



CSC-257

Theory Of Computation

(BSc CSIT, TU)

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Language of Turing Machine

- If $T = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$ is a Turing machine and $w \in \Sigma^*$, then language accepted by T is defined by, $L(T) = \{w \mid w \in \Sigma^* \text{ and } q_0 w \vdash^* \alpha p \beta\}$ for some $p \in F$ and any tape string α and β .
- The set of languages that can be accepted using TM are called recursively enumerable languages or RE languages.

Language of Turing Machine

- The Turing Machine is designed to perform at least the following three roles :
 - 1. As a language recognizer :** TM can be used for accepting a language like Finite Automaton and Pushdown Automata.
 - 2. As a Computer of function :** A TM represents a particular function. Initial input is treated as representing an argument of the function and final string on tape when the TM enters the halt state; treated as representative of the value obtained by an application of the function to the argument represented by the initial string
 - 3. As an enumerator of string of a language :** It outputs the strings of a language, one at a time in some systematic order that is as a list.

Turing Machine for Computing a Function

- A Turing Machine can be used to compute functions.
- For such TM, we adopt the following policy to input any string to the TM which is an input of the computation function :
 - The string w is presented into the form BwB , where B is a blank symbol, and placed onto the tape; the head of TM is positioned at a blank symbol which immediately follows the string w
 - We can show by underlining that symbol to the current position of machine head in the tape as (q, BwB) or, we can represent it by ID of TM as $BwqB$
 - The TM is said to halt on input w if we can reach to halting state after performing some operation. i.e. If $TM = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$ is a Turing machine.

Turing Machine for Computing a Function : Formal Definition

- A function $f(x) = y$ is said to be computable by a TM and defined as; $(Q, \Sigma, \Gamma, \delta, q_0, B, F)$ If $(q_0, B x B) \vdash^* (q_a, ByB)$; where $x \in \Sigma^*$, and $y \in \Sigma^*$
- It means that if we give input x to the Turing machine, it gives output as a string if it computes the function $f(x) = y$.

Turing Machine for Computing a Function : Formal Definition

- **Example :** Design a TM which computes the function $f(x) = x+1$ for each x belonging to set of natural numbers.
- Given the function, $f(x) = x+1$. Here, we represent the input x on the tape by a number of 1's on the tape
- i.e. for $x=1$, input tape will have B1B, for $x=2$ input tape will have B11B and so on.
- Similarly, output can be seen by the number of 1's on the tape when machine halts

| | B | 1 |
|-----------|------------|------------|
| q0 | (q0, 1, S) | (qf, 1, R) |
| q1 | | |

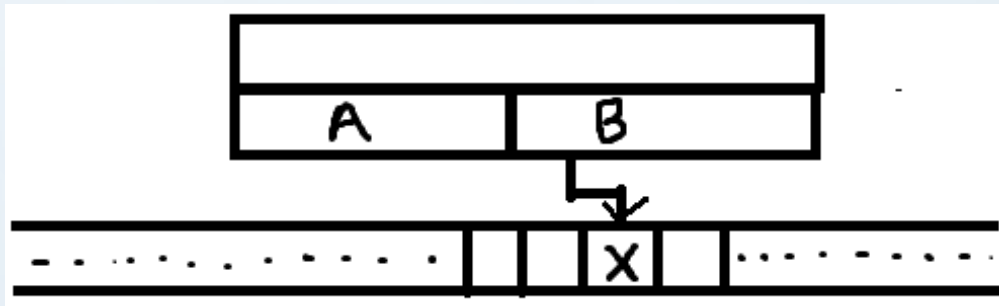
- So, let the input be $x = 4$. So, input tape at initial step consists of B1111B.
- $(q_0, B1111B) \vdash^* (q_0, B11111) \vdash (q_f, B11111B)$. Which means output is 5 accepted

Turing Machines and Halting

- There is another notion of acceptance that is commonly used for Turing machines : acceptance by Halting.
- We say a TM halts if it enters a state q , scanning a tape symbol X and there is no move in this situation; i.e $\delta(q, X)$ is undefined.
- The Turing machine described above was not designed to accept any language rather we viewed it as computing an arithmetic function.
- We always assume that a TM halts if it accepts. i.e. without changing language accepted, we can make $\delta(q, X)$ undefined whenever q is an accepting state

Turing Machine with Storages in the state

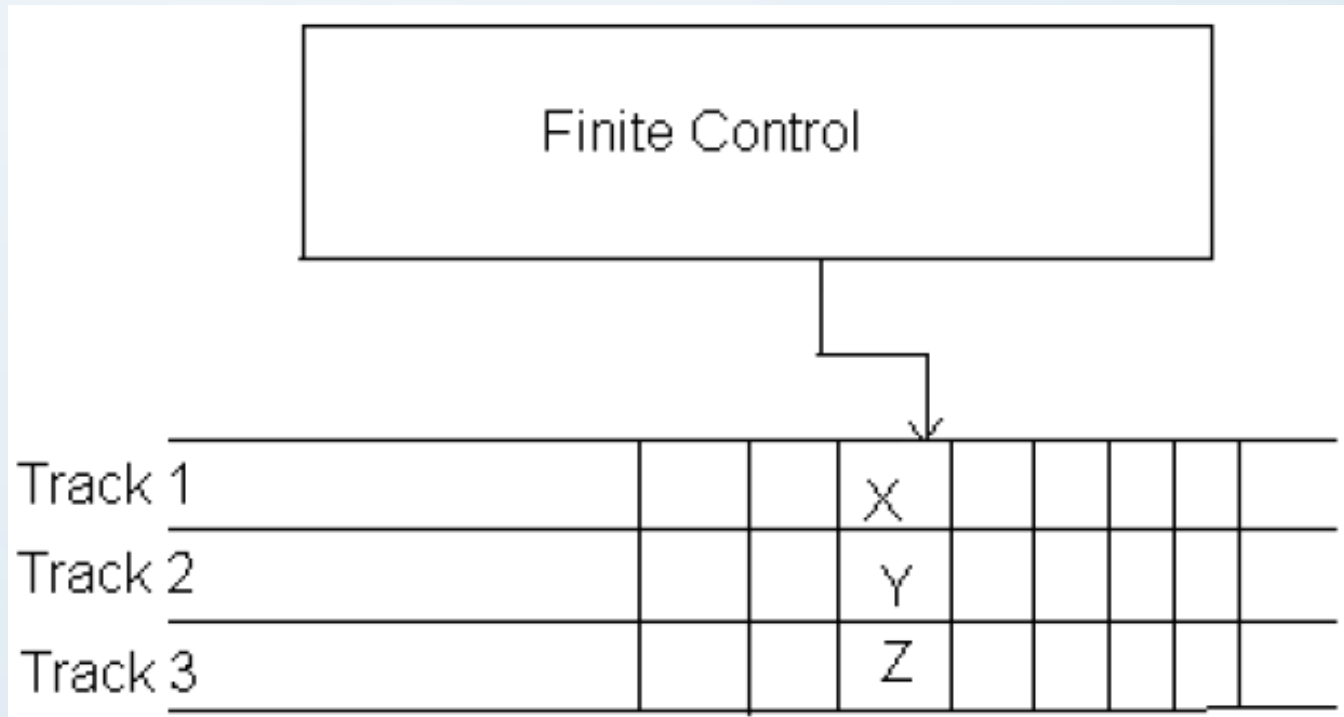
- In Turing Machine, generally, any state represents the position in the computation.
- But the state can also be used to hold a finite amount of data.
- We can use the finite control not only to represent a position in the computation / program of the Turing Machine, but to hold a finite amount of data.
- In this case, a state is considered as a tuple; (state, data).



- δ is defined by : $\delta([q, A], X) = ([q1, X], Y, R)$; means that q is the state and data portion associated with q is A . The symbol scanned on the tape is copied into the second component of the state and moves right entering state $q1$ and replacing tape symbol by Y .

Turing Machine with Multiple Tracks

- The tape of TM can be considered as having multiple tracks.
- Each track can hold one symbol, and the tape alphabet of the TM consists of tuples, with one component for each track.
- Following figure illustrates the TM with multiple tracks :

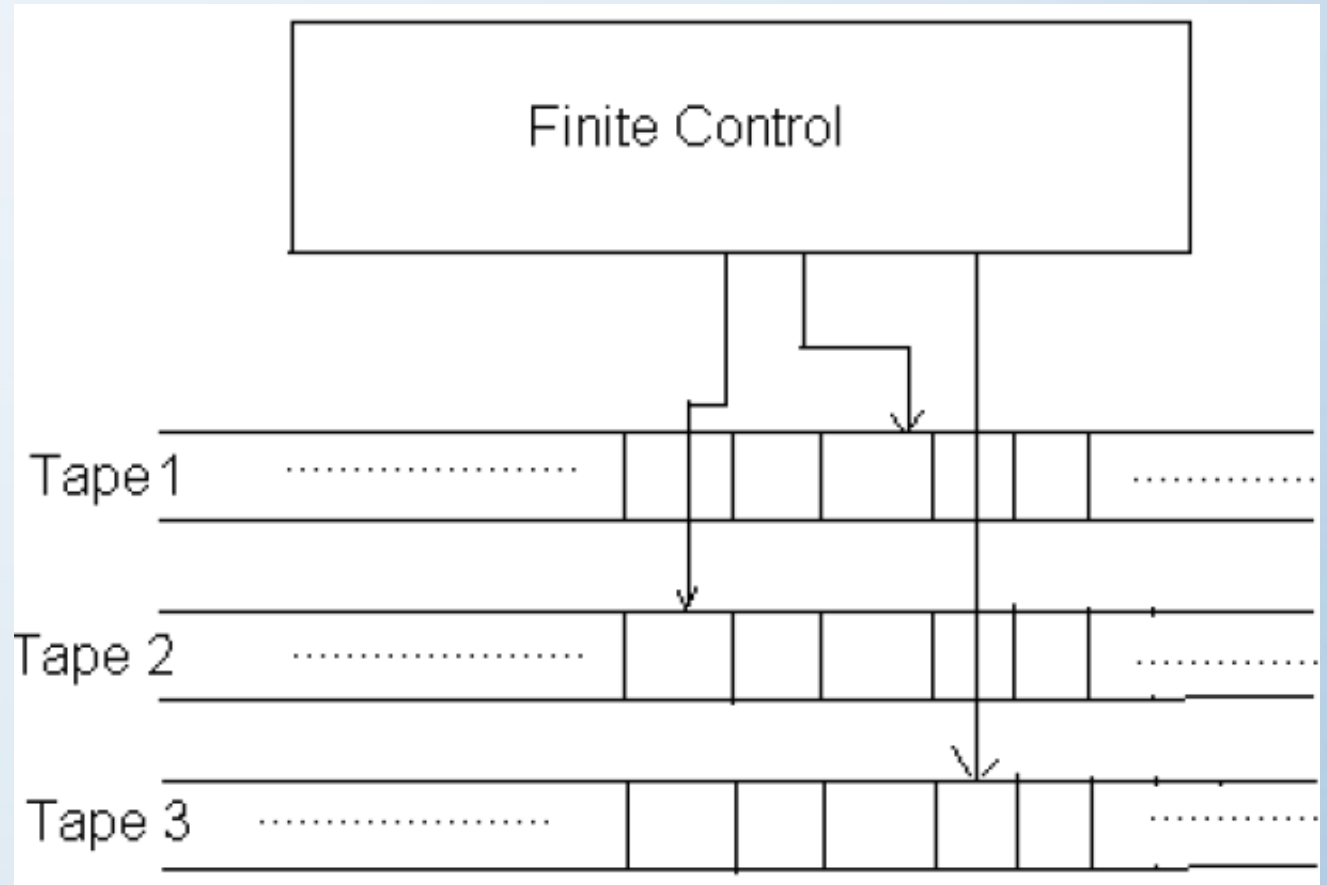


Turing Machine with Multiple Tracks

- The tape alphabet Γ is a set consisting of tuples like : $\Gamma = \{ (X, Y, Z), \dots \}$
- The tape head moves up and down scanning symbols in the tape at one position.
- Like the technique of storage in the state, using multiple tracks does not extend what the TM can do.
- It is simply a way to view tape symbols and to imagine that they have a useful structure

Multi Tape Turing Machine

- Modern computing devices are based on the foundation of TM computation models.
- To simulate the real computers, a TM can be viewed as multi-tape machine in which there is more than one tape.
- However, adding extra tape adds no power to the computational model, only the ability to accept the language is concerned.



Multi Tape Turing Machine

- A multi-tape TM consists of finite control and finite number of tapes.
- Each tape is divided into cells and each cell can hold any symbol of finite tape alphabets.
- The set of tape symbols include a blank and the input symbols.
- Initially,
 - The Input (finite sequence of input symbols) w is placed on the first tape.
 - All other cells of the tapes hold blanks.
 - TM is in initial state q_0 .
 - The head of the first tape is at the left end of the input.
 - All other tape heads are at some arbitrary cell. Since all other tapes except first tape consists completely blank

Multi Tape Turing Machine

- A move of multi- tape TM depends on the state and the symbol scanned by each of the tape head. In one move, the multi-tape TM does the following :
 - The control enters in a new state, which may be same previous state.
 - On each step, a new symbol is written on the cell scanned, these symbols may be same as the symbols previously there.
 - Each of the tape head make a move either left or right or remains stationary. Different head may move different direction independently i.e. if head of first tape moves leftward; at same time other head can move another direction or remains stationary