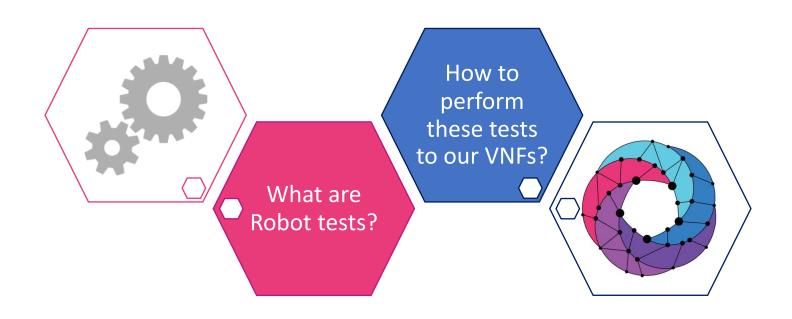
How to test your VNFs with the Robot Framework





How will we perform the test?

Robot Framework



ROBOT FRAME WORK/



What do Robot tests perform?

Perform network tests between 2 VNFs:

- Bandwidth
- Open Ports
- Packet Loss
- Transmission Speed
- Jitter
- etc



First of all, start by installing the needed framework

```
# install the robot framework
$ pip install robotframework

# check the installation
$ robot --version
```



Create the needed files to perform the test

We will be making a Jitter test

```
# create the folder
$ mkdir jitter
$ cd jitter/

# create the files
$ touch jitter.py
$ touch testJitter.robot
```



After running these commands, you should have the following file structure

```
robot_test_tutorial
____ jitter
____ jitter.py
____ testJitter.robot
```



How to use Robot framework to perform network tests between VNFs?



We will use environment variables to define the 2 VNFs and the Jitter values Start by exporting these variables.

```
# VNF 1
$ export jitter_host1_ip=10.0.12.223 # change to your VNF 1 IP
# change to your credentials
$ export jitter host1_username=ubuntu
$ export jitter_host1_password=password
# VNF 2
$ export jitter host1 ip=10.0.12.212 # change to your VNF 2 IP
# change to your credentials
$ export jitter_host1_username=ubuntu
$ export jitter_host1_password=password
# Jitter
$ export jitter_comparator=less_or_equal_than
$ export jitter threshold=0.03
```



Edit the *jitter/jitter.py* file. Add the following content:

```
import json
import os
import pip
import importlib.util
host1 = os.getenv('jitter_host1_ip')
username1 = os.getenv('jitter_host1_username')
password1 = os.getenv('jitter_host1_password')
host2 = os.getenv('jitter_host2_ip')
username2 = os.getenv('jitter_host2_username')
password2 = os.getenv('jitter_host2_password')
packages = ['paramiko','robotframework']
for package in packages:
   if (spec := importlib.util.find_spec(package)) is None:
        pip.main(['install', package])
import paramiko
```



Edit the *jitter/jitter.py* file. Add the test function:

```
#test
def jitter():
    machine1 = paramiko.SSHClient()
    machine1.set_missing_host_key_policy(paramiko.AutoAddPolicy())
    machine2 = paramiko.SSHClient()
    machine2.set_missing_host_key_policy(paramiko.AutoAddPolicy())
    try:
        machine1.connect(hostname=host1, username=username1, password=password1)
        machine2.connect(hostname=host2, username=username2, password=password2)
    except:
        print("[!] Cannot connect to the SSH Server")
        exit()
    # Executing iPerf commands
    machine1.exec command("iperf3 -s -1")
    stdin, stdout, stderr = machine2.exec_command(f"iperf3 -c {host1} -u --json -t 5")
    iperfResult = stdout.read().decode()
    obj = json.loads(iperfResult)
        jitter_ms = float(obj['end']['sum']['jitter_ms'])
        print(f"Jitter: {jitter_ms}")
    except:
        return "Not found"
    return jitter_ms
if __name__ == '__main__':
    jitter()
```



We will now add the needed code to the robot test file.

Add the following to *jitter/testJitter.robot*:

```
*** Settings ***
Library
              jitter.py
*** Test Cases ***
Testing if the jitter is %{jitter_comparator} %{jitter_threshold} ms
    ${COMPARATOR}=
                        Run Keyword If
                                           '%{jitter_comparator}' == 'more_than'
                                                                                       Set Variable >
          ELSE IF
                   '%{jitter_comparator}' == 'more_or_equal_than'
                                                                          Set Variable
                   '%{jitter_comparator}' == 'less_than'
          ELSE IF
                                                                 Set Variable
                     '%{jitter_comparator}' == 'less_or_equal_than'
          ELSE IF
                                                                          Set Variable
                   Fail \nComparator has not been defined
          ELSE
   ${jitter_ms}=
                   jitter
          '${jitter_ms}' != '-1'
   Should Be True ${jitter_ms} ${COMPARATOR} %{jitter_threshold}
    ELSE
           \nImpossible to compute Jitter
    FAIL
    END
```



Before running the tests, you need to have iperf3 installed in both VNFs.

This is the package that will obtain the values so that we can run the tests.

You have 2 options:

- Install through SSH command in each VNF: sudo apt-get install iperf3
- Through the VNF cloud-init files



Now, let's run our test:

```
# if you haven't already exported the environment variables, go back in the tutorial and export them
# In this case, we are checking if the average Jitter between the VNFs is less than 0.03 ms
$ robot jitter # this references the folder
```



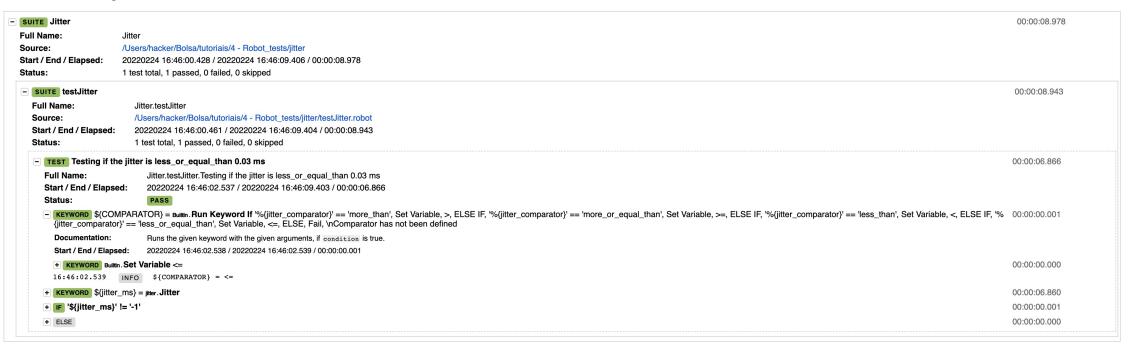
If everything goes accordingly, you should have this output:

```
•100% → robot jitter
Jitter
Jitter.testJitter
Testing if the jitter is less_or_equal_than 0.03 ms
Jitter.testJitter
                                      PASS
1 test, 1 passed, 0 failed
Jitter
                                      PASS
1 test, 1 passed, 0 failed
Output: /Users/hacker/Bolsa/tutoriais/4 - Robot tests/output.xml
    /Users/hacker/Bolsa/tutoriais/4 - Robot_tests/log.html
Report: /Users/hacker/Bolsa/tutoriais/4 - Robot tests/report.html
```



Inside log.html you can find pore information on the test:

Test Execution Log





The code developed during this tutorial is available at

https://github.com/5gasp/tutorials

If you have any questions regarding the contents addressed in this tutorial you can send an e-mail to Rafael Direito rdireito@av.it.pt, or contact us via contact@5gasp.eu

