



# OSGi<sup>TM</sup> Alliance

## RFP-195 Actor Runtime

Draft

13 Pages

### Abstract

~~These are the requirements on~~The Actor model is an architectural pattern designed to support high-scale concurrency without the need for locking constructs and with simple memory safety rules. This RFP looks at how to add support for the Actor concurrency model to the OSGi environment. The general direction is to retain the composition of OSGi services as the basic model for creating applications, while at the same time allowing application developers to schedule concurrent execution with an actor runtime, rather than to use threads and locks. This requires that a balanced way is found to mix the blocking parts of the computation as expressed by calling services with the non-blocking parts of the computation as expressed by sending messages between actors. Each type of computation is structured around a modularity construct with different properties – bundles for the blocking and actors for the non-blocking. ~~Perhaps the middle-ground lies with a type of “actor service” which communicates through messages rather than method calls.~~

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# 0 Document Information

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## 0.3 Feedback

This document can be downloaded from the OSGi Alliance design repository at <https://github.com/osgi/design>. The public can provide feedback about this document by opening a bug at <https://www.osgi.org/bugzilla/>.

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## 0.5 Terminology and Document Conventions

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "NOT RECOMMENDED", "MAY" and "OPTIONAL" in this document are to be interpreted as described in 6.1.

Source code is shown in this typeface.

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## 0.6 Revision History

The last named individual in this history is currently responsible for this document.

Revision	Date	Comments
Initial	Apr 16 2019	Todor Boev: Initial draft based largely on research in integrating Akka with OSGi services.
0.1	May 9 2019	Todor Boev: Numerous clarifications and updates. Added requirement numbers.
0.2	May 21 2019	Todor Boev: Substantially improved the persistence section, clarified the "ask" pattern
<u>0.3</u>	<u>May 21 2019</u>	<u>Tim Ward: Updates to fill out the RFP ahead of discussions at the Face to Face meeting</u>

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# 1 Introduction

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Software built using OSGi technology is primarily based around interactions between services published by OSGi bundles. These services are Java Objects, and therefore typically use a synchronous, blocking invocation model (as is common throughout Java). Service Objects may be called concurrently from many threads in many bundles, and therefore it is critical that services are thread-safe.

Writing thread-safe services is simple if the services are stateless, however if the service does have internal state then access to it must be protected correctly. This can quickly become difficult to manage, and result in a service object which is difficult to maintain. In some cases these stateful services could be implemented much more simply using the Actor Model. This RFP began as an investigation into the possibility of using the Actor model inside OSGi as a simpler way to handle concurrency for some types of OSGi services, especially those representing external devices.

Initial research was carried out using the Akka framework, however the intent of this RFP is to explore actors generally, and not a specific implementation.

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## 2 Application Domain

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Today's software needs to be highly concurrent for several reasons. On one hand concurrent programs can make efficient use of all processor cores available to them. In this way concurrent programs can scale through parallelism. This is critical since for many years the only way to increase computational power is to add more cores or more machines rather than to make faster cores. On the other hand a lot of the software today needs to operate in real world conditions where it faces unpredictable concurrent events coming from the environment much like humans do. These two forces combine to create the need for software that can use efficiently all computational resources available to execute as quickly as possible reactions to concurrently occurring events.

One proven way to build software that can handle such conditions is the Actor model of computation. On the JVM the most prominent implementation of this model is the Akka framework based on the Scala programming language. Outside the JVM the most prominent implementation of actors is the Erlang programming language and libraries and it's underlying runtime.

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### 2.1 Terminology + Abbreviations

- **Message:** a data structure (DTO) which is considered immutable.
- **Behavior:** a functional object, which receives a message and returns a new behavior. Useful work is performed as side effects during the function call. State is passed from one behavior by enclosing it in the next behavior.
- **Actor:** an abstract container that manages the sequential atomic processing of messages by an unfolding chain of behaviors. The actor uses each behavior to processes one message and then replaces it with the next behavior.
- **Actor address:** an immutable identifier of an actor. Each actor has at least one address. The only way to send a message to an actor is to sent it to it's address. Actors can send messages to their own address.
- **Asynchronous message delivery:** sending a message does not return a value and does not block behavior execution (fire and forget).
- **At-most-once message delivery:** once sent a message can be delivered to the recipient zero or one time.
- **Supervisor:** an actor that decides how to handle failures in one or more other actors. Each actor has zero or one supervisor.
- **Supervisor hierarchy:** the tree formed by traversing the supervisor relationships between all actors.
- **Supervisor strategy:** a function specified by the supervisor that is called to make a decision on what to do with a failed child. E.g. the function can return a signal "restart" to cause the failed child to be reset to it's initial behavior and continue processing.
- **Actor runtime:** the engine which drives the concurrent execution of a large number of actors

## 3 Problem Description

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As all other applications OSGi programs increasingly need to be deployed in real world conditions where the primary model of interaction is through large numbers of concurrent events coming over network interfaces or other asynchronous and unreliable channels.

Up until now we have addressed these conditions with concurrency primitives like Promises and PushStreams. These models however are functional in nature and do not model well concurrently changing state. At present we model dynamic state with services and service events. While this model has proven to be an effective way to structure an application the communication between the stateful services is still done through regular method calls done on multiple threads and protected by locks. These concurrency mechanisms have proven extremely hard to get right on one machine let alone in a distributed environment. There is a need for a more robust communication mechanism between services. One alternative to blocking method calls is asynchronous message passing. Introducing this communication mechanism should complement Promises and PushStreams to give OSGi an all-round ability to handle highly concurrent loads.

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## 4 Use Cases

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The IoT “Digital Twin” model is implemented by providing a virtual representation of a real physical device. Users interact with the virtual representation of the device, with the state of the digital twin being synchronized with the physical device. By necessity a digital twin must contain a significant amount of internal state, and it is vital that the internal state remain consistent, even when a large number of users are competing for access to the digital twin. Implementing the digital twin using the actor model can greatly simplify the state machine representing the allowed actions and behaviours of the digital twin. This pattern is being used to help build automated factories and modular manufacturing pipelines.[3].

As OSGi is often used in industrial embedded control systems it would therefore be beneficial for an OSGi developer to implement a digital twin using the Actor Model, restricting access to the Digital Twin so that it can be implemented simply, while still remaining able to access OSGi services provided by other bundles from inside the Actor.

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# 5 Requirements

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The requirements describe the minimal viable actor system. Even though a lot of requirements go beyond the minimal actor execution model they are nevertheless needed to implement practical actor applications.

Still it is highly preferable to use existing OSGi specifications to support as many of the requirements as possible. E.g. Promises are a great candidate to support any interactions of actors with non-actor services. The goal is to have an OSGi system extended with the actor programming model, rather than other way around.

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## 5.1 Execution model

This is simply a generic actor execution model not related to OSGi

- **Exec 1:** The actor runtime **must** provide at least one address for each actor
- **Exec 2:** The actor runtime **must** store behaviors as (functional) objects/closures
  - So that they can capture state by closing over effectively-final variables visible in their lexical scope.
- **Exec 3:** The actor runtime **must** guarantee that at all times an actor is associated with exactly one behavior
  - This also implies an actor is atomically initialized with a behavior upon creation
- **Exec 4:** An actor **must** have a way to access it's own address (self) from it's behavior
- **Exec 5:** An actor behavior **must** have a way to send messages to an actor address it has access to
  - Behaviors close over effectively-final actor addresses like any other piece of state.
- **Exec 6:** The actor runtime **must** guarantee asynchronous message delivery.
  - Behavior code **must** not block waiting for the message to be processed by the recipient.
- **Exec 7:** The actor runtime **must** guarantee "at-most-once" message delivery.
  - While it is allowed for messages to not be delivered it is not allowed for the same message to be delivered twice.
- **Exec 8:** It **must** be possible for messages to contain addresses of actors.
- **Exec 9:** An actor **must** process messages only in sequential atomic steps. At each step the actor first calls it's current behavior with the current message and gets back a new behavior. Then the actor replaces it's current behavior with that new behavior.
  - Therefore an actor maintains a continuation passing style of execution driven by messages.

- It is permissible to execute each step on a different thread (e.g. from a pool), but it is not under any conditions permissible for two or more threads to execute steps concurrently. *Violating this principle renders the actor system unusable.*
- This still allows users to have a mutable behavior object, which always returns itself, thus enabling an “object oriented” style of actor.
- **Exec 10:** The actor runtime **must** not deliver messages to a behavior which is no longer current for an actor
- **Exec 11:** It **must** be possible for a behavior to return a value which signals no more messages should be processed. After this happens the actor runtime must stop delivering messages to the actor and perform any post-death actions (see supervision and “death watch”) below.
- **Exec 12:** An actor behavior **must** have a way to create a new actor by specifying an initial behavior for that actor. The creation call must return **synchronously** the address of the new actor.
- Exec 13: Messages exchanged by Actors **must** support type-safe data access. It is not acceptable for the programming model to provide only Map as an exchange type.

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## 5.2 Error handling

- **Err 1:** Each actor must have exactly one supervisor. The supervisor is always the actor who created the supervised (child) actor.
- **Err 2:** The supervisor is established once during actor creation and can not be changed subsequently.
- **Err 3:** There must be exactly one root actor which has no supervisor.
- **Err 4:** There must be a way for a behavior to specify a supervisor strategy function when it creates a child actor.
- **Err 5:** An actor must process the errors of it's children sequentially as special messages within the regular message stream. The difference is that the error message is delivered to the parent's supervisor strategy function rather than to the parent's behavior.
  - The definition of an actor is thus expanded to include not just the current behavior function, but also the set of supervisor strategy functions it has attached to it's children. Each member function of the actor processes the next message (error or regular respectively) as appropriate. No message is processed by more than one member function.
- **Err 6:** The following return values from the supervisor strategy function must be supported:
  - **resume:** the failed actor retains it's behavior. It then proceeds to process the next message.
  - **reset:** the failed actor is reset to the behavior with which it was created. It will then proceed to process the next message.
  - **stop:** the failed actor is stopped. It can no longer process messages and is garbage collected.
  - **escalate:** the supervising actor is stopped. The error is propagated up the hierarchy to it's supervisor.
- **Err 7:** When a supervisor is stopped all of it's children are stopped first.



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## 5.3 Core capabilities

Not part of the core execution model, hard or impossible to implemented on top of the core execution model, so must be supported by the actor runtime instead.

- **Core 1:** Message ordering. Sender and receiver observe the same message order
- **Core 2:** Death watch: an actor can register an address in order to receive a message signifying that the actor referenced by this address has died.
  - This allows actors to clean invalid addresses they have
  - This allows actors to stop when the other actor was critical to their function, even though they are not it's supervisor
- **Core 3:** Message buffering. The actor runtime must be able to buffer (rather than drop) messages sent to an address while the actor targeted by the message executes it's current behavior.
- **Core 4:** Scheduled message delivery. It must be possible for an actor to schedule one-shot or periodic delivery of a message to an arbitrary address (including "self") with a given time interval.
- **Core 5:** Pub/Sub message delivery. The actor runtime should provide a global pub/sub subsystem where actors can subscribe for messages of a given type and respectively post messages.
- **Core 6 (?)**: Dead letters: subscribe to messages sent to addresses of dead actors
- **Core 7:** Logging: the actor runtime must provide behaviors with a logger that does not block execution until the log is fully processed (e.g. committed to a file or printed on the console)

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## 5.4 Core patterns

Can be implemented on top of the core execution model and capabilities as utilities, base classes, etc. or if preferable can be built into the actor runtime.

- **Pat 1:** Message deconstruction: something to help with pattern matching
- **Pat 2:** "Ask" (Request/Response) message exchange
  - Actor sends a request and starts a timer to send a failure message to "self".
  - If response arrives before the failure message the failure message is ignored.
  - If response arrives after failure message the response is ignored.
  - Similar to a Promise: the failure message and the response message race to resolve the promise. Once resolved no further updates can take effect.
- **Pat 3:** "At-least-once" message delivery: requires message equality, receiver acknowledges messages, sender tracks outgoing messages (to resend unacknowledged)
  - The tracking of acknowledgments may be supported by persistence (see the Persistence section)

- **Pat 4:** “Exactly-once” message delivery: requires message equality, receiver acknowledges messages, sender tracks outgoing messages (to resend unacknowledged), receiver tracks incoming messages (to ignore repeats)
  - The tracking of acknowledgments and duplicates may be supported by persistence (see the Persistence section)

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## 5.5 OSGi integration

- **Int 1:** As a general rule actors should be treated more as a concurrency model, rather than as the default programming model. The structure of the program should be expressed first as standard OSGi service composition as much as possible (e.g. DS components). Then some services may have message oriented APIs and run actors to support them.
- **Int 2:** As a general rule all communication from the external world to the actor system **must** be asynchronous.
  - In practice this means external parties should be able to send messages to an address provided by the actor system, just like regular actors do.
- **Int 3:** As a general rule all communication from the actor system to the external world **should** be asynchronous.
  - In practice this means actors should wrap calls to the outside world in Promises, which once resolved send messages back to “self” as a regular external party (**Int 2**). The Promises should be scheduled on threads that do not drive the actor message delivery (bulk-heading).
- **Int 4:** It **must** be possible to initialize behaviors with arbitrary OSGi services prior to the first message being processed.
- **Int 5:** It **must** be possible to initialize behaviors with configuration provided by the Configuration Admin prior to the first message being processed
- **Int 6:** It **must** be possible to stop any actor when it’s configuration or a service dependency goes away
  - This **must** happen asynchronously via messages or other native actor mechanisms (death watch).
  - Still the actor **must** be prevented from calling stale services even though it will observe the service unregistration after the fact due to asynchrony. Since the actor should call the service through Promises as per **Int 2** one way is to fail those Promises immediately and let the actor run into the failure later within it’s regular message flow.
- **Int 7:** It **should** be possible for supervisors to specify an “escalate” strategy when a child starts to fail because of an unbound service / configuration.
  - In practice this means there must be a dedicated exception or error message to which the supervisor strategy function can react.
- **Int 8:** It **must** be possible for any bundle to call the actor system to discover actor addresses
- **Int 9:** It **must** be possible for any bundle to send a message to an actor address asynchronously

- **Int 10:** It **must** be possible for any bundle to do an asynchronous request/response exchange with an actor
  - In practice this means the external party uses the “ask” pattern (**Pat 2**).
- **Int 11:** It **must** be possible for any bundle to subscribe to messages or to publish messages
- **Int 12:** It **must** be possible for a bundle to create an actor and receive back it's address

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## 5.6 Persistence

Although actors can implement persistence by calling standard OSGi service, it will be hard for developers to implement a behavior that guarantees consistency on one hand, but does not block on the other (e.g. for transactions).

This is why it is preferable that a safe behavior is supported directly by the actor system or as a core pattern. In practice the pattern is likely to be implemented by instantiating a small system of actors.

- **Pers 1:** An actor **must** be able to receive, examine and update a persistent state object during message processing
- **Pers 2:** It **must** be possible to identify an actor's persistent state across system reboots
- **Pers 3:** It **must** be possible to initialize an actor not only with a behavior, but with initial state.
- **Pers 4:** It **must** be possible for a behavior to request commit to storage before it executes any side effects (creating actors, sending messages)
  - One would expect applying persistence to cause messages to be handled as follows:
    - *(behavior) examine message and state →*
    - *(behavior) execute side effects →*
    - *(behavior) build new state →*
    - *(system) commit new state to storage*
    - In this case it is possible for the actor to first affect the runtime state of the system, then for the system to crash before the state is committed. The system can't be recovered to a state that reflects what the actor has done.
  - Instead applying persistence **must** cause messages to be handled as follows:
    - *(behavior) examine message and state →*
    - *(behavior) build new state →*
    - *(system) commit new state to storage →*
    - *(behavior) execute side effects*

- In this case if the system crashes during commit one message will be lost, but the last committed state will remain valid since nothing else was done. On the other hand if the system crashes right after commit, but before the side effects, once recovered the actor can re-run the side effects based on the last stored state.
- The pattern implies the behavior function should be split into two sub-functions:
  - “command handler” with signature: *(message, state) → state*
  - “effects handler” with signature: *state → void*
- A message is then processed as follows:
  - Call “command handler” with *(message, current-state)* and get *next-state*
  - Commit *next-state* to storage
  - Call the “effects handler” with *next-state* to execute any runtime effects
  - Return a next Behavior which encloses *next-state, command handler, effects handler*
- “Commit *next-state*”, **must** be executed asynchronously
- Any messages that arrive while the actor is in the “Commit *next-state*” **must** be buffered (**Core 3**) until the entire sequence is completed
- **Pers 5:** It must be possible to re-run the behavior side effects when an actor is loaded from storage
  - I.e. run the “*effects handler*” from **Pers 4** on actor recovery.

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## 5.7 Clustering

This is needed to implement classic actor “distributed applications”, where the same tightly coupled code base is split across many VMs, specialized protocols to move messages between VMs are used, dedicated cluster discovery is used.

This is not needed to implement “distributed systems”, consisting of multiple (not one) loosely coupled applications talking through generic protocols (e.g. REST, gRPC, MQTT).

This is why this section should be considered optional.

- **Clust 1:** Provide a way to send messages to a remote actor address
- **Clust 2:** Provide a way to discover a remote or local actor address
  - I.e. call the system with some search query and get back an actor address.
- **Clust 3(?):** Use the RSA to distribute actor services

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# 6 Document Support

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## 6.1 References

- [1]. Bradner, S., Key words for use in RFCs to Indicate Requirement Levels, RFC2119, March 1997.
- [2]. Software Requirements & Specifications. Michael Jackson. ISBN 0-201-87712-0
- [3]. [Digital Twin: Manufacturing Excellence through Virtual Factory Replication. Dr Michael Griev.es.](https://research.fit.edu/media/site-specific/researchfitedu/camid/documents/1411.0_Digital_Twin_White_Paper_Dr_Griev.es.pdf)  
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## 6.2 Author's Address

Name	Todor Boev
Company	Software AG
Address	
Voice	
e-mail	<a href="mailto:todor.boev@softwareag.com">todor.boev@softwareag.com</a>

<a href="#">Name</a>	<a href="#">Tim Ward</a>
<a href="#">Company</a>	<a href="#">Paremus Ltd</a>
<a href="#">Address</a>	
<a href="#">Voice</a>	
<a href="#">e-mail</a>	<a href="mailto:tim.ward@paremus.com">tim.ward@paremus.com</a>

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