

2015 - 2016.

一. $\lambda < 0$ $Y(x) = Ae^{\sqrt{\lambda}x} + Be^{-\sqrt{\lambda}x}$

代入边界条件 $A = B = 0$

$\lambda = 0$ $Y(x) = A + Bx$ $Y' = B$

故 $B = 0$ 得 $Y(x) = 1$ 此时 $\lambda = 0$

$\lambda > 0$ $Y(x) = A \cos \sqrt{\lambda}x + B \sin \sqrt{\lambda}x$

$Y'(x) = -A\sqrt{\lambda} \sin \sqrt{\lambda}x + B\sqrt{\lambda} \cos \sqrt{\lambda}x$

$Y'(0) = 0 \Rightarrow B = 0$

$Y(x) = \cos \sqrt{\lambda}x$ $Y'(x) = -\sqrt{\lambda} \sin \sqrt{\lambda}x$

$Y'(16) = -\sqrt{\lambda} \sin \sqrt{\lambda} \cdot 16 = 0$ $16\sqrt{\lambda} = n\pi$

$\lambda = \frac{n^2\pi^2}{256}$ $Y(x) = \cos \frac{n\pi x}{16}$

二. $\begin{cases} u_t = 4u_{xx} \\ u(t, 0) = u(t, 5) = 0 \\ u(0, x) = \phi(x) \end{cases} \quad u = TX$

$T'X = 4TX'' \Rightarrow \frac{T'}{4T} = \frac{X''}{X} = \lambda$

$X = \sin \frac{n\pi x}{5}$ $\lambda = -\frac{n^2\pi^2}{25}$ $T = e^{-\frac{4n^2\pi^2}{25}t}$

故: $u = \sum_{n=1}^{\infty} A_n e^{-\frac{4n^2\pi^2}{25}t} \sin \frac{n\pi x}{5}$

$A_n = \frac{2}{5} \int_0^5 \phi(x) \sin \frac{n\pi x}{5} dx$

$\phi(x) = \delta(x-2)$ $A_n = \frac{2}{5} \sin \frac{2n\pi}{5}$

三. 1. $u = a = 2$

$u = \frac{1}{2} [(x+2t)^2 + (x-2t)^2] + \frac{1}{4} \int_{x-2t}^{x+2t} \sin 2s ds$
 $= x^2 + 4t^2 + \frac{1}{8} \cos 2(x-2t) - \frac{1}{8} \cos 2(x+2t)$
 $= x^2 + 4t^2 + \frac{1}{4} \sin 2x \cos 4t$

2. $u = v + w$ $v = \frac{1}{2} - \frac{2}{3}u$

$w = \int_0^t \frac{1}{4} \int_{x-2(t-\tau)}^{x+2(t-\tau)} f(\tau, s) ds d\tau$
 $= \int_0^t x^2(t-\tau)\tau^2 + \frac{8}{3}\tau^2(t-\tau)^3 d\tau$
 $= \frac{1}{12}x^2t^4 + \frac{1}{45}t^6$

$u = x^2 + 4t^2 + \frac{1}{4} \sin 2x \cos 4t + \frac{1}{12}x^2t^4 + \frac{1}{45}t^6$

四. $F[u] = \bar{u}$ $\frac{d\bar{u}}{dt} = 4(-i\lambda)^2 \bar{u} + 5\bar{u} = (5 - 4\lambda^2) \bar{u}$ $u|_{t=0} = \phi(x)$

$\bar{u} = \phi(\lambda) e^{(5-4\lambda^2)t}$

$u = \phi(x) * F^{-1}[e^{5t} e^{-4\lambda^2 t}] = \phi(x) * \frac{1}{4\sqrt{\pi t}} e^{-\frac{x^2}{4t}} e^{5t}$

$\phi(x) = e^{-x^2}$ $u = \int_{-\infty}^{+\infty} \frac{e^{5t}}{4\sqrt{\pi t}} e^{-\frac{(x-s)^2}{4t}} e^{-\frac{s^2}{4t}} ds$
 $= \frac{e^{5t}}{4\sqrt{\pi t}} \int_{-\infty}^{+\infty} e^{-\frac{(x-s)^2 + s^2}{4t}} ds$
 $= \frac{e^{5t}}{4\sqrt{\pi t}} \int_{-\infty}^{+\infty} e^{-\frac{(1+\frac{1}{t})s^2 - 2sx + x^2}{4t}} ds$
 $= \frac{e^{5t}}{4\sqrt{\pi t}} \int_{-\infty}^{+\infty} e^{-\frac{(1+\frac{1}{t})s^2}{4t} + \frac{2sx}{4t} - \frac{x^2}{4t}} ds$



五.

$$u = TR$$

$$T'R = TR'' + \frac{1}{r} TR' \Rightarrow \frac{T'}{T} = \frac{R''}{R} + \frac{1}{r} \frac{R'}{R} = -\lambda$$

$$T' = -\lambda T \quad T = e^{-\lambda t}$$

$$r^2 R'' + \frac{1}{r} TR' + \lambda R r^2 = 0 \quad \lambda = \omega^2$$

$$\Rightarrow R = \sum_{n=1}^{\infty} J_0(\omega_n r) \quad \omega_n \text{ 为 } J_0(\omega) \text{ 的第 } n \text{ 个正根 } \lambda = \omega_n^2$$

$$\text{故 } u = \sum_{n=1}^{\infty} A_n e^{-\lambda_n t} J_0(\omega_n r)$$

$$A_n = \frac{2}{J_1^2(\omega_n)} \int_0^1 r J_0(\omega_n r) \phi(r) dr$$

$$\phi(r) = J_0(ar) + 3J_0(br)$$

$$u = e^{-a^2 t} J_0(ar) + 3e^{-b^2 t} J_0(br)$$

六.

1.

$$G(M_1, M_0) = \frac{1}{4\pi r(M_1, M_0)} - \frac{1}{4\pi r(M_1, M_0)} \quad (x < 0, x, y \in \mathbb{R})$$

$$= \frac{1}{4\pi \sqrt{(x-s)^2 + (y-\eta)^2 + (z-\zeta)^2}} - \frac{1}{4\pi \sqrt{(x+s)^2 + (y-\eta)^2 + (z-\zeta)^2}}$$

$$2.. \quad \nabla^2 2s = \frac{1}{2} \quad u_s = 2u_x \quad u_{ss} = 2u_{xx} - 2 = 4u_{xx}$$

$$\text{故: } 4u_{xx} + u_{yy} + u_{zz} = -\delta(x, y, z)$$

$$\Rightarrow u_{ss} + u_{yy} + u_{zz} = -\delta(2s, y, z) = -\frac{1}{2} \delta(s, y, z)$$

$$G(M_1, M_0) = \frac{1}{8\pi \sqrt{(s-y)^2 + (y-\eta)^2 + (z-\zeta)^2}} - \frac{1}{8\pi \sqrt{(s+y)^2 + (y-\eta)^2 + (z-\zeta)^2}}$$

$$\frac{\partial G}{\partial s} \Big|_{s=0} = \frac{1}{2} \frac{1}{8\pi \sqrt{(s-y)^2 + (y-\eta)^2 + (z-\zeta)^2}} - \frac{1}{2} \frac{1}{8\pi \sqrt{(s+y)^2 + (y-\eta)^2 + (z-\zeta)^2}}$$

$$= \frac{2z}{8\pi \sqrt{(s-y)^2 + (y-\eta)^2 + (z-\zeta)^2}} = \frac{z}{4\pi \sqrt{(s-y)^2 + (y-\eta)^2 + (z-\zeta)^2}}$$

$$x = \frac{1}{2} 2s \quad s' = \frac{1}{2} 2s$$

$$\frac{\partial G}{\partial s} = \frac{\partial G}{\partial s} \Big|_{s=0} = \frac{z}{2\pi \sqrt{(x-s)^2 + 4(y-\eta)^2 + 4z^2}}$$

$$u(x, y) = - \iint_{\mathbb{R}^2} \frac{z \cdot \delta(s, y, z)}{2\pi \sqrt{(x-s)^2 + 4(y-\eta)^2 + 4z^2}} dy dz$$

$$7. \quad \Delta u \Rightarrow \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{\partial u}{\partial r}) = \frac{1}{r^2} (2r \frac{\partial u}{\partial r}) + \frac{1}{r^2} \frac{\partial^2 u}{\partial r^2} = \frac{2}{r} \frac{\partial u}{\partial r} + \frac{\partial^2 u}{\partial r^2}$$

$$\text{故 } u = TR$$

$$\frac{T''R}{\alpha^2} = \frac{2}{r} TR' + TR'' \Rightarrow \frac{T''}{\alpha^2 T} = \frac{2}{r} \frac{R'}{R} + \frac{R''}{R} = -\lambda$$

$$T = A_n \sin \alpha_n t + B_n \cos \alpha_n t \quad R = r^{-(n+1)} \quad \lambda_n = n(n+1)$$

$$u = TR = \sum_{n=0}^{\infty} (A_n \sin \alpha_n t + B_n \cos \alpha_n t) r^{-(n+1)}$$

$$18. \quad a = 2n^2 n + 1 \quad y = P_{2n}(x) \quad 2x+1 = \sum_{n=0}^{\infty} A_{2n} P_{2n}(x)$$

$$A_{2n} = \frac{4^{n+1}}{2} \int_0^1 (2x+1) P_{2n}(x) dx = \frac{1}{2} \int_0^1 (2x+1) d[P_{2n+1}(x) - P_{2n-1}(x)]$$

$$= \frac{1}{2} \int_0^1 P_{2n+1}(x) - P_{2n-1}(x) dx = \frac{1}{2(n+3)} [P_{2n+2}(0) - P_{2n}(0)] - \frac{1}{2(n-1)} [P_{2n+1}(0) - P_{2n-1}(0)]$$



2016 - 2017 B.

一. $u_x + y u_{xy} = 0 \quad \Delta u_x = v$

$v + y v_y = 0 \quad v = v(x, y) \quad \frac{dy}{y} = -\frac{dv}{v} \quad \ln y = -\ln v + C$

$\ln v = -\ln y + C \quad v = \frac{C}{y} = u_x$

$u = \frac{C}{y} + f(y).$

二. 对原问题作延拓:

$\begin{cases} u_{tt} = 9u_{xx} & (t > 0, -\infty < x < +\infty) \\ u|_{t=0} = x & u_t|_{t=0} = 2\sin x \end{cases}$

$2\sin x - 2\cos x$

$$\begin{aligned} u &= \frac{1}{2} [\varphi(x+at) + \varphi(x-at)] + \frac{1}{2a} \int_{x-at}^{x+at} \psi(s) ds \\ &= \frac{1}{2} (x+3t + x-3t) + \frac{1}{2 \cdot 3} [2\cos(x-3t) - 2\cos(x+3t)] \\ &= x + \frac{2}{3} \sin x \sin 3t. \end{aligned}$$

三. (1) $u_{tt} = u_{xx}, \quad \varphi. u = XT.$

$X = A \sin \omega x + B \cos \omega x \quad x=0 \quad X|_{x=0} = 0$

$B=0 \quad X = \sin \omega x \quad X' = \omega \cos \omega x$

$X|_{x=\pi} = \omega \cos \omega \pi = 0 \quad \omega = n + \frac{1}{2}$

故 $X = \sin(n + \frac{1}{2})x, \quad \omega = (n + \frac{1}{2})$

$T = A_n \cos(n + \frac{1}{2})t + B_n \sin(n + \frac{1}{2})t.$

故 $u(x,t) = \sum_{n=0}^{\infty} [A_n \cos(n + \frac{1}{2})t + B_n \sin(n + \frac{1}{2})t] \sin(n + \frac{1}{2})x.$

$t=0, \quad A_n = 1$

$\frac{1}{2} B_n \sin(n + \frac{1}{2})t = 1 \quad B_0 = 2,$

$u(x,t) = \cos \frac{3}{2}t \sin \frac{3}{2}x + 2 \sin \frac{1}{2}t \sin \frac{1}{2}x.$

(2), 设 $v = A \sin \frac{x}{2} \sin \omega t, \quad A v_t = A \omega \sin \frac{x}{2} \cos \omega t$

$v_{tt} - v_{xx} = (A\omega^2 - \frac{A}{4}) \sin \frac{x}{2} \sin \omega t. = A(\frac{1}{4} - \omega^2) \sin \frac{x}{2} \sin \omega t.$

$A = \frac{1}{\frac{1}{4} - \omega^2}$

$u = v + w,$

边界条件: 左端固定, 右端自由

初始条件: $\sin \frac{3}{2}x$ 初位置

$\sin \frac{1}{2}x$ 初速度

$f(t,x)$: 各点受力

$\begin{cases} w_{tt} = w_{xx} \\ w|_{x=0} = 0 \quad w|_{x=\pi} = 0 \\ w_t|_{t=0} = \sin \frac{3}{2}x \quad w|_{t=0} = \sin \frac{x}{2} (1 - \frac{4}{1-\omega^2}) \end{cases}$

$w = \cos \frac{3}{2}t \sin \frac{3}{2}x + 2(1 - \frac{4}{1-\omega^2}) \sin \frac{1}{2}t \sin \frac{1}{2}x.$

$\Rightarrow u = \cos \frac{3}{2}t \sin \frac{3}{2}x + 2(1 - \frac{4}{1-\omega^2}) \sin \frac{1}{2}t \sin \frac{1}{2}x + \frac{1}{\frac{1}{4} - \omega^2} \sin \omega t \sin \frac{x}{2}$



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四.

$$\frac{\partial u}{\partial t} = \frac{1}{x} \frac{\partial}{\partial x} (x \frac{\partial u}{\partial x}) + u, \quad u = XT$$

$$\begin{aligned} T'X &= \frac{1}{x} \frac{\partial^2 u}{\partial x^2} + \frac{1}{x} \frac{\partial u}{\partial x} + u \\ &= TX'' + \frac{1}{x} TX' + TX \end{aligned}$$

$$\frac{T'}{T} = \frac{X''}{X} + \frac{1}{x} \frac{X'}{X} + 1 = -\lambda$$

$$X'' + \frac{1}{x} X' + X = -\lambda X$$

$$x^2 X'' + x X' + x^2 (\lambda + 1) X = 0.$$

$$\text{解为: } X = J_0(\omega_n x) \quad \omega_n^2 = \lambda_n + 1,$$

$$\omega_n: J_0'(\omega_n x)|_{x=1} = 0 \text{ 的第 } n \text{ 个正根,}$$

$$T = e^{-(\omega_n^2 - 1)t}$$

$$\text{故 } u = \sum_{n=1}^{\infty} C_n e^{-(\omega_n^2 - 1)t} J_0(\omega_n x)$$

$$C_n = \frac{1}{\int_0^1 J_0^2(\omega_n x) dx} \int_0^1 x \phi(x) J_0(\omega_n x) dx.$$

五. $\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{\partial u}{\partial r}) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \theta} (\sin^2 \theta \frac{\partial u}{\partial \theta}) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u}{\partial \phi^2} = r \cos \theta.$

$$\text{解: } u = \frac{1}{6} z^3 \quad \text{故: } u = v + w$$

$$\begin{cases} w_{xx} + w_{yy} + w_{zz} = 0 \\ w|_{x^2+y^2+z^2=1} = -\frac{1}{6} z^3 = -\frac{1}{6} \cos^3 \theta \end{cases}$$

$$\text{解: } w = \sum_{n=0}^{\infty} A_n r^n \cdot P_n(\cos \theta).$$

$$\begin{aligned} A_n &= \frac{2n+1}{2} \int_0^\pi -\frac{1}{6} \cos^3 \theta P_n(\cos \theta) \sin \theta d\theta \\ &= \frac{2n+1}{2} \int_{-1}^1 -\frac{1}{6} x^3 P_n(x) dx, \end{aligned}$$

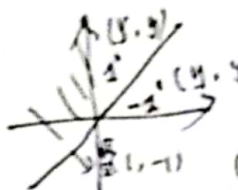
$$P_0(x) = 1 \quad P_1(x) = x \quad P_2(x) = \frac{3}{2} x^2 - \frac{1}{2} \quad P_3(x) = \frac{5}{2} x^3 - \frac{3}{2} x$$

$$A_3 = -\frac{1}{15} \quad A_2 = 0 \quad A_1 = -\frac{1}{16} \quad A_0 = 0$$

$$\text{故 } u = -\frac{1}{15} r^3 P_3(\cos \theta) - \frac{1}{16} r \cos \theta + \frac{1}{6} r^3 \cos^3 \theta$$

$$x = r \cos \theta \cos \phi, \quad y = r \sin \theta \sin \phi, \quad z = r \cos \theta.$$



六. (1)  故: 由格林法,

$$G(A, M_0) = \frac{1}{4\pi} \ln \frac{1}{(x-y)^2 + (y-y)^2} - \frac{1}{4\pi} \ln \frac{1}{(x-1)^2 + (y-0)^2}$$

$$= \frac{1}{4\pi} \ln \frac{(x-y)^2 + (y-y)^2}{(x-1)^2 + (y-0)^2}$$

(2). $u(x, y) = \iint_D f(M) G(A, M_0) dM_0 - \int_{\partial D} \frac{\partial G(A, M_0)}{\partial n_0} \varphi(M_0) dl$

$$\vec{n} = \frac{\sqrt{2}}{2} (1, -1) \quad dl = \sqrt{2} ds$$

$$\frac{\partial G}{\partial y} = \frac{1}{4\pi} \frac{2(y-y)}{(x-y)^2 + (y-y)^2} - \frac{1}{4\pi} \frac{2(y-0)}{(x-1)^2 + (y-0)^2}$$

$$= \frac{1}{4\pi} \left[\frac{2(y-y)}{(x-y)^2 + (y-y)^2} - \frac{2(y-0)}{(x-1)^2 + (y-0)^2} \right]$$

$$\frac{\partial G}{\partial y} = \frac{1}{4\pi} \frac{2(y-y)}{(x-y)^2 + (y-y)^2} - \frac{1}{4\pi} \frac{2(y-0)}{(x-1)^2 + (y-0)^2}$$

$$\frac{\sqrt{2}}{2} \left(\frac{\partial G}{\partial y} - \frac{\partial G}{\partial y} \right) \Big|_{s=y} = \frac{1}{\sqrt{2}\pi} \frac{x-y}{(x-y)^2 + (y-y)^2}$$

$$u(x, y) = - \int_{-\infty}^{+\infty} \frac{1}{4\pi} \frac{x-y}{(x-y)^2 + (y-y)^2} \phi(y) dy$$

七. (1) $u_t = 4u_{xx} + 3u \quad \bar{u} = F(u)$

$$\frac{d\bar{u}}{dt} = (-4\lambda^2 + 3)\bar{u} \quad \bar{u} = e^{(-4\lambda^2 + 3)t} = e^{3t} e^{-4\lambda^2 t}$$

$$u = e^{3t} \cdot \frac{1}{4\sqrt{\pi t}} e^{-\frac{x^2}{16t}}$$

$$u = \frac{1}{4\sqrt{\pi t}} e^{3t - \frac{x^2}{16t}}$$

2. $u = u(0, x) \cdot \varphi(x) = \frac{1}{4\sqrt{\pi t}} e^{3t} \int_{-\infty}^{+\infty} m e^{-\frac{(x-m)^2}{16t}} dm$

$$= \frac{4x\sqrt{\pi t}}{4\sqrt{\pi t}} e^{3t} = x e^{3t}$$

