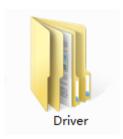
USB-CAN User Manual

1.Install the driver

In the data to see the following folder



Double-click, according to your specific system to install the driver

- driver for USB(232)CAN(FT232)
- driver for USBCAN(CHS40)

2.The USB - CAN insert computer

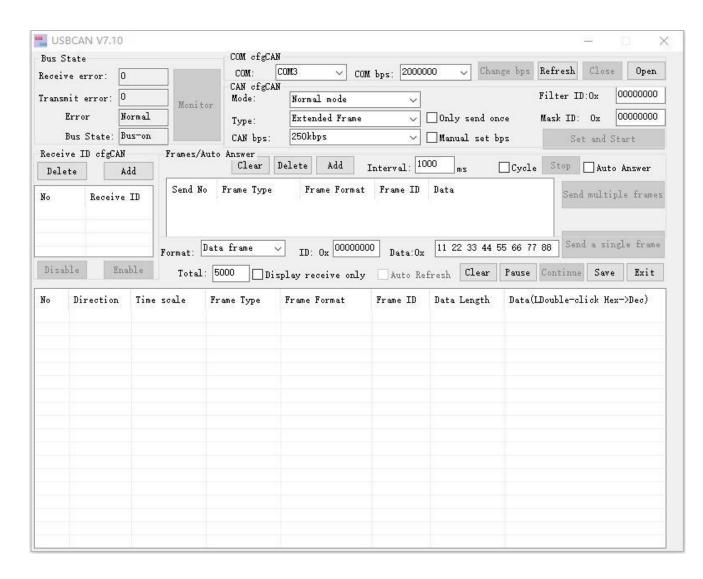
From the device manager see USB - CAN virtual COM port



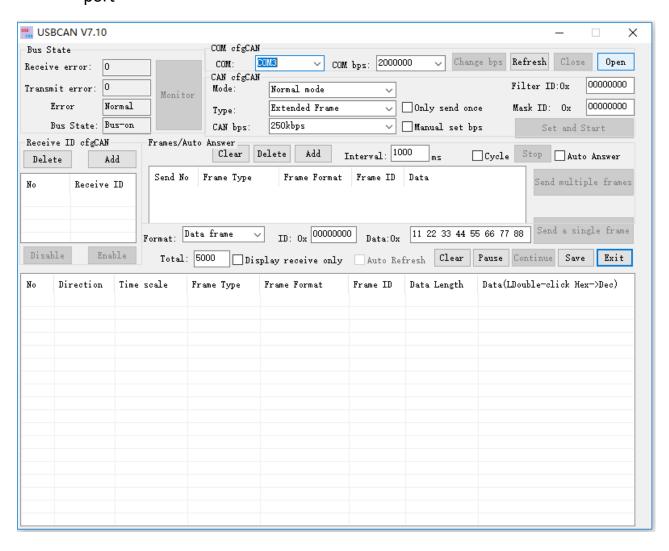
From the device manager see USB(232) - CAN virtual COM port



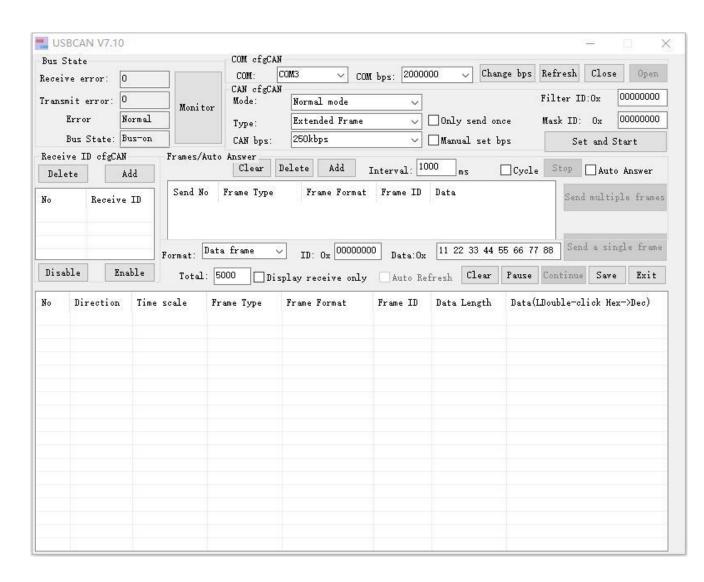
3. Open the USB - CAN software



Click the refresh button, from port right drop-down box choose port



Click on the Open button



According to the CAN bus selecting frame type and set CAN baud rate, point solution set and start button, the CAN bus and the equipment the communication.

4. Software and introduces

4.1 COM Port Settings

COM Configure								
COM:	COM3 ~	COM bps:	2000000		ge bps	Refresh	Close	Open

Will the USB - CAN insert computer, CAN automatic find the computer COM port, choose good port CAN, CAN open or closed port, this with serial debugging assistant similar, communication baud rate is fixed 1228800 BSP.

4.2 CAN Settings



Work patterns include normal mode, Loop back mode, silent mode, Loop back + silent mode

Normal mode: is CAN normal communication model, CAN be normal to the bus to send and receive data

Loop back mode: send data CAN be sent to CAN bus, and at the same

time, feedback internal region of acceptance, ignore accept pin of the actual state and CAN be used for self test

Silent mode: CAN normal accept data, but CAN only send recessive position, and CAN't really send message, often is applied to the analysis of CAN bus activities

Loop back + silent mode: the model can be used for "hot self test", namely online self test. Like a ring back mode that self test, but does not affect the CAN bus system.

Frame type: standard frame (CAN2.0 A 11 ID) extended frame (CAN2.0 B 29 ID)

CAN baud rate: CAN the direct selection CAN communication commonly used baud rate:

1M,800K,500K,400K,250K,200K,125K,100K,50K,20K,10K,5K

f it CAN be directly set the baud rate and you CAN equipment baud rate does not agree, CAN choose

Manual set bps

After the choice will jump out of a custom baud rate dialog box

Moni t	can ciguan Mode:	Normal mode				Filter ID:0x 00000000		
	Type:	Extended Frame	~	Only send	once	Mask ID: 0	000000000	
	CAN bps:	250kbps	~	✓ Manual se	t bps	Set a	and Start	
mes/	Auto Answer Clear De	elete Add In	terval: 1	000 ms	☐ Cycle	Stop	Auto Answer	
end N	o Frame Type	Frame Format	Frame ID	Data		Send m	ultiple frames	
	CAN bps							
	CAN bps=3600000	D/(SYNC_SEG+BP1+BP	2)/Preassig	ned frequency				
at:	CAN bps:	250000	bsp		66 77	88 Send 8	a single frame	
otal	SYNC_SEG:	CAN_SJW_1tq			inze	Continue	Save Exit	
e	BP1:	CAN_BS1_8tq	~	ОК	lata()	LDouble-clic	k Hex->Dec)	
	BP2:	CAN_BS1_7tq	~					
	Preassigned frequ	ency 9						

The top position CAN baud rate calculation formula, and at the same time set phase buffer 1, phase buffer 2, and preassigned frequency is ok

Filter ID and Mask ID: are hexadecimal data filtering the IDs and Mask ID standard frames low 11 (range: 0x00000000 to 0x000007ff) extended frame filter ID and Mask ID 29 (range 0x00000000 to 0x1fffffff)

Only send once: CAN communication is usually send unsuccessful automatic repeat, if have been circulating send data, CAN set banned message automatic repeat



Frame format contains data frames and remote frame, frame ID is

hexadecimal data, the standard frame ID the range of 0 x000000000 $^{\sim}$ 0 x0000007fff, to expand frame ID the range of 0 x00000000 $^{\sim}$ 0 x1fffffff. To send data also for hexadecimal data, map the data in the db x00 0, 0 x01, 0 x02, 0 x03, 0 x04, 0 x05, 0 x06, 0 x07

4.3 Send multiple frames data

Frames/Auto Arewer Clear Dele	te Add Interval: 1000 ms	Cycle Stop Auto Answer
Send No Frame Type	Frame Format Frame ID Data	Send multiple frames Chinese

Add button: in sending multiple frames area will add a send frame data

Delete button: will delete the final article of sending multiple frames area data

Clear button: will clear to send multiple frames area all the data

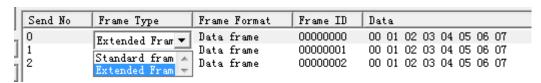
Interval : send multiple frames area connected two frame interval send time

Cycle: send cycle is repeated

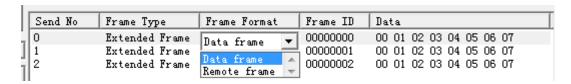
Stop: cancel sending multiple frames command

Data editing in sending multiple frames area editor

Choose frame type



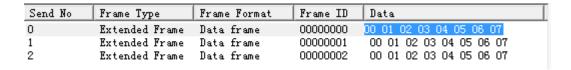
Choose the frame format



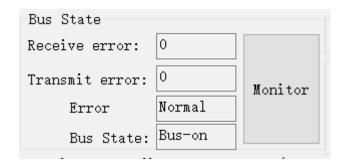
Edit frame ID

Send No	Frame Type	Frame Format	Frame ID	Data
0	Extended Frame	Data frame	00000000	00 01 02 03 04 05 06 07
1	Extended Frame	Data frame	00000001	00 01 02 03 04 05 06 07
2	Extended Frame	Data frame	00000002	00 01 02 03 04 05 06 07

Modification to send data

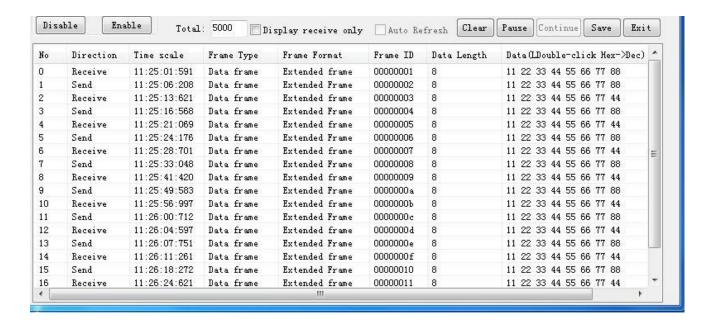


4.4 CAN Bus State



Mainly used in turn CAN see USB device CAN state

4.5 ending and receiving data display area



Clear: empty to send and receive data display so data

Pause: pause in the sending and receiving display area shows that other data

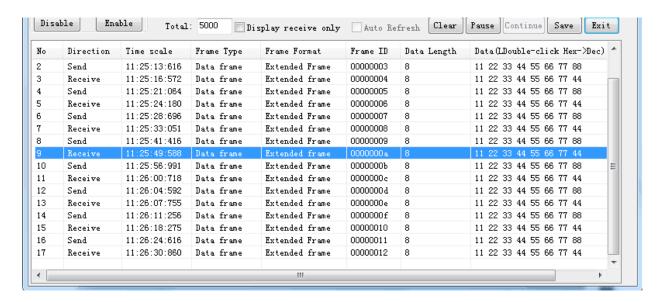
Continue to: continue to show to send and receive data

Save: can send and receive data buffer data storage that can hold two format, excel or TXT text

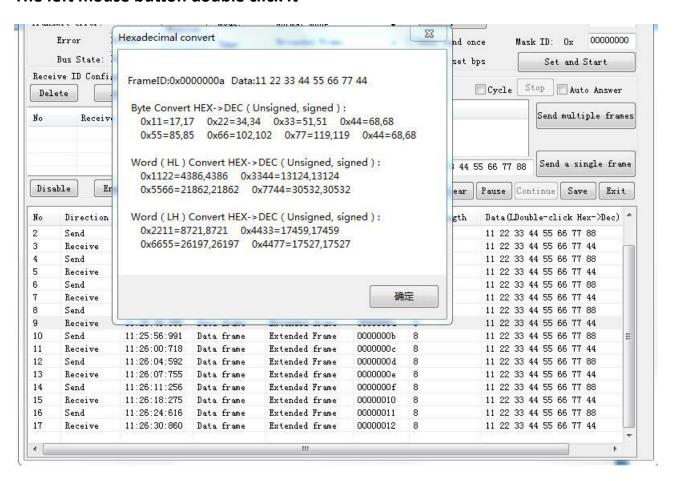
Display receive only: can send and receive data area show only accept data

Auto refresh: when display only accept data, CAN choose to be automatic refresh, this time data are real-time refresh, rather than increasing column display, this function CAN be concluded CAN summarize ID data

Select any line



The left mouse button double click it



5.COM bps select

USB - CAN power on when to send and receive light flash one at the

same time, the COM baud rate to 2000000 BPS, flash two at the same time, the COM baud rate to 1228800 BPS, flash three times at the same time, the COM baud rate to 115200 BPS, flash four at the same time, the corresponding COM baud rate to 38400 BPS, flash five times at the same time, the corresponding COM baud rate to 19200 BPS, flash six at the same time, the corresponding COM baud rate to 9600 BPS