

Chap. 4. No. 2.

1. 由热电子发射理论.

$$I = I_{st} \left[\exp\left(\frac{V}{nU_T}\right) - 1 \right] \quad n=1 \quad T=300K$$

$$I_{st} = A S \cdot J_{st}$$

$$J_{st} = R^* T^2 \exp\left(-\frac{\phi_{Bn}}{kT}\right)$$

$$I_{st} = 10^{-4} \text{ cm}^2 \cdot 114 \cdot 300^2 \cdot \exp\left(-\frac{0.42V}{26mV}\right) = 9.9 \times 10^{-6} A$$

$$I(V=0.5V) = 2.23 \times 10^4 A$$

2. (1) V_{bi} 由两个器件 J 之间作差得到变化速率最大值得出.

R_{on} 由开启电压和饱和电压之间线性拟合得出.

$$V_{bi}: \text{speed}(n) = I(n+1) - I(n)$$

$$\text{accelerate}(n) = \text{speed}(n+1) - \text{speed}(n)$$

accelerate 最大值对应开启电压. 最小值对应饱和电压.

$$\therefore V_{bi} = 0.75V$$

$$V_{\text{饱和}} = 2.08V$$

$$R_{on} = (0.0562S)^{-1} = 17.78 \Omega$$

(2) 当肖克莱方程只对饱和前有效. 先去除 $V_{\text{饱和}}$ 及以后数据.

再取曲线中较为线性的部分. 这里取 $[0.5, 1.5]$

即 $\sim 0.75V$ 部分



$$J = J_{st} [\exp(\frac{V}{nV_T}) - 1] \approx J_{st} \exp(\frac{V}{nV_T})$$

$$\ln J = \ln J_{st} + \frac{1}{nV_T} V$$

$$\ln J_{st} = \frac{-17.71}{-18.46} A \mu m^{-2}$$

$$\frac{1}{nV_T} = \frac{-17.71}{37.08} = m_{\text{Red3}}^* = 0.34 m_0$$

$$\therefore n = 0.97 \cdot 1.04 \cdot 3.1 \times 10^{-12} A cm^{-2} \cdot R^* = 12 \frac{m^*}{m_0} = 40.8 / A/cm^2 k^2$$

$$J_{st} = 3.71 \times 10^{-8} A \mu m^{-2} = 3.71 A/cm^2$$

$$q\phi_{Bn} = \ln\left(\frac{J_{st}}{q^2 T^2}\right) \cdot \left(-\frac{kT}{q}\right) \cdot q \approx 1.082 eV$$



设计值: $f_T = 1.6e-19$
 $C_g = 8.85e-14$

Chap. 4. No. 3.

1. $V_{bi} = V_T \ln \left(\frac{N_A N_D}{n_i^2} \right) = 26mV \cdot \ln \left(\frac{10^{18} \cdot 10^{15}}{(5.65 \times 10^{19})^2} \right) = 0.798V$

$V_{p0} = \frac{q a^2 N_D}{2 \epsilon S_i} = \frac{3.013}{2.215} V$

$V_p = V_{p0} - V_{bi} = 2.24V$

$G_0 = \frac{q q_{ND} \mu_n E_L}{2 \pi L} = 9.28mS$

$I_D = G_0 \left(V_D - \frac{2}{3} \sqrt{\frac{L}{V_{p0}}} \left[(V_D + V_{bi} - V_G)^{3/2} - (V_{bi} - V_G)^{3/2} \right] \right)$
 $V_G = 0$

$\frac{\partial I_D}{\partial V_D} = \frac{2}{3 V_{p0}} G_0 \left[V_D - \frac{2}{3} \sqrt{\frac{L}{V_{p0}}} \left[(V_D + V_{bi})^{3/2} - V_{bi}^{3/2} \right] \right]$
 $= G_0 \left\{ 1 - \frac{2}{3} \sqrt{\frac{L}{V_{p0}}} \cdot \frac{3}{2} \sqrt{V_D + V_{bi}} \right\}$

$= G_0 \left(1 - \sqrt{\frac{V_D + V_{bi}}{V_{p0}}} \right)$
 $\frac{\partial I_D}{\partial V_D} \bigg|_{V_D=0} = G_0 \left(1 - \sqrt{\frac{V_{bi}}{V_{p0}}} \right) = 4.6mS$

$f_T = \frac{q^2 q_{ND} \mu_n}{2 \pi \epsilon S_i L^2} = 3.48 \times 10^8 Hz$

$= \frac{V_{p0} \mu_n}{2 \pi L^2} = 695.3 MHz$



$$0.84V$$

$$2. V_{bi} = U_T \ln \left(\frac{N_A N_D}{n_i^2} \right) = 0.85804V$$

$$V_{D0} = V_D + V_{bi} = 3.24V$$

$$a = \sqrt{\frac{2V_{D0} \epsilon_{Si}}{q N_A}} = 6.42 \times 10^{-8} m = 6.42 \times 10^{-5} cm$$

$$2a = 1.284 \times 10^{-4} m = 1.284 \times 10^{-5} cm$$

$$3. A = [2a - 2W(x)]^2$$

$$I_D = A n q \mu_n E$$

$$E = \frac{-\partial V}{\partial x}$$

$$W(x) = \sqrt{\frac{2\epsilon_s}{q N_A} (V_{bi} + V_D - V_G)}$$

$$I_D = \int_0^L I_D dx = -q n q \mu_n \int_0^L \left(a - \sqrt{\frac{2\epsilon_s}{q N_A} (V_{bi} + V_D - V_G)} \right) dx$$

$$I_D = \frac{q n q \mu_n}{L} \left(a^2 L - \frac{4a}{3} \sqrt{\frac{2\epsilon_s}{q N_A}} \left[(V_D + V_{bi} - V_G)^{3/2} - (V_{bi} - V_G)^{3/2} \right] + \frac{2\epsilon_s}{q N_A} \left[(V_D + V_{bi} - V_G)^{3/2} - (V_{bi} - V_G)^{3/2} \right] \right)$$



$w < a$ 耗尽型. $N_C = 2.8 \times 10^{11} \text{ cm}^{-3}$.

$$\psi_p = \psi_a + \frac{kT}{q} \ln \left(\frac{N_D}{N_C} \right) = \psi_c - 0.11 \text{ V} \quad \text{---} \quad -0.080 \text{ V}.$$

$$V_{bi} = \phi_{Bn} - \phi_n = 0.89 \text{ V}.$$

$$W = \sqrt{\frac{2\epsilon_s V_{bi}}{q N_D}} = 0.11 \mu\text{m} < a.$$

耗尽型 G_0 .

$$I_D = \frac{q A N_D \mu_n E}{L} \left(V_0 - \frac{2}{3} k \sqrt{\frac{1}{V_{p0}}} [(V_b + V_{bi} - V_G)^{3/2} - (V_{bi} - V_G)^{3/2}] \right)$$

$$G_0 = \frac{q A N_D \mu_n E}{L} = 8 \text{ mS}.$$

$$V_{p0} = \frac{2a^2 N_D}{2\epsilon_s} = 2.8 \text{ V}.$$

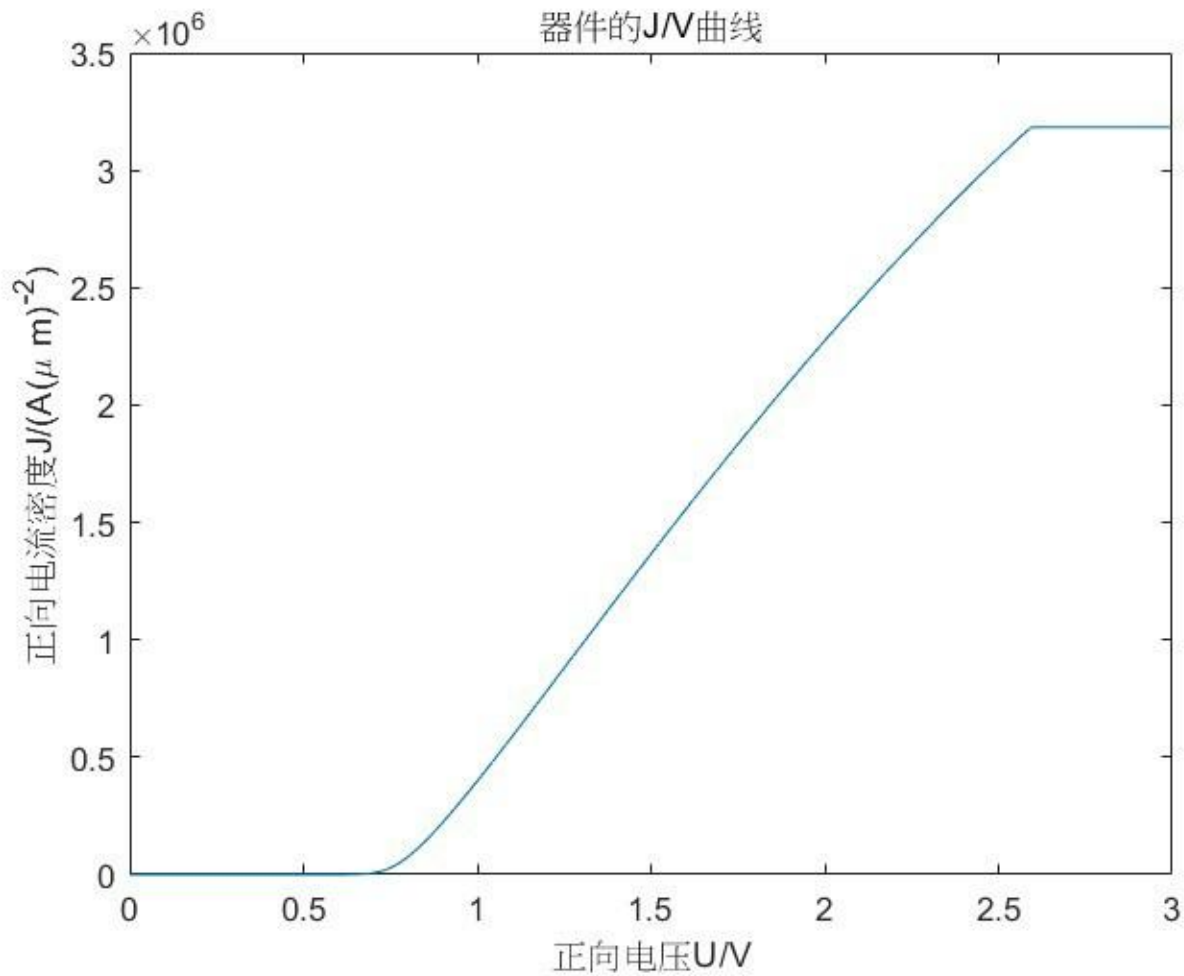
$$V_D = V_{p0} - V_{bi} = 1.94 \text{ V}.$$

$$V_D = V_{p0} = V_{p0} + V_{Gm}$$

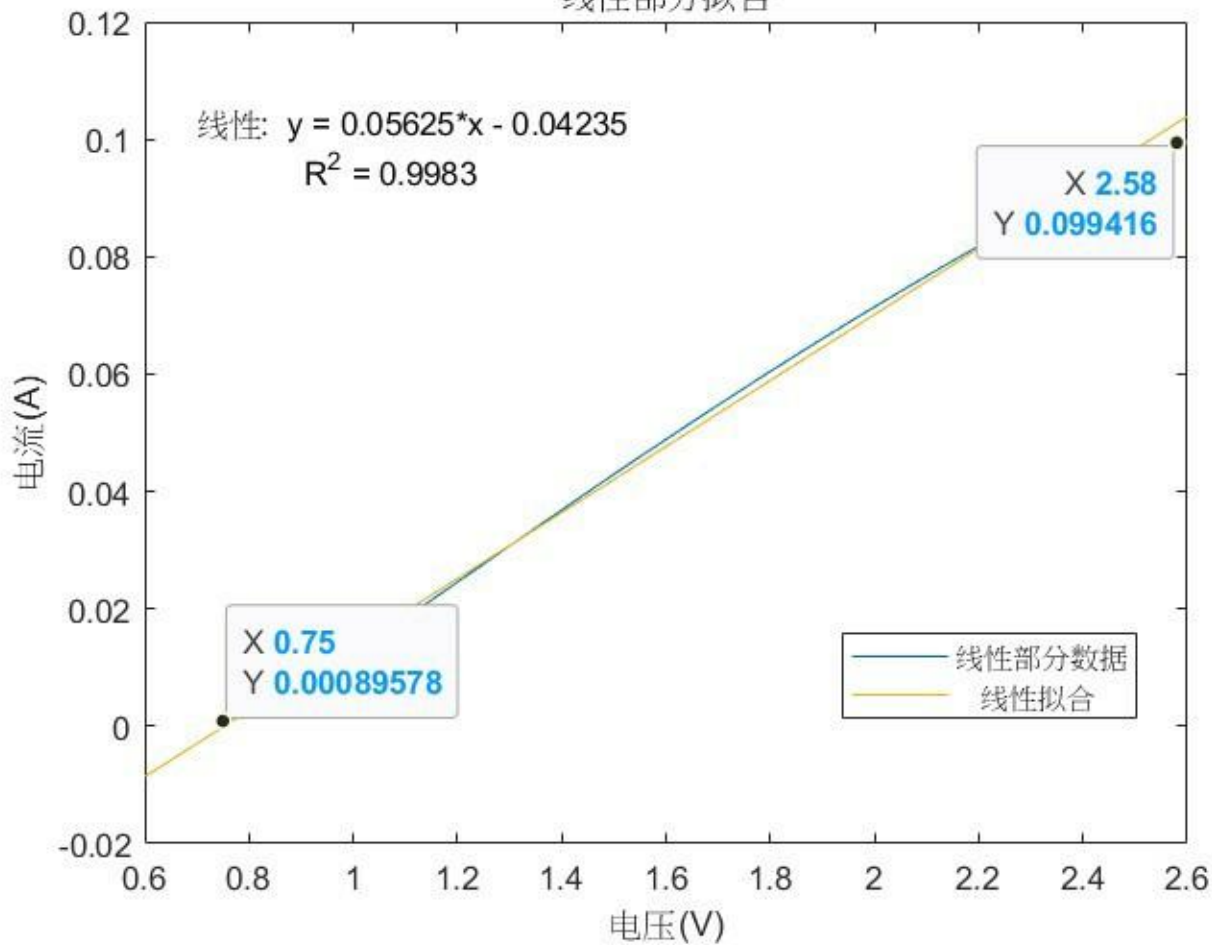
$$I_{DS} \text{ 饱和, } V_G = 0. \quad = G_0 \left(\frac{2}{3} \sqrt{\frac{V_{bi}}{V_{p0}}} - 1 \right) V_{bi} + \frac{1}{3} G_0 V_{p0} = 3.13 \text{ mA}$$



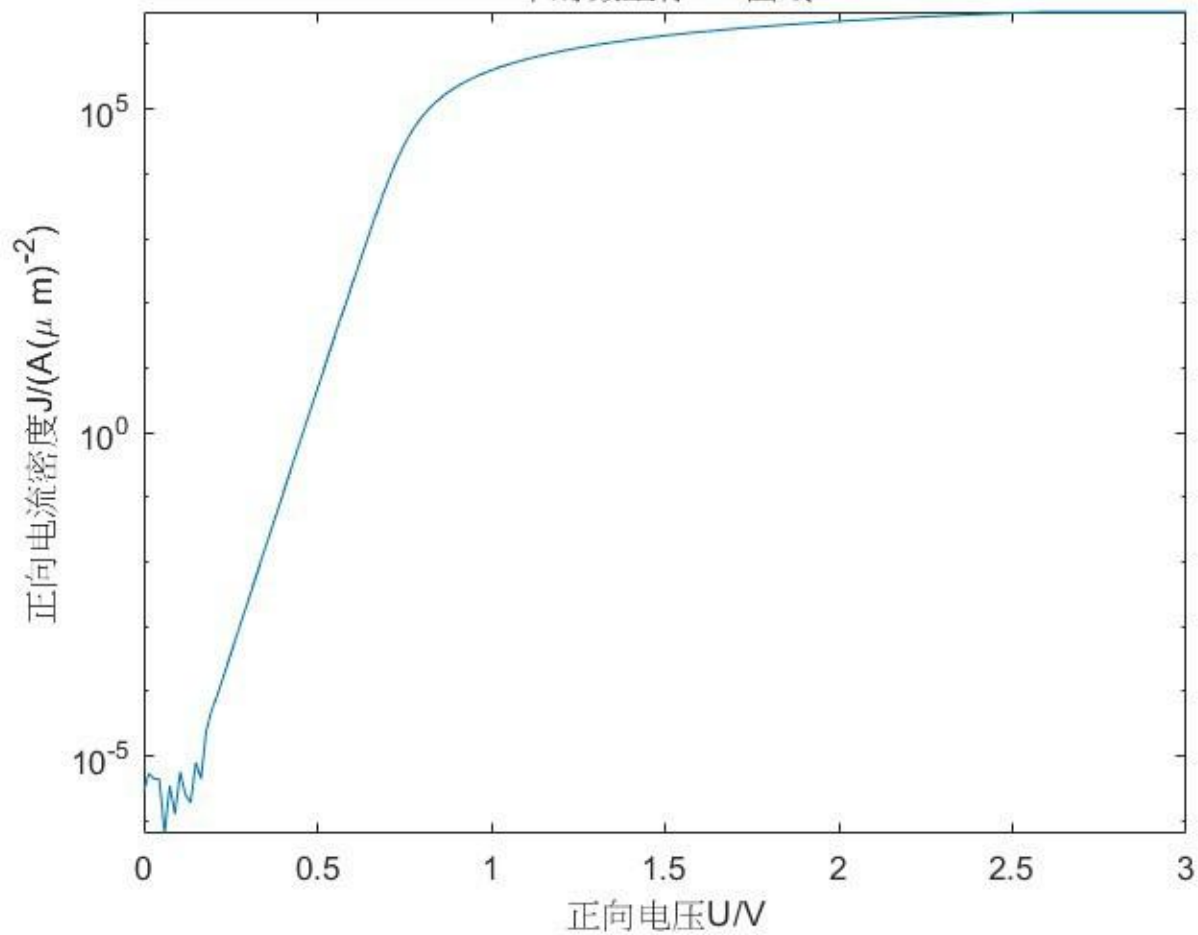
器件的J/V曲线



线性部分拟合



半对数坐标J-V曲线



半对数坐标ln(J)-V曲线

