```
0.00
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import rawpy
import os
import sys
import time
import argparse
os.environ["OPENCV IO ENABLE OPENEXR"]="1"
import cv2 #only for save images to jpg
import exifread
from matplotlib import pyplot as plt #use it only for debug
import numpy as np
from tqdm import tqdm
from BayerDomainProcessor import *
from RGBDomainProcessor import *
from YUVDomainProcessor import *
def get arg():
    parser = argparse.ArgumentParser()
    parser.add argument("--draw-intermediate", type=bool,
default=True)
    parser.add argument("--set-dir", type=str,
default="../data/set03")
    parser.add argument("--output-dir", type=str, default="data")
    parser.add argument("--itmd dir", type=str, default="itmd", help=\
        "intermediate file root directory.")
    parser.add_argument("--fast", type=bool, action="store_true",
help=\
        "User can choose open cv bilateral filter for larger and
faster convolution computation")
    args = parser.parse args()
    assert os.path.exists(args.set dir)
    if os.path.exists(args.output dir) == False:
        os.makedirs(args.output dir)
    args.itmd dir = os.path.join(args.itmd dir,
args.set dir.strip("/")[-1])
    if os.path.exists(args.itmd dir) == False:
        os.makedirs(args.itmd dir)
    assert os.path.exists(args.output_dir)
    assert os.path.exists(args.itmd dir)
    return args
# fake args
class ARGs:
    def __init__(self, fast=True):
        self.set dir = "../data/set03"
        self.draw intermediate = True
```

```
self.output dir = "data"
        self.itmd dir = "itmd"
        self.itmd dir = os.path.join(self.itmd dir,
self.set dir.strip("/")[-1])
        self.sub dir = os.path.join(self.output dir,
self.set_dir.split("/")[-1])
        self.fast = fast
        if os.path.exists(self.itmd dir) == False:
            os.makedirs(self.itmd dir)
        if os.path.exists(self.output dir) == False:
            os.makedirs(self.output dir)
        if os.path.exists(self.sub dir) == False:
            os.makedirs(self.sub dir)
        assert os.path.exists(self.output dir)
        assert os.path.exists(self.itmd dir)
args = ARGs()
image name list = []
for file in os.listdir(args.set dir):
    if os.path.splitext(file)[1]=='.ARW':
        file dir = os.path.join(args.set dir, file)
        image name list.append(file dir)
image name list.sort()
image list = []
exposure times = []
raw list = []
for name in image name list:
    raw = rawpy.imread(name)
    raw list.append(raw)
    image list.append(raw.raw image)
    raw file = open(name, 'rb')
    exif file = exifread.process file(raw file, details=False,
strict=True)
    ISO str = exif file['EXIF ISOSpeedRatings'].printable
    ExposureTime = exif file['EXIF ExposureTime'].printable
    exposure times.append(float(ExposureTime.split(
        '/')[0]) / float(ExposureTime.split('/')[1]) * float(ISO_str))
clip list = []
for image in image list:
    clip list.append(np.clip(image, raw.black level per channel[0],
2**14))
print(50*'-' + '\nLoading RAW Image Done.....')
```

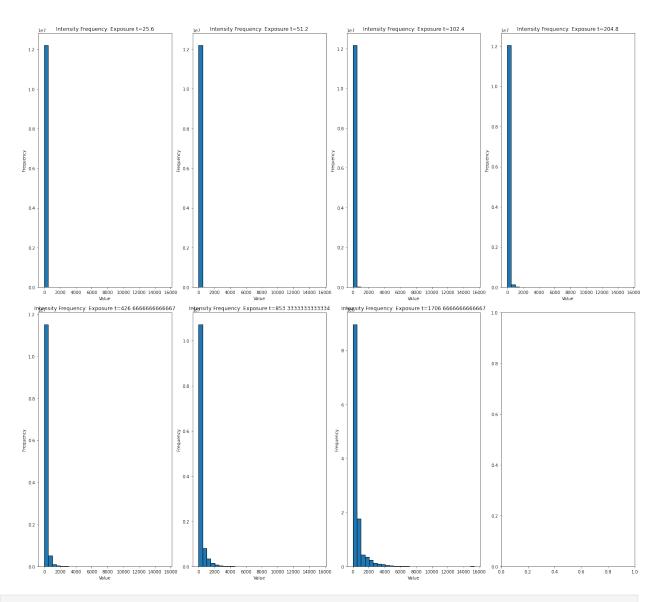
```
______
Loading RAW Image Done.....
# Step 1. Dead Pixel Correction (10pts)
Bayer dpcs = []
dpc thres, dpc mode, dpc clip = 4096, 'gradient',
raw.camera white level per channel[0]
for i, raw image in enumerate(clip list):
   dpc = deadPixelCorrection(raw image, dpc thres, dpc mode,
dpc clip)
   dpc output = dpc.execute()
   Bayer dpcs.append(dpc output)
   if args.draw intermediate:
      output dir = os.path.join(args.itmd dir, 'Dead-Pixel-
Correction'+str(i)+'.jpg')
      cv2.imwrite(output dir,dpc output)
print(50*'-' + '\n 1.1 Dead Pixel Correction Done.....')
     1.1 Dead Pixel Correction Done.....
# Step 2. 'Black Level Compensation' (5pts)
alpha, beta = 0, 0
parameter = raw.black level per channel + [alpha, beta]
Bayer blackLevelCompensations = []
for dpc output in Bayer dpcs:
   blkC = blackLevelCompensation(dpc output, parameter, 2**14, "rggb")
   blkc output = blkC.execute()
   Bayer blackLevelCompensations.append(blkc output)
print(50*'-' + '\n 1.2 Black Level Compensation Done.....')
1.2 Black Level Compensation Done.....
# Step 3.'lens shading correction
# skip this
# Step 4. Anti Aliasing Filter (10pts)
Bayer antiAliasingFilters = []
for i, blkc output in enumerate(Bayer blackLevelCompensations):
   antiAliasingFilter = AntiAliasingFilter(blkc output)
   aaf output = antiAliasingFilter.execute()
   Bayer antiAliasingFilters.append(aaf output)
   if args.draw intermediate:
```

```
output dir = os.path.join(args.itmd dir, 'Bayer-
antiAliasingFilter'+str(i)+'.jpg')
        cv2.imwrite(output dir, aaf output)
print(50*'-' + '\n 1.4 Anti-aliasing Filtering Done.....')
                      1.4 Anti-aliasing Filtering Done.....
# Step 5. Auto White Balance and Gain Control (10pts)
r gain, gr gain, gb gain, b gain = [2,1,2,1]
parameter = [r_gain, gr_gain, gb_gain, b_gain]
Bayer awbs = []
for i, aff output in enumerate(Bayer antiAliasingFilters):
    raw = raw list[i]
   awb clip = raw.camera white level per channel[0]
   awb = AWB(aff output, parameter, "rggb", awb clip)
   awb output = awb.execute()
   Bayer awbs.append(awb output)
   if args.draw intermediate:
        output dir = os.path.join(args.itmd dir, "White-Balance-
Gain"+str(i)+".jpg")
        cv2.imwrite(output dir,awb output)
print(50*'-' + '\n 1.5 White Balance Gain Done.....')
1.5 White Balance Gain Done.....
# Step 6. Raw Exposure Fusion
# your code here
def stat draw times(image list:list, times:list):
   fig, axs = plt.subplots(2, 4, figsize=(20, 18))
   for i in range(len(times)):
        img = image list[i]
        axs[i//4, i%4].hist(img[:, :].flatten(), bins=30,
edgecolor='black')
        axs[i//4, i%4].set title('Intensity Frequency: Exposure
t='+str(times[i]))
        axs[i//4, i%4].set xlabel('Value')
        axs[i//4, i%4].set ylabel('Frequency')
   # Adjust layout to prevent overlapping
   plt.tight layout()
   # Show the plot
   plt.savefig(os.path.join(args.itmd dir, "Exporture-Intensity-
Frequency.jpg"))
   plt.show()
def stat draw(img):
   plt.hist(img[:, :].flatten(), bins=30, edgecolor='black')
   plt.title('Intensity Frequency of Merge')
```

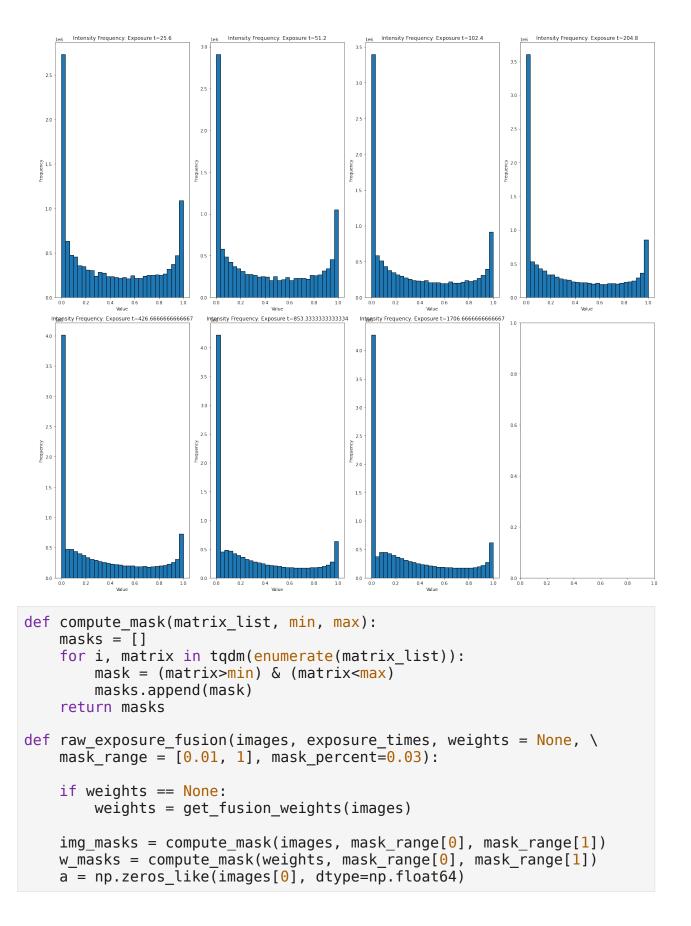
```
plt.xlabel('Value')
    plt.ylabel('Frequency')
    plt.savefig(os.path.join(args.itmd dir, "Intensity-Frequency-of-
Merge.jpg"))
    plt.show()
def stat draw rbg(img:np.ndarray, use float = False):
    if (img.dtype != np.int) and (use float == False):
        img = img.astype(np.int)
    fig, axs = plt.subplots(\frac{2}{2}, figsize=(\frac{10}{8}))
    # Plot histograms
    axs[0, 0].hist(img[:, :, 0].flatten(), bins=30, edgecolor='black',
color='r')
    axs[0, 0].set title('Red Channel Histogram')
    axs[0, 0].set xlabel('Value')
    axs[0, 0].set ylabel('Frequency')
    axs[0, 1].hist(img[:, :, 1].flatten(), bins=30, edgecolor='black',
color='g')
    axs[0, 1].set title('Green Channel Histogram')
    axs[0, 1].set xlabel('Value')
    axs[0, 1].set_ylabel('Frequency')
    axs[1, 0].hist(img[:, :, 2].flatten(), bins=30, edgecolor='black',
color='b')
    axs[1, 0].set_title('Blue Channel Histogram')
    axs[1, 0].set xlabel('Value')
    axs[1, 0].set ylabel('Frequency')
    # Plot the image
    axs[1, 1].imshow(img)
    axs[1, 1].set title('RGB Image')
    # Hide the x and y ticks for the image plot
    axs[1, 1].tick params(axis='both', which='both', bottom=False,
left=False, labelbottom=False, labelleft=False)
    # Adjust layout to prevent overlapping
    plt.tight layout()
    # Show the plot
    plt.show()
def stat_draw_yuv(img:np.ndarray, use_float = False):
    if (img.dtype != np.int) and (use float == False):
        img = img.astype(int)
    fig, axs = plt.subplots(\frac{2}{2}, figsize=(\frac{10}{8}))
    # Plot histograms
```

```
axs[0, 0].hist(img[:, :, 0].flatten(), bins=30, edgecolor='black',
color='r')
    axs[0, 0].set title('Y Channel Histogram')
    axs[0, 0].set xlabel('Value')
    axs[0, 0].set ylabel('Frequency')
    axs[0, 1].hist(img[:, :, 1].flatten(), bins=30, edgecolor='black',
color='q')
    axs[0, 1].set_title('U Channel Histogram')
    axs[0, 1].set xlabel('Value')
    axs[0, 1].set ylabel('Frequency')
    axs[1, 0].hist(img[:, :, 2].flatten(), bins=30, edgecolor='black',
color='b')
    axs[1, 0].set_title('V Channel Histogram')
    axs[1, 0].set xlabel('Value')
    axs[1, 0].set ylabel('Frequency')
    # Plot the image
    axs[1, 1].imshow(img)
    axs[1, 1].set title('YUV Image')
    # Hide the x and y ticks for the image plot
    axs[1, 1].tick params(axis='both', which='both', bottom=False,
left=False, labelbottom=False, labelleft=False)
    # Adjust layout to prevent overlapping
    plt.tight layout()
    # Show the plot
    plt.show()
def normalize(img):
    imq min = np.min(imq)
    img max = np.max(img)
    return (img-img min)/(img max-img min)
def normalize rgb(img, bias = True):
    r \min = np.\min(img[:, :, 0])
    g \min = np.\min(img[:, :, 1])
    b \min = np.\min(imq[:, :, 2])
    r max = np.max(img[:, :, 0])
    g max = np.max(img[:, :, 1])
    b max = np.max(img[:, :, 2])
    if bias:
        img[:, :, 0] = (img[:, :, 0]-r min)/(r max-r min)
        img[:, :, 1] = (img[:, :, 1]-g min)/(g max-g min)
        img[:, :, 2] = (img[:, :, 2]-b_min)/(b_max-b_min)
    else:
```

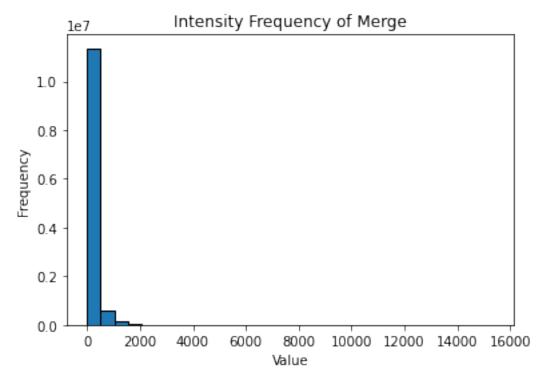
```
img[:, :, 0] = (img[:, :, 0])/(r max)
        img[:, :, 1] = (img[:, :, 1])/(g max)
        img[:, :, 2] = (img[:, :, 2])/(b max)
    return imq
def get fusion weights(images:list, median = False):
    w list = []
    for i, img in tqdm(enumerate(images)):
        w = np.zeros like(img)
        if median:
            median = np.median(img)
            w = np.exp(-4 * ((img-median)**2/median**2),
dtype=np.float64)
        else:
            w = np.exp(-4 * ((img-0.5)**2/0.5**2), dtype=np.float64)
        w list.append(w)
    return w list
# norm awbs = [normalize(awb) for awb in Bayer awbs]
stat draw times(Bayer awbs, exposure times)
weights = get_fusion_weights(Bayer_awbs, median=True)
if args.draw intermediate:
    for i, w in enumerate(weights):
        output_dir = os.path.join(args.itmd dir, "fusion-
weight-"+str(i)+".jpg")
        plt.imshow(w)
        plt.title("fusion-weight-"+str(i))
        plt.axis("off")
        plt.savefig(output dir)
        plt.clf()
```



7it [00:07, 1.09s/it]
<Figure size 432x288 with 0 Axes>
stat\_draw\_times(weights, exposure\_times)



```
b = np.zeros like(images[0], dtype=np.float64)
    c = np.mean(np.array(images), axis=0)
    for i, w in tqdm(enumerate(weights)):
        img i = images[i]
        t i = exposure times[i]
        \# i m = img masks[i]
        w_m = w masks[i]
        \#\overline{a[w m]} += w[w m] * (np.log(img i[w m], dtype=np.float64)
np.log(t i, dtype=np.float64))
        \# b[w m] += w[w m]
        i m = img masks[i]
        m = i m \& w m
        a[m] = w[m] * (np.log(img i[m], dtype=np.float64)-np.log(t i,
dtype=np.float64))
        b[m] += w[m]
    b mask = b > 0
    c[b mask] = np.exp(a[b mask]/b[b mask])
    return c.astype(np.float32)
Fusion = raw exposure fusion(Bayer awbs, exposure times, weights)
\# Fusion = \overline{normalize}(\overline{Fusion})
if args.draw intermediate:
    plt.imshow(Fusion)
    plt.title("Merging LDR Exposures")
    plt.axis("off")
    plt.savefig(os.path.join(args.itmd dir, "Merging-LDR-
Exposures.jpg"))
    plt.clf()
    stat draw(Fusion)
0it [00:00, ?it/s]
7it [00:00, 12.85it/s]
7it [00:00, 20.72it/s]
7it [00:00, 9.65it/s]
```

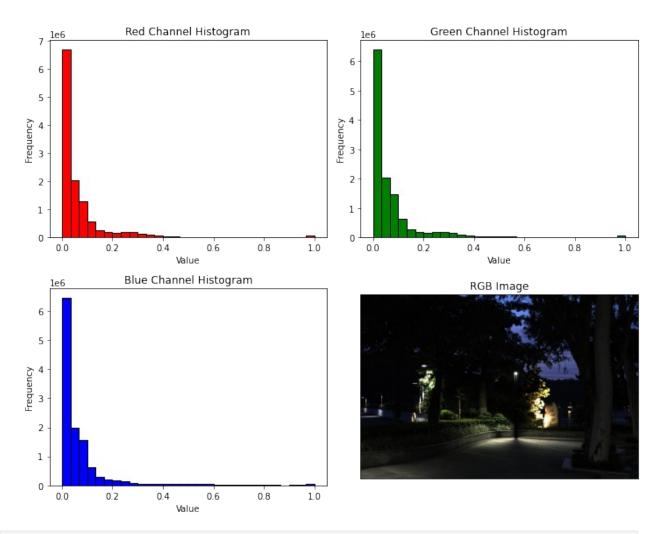


```
np.max(Fusion)
15360.0
class CFA beta:
    def __init__(self, img, mode, bayer pattern, clip):
        self.img = img
        self.mode = mode
        self.bayer pattern = bayer pattern
        self.clip = clip
    def padding(self):
        # Fill your code here
        img pad = np.pad(self.img, ((2,2),(2,2)), 'reflect')
        return img_pad
    def clipping(self):
        # Fill your code here
        return
    def execute(self):
        img pad = self.padding()
        img_pad = img_pad.astype(np.float32)
        raw_h = self.img.shape[0]
        raw w = self.img.shape[1]
```

```
cfa img = np.empty((raw h, raw w, 3), np.float32)
                       r = np.zeros((self.img.shape))
                       g = np.zeros((self.img.shape))
                       b = np.zeros((self.img.shape))
                       G_{at}R = G_{at}B = np.array([[0,0,-1,0,0],[0,0,2,0,0],[-
1,2,4,2,-1], [0,0,2,0,0], [0,0,-1,0,0]])
                      R_{\text{row}} = B_{\text{row}} = B_{
1,0],[-1,4,5,4,-1],[0,-1,0,-1,0],[0,0,1/2,0,0]])
                      R col_at_G = B_col_at_G = R_row_at_G.T
                      R at B = B at R = np.array([[0,0,-3/2,0,0],[0,2,0,2,0],[-3/2,0,0])
3/2,0,6,0,-3/2], [0,2,0,2,0], [0,0,-3/2,0,0]])
                       r[::2,::2] = img_pad[2:-2:2,2:-2:2]
                       for i in range(-2,3):
                                  for j in range(-2,3):
                                             if R at B[i+2,j+2] != 0:
                                                         r[1::2,1::2] +=
(img pad[3+i:,3+j:]*R at B[i+2,j+2])[:raw h:2,:raw w:2]
                                             if R col at G[i+2,j+2] != 0:
                                                          r[1::2,::2] +=
(img pad[3+i:,2+j:]*R col at G[i+2,j+2])[:raw h:2,:raw w:2]
                                             if R row at \overline{G}[i+2,j+2] != 0:
                                                         r[::2,1::2] +=
(img_pad[2+i:,3+j:]*R_row_at_G[i+2,j+2])[:raw_h:2,:raw w:2]
                       r[1::2,::2] /= 8
                       r[::2,1::2] /= 8
                       r[1::2,1::2] /= 8
                       g[1::2,::2] = img pad[3:-1:2,2:-2:2]
                       g[::2,1::2] = img pad[2:-2:2,3:-1:2]
                       for i in range(-2,3):
                                  for j in range(-2,3):
                                              if G at B[i+2,j+2] != 0:
                                                         g[1::2,1::2] +=
(img_pad[3+i:,3+j:]*G_at_B[i+2,j+2])[:raw_h:2,:raw_w:2]
                                             if G_{\overline{a}}t_{\overline{R}}[i+2,j+2] != 0:
                                                         g[::2,::2] += (img pad[2+i:,2+j:]*G at R[i+2,j+2])
[:raw h:2,:raw w:2]
                       g[::2,::2] /= 8
                       q[1::2,1::2] /= 8
                       b[1::2,1::2] = img pad[3:-1:2,3:-1:2]
                       for i in range(-2,3):
                                  for j in range(-2,3):
                                             if B at R[i+2,j+2] != 0:
                                                         b[::2,::2] += (img_pad[2+i:,2+j:]*B_at_R[i+2,j+2])
[:raw_h:2,:raw_w:2]
                                              if B row at_G[i+2,j+2] != 0:
```

```
b[1::2,::2] +=
(img pad[3+i:,2+j:]*B row at G[i+2,j+2])[:raw h:2,:raw w:2]
                if B col at G[i+2, j+2] != 0:
                    b[::2,1::2] +=
(img_pad[2+i:,3+j:]*B_col_at_G[i+2,j+2])[:raw_h:2,:raw_w:2]
        b[::2,::2] /= 8
        b[1::2,::2] /= 8
        b[::2,1::2] /= 8
        # Fill your code here
        cfa img = np.stack([r,g,b],axis=2)
        cfa img = np.clip(cfa img, 0, 2^{**}14)
        sorted = np.sort(cfa img.flatten())
        max = np.percentile(sorted,99.5)
        tone mapping factor = 0
        percentage = 0.02
        min = np.percentile(sorted, 0.05)
        step size = 0.01
        while min == 0.0:
            if percentage+step size>=1:
                break
            percentage+=step size
            min = np.percentile(sorted, percentage)
            print("percentage = ", percentage)
        tone_mapping factor = max/min
        cfa img norm = (np.clip((cfa img-min)/(max-min), 1E-8,1))
        return cfa img, cfa img norm, tone mapping factor
# Step 7. 'Color Filter Array Interpolation' Malvar (20pts)
cfa mode = 'malvar'
cfa clip = raw list[0].camera white level per channel[0]
cfa = CFA beta(Fusion, cfa mode, "rggb", cfa clip)
rgbimg cfa, rgbimg cfa norm, tone mapping factor = cfa.execute()
stat draw rbg(rgbimg cfa norm, use float = True)
print("tone_mapping_factor = ", tone_mapping_factor)
print(50*'-' + '\n 1.7 Demosaicing Done....')
if args.draw intermediate:
    output jpg dir = os.path.join(args.itmd dir,
'CFA Interpolation.jpg')
    output hdr dir = os.path.join(args.itmd_dir,
'CFA Interpolation.hdr')
    plt.imshow(rgbimg cfa norm)
    plt.title("CFA Interpolation after Merge")
    plt.axis("off")
    plt.savefig(output jpg dir)
cv2.imwrite(output hdr dir,cv2.cvtColor(rgbimg cfa norm.astype(np.floa
t32),cv2.COLOR RGB2BGR))
```

```
percentage = 0.03
percentage = 0.04
percentage = 0.05
percentage =
            0.060000000000000005
percentage = 0.07
percentage = 0.08
percentage = 0.09
percentage = 0.11999999999999998
percentage = 0.129999999999998
percentage = 0.15
percentage = 0.16
percentage = 0.17
percentage = 0.1800000000000002
percentage = 0.1900000000000003
percentage = 0.20000000000000004
percentage = 0.21000000000000005
percentage = 0.23000000000000007
percentage = 0.24000000000000007
percentage = 0.25000000000000006
percentage = 0.26000000000000006
percentage = 0.2700000000000001
percentage = 0.2800000000000001
percentage = 0.2900000000000001
percentage = 0.300000000000001
percentage = 0.3100000000000001
percentage = 0.320000000000001
percentage = 0.330000000000001
percentage = 0.3400000000000014
percentage = 0.3500000000000014
percentage = 0.36000000000000015
percentage = 0.3700000000000016
percentage = 0.3800000000000017
C:\Users\surface\AppData\Local\Temp\ipykernel_15684\2878482894.py:27:
DeprecationWarning: `np.int` is a deprecated alias for the builtin
`int`. To silence this warning, use `int` by itself. Doing this will
not modify any behavior and is safe. When replacing `np.int`, you may
wish to use e.g. `np.int64` or `np.int32` to specify the precision. If
you wish to review your current use, check the release note link for
additional information.
Deprecated in NumPy 1.20; for more details and guidance:
https://numpy.org/devdocs/release/1.20.0-notes.html#deprecations
 if (img.dtype != np.int) and (use float == False):
```



```
tone_mapping_factor = 3258556.027478817
1.7 Demosaicing Done.....
```

## CFA Interpolation after Merge



```
if args.set dir.split("/")[-1] == "set03":
    show img list = [
        cv2.imread(os.path.join(args.set dir, "DSC00163.jpg")),
        cv2.imread(os.path.join(args.set dir,
                                               "DSC00164.jpg")),
        cv2.imread(os.path.join(args.set dir,
                                               "DSC00165.jpg")),
        cv2.imread(os.path.join(args.set_dir, "DSC00166.jpg")),
        cv2.imread(os.path.join(args.set dir,
                                               "DSC00167.jpg")),
        cv2.imread(os.path.join(args.set_dir, "DSC00168.jpg")),
        cv2.imread(os.path.join(args.set_dir, "DSC00169.jpg")),
        rgbimg cfa norm
    show img list[:-1] = [cv2.cvtColor(img, cv2.COLOR BGR2RGB) for img
in show img list[:-1]]
    fig, axs = plt.subplots(4, 2, figsize=(20, 18))
    for i, img in enumerate(show img list[:-1]):
        time i = exposure times[i]
        axs[i//2, i%2].imshow(img)
        axs[i//2, i%2].set title('Exposure Time:'+str(time i))
        axs[i//2, i\%2].axis("off")
    axs[7//2, 7%2].imshow(rgbimg cfa norm)
    axs[7//2, 7%2].set_title('Fusion')
    axs[7//2, 7\%2].axis("off")
# Adjust layout to prevent overlapping
plt.tight layout()
# Show the plot
plt.savefig(os.path.join(args.itmd dir, ".jpg"))
plt.show()
```

















import OpenEXR
import Imath

def save\_hdr\_image\_to\_exr(rgb\_matrix, file\_path):
 # Convert the RGB matrix to a 32-bit float array

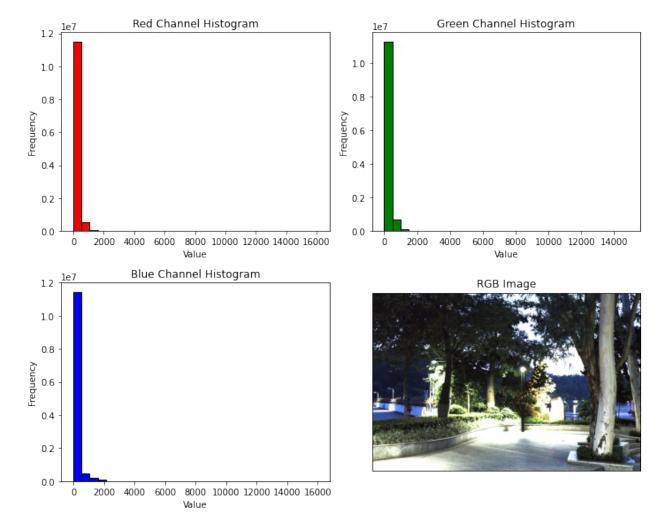
```
hdr data = np.array(rgb matrix, dtype=np.float32)
    # Create an OpenEXR image header with the dimensions of the matrix
    header = OpenEXR.Header(hdr data.shape[1], hdr data.shape[0])
    # Set the channels in the header
    header['channels'] = {
        'R': Imath.Channel(Imath.PixelType(Imath.PixelType.FLOAT)),
        'G': Imath.Channel(Imath.PixelType(Imath.PixelType.FLOAT)),
        'B': Imath.Channel(Imath.PixelType(Imath.PixelType.FLOAT))
    }
    # Create an OpenEXR image object
    exr image = OpenEXR.OutputFile(file path, header)
    # Convert the RGB matrix to a planar configuration (separate R, G,
B channels)
    r_channel = hdr_data[:, :, 0].tobytes()
    g channel = hdr data[:, :, 1].tobytes()
    b_channel = hdr_data[:, :, 2].tobytes()
    # Write the channel data to the EXR image
    exr image.writePixels({'R': r channel, 'G': g channel, 'B':
b channel})
    # Close the EXR image file
    exr image.close()
file_path = 'output_image.exr' # Replace with the desired output file
path
save_hdr_image_to_exr(rgbimg_cfa, file_path)
stat draw rbg(rgbimg cfa)
C:\Users\surface\AppData\Local\Temp\ipykernel 15684\2878482894.py:27:
DeprecationWarning: `np.int` is a deprecated alias for the builtin
`int`. To silence this warning, use `int` by itself. Doing this will not modify any behavior and is safe. When replacing `np.int`, you may
wish to use e.g. `np.int64` or `np.int32` to specify the precision. If
you wish to review your current use, check the release note link for
additional information.
Deprecated in NumPy 1.20; for more details and guidance:
https://numpy.org/devdocs/release/1.20.0-notes.html#deprecations
  if (img.dtype != np.int) and (use float == False):
C:\Users\surface\AppData\Local\Temp\ipykernel 15684\2878482894.py:28:
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```

you wish to review your current use, check the release note link for additional information.

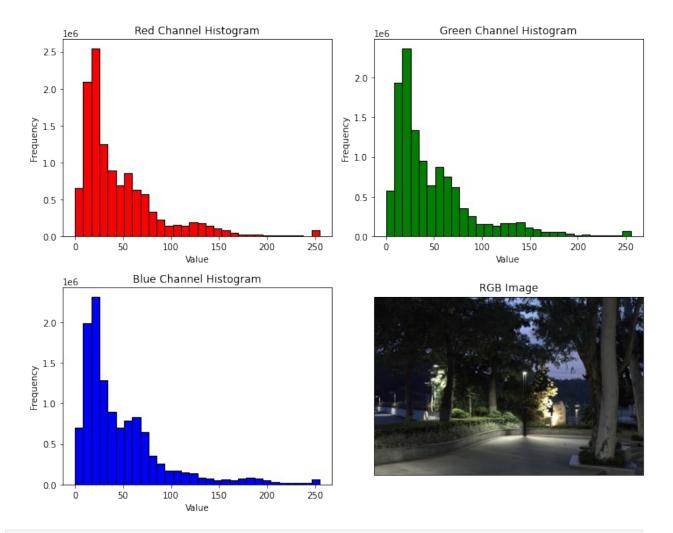
Deprecated in NumPy 1.20; for more details and guidance:

https://numpy.org/devdocs/release/1.20.0-notes.html#deprecations img = img.astype(np.int)

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).



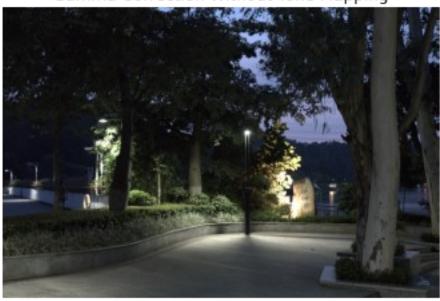
```
plt.title("Gamma Correction Without Tone Mapping")
    plt.axis("off")
    plt.savefig(output dir)
C:\Users\surface\AppData\Local\Temp\ipykernel 15684\2878482894.py:27:
DeprecationWarning: `np.int` is a deprecated alias for the builtin
`int`. To silence this warning, use `int` by itself. Doing this will
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Deprecated in NumPy 1.20; for more details and guidance:
https://numpy.org/devdocs/release/1.20.0-notes.html#deprecations
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C:\Users\surface\AppData\Local\Temp\ipykernel 15684\2878482894.py:28:
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you wish to review your current use, check the release note link for
additional information.
Deprecated in NumPy 1.20; for more details and guidance:
https://numpy.org/devdocs/release/1.20.0-notes.html#deprecations
  img = img.astype(np.int)
```



C:\Users\surface\AppData\Local\Temp\ipykernel\_15684\2046979550.py:8: DeprecationWarning: `np.int` is a deprecated alias for the builtin `int`. To silence this warning, use `int` by itself. Doing this will not modify any behavior and is safe. When replacing `np.int`, you may wish to use e.g. `np.int64` or `np.int32` to specify the precision. If you wish to review your current use, check the release note link for additional information.

Deprecated in NumPy 1.20; for more details and guidance: https://numpy.org/devdocs/release/1.20.0-notes.html#deprecations plt.imshow(gamma\_corrected.astype(np.int))

## Gamma Correction Without Tone Mapping

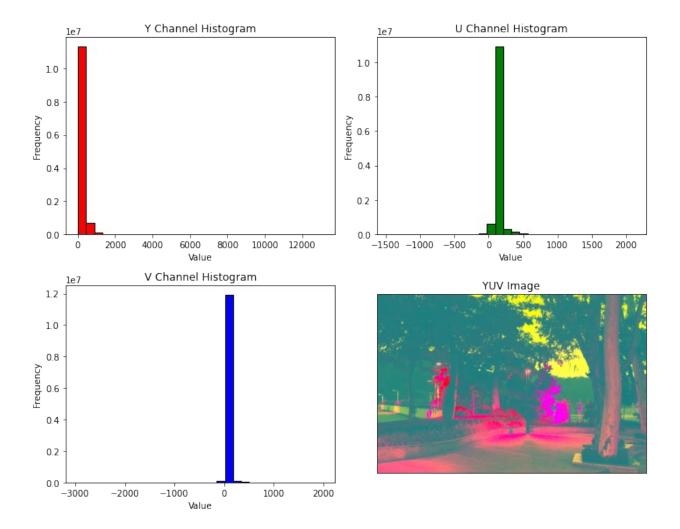


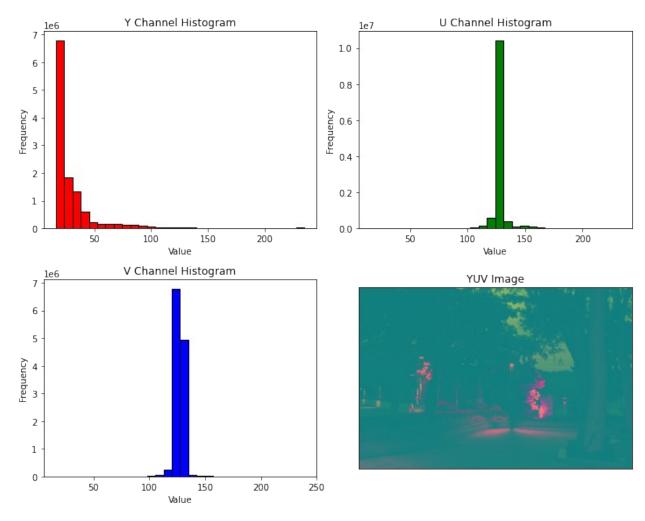
```
YUV = RGB2YUV(rgbimg_cfa)
YUV_norm = RGB2YUV(rgbimg_cfa_norm*255)
stat_draw_yuv(YUV)
stat_draw_yuv(YUV norm)
```

d:\2024\_Spring\DDA4310\TaCode\RGBDomainProcessor.py:67:
VisibleDeprecationWarning: Creating an ndarray from ragged nested
sequences (which is a list-or-tuple of lists-or-tuples-or ndarrays
with different lengths or shapes) is deprecated. If you meant to do
this, you must specify 'dtype=object' when creating the ndarray.
 yuv = mat.dot(np.array([R,G,B,1.0]))

C:\Users\surface\AppData\Local\Temp\ipykernel\_15684\2878482894.py:61: DeprecationWarning: `np.int` is a deprecated alias for the builtin `int`. To silence this warning, use `int` by itself. Doing this will not modify any behavior and is safe. When replacing `np.int`, you may wish to use e.g. `np.int64` or `np.int32` to specify the precision. If you wish to review your current use, check the release note link for additional information.

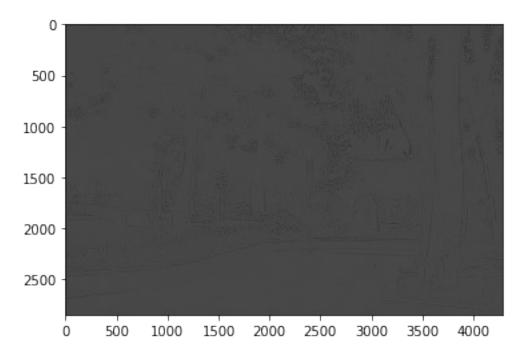
Deprecated in NumPy 1.20; for more details and guidance: https://numpy.org/devdocs/release/1.20.0-notes.html#deprecations if (img.dtype != np.int) and (use\_float == False): Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).



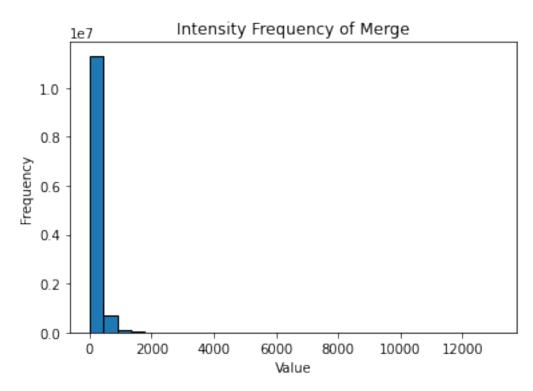


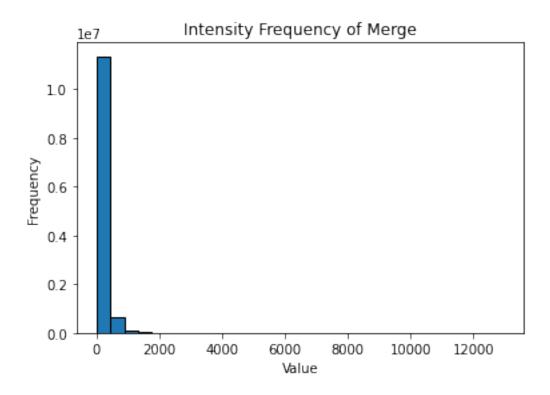
```
def bilateral_filtering(args, img:np.ndarray, sig1, sig2, radius =
15):
    print("range_sigma = ", range_sigma)
print("spatial_sigma = ", spatial_sigma)
    print(type(img), img.dtype)
    img = img.astype(np.float32)
    if args.fast:
        base = cv2.bilateralFilter(img, radius, range sigma,
spatial sigma)
    else:
         radius = 3
        h, w = img.shape[0], img.shape[1]
        img pad = np.pad(img, radius+1)
        print(img pad.shape)
        ys, xs = np.meshgrid(np.arange(h), np.arange(w))
        P = img_pad[ys+radius, xs+radius]
        W = np.zeros_like(img.T)
        base = np.zeros like(img.T)
```

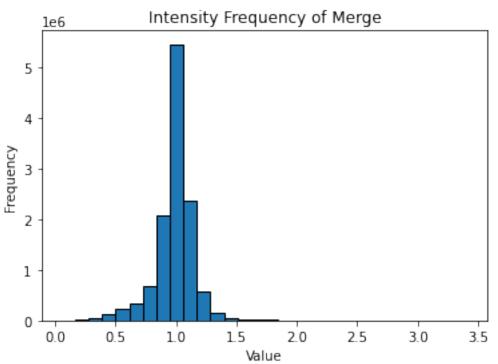
```
for i in tqdm(range(2*radius-1)):
             for j in tqdm(range(2*radius-1)):
                 Q = img pad[ys+i, xs+j]
                 val = P-0
                 gr = \frac{1}{(sig1*np.sqrt(2*np.pi))} * np.exp(-
0.5*(val**2)/(sig1**2))
                 dis = np.sqrt((i-radius)**2+(j-radius)**2)
                 gs = \frac{1}{(sig2*np.sqrt(2*np.pi))} * np.exp(-
0.5*(dis**2)/(sig2**2))
                 grgs = gr*gs
                 base += grgs*Q
                 W += grgs
        base/=W
        base = base.T
    return base
range sigma = 200
width, height, _ = rgbimg_cfa.shape
spatial sigma = 0.02 * min(width, height)
Y = YUV[:, :, 0]
Y base = bilateral filtering(args, Y, range sigma, spatial sigma)
# Y base = fastbilateral2d(Y, range sigma, spatial sigma)
import copy
Y detail = copy.deepcopy(Y)
m = Y base!=0
Y detail[m] = Y[m]/Y base[m]
cv2.imwrite(os.path.join(args.itmd_dir, "Y.jpg"), Y)
cv2.imwrite(os.path.join(args.itmd_dir, "Y_base.jpg"), Y_base)
cv2.imwrite(os.path.join(args.itmd_dir, "Y_detail.jpg"),
normalize(Y detail)*255)
plt.imshow(Y detail, cmap="gray")
range sigma = 200
spatial sigma = 56.96
<class 'numpy.ndarray'> float64
<matplotlib.image.AxesImage at 0x245bb897fd0>
```



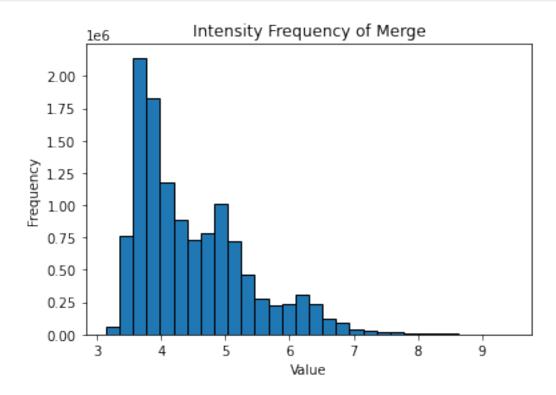
```
stat_draw(Y)
stat_draw(Y_base)
stat_draw(Y_detail)
```

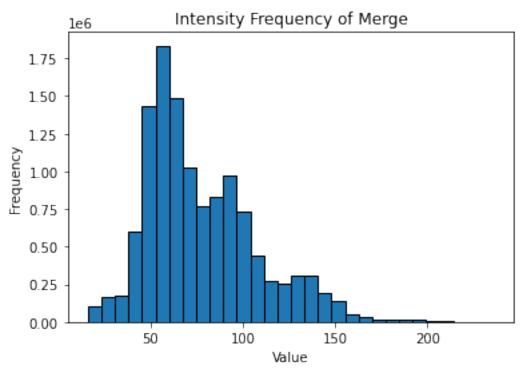






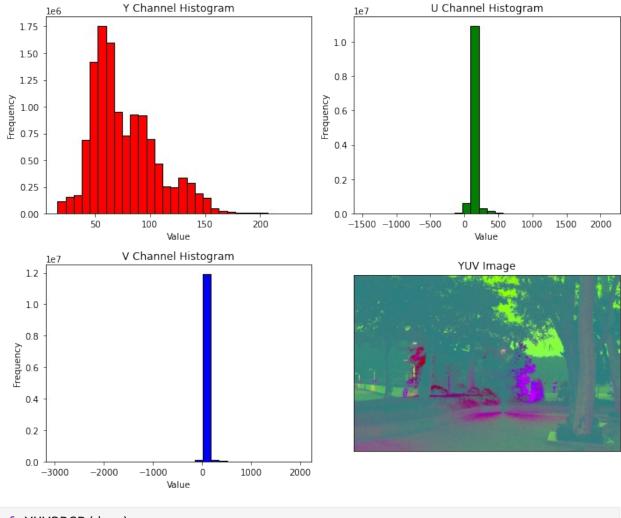
```
Y_base_log = np.clip(np.log(Y_base), 2, 10)
stat_draw(Y_base_log)
Y_new = normalize(normalize(Y_base_log)+normalize(Y_detail))
stat_draw(Y_new*220+16)
```





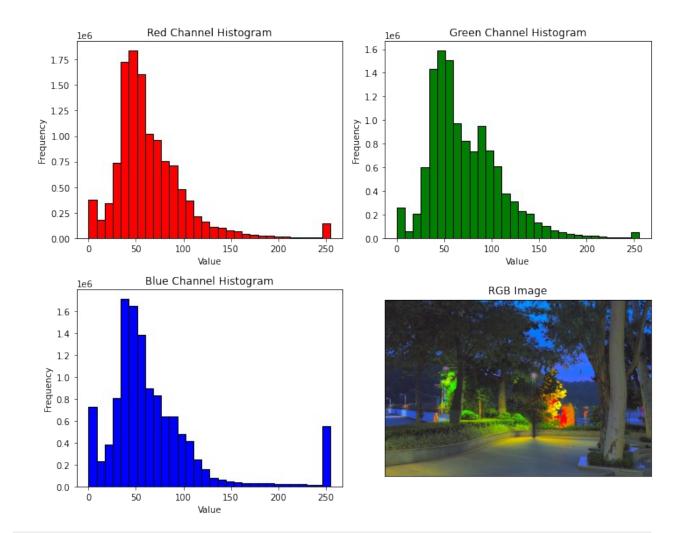
C:\Users\surface\AppData\Local\Temp\ipykernel\_15684\2878482894.py:61: DeprecationWarning: `np.int` is a deprecated alias for the builtin `int`. To silence this warning, use `int` by itself. Doing this will not modify any behavior and is safe. When replacing `np.int`, you may wish to use e.g. `np.int64` or `np.int32` to specify the precision. If you wish to review your current use, check the release note link for additional information.

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```
def YUV2RGB(img):
    Y = img[:,:,0] - 16
    U = img[:,:,1] -128
    V = img[:,:,2] -128
    # your code here
    R = 1.164 * Y + 1.596 * V
```

```
G = 1.164 * Y - 0.392 * U - 0.813 * V
    B = 1.164 * Y + 2.017 * U
    return np.clip(np.stack([R,G,B], axis=2),0,255)
rab new = YUV2RGB(YUV)
stat draw rbg(rgb new)
C:\Users\surface\AppData\Local\Temp\ipykernel 15684\2878482894.py:27:
DeprecationWarning: `np.int` is a deprecated alias for the builtin
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Deprecated in NumPy 1.20; for more details and guidance:
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  img = img.astype(np.int)
```



```
Part 2: YUV Domain Processing
    # Step Luma-2 Edge Enhancement for Luma (20pts)
edge_filter = np.asarray([[-1., 0., -1., 0., -1.], [-1., 0., 8.,
0., -1.], [-1., 0., -1., 0., -1.]
ee_gain, ee_thres, ee_emclip = [32, 128],
                         [32, 64], [-64, 64]
ee = EdgeEnhancement(YUV[:,:,0], edge filter, ee gain, ee thres,
ee emclip)
yuvimg_ee,yuvimg_edgemap = ee.execute()
print(50*'-' + '\n 3.Luma.2 Edge Enhancement Done.....')
(2850, 4292)
3.Luma.2 Edge Enhancement Done.....
```

```
# Step Luma-3 Brightness/Contrast Control (5pts)
brightness, contrast, bcc clip = 0, 0, 255
contrast = contrast / pow(2,5) #[-32,128]
bcc = BrightnessContrastControl(yuvimg ee, brightness, contrast,
bcc clip)
yuvimg_bcc = bcc.execute()
print(50*'-' + '\nBrightness/Contrast Adjustment Done.....')
Brightness/Contrast Adjustment Done.....
# Step Chroma-1 False Color Suppresion (10pts)
fcs_edge, fcs_gain, fcs_intercept, fcs_slope = [32, 32], 32, 2, 3
fcs = FalseColorSuppression(YUV[:,:,1:3], yuvimg edgemap, fcs edge,
fcs gain, fcs intercept, fcs slope)
yuvimg fcs = fcs.execute()
print(50*'-' + '\n 3.Chroma.1 False Color Suppression Done.....')
3.Chroma.1 False Color Suppresion Done.....
# Step Chroma-2 Hue/Saturation control (10pts)
hue, saturation, hsc clip = 128, 256, 255
hsc = HueSaturationControl(yuvimg fcs, hue, saturation, hsc clip)
yuvimg hsc = hsc.execute()
print(\overline{50}*'-' + ' \setminus n \ 3.Chroma.2 \ Hue/Saturation Adjustment Done.....')
3.Chroma.2 Hue/Saturation Adjustment Done.....
# Concate Y UV Channels
vuvimg out = np.zeros like(YUV)
yuvimg out[:,:,0] = yuvimg bcc
yuvimg_out[:,:,1:3] = yuvimg_hsc
RGB = YUV2RGB(yuvimg out) # Pay attention to the bits
stat draw rbg(RGB)
C:\Users\surface\AppData\Local\Temp\ipykernel_15684\2878482894.py:27:
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  if (img.dtype != np.int) and (use_float == False):
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```

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img = img.astype(np.int)

