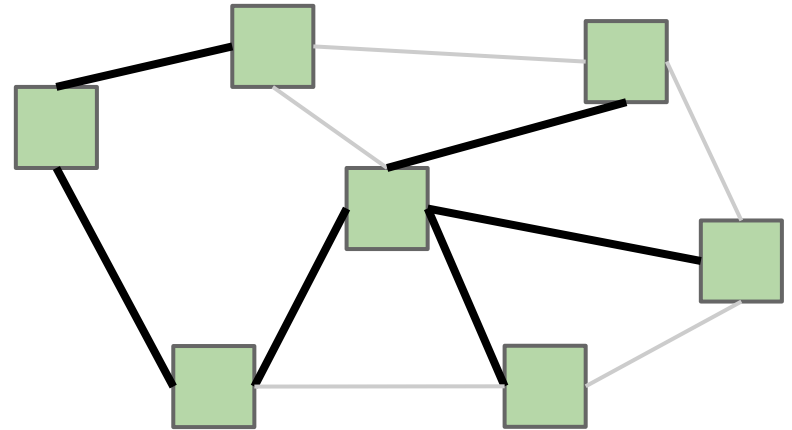
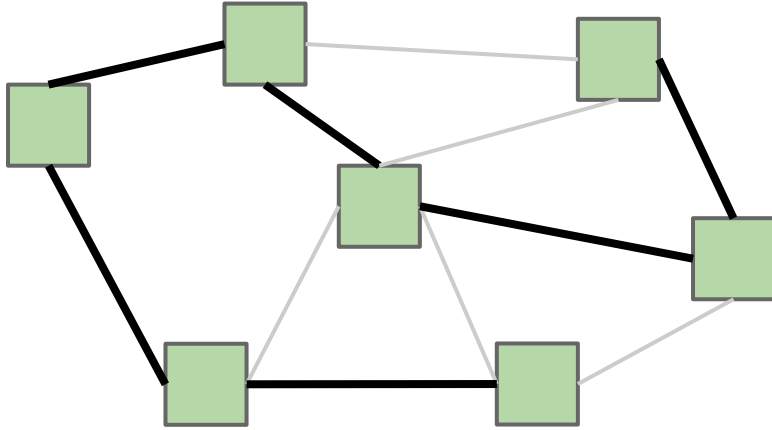


A **minimum spanning tree** is a spanning tree of minimum total weight.

- Example: Directly connecting buildings by power lines.

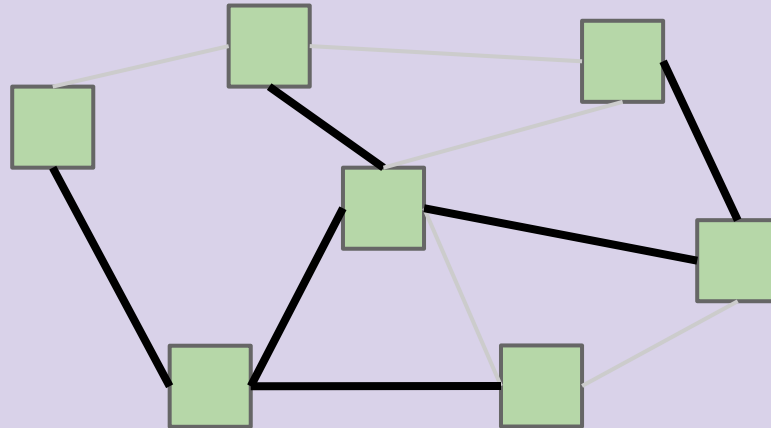
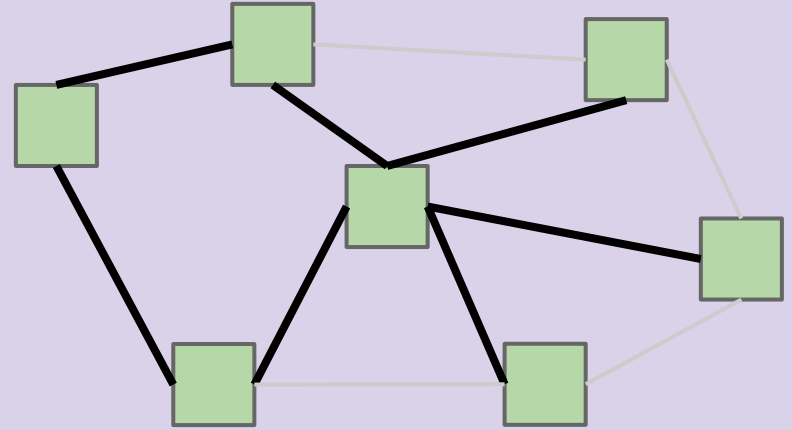
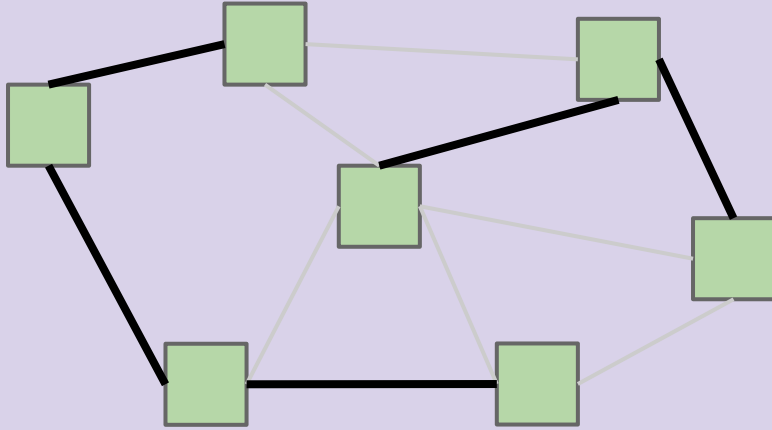
# Spanning Trees

---



# How Many are Spanning Trees?

<http://yellkey.com/now>



# MST Applications

Old school handwriting recognition (left ([link](#)))

Medical imaging (e.g. arrangement of nuclei in cancer cells (right))

For more, see: <http://www.ics.uci.edu/~eppstein/gina/mst.html>

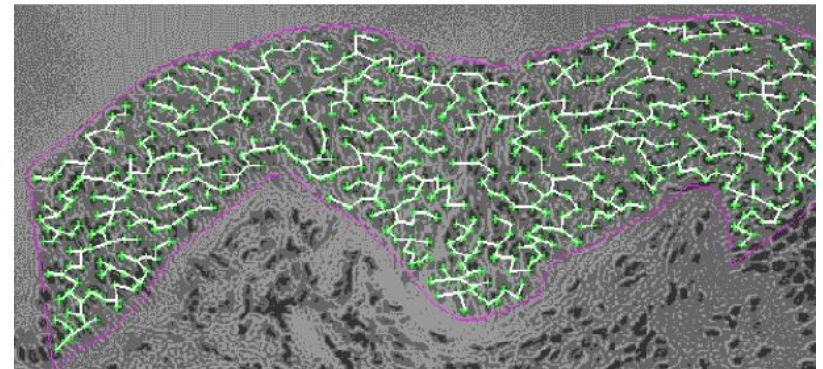
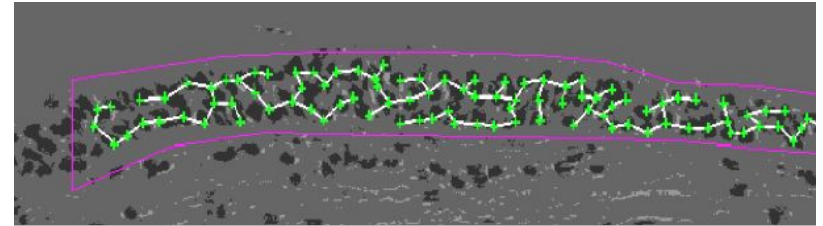
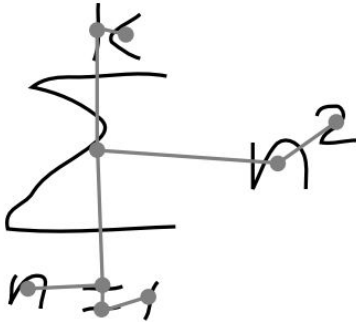
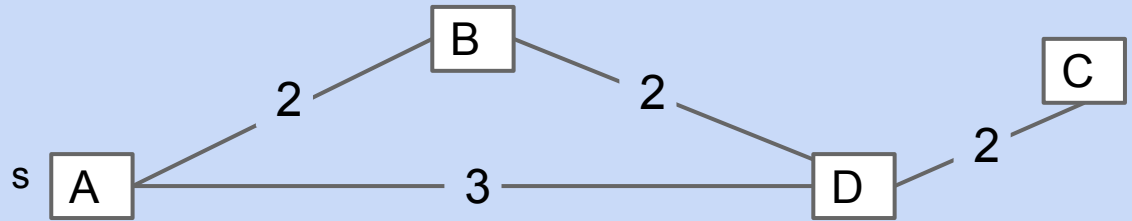


Figure 4-3: A typical minimum spanning tree



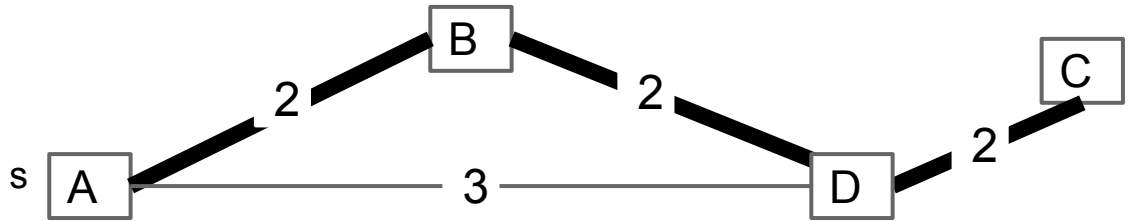
# MST

Find the MST for the graph.



# MST

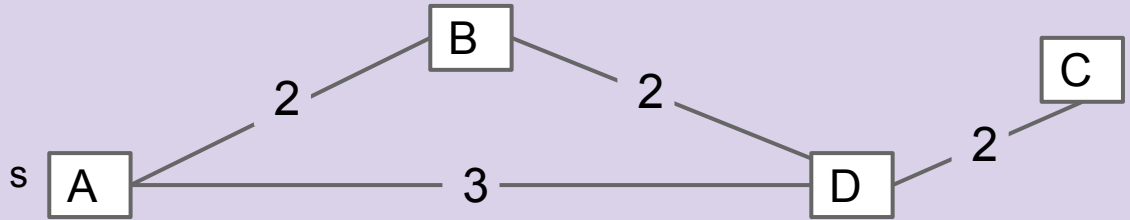
Find the MST for the graph.



## MST vs. SPT, <http://yellkey.com/sit>

Is the MST for this graph also a shortest paths tree? If so, using which node as the starting node for this SPT?

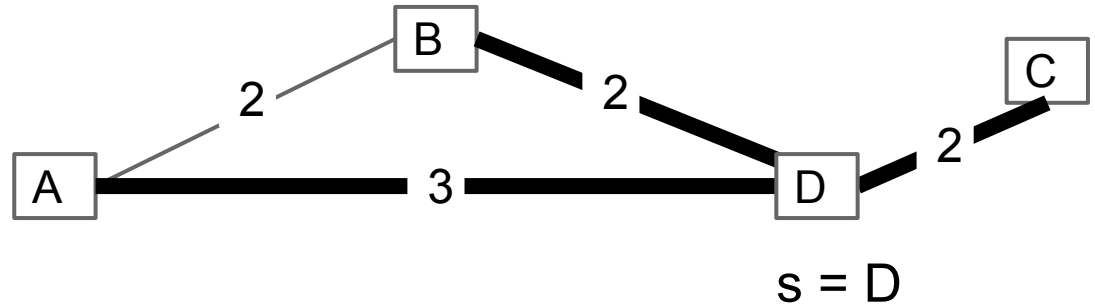
- A. A
- B. B
- C. C
- D. D
- E. No SPT is an MST.



## MST vs. SPT

Is the MST for this graph also a shortest paths tree? If so, using which node as the starting node for this SPT?

- A. A
- B. B
- C. C
- D. D
- E. No SPT is an MST.

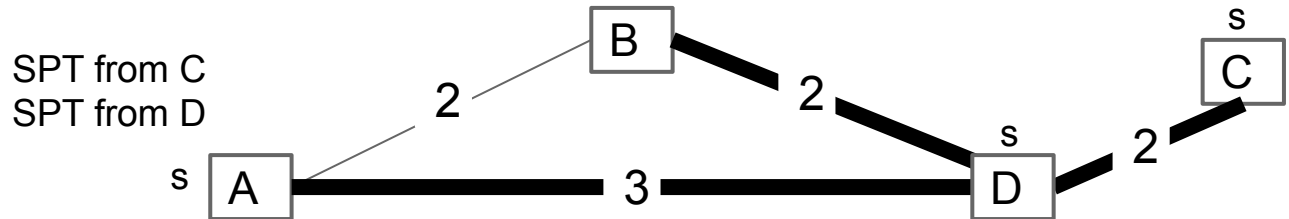
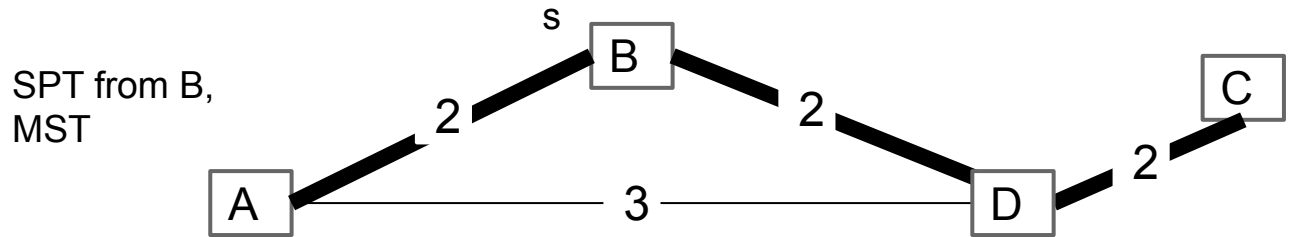
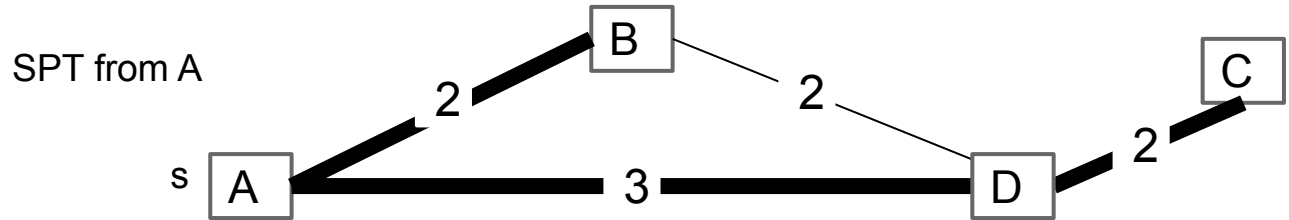


Doesn't work for  $s = D$ !

## MST vs. SPT, <http://yellkey.com/approach>

Is the MST for this graph also a shortest paths tree? If so, using which node as the starting node for this SPT?

- A. A
- B. B**
- C. C
- D. D
- E. No SPT is an MST.



## MST vs. SPT, <http://yellkey.com/approach>

---

A shortest paths tree depends on the start vertex:

- Because it tells you how to get from a source to EVERYTHING.

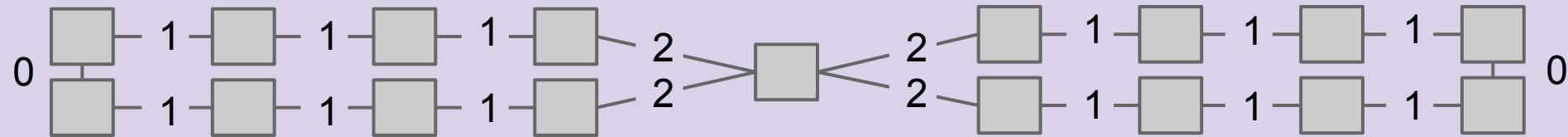
There is no source for a MST.

Nonetheless, the MST sometimes happens to be an SPT for a specific vertex.

# Spanning Tree, <http://yellkey.com/both>

Give a valid MST for the graph below.

- Hard B level question: Is there a node whose SPT is also the MST?

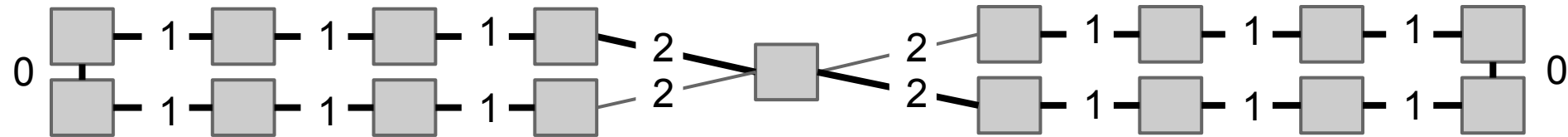


- A. Yes  
B. No

# Spanning Tree

Give a valid MST for the graph below.

- Is there a node whose SPT is also the MST? [see next slide]

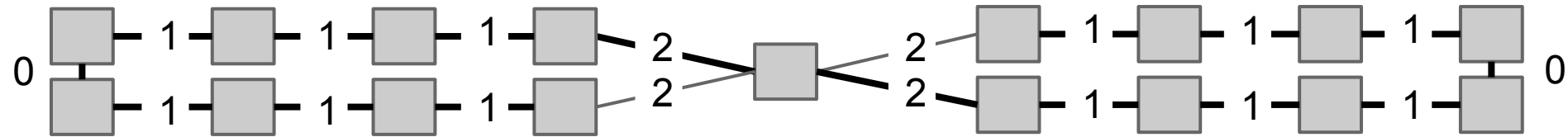




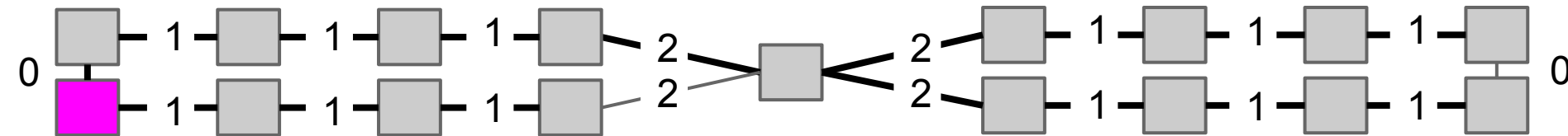
# Spanning Tree

Give a valid MST for the graph below.

- Is there a node whose SPT is also the MST?
- **No!** Minimum spanning tree must include only 2 of the 2 weight edges, but the SPT always includes at least 3 of the 2 weight edges.

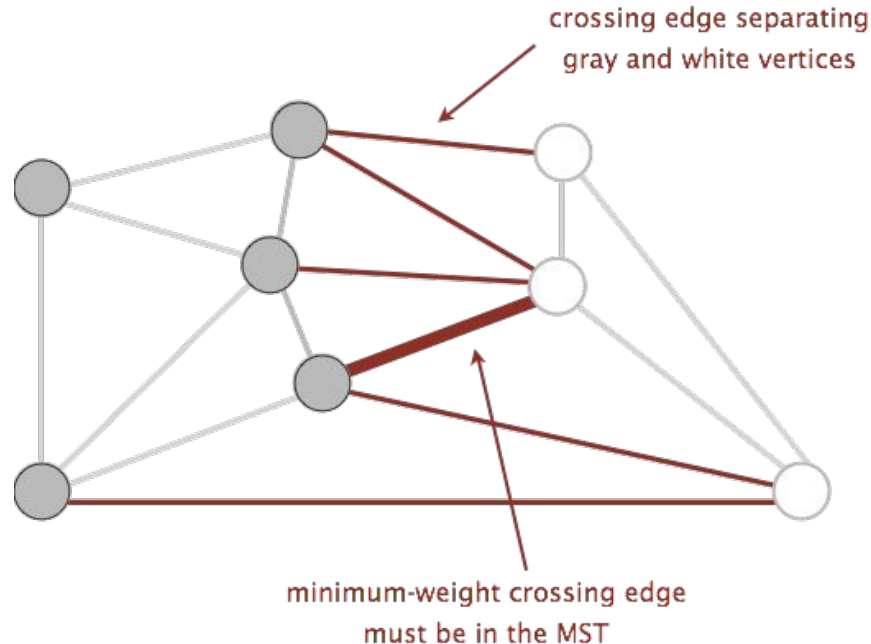


Example SPT from bottom left vertex:



# A Useful Tool for Finding the MST: Cut Property

- A **cut** is an assignment of a graph's nodes to two non-empty sets.
- A **crossing edge** is an edge which connects a node from one set to a node from the other set.



**Cut property:** Given any cut, minimum weight crossing edge is in the MST.

- For rest of today, we'll assume edge weights are unique.

# Prim's Runtime

---

Exactly like Dijkstra's runtime:

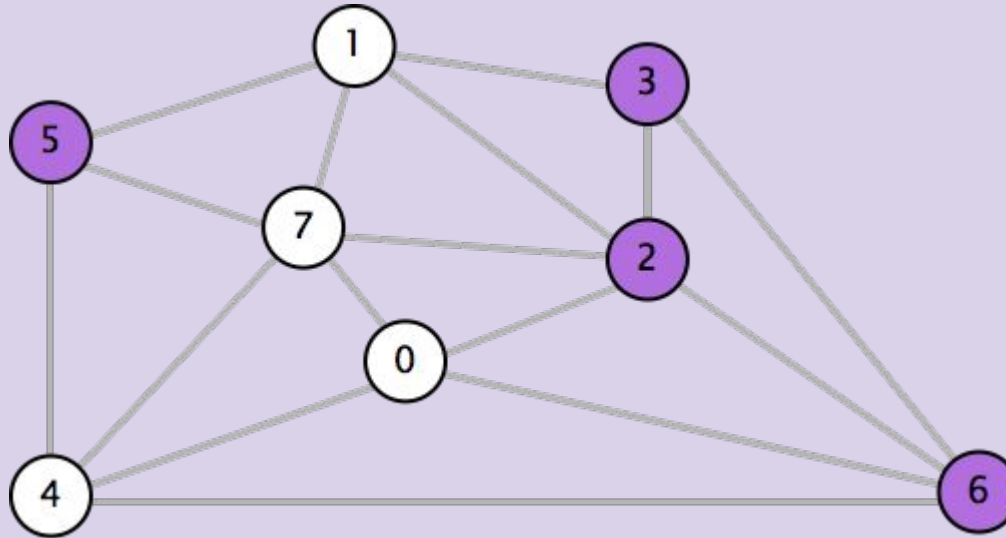
- Insertions:  $V$ , each costing  $O(\log V)$  time.
- Delete-min:  $V$ , each costing  $O(\log V)$  time.
- DecreasePriority:  $E$ , each costing  $O(\log V)$  time.
  - Data structure not discussed in class.

Overall runtime, assuming  $E > V$ , we have  $O(E \log V)$  runtime.

Operation	Number of Times	Time per Operation	Total Time
Insert	$V$	$O(\log V)$	$O(V \log V)$
Delete minimum	$V$	$O(\log V)$	$O(V \log V)$
Decrease priority	$E$	$O(\log V)$	$O(E \log V)$

## Cut Property in Action: <http://yellkey.com/drive>

Which edge is the minimum weight edge crossing the cut  $\{2, 3, 5, 6\}$ ?

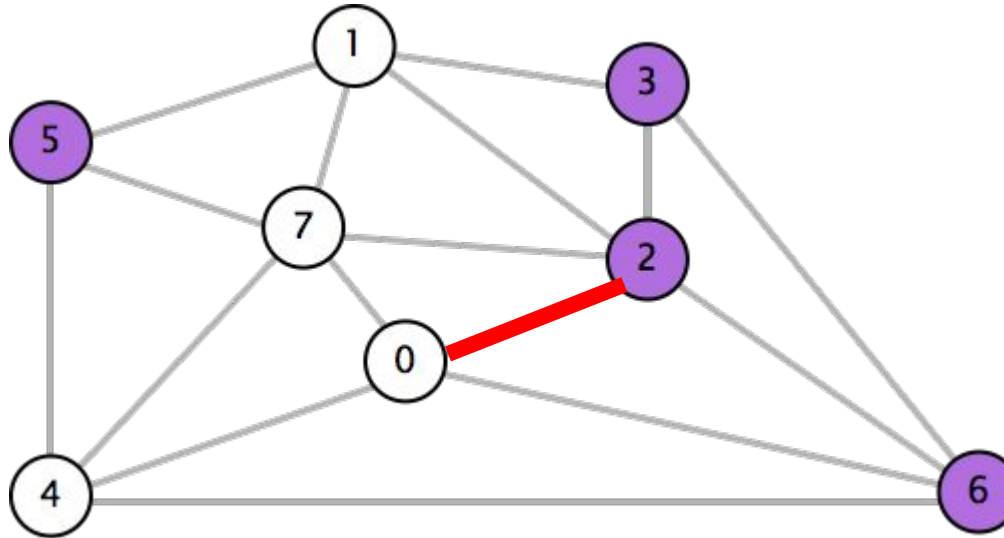


0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
5-7	0.28
1-3	0.29
1-5	0.32
2-7	0.34
4-5	0.35
1-2	0.36
4-7	0.37
0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

# Cut Property in Action

Which edge is the minimum weight edge crossing the cut  $\{2, 3, 5, 6\}$ ?

- 0-2. Must be part of the MST!

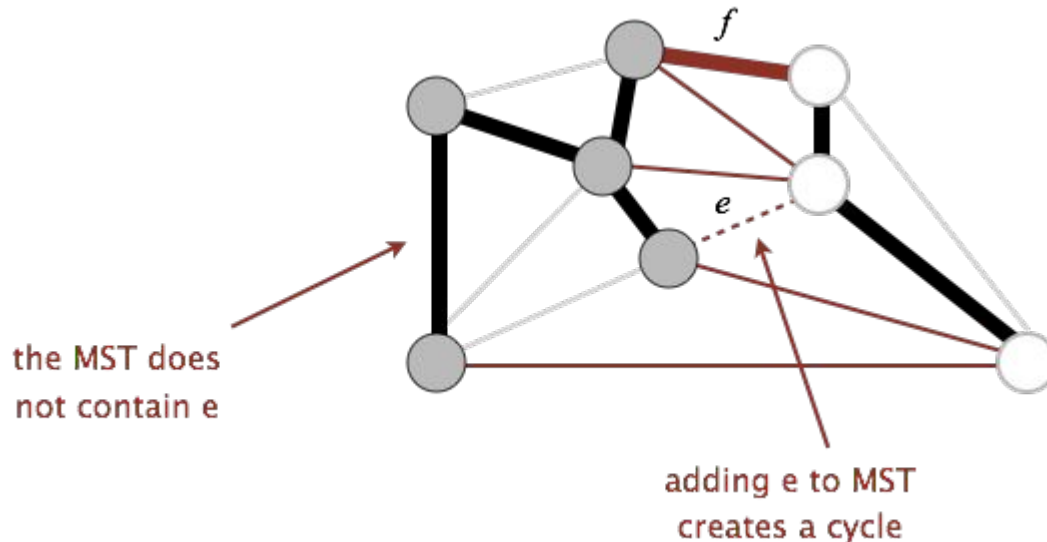


0-7	0.16
2-3	0.17
1-7	0.19
<b>0-2</b>	<b>0.26</b>
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1-2	0.36
4-7	0.37
0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

# Cut Property Proof

Suppose that the minimum crossing edge  $e$  were not in the MST.

- Adding  $e$  to the MST creates a cycle.
- Some other edge  $f$  must also be a crossing edge.
- Removing  $f$  and adding  $e$  is a lower weight spanning tree.
- Contradiction!



# Generic MST Finding Algorithm

---

Start with no edges in the MST.

- Find a cut that has no crossing edges in the MST.
- Add smallest crossing edge to the MST.
- Repeat until  $V-1$  edges.

This should work, but we need some way of finding a cut with no crossing edges!

- Random isn't a very good idea.

# Prim's Algorithm



# Prim's Algorithm

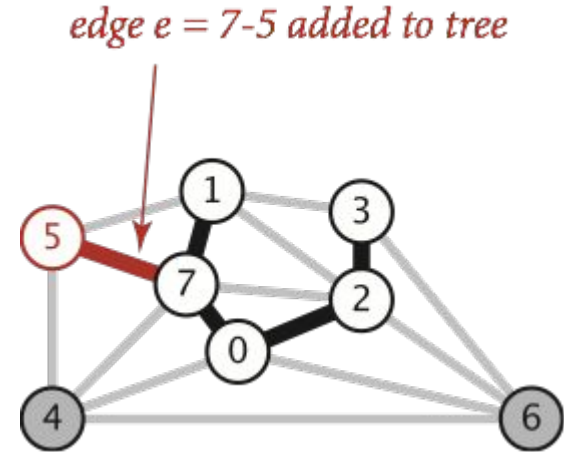
Start from some arbitrary start node.

- Repeatedly add shortest edge (mark black) that has one node inside the MST under construction.
- Repeat until  $V-1$  edges.

Conceptual Prim's Algorithm Demo ([Link](#))

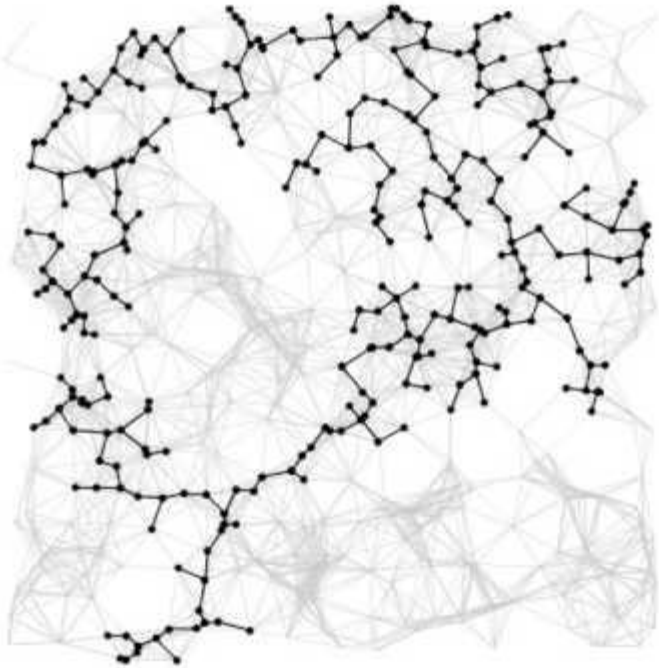
Why does Prim's work? Special case of generic algorithm.

- Suppose we add edge  $e = v \rightarrow w$ .
- Side 1 of cut is all vertices connected to start, side 2 is all the others.
- No crossing edge is black (all connected edges on side 1).
- No crossing edge has lower weight (consider in increasing order).

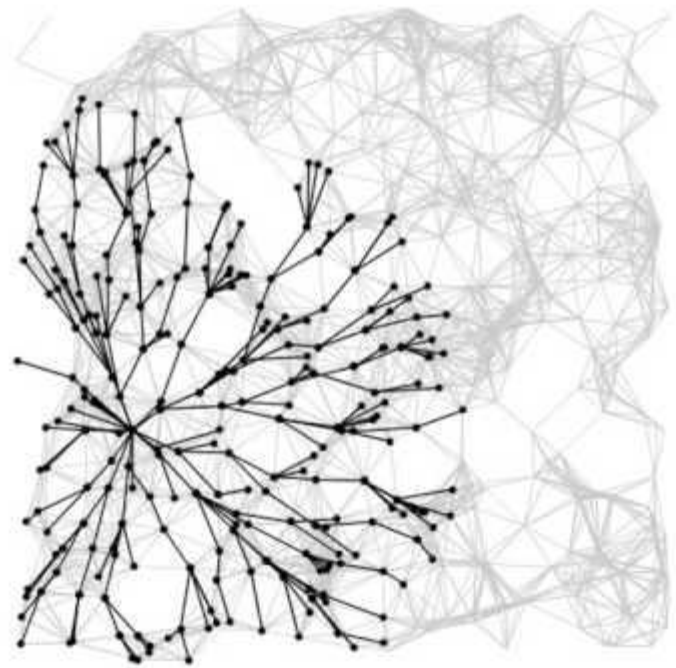


# Prim's vs. Dijkstra's (visual)

---



Prim's Algorithm



Dijkstra's Algorithm

Demos courtesy of Kevin Wayne, Princeton University

# Prim's Algorithm Implementation

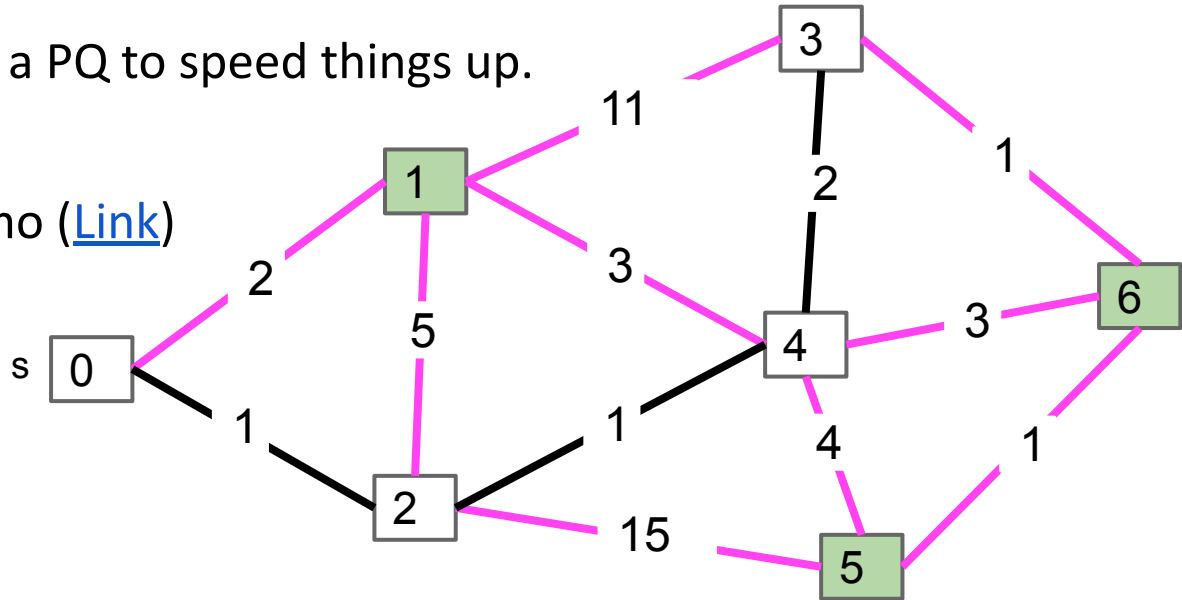
The natural implementation of the conceptual version of Prim's algorithm is highly inefficient.

- Example: Iterating over purple edges shown is unnecessary and slow.

Can use some cleverness and a PQ to speed things up.

Realistic Implementation Demo ([Link](#))

- Very similar to Dijkstra's!



# Prim's vs. Dijkstra's

---

Prim's and Dijkstra's algorithms are exactly the same, except Dijkstra's considers "distance from the source", and Prim's considers "distance from the tree."

Visit order:

- Dijkstra's algorithm visits vertices in order of distance from the source.
- Prim's algorithm visits vertices in order of distance from the MST under construction.

Relaxation:

- Relaxation in Dijkstra's considers an edge better based on distance to source.
- Relaxation in Prim's considers an edge better based on distance to tree.

# Prim's Implementation (Pseudocode, 1/2)

```
public class PrimMST {  
    public PrimMST(EdgeWeightedGraph G) {  
        edgeTo = new Edge[G.V()];  
        distTo = new double[G.V()];  
        marked = new boolean[G.V()];  
        fringe = new SpecialPQ<Double>(G.V());  
  
        distTo[s] = 0.0;  
        setDistancesToInfinityExceptS(s);  
        insertAllVertices(fringe);  
  
        /* Get vertices in order of distance from tree. */  
        while (!fringe.isEmpty()) {  
            int v = fringe.delMin();  
            scan(G, v);  
        }  
    }  
    ...  
}
```

Fringe is ordered by distTo tree. Must be a specialPQ like Dijkstra's.

Get vertex closest to tree that is unvisited.

Scan means to consider all of a vertices outgoing edges.

# Prim's Implementation (Pseudocode, 2/2)

```
while (!fringe.isEmpty()) {  
    int v = fringe.delMin();  
    scan(G, v);  
}
```

Important invariant, fringe must be ordered by current best known distance from tree.

```
private void scan(EdgeWeightedGraph G, int v) {  
    marked[v] = true;  
    for (Edge e : G.adj(v)) {  
        int w = e.other(v);  
        if (marked[w]) { continue; }  
        if (e.weight() < distTo[w]) {  
            distTo[w] = e.weight();  
            edgeTo[w] = e;  
            pq.decreasePriority(w, distTo[w]);  
        }  
    }  
}
```

Vertex is closest, so add to MST.

Already in MST, so go to next edge.

Better path to a particular vertex found, so update current best known for that vertex.

# Prim's Runtime

```
while (!fringe.isEmpty()) {  
    int v = fringe.delMin();  
    scan(G, v);  
}
```

```
private void scan(EdgeWeightedGraph G, int v) {  
    marked[v] = true;  
    for (Edge e : G.adj(v)) {  
        int w = e.other(v);  
        if (marked[w]) { continue; }  
        if (e.weight() < distTo[w]) {  
            distTo[w] = e.weight();  
            edgeTo[w] = e;  
            pq.decreasePriority(w, distTo[w]);  
        }  
    }  
}
```

What is the runtime of Prim's algorithm?

- Assume all PQ operations take  $O(\log(V))$  time.
- Give your answer in Big O notation.

# Prim's Algorithm Runtime

---

Priority Queue operation count, assuming binary heap based PQ:

- Insertion:  $V$ , each costing  $O(\log V)$  time.
- Delete-min:  $V$ , each costing  $O(\log V)$  time.
- Decrease priority:  $O(E)$ , each costing  $O(\log V)$  time.
  - Operation not discussed in lecture, but it was in lab 10.

Overall runtime:  $O(V \cdot \log(V) + V \cdot \log(V) + E \cdot \log V)$ .

- Assuming  $E > V$ , this is just  $O(E \log V)$ .

	# Operations	Cost per operation	Total cost
PQ add	$V$	$O(\log V)$	$O(V \log V)$
PQ delMin	$V$	$O(\log V)$	$O(V \log V)$
PQ decreasePriority	$O(E)$	$O(\log V)$	$O(E \log V)$



# Kruskal's Algorithm

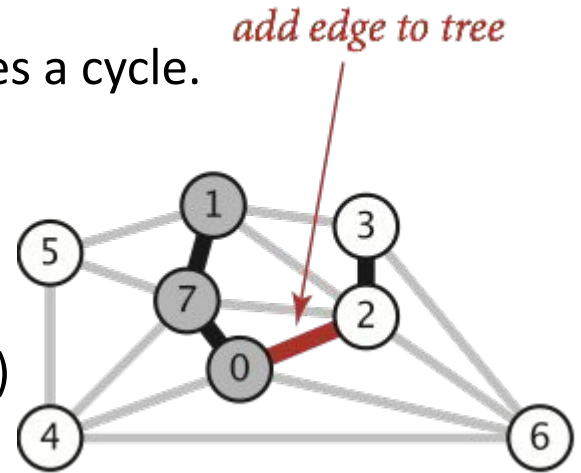
# Kruskal's Algorithm

Initially mark all edges gray.

- Consider edges in increasing order of weight.
- Add edge to MST (mark black) unless doing so creates a cycle.
- Repeat until  $V-1$  edges.

Conceptual Kruskal's Algorithm Demo ([Link](#))

Realistic Kruskal's Algorithm Implementation Demo ([Link](#))

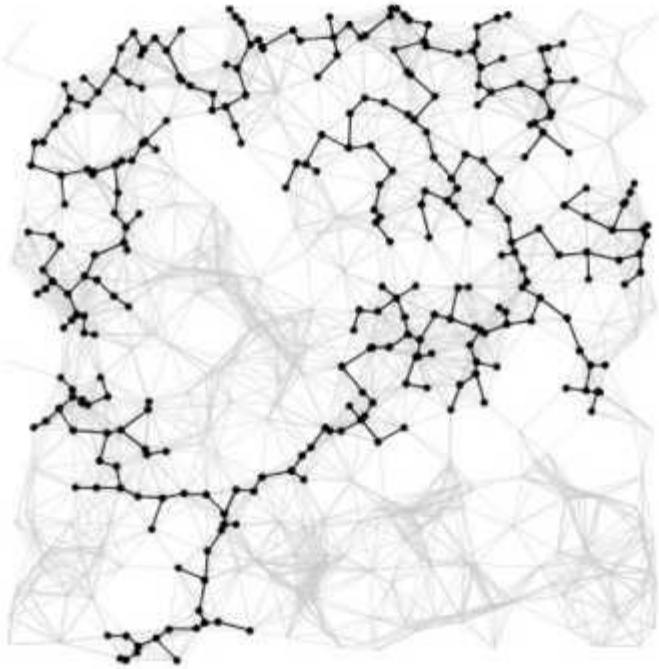


Why does Kruskal's work? Special case of generic MST algorithm.

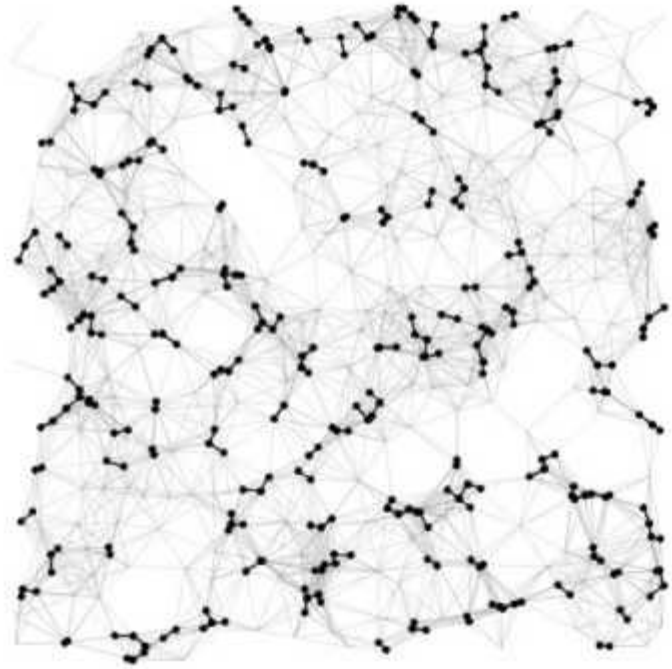
- Suppose we add edge  $e = v \rightarrow w$ .
- Side 1 of cut is all vertices connected to  $v$ , side 2 is everything else.
- No crossing edge is black (since we don't allow cycles).
- No crossing edge has lower weight (consider in increasing order).

# Prim's vs. Kruskal's

---



Prim's Algorithm



Kruskal's Algorithm

Demos courtesy of Kevin Wayne, Princeton University

# Kruskal's Implementation (Pseudocode)

```
public class KruskalMST {
    private List<Edge> mst = new ArrayList<Edge>();

    public KruskalMST(EdgeWeightedGraph G) {
        MinPQ<Edge> pq = new MinPQ<Edge>();
        for (Edge e : G.edges()) {
            pq.insert(e);
        }
        WeightedQuickUnionPC uf =
            new WeightedQuickUnionPC(G.V());
        while (!pq.isEmpty() && mst.size() < G.V() - 1) {
            Edge e = pq.delMin();
            int v = e.from();
            int w = e.to();
            if (!uf.connected(v, w)) {
                uf.union(v, w);
                mst.add(e);
            }
        }
    }
}
```

What is the runtime of Kruskal's algorithm?

- Assume all PQ operations take  $O(\log(V))$  time.
- Assume all WQU operations take  $O(\log^* V)$  time.
- Give your answer in Big O notation.

# Kruskal's Runtime

Kruskal's algorithm on previous slide is  $O(E \log E)$ .

Fun fact: In HeapSort lecture, we discuss how do this step in  $O(E)$  time using "bottom-up heapification".

Operation	Number of Times	Time per Operation	Total Time
Insert	$E$	$O(\log E)$	$O(E \log E)$
Delete minimum	$O(E)$	$O(\log E)$	$O(E \log E)$
union	$O(V)$	$O(\log^* V)$	$O(V \log^* V)$
isConnected	$O(E)$	$O(\log^* V)$	$O(E \log^* V)$

Note: If we use a pre-sorted list of edges (instead of a PQ), then we can simply iterate through the list in  $O(E)$  time, so overall runtime is  $O(E + V \log^* V + E \log^* V) = O(E \log^* V)$ .

# Shortest Paths and MST Algorithms Summary

---

Problem	Algorithm	Runtime (if $E > V$ )	Notes
Shortest Paths	Dijkstra's	$O(E \log V)$	Fails for negative weight edges.
MST	Prim's	$O(E \log V)$	Analogous to Dijkstra's.
MST	Kruskal's	$O(E \log E)$	Uses WQUPC.
MST	Kruskal's with pre-sorted edges	$O(E \log^* V)$	Uses WQUPC.

Question: Can we do better than  $O(E \log^* V)$ ?

# 170 Spoiler: State of the Art Compare-Based MST Algorithms

year	worst case	discovered by
1975	$E \log \log V$	Yao
1984	$E \log^* V$	Fredman-Tarjan
1986	$E \log (\log^* V)$	Gabow-Galil-Spencer-Tarjan
1997	$E \alpha(V) \log \alpha(V)$	Chazelle
2000	$E \alpha(V)$	Chazelle
2002	optimal ( <a href="#">link</a> )	Pettie-Ramachandran
???	$E ???$	???

(Slide Courtesy of Kevin Wayne, Princeton University)

# Citations

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Tree fire:

[http://www.miamidade.gov/fire/library/hotlines/2011-december\\_files/tree-fire.jpg](http://www.miamidade.gov/fire/library/hotlines/2011-december_files/tree-fire.jpg)

Bicycle routes in Seattle: <https://www.flickr.com/photos/ewedistrict/21980840>

Cancer MST: [http://www.bccrc.ca/ci/ta01\\_archlevel.html](http://www.bccrc.ca/ci/ta01_archlevel.html)