

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
from scipy.sparse.linalg import spsolve
from scipy.integrate import quad
from scipy.optimize import fsolve
from scipy.interpolate import interp1d, PchipInterpolator
from scipy.optimize import fsolve
```

```
In [2]: def double_well_potential(x1, x2, xm, V1, V2, Vm):
    # System of equations to determine A1, A2, Am, w1, w2, wm
    def equations(vars):
        A1, A2, Am, w1, w2, wm = vars
        eq1 = A1 * np.exp(-((x1 - x1) / w1) ** 2) + A2 * np.exp(-((x1 - x2)
        eq2 = A1 * np.exp(-((x2 - x1) / w1) ** 2) + A2 * np.exp(-((x2 - x2)
        eq3 = A1 * np.exp(-((xm - x1) / w1) ** 2) + A2 * np.exp(-((xm - x2)
        eq4 = -2 * A1 * (xm - x1) / (w1 ** 2) * np.exp(-((xm - x1) / w1) **
        eq5 = -2 * A1 * (x1 - x1) / (w1 ** 2) * np.exp(-((x1 - x1) / w1) **
        eq6 = -2 * A1 * (x2 - x1) / (w1 ** 2) * np.exp(-((x2 - x1) / w1) **
        return [eq1, eq2, eq3, eq4, eq5, eq6]

    # Initial guess for A1, A2, Am, w1, w2, wm
    initial_guess = [V1, V2, Vm, 0.5, 1.0, 0.6]

    # Solve the system of equations
    A1, A2, Am, w1, w2, wm = fsolve(equations, initial_guess)
    print(f"A1={A1}, A2={A2}, Am={Am}, w1={w1}, wm={wm}, w2={w2}")

    # Define the potential function
    def V(x):
        return A1 * np.exp(-((x - x1) / w1) ** 2) + A2 * np.exp(-((x - x2) /

    # Define the first derivative of the potential function
    def dV_dx(x):
        term1 = -2 * A1 * (x - x1) / (w1 ** 2) * np.exp(-((x - x1) / w1) **
        term2 = -2 * A2 * (x - x2) / (w2 ** 2) * np.exp(-((x - x2) / w2) **
        term3 = -2 * Am * (x - xm) / (wm ** 2) * np.exp(-((x - xm) / wm) **
        return term1 + term2 + term3

    return V, dV_dx

# Parameters
x1 = 0.5    # Location of the first minimum
xm = 1.5    # Location of the maximum (barrier)
x2 = 3.5    # Location of the second minimum
V1 = -3.0   # Value at the first minimum
V2 = -5.0   # Value at the second minimum
Vm = 6.0    # Value at the maximum (barrier height)

# Calculate the potential and its derivative
beta_U, beta_Up = double_well_potential(x1, x2, xm, V1, V2, Vm)

# x range for plotting
x = np.linspace(0, 4, 1000)
```

```

potential = beta_U(x)
dV_dx = beta_Up(x)

# Plotting the potential
plt.figure(figsize=(8, 7))
plt.subplot(2, 1, 1)
plt.plot(x, potential)
plt.xlabel('x')
plt.ylabel("$ \\beta U(x)$")
plt.title('Double-Well Potential')
plt.grid(True)

# Plotting the first derivative of the potential
plt.subplot(2, 1, 2)
plt.plot(x, dV_dx)
plt.xlabel('x')
plt.ylabel("$ \\beta U'(x)$")
plt.title("First Derivative of the Double-Well Potential")
plt.grid(True)

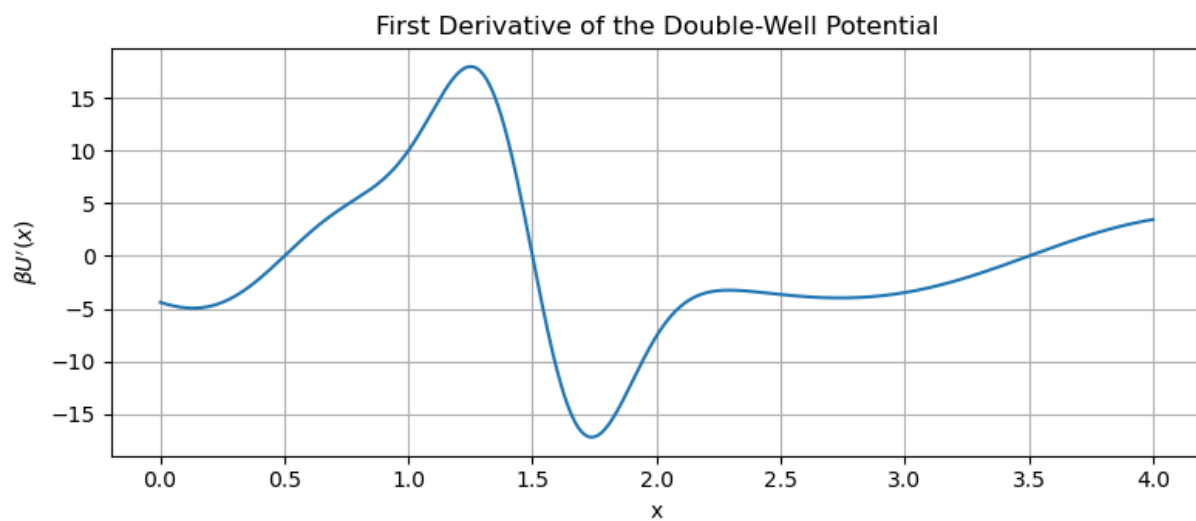
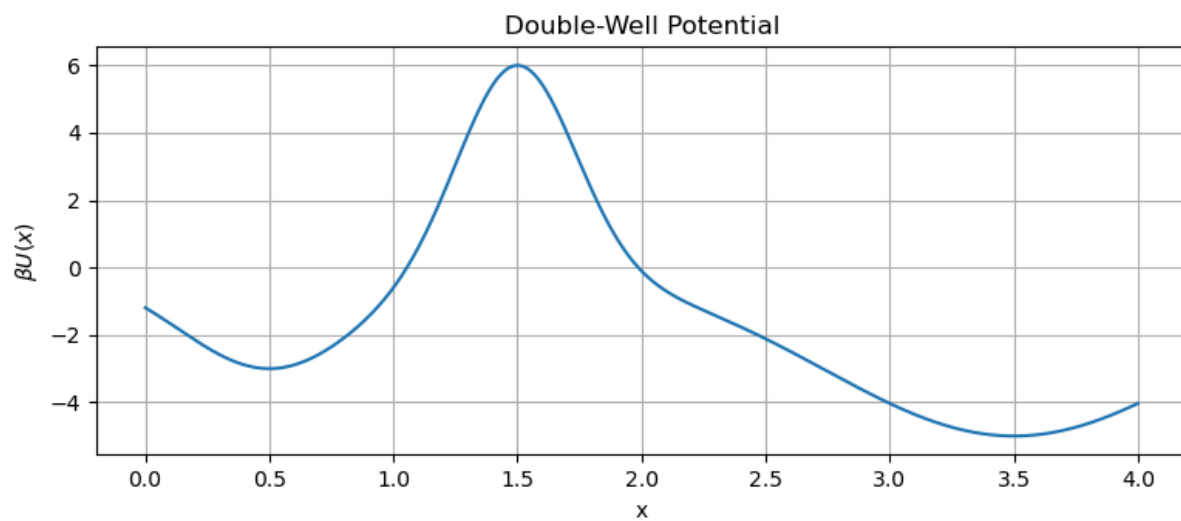
plt.tight_layout()
plt.show()

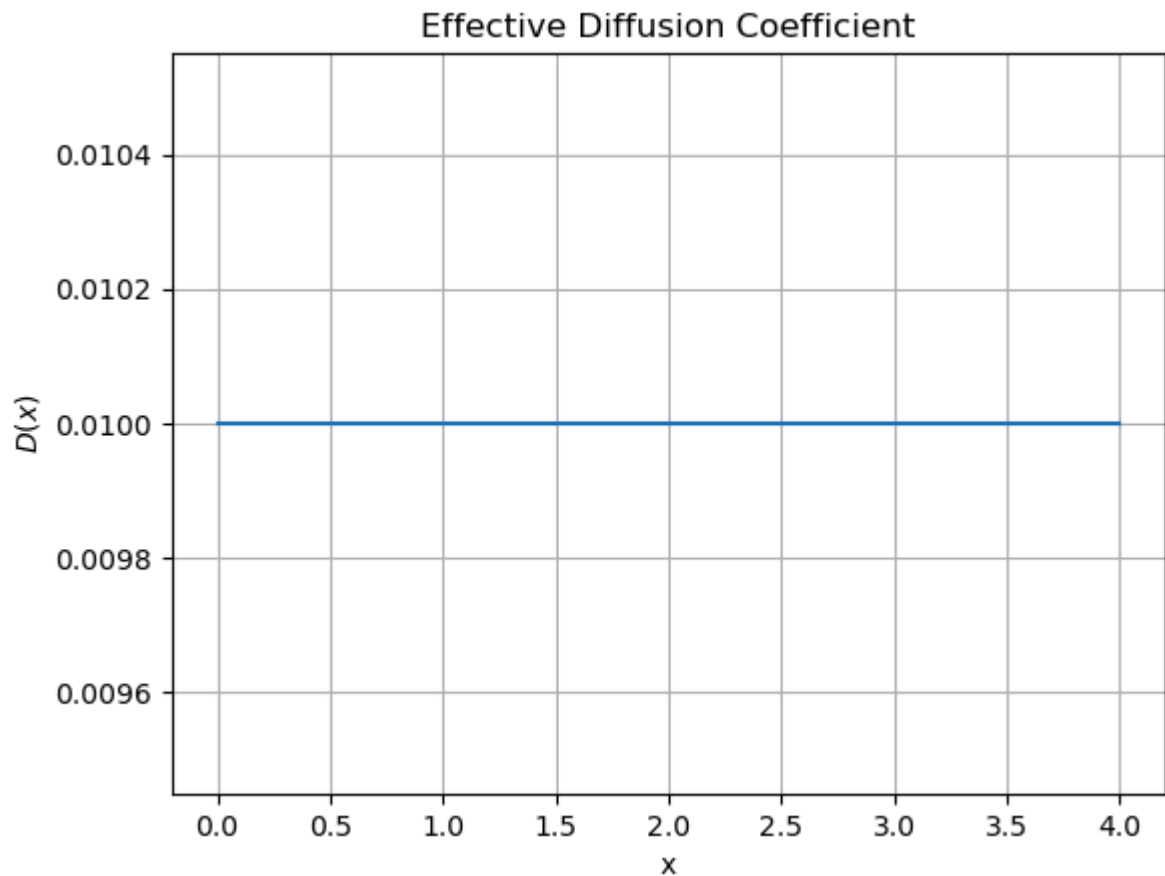
D0 = 0.01
def D(x):
    # return D0*x**(2/3)
    return D0*x**0

plt.plot(x, D(x))
plt.xlabel('x')
plt.ylabel("$ D(x)$")
plt.title('Effective Diffusion Coefficient')
plt.grid(True)
plt.show()

```

A1=-2.9984306623906316, A2=-5.000000000000002, Am=6.235107362393493, w1=0.520421938809253, wm=0.32906358123352797, w2=1.0784000138556546





```
In [3]: a = 0.5    # location of reflecting boundary
        b = 3.5    # location of absorbing boundary

        h = 0.01
        N = int((b-a)/h+1)

        x_arr = np.linspace(a, b, N)
```

Numerical solve ODE with injecting boundary condition to find steady state solution

```
In [4]: def kappa(x):
        return D(x)*np.exp(-beta_U(x))

        x_minus_half = x_arr - h/2.0
        x_plus_half = x_arr + h/2.0
        u_arr = np.zeros(x_arr.size)

        A = np.zeros((N-1, N-1))
        np.fill_diagonal(A, -(kappa(x_minus_half)+kappa(x_plus_half)))
        np.fill_diagonal(A[1:, ], kappa(x_minus_half[1:-1])) # subdiagonal
        np.fill_diagonal(A[:, 1:], kappa(x_plus_half[:-2])) # superdiagonal
        A[0, 1] += kappa(x_minus_half[0])

        f_vect = np.zeros(N-1)
        f_vect[0] = 1
```

```

u_arr[0:-1] = spsolve(A, f_vect)
Pst_arr = u_arr*np.exp(-beta_U(x_arr))
Pst_arr /= (np.sum(Pst_arr)*h)

plt.plot(x_arr, Pst_arr)
plt.grid()

inject_rate = D(x_arr[-1])*np.exp(-beta_U(x_arr[-1])+beta_U(x_arr[-2]))*Pst_1/inject_rate

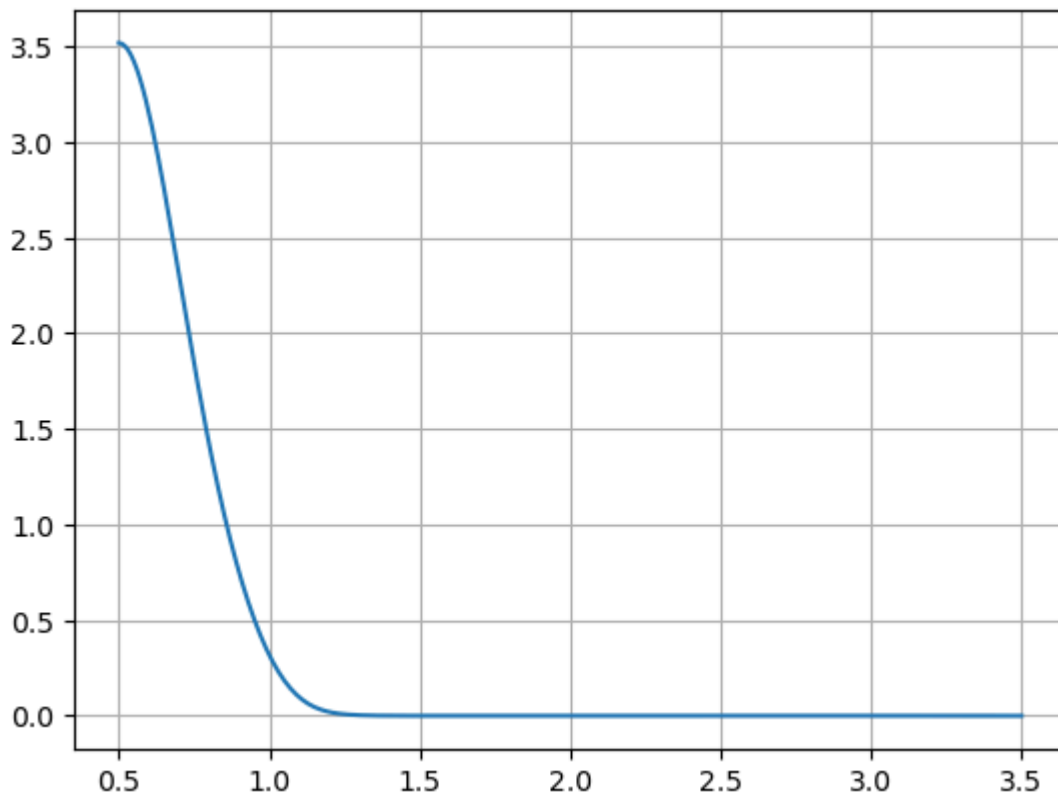
```

```

/tmp/ipykernel_789248/1491311078.py:17: SparseEfficiencyWarning: spsolve requires A be CSC or CSR matrix format
  u_arr[0:-1] = spsolve(A, f_vect)

```

Out[4]: 112932.29344885287



In []:

Numerically Nest integrate for Steady-State Flux and Probability distribution function

```

In [5]: # Define the inner function to integrate as a function of y
def inner_integrand(y):
    return 1.0/D(y)*np.exp(beta_U(y))

# Define the inner integral as a function of x
def inner_integral(x):
    y_lower = x
    y_upper = b
    result, error = quad(inner_integrand, y_lower, y_upper)

```

```

    return result

# Define the outer integral
x_lower = a
x_upper = b

# Define the outer function to integrate (also as a function of x)
def outer_integrand(x):
    return np.exp(-beta_U(x))*inner_integral(x)

# Perform the outer integration
invert_st_flux, error = quad(outer_integrand, x_lower, x_upper)
st_flux = 1.0/invert_st_flux
print(invert_st_flux)

```

55478.78943520375

```

In [6]: def st_P_func(x):
        def integrand(y):
            return 1.0/D(y)*np.exp(beta_U(y))
        # Perform the integration
        y_lower = x
        y_upper = b
        result, error = quad(integrand, y_lower, y_upper)
        result *= st_flux*np.exp(-beta_U(x))
        return result

        st_P_arr = np.zeros(x_arr.size)
        for i in np.arange(x_arr.size):
            st_P_arr[i] = st_P_func(x_arr[i])

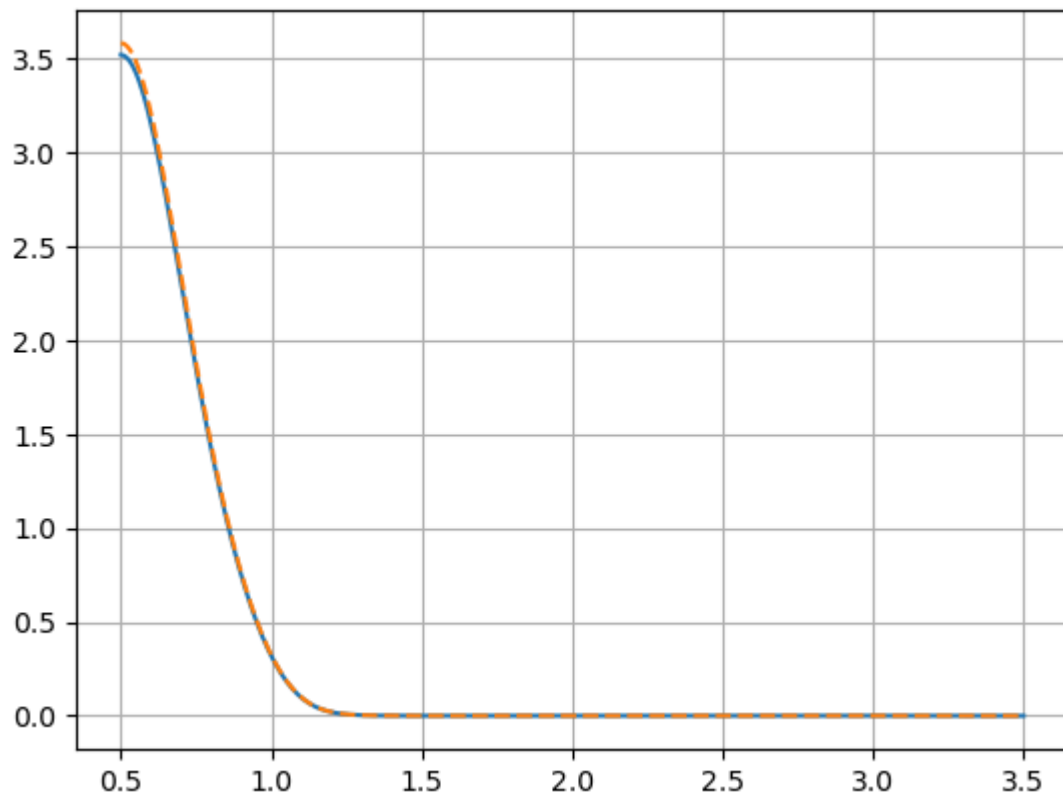
        plt.plot(x_arr, Pst_arr)
        plt.plot(x_arr, st_P_arr, '--')

        plt.grid()

        print(Pst_arr[:5], st_P_arr[:5])

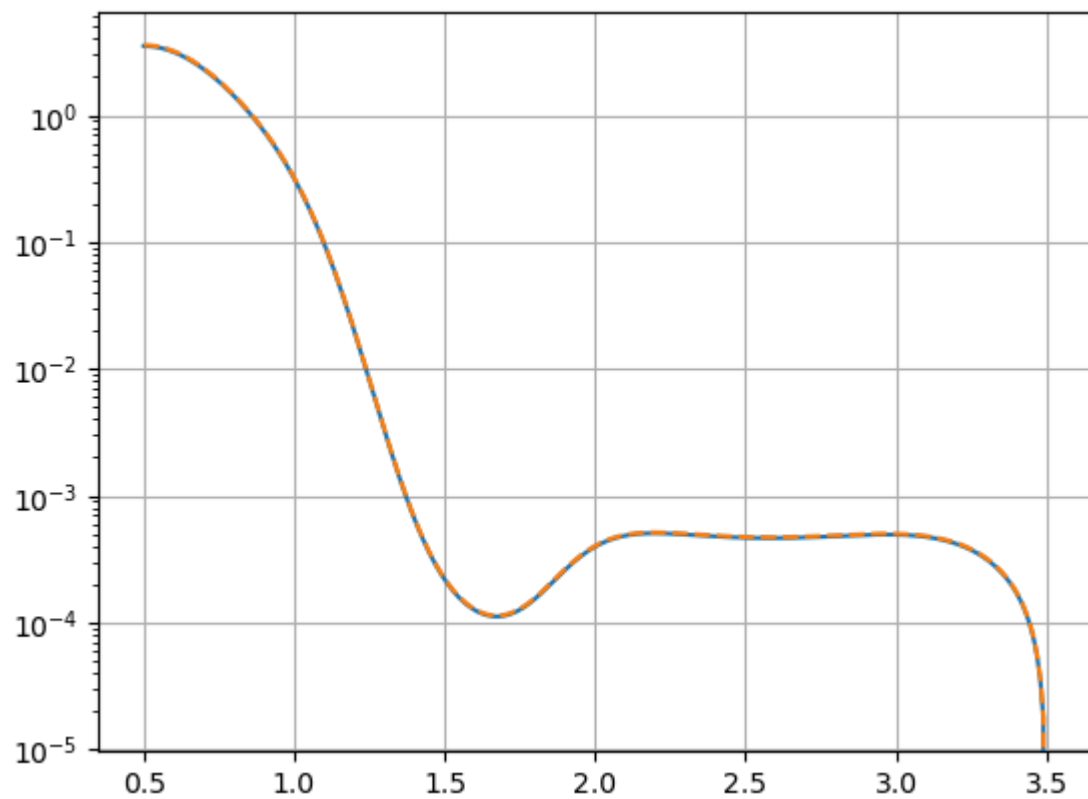
```

[3.5182883 3.51435165 3.50260409 3.48313637 3.45610469] [3.58128827 3.57728112 3.56532321 3.54550689 3.51799117]



```
In [7]: plt.semilogy(x_arr, Pst_arr)
plt.semilogy(x_arr, st_P_arr, '--')

plt.grid()
```



In []:

Numerically Nest integrate for MFPT

In [8]: `x0 = a` *# Regura's method, overlap the starting point and reflecting bounda*

```
# Define the inner function to integrate as a function of z
def inner_integrand(z):
    return np.exp(-beta_U(z))

# Define the inner integral as a function of y
def inner_integral(y):
    z_lower = a
    z_upper = y
    result, error = quad(inner_integrand, z_lower, z_upper)
    return result

# Define the outer integral
y_lower = x0
y_upper = b

# Define the outer function to integrate (also as a function of y)
def outer_integrand(y):
    return np.exp(beta_U(y))*inner_integral(y)/D(y)

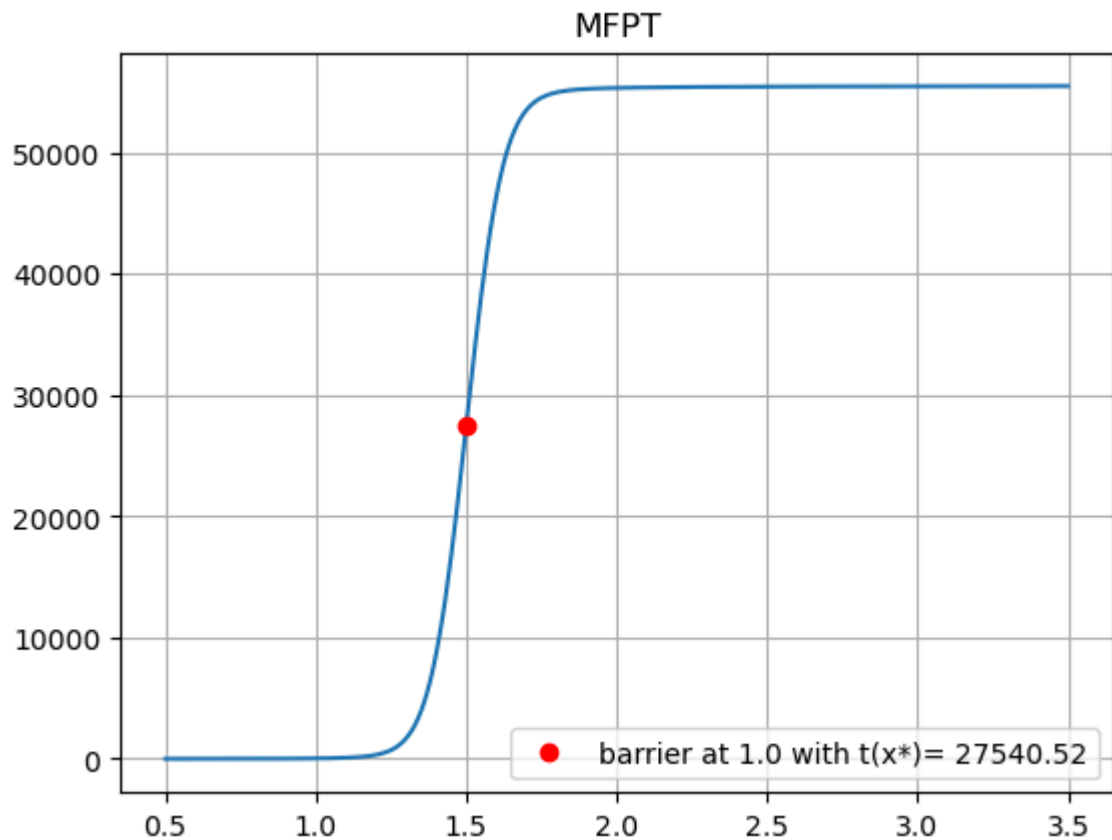
# Perform the outer integration (from x0 to b)
result, error = quad(outer_integrand, y_lower, y_upper)

mfpt_arr = np.zeros(x_arr.size)
for i in np.arange(x_arr.size):
    mfpt_arr[i], _ = quad(outer_integrand, y_lower, x_arr[i])
```

In [9]: `idx_barrier = np.where((x_arr > 1.5-h/2) & (x_arr < 1.5 + h/2))`
`t_star = mfpt_arr[idx_barrier][0]`
`print(f"2*t_star = 2*t(x*)")`
`print(f"mfpt_arr[-1] = t(b)")`
`print(f"invert_st_flux = 1/J")`
`print(f"1/inject_rate/2 = 1/inject_rate")`

```
plt.plot(x_arr, mfpt_arr)
plt.plot(1.5, t_star, 'ro', label=f"barrier at 1.0 with t(x*)={t_star: .2f}")
plt.title('MFPT')
plt.legend()
plt.grid()
```

```
55081.04319401654 = 2*t(x*)
55478.78943520375 = t(b)
55478.78943520375 = 1/J
56466.146724426435 = 1/inject_rate
```

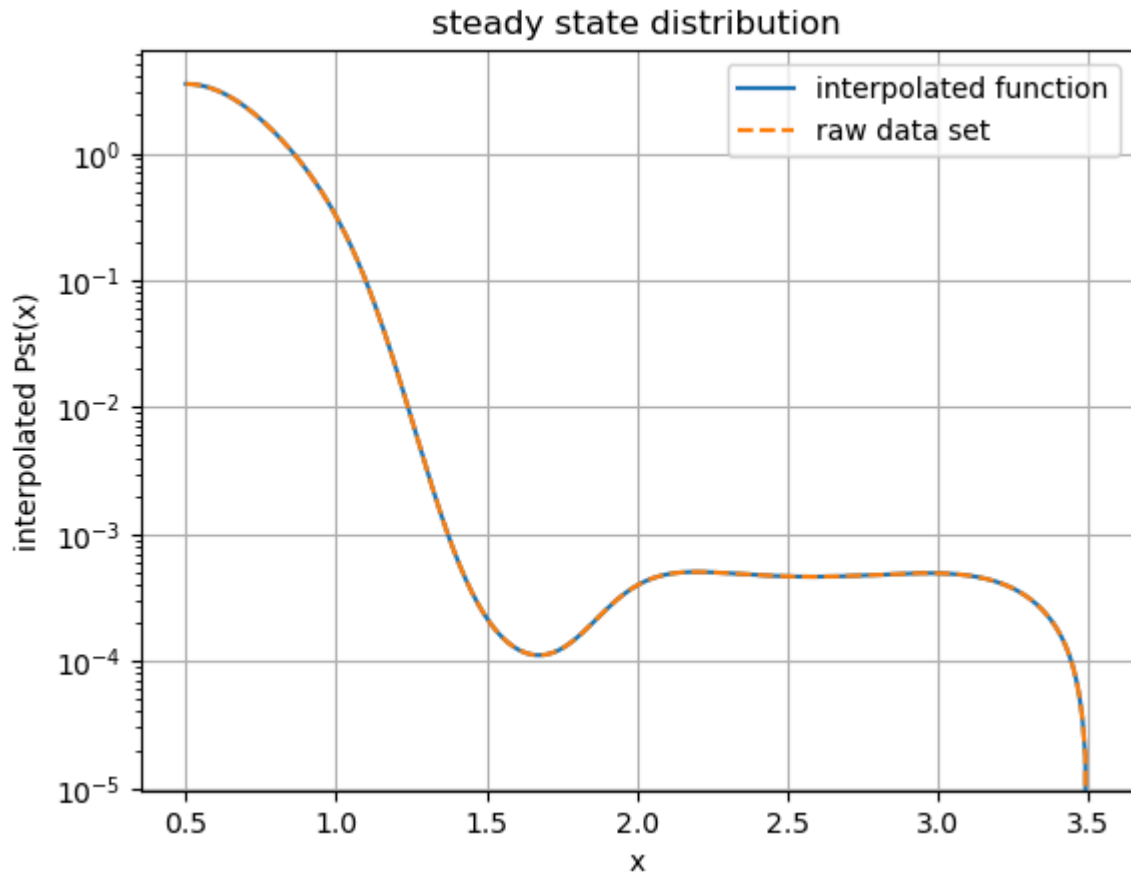



In []:

Reconstruct Free Energy from Numerical Solution of Pst_arr and Numerical Integration of mfpt

```
In [10]: interp_Pst_func = interp1d(x_arr, Pst_arr, kind='cubic', fill_value="extrapolate")
# interp_Pst_func = PchipInterpolator(b_arr, Pst_arr)

plt.semilogy(x_arr, interp_Pst_func(x_arr), label="interpolated function")
plt.semilogy(x_arr, Pst_arr, '--', label="raw data set")
# Plot formatting
plt.xlabel('x')
plt.ylabel('interpolated Pst(x)')
plt.title('steady state distribution')
plt.legend()
plt.grid()
```

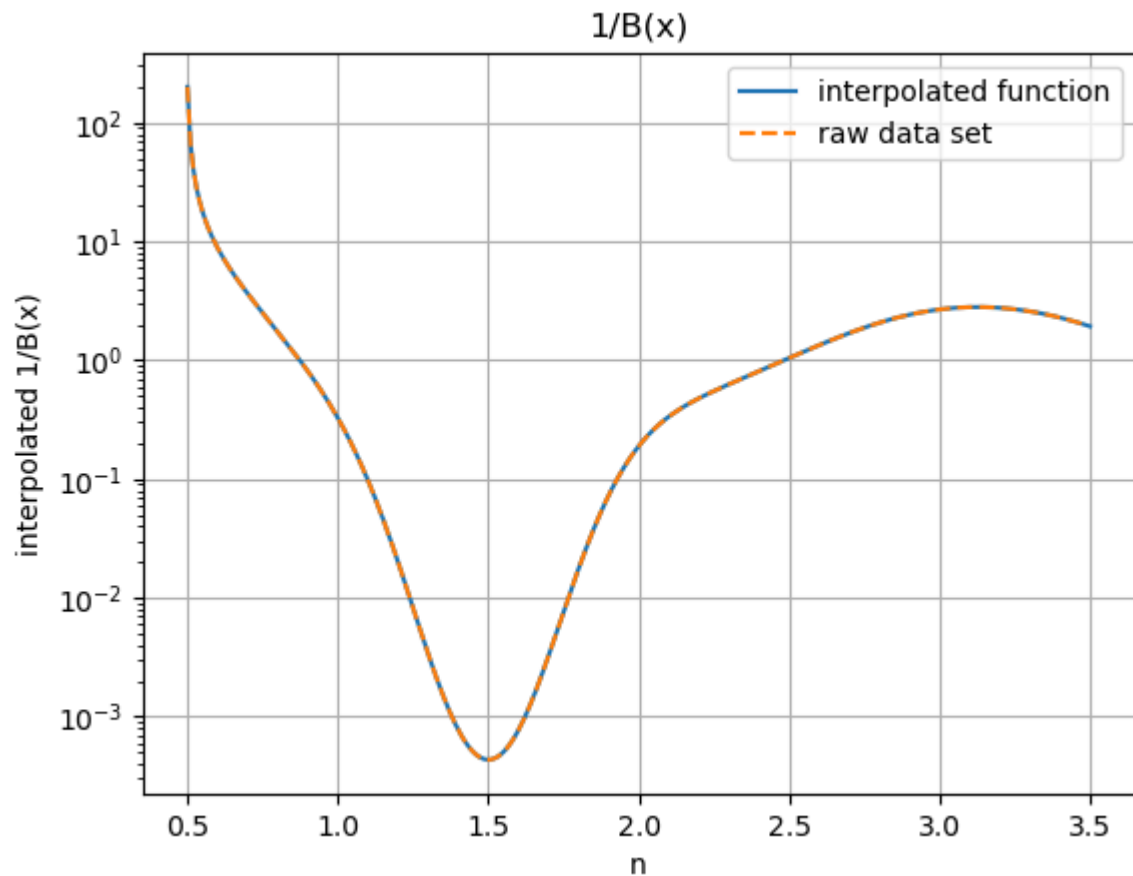


```
In [11]: # Except for the absorbing boundary  $Pst(b) = 0$ , and also avoid  $D(x)=0$ 
integral_Pst_arr = np.zeros(N-1)
Bx_arr = np.zeros(N-1)

for i in range(N-1):
    integral_Pst_arr[i], _ = quad(interp_Pst_func, x_arr[i], x_arr[-1])
    Bx_arr[i] = -1.0/Pst_arr[i]*(integral_Pst_arr[i]-(mfpt_arr[-1]-mfpt_arr[

interp_invertBx_func = interp1d(x_arr[:-1], 1.0/Bx_arr, kind='cubic', fill_v

plt.semilogy(x_arr, interp_invertBx_func(x_arr), label="interpolated function")
plt.semilogy(x_arr[:-1], 1.0/Bx_arr, '--', label="raw data set")
# Plot formatting
plt.xlabel('n')
plt.ylabel('interpolated 1/B(x)')
plt.title('1/B(x)')
plt.legend()
plt.grid()
```



```
In [12]: Bx_arr[:10]
```

```
Out[12]: array([0.005      , 0.01501303, 0.02508193, 0.03525176, 0.0455682 ,
                0.05607776, 0.06682802, 0.07786791, 0.08924796, 0.10102059])
```

```
In [13]: integral_invertBx_arr = np.zeros(N-1)
        beta_Urec1_arr = np.zeros(N-1)

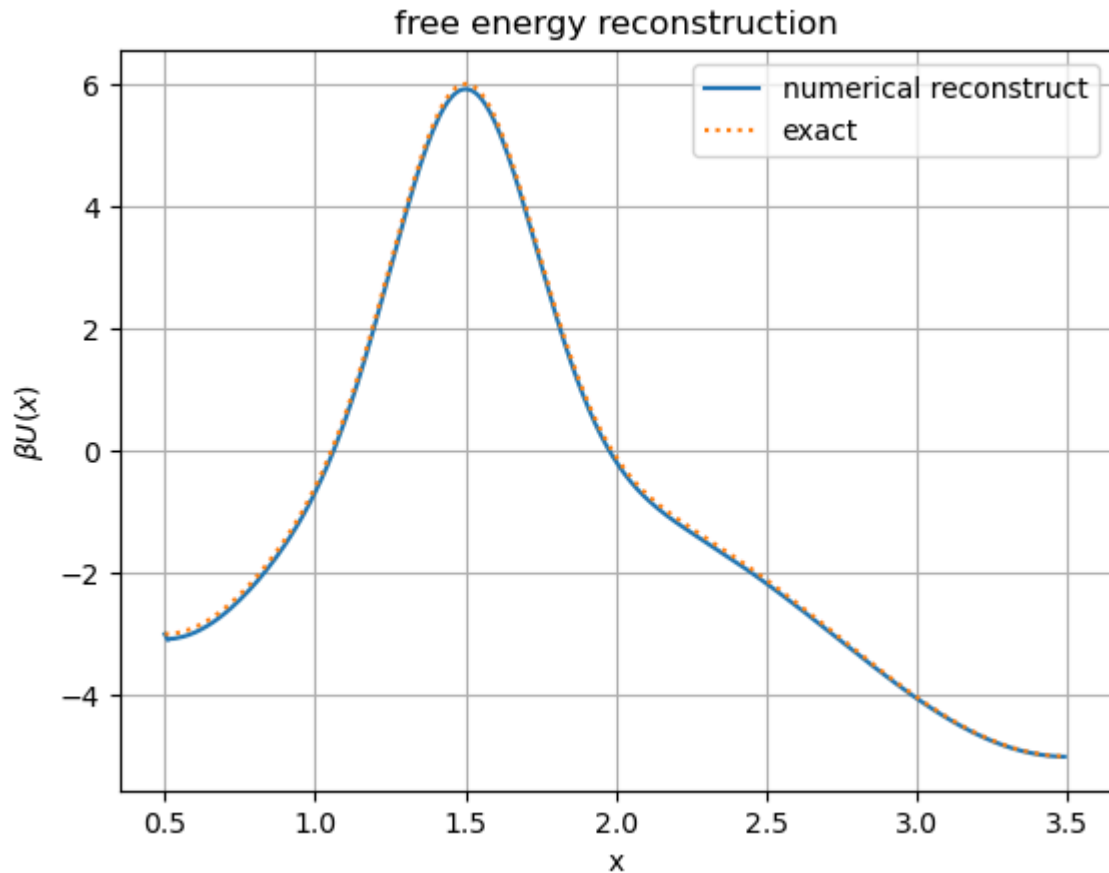
        for i in range(x_arr.size-1):
            # Here x0 is b_arr[0]
            integral_invertBx_arr[i], _ = quad(interp_invertBx_func, x_arr[0], x_arr[i])
            beta_Urec1_arr[i] = beta_U(x_arr[0]) + np.log(Bx_arr[i]/Bx_arr[0]) - integral_invertBx_arr[i]

        print(_)

        plt.plot(x_arr[:-1], beta_Urec1_arr, label="numerical reconstruct")
        plt.plot(x_arr, beta_U(x_arr), ":", label="exact")

        # Plot formatting
        plt.xlabel('x')
        plt.ylabel('$ \beta U(x) $')
        plt.title('free energy reconstruction')
        plt.legend()
        plt.grid()
```

```
7.233454141622772e-08
```



```
In [14]: print(beta_Urec1_arr[0], beta_U(x_arr[0]))
         beta_Urec1_arr[:20]
```

```
-3.000000000000018456 -3.00000000000018456
```

```
Out[14]: array([-3.00000000, -3.0977337, -3.07497171, -3.07458831, -3.06538317,
               -3.05575949, -3.04347431, -3.02914846, -3.01264249, -2.99402583,
               -2.97331624, -2.95054899, -2.92575786, -2.89897971, -2.87025299,
               -2.83961716, -2.80711271, -2.77278039, -2.73666085, -2.69879408])
```

```
In [ ]:
```

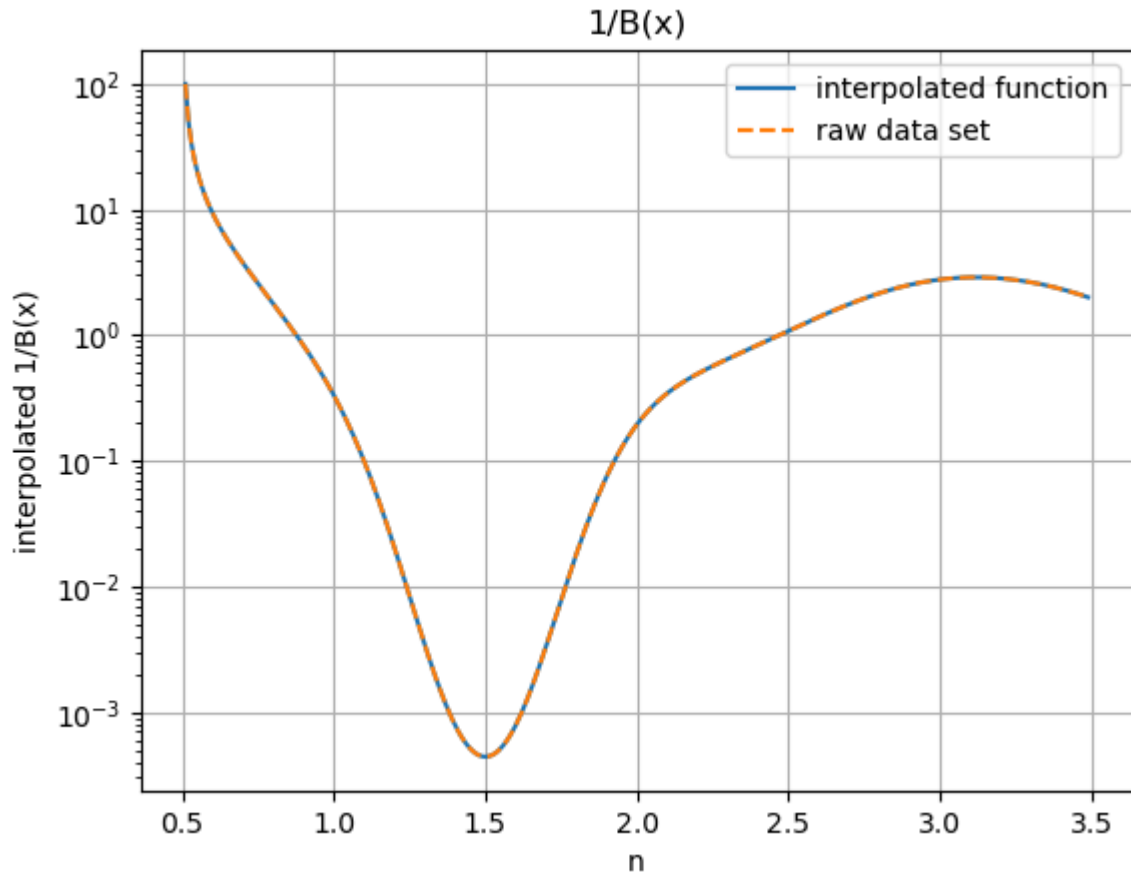
Reconstruct Free Energy from Numerical Integration of mfpt and Pst (st_P_func)

```
In [15]: # Except for the absorbing boundary Pst(b) = 0, D(x)=0, also avoid at reflect
Bx_arr = np.zeros(N-2)
integral_Pst_arr = np.zeros(N-2)
for i in range(N-2):
    integral_Pst_arr[i], _ = quad(st_P_func, x_arr[1+i], x_arr[-1])
    Bx_arr[i] = -1.0/st_P_func(x_arr[1+i])*(integral_Pst_arr[i]-st_flux*(mfpt))

interp_invertBx_func = interp1d(x_arr[1:-1], 1.0/Bx_arr, kind='cubic') # fit

plt.semilogy(x_arr[1:-1], interp_invertBx_func(x_arr[1:-1]), label="interpolated")
plt.semilogy(x_arr[1:-1], 1.0/Bx_arr, '--', label="raw data set")
# Plot formatting
plt.xlabel('n')
```

```
plt.ylabel('interpolated 1/B(x)')
plt.title('1/B(x)')
plt.legend()
plt.grid()
```



```
In [16]: Bx_arr[:10]
```

```
Out[16]: array([0.01000743, 0.02005954, 0.03020131, 0.04047825, 0.05093668,
                0.06162391, 0.07258855, 0.08388076, 0.09555251, 0.10765791])
```

```
In [17]: integral_invertBx_arr = np.zeros(N-2)
        beta_Urec2_arr = np.zeros(N-2)

        for i in range(N-2):
            # Here x0 is x_arr[1]
            integral_invertBx_arr[i], _ = quad(interp_invertBx_func, x_arr[1], x_arr[N-1])
            beta_Urec2_arr[i] = beta_U(x_arr[1]) + np.log(Bx_arr[i]/Bx_arr[0]) - integral_invertBx_arr[i]

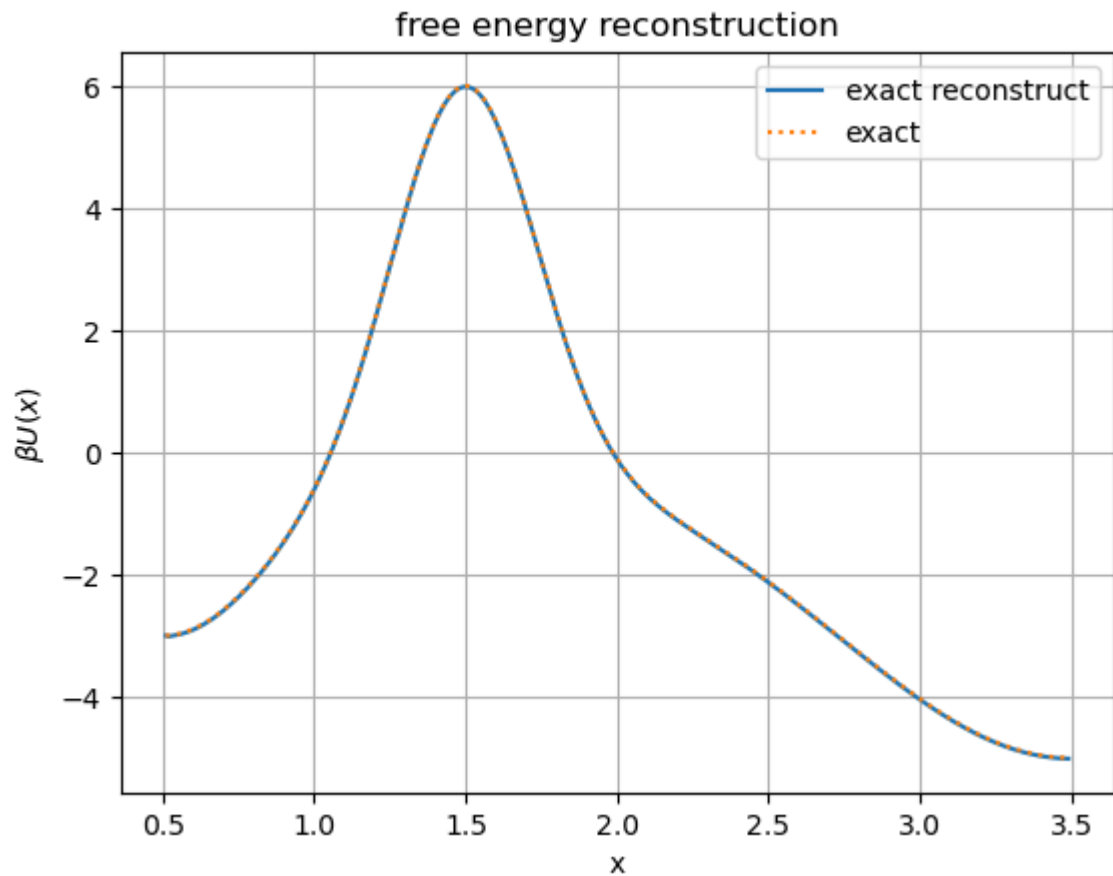
        print(_)

        plt.plot(x_arr[1:-1], beta_Urec2_arr, label="exact reconstruct")
        plt.plot(x_arr[1:-1], beta_U(x_arr[1:-1]), ':', label="exact")

        # Plot formatting
        plt.xlabel('x')
        plt.ylabel('$ \beta U(x) $')
        plt.title('free energy reconstruction')
```

```
plt.legend()
plt.grid()
```

3.26602241456593e-08



```
In [18]: print(f"reconstructed: \n {beta_Urec2_arr[:20]}, \n exat data: \n {beta_U(x_
```

reconstructed:

```
[-2.9988855 -3.01206044 -3.00247252 -2.99572302 -2.9854352 -2.97332585
 -2.95895219 -2.94245886 -2.92383886 -2.90313029 -2.88036291 -2.85557196
 -2.82879398 -2.80006731 -2.76943161 -2.73692725 -2.70259503 -2.66647558
 -2.6286089 -2.58903382],
```

exat data:

```
[-3.          -2.9988855  -2.9955422  -2.9899737  -2.9821878  -2.97219644
 -2.96001549 -2.9456646  -2.92916698 -2.9105491  -2.88984052 -2.86707349
 -2.84228268 -2.81550479 -2.78677821 -2.75614254 -2.72363822 -2.68930603
 -2.6531866  -2.61531993]
```

```
In [ ]:
```

Verification Hill Relation: plot the $1/\text{flux}$, $\tau(b)$, and $2\tau(x^*)$ v.s different location of absorbing boundary

```
In [19]: def exact_flux(a, b):
# Define the inner function to integrate as a function of y
def inner_integrand(y):
return 1.0/D(y)*np.exp(beta_U(y))
```

```

# Define the inner integral as a function of x
def inner_integral(x):
    y_lower = x
    y_upper = b
    result, error = quad(inner_integrand, y_lower, y_upper)
    return result

# Define the outer integral
x_lower = a
x_upper = b

# Define the outer function to integrate (also as a function of x)
def outer_integrand(x):
    return np.exp(-beta_U(x))*inner_integral(x)

# Perform the outer integration
invert_Jst, error = quad(outer_integrand, x_lower, x_upper)
return 1/invert_Jst

```

```

In [20]: # for valid value, exclude the reflecting boundary
Jst_arr = np.zeros(N-1)

for i in np.arange(N-1):
    Jst_arr[i] = exact_flux(x_arr[0], x_arr[1+i])

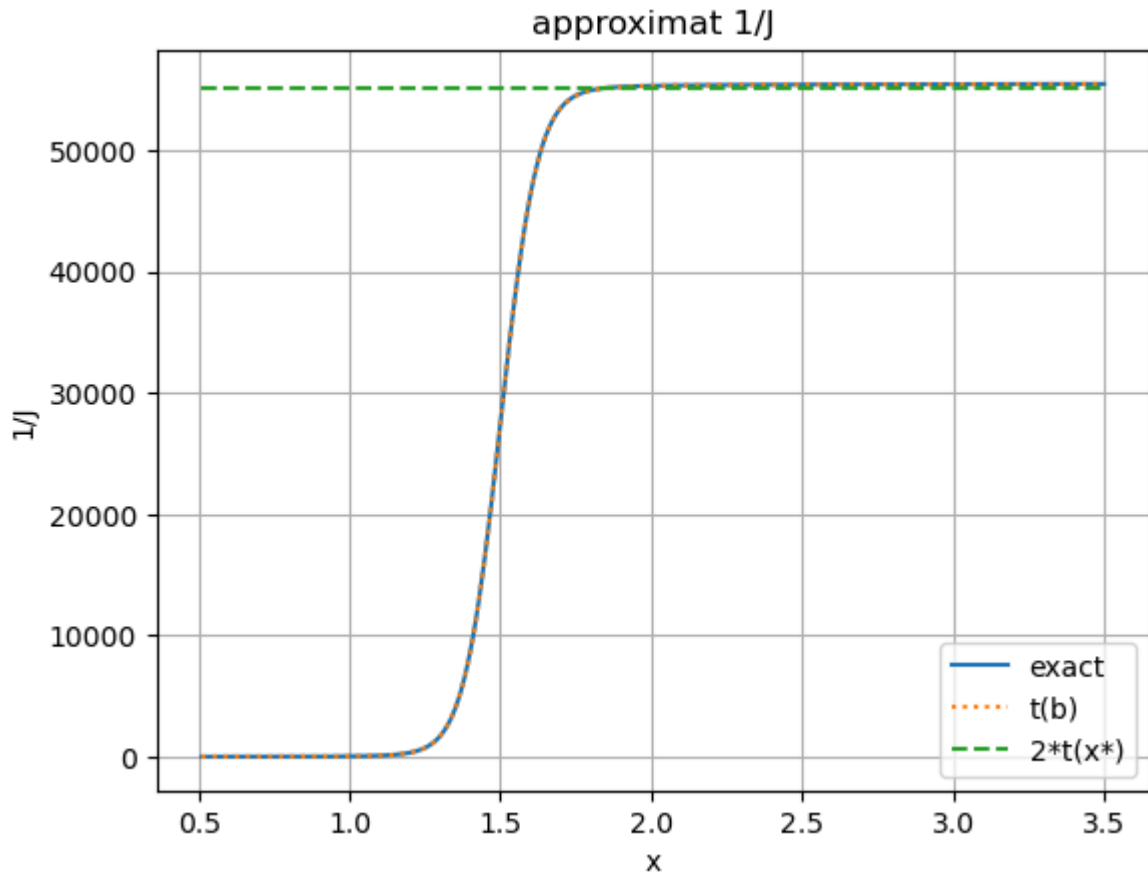
```

```

In [21]: plt.plot(x_arr[1:], 1/Jst_arr, label="exact")
plt.plot(x_arr[1:], mfpt_arr[1:], ':', label="t(b)")
plt.plot(x_arr[1:], 2*t_star*np.ones(x_arr[1:].size), '--', label="2*t(x*)")

# Plot formatting
plt.xlabel('x')
plt.ylabel('1/J')
plt.title('approximat 1/J')
plt.legend()
plt.grid()

```



```
In [22]: print(f"1/J(b;x0):\n {1/Jst_arr[:20]}, \n t(b;x0): \n {mfpt_arr[1:21]}")
```

```
1/J(b;x0):
[0.00500186 0.02002976 0.04515082 0.08047742 0.12616781 0.18242703
 0.24950807 0.3277133  0.41739609 0.51896285 0.63287527 0.75965299
 0.89987648 1.0541905  1.22330782 1.40801353 1.6091698  1.82772134
 2.06470142 2.32123875],
t(b;x0):
[0.00500186 0.02002976 0.04515082 0.08047742 0.12616781 0.18242703
 0.24950807 0.3277133  0.41739609 0.51896285 0.63287527 0.75965299
 0.89987648 1.0541905  1.22330782 1.40801353 1.6091698  1.82772134
 2.06470142 2.32123875]
```

```
In [ ]:
```

Transfer Matrix with Recycling Boundary Condition

```
In [23]: from transfer_matrix_reptile import TransferMatrix_ReInAb
```

```
ria_trans = TransferMatrix_ReInAb(h, x_arr, beta_U, 0)
```

```
In [24]: # plt.plot(x_arr[:-1], ria_trans.steady_state, label="RIA")
# plt.plot(x_arr, st_P_arr, '--', label="exact")
# plt.plot(x_arr, Pst_arr, ':', label="numerical")
plt.semilogy(x_arr[:-1], ria_trans.steady_state, label="RIA")
plt.semilogy(x_arr, st_P_arr, '--', label="exact")
plt.semilogy(x_arr, Pst_arr, ':', label="numerical")
```



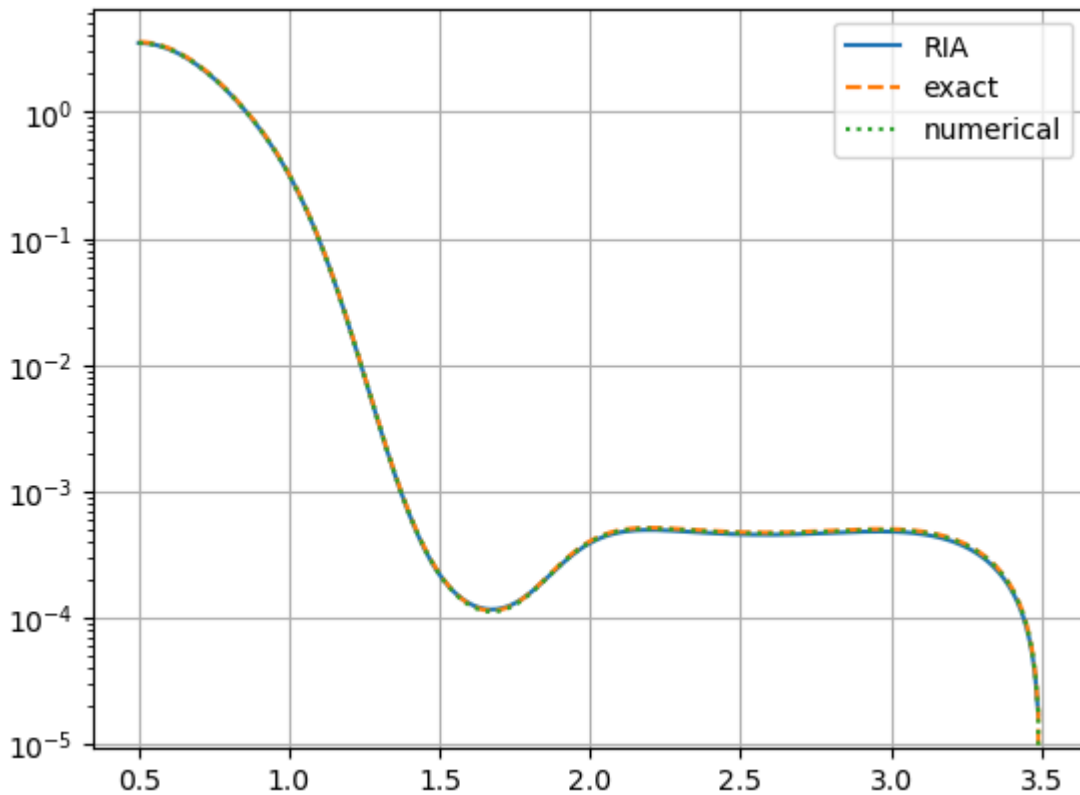
```
plt.legend()  
plt.grid()
```

```
/home/yjiang23/anaconda3/lib/python3.11/site-packages/matplotlib/cbook.py:16  
99: ComplexWarning: Casting complex values to real discards the imaginary part
```

```
    return math.isfinite(val)
```

```
/home/yjiang23/anaconda3/lib/python3.11/site-packages/matplotlib/cbook.py:13  
45: ComplexWarning: Casting complex values to real discards the imaginary part
```

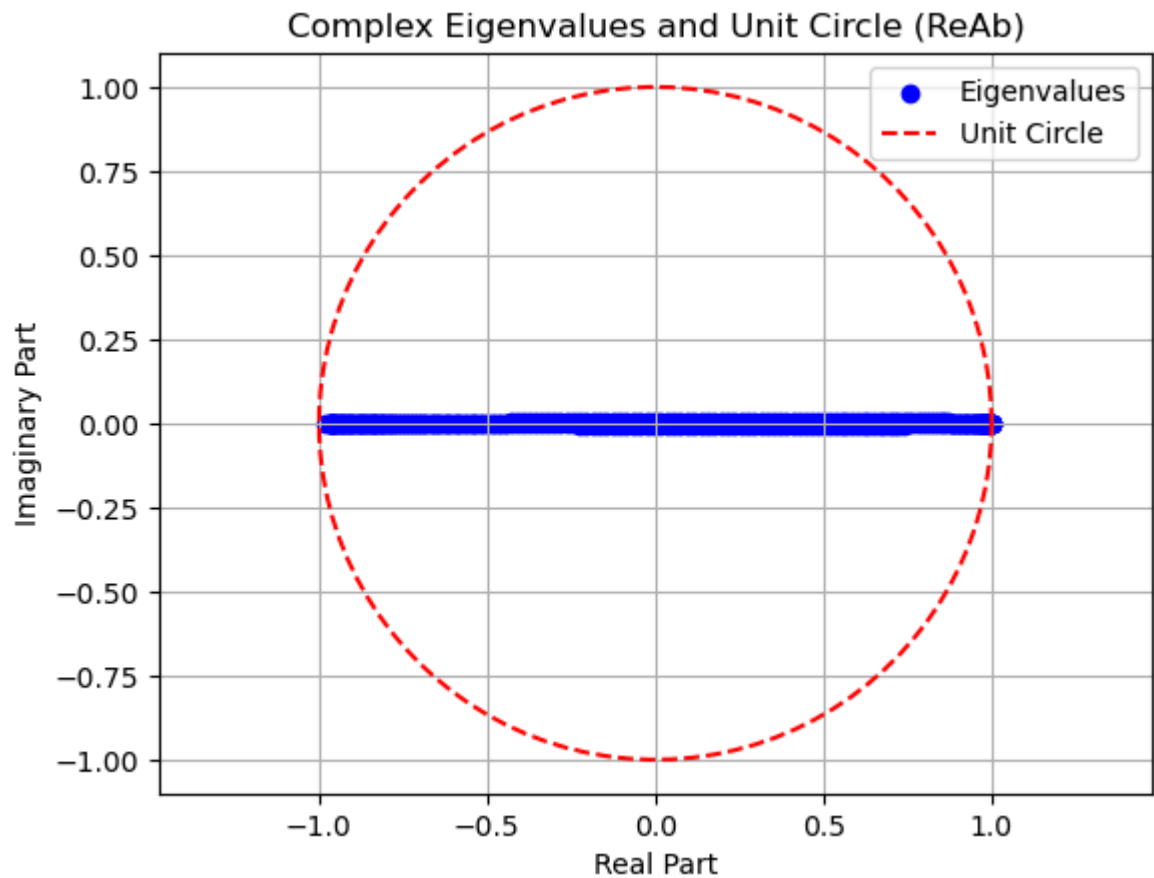
```
    return np.asarray(x, float)
```



```
In [25]: ria_trans.plot_eigenvalues()  
print(ria_trans.eig6_w)
```

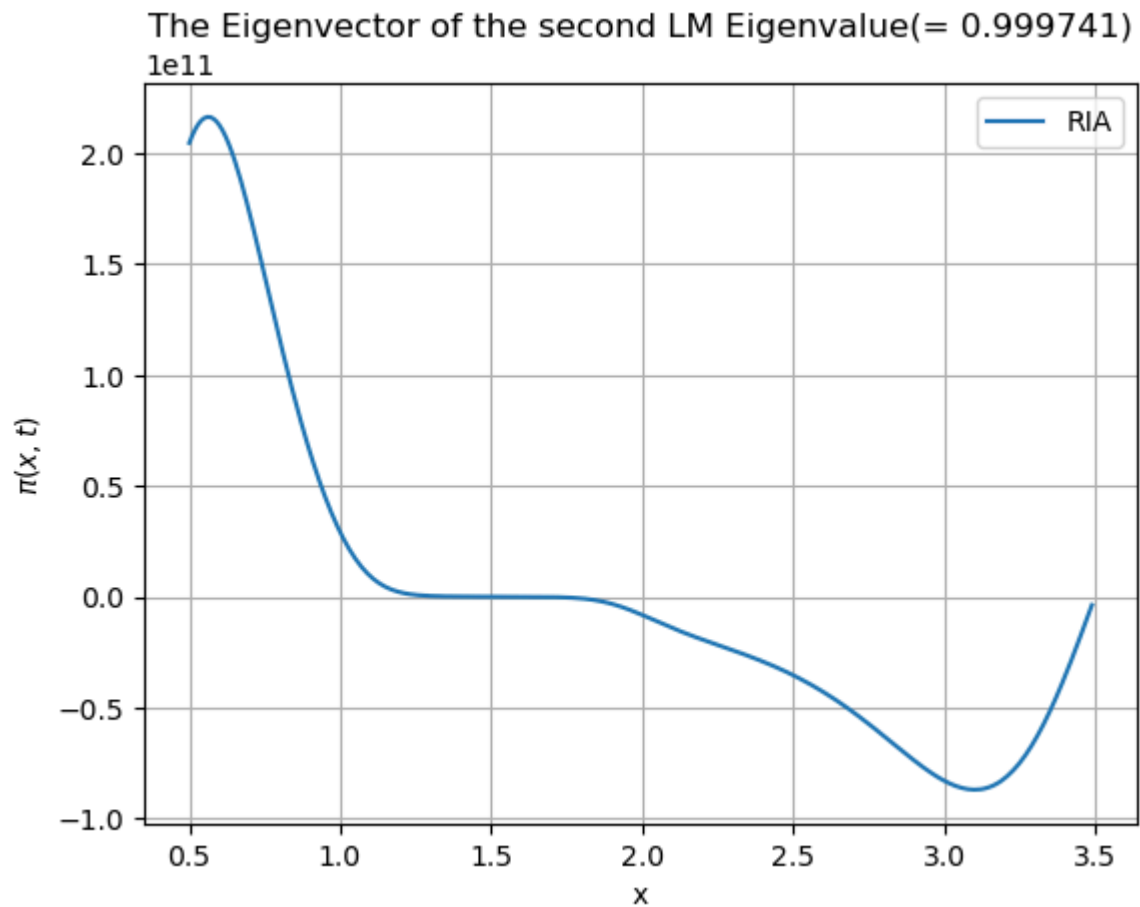
```
/home/yjiang23/Desktop/research/MFPT/MFPT_reconst_experiment/transfer_matrix  
_reptile.py:547: RuntimeWarning: k >= N - 1 for N * N square matrix. Attempt  
ing to use scipy.linalg.eig instead.
```

```
    eigenvalues, eigenvectors_mat = eigs(self.trans_mat, k=num_eigenvalues)
```



```
[1.          +0.j 0.99974063+0.j 0.99938798+0.j 0.99859263+0.j
 0.99807524+0.j 0.99749394+0.j]
```

```
In [26]: plt.plot(x_arr[:-1], 1.0/(h*np.sum(ria_trans.eig6_v[:, 1]))*ria_trans.eig6_v
# Plot formatting
plt.xlabel('x')
plt.ylabel('$ \pi(x,t) $')
plt.title(f'The Eigenvector of the second LM Eigenvalue(= {ria_trans.eig6_w[
plt.legend()
plt.grid(True)
```



In []:

Extract Steady State Distribution and MFPT from Simulation

```
In [27]: from mfpt_Pst_RW_simulate import simulate_ReAb, simulate_ReAb_accelerate

num_particles = 30
init_position_arr = a*np.ones(num_particles, dtype=float)
simu_x_arr = np.linspace(a, b, 301)
hx = (b-a)/(301-1)
ht = hx**2/(2*D0)
n_arr = np.arange(a, b+0.01, 0.01)
n_arr = np.round(n_arr, decimals=5)
hx == 0.01
```

Out[27]: True

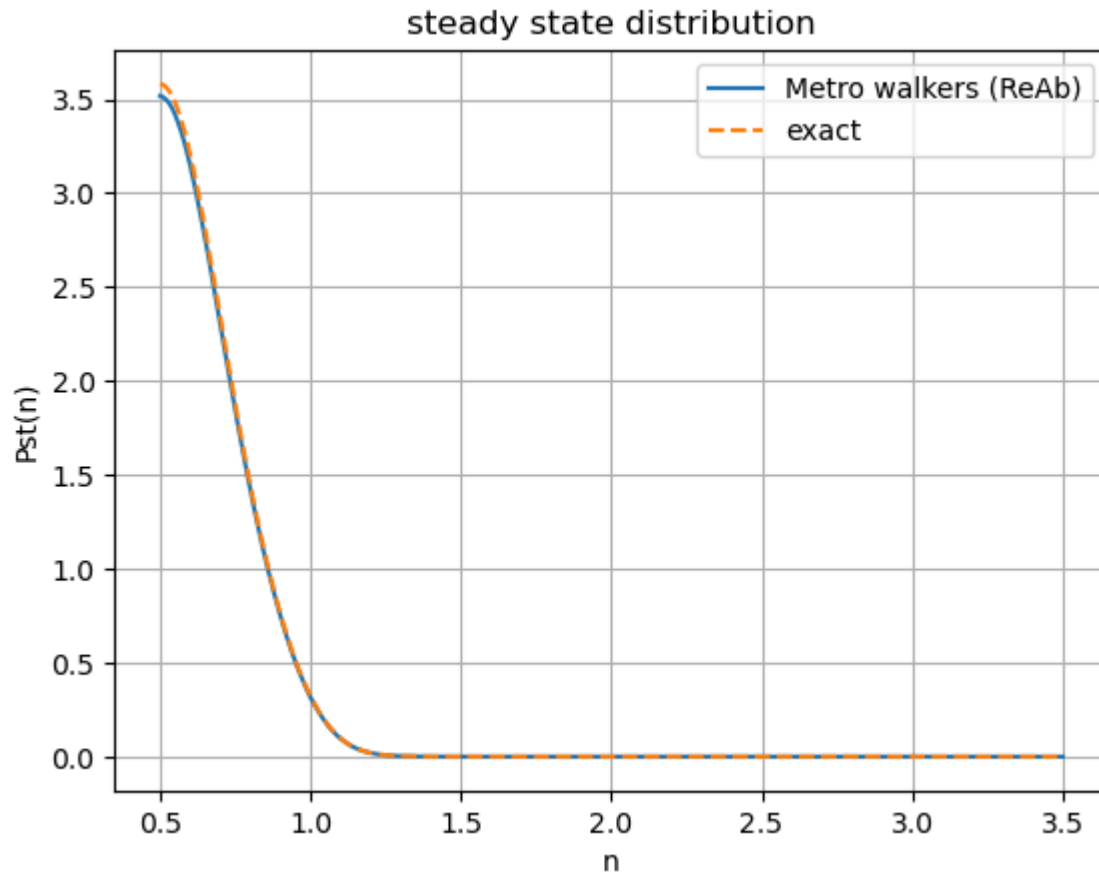
```
In [28]: count_n, ti_n = simulate_ReAb_accelerate(init_position_arr=init_position_arr)
```

```
In [29]: Pst_n = count_n/(hx*np.sum(count_n))
plt.plot(n_arr, Pst_n, label="Metro walkers (ReAb)")
plt.plot(x_arr, st_P_arr, '--', label="exact")
# plt.plot(x_arr[:-1], ria_trans.steady_state, label="RIA")
# plt.plot(x_arr[:-1], 1.0/(h*np.sum(ria_trans.eig6_v[:, 1]))*ria_trans.eig6_v[:, 1], label="exact")
```

```

# Plot formatting
plt.xlabel('n')
plt.ylabel('Pst(n)')
plt.title('steady state distribution')
plt.legend()
plt.grid()

```

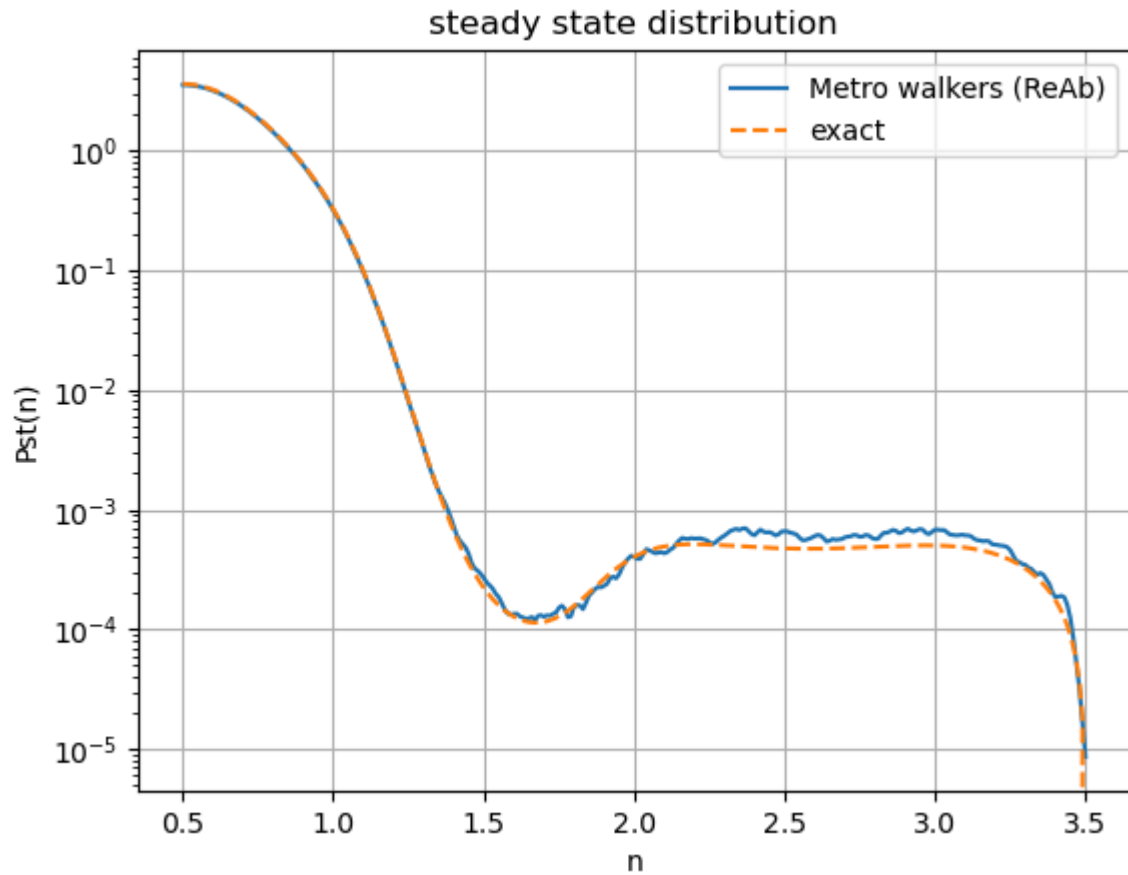


```

In [30]: plt.semilogy(n_arr, Pst_n, label="Metro walkers (ReAb)")
# plt.semilogy(x_arr[:-1], ria_trans.steady_state, label="RIA")
# plt.semilogy(x_arr[:-1], 1.0/(h*np.sum(ria_trans.eig6_v[:, 1]))*ria_trans.
plt.semilogy(x_arr, st_P_arr, '--', label="exact")

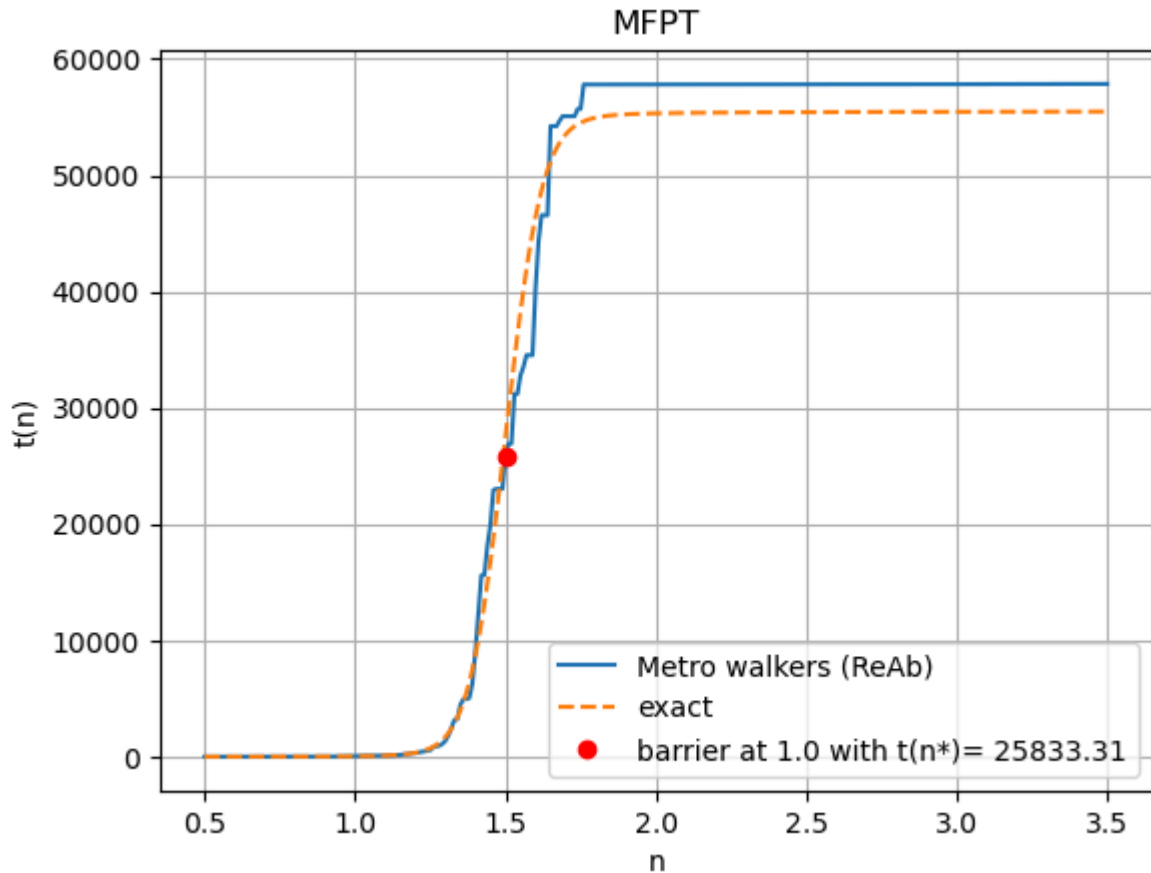
# Plot formatting
plt.xlabel('n')
plt.ylabel('Pst(n)')
plt.title('steady state distribution')
plt.legend()
plt.grid()

```



```
In [44]: mfpt_simu_arr = np.mean(ti_n, axis=0)
idx_barrier = np.where(n_arr == 1.5)[0][0]
t_star = mfpt_simu_arr[idx_barrier]

plt.plot(n_arr, mfpt_simu_arr, label="Metro walkers (ReAb)")
plt.plot(x_arr, mfpt_arr, '--', label="exact")
plt.plot(1.5, t_star, 'ro', label=f'barrier at 1.0 with t(n*)={t_star: .2f}')
# Plot formatting
plt.xlabel('n')
plt.ylabel('t(n)')
plt.title('MFPT')
plt.legend()
plt.grid()
```



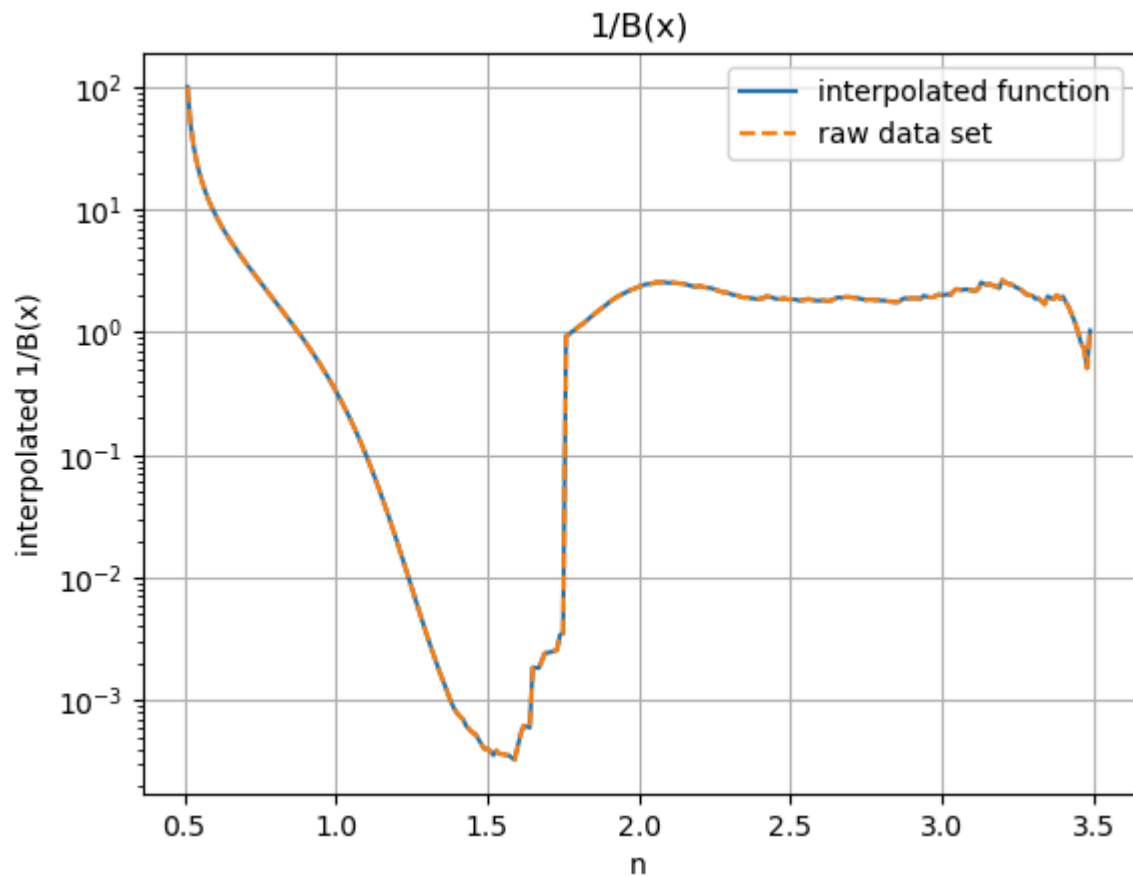
Reconstruct Free Energy Using mfpt (mfpt_simu_arr)
and Pst (Pst_n) extracted from Simulation

(1) Exact Steady State Distribution with simulated MFPT

```
In [32]: # Except for the absorbing boundary  $P_{st}(b) = 0$ ,  $D(x)=0$ , also avoid at reflection
Bx_arr = np.zeros(N-2)
integral_Pst_arr = np.zeros(N-2)
for i in range(N-2):
    integral_Pst_arr[i], _ = quad(st_P_func, x_arr[1+i], x_arr[-1])
    Bx_arr[i] = -1.0/st_P_func(x_arr[1+i])*(integral_Pst_arr[i]-(mfpt_simu_a

interp_invertBx_func = interp1d(x_arr[1:-1], 1.0/Bx_arr, kind='cubic') # file

plt.semilogy(x_arr[1:-1], interp_invertBx_func(x_arr[1:-1]), label="interpolated 1/B(x)")
plt.semilogy(x_arr[1:-1], 1.0/Bx_arr, '--', label="raw data set")
# Plot formatting
plt.xlabel('n')
plt.ylabel('interpolated 1/B(x)')
plt.title('1/B(x)')
plt.legend()
plt.grid()
```



```
In [33]: integral_invertBx_arr = np.zeros(N-2)
beta_Grec2_arr = np.zeros(N-2)

for i in range(N-2):
    # Here x0 is x_arr[1]
    integral_invertBx_arr[i], _ = quad(interp_invertBx_func, x_arr[1], x_arr
    beta_Grec2_arr[i] = beta_U(x_arr[1])+np.log(Bx_arr[i]/Bx_arr[0])-integra

print(_)

plt.plot(x_arr[1:-1], beta_Grec2_arr, label="exact Pst with simulated MFPT")
plt.plot(x_arr[1:-1], beta_U(x_arr[1:-1]), ':', label="exact")

# Plot formatting
plt.xlabel('n')
plt.ylabel('$ \beta \Delta G(n) $')
plt.title('free energy reconstruction')
plt.legend()
plt.grid()
```

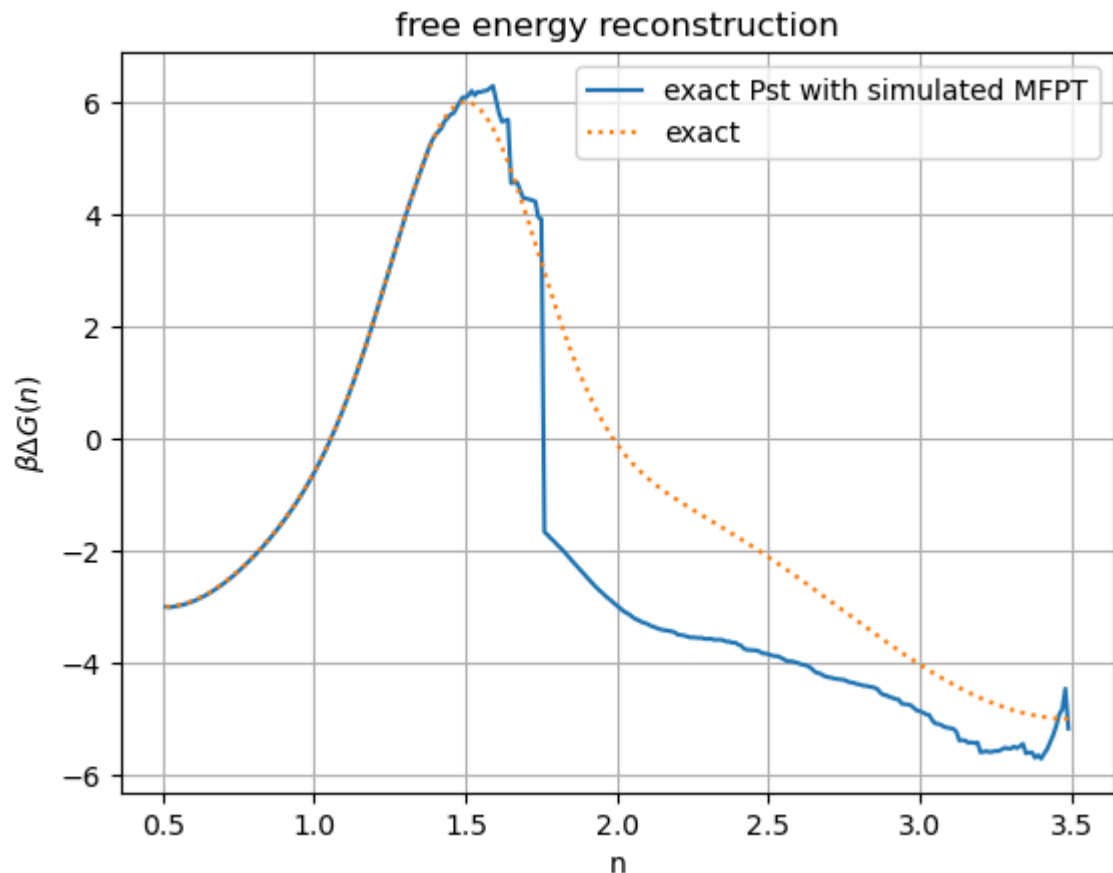
```
/tmp/ipykernel_789248/3282593085.py:6: IntegrationWarning: The maximum number of subdivisions (50) has been achieved.
```

If increasing the limit yields no improvement it is advised to analyze the integrand in order to determine the difficulties. If the position of a

local difficulty can be determined (singularity, discontinuity) one will probably gain from splitting up the interval and calling the integrator on the subranges. Perhaps a special-purpose integrator should be used.

```
integral_invertBx_arr[i], _ = quad(interp_invertBx_func, x_arr[1], x_arr[1+i])
```

```
0.004272760156140976
```



(2) Transfer Matrix Steady State Distribution with exact MFPT and then with simulated MFPT

```
In [34]: # interp_Pst_func = interp1d(x_arr[:-1], np.array(1.0/(h*np.sum(ria_trans.eig6_v[:, 1]))*r
interp_Pst_func = interp1d(x_arr[:-1], np.array(ria_trans.steady_state, dtype=float))
# interp_Pst_func = PchipInterpolator(b_arr, Pst_arr)

plt.semilogy(x_arr[:-1], interp_Pst_func(x_arr[:-1]), label="interpolated function")
# plt.semilogy(x_arr[:-1], np.array(1.0/(h*np.sum(ria_trans.eig6_v[:, 1]))*r
plt.semilogy(x_arr[:-1], ria_trans.steady_state, '--', label="raw data set")

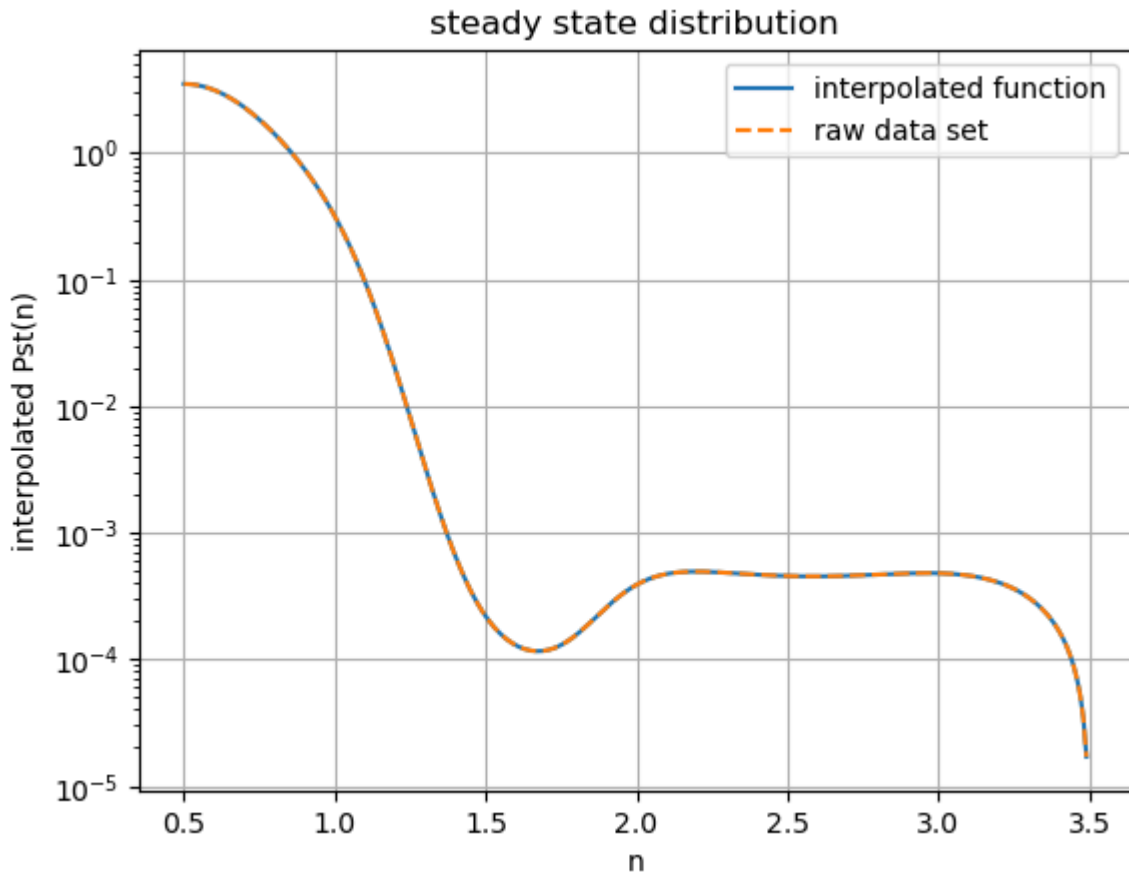
# Plot formatting
plt.xlabel('n')
plt.ylabel('interpolated Pst(n)')
plt.title('steady state distribution')
```



```
plt.legend()
plt.grid()
```

/tmp/ipykernel_789248/3766657854.py:2: ComplexWarning: Casting complex values to real discards the imaginary part

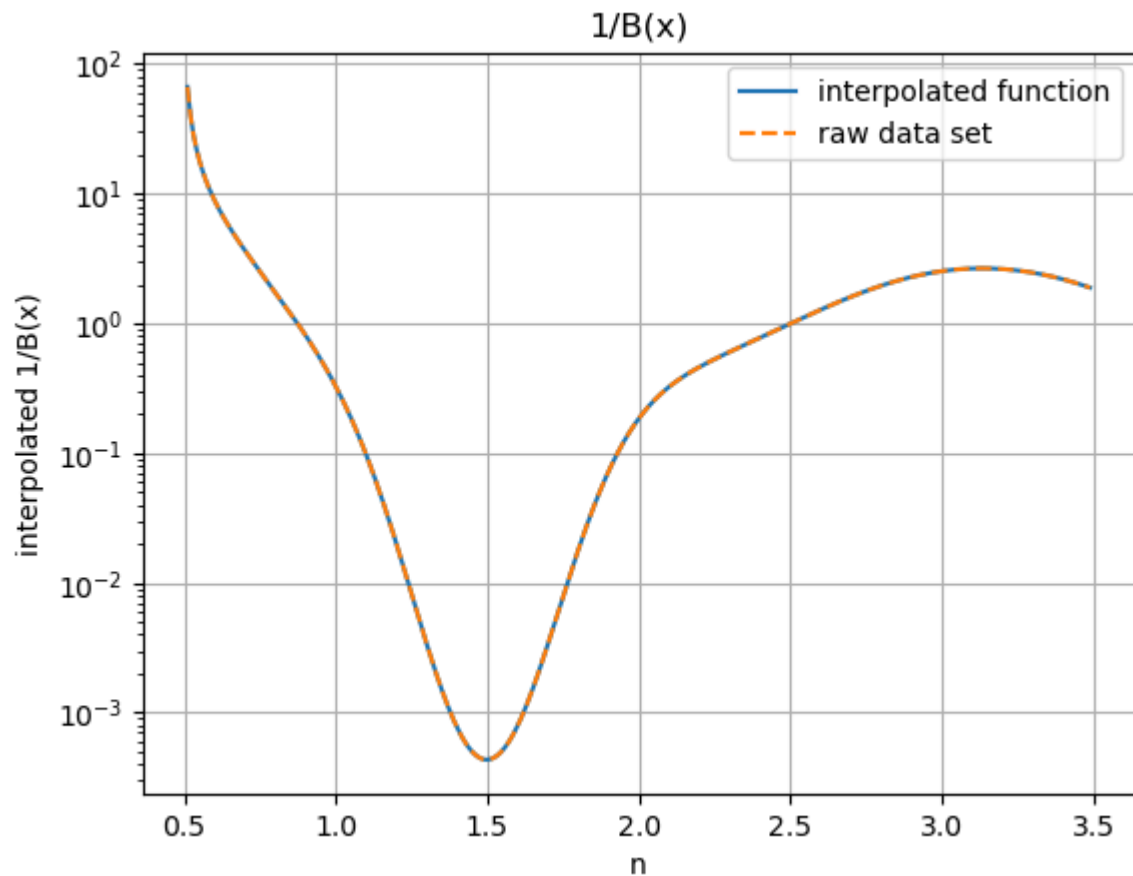
```
interp_Pst_func = interp1d(x_arr[:-1], np.array(ria_trans.steady_state, dtype=float), kind='cubic', fill_value="extrapolate")
```



```
In [35]: # Except for the absorbing boundary  $Pst(b) = 0$ ,  $D(x)=0$ , also avoid at reflection
Bx_arr = np.zeros(N-2)
integral_Pst_arr = np.zeros(N-2)
for i in range(N-2):
    integral_Pst_arr[i], _ = quad(interp_Pst_func, x_arr[1+i], x_arr[-1])
    Bx_arr[i] = -1.0/interp_Pst_func(x_arr[1+i])*(integral_Pst_arr[i]-(mfpt_

interp_invertBx_func = interp1d(x_arr[1:-1], 1.0/Bx_arr, kind='cubic') # file

plt.semilogy(x_arr[1:-1], interp_invertBx_func(x_arr[1:-1]), label="interpolated 1/B(x)")
plt.semilogy(x_arr[1:-1], 1.0/Bx_arr, '--', label="raw data set")
# Plot formatting
plt.xlabel('n')
plt.ylabel('interpolated 1/B(x)')
plt.title('1/B(x)')
plt.legend()
plt.grid()
```



```
In [36]: integral_invertBx_arr = np.zeros(N-2)
beta_Grec2_arr = np.zeros(N-2)

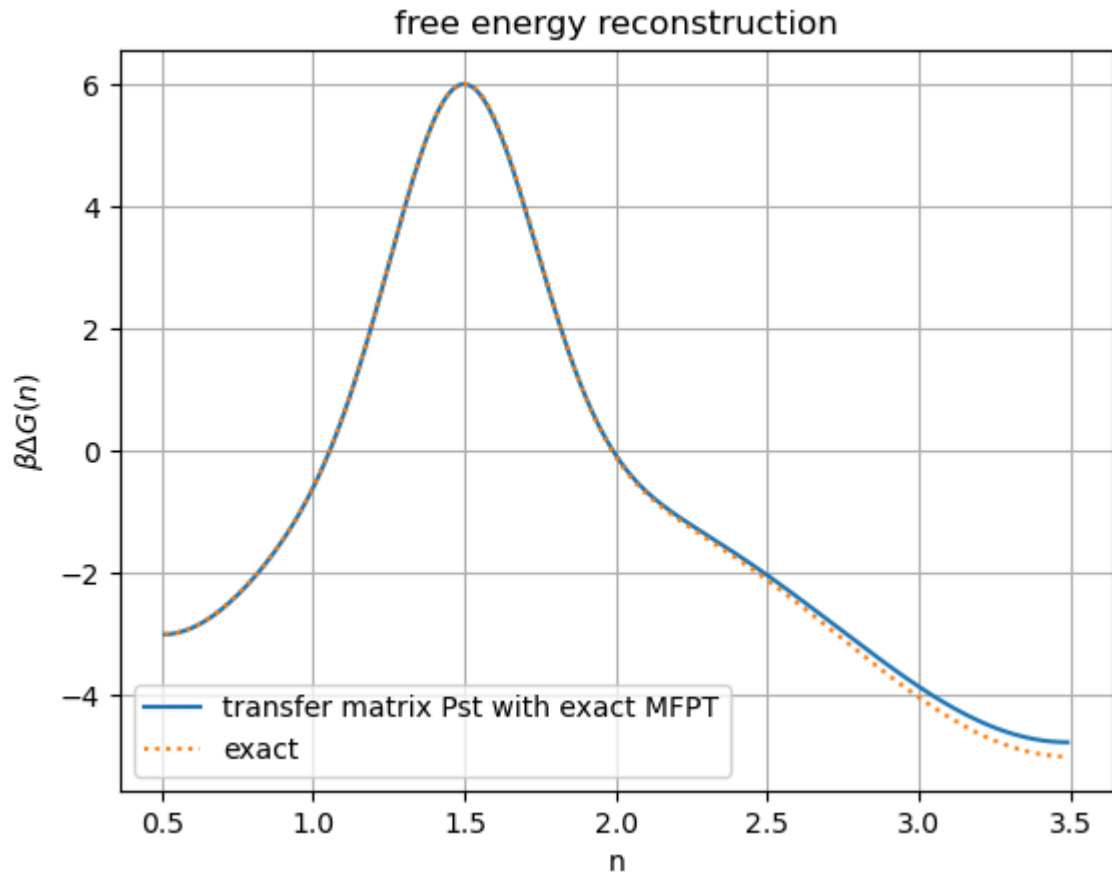
for i in range(N-2):
    # Here x0 is x_arr[1]
    integral_invertBx_arr[i], _ = quad(interp_invertBx_func, x_arr[1], x_arr
    beta_Grec2_arr[i] = beta_U(x_arr[1])+np.log(Bx_arr[i]/Bx_arr[0])-integra

print(_)

plt.plot(x_arr[1:-1], beta_Grec2_arr, label="transfer matrix Pst with exact
plt.plot(x_arr[1:-1], beta_U(x_arr[1:-1]), ':', label="exact")

# Plot formatting
plt.xlabel('n')
plt.ylabel('$ \\beta \\Delta G(n) $')
plt.title('free energy reconstruction')
plt.legend()
plt.grid()
```

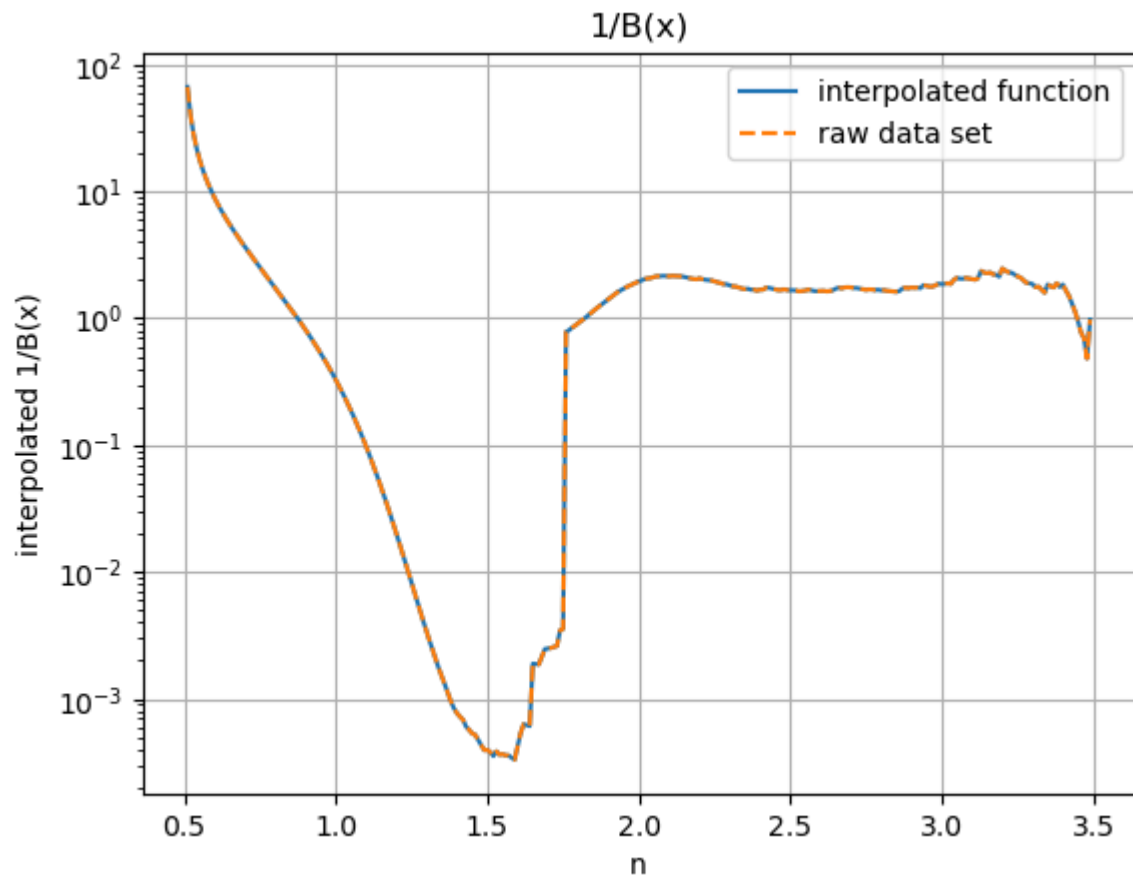
7.050729470223247e-08



```
In [37]: # Except for the absorbing boundary  $Pst(b) = 0$ ,  $D(x)=0$ , also avoid at reflection
Bx_arr = np.zeros(N-2)
integral_Pst_arr = np.zeros(N-2)
for i in range(N-2):
    integral_Pst_arr[i], _ = quad(interp_Pst_func, x_arr[1+i], x_arr[-1])
    Bx_arr[i] = -1.0/interp_Pst_func(x_arr[1+i])*(integral_Pst_arr[i]-(mfpt_

interp_invertBx_func = interp1d(x_arr[1:-1], 1.0/Bx_arr, kind='cubic') # file

plt.semilogy(x_arr[1:-1], interp_invertBx_func(x_arr[1:-1]), label="interpolated 1/B(x)")
plt.semilogy(x_arr[1:-1], 1.0/Bx_arr, '--', label="raw data set")
# Plot formatting
plt.xlabel('n')
plt.ylabel('interpolated 1/B(x)')
plt.title('1/B(x)')
plt.legend()
plt.grid()
```



```
In [38]: integral_invertBx_arr = np.zeros(N-2)
beta_Grec2_arr = np.zeros(N-2)

for i in range(N-2):
    # Here x0 is x_arr[1]
    integral_invertBx_arr[i], _ = quad(interp_invertBx_func, x_arr[1], x_arr
    beta_Grec2_arr[i] = beta_U(x_arr[1])+np.log(Bx_arr[i]/Bx_arr[0])-integra

print(_)

plt.plot(x_arr[1:-1], beta_Grec2_arr, label="transfer matrix Pst with simula
plt.plot(x_arr[1:-1], beta_U(x_arr[1:-1]), ':', label="exact")

# Plot formatting
plt.xlabel('n')
plt.ylabel('$ \\beta \\Delta G(n) $')
plt.title('free energy reconstruction')
plt.legend()
plt.grid()
```

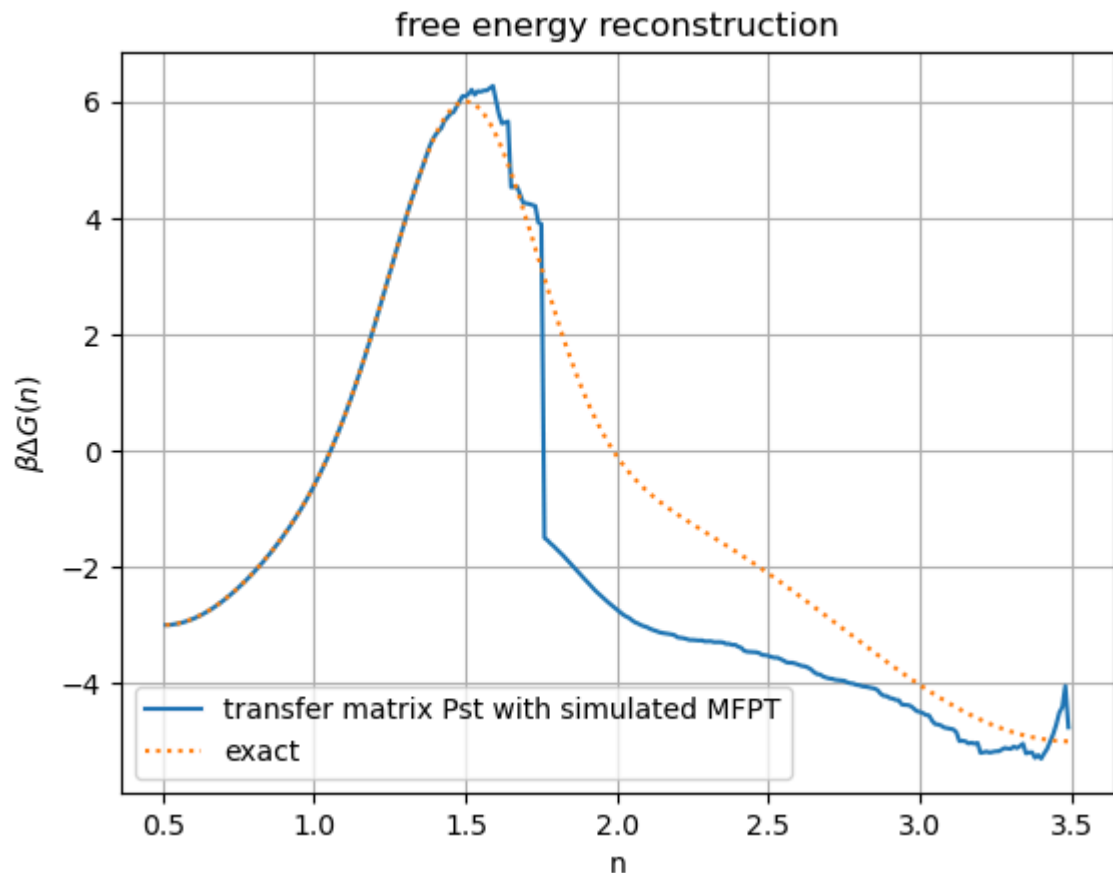
```
/tmp/ipykernel_789248/683931227.py:6: IntegrationWarning: The maximum number of subdivisions (50) has been achieved.
```

If increasing the limit yields no improvement it is advised to analyze the integrand in order to determine the difficulties. If the position of a

local difficulty can be determined (singularity, discontinuity) one will probably gain from splitting up the interval and calling the integrator on the subranges. Perhaps a special-purpose integrator should be used.

```
integral_invertBx_arr[i], _ = quad(interp_invertBx_func, x_arr[1], x_arr[1+i])
```

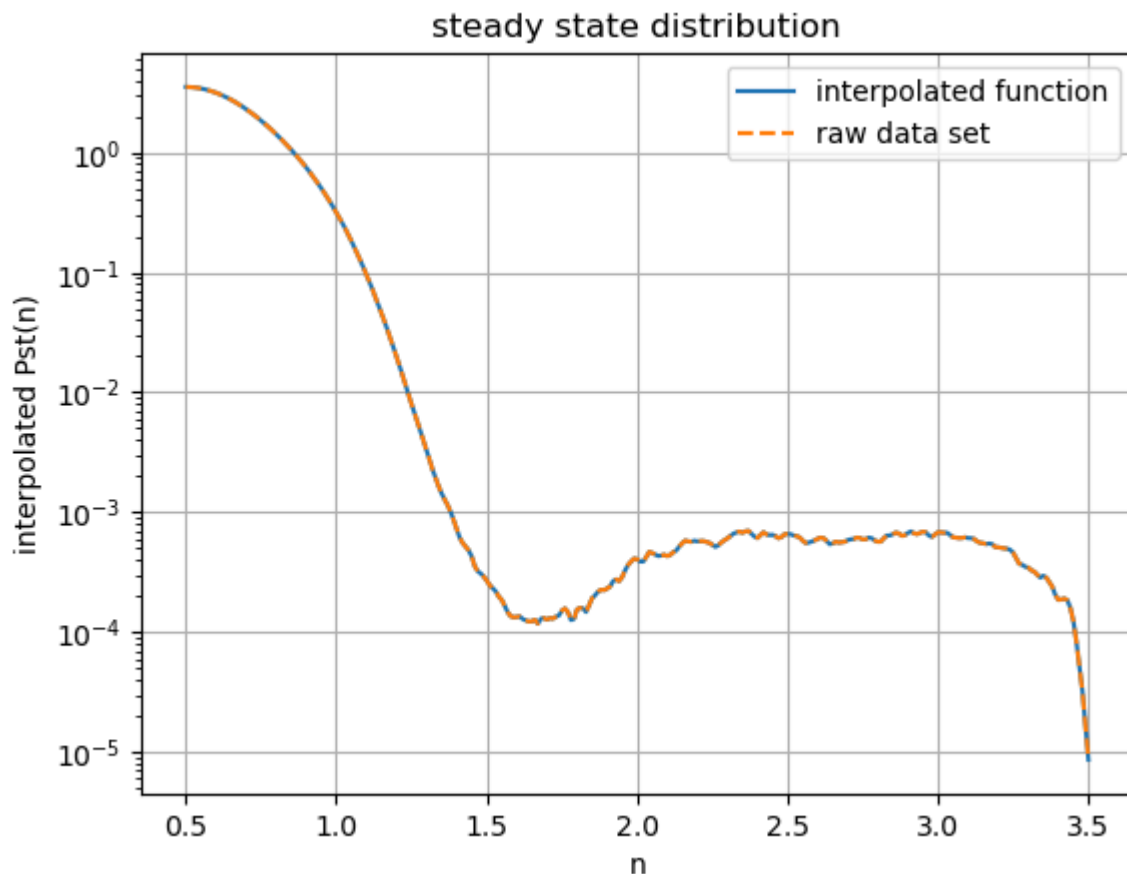
```
0.004042818371613879
```



(3) Simulated Steady State Distribution with exact MFPT and then with simulated MFPT

```
In [39]: interp_simu_Pst_func = interp1d(simu_x_arr, Pst_n, kind='cubic', fill_value=
# interp_Pst_func = PchipInterpolator(b_arr, Pst_arr)

plt.semilogy(simu_x_arr, interp_simu_Pst_func(simu_x_arr), label="interpolat
plt.semilogy(simu_x_arr, Pst_n, '--', label="raw data set")
# Plot formatting
plt.xlabel('n')
plt.ylabel('interpolated Pst(n)')
plt.title('steady state distribution')
plt.legend()
plt.grid()
```



```
In [40]: # Except for the absorbing boundary  $Pst(b) = 0$ ,  $D(x)=0$ , also avoid at reflection
simu_Bx_arr = np.zeros(N-2)
integral_Pst_arr = np.zeros(N-2)
for i in range(N-2):
    integral_Pst_arr[i], _ = quad(interp_simu_Pst_func, simu_x_arr[1+i], simu_x_arr[-1])
    simu_Bx_arr[i] = -1.0/Pst_n[1+i]*(integral_Pst_arr[i]-(mfpt_arr[-1]-mfpt_arr[i]))

interp_simu_invertBx_func = interp1d(x_arr[1:-1], 1.0/simu_Bx_arr, kind='cubic')

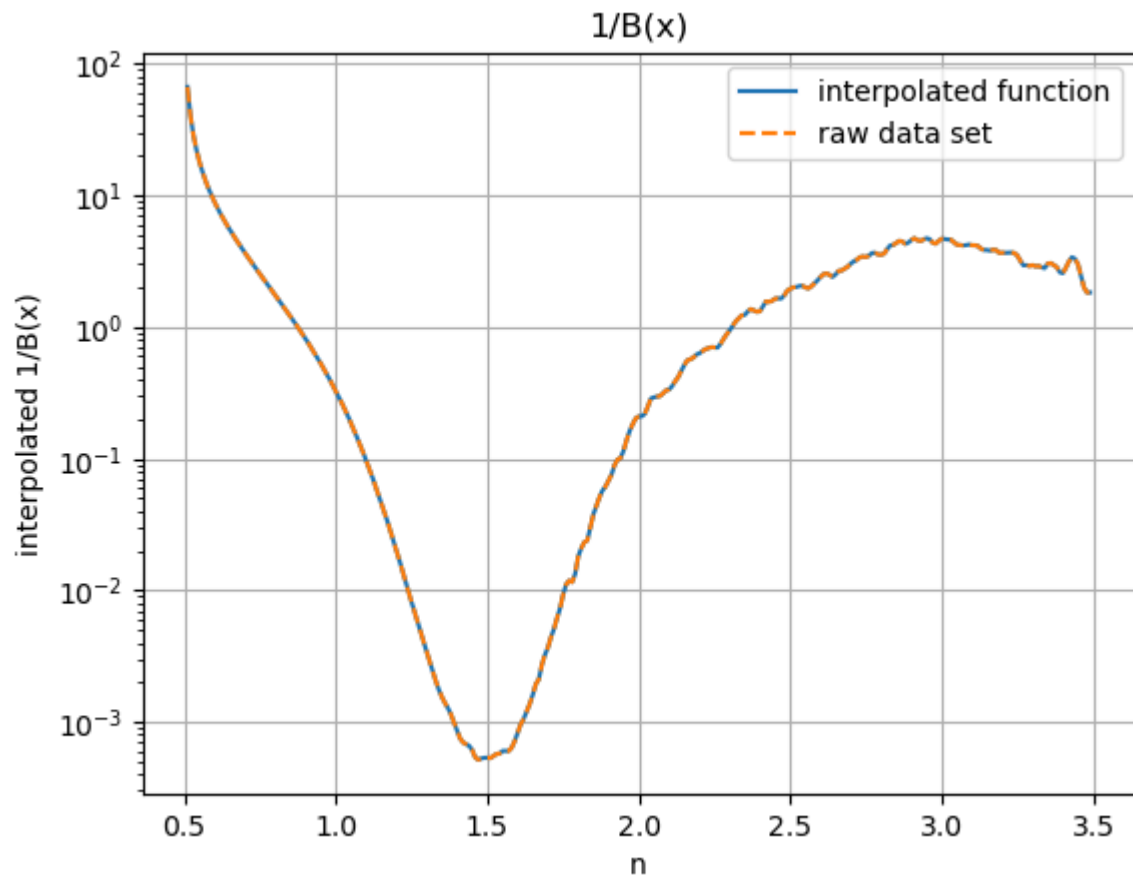
plt.semilogy(simu_x_arr[1:-1], interp_simu_invertBx_func(x_arr[1:-1]), label='interpolated 1/B(x)')
plt.semilogy(simu_x_arr[1:-1], 1.0/simu_Bx_arr, '--', label="raw data set")
# Plot formatting
plt.xlabel('n')
plt.ylabel('interpolated 1/B(x)')
plt.title('1/B(x)')
plt.legend()
plt.grid()
```

/tmp/ipykernel_789248/3951444635.py:5: IntegrationWarning: The maximum number of subdivisions (50) has been achieved.

If increasing the limit yields no improvement it is advised to analyze the integrand in order to determine the difficulties. If the position of a

local difficulty can be determined (singularity, discontinuity) one will probably gain from splitting up the interval and calling the integrator on the subranges. Perhaps a special-purpose integrator should be used.

```
integral_Pst_arr[i], _ = quad(interp_simu_Pst_func, simu_x_arr[1+i], simu_x_arr[-1])
```



```
In [41]: integral_invertBx_arr = np.zeros(N-2)
beta_Grec2_arr = np.zeros(N-2)

for i in range(N-2):
    # Here x0 is x_arr[1]
    integral_invertBx_arr[i], _ = quad(interp_simu_invertBx_func, simu_x_arr[i], simu_x_arr[i+1])
    beta_Grec2_arr[i] = beta_U(simu_x_arr[i+1]) + np.log(simu_Bx_arr[i]/simu_Bx_arr[i+1])

print(_)

plt.plot(simu_x_arr[1:-1], beta_Grec2_arr, label="simulated Pst with exact M")
plt.plot(simu_x_arr[1:-1], beta_U(x_arr[1:-1]), ':', label="exact")

# Plot formatting
plt.xlabel('n')
plt.ylabel('$ \beta \Delta G(n) $')
plt.title('free energy reconstruction')
plt.legend()
plt.grid()
```

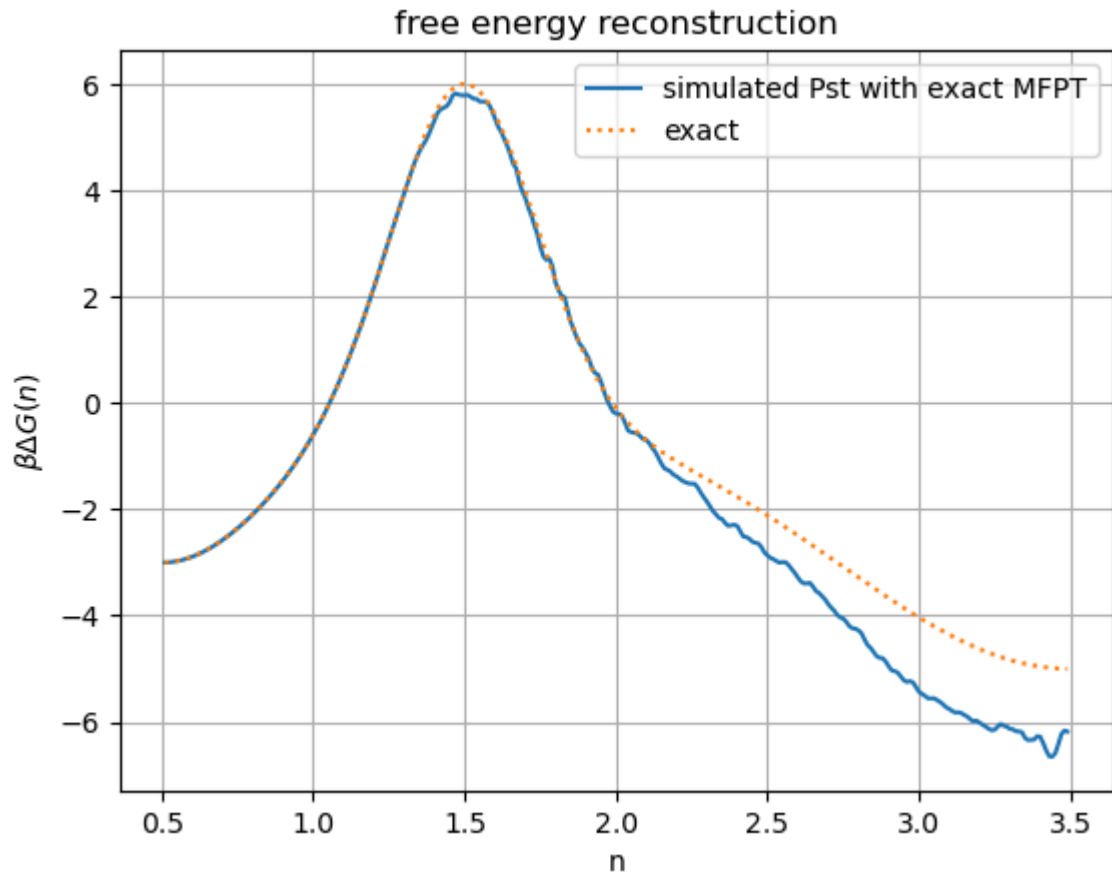
/tmp/ipykernel_789248/2109196022.py:6: IntegrationWarning: The maximum number of subdivisions (50) has been achieved.

If increasing the limit yields no improvement it is advised to analyze the integrand in order to determine the difficulties. If the position of a

local difficulty can be determined (singularity, discontinuity) one will probably gain from splitting up the interval and calling the integrator on the subranges. Perhaps a special-purpose integrator should be used.

```
integral_invertBx_arr[i], _ = quad(interp_simu_invertBx_func, simu_x_arr[1], simu_x_arr[1+i])
```

0.0011142226443684564



```
In [42]: # Except for the absorbing boundary  $Pst(b) = 0$ ,  $D(x)=0$ , also avoid at reflection
simu_Bx_arr = np.zeros(N-2)
integral_Pst_arr = np.zeros(N-2)
for i in range(N-2):
    integral_Pst_arr[i], _ = quad(interp_simu_Pst_func, simu_x_arr[1+i], simu_x_arr[1+i])
    simu_Bx_arr[i] = -1.0/Pst_n[1+i]*(integral_Pst_arr[i]-(mfpt_simu_arr[-1]-mfpt_simu_arr[i]))

interp_simu_invertBx_func = interp1d(simu_x_arr[1:-1], 1.0/simu_Bx_arr, kind='linear')

plt.semilogy(simu_x_arr[1:-1], interp_simu_invertBx_func(x_arr[1:-1]), label='simulated Pst with exact MFPT')
plt.semilogy(simu_x_arr[1:-1], 1.0/simu_Bx_arr, '--', label="raw data set")
# Plot formatting
plt.xlabel('n')
plt.ylabel('interpolated 1/B(x)')
plt.title('1/B(x)')
plt.legend()
plt.grid()
```

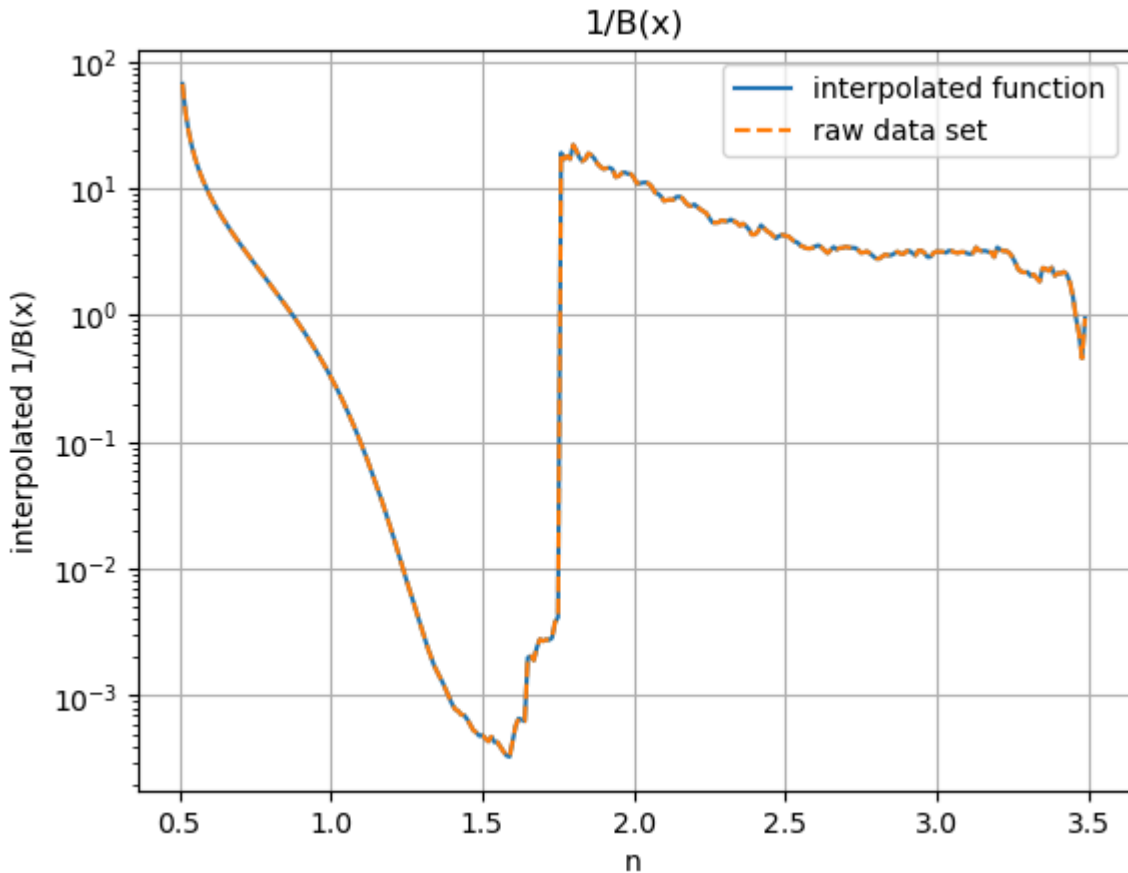


```
/tmp/ipykernel_789248/1053423012.py:5: IntegrationWarning: The maximum number of subdivisions (50) has been achieved.
```

If increasing the limit yields no improvement it is advised to analyze the integrand in order to determine the difficulties. If the position of a

local difficulty can be determined (singularity, discontinuity) one will probably gain from splitting up the interval and calling the integrator on the subranges. Perhaps a special-purpose integrator should be used.

```
integral_Pst_arr[i], _ = quad(interp_simu_Pst_func, simu_x_arr[1+i], simu_x_arr[-1])
```



```
In [43]: integral_invertBx_arr = np.zeros(N-2)
beta_Grec2_arr = np.zeros(N-2)

for i in range(N-2):
    # Here x0 is x_arr[1]
    integral_invertBx_arr[i], _ = quad(interp_simu_invertBx_func, simu_x_arr[1+i], simu_x_arr[-1])
    beta_Grec2_arr[i] = beta_U(simu_x_arr[1]) + np.log(simu_Bx_arr[i]/simu_Bx_arr[1])

print(_)

plt.plot(simu_x_arr[1:-1], beta_Grec2_arr, label="simulated Pst & MFPT")
plt.plot(simu_x_arr[1:-1], beta_U(x_arr[1:-1]), ':', label="exact")

# Plot formatting
plt.xlabel('n')
plt.ylabel('$ \beta \Delta G(n) $')
plt.title('free energy reconstruction')
```

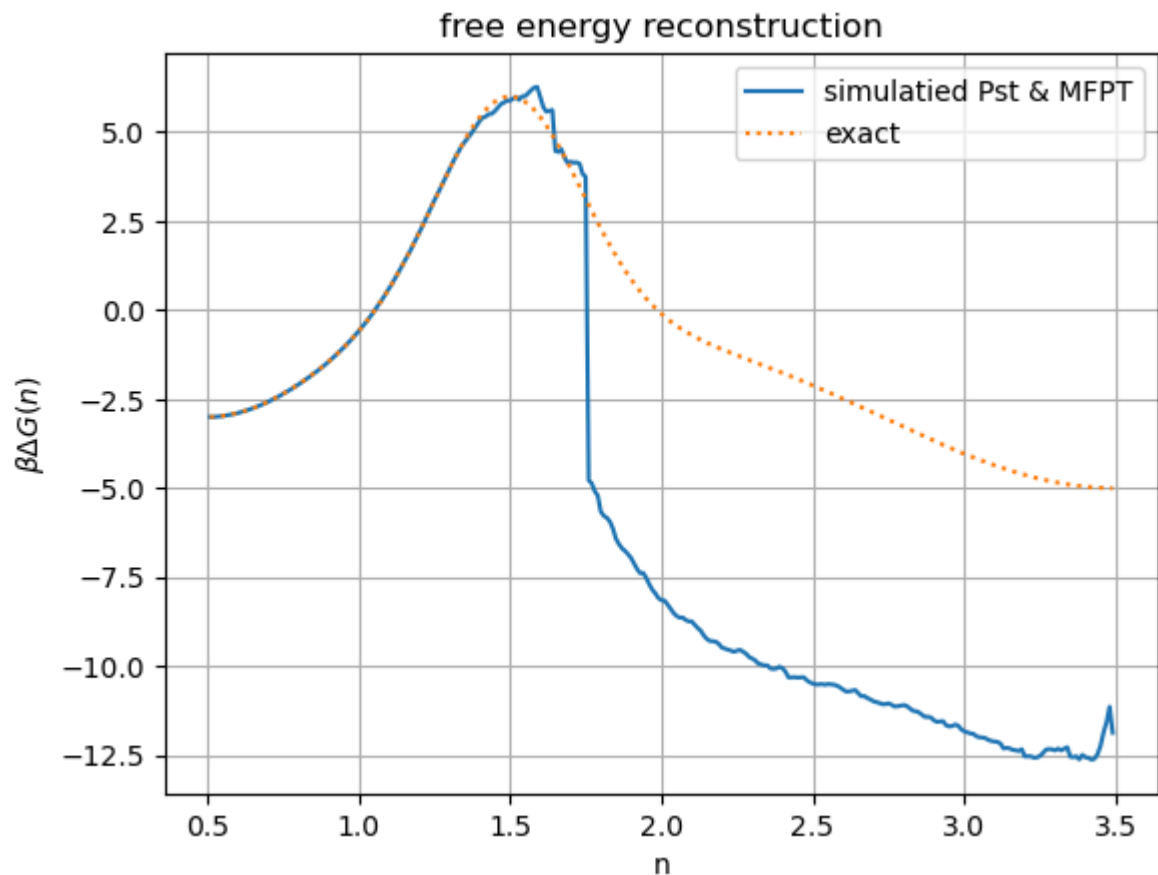
```
plt.legend()  
plt.grid()
```

/tmp/ipykernel_789248/3105494345.py:6: IntegrationWarning: The maximum number of subdivisions (50) has been achieved.

If increasing the limit yields no improvement it is advised to analyze the integrand in order to determine the difficulties. If the position of a

local difficulty can be determined (singularity, discontinuity) one will probably gain from splitting up the interval and calling the integrator on the subranges. Perhaps a special-purpose integrator should be used.
integral_invertBx_arr[i], _ = quad(interp_simu_invertBx_func, simu_x_arr[1], simu_x_arr[1+i])

0.024111570733485937



In []: