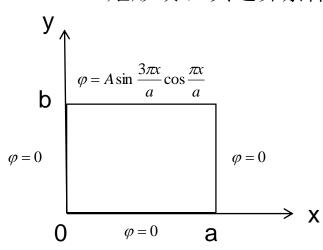
#### 解法类似教材P83,例3-4

## 分离变量法求解方法

3-19 一矩形域, 其边界条件如图所示, 求此域内的电位解(其中电位满足拉普拉斯方程)



$$\begin{cases}
\nabla^2 \varphi = \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0 & (1) \\
\varphi(x,0) = 0 & (2) \\
\varphi(x,b) = A \sin \frac{3\pi x}{a} \cos \frac{\pi x}{a} & (3) \\
\varphi(0,y) = 0 & (4)
\end{cases}$$

$$\varphi(0,y) = 0 \qquad a \qquad (4)$$

$$\varphi(a,y) = 0 \tag{5}$$

第二步:利用分离变量法和电位方程(1)给出电位的形式解

将
$$\varphi(x,y)=X(x)Y(y)$$
代入(1),再方程两边同除以 $\varphi(x,y)$ , 得

$$\frac{X''(x)}{X(x)} + \frac{Y''(y)}{Y(y)} = 0$$

$$\frac{k_1^2 = k_2^2 = 0}{k_1^2 > 0, k_2^2 < 0} \Rightarrow \frac{X''(x)}{X(x)} = -k_1^2, \frac{Y''(y)}{Y(y)} = -k_2^2, \text{ fix}_1^2 = -k_2^2$$

$$\varphi(x, y) = (C_1 \sin k_1 x + C_2 \cos k_1 x)(D_1 \sinh k_1 y + D_2 \cosh k_1 y)$$

曲边界条件(4)、(5)知电位沿x方向要求有重复零点,

X(x)取三角函数, Y(y)取双曲函数,  $k_1^2 > 0, k_2^2 < 0$ X(x)取双曲函数, Y(y)取三角函数,  $k_1^2 < 0, k_2^2 > 0$ 

查教材P82, 表3-1可得/ppt ch3 p60

X(x)、Y(y)取常数或线性函数,

X(x)取三角函数,Y(y)取双曲函数,得出电位形式解

$$f'' + k_x^2 f = 0$$
  $\Longrightarrow f(x) = Ae^{-jk_x x} + Be^{jk_x x}$ 

x-方向齐次 k <sub>x</sub> <sup>2</sup> >0, k <sub>x</sub> 为实数	$x$ -方向非齐次 $k_x^2 \le 0, k_x$ 为虚数	
$\int \sin k_x x$	$\begin{bmatrix} k_x^2 = 0 \end{bmatrix} \left\{ \begin{array}{c} x \\ 1 \end{array} \right.$	
$\begin{cases} \sin k_x x \\ \cos k_x x \end{cases}$	$\begin{vmatrix} k_x^2 \neq 0 \\ \cosh k_x \mid x \\ \cosh k_x \mid x \end{vmatrix}$	取e <sup>±k,l</sup> x 及其组合(sinh,cosh)

---齐次方向:

选择振荡型函数

--非齐次方向:

'第三步: 利用边界条件确定电位的形式解中的未知系数

由边界条件(4)知
$$C_2 = 0, \varphi(x, y)$$
简化为

$$\varphi(x,y) = (C_1 \sin k_1 x)(D_1 shk_1 y + D_2 chk_1 y)$$

由边界条件(5)知
$$k_1 = \frac{n\pi}{a} (n = 1, 2, 3, ...)$$

由边界条件(2)知
$$\varphi(x,0) = \sum_{n=1}^{\infty} \left( C_n \sin \frac{n\pi}{a} x \right) (D_{1n} sh0 + D_{2n} ch0) = \sum_{n=1}^{\infty} \left( C_n \sin \frac{n\pi}{a} x \right) (D_{2n}) = 0$$

$$D_{2n} = 0, \varphi(x, y) = \sum_{n=1}^{\infty} \left( C_n \sin \frac{n\pi}{a} x \right) \left( D_{1n} sh \frac{n\pi}{a} y \right)$$

由边界条件(3)知 $\varphi(x,y) = \sum_{n=1}^{\infty} \left( C_n \sin \frac{n\pi}{a} x \right) \left( D_{1n} sh \frac{n\pi}{a} b \right) = A \sin \frac{3\pi x}{a} \cos \frac{\pi x}{a} = A \frac{\sin \frac{4\pi x}{a} + \sin \frac{2\pi x}{a}}{2} \longrightarrow = \frac{1}{2} \left[ \sin (\alpha + \beta) + \sin (\alpha - \beta) \right]$ 

 $\sin \alpha \sin \beta$ 

令 $C_nD_n = A_n$ ,方程两边对应系数相等,得

$$A_{2} = \frac{A}{2sh\frac{2\pi b}{a}}, A_{4} = \frac{A}{2sh\frac{4\pi b}{a}}, A_{n} = 0 (n \neq 2, 4), \varphi(x, y) = \frac{A}{2sh\frac{2\pi b}{a}} \sin \frac{2\pi x}{a} sh \frac{2\pi y}{a} + \frac{A}{2sh\frac{4\pi b}{a}} \sin \frac{4\pi x}{a} sh \frac{4\pi y}{a}$$

# 第一章作业

1 求 $\nabla' \frac{e^{-jkR}}{R}$ 

$$\nabla [f(u)] = f'(u) \nabla u \qquad (ppt ch1 p73)$$

$$\nabla' \frac{e^{-jkR}}{R} = -\nabla \frac{e^{-jkR}}{R} = -\left[\nabla e^{-jkR} \cdot \frac{1}{R} + e^{-jkR} \cdot \nabla \frac{1}{R}\right]$$

$$= -\left[-jke^{-jkR}\nabla R \cdot \frac{1}{R} + e^{-jkR} \cdot \nabla \frac{1}{R}\right]$$

$$= -\left[-jke^{-jkR}\hat{R} \cdot \frac{1}{R} + e^{-jkR} \cdot \left(-\frac{\hat{R}}{R^2}\right)\right]$$

$$= \frac{\left(jkR+1\right)e^{-jkR}\hat{R}}{R^2}$$

$$\nabla'R = \frac{\partial R}{\partial x'}\hat{\mathbf{x}} + \frac{\partial R}{\partial y'}\hat{\mathbf{y}} + \frac{\partial R}{\partial z'}\hat{\mathbf{z}} = \frac{-2(x-x')}{2R}\hat{\mathbf{x}} + \frac{-2(y-y')}{2R}\hat{\mathbf{y}} + \frac{-2(z-z')}{2R}\hat{\mathbf{z}} = \frac{-\vec{R}}{R}$$

$$\nabla(\nabla \cdot \vec{A}) = \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial x \partial y} + \frac{\partial^2 A_z}{\partial z \partial x}\right)\hat{\mathbf{x}}$$

$$\nabla R = -\nabla'R = \frac{\vec{R}}{R}, \nabla \frac{1}{R} = -\frac{\nabla R}{R^2} = -\frac{\vec{R}}{R^3}$$

$$+ \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y \partial z}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y \partial z}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y \partial z}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} + \left(\frac{\partial^2 A_x}{\partial y^2} + \frac{\partial^2 A_z}{\partial y^2}\right)\hat{\mathbf{y}} +$$

# (ppt ch1 p72)

**2** 证明
$$\nabla \times \nabla \times \vec{A} = \nabla \nabla \cdot \vec{A} - \nabla^2 \vec{A}$$

$$\nabla \times \vec{A} = \begin{vmatrix} x & y & z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \left( \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \hat{x} + \left( \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \hat{y} + \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{z}$$

$$\pm i \underline{\partial} = \nabla \times \nabla \times \vec{A} = \left( \frac{\partial^2 A_y}{\partial y \partial x} - \frac{\partial^2 A_x}{\partial y^2} - \frac{\partial^2 A_x}{\partial z^2} + \frac{\partial^2 A_z}{\partial z \partial x} \right) \hat{x}$$

$$- \left( \frac{\partial^2 A_y}{\partial x^2} - \frac{\partial^2 A_y}{\partial x \partial y} - \frac{\partial^2 A_z}{\partial y \partial z} + \frac{\partial^2 A_y}{\partial z^2} \right) \hat{y} + \left( \frac{\partial^2 A_x}{\partial x \partial z} - \frac{\partial^2 A_z}{\partial x^2} - \frac{\partial^2 A_z}{\partial y^2} + \frac{\partial^2 A_y}{\partial y \partial z} \right) \hat{z}$$

$$\nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$\nabla \left( \nabla \cdot \vec{A} \right) = \left( \frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial x \partial y} + \frac{\partial^2 A_z}{\partial z \partial x} \right) \hat{x}$$

$$+ \left( \frac{\partial^2 A_x}{\partial x \partial y} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y \partial z} \right) \hat{y} + \left( \frac{\partial^2 A_x}{\partial x \partial y} + \frac{\partial^2 A_z}{\partial z \partial x} \right) \hat{z}$$

$$\nabla^{2}\vec{A} = \nabla \bullet \nabla \vec{A} = \frac{\partial^{2}\vec{A}}{\partial x^{2}} + \frac{\partial^{2}\vec{A}}{\partial y^{2}} + \frac{\partial^{2}\vec{A}}{\partial z^{2}}$$

$$= \left(\frac{\partial^{2}A_{x}}{\partial x^{2}} + \frac{\partial^{2}A_{x}}{\partial y^{2}} + \frac{\partial^{2}A_{x}}{\partial z^{2}}\right)\hat{\mathbf{x}} + \left(\frac{\partial^{2}A_{y}}{\partial x^{2}} + \frac{\partial^{2}A_{y}}{\partial y^{2}} + \frac{\partial^{2}A_{y}}{\partial z^{2}}\right)\hat{\mathbf{y}} + \left(\frac{\partial^{2}A_{z}}{\partial x^{2}} + \frac{\partial^{2}A_{z}}{\partial y^{2}} + \frac{\partial^{2}A_{z}}{\partial z^{2}}\right)\hat{z}$$

右边=
$$\nabla \nabla \bullet \vec{A} - \nabla^2 \vec{A} = \left( \frac{\partial^2 A_y}{\partial y \partial x} - \frac{\partial^2 A_z}{\partial y^2} - \frac{\partial^2 A_x}{\partial z^2} + \frac{\partial^2 A_z}{\partial z \partial x} \right) \hat{x}$$

$$- \left( \frac{\partial^2 A_y}{\partial x^2} - \frac{\partial^2 A_y}{\partial x \partial y} - \frac{\partial^2 A_z}{\partial y \partial z} + \frac{\partial^2 A_y}{\partial z^2} \right) \hat{y} + \left( \frac{\partial^2 A_x}{\partial x \partial z} - \frac{\partial^2 A_z}{\partial x^2} - \frac{\partial^2 A_z}{\partial y^2} + \frac{\partial^2 A_y}{\partial y \partial z} \right) \hat{z} = \pm \dot{z} \dot{z}$$
即证明成立

3 若有 $\phi(\overline{r}) = \frac{1}{4\pi\varepsilon} \iiint_{V} \frac{\rho(\overline{r'})}{|\overline{r} - \overline{r'}|} dV'$ ,求 $\overline{E} = -\nabla \phi = ?$ 

$$\vec{E} = -\nabla \left( \frac{1}{4\pi\varepsilon_0} \iiint_{\nu} \frac{\rho(\vec{r'})}{R} dV' \right) \qquad \vec{E} = -\nabla \rho \qquad \varphi(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \iiint_{\nu} \frac{\rho(\vec{r'})}{|\vec{r} - \vec{r'}|} dV'$$

$$= -\frac{1}{4\pi\varepsilon_0} \iiint_{\nu} \rho(\vec{r'}) \nabla \frac{1}{R} dV' \qquad \nabla \frac{1}{R} = -\frac{\hat{R}}{R^2} \qquad \frac{\frac{1}{R} + \frac{1}{R} + \frac{1}{R$$

$$\vec{E} = -\nabla \phi = \frac{1}{4\pi\varepsilon} \iiint_{v} \frac{\rho(\vec{r}')}{R^{3}} \vec{R} dv'$$

**4** 证明
$$\nabla \times \nabla \times (\varphi \vec{A}) = \nabla \varphi \times (\nabla \times \vec{A}) - \vec{A} \nabla^2 \varphi + (\vec{A} \cdot \nabla) \nabla \varphi + \varphi \nabla \times (\nabla \times \vec{A}) + (\nabla \varphi) \nabla \cdot \vec{A} - (\nabla \varphi \cdot \nabla) \vec{A}$$

$$\nabla \times \nabla \times (\varphi \vec{A}) = \nabla \times (\varphi(\nabla \times \vec{A}) + \nabla \varphi \times \vec{A}) = \nabla \times (\varphi(\nabla \times \vec{A})) + \nabla \times \nabla \varphi \times \vec{A} (使用公式 (1-49))$$
 (1)

$$\nabla \times (\varphi(\nabla \times \vec{A})) = \varphi(\nabla \times \nabla \times \vec{A}) + \nabla \varphi \times (\nabla \times \vec{A}) (使用公式 (1-49))$$
 (2)

$$\nabla \times \nabla \varphi \times \vec{A} = (\vec{A} \cdot \nabla) \nabla \varphi - \vec{A} (\nabla \cdot \nabla \varphi) - (\nabla \varphi \cdot \nabla) \vec{A} + \nabla \varphi (\nabla \cdot \vec{A}) (使用公式 (1-50))$$
$$= (\vec{A} \cdot \nabla) \nabla \varphi - \vec{A} \nabla^2 \varphi - (\nabla \varphi \cdot \nabla) \vec{A} + \nabla \varphi (\nabla \cdot \vec{A})$$
(3)

$$\nabla r = \cdots = \hat{r}$$

1.3 证明
$$\nabla r^n = nr^{n-2}\vec{r}$$

$$\nabla f(r) = \dots = f'(r) \nabla r = \dots = f'(r) \hat{r}$$

$$\nabla f(r) = f(r) \nabla r$$
  $\nabla r^n = nr^{n-1} \nabla r = nr^{n-2} \vec{r}$ 

**1.15** 证明
$$\nabla \times (f\nabla f) = 0$$

$$\nabla \times (f \nabla f) = f \nabla \times \nabla f + \nabla f \times \nabla f$$
 (使用公式(1-49))

 $\nabla \times \nabla f = 0$  (梯度场总是无旋的,ppt ch1 p66)  $\nabla f \times \nabla f = 0$ ,证毕

$$1.5 \quad 证明 \nabla \cdot \left(\frac{\vec{r}}{r^3}\right) = 0$$

$$\nabla \cdot \left(\frac{\vec{r}}{r^3}\right) = \nabla \frac{1}{r^3} \cdot \vec{r} + \frac{1}{r^3} \nabla \cdot \vec{r} = -\frac{3\vec{r}}{r^5} \cdot \vec{r} + \frac{3}{r^3} = 0$$

$$\nabla \cdot f \vec{A} = f \nabla \cdot \vec{A} + \nabla f \cdot \vec{A}$$

6 证明(1)
$$\nabla \times (f(r)\vec{r}) = 0$$
  
(2) $f(\vec{r} - \vec{r}')$ 的泰勒展开式可表示为

$$f(\vec{r}-\vec{r}')=f(\vec{r})-(\vec{r}'\bullet\nabla)f(\vec{r})+\frac{1}{2}(\vec{r}'\bullet\nabla)^2f(\vec{r})+\cdots$$

$$(1)\nabla\times(f(r)\vec{r})=f(r)(\nabla\times\vec{r})+\nabla f(r)\times\vec{r}(使用公式(1-49))$$

$$\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$$

$$\nabla \times \vec{r} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix} = 0$$

$$\nabla f(r) \times \vec{r} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \\ x & y & z \end{vmatrix} = 0$$

(2)根据三元函数的泰勒展开式

$$f(x_0 + h, y_0 + k, z_0 + l) = \sum_{m=0}^{n} \frac{1}{m!} \left( h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} + l \frac{\partial}{\partial z} \right)^m f(x, y, z) + R_0$$

$$\Rightarrow$$
h=-x', k = -y', l = -z'

$$f(\vec{r} - \vec{r}') = f(x - x', y - y', z - z') = f(x, y, z) + \left(-x'\frac{\partial}{\partial x} - y'\frac{\partial}{\partial y} - z'\frac{\partial}{\partial z}\right)f(x, y, z)$$

$$+\frac{1}{2!}\left(-x'\frac{\partial}{\partial x}-y'\frac{\partial}{\partial y}-z'\frac{\partial}{\partial z}\right)^2+\cdots$$

由于
$$\vec{r}$$
'•∇ =  $(x'\hat{x} + y'\hat{y} + z'\hat{z})\left(\frac{\partial}{\partial x}\hat{x} + \frac{\partial}{\partial y}\hat{y} + \frac{\partial}{\partial z}\hat{z}\right) = x'\frac{\partial}{\partial x} + y'\frac{\partial}{\partial y} + z'\frac{\partial}{\partial z}$ 

代入上式,可得
$$f(\vec{r}-\vec{r}')=f(\vec{r})-(\vec{r}'\bullet\nabla)f(\vec{r})+\frac{1}{2!}(\vec{r}'\bullet\nabla)^2f(\vec{r})+\cdots$$

即证明成立

**2.11**证明:如果一个点电荷在一个半径为a的球面内(球外无电荷),则q在球面上产生的电位平  $\bar{\varphi} = \frac{q}{4\pi \epsilon_0 a}$ 。对球内任意一点,其电位可表示为球内电荷和边界对其贡献的总和

设点电荷距离球心为d,选无穷远为零电势点,则球心的电势为: 
$$\varphi = \frac{q}{4\pi\varepsilon_0 d} = \frac{q}{4\pi\varepsilon_0 d} + \frac{1}{4\pi} \oint_s \left( \frac{1}{R} \frac{\partial \varphi}{\partial n} - \varphi \frac{\partial}{\partial n} \frac{1}{R} \right) ds' = \frac{q}{4\pi\varepsilon_0 d} + \frac{1}{4\pi} \oint_s \left( \frac{1}{R} \nabla \varphi \cdot \hat{n} + \varphi \frac{\hat{R} \cdot \hat{n}}{R^2} \right) ds'$$

$$= \frac{q}{4\pi\varepsilon_0 d} + \frac{1}{4\pi} \oint_{\mathcal{S}} \left( \frac{\nabla \varphi \cdot \hat{n}}{R} + \frac{\varphi}{R^2} \right) ds' = \frac{q}{4\pi\varepsilon_0 d} + \frac{1}{4\pi a} \int_{\mathcal{S}} -\vec{E} \cdot \hat{n} ds' + \frac{1}{4\pi a^2} \oint_{\mathcal{S}} \varphi ds'$$

$$=\frac{q}{4\pi\varepsilon_{0}d}-\frac{1}{4\pi a}\oint_{\mathcal{S}}\vec{E}\,ds'+\frac{1}{4\pi a^{2}}\oint_{\mathcal{S}}\varphi\,ds'=\frac{q}{4\pi\varepsilon_{0}d}-\frac{q}{4\pi\varepsilon_{0}a}+\bar{\varphi}$$

$$=\frac{q}{4\pi\varepsilon_{0}d}\frac{\partial \varphi}{\partial r}+\frac{\partial \varphi}{\partial r}\int_{\mathcal{F}}\frac{\partial \varphi}{\partial r}\frac{\partial \varphi}{\partial r}-\frac{\partial \varphi}{\partial r}\left(\frac{1}{R}\right)ds'}{\left[\varphi(\vec{r})=\frac{1}{4\pi\varepsilon_{0}}\int_{\mathcal{F}}\frac{\rho(\vec{r}')}{R}dV'+\frac{1}{4\pi}\oint_{\mathcal{S}}\left\{\frac{1}{R}\frac{\partial \varphi}{\partial r}-\varphi\frac{\partial}{\partial r}\left(\frac{1}{R}\right)\right\}ds'}\right]$$

$$\varphi(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int_{V} \frac{\rho(\vec{r}')}{R} dV' + \frac{1}{4\pi} \oint_{S} \left\{ \frac{1}{R} \frac{\partial \varphi}{\partial n} - \varphi \frac{\partial}{\partial n} \left( \frac{1}{R} \right) \right\} dS'$$

则有: 
$$\bar{\varphi} = \frac{q}{4\pi\varepsilon_0 a}$$

2.21 已知某种形式分布的电荷在球坐标系中所产生的电位为 $\varphi(\vec{r}) = \frac{qe^{-br}}{r}$ ,其中q,b均为常数,求此电荷分布。有源区域内电荷和电位分布满足泊松方程 $\nabla^2 \varphi(\vec{r}) = -\frac{\rho(\vec{r})}{r}$ 

球坐标系下Laplace表示式为 
$$(r \neq 0)$$

以主体系 「Laplace 没外及り (アーの) 
$$\nabla^2 f = \frac{\partial^2 f}{\partial r^2} + \frac{2}{r} \frac{\partial f}{\partial r} + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{1}{r^2 \tan \theta} \frac{\partial f}{\partial \theta} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}$$
(公式(1-152)) 
$$\nabla \nabla^2 \varphi(r) = \frac{\partial^2 \varphi}{\partial r^2} + \frac{2}{r} \frac{\partial \varphi}{\partial r} = -\frac{\rho}{\varepsilon_0}, \text{则电荷分布} \rho = -\varepsilon_0 \nabla^2 \varphi(r)$$
 
$$= -q\varepsilon_0 \left( e^{-br} \nabla^2 \frac{1}{r} + \frac{1}{r} \nabla^2 e^{-br} + 2\nabla \frac{1}{r} \cdot \nabla e^{-br} \right)$$

有 
$$\frac{\partial \varphi}{\partial r} = \frac{r \times qe^{-br} \times (-b) - qe^{-br}}{r^2} = \frac{-(br+1)qe^{-br}}{r^2}, \frac{\partial^2 \varphi}{\partial r^2} = \frac{\left(b^2r^3 + 2br^2 + 2r\right)qe^{-br}}{r^4}$$
 综合上式,整理得 $\rho = \frac{-b^2q\varepsilon_0}{r}e^{-br}$ 

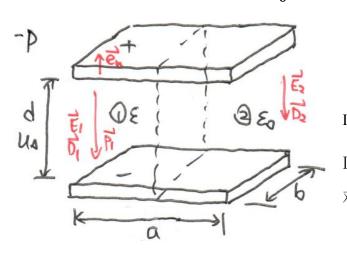
 $=-q\varepsilon_0e^{-br}\iiint_V\nabla\bullet\nabla\frac{1}{r}dV=-q\varepsilon_0e^{-br}\iiint_V\nabla^2\frac{1}{r}dV=-q\varepsilon_0e^{-br}\iiint_V-4\pi\delta(r)dV=4\pi\delta(r)q\varepsilon_0e^{-br}$ 

$$\frac{f \frac{\partial \varphi}{\partial r} = \frac{r \times q e^{-\kappa} \times (b) \cdot q e^{-br}}{r^2} = \frac{(br+1)q e^{-br}}{r^2}, \frac{\partial \varphi}{\partial r^2} = \frac{(br+1)q e^{-br}}{r^4} = -q\varepsilon_0 \left[ -4\pi\delta(r)e^{-br} + \frac{b^2e^{-br}}{r} \right]$$
综合上式,整理得 $\rho = \frac{-b^2q\varepsilon_0}{r}e^{-br}$ 

$$r = 0$$
时,取 $r \to 0$ 的高斯球面,利用高斯定理: $\rho = \varepsilon_0 \oint_s -\nabla \frac{q e^{-br}}{r} \cdot d\bar{S} = -q\varepsilon_0 \oint_s \left( -b e^{-br} \nabla r \frac{1}{r} + e^{-br} \nabla \frac{1}{r} \right) \cdot d\bar{S} = -q\varepsilon_0 \oint_s \left( -b e^{-br} \frac{\hat{r}}{r} + e^{-br} \nabla \frac{1}{r} \right) \cdot d\bar{S}$ 

综上所述 $\rho = 4\pi\delta(r)q\varepsilon_0e^{-br} - \frac{b^2q\varepsilon_0}{2}e^{-br}$ 

2.27一平板电容器的长宽为a、b,极板间距离d,其中一半( $0\sim a/2$ )用介电常数为 $\varepsilon$ 的介质充填,另 一半为空气,极板间加电压 $U_0$ 。求极板上自由电荷密度与介质表面上极化电荷密度。(2)



$$E_{\mathrm{I}} = E_{\mathrm{II}} = \frac{U_{\mathrm{0}}}{d}$$
  $D_{\mathrm{I}} = \varepsilon E_{\mathrm{I}} = \varepsilon \frac{U_{\mathrm{0}}}{d}, \ D_{\mathrm{II}} = \varepsilon_{\mathrm{0}} E_{\mathrm{II}} = \varepsilon_{\mathrm{0}} \frac{U_{\mathrm{0}}}{d}$  极化面电荷 $\rho_{sb} = \vec{P} \cdot \hat{n}, \ \vec{P} = \vec{D} - \varepsilon_{\mathrm{0}} \vec{E}$ 

I区自由面电荷密度 $\rho_{\text{fl+}} = D_{\text{I}} = \varepsilon \frac{U_0}{d}$ ,则极化面电荷 $\rho_{sb\text{I+}} = \rho_{\text{+}} - \rho_{\text{fl+}} = (\varepsilon_0 - \varepsilon) \frac{U_0}{d} (\hat{n} \times \hat{E} \times \hat{D})$ II区自由面电荷密度 $\rho_{\text{fII+}} = D_{\text{II}} = \varepsilon_0 \frac{U_0}{d}$ ,由于无介质,则极化面电荷为0, 对下极板, 所有结果取相反, 结果略

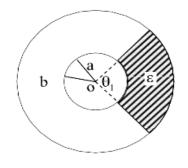
2.28两个同轴圆筒之间, $0 < \theta < \theta_1$ 部分填充了介电常数为 $\epsilon$ 的介质,其余部分为空气,求它单位 长度的电容量。

取一个单位长度的圆柱,其半径为 $\mathbf{r}$ (a < r < b),设内筒的电量为 $\mathbf{Q}$ ,由高斯定理:

$$\vec{E} = \frac{Q}{\varepsilon_0 (2\pi - \theta_1) + \varepsilon \theta_1} \frac{1}{r} \hat{r}$$

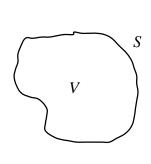
$$C = \frac{Q}{U} = \frac{\varepsilon_0 (2\pi - \theta_1) + \varepsilon \theta_1}{\ln \frac{b}{\sigma}}$$

$$\vec{E} = \frac{Q}{\varepsilon_0(2\pi - \theta_1) + \varepsilon\theta_1} \frac{1}{r} \hat{r} \qquad \qquad \mathbf{U} = \int_a^b \vec{E} \cdot d\vec{r} = \frac{Q}{\varepsilon_0(2\pi - \theta_1) + \varepsilon\theta_1} ln \frac{b}{a}$$



2.33 试证在没有电荷存在的区域V内,如V的边界S上,电f<sub>Q</sub> =常数 ,则区域V内也是等位的。(1)

根据有界区域内电势泊松方程的形式解(ppt ch2 p8),有



**唯一性定理** → V区域内的源产生的位 边值(包括区域外电荷的贡献) 第1、2、3

**2.34**试证偶极矩为**p**的电偶极子所产生的电位  $\varphi = \frac{1}{4\pi\epsilon} \frac{p \cdot r}{r^3}$ , 在 $r \neq 0$ 的区域内满足Laplace方程。

$$\varphi = \frac{1}{4\pi\varepsilon_0} \frac{ql\cos\theta}{r^2} (公式(2-79))$$
参照书49~50页

球坐标系下Laplace表示式为

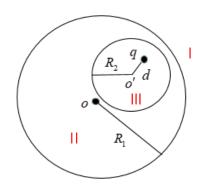
综合上式,整理得 $\nabla^2 \varphi = 0$ ,证明成立

# 第三章作业

3-1 如图,一导体球半径为R1,其中有一球形空腔,球心为o',半径为R2,腔内有一点电荷置于 距o'为d处,设导体球所带净电荷为零,求空间各个区域内的电位表示式。

设球外为Ⅰ区,球壳为Ⅱ区,空腔为Ⅲ区

1、选择略大于R2面Gauss积分



$$\int E \mathrm{d}s = \frac{Q}{\varepsilon_0}$$

导体内部E=0则Q=0,内壁感应电荷q'=-q 球壳为电中性,外壁感应电荷q

2、选择大于R1面Gauss积分

$$\int E ds = 4\pi r^2 E = \frac{q}{\varepsilon_0} \Rightarrow E_1 = \frac{q}{4\pi \varepsilon_0 r^2} \Rightarrow \varphi_1 = \frac{q}{4\pi \varepsilon_0 r}$$

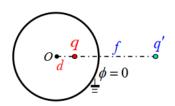
**3、**
$$\varphi_{\Pi} = \frac{q}{4\pi\varepsilon_0 R_1}$$
 (导体球等势体)

4、对Ⅲ区球形腔,其电位可以看成是表面电位为0且内部含有点电荷q的 球形腔和表面电位为ኇ且腔内不含电荷的球形腔

内表面电位  $\varphi_{II} = \frac{q}{4\pi\epsilon_0 R_1}$  若内表面电位为0,q有一镜像电荷  $q' = \frac{-R_2 q}{d}$ 距离o'为 $R_2^2$ 

$$\varphi_{\text{III}} = \frac{q}{4\pi\varepsilon_{0}R_{1}} + \frac{q}{4\pi\varepsilon_{0}R} + \frac{\frac{-R}{d}q}{4\pi\varepsilon_{0}R'}$$
 参考ppt ch3 p22例

电荷+镜像电荷+球面电势



$$\frac{q = -\frac{a}{f}q'}{f} \Longrightarrow q' = -\frac{f}{a}q = -\frac{a}{d}q$$

$$d = \frac{a^2}{f} \qquad \Longrightarrow f = \frac{a^2}{d}$$

#### 3-2 球面镜像+平面镜像

$$q_1 = \frac{-a}{r_0}q, q_2 = -q, q_3 = \frac{a}{r_0}q$$
,到球心距离为 $\frac{a}{r^2}, r_0, \frac{a^2}{r_0}$ 

$$\phi = \frac{q}{4\pi\epsilon_{R}R} - \frac{aq}{4\pi\epsilon_{R}R} - \frac{q}{4\pi\epsilon_{R}R} + \frac{aq}{4\pi\epsilon_{R}R}, R, R_{1}, R_{2}, R_{3}$$
是 $q, q1, q2, q3$ 到场点的距离

3-5 镜像电荷如图所示, $q' = -\frac{a}{b}q$ ,其到圆心距离为 $b' = \frac{a^2}{b}$ ,q受到的静电力来自q'

$$F = \frac{abq^2}{4\pi\varepsilon_0(a^2 - b^2)^2}$$
,方向由电荷指向镜像电荷

该电荷所受的力仅与球壳内电荷有关,当导体球壳接地时,球面镜像,注意力的方向 球壳内电荷保持不变,即该电荷受力大小与接地与否无关

# 3-8 采用保角变换法(教材p80 例3-3/ppt ch3 p16)

将区域映射为上半平面, 再利用镜像法求解

# 注意:无限长线电荷的场和电势公式(ppt ch3 p24)

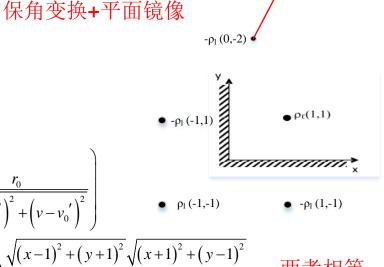
$$E_r = \frac{\rho_l}{2\pi\varepsilon_0 r}, \phi(r) = \int_r^{r_0} E_r dr = \frac{\rho_l}{2\pi\varepsilon_0} \ln \frac{r_0}{r},$$
其中 $r_0$ 为电势为0的点的位置

$$\frac{dr}{2\pi\varepsilon_{0}r} = \frac{r}{2\pi\varepsilon_{0}}, \phi(r) = \int_{r}^{r} E_{r}dr = \frac{r}{2\pi\varepsilon_{0}} \ln \frac{\sigma}{r}, \text{其中}r_{0} \text{为电势为0的点的证置}$$

$$\phi = \frac{\rho_{l}}{2\pi\varepsilon_{0}} \ln \frac{r_{0}}{R} + \frac{\rho_{l}'}{2\pi\varepsilon_{0}} \ln \frac{r_{0}}{R'} = \frac{\rho_{l}}{2\pi\varepsilon_{0}} \left( \ln \frac{r_{0}}{\sqrt{(u-u_{0})^{2} + (v-v_{0})^{2}}} - \ln \frac{r_{0}}{\sqrt{(u-u_{0}')^{2} + (v-v_{0}')^{2}}} \right)$$

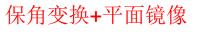
$$= \frac{\rho_l}{2\pi\varepsilon_0} \ln \frac{\sqrt{u^2 + (v+2)^2}}{\sqrt{u^2 + (v-2)^2}}$$

镜像法结果: 
$$\frac{\rho_l}{2\pi\varepsilon_0} \ln \frac{\sqrt{(x-1)^2 + (y+1)^2} \sqrt{(x+1)^2 + (y-1)^2}}{\sqrt{(x-1)^2 + (y-1)^2} \sqrt{(x+1)^2 + (y+1)^2}}$$



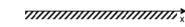
3-9: 
$$W = \sqrt{z}, \phi = \frac{\rho_l}{2\pi\varepsilon_0} \ln \frac{\sqrt{(u - u_0)^2 + (v + v_0)^2}}{\sqrt{(u - u_0)^2 + (v - v_0)^2}}$$

$$\int x_0 = u_0^2 - v_0^2$$



• 
$$\rho_l(u_0,v_0)$$

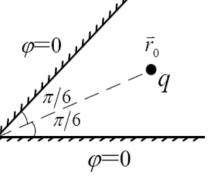




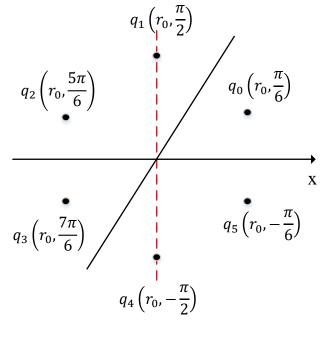
•  $-\rho_1(u_0,-v_0)$ 

一、镜像法

$$\varphi = \frac{1}{4\pi\varepsilon_0} \sum_{i=0}^{5} \frac{q_i}{R_i}$$
其中, $R_i$ 为 $q_i$ 到观察点的距离



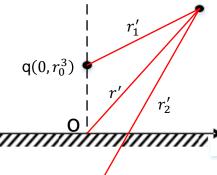
其中,
$$R_i$$
为 $q_i$ 到观察点的距离



# 二、保角变换法

$$\Re W = Z^3 = r_0^3 e^{i3\theta_0} \ \theta_0 = \frac{\pi}{6} \ r' = r^3 \ \theta' = 3\theta$$

$$\begin{cases} r_1' = \left| r'e^{i\theta'} - r_0^3 e^{i\frac{\pi}{2}} \right| \\ r_2' = \left| r'e^{i\theta'} - r_0^3 e^{-i\frac{\pi}{2}} \right| & \text{代入}r', \theta'反变换回z平面即可得到电势} \\ \varphi = \frac{q}{4\pi\varepsilon_0} \left( \frac{1}{r_1'} - \frac{1}{r_2'} \right) & \text{保角变换+平面镜像} \end{cases}$$





<u>镜像法实质</u>: 反过来寻找符合边界上场/位分布的等效电荷分布, 以代替边界的作用(包括其上的感应、极化电荷)!

## 镜像法的关键:

- ▶着眼点: 边界及边界条件
- ▶注意等效、求解区域!!

## ◆镜像法小结

- 镜像法是等效问题的反问题, 其理论基础是静电场唯一性定理;
- 镜像法的实质是用虚设的镜像电荷替代未知(或已知)区域外以及 边界上的电荷分布,使计算场域为无限大均匀介质;
- 镜像法的关键是:确定镜像电荷的个数、大小及位置;
- 应用镜像法解题时,注意: 镜像电荷只能放在待求场域以外的区域。
- 叠加时,要注意场的适用区域。

■ 方法虽好,但过分局限于特殊形状边界!

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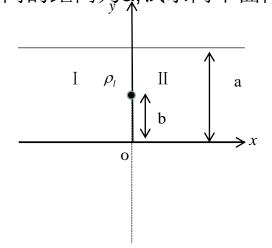
## 保角变换法:

- 选择合适的解析函数将 Z平面上较为复杂的边界变换为 W平面上较易求解的边界;
- 2. 在W平面上求解后,再反变换到原平面上。

## 几点说明:

- ▶ 如果一函数 f(x, y)在Z平面上是拉普拉斯方程的解,通过保角变换后变成 u、v 的函数,此函数在W平面上仍满足拉氏方程。
- 》保角变换前后,电荷密度分布发生变化,但<u>总荷电量不变</u>。Z平面和W平面上对应点的电场强度要改变,它们之间的关系是:  $E^{(z)}=|f'(z)|E^{(w)}$
- ▶ 保角变换前后两导体之间的电容量不变。若只求电容, 不必反变换!
- > 如果一次变换不足以简化问题,可以采取多次变换。

**3-11** 在接地的两个无限大平行导体平面之间,有一线电荷  $\rho_i$  ,它到一板的距离为**b**,两平面间的距离为**q**,试求两平面间的电位分布、电场强度和两极板上的感应电荷面密度。



解法类似教材P105,例3-12

第一步:根据题目条件,列出电位方程(1)和电位边界条件(2)~(4)

$$\begin{cases}
\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = -\frac{\rho_l \delta(x) \delta(y - b)}{\varepsilon_0} & (1) \\
\phi(x, 0) = 0 & (2) \\
\phi(x, a) = 0 & (3) \\
\phi(\infty, y) = 0 & (4)
\end{cases}$$

为使用分离变量法求解,设法将上式中自由项转移到边界上,使非齐次方程变为 齐次方程,可人为将场域划分为两个部分 I、 $\Pi$ ,使源点恰好位于分区的公共边界上

I区电位方程和边界条件

Ⅱ区电位方程和边界条件

$$\begin{cases}
\nabla^{2}\phi = \frac{\partial^{2}\phi_{I}}{\partial x^{2}} + \frac{\partial^{2}\phi_{I}}{\partial y^{2}} = 0 & (1) \\
\phi_{I}(x,0) = 0, \phi_{I}(x,a) = 0 & (2) \\
\phi_{I}(0,y) - \phi_{II}(0,y) = 0 & (3) \\
\frac{\partial\phi_{I}}{\partial x}|_{x=0} - \frac{\partial\phi_{II}}{\partial x}|_{x=0} = -\frac{\rho_{I}\delta(y-b)}{\varepsilon_{0}} & (4) \\
\phi_{I}(\infty,y) = 0 & (5)
\end{cases}$$

$$\begin{cases}
\nabla^{2}\phi = \frac{\partial^{2}\phi_{II}}{\partial x^{2}} + \frac{\partial^{2}\phi_{II}}{\partial y^{2}} = 0 & (1) \\
\phi_{II}(x,a) = 0, \phi_{II}(x,0) = 0 & (2) \\
\phi_{I}(0,y) - \phi_{II}(0,y) = 0 & (3) \\
\frac{\partial\phi_{I}}{\partial x}|_{x=0} - \frac{\partial\phi_{II}}{\partial x}|_{x=0} = -\frac{\rho_{I}\delta(y-b)}{\varepsilon_{0}} & (4) \\
\phi_{II}(\infty,y) - \phi_{II}(0,y) = 0 & (3)
\end{cases}$$

$$x$$
-方向齐次  
 $k_x^2 > 0, k_x$ 为实数  

$$\begin{cases} \sin k_x x \\ \cos k_x x \end{cases}$$

$$\begin{cases} \sin k_x x \\ \cos k_x x \end{cases}$$

$$\begin{cases} \sinh |k_x| x \\ \cosh |k_x| x \end{cases}$$

$$\begin{cases} \sinh |k_x| x \\ \cosh |k_x| x \end{cases}$$

$$\begin{cases} \cosh |k_x| x \\ \cosh |k_x| x \end{cases}$$

$$\begin{cases} \cosh |k_x| x \\ \cosh |k_x| x \end{cases}$$

$$\Rightarrow \text{ D} \text{ Example 1.15}$$

---齐次方向: --非齐次方向: 选择振荡型函数 选择衰减型函数 第二步:利用分离变量法和电位方程(1)给出电位的形式解由分离变量法知识,写出Ⅰ、Ⅱ区域内形式解

$$\varphi_{\text{I}} = \sum_{n=1}^{\infty} A_n \sin\left(\frac{n\pi}{a}y\right) e^{-\frac{n\pi}{a}x}$$
 $y$ 方向有重复零点,x方向无穷远处为0

$$\varphi_{\text{II}} = \sum_{n=1}^{\infty} B_n \sin\left(\frac{n\pi}{a}y\right) e^{\frac{n\pi}{a}x}$$
y方向有重复零点,x方向

第三步: 利用边界条件确定电位的形式解中的未知系数

由边界条件(3)知 $A_n = B_n$ ,由边界条件(4)知 $\sum_{n=1}^{\infty} 2A_n \sin\left(\frac{n\pi}{a}y\right)\left(\frac{n\pi}{a}\right) = \frac{\rho_l \delta(y-b)}{\varepsilon_0}$ 

利用三角函数的正交性,方程两边同乘
$$\sin\left(\frac{n\pi}{a}y\right)$$
,并在0~a上对y积分,得

$$A_{n} = \frac{\rho_{l}}{n\pi\varepsilon_{0}} \sin\frac{n\pi b}{a}$$

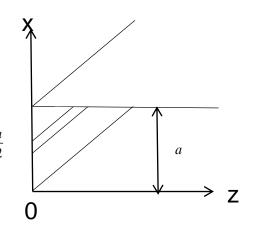
$$\varphi = \sum_{n=1}^{\infty} \frac{\rho_{l}}{n\pi\varepsilon_{0}} \sin\frac{n\pi b}{a} \sin\left(\frac{n\pi}{a}y\right) e^{-\frac{n\pi}{a}|x|}$$

电场强度

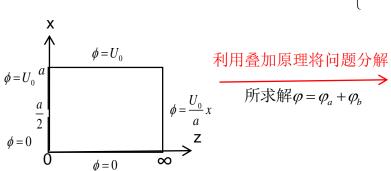
$$\vec{E} = -\nabla \varphi = -\frac{\partial \varphi}{\partial x} \hat{x} - \frac{\partial \varphi}{\partial y} \hat{y}$$

感应电荷面密度 
$$\rho_s = D_n \mid_{y=0/a} = \varepsilon_0 E_y \mid_{y=0/a}$$

# 3-13 一导体制成的矩形槽, <u>在端面的中心(x=a/2)有一小缝,如图所示,上板电位为U<sub>0</sub>,</u> 下板电位为0, 求0<x<a,z>0区间内的电位解



解法类似教材P84,例3-5



一步:根据题目条件,列出电位方程(1)和电位边界条件(2)~(6) (其中,电位与y无关,x→∞时,x=0处的边界情况不影响x→∞处场分量, 故此处边界条件为(4))

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial z^2} = 0 \qquad (1)$$

$$\phi(x,0) = 0, 0 < x < \frac{a}{2}$$
 (2)

$$\phi(x,0) = U_0, \frac{a}{2} < x < a \quad (3)$$

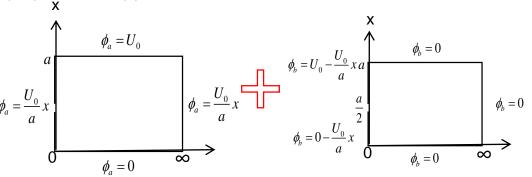
$$\phi(x,\infty) = \frac{U_0}{a}x \qquad (4)$$

$$\phi(0,z) = 0 \qquad (5)$$

$$\phi(a,z) = U_0 \qquad (6)$$

$$\phi(0,z) = 0 \tag{5}$$

$$\phi(a,z) = U_0 \tag{6}$$



$$\nabla^2 \phi_a = \frac{\partial^2 \phi_a}{\partial x^2} + \frac{\partial^2 \phi_a}{\partial z^2} = 0 \quad (1)$$

$$\phi_a(x,0) = \frac{U_0}{a}x \qquad (2)$$

$$\phi_a(x,\infty) = \frac{U_0}{a}x \tag{3}$$

$$\phi(0,z) = 0 \tag{4}$$

$$\phi(a,z) = U_0 \tag{5}$$

$$\bigcup_{t}$$

$$\phi_a = \frac{U_0}{a} x$$

$$\nabla^2 \phi_b = \frac{\partial^2 \phi_b}{\partial x^2} + \frac{\partial^2 \phi_b}{\partial z^2} = 0 \tag{1}$$

$$\phi_b(x,0) = 0 - \frac{U_0}{a}x, 0 < x < \frac{a}{2}$$
 (2)

$$\begin{cases} \phi_b(x,0) = U_0 - \frac{U_0}{a}x, \frac{a}{2} < x < a \quad (3) \end{cases}$$

$$\phi_b(x,\infty) = 0 \qquad (2)$$

$$\phi(0,z) = 0 \qquad (5)$$

$$\phi(0,z) = 0 \tag{5}$$

$$\phi(a,z)=0$$

## x-方向齐次

$$k_x^2 > 0$$
,  $k_x$ 为实数

 $\int \sin k_x x$  $\cos k x$   $k_x^2 = 0$   $\begin{cases} x \\ 1 \end{cases}$ 

$$k_x^2 \neq 0$$

x-方向非齐次

 $k_x^2 \leq 0$ ,  $k_x$ 为虚数

及其组合 (sinh, cosh)

### ---齐次方向:

选择振荡型函数

#### --非齐次方向:

选择衰减型函数

#### 第二步:利用分离变量法和电位方程(1)给出电位的形式解

由(4)知,沿z方向的本征函数不应该取为双曲函数(在无穷远处发散),

应取指数形式 $e^{-n\pi/a}$ ,由边界条件(5)、(6)知,沿x方向的本征函数要求有

重复的零点,应取
$$\sin \frac{n\pi}{a}$$
,最终得到电位形式解 $\varphi_{\rm b} = \sum_{n=1}^{\infty} A_n \sin \left( \frac{n\pi}{a} x \right) e^{-\frac{n\pi}{a} z}$ 

#### 第三步: 利用边界条件确定电位的形式解中的未知系数

曲边界条件(2)、(3)知
$$\phi_b(x,0) = \sum_{n=1}^{\infty} A_n \sin\left(\frac{n\pi}{a}x\right) = \begin{cases} 0 - \frac{U_0}{a}x, & 0 < x < \frac{a}{2} \\ U_0 - \frac{U_0}{a}x, & \frac{a}{2} < x < a \end{cases}$$

利用三角函数的正交性,方程两边同乘 $\sin\left(\frac{n\pi}{a}x\right)$ ,并在0~a 上对x 积分,得

$$-A_n = \frac{2}{a} \left[ \int_0^{\frac{a}{2}} \left( -\frac{U_0}{a} x \right) \sin\left(\frac{n\pi}{a} x\right) dx + \int_{\frac{a}{2}}^a \left( U_0 - \frac{U_0}{a} x \right) \sin\left(\frac{n\pi}{a} x\right) dx \right] = \frac{2U_0}{n\pi} \cos\frac{n\pi}{2}$$

$$\varphi_b = \sum_{i=1}^{\infty} \frac{2U_0}{n\pi} \cos \frac{n\pi}{2} \sin \frac{n\pi x}{a} e^{-\frac{n\pi}{a}z}$$

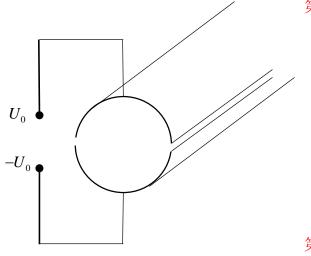
最终,
$$\varphi = \varphi_a + \varphi_b = \frac{U_0}{a}x + \sum_{n=1}^{\infty} \frac{2U_0}{n\pi} \cos \frac{n\pi}{2} \sin \frac{n\pi x}{a} e^{-\frac{n\pi}{a}z}$$

分步积分

$$(uv)' = u'v + uv', uv' = (uv)' - u'v$$

$$\int uv'dx = uv - \int u'vdx$$

# 3-17 一圆形电容器,其半径为a,上半部分加电压U0,下半部分加电压-U0,如图,求此电容器内的电位分布(极板间缝隙的影响忽略)



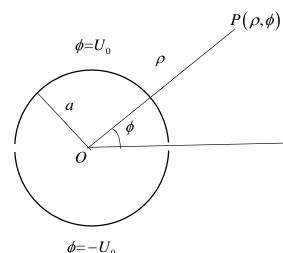
#### 第一步:根据题目条件,列出电位方程(1)和电位边界条件(2)~(6)

(其中, 电位与**Z**无关, 采用圆柱坐标系)

#### 第二步:利用分离变量法和电位方程(1)给出电位的形式解

由(5)知,沿 $\theta$ 方向为齐次边界,选择振荡型函数,且满足(6),故应取为 $\sin(n\theta)$ ,又根据z向平面场和沿 $\rho$ 方向为非齐次边界的条件,满足欧拉方程解 $c_n \rho^n + d_n \rho^{-n}$ ,再由

(4)知,应取
$$\rho^n \left( \rho^{-n}$$
在 $\rho$ =0处发散 $\right)$ ,最终得到电位形式解 $\varphi_b = \sum_{n=1}^{\infty} A_n \sin(n\theta) \rho^n$ 



### 参考ppt ch3 p68 和 ppt ch3 p83

#### 第三步: 利用边界条件确定电位的形式解中的未知系数

由边界条件(2)、(3)知
$$\phi(a,\theta) = \sum_{n=1}^{\infty} A_n \sin(n\theta) a^n = \begin{cases} U_0, & 0 < \theta < \pi \\ -U_0, & \pi < \theta < 2\pi \end{cases}$$

利用三角函数的正交性,方程两边同乘 $\sin(n\theta)$ ,并在 $0\sim 2\pi$ 上对 $\theta$ 积分,得

$$A_n = \frac{2}{2\pi a^n} \left[ \int_0^{\pi} (U_0) \sin(n\theta) d\theta + \int_{\pi}^{2\pi} (-U_0) \sin(n\theta) d\theta \right] = \frac{2U_0}{n\pi a^n} (1 - \cos n\pi)$$

$$\varphi = \sum_{n=1}^{\infty} \frac{2U_0}{n\pi a^n} (1 - \cos n\pi) \sin (n\theta) \rho^n$$

11. 一扇形纹如图的示,此线由p=0, p=0。和r=a的图成,求此较内第一类吃值问题的特种函数

(3-27)
解,  $Z=re^{j\theta}$ , $W=r,e^{j\theta}$  (分面報度) 强  $Q_1=Q_2=q_1=1$  作件的变换, $W=Z^{\frac{1}{10}}=Q_1=q_2=1$  在 W 平面 使用 钱信任:  $\begin{cases} Q_2=-Q_1\\ Q_1'=-Q_1'\\ Q_2'=-Q_1' \end{cases}$   $\begin{cases} r_2'=r_1'=Q_1'\\ r_2'=r_1'=Q_1' \end{cases}$   $\begin{cases} r_2'=r_1'=Q_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1' \end{cases}$   $\begin{cases} r_1'=r_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1' \end{cases}$   $\begin{cases} r_1'=r_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1' \end{cases}$   $\begin{cases} r_1'=r_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1' \end{cases}$   $\begin{cases} r_1'=r_1'\\ r_1'=r_1'=Q_1'\\ r_1'=r_1'=Q_1'$ 

保角变换+球面镜像+平面镜像

