Some computational results for generalized pressure Schur complement eigenvalues of the surface Stokes problem

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1 Bilinear forms and matrices

We set $n_{\mathbf{A}}$ to be the number of velocity d.o.f. and $n_{\mathbf{S}}$ to be the number of pressure d.o.f. Vector stiffness, divergence, pressure mass, normal stabilization, and full stabilization matrices resulting from Trace FEM discretization of the surface Stokes problem [1] are defined via

$$\begin{aligned}
\langle \mathbf{A}\,\bar{\mathbf{u}}, \bar{\mathbf{v}}\rangle &\approx \int_\Gamma \big(E_s(\mathbf{u}) : E_s(\mathbf{v}) + \mathbf{u}\cdot\mathbf{v} + \tau\,(\mathbf{u}\cdot\mathbf{n})\,(\mathbf{v}\cdot\mathbf{n})\big)\,\mathrm{d}s + \rho_u \int_{\Omega_h^\Gamma} \frac{\partial \mathbf{u}}{\partial \mathbf{n}}\cdot\frac{\partial \mathbf{v}}{\partial \mathbf{n}}\,\mathrm{d}\mathbf{x}, \quad \mathbf{A}\in\mathbb{R}^{n_{\mathbf{A}}\times n_{\mathbf{A}}},\\
\langle \mathbf{B}\,\bar{\mathbf{u}}, \bar{\mathbf{q}}\rangle &\approx -\int_\Gamma q\ \mathrm{div}_\Gamma\,\mathbf{u}\,\mathrm{d}s, \quad \mathbf{B}\in\mathbb{R}^{n_{\mathbf{S}}\times n_{\mathbf{A}}},\\
\langle \mathbf{M}_0\,\bar{\mathbf{p}}, \bar{\mathbf{q}}\rangle &\approx \int_\Gamma p\,q\,\mathrm{d}s, \quad \mathbf{M}_0\in\mathbb{R}^{n_{\mathbf{S}}\times n_{\mathbf{S}}},\\
\langle \mathbf{C}_n\,\bar{\mathbf{p}}, \bar{\mathbf{q}}\rangle &\approx \rho_p \int_{\Omega_h^\Gamma} \frac{\partial p}{\partial \mathbf{n}}\frac{\partial q}{\partial \mathbf{n}}\,\mathrm{d}\mathbf{x}, \quad \mathbf{C}_n\in\mathbb{R}^{n_{\mathbf{S}}\times n_{\mathbf{S}}},\\
\langle \mathbf{C}_{\text{full}}\,\bar{\mathbf{p}}, \bar{\mathbf{q}}\rangle &\approx \rho_p \int_{\Omega_h^\Gamma} \nabla p\cdot\nabla q\,\mathrm{d}\mathbf{x}, \quad \mathbf{C}_{\text{full}}\in\mathbb{R}^{n_{\mathbf{S}}\times n_{\mathbf{S}}},
\end{aligned} \tag{1}$$

respectively. We use notations as in [1], in particular, Ω_Γ^h is the domain consisting of tetrahedra cut by Γ. Here $\bar{\mathbf{u}}$ denotes a vector of d.o.f. corresponding to a FE interpolant $\mathbf{u}$ (analogously for $\bar{\mathbf{p}}$ and p). See (11) for the computational details. Mesh-dependent parameters are set as

$$\tau = h^{-2}, \quad \rho_u = \rho_p = h, \tag{2}$$

and h is the typical mesh size for tetrahedra from Ω_h^Γ. Γ is chosen either as the unit sphere or torus, $\Gamma = \Gamma_{\text{sph}}$ or $\Gamma = \Gamma_{\text{tor}}$ (see Figure 1).

We also define matrices

$$\begin{aligned}
\mathbf{C}_0 &\coloneqq \mathbf{0},\\
\mathbf{M}_n &\coloneqq \mathbf{M}_0 + \mathbf{C}_n,\\
\mathbf{M}_{\text{full}} &\coloneqq \mathbf{M}_0 + \mathbf{C}_{\text{full}}.
\end{aligned} \tag{3}$$

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We are interested in (generalized) extreme eigenvalues of the pressure Schur complement matrices

$$\begin{aligned} \mathbf{S}_0 &:= \mathbf{B}\,\mathbf{A}^{-1}\,\mathbf{B}^T, \\ \mathbf{S}_n &:= \mathbf{S}_0 + \mathbf{C}_n, \\ \mathbf{S}_{\text{full}} &:= \mathbf{S}_0 + \mathbf{C}_{\text{full}}, \end{aligned} \tag{4}$$

i.e. in solving

$$\mathbf{S}_\star\,\mathbf{x} = \lambda\,\mathbf{M}_\star\,\mathbf{x}, \tag{5}$$

where "$\star$" stands for "0," "n," or "full." We denote by $0 = \lambda_1 < \lambda_2 \le \cdots \le \lambda_{n_\mathbf{S}} = O(1)$ the spectrum of (5).

2 Solution description

Computing $\mathbf{A}^{-1}$ in (4) becomes troublesome already for $h = 5.21 \times 10^{-2}$ ($n_\mathbf{A} = 32736$ for $\mathbf{u} \in \mathbf{P}_1$ FE space): although $\mathbf{A}$ is sparse, $\mathbf{A}^{-1}$ is dense and consumes 8.5+ GB in double-precision arithmetic. A quick research showed that `Mathematica` has no built-in matrix-free eigenvalue routines. `Intel MKL`'s FEAST algorithm for computing (generalized) eigenvalues in an interval is suitable for matrix-free implementations; however, it requires some expensive operations to be implemented (e.g. matrix-matrix multiplications $\mathbf{Y} \leftarrow \mathbf{S}_\star\,\mathbf{X}$, $\mathbf{Y} \leftarrow \mathbf{M}_\star\,\mathbf{X}$ and approximating the action of inverses in the form $\mathbf{y} \leftarrow (\sigma\,\mathbf{M}_\star - \mathbf{S}_\star)^{-1}\,\mathbf{x}$).

Taking this into account, instead of (5) we consider a perturbed[1] problem

$$\underbrace{\begin{bmatrix} \mathbf{A} & \mathbf{B}^T \\ \mathbf{B} & -\mathbf{C}_\star \end{bmatrix}}_{\mathcal{A}_\star :=} \begin{bmatrix} \mathbf{x} \\ \mathbf{y} \end{bmatrix} = \mu \underbrace{\begin{bmatrix} \epsilon\,\mathbf{A} & \\ & \mathbf{M}_\star \end{bmatrix}}_{\mathcal{M}^\epsilon_\star :=} \begin{bmatrix} \mathbf{x} \\ \mathbf{y} \end{bmatrix} \tag{6}$$

with $0 < \epsilon \ll 1$. For $\mathcal{A}_0$ and $\mathcal{M}^\epsilon_0$ we have

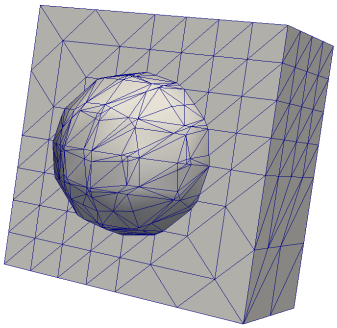
$$\mu = -\lambda + o(1) \quad \text{or} \quad \epsilon^{-1} + \lambda + o(1), \qquad \epsilon \to 0. \tag{7}$$

This makes it easy to pick only "correct" eigenvalues. To ease the computation further we replace the $(1,1)$-block of $\mathcal{M}^\epsilon_\star$ with $\epsilon\,\mathbf{I}$.

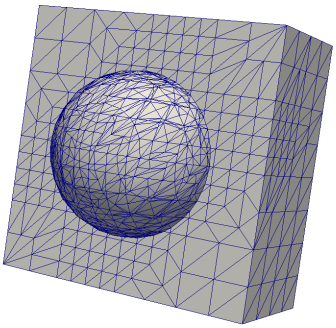
To make sure that results are consistent we solve (6) for $\epsilon = 10^{-5}$ and $\epsilon = 10^{-6}$; for the coarse mesh levels we also check that the dense solver for (5) and the iterative one for (6) give solutions that coincide.

3 Numerical results: dependency of the spectrum on the mesh size

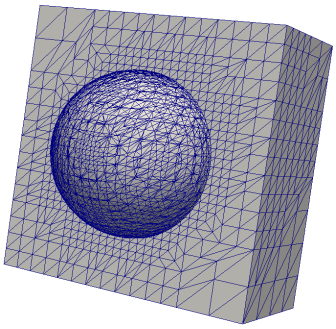
[1] The majority of generalized eigenvalue solvers require left-hand-side matrix to be Hermitian and right-hand-side matrix to be Hermitian **positive definite**; that's why we need to introduce $\epsilon > 0$.



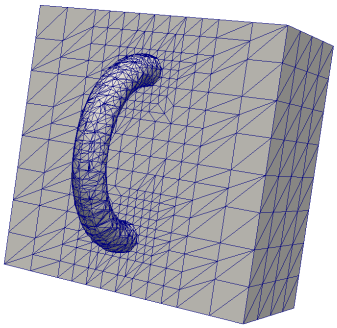
(a) $h = 8.33 \times 10^{-1}$



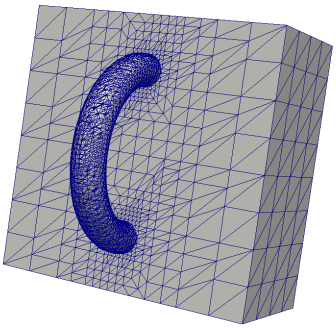
(b) $h = 4.17 \times 10^{-1}$



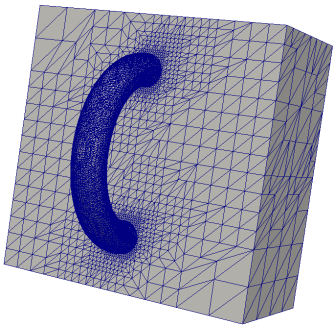
(c) $h = 2.08 \times 10^{-1}$



(d) $h = 2.08 \times 10^{-1}$



(e) $h = 1.04 \times 10^{-1}$



(f) $h = 5.21 \times 10^{-2}$

Figure 1: First three mesh levels for Γ_{sph} (top) and Γ_{tor} (bottom)

Table 1: Spectrum of (5) for $\mathbf{P}_1 - P_1$

(a) $\Gamma = \Gamma_{\text{sph}}$

h	$n_{\mathbf{A}}$	$n_{\mathbf{S}}$	$\mathbf{S}_0$		$\mathbf{S}_n$		$\mathbf{S}_{\text{full}}$	
			λ_2	$\lambda_{n_{\mathbf{S}}}$	λ_2	$\lambda_{n_{\mathbf{S}}}$	λ_2	$\lambda_{n_{\mathbf{S}}}$
8.33×10^{-1}	153	51	1.32×10^{-2}	1.42	7.48×10^{-1}	1.13	9.58×10^{-1}	1.06
4.17×10^{-1}	570	190	5.12×10^{-3}	1.04	5.77×10^{-1}	1.	8.54×10^{-1}	1.
2.08×10^{-1}	1992	664	4.4×10^{-3}	7.93×10^{-1}	3.87×10^{-1}	1.	6.71×10^{-1}	1.
1.04×10^{-1}	8292	2764	2.01×10^{-3}	7.79×10^{-1}	2.19×10^{-1}	1.	5.82×10^{-1}	1.
5.21×10^{-2}	32736	10912	6.04×10^{-5}	9.81×10^{-1}	1.17×10^{-1}	1.	5.37×10^{-1}	1.
2.6×10^{-2}	131592	43864	3.53×10^{-5}	8.67×10^{-1}	5.72×10^{-2}	1.	5.16×10^{-1}	1.
1.3×10^{-2}	525864	175288	2.16×10^{-6}	7.34×10^{-1}	2.84×10^{-2}	1.	5.04×10^{-1}	1.

(b) $\Gamma = \Gamma_{\text{tor}}$

h	$n_{\mathbf{A}}$	$n_{\mathbf{S}}$	$\mathbf{S}_0$		$\mathbf{S}_n$		$\mathbf{S}_{\text{full}}$	
			λ_2	$\lambda_{n_{\mathbf{S}}}$	λ_2	$\lambda_{n_{\mathbf{S}}}$	λ_2	$\lambda_{n_{\mathbf{S}}}$
2.08×10^{-1}	972	324	5.04×10^{-2}	4.93	2.84×10^{-1}	1.35	3.64×10^{-1}	1.19
1.04×10^{-1}	4740	1580	2.99×10^{-3}	3.83	1.58×10^{-1}	1.02	3.35×10^{-1}	1.01
5.21×10^{-2}	19704	6568	1.11×10^{-3}	5.45	7.73×10^{-2}	1.01	3.25×10^{-1}	1.
2.6×10^{-2}	80808	26936	1.2×10^{-4}	5.42	3.07×10^{-2}	1.01	3.21×10^{-1}	1.
1.3×10^{-2}	327036	109012	1.77×10^{-5}	5.23	1.18×10^{-2}	1.01	3.16×10^{-1}	1.

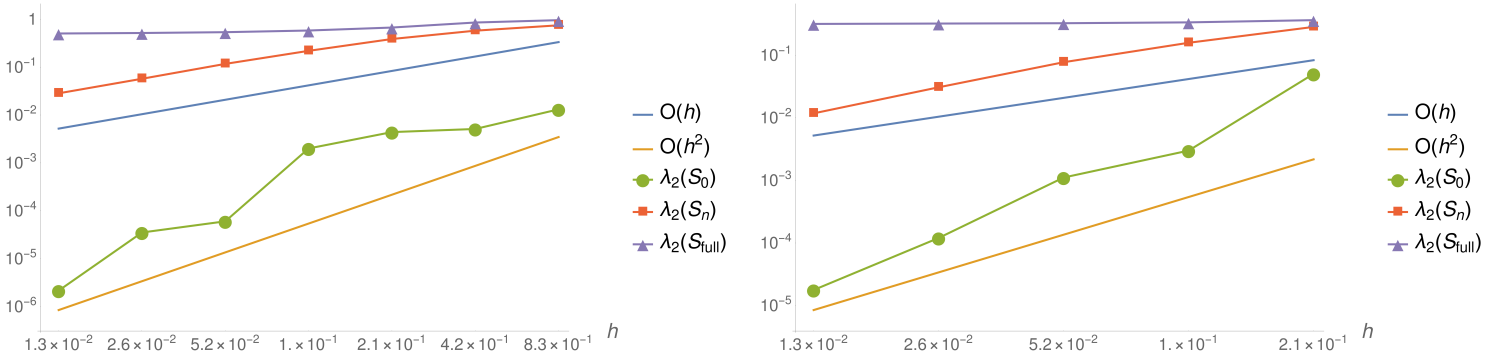


Figure 2: Log-log plot of λ_2 for Tables 1a (left) and 1b (right)

Table 2: Spectrum of (5) for $\mathbf{P}_2 - P_1$

(a) $\Gamma = \Gamma_{\text{sph}}$

h	$n_{\mathbf{A}}$	$n_{\mathbf{S}}$	$\mathbf{S}_0$		$\mathbf{S}_n$		$\mathbf{S}_{\text{full}}$	
			λ_2	$\lambda_{n_{\mathbf{S}}}$	λ_2	$\lambda_{n_{\mathbf{S}}}$	λ_2	$\lambda_{n_{\mathbf{S}}}$
8.33×10^{-1}	789	51	3.22×10^{-1}	1.73	8.27×10^{-1}	1.17	9.68×10^{-1}	1.07
4.17×10^{-1}	3240	190	9.17×10^{-2}	1.08	6.45×10^{-1}	1.	8.56×10^{-1}	1.
2.08×10^{-1}	11718	664	1.78×10^{-1}	8.31×10^{-1}	5.49×10^{-1}	1.	6.75×10^{-1}	1.
1.04×10^{-1}	48762	2764	1.04×10^{-1}	8.35×10^{-1}	5.14×10^{-1}	1.	5.82×10^{-1}	1.
5.21×10^{-2}	193014	10912	2.99×10^{-3}	9.89×10^{-1}	5.02×10^{-1}	1.	5.34×10^{-1}	1.
2.6×10^{-2}	775998	43864	1.17×10^{-3}	7.9×10^{-1}	4.96×10^{-1}	1.	5.17×10^{-1}	1.

(b) $\Gamma = \Gamma_{\text{tor}}$

h	$n_{\mathbf{A}}$	$n_{\mathbf{S}}$	$\mathbf{S}_0$		$\mathbf{S}_n$		$\mathbf{S}_{\text{full}}$	
			λ_2	$\lambda_{n_{\mathbf{S}}}$	λ_2	$\lambda_{n_{\mathbf{S}}}$	λ_2	$\lambda_{n_{\mathbf{S}}}$
2.08×10^{-1}	5184	324	9.92×10^{-2}	3.89	1.33×10^{-1}	1.37	1.75×10^{-1}	1.19
1.04×10^{-1}	27906	1580	1.46×10^{-2}	4.35	2.84×10^{-1}	1.04	2.99×10^{-1}	1.02
5.21×10^{-2}	116568	6568	6.08×10^{-3}	4.85	3.19×10^{-1}	1.01	3.24×10^{-1}	1.01
2.6×10^{-2}	477660	26936	1.36×10^{-3}	4.92	3.14×10^{-1}	1.01	3.16×10^{-1}	1.

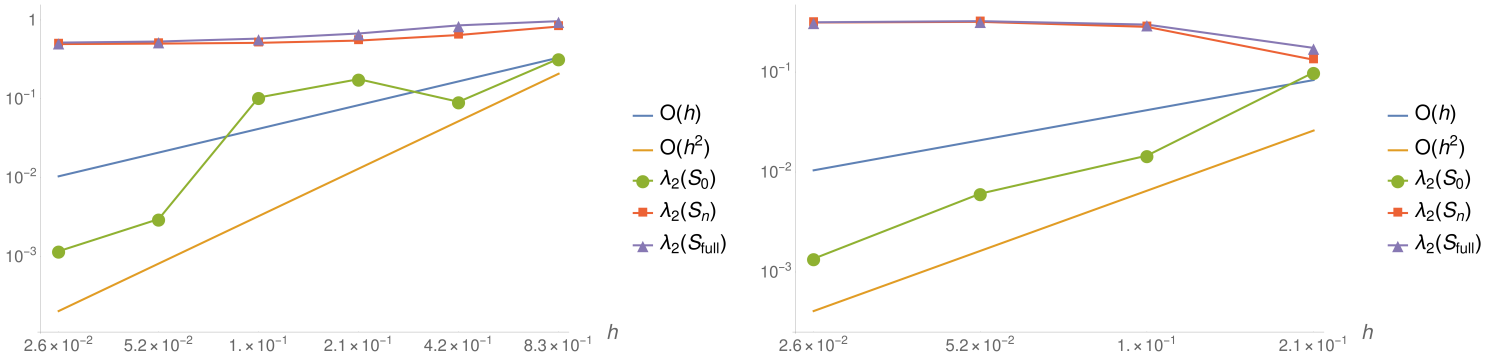


Figure 3: Log-log plot of λ_2 for Tables 2a (left) and 2b (right)

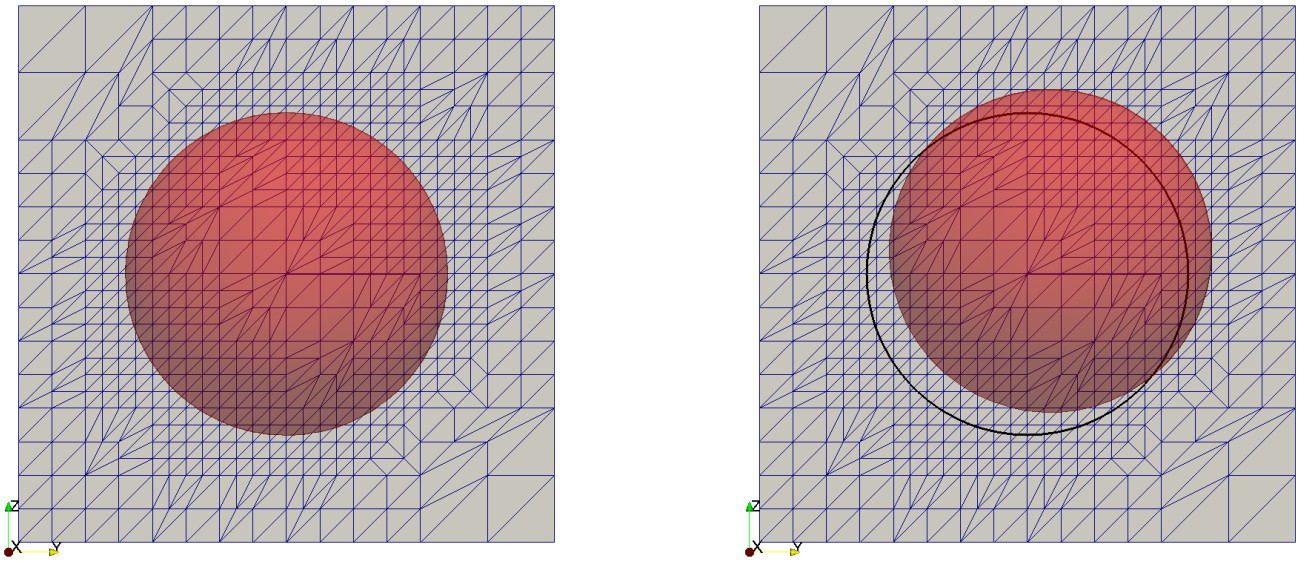
4 Numerical results: sensitivity of the spectrum to levelset shifts

In this section we investigate the sensitivity of the spectrum to levelset shifts

$$\Gamma \mapsto \Gamma + \alpha\,\mathbf{s}, \tag{8}$$

for some $\alpha \in \mathbb{R}$ and $\mathbf{s} \in \mathbb{R}^3$, $\|\mathbf{s}\| = 1$.

We construct the bulk mesh Ω_h^Γ and then perform the assembly of matrices (1) using the shifted levelset (8). That is, the refinement of Ω_h^Γ is performed using Γ, not $\Gamma + \alpha\,\mathbf{s}$, and $\Omega_h^{\Gamma+\alpha\,\mathbf{s}}$ is never constructed. We choose $\alpha \in [0, h]$ to guarantee the appearance of "small cuts" in Ω_h^Γ.



(a) Γ_{sph} (b) $\Gamma_{\text{sph}} + \alpha\,\mathbf{s}$

Figure 4: The unit sphere (left) and the shifted unit sphere (right). Here $\mathbf{s} = (0, 1, 1)^T/\sqrt{2}$, $\alpha = 0.2$, and $h = 2.08 \times 10^{-1}$. The bulk mesh Ω_Γ^h is computed for Γ_{sph} and then used for $\Gamma_{\text{sph}} + \alpha\,\mathbf{s}$

Table 3: Spectrum of (5) for perturbed levelset $\Gamma_{\text{sph}} + \alpha\,\mathbf{s}$. Here $\mathbf{s} = (1,1,1)^T/\sqrt{3}$, $h = 1.04 \times 10^{-1}$

(a) $\mathbf{P}_1 - P_1$

Surface	$\mathbf{S}_0$		$\mathbf{S}_n$		$\mathbf{S}_{\text{full}}$	
	λ_2	$\lambda_{n_\mathbf{S}}$	λ_2	$\lambda_{n_\mathbf{S}}$	λ_2	$\lambda_{n_\mathbf{S}}$
Γ_{sph}	2.006×10^{-3}	7.79×10^{-1}	2.19×10^{-1}	1.	5.818×10^{-1}	1.
$\Gamma_{\text{sph}} + 0.1\,h\,\mathbf{s}$	4.832×10^{-4}	8.01×10^{-1}	2.195×10^{-1}	1.	5.818×10^{-1}	1.
$\Gamma_{\text{sph}} + 0.3\,h\,\mathbf{s}$	7.278×10^{-4}	8.17×10^{-1}	2.203×10^{-1}	1.	5.818×10^{-1}	1.
$\Gamma_{\text{sph}} + 0.5\,h\,\mathbf{s}$	3.121×10^{-4}	8.67×10^{-1}	2.221×10^{-1}	1.	5.82×10^{-1}	1.
$\Gamma_{\text{sph}} + 0.7\,h\,\mathbf{s}$	1.438×10^{-3}	1.51	2.254×10^{-1}	1.	5.82×10^{-1}	1.
$\Gamma_{\text{sph}} + \quad h\,\mathbf{s}$	1.79×10^{-3}	2.07	2.332×10^{-1}	1.	5.827×10^{-1}	1.

(b) $\mathbf{P}_2 - P_1$

Surface	$\mathbf{S}_0$		$\mathbf{S}_n$		$\mathbf{S}_{\text{full}}$	
	λ_2	$\lambda_{n_\mathbf{S}}$	λ_2	$\lambda_{n_\mathbf{S}}$	λ_2	$\lambda_{n_\mathbf{S}}$
Γ_{sph}	1.041×10^{-1}	8.35×10^{-1}	5.138×10^{-1}	1.	5.841×10^{-1}	1.
$\Gamma_{\text{sph}} + 0.1\,h\,\mathbf{s}$	1.705×10^{-3}	8.58×10^{-1}	5.138×10^{-1}	1.	5.841×10^{-1}	1.
$\Gamma_{\text{sph}} + 0.3\,h\,\mathbf{s}$	2.293×10^{-3}	8.81×10^{-1}	5.137×10^{-1}	1.	5.841×10^{-1}	1.
$\Gamma_{\text{sph}} + 0.5\,h\,\mathbf{s}$	5.63×10^{-3}	9.35×10^{-1}	5.138×10^{-1}	1.	5.844×10^{-1}	1.
$\Gamma_{\text{sph}} + 0.7\,h\,\mathbf{s}$	8.188×10^{-3}	1.77	5.138×10^{-1}	1.	5.843×10^{-1}	1.
$\Gamma_{\text{sph}} + \quad h\,\mathbf{s}$	1.93×10^{-2}	2.21	5.142×10^{-1}	1.	5.852×10^{-1}	1.

5 Notes on DROPS implementation

5.1 Notations

We denote by $P_h^n \subset \bar{P}_h^n$ spaces of continuous and discontinuous nodal P_n interpolants defined on Ω_Γ^h, respectively. For a function f, $I_h^n(f) \in P_h^n$ is the corresponding interpolant; we will use the notation f_h^n to emphasize that $f_h^n \in P_h^n$ and f_h^n approximates f in some sense, but $I_h^n(f) \neq f_h^n$.

We set

$$\Gamma_h^n \coloneqq \{\mathbf{x} \in \mathbb{R}^3 : \big(I_h^n(\phi)\big)(\mathbf{x}) = 0\}, \tag{9}$$

$$\mathbf{n}_{\Gamma_h^n} = \frac{\nabla I_h^n(\phi)}{\|\nabla I_h^n(\phi)\|} \notin \bar{P}_h^m \text{ for any } m. \tag{10}$$

Note that Γ_h^n is a continuous piecewise P_n surface in Ω_Γ^h, and $\Gamma_h^n \neq I_h^n(\Gamma)$. The unit normal $\mathbf{n}_{\Gamma_h^n}$ is not a rational function; it is continuous in $T \in \Omega_\Gamma^h$ and discontinuous on faces.

5.2 Approximation of integrands involving $\mathbf{n}_\Gamma$

We start with description of the continuous levelset ϕ of $\Gamma = \{\mathbf{x} \in \mathbb{R}^3 : \phi(\mathbf{x}) = 0\}$. It is stored in `levelset_fun` variable. For example, for the unit sphere we have:

```
// surfnavierstokes_funcs.h
DROPS::Point3DCL sphere_2_shift(0.);
double sphere_2 (const DROPS::Point3DCL& p, double) {
  return pow(p[0] - sphere_2_shift[0], 2.) +
         pow(p[1] - sphere_2_shift[1], 2.) +
         pow(p[2] - sphere_2_shift[2], 2.) - 1.;
}

// surfnavierstokes.cpp
instat_scalar_fun_ptr levelset_fun;
// ...
levelset_fun = &sphere_2;
```

Continuous piecewise P_2 interpolant $I_h^2(\phi)$ of ϕ is built on Ω_Γ^h via iterating over vertices and edges of Ω_Γ^h. It is stored in `lset` object:

```
// levelset.cpp
void LevelsetP2ContCL::Init( instat_scalar_fun_ptr phi0, double t) {
  const Uint lvl= Phi.GetLevel(),
  idx= Phi.RowIdx->GetIdx();
  for (auto it = MG_.GetTriangVertexBegin(lvl), end = MG_.GetTriangVertexEnd(lvl); it
      != end; ++it) {
    if (it->Unknowns.Exist(idx))
      Phi.Data[it->Unknowns(idx)]= phi0( it->GetCoord(), t);
  }
  for (auto it = MG_.GetTriangEdgeBegin(lvl), end = MG_.GetTriangEdgeEnd(lvl); it !=
      end; ++it) {
    if (it->Unknowns.Exist(idx))
      Phi.Data[it->Unknowns(idx)]= phi0( GetBaryCenter( *it), t);
  }
}

// surfnavierstokes.cpp
```

```
DROPS::LevelsetP2CL& lset(*DROPS::LevelsetP2CL::Create(mg, lsbnd, sf));
// ...
lset.Init(levelset_fun);
```

In order to assemble matrices in (1) for e.g. $\mathbf{P}_1 - P_1$ elements, one calls

```
SetupNavierStokesIF_P1P1(mg, &A, /* ... */ lset.Phi, /* ... */);
```

(**Interestingly enough**, this function does not get `lset` object that represents the interpolant; it gets only `lset.Phi`, which is the object of type `VecDescCL`. `lset.Phi` is essentially just a vector of values of ϕ at interpolation points (i.e. vertices and edges' centroids of Ω_Γ^h). That is, the assembling function above has no idea what `lset.Phi` actually represents: one may interpret it as an element of P_h^2 or e.g. $P_{h/2}^1$. Who knows?..)

No interpolation is built explicitly for $\mathbf{n}_{\Gamma_h^2}$ in (10); it is implicitly represented via `qnormal` data field:

```
// ifacetransp.cpp
class LocalStokesCL {
  // ...
  GridFunctionCL<Point3DCL> qnormal;
  // ...
}
```

`qnormal` object is essentially a set of values of type `Point3DCL` which are obtained by mapping a (vector valued) function to suitable quadrature nodes. This is how it is constructed:

```
// ifacetransp.cpp
void LocalStokesCL::Get_Normals(const LocalP2CL<>& ls, LocalP1CL<Point3DCL>& Normals) {
  for(int i=0; i<10 ; ++i)
    Normals+=ls[i]*P2Grad[i];
}
// ...
void LocalStokesCL::calcIntegrands(const SMatrixCL<3,3>& T, const LocalP2CL<>& ls,
    const TetraCL& tet) {
  // ...
  LocalP1CL<Point3DCL> Normals;
  Get_Normals(ls, Normals);
  resize_and_evaluate_on_vertexes (Normals, q2Ddomain, qnormal);
  for(Uint i=0; i<qnormal.size(); ++i)
    qnormal[i]= qnormal[i]/qnormal[i].norm();
  // ...
}
```

First $\nabla I_h^2(\phi|_T)$ is built (locally for a tetrahedron $T \in \Omega_\Gamma^h$ represented by `tet`) and saved to `Normals` object. `ls[i]` gives the value of $\phi|_T$ at ith node (vertices and edges' centroids — there are 10 of them for tetrahedra), and `P2Grad[i]` represents the gradient of quadratic basis function which itself is linear. (Actually, it is sufficient to have $4 < 10$ linear functions to represent $\nabla I_h^2(\phi|_T)$, but this is how it is implemented here.) Finally, `qnormal` object is built via evaluating `Normals` at quadrature nodes and normalization.

Objects `qnormal` for surface integrals and `q3Dnormal` for volume integrals are used in approximation of $\mathbf{P} = \mathbf{I} - \mathbf{n}\,\mathbf{n}^T$, normal derivatives, and taking-normal-components in (1). `q3Dnormal` is constructed as `qnormal` but for quadrature points of tetrahedrons, not triangles.

For one, $\mathbf{P}\,\nabla f_h^2$, $f_h^2 \coloneqq P_2$ basis function on Ω_Γ^h, is approximated via `qsurfP2grad` object:

```
// ifacetransp.cpp
void LocalStokesCL::calcIntegrands(/* ... */) {
    // ...
    for(int j=0; j<10 ;++j) {
    resize_and_evaluate_on_vertexes(P2Grad[j], q2Ddomain, qsurfP2grad[j]);
    qsurfP2grad[j]-= dot(qsurfP2grad[j], qnormal)*qnormal;
```

```
  }
  // ...
}
```

The term $\int_{\Omega_h^\Gamma} \frac{\partial p}{\partial \mathbf{n}} \frac{\partial q}{\partial \mathbf{n}} \, d\mathbf{x}$ in (1) is computed as

```
// ifacetransp.cpp
void LocalStokesCL::setupA_P1_stab(double A_P1_stab[4][4], double absdet) {
  for (int i=0; i<4; ++i)
    for (int j=0; j<4; ++j)
      A_P1_stab[i][j] = quad(dot(q3Dnormal, q3DP1Grad[i])*dot(q3Dnormal, q3DP1Grad[j]),
          absdet, q3Ddomain, AllTetraC);
}
```

5.3 Quadrature rules for $\int_\Gamma$ and $\int_{\Omega_\Gamma^h}$

All the 3D integrals in (1) are computed via iteration over $T \in \Omega_\Gamma^h$ without any virtual refinements. `q3Ddomain` object represents the set of quadrature nodes and weights:

```
// ifacetransp.cpp
void LocalStokesCL::calc3DIntegrands(/* ... */) {
  make_SimpleQuadDomain<Quad5DataCL> (q3Ddomain, AllTetraC);
  // ...
}
```

It is used e.g. in `setupA_P1_stab` above. 15 nodes and weights are used, and the quadrature is exact for functions in $\bar{P}_h^5$.

All the surface integrals are computed using $\Gamma_{h/2}^1$. One extra "virtual" refinement is achieved via setting

```
// ifacetransp.cpp
LocalStokesCL(bool fullGradient)
  : lat(PrincipalLatticeCL::instance(2))
  , /* ... */ { /* ... */ }
```

(Changing 2 to 4 will give us $\Gamma_{h/4}^1$ and so forth.) `q2Ddomain` object represents the set of quadrature nodes and weights:

```
// ifacetransp.cpp
void LocalStokesCL::calcIntegrands(/* ... */) {
  // ...
  evaluate_on_vertexes( ls, lat, Addr( ls_loc));
  spatch.make_patch<MergeCutPolicyCL>( lat, ls_loc);
  make_CompositeQuad5Domain2D ( q2Ddomain, spatch, tet);
  // ...
}
```

Each linear subsurface in $T \in \Omega_\Gamma^h$ has 7 quadrature nodes and weights, and the quadrature rule is again exact for functions in $\bar{P}_h^5$.

5.4 Summary

The matrices in (1) are assembled as

$$
\begin{aligned}
\langle \mathbf{A}\,\bar{\mathbf{u}}, \bar{\mathbf{v}} \rangle &= \int_{\Gamma^1_{h/2}}^{5} \left(E_{s,\,\Gamma^2_h}(\mathbf{u}) : E_{s,\,\Gamma^2_h}(\mathbf{v}) + \mathbf{u}\cdot\mathbf{v} + \tau\,(\mathbf{u}\cdot\mathbf{n}_{\Gamma^2_h})\,(\mathbf{v}\cdot\mathbf{n}_{\Gamma^2_h}) \right) \mathrm{d}s \\
&\quad + \rho_u \int_{\Omega^\Gamma_h}^{5} \frac{\partial \mathbf{u}}{\partial \mathbf{n}_{\Gamma^2_h}} \cdot \frac{\partial \mathbf{v}}{\partial \mathbf{n}_{\Gamma^2_h}}\,\mathrm{d}\mathbf{x}, \quad \mathbf{A} \in \mathbb{R}^{n_\mathbf{A} \times n_\mathbf{A}}, \\
\langle \mathbf{B}\,\bar{\mathbf{u}}, \bar{\mathbf{q}} \rangle &= -\int_{\Gamma^1_{h/2}}^{5} q\ \mathrm{div}_{\Gamma^2_h}\,\mathbf{u}\,\mathrm{d}s, \quad \mathbf{B} \in \mathbb{R}^{n_\mathbf{S} \times n_\mathbf{A}}, \\
\langle \mathbf{M}_0\,\bar{\mathbf{p}}, \bar{\mathbf{q}} \rangle &= \int_{\Gamma^1_{h/2}}^{5} p\,q\,\mathrm{d}s, \quad \mathbf{M}_0 \in \mathbb{R}^{n_\mathbf{S} \times n_\mathbf{S}}, \\
\langle \mathbf{C}_n\,\bar{\mathbf{p}}, \bar{\mathbf{q}} \rangle &= \rho_p \int_{\Omega^\Gamma_h}^{5} \frac{\partial p}{\partial \mathbf{n}_{\Gamma^2_h}} \frac{\partial q}{\partial \mathbf{n}_{\Gamma^2_h}}\,\mathrm{d}\mathbf{x}, \quad \mathbf{C}_n \in \mathbb{R}^{n_\mathbf{S} \times n_\mathbf{S}}, \\
\langle \mathbf{C}_{\text{full}}\,\bar{\mathbf{p}}, \bar{\mathbf{q}} \rangle &= \rho_p \int_{\Omega^\Gamma_h}^{5} \nabla p \cdot \nabla q\,\mathrm{d}\mathbf{x}, \quad \mathbf{C}_{\text{full}} \in \mathbb{R}^{n_\mathbf{S} \times n_\mathbf{S}},
\end{aligned}
\tag{11}
$$

Comments:

- $\int^5$ denotes a composite quadrature rule that is exact for $\bar{P}^5_h$,
- $E_{s,\,\Gamma^2_h}$ and $\mathrm{div}_{\Gamma^2_h}$ are defined as their continuous analogues with $\mathbf{n}_\Gamma$ in $\mathbf{P}$ replaced with $\mathbf{n}_{\Gamma^2_h}$,
- It is always the case that integrands use $\mathbf{n}_{\Gamma^2_h} \neq \mathbf{n}_{\Gamma^1_{h/2}}$, and the actual domain of integration is $\Gamma^1_{h/2} \neq \Gamma^2_h$,
- $\mathbf{n}_{\Gamma^2_h}$ is defined in (10) and it is not a polynomial even locally, thus quadrature rules are never exact (although for $\mathbf{P}_2 - P_1$ shape functions alone these quadratures are exact),
- In our examples we know ϕ and $\nabla\phi$ exactly, and thus it is super easy to feed the **exact** normal $\mathbf{n}_\Gamma \neq \mathbf{n}_{\Gamma^2_h}$ to quadratures. Shall we do this?

References

[1] M. Olshanskii, A. Quaini, A. Reusken, and V. Yushutin. A finite element method for the surface stokes problem. *SIAM Journal on Scientific Computing*, 40(4):A2492–A2518, 2018.