

Artificial Bee Colony Algorithm – Analysis



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Introduction

The Artificial Bee Colony (ABC) algorithm is a swarm-based metaheuristic optimization algorithm inspired by the foraging behavior of honey bees. It was proposed by Derviş Karaboğa in 2005 and has been widely applied to solve continuous and combinatorial optimization problems.

Biological Inspiration

In a bee colony, the search for food involves three types of bees: employed bees, onlooker bees, and scout bees. Each type plays a vital role in exploring and exploiting food sources. This behavior translates well into solving optimization problems where each food source represents a possible solution.

Core Concepts and Mechanisms

Employed Bees

Each employed bee is associated with a food source (solution) and searches its neighborhood to find better solutions.

Onlooker Bees

These bees evaluate the information shared by employed bees and choose food sources with a probability based on nectar quality.

Scout Bees

When a food source is abandoned, scout bees randomly explore the search space to find new food sources.

Food Source

Represents a potential solution to the optimization problem.

Nectar Amount

Represents the quality (fitness) of a solution.

Algorithm Phases

1. Initialization Phase

Randomly generate the initial population of food sources.

2. Employed Bee Phase

Generate a new solution in the neighborhood of the food source and apply greedy selection.

3. Onlooker Bee Phase

Select good solutions based on probability and explore their neighborhood.

4. Scout Bee Phase

Abandon poor solutions and generate new random ones.

Convergence Properties

- **Asymptotic Convergence:**
Given infinite iterations, the algorithm converges to the global optimum with a high probability.
 - **Exploration vs. Exploitation:**
Employed and onlooker bees focus on exploitation, while scout bees enhance exploration.
 - **Parameter Influence:** Larger colony sizes improve diversity but increase computational cost.
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Complexity Analysis

A. Time Complexity

Let:

n = number of dimensions

SN = number of food sources (half the colony)

MCN = maximum cycle number (iterations)

1. Initialization:

$O(SN * n)$ to initialize population and evaluate fitness.

2. Main Loop:

Runs for MCN iterations:

Employed Bee Phase: $O(SN * n)$

Onlooker Bee Phase: $O(SN * n)$

Scout Bee Phase: $O(SN * n)$

Overall Time Complexity:

$O(MCN * SN * n)$

B. Space Complexity

Each food source takes $O(n)$, total $O(SN * n)$

Additional arrays (probabilities, fitness): $O(SN)$

Total space complexity: $O(SN * n)$

Conclusion

The Artificial Bee Colony (ABC) algorithm is a powerful, nature-inspired optimization technique that mimics the intelligent foraging behavior of honey bees. Its balance of exploration (through scouts) and exploitation (through employed and onlooker bees) enables it to efficiently search complex solution spaces. With low implementation complexity, tunable parameters, and adaptability through hybridization and parallelism, ABC is suitable for a wide range of optimization problems, from engineering design to machine learning.