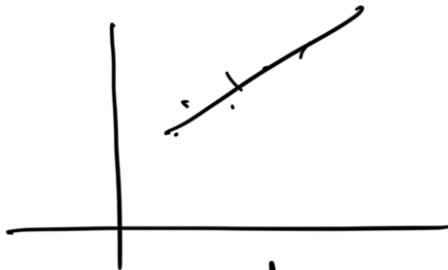


COL774  
Machine Learning  
Aug 24, 2021

Last class:- Linear Regression:



$h_0(x)$ :- linear function.

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^m [y^{(i)} - \underbrace{h_0(x^{(i)})}_{\theta^T x^{(i)}}]^2$$

Gradient update Rule

$$\theta^{(t+1)} \leftarrow \theta^{(t)} - \eta \cdot \nabla_{\theta} J(\theta)$$

↙  $\epsilon R^{m \times 1}$  ↘

if  $\theta \in R^{m \times 1}$

↖ optimization ↗

$$f(\theta) = \theta_1^2 + \theta_2^2 + 3\theta_1\theta_2 + 2\theta_2 + 5$$

$\nabla f(\theta)$  2 eq. Analytical?

loss  $J_n$  ✓  $J(\theta) = \frac{1}{2m} \sum_{i=1}^m [y^{(i)} - h_0(x^{(i)})]^2$

\* argmin  $J(\theta)$   $\Rightarrow$  can be done by using gradient descent.

Gradient Descent:

$$\nabla_{\theta} J(\theta) = \nabla_{\theta} \left( \frac{1}{2m} \sum_{i=1}^m [y^{(i)} - \theta^T x^{(i)}]^2 \right)$$

$$= \frac{1}{m} \sum_{i=1}^m \nabla_{\theta} [y^{(i)} - \theta^T x^{(i)}]^2$$

$$\begin{aligned}
 &= \frac{1}{2m} \sum_{i=1}^m 2(y^{(i)} - h_0(x^{(i)})) \nabla_0 (y^{(i)} - \theta^T x^{(i)}) \\
 &= \frac{1}{m} \sum_{i=1}^m (y^{(i)} - h_0(x^{(i)})) \nabla_0 [\theta^T x^{(i)}]
 \end{aligned}$$

Asider

$$\begin{aligned}
 \sum_{j=0}^n \theta_j x_j &\equiv \theta^T x^{(i)} \\
 \frac{\partial}{\partial \theta_j} \sum_{j=0}^n \theta_j x_j &= x_j
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{1}{m} \sum_{i=1}^m (y^{(i)} - h_0(x^{(i)})) (-1) x^{(i)} \\
 &\quad \nabla_0 \theta^T x^{(i)}
 \end{aligned}$$

$x^{(i)}$  is a vector  $\begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{bmatrix}$

$\Rightarrow$  parameter updates rule  
 do  $t=0$ ;  $\theta^{(0)}$  &  $\epsilon$  with  $\eta$

Gradient Descent  
 for learning parameters  
 of linear regression

$$\begin{aligned}
 \theta^{(t+1)} &\leftarrow \theta^{(t)} - \eta \cdot \nabla_0 J(\theta) \\
 \epsilon^{(t+1)} &\leftarrow \epsilon^{(t)} + \eta \cdot \frac{1}{m} \sum_{i=1}^m (y^{(i)} - h_0(x^{(i)})) x^{(i)} \\
 &= \theta^{(t)} + \eta \cdot \frac{1}{m} \sum_{i=1}^m (y^{(i)} - \theta^T x^{(i)}) x^{(i)}
 \end{aligned}$$

$t \leftarrow t+1$ ;  
 3 while 1 (converged)

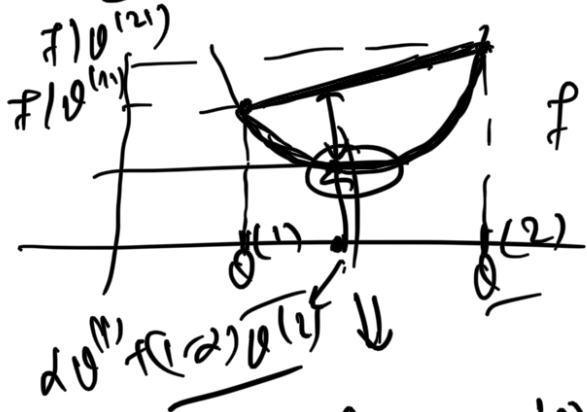
↳ Convexity:- (Convex function) | SGD. 1 Making GD more efficient

$f(\theta)$ :-

$$f: \mathbb{R} \rightarrow \mathbb{R}$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

Convex function



$$f(\theta) = (\theta - 3)^2 + 1$$

∴ strictly convex

$$\hookrightarrow \frac{\partial^2 f(\theta)}{\partial^2 \theta} \geq 0$$

$$\theta, \theta^{(1)}, \theta^{(2)} \in \mathbb{R}$$

$f$  is convex iff  $f: \mathbb{R} \rightarrow \mathbb{R}$  ( $0 \leq \alpha \leq 1$ )

$$f(\alpha \theta^{(1)} + (1-\alpha) \theta^{(2)}) \leq \alpha f(\theta^{(1)}) + (1-\alpha) f(\theta^{(2)})$$

Convex combination

↓ convex

strictly convex  
 $0 < \alpha < 1$

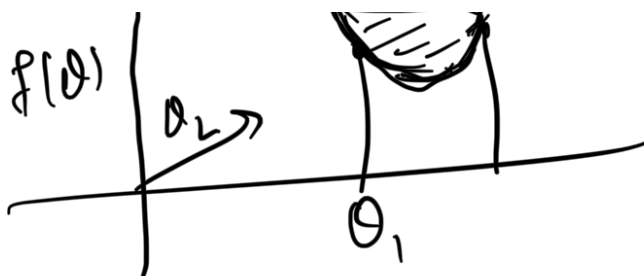
↳ Generalize  $f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$

$f$  is convex iff

$$f(\alpha \theta^{(1)} + (1-\alpha) \theta^{(2)}) \leq \alpha f(\theta^{(1)}) + (1-\alpha) f(\theta^{(2)})$$

$\theta^{(1)}, \theta^{(2)} \in \mathbb{R}^{n+1}$

Convex set:-  
 $C: \theta^{(1)}, \theta^{(2)}$



$$\theta^{(1)}, \theta^{(2)} \in \mathbb{C}$$

$$\lambda \theta^{(1)} + (1-\lambda) \theta^{(2)} \in \mathbb{C}$$

Last Bit:- ~~How~~ Understanding Convexity in terms of second order derivatives.

$$f: \mathbb{R} \rightarrow \mathbb{R}$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\frac{\partial^2 f(\theta)}{\partial^2 \theta} \geq 0$$

$$\begin{bmatrix} \frac{\partial f(\theta)}{\partial \theta_j} \end{bmatrix}$$

$$\nabla_{\theta} f(\theta)$$

1st derivative

Hessian matrix

2nd derivative

$$H = \begin{bmatrix} \frac{\partial^2 f(\theta)}{\partial \theta_j \partial \theta_k} \end{bmatrix}$$

$$\frac{\partial^2 f(\theta)}{\partial \theta_j \partial \theta_k}$$

$$H_{jk}$$

$$\equiv \frac{\partial^2 f(\theta)}{\partial \theta_k \partial \theta_j}$$

Convexity & Hessian matrix

If  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is convex then

the corresponding Hessian matrix

$H$  is +ve semi-definite

B:- symmetric

$\Rightarrow$  A matrix

$B$  is +ve semi-definite

$$B \in \mathbb{R}^{n \times n}$$

if

matrix

$$B = \begin{bmatrix} \lambda_1 & \dots & \lambda_n \end{bmatrix}$$

$$\left( \quad \forall \underline{z} \in \mathbb{R}^n \quad \underbrace{|\underline{z}^T B \underline{z}| \geq 0}_{\text{Quadratic form}} \right)$$

$$\underline{z}^T \underbrace{\sum_{j,k} z_j B_{jk} z_k}_{\text{Quadratic form}} = \underline{z}^T B \underline{z}$$

$$\begin{bmatrix} \underline{z}^T \\ \end{bmatrix} \begin{bmatrix} B \\ \end{bmatrix} \begin{bmatrix} \underline{z} \\ \end{bmatrix} \geq 0$$

if  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is convex & locally differentiable then  
Hessian  $H$  must be the semi-definite

$$\underline{z}^T H \underline{z} \geq 0 \quad \forall \underline{z} \in \mathbb{R}^{n+1}$$

Hessian expression

we will be able to show that  

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^m \left[ y^{(i)} - \sigma^T x^{(i)} \right]^2$$
 is a convex function in  $\theta$  parameters.

70510) I

H Benkan mahog  $\Sigma R^{(n+1)} \times \underline{(n+1)}$

$$\underline{\underline{Z^T H Z \geq 0}} \quad \underline{\underline{\forall Z \in R^{(n+1)}}}$$

Concam ✓