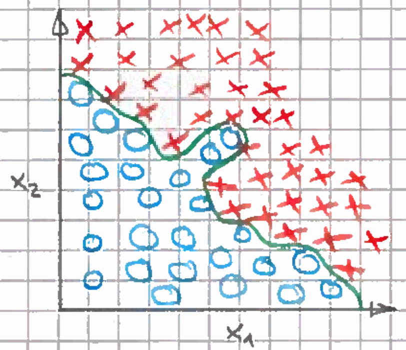
Chapter 8

Neural Networks -

Non linear hypothesis



$$g(\Theta_0 + \Theta_1 x_1 + \Theta_2 x_2 + \Theta_3 x_1 x_2 + \Theta_4 x_1^2 x_2 + \Theta_5 x_1^3 x_2 + \Theta_6 x_1 x_2^2 + \dots)$$

by using only second order therms

$x_1^2, x_1 x_2 \dots \quad x_{100}$

x_1 = size
x_2 = # bedrooms
x_3 = # floors
x_4 = age
⋮
x_{100}

$n = 100$

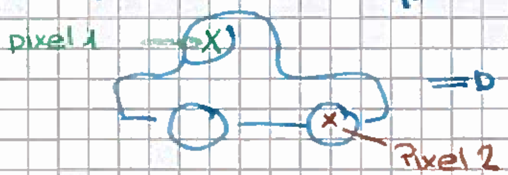
Including all the quadratic features would mean to have ≈ 5000 features

⇒ grows $O(n^2)$ ⇒ $\frac{n^2}{2}$ ⇒ could lead to overfitting

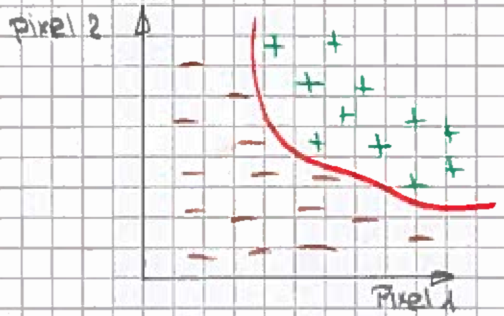
just using the $x_1^2, x_2^2, x_3^2 \dots x_{100}^2$ does not allow to create a function as more complex functions, would not fit the complex dataset

while using cubic features it would be about 170'000 features for $n = 100$ features $O(n^3)$

Why is non linear hypothesis relevant?



⇒ Learning Algorithm



\+ Cars
\- Non Cars

⇒ 50 x 50 pixels images ⇒ 2500 pixels

$n = 2500$ (7500 RGB)

$$x = \begin{bmatrix} \text{pixel 1 intensity} \\ \text{" 2 "} \\ \text{" 3 "} \\ \vdots \\ \text{pixel } n \text{ itensity} \end{bmatrix}$$

← Value 0 - 255

2500

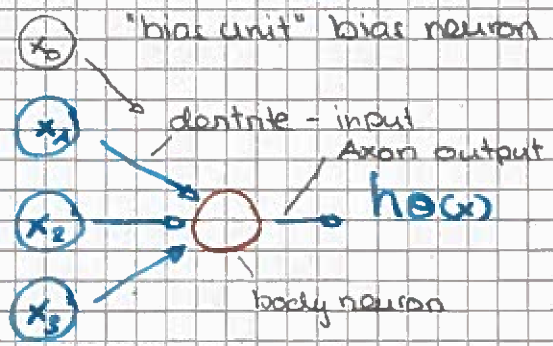
by using all quadratic features ($x_i \times x_j$)

≈ 3 million features per training example

is computational expensive

Not good for algorith. with lot of features

Neuron model: Logistic unit



$\Rightarrow x_0 = 1$

$$\Rightarrow h_\theta(x) = \frac{1}{1+e^{-\theta^T x}}$$

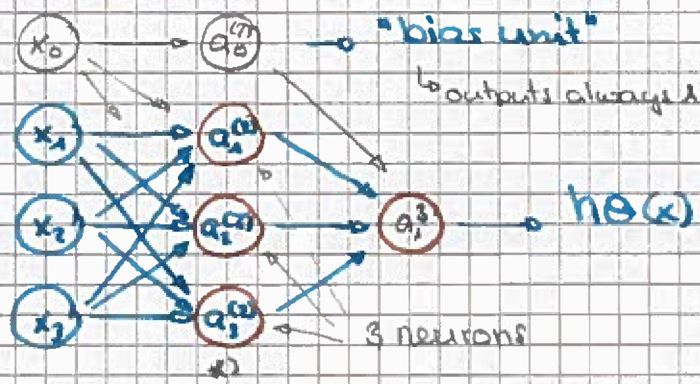
$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \qquad \theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \theta_3 \end{bmatrix}$$

sometimes called "weights" - parameter of model

Sigmoid (logistic) activation function.

$$g(z) = \frac{1}{1+e^{-z}}$$

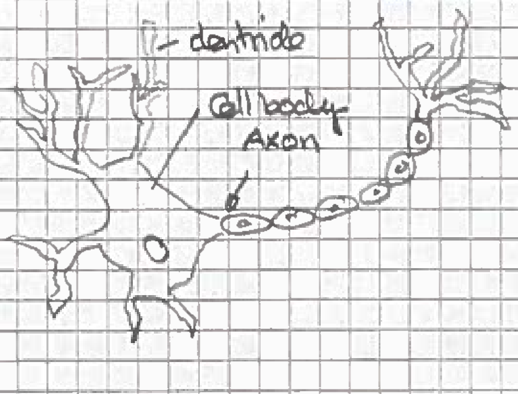
Neural Network



layer 1 ⇓ x — input lay.

Layer 2 ⇓ — hidden lay.

Layer 3 ⇓ y — output lay.

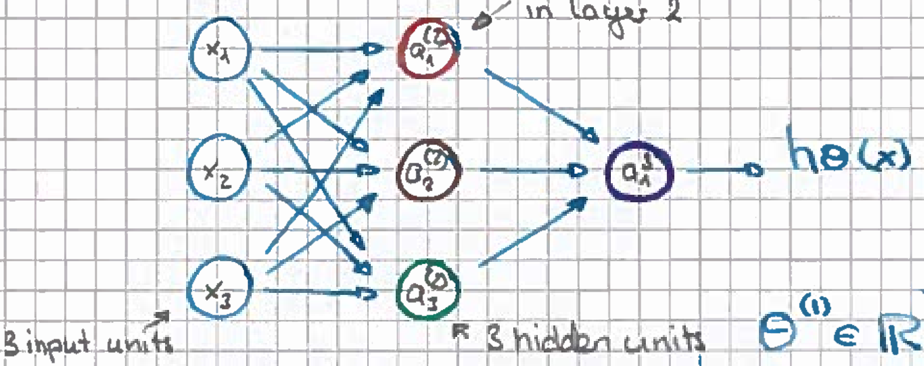


Neuron

*) you don't observe the values processed in the hidden layer

$a_i^{(j)}$ = activation of unit i in layer j

$\Theta^{(j)}$ = matrix of weights controlling function mapping from layer j to layer j+1



$\Theta^{(1)} \in \mathbb{R}^{3\times4}$ 'dim Matrix

a "activation" is the value which is computed and output by the node

Sigmoid

$$a_1^{(2)} = g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3)$$

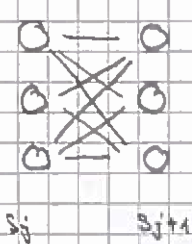
$$a_2^{(2)} = g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{13}^{(1)} x_3)$$

$$a_3^{(2)} = g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3)$$

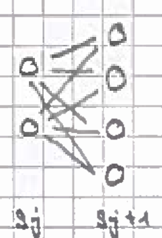
$$h_\Theta(x) = a_1^{(3)} = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})$$

If network has s_j units in layer j, s_{j+1} in unit j+1, then $\Theta^{(j)}$ will be of dimension $(s_{j+1} \times s_j+1)$

Example ⇒



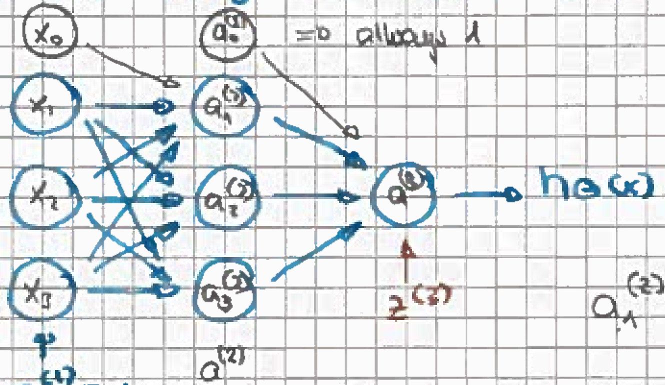
⇒ $\mathbb{R}$ 3 × 4



⇒ 4 × 3

Model Representation II

Forward propagation: vectorized implementation



$a^{(1)} = x$

$$a_1^{(2)} = g(z_1^{(2)})$$

$$a_1^{(2)} = g(\underbrace{\Theta_{10}^{(1)}x_0 + \Theta_{11}^{(1)}x_1 + \Theta_{12}^{(1)}x_2 + \Theta_{13}^{(1)}x_3}_{z_1^{(2)}})$$

$$a_2^{(2)} = g(\underbrace{\Theta_{20}^{(1)}x_0 + \Theta_{21}^{(1)}x_1 + \Theta_{22}^{(1)}x_2 + \Theta_{23}^{(1)}x_3}_{z_2^{(2)}})$$

$$a_3^{(2)} = g(\underbrace{\Theta_{30}^{(1)}x_0 + \Theta_{31}^{(1)}x_1 + \Theta_{32}^{(1)}x_2 + \Theta_{33}^{(1)}x_3}_{z_3^{(2)}})$$

$$h_\Theta(x) = g(\underbrace{\Theta_{10}^{(2)}a_0^{(2)} + \Theta_{11}^{(2)}a_1^{(2)} + \Theta_{12}^{(2)}a_2^{(2)} + \Theta_{13}^{(2)}a_3^{(2)}}_{z^{(3)}})$$

$$a_3^{(2)} = g(z_3^{(2)})$$

$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \qquad z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \\ \cancel{z_4^{(2)}} \end{bmatrix}$$

Vectorized implementation

$$z^{(2)} = \Theta^{(1)} x \Rightarrow \Theta^{(1)} \cdot a^{(1)}$$

$$\underbrace{a^{(2)}}_{\mathbb{R}^3} = g(\underbrace{z^{(2)}}_{\mathbb{R}^3})$$

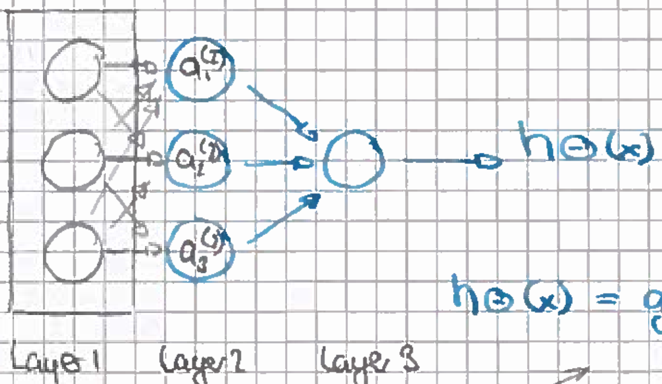
$\mathbb{R}^3$ => 3 dim. Vector

Add $a_0^{(2)} = 1$ => $a^2 \in \mathbb{R}^4$

$$z^{(3)} = \Theta^{(2)} a^{(2)}$$

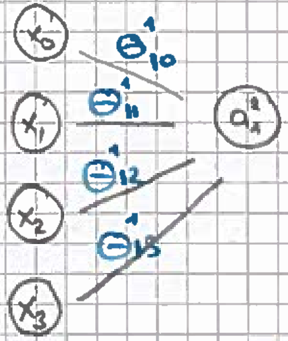
$$h_\Theta(x) = a^{(3)} = g(z^{(3)})$$

Neural Network learning its own features.



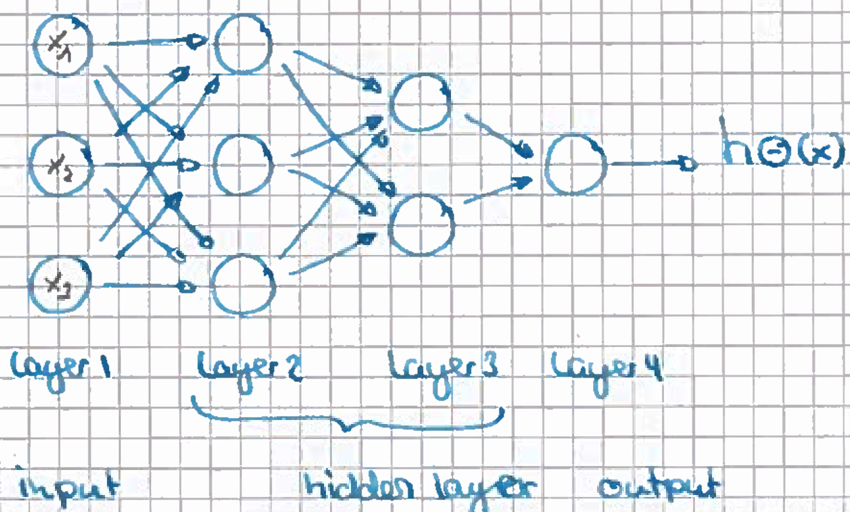
$$h_\Theta(x) = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})$$

it's just logistic regression except using the new features $a_1^{(2)}, a_2^{(2)}, a_3^{(2)}$ instead of x_1, x_2, x_3



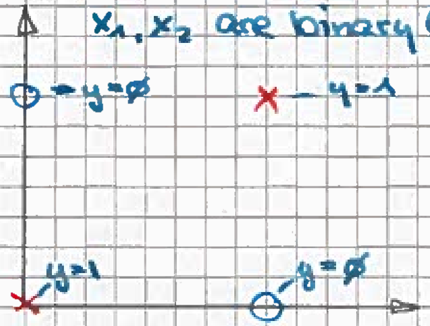
$$\hookrightarrow g(\Theta_{10}^1 x_0 + \Theta_{11}^1 x_1 + \Theta_{12}^1 x_2 + \Theta_{13}^1 x_3)$$

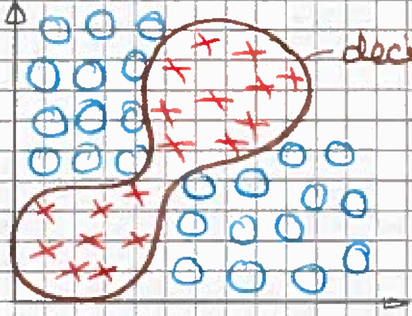
Other network architectures



Non linear classification example: XOR\XNOR

x_1, x_2 are binary (0 or 1)





$$y = x_1 \text{ XOR } x_2$$

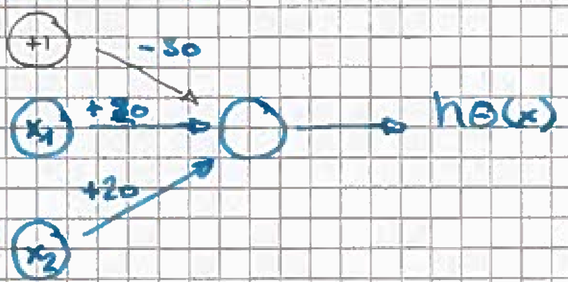
$$x_1 \text{ XNOR } x_2$$

$$\text{NOT } (x_1 \text{ XOR } x_2)$$

Simple example AND:

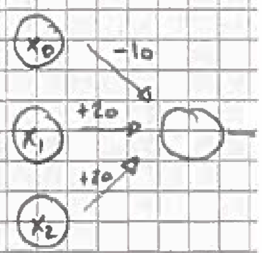
$x_1, x_2 \in \{0, 1\}$

$y = x_1 \text{ AND } x_2$



OR:

x_1	x_2	$h_\Theta(x)$
0	0	$g(-10) - 0$
0	1	$g(+10) - 1$
1	0	$g(+10) - 1$
1	1	$g(30) - 1$

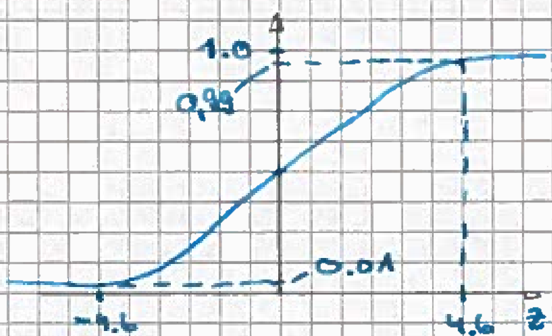


$g(-10 \cdot 1 + 20 \cdot \emptyset + 20 \cdot 0) = g(-10$

$$\Rightarrow h_\Theta(x) = g(-30 + 20x_1 + 20x_2)$$

$$\Theta_{10}^{(1)} \quad \Theta_{11}^{(1)} \quad \Theta_{12}^{(1)}$$

$(-30 + 20 \cdot 1 + 20 \cdot 0)$

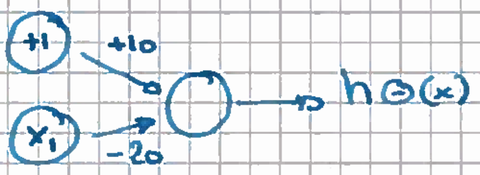


x_1	x_2	$h_\Theta(x)$
0	0	$g(-30) \approx 0$
0	1	$g(-10) \approx 0$
1	0	$g(-10) \approx 0$
1	1	$g(10) \approx 1$

x_1 AND x_2

Examples and Intuitions II

Negation: NOT x_1

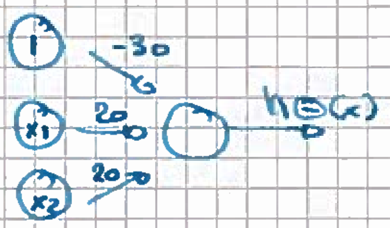


x_1	$h_\Theta(x)$
0	$g(10) \to 1$
1	$g(-10) \to 0$

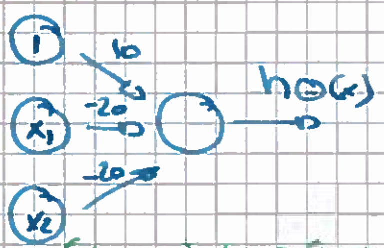
$$h_\Theta(x) = g(\Theta_{10} + \Theta_{11} x_1)$$

$$g(+10 - 20 x_1)$$

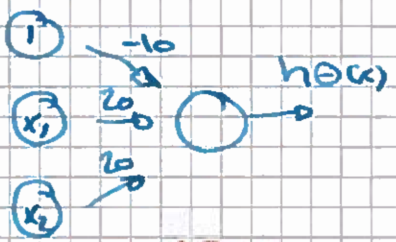
Putting it together: x_1 XNOR x_2



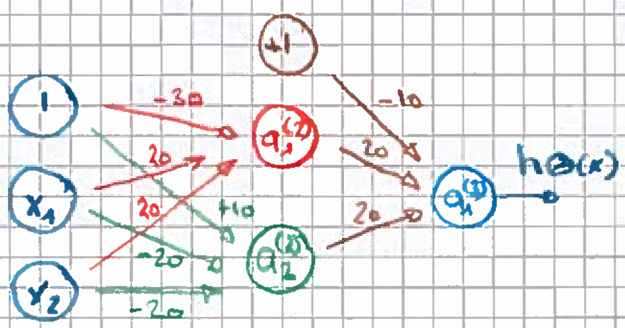
x_1 AND x_2



(NOT x_1) AND (NOT x_2)



x_1 OR x_2



$\bar{x}_1$ AND $\bar{x}_2$

AND

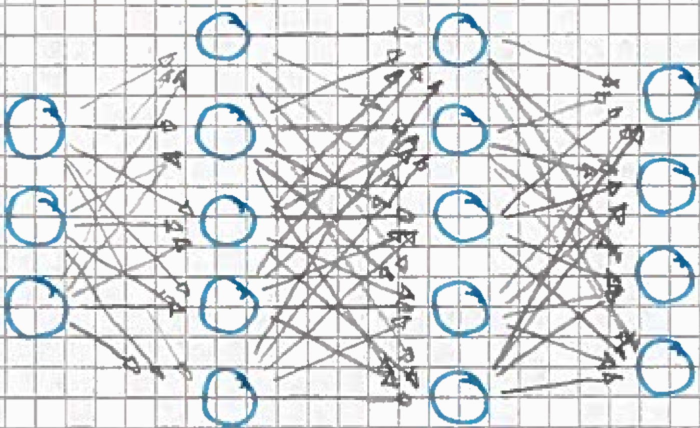
OR

x_1	x_2	$a_1^{(2)}$	$a_2^{(2)}$	$h_\Theta(x)$
0	0	0	1	1
0	1	0	0	0
1	0	0	0	0
1	1	1	0	1

Multiclass Classification

Multiple output units: One vs. all

image	image	image	image
pedestrian	car	motorcycle	truck



pedestrian

car

motorcycle

truck

output would be a vector

$h_\Theta(x) \in \mathbb{R}^4$

want $h_\Theta(x)$ $\begin{bmatrix}1\\0\\0\\0\end{bmatrix}$ $h_\Theta(x)$ $\begin{bmatrix}0\\1\\0\\0\end{bmatrix}$ $h_\Theta(x)$ $\begin{bmatrix}0\\0\\1\\0\end{bmatrix}$ $h_\Theta(x)$ $\begin{bmatrix}0\\0\\0\\1\end{bmatrix}$

pedestrian car motorcycle truck

Training set $(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots (x^{(m)}, y^{(m)})$

image

$y^{(i)}$ one of $\begin{bmatrix}1\\0\\0\\0\end{bmatrix}, \begin{bmatrix}0\\1\\0\\0\end{bmatrix}, \begin{bmatrix}0\\0\\1\\0\end{bmatrix}, \begin{bmatrix}0\\0\\0\\1\end{bmatrix} \Rightarrow (x^{(i)}, y^{(i)})$

pedestrian car motor-cycle truck

$h_\Theta(x^{(i)}) \approx y^{(i)}$

$\mathbb{R}^4$ 4 dym. vectors