# Lecture 09 (Load Store Queue)

### 1 Issue with Load Store

ld r1, 4[r3] st r2, 10[r5]

- 1. Can't execute OOO
- 2. Both may resolve to same address
- 3. In case of exception, we need to make a clean cut
- 4. But if store has executed OOO, then memory state is corrupted
- 5. Loads cannot be directly sent to cache since there might be a pending store

### 1.1 Resolution Ideas

- 1. Stores need to wait
- 2. Need to maintain their information somewhere
- 3. We use a store queue for this

## 2 Load Store Queue

- 1. Allocate an entry at decode time
- 2. Deallocate later
- 3. Update entry when address is computed

### 2.1 Computed Address of Store

Scan entries after this entry (if we encounter a load with same address, then forward) until

- 1. Store to same address
- 2. Store with unresolved address

### 2.2 Computed Address of Load

Scan stores before this entry until

1. Found entry with same address - forward

- 2. Found entry with unresolved address wait
- 3. Reached end of queue request from memory

### 2.3 Actual Implementation

Have two separate circular queues for load and store

#### 2.3.1 Load Queue Entry

- 1. Load address
- 2. Index of tail pointer in store queue when entry was added

#### 2.3.2 Store Queue Entry

- 1. Store address and value
- 2. Index of tail pointer in load queue when entry was added

#### 2.3.3 Basic Search

- 1. If there are n entries, have a n bit vector
- 2. prec(i) = all locations before i are set to 1
- 3.  $before(j) = \overline{prec(head)} \wedge prec(j)$  (if no wrap around)
- 4.  $before(j) = \overline{prec(head)} \vee prec(j)$  (if wrap around)
- 5.  $after(j) = \overline{prec(j)} \wedge \overline{map(j)} \wedge (prec(tail) \vee map(tail))$  (no wrap around)
- 6.  $after(j) = (\overline{prec(j)} \vee prec(tail) \vee map(tail)) \wedge \overline{map(j)}$  (no wrap around)
- 7. To search for resolved entries before  $j: before(j) \land (match \lor \overline{resvd})$
- 8. Now to choose the leftmost or rightmost entry, we can use a similar to select logic

We use a tree since it is completely parallelizable. Nix problems exist similar to P vs NP. (size n, poly(n) resources, time taken is poly(log(n)))