mcode.sty Demo

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NOTE

Partial Code,

```
detJacobian=Le(e)/2;
invJacobian=1/detJacobian;
ngp = 4; % Prepare for integration with 4 gauss points
[w,xi]=gaussld(ngp);
xc=0.5*(nodeCoordinates(elementDof(1))+...
nodeCoordinates(elementDof(end)));
Coefficient=zeros(ngp,ngp);
for ip=1:ngp
    x_global = xc + detJacobian*xi(ip);
[shape,naturalDerivatives]=shapeFunctionL2(xi(ip));
```

Full Code,

```
1 % Compute Normed Errors,
2 L2 = zeros(1, numberElements); en = zeros(1, numberElements);
3 for e=1:numberElements;
    % elementDof: element degrees of freedom (Dof)
    elementDof=elementNodes(e,:);
    detJacobian=Le(e)/2;
    invJacobian=1/detJacobian;
    ngp = 4; % Prepare for integration with 4 gauss points
     [w,xi]=gauss1d(ngp);
    xc=0.5*(nodeCoordinates(elementDof(1))+...
      nodeCoordinates(elementDof(end)));
11
     Coefficient=zeros(ngp,ngp);
      for ip=1:ngp
13
           x_global = xc + detJacobian*xi(ip);
           [shape, naturalDerivatives] = shapeFunctionL2(xi(ip));
```

```
N=shape;
16
17
           B=naturalDerivatives*invJacobian;
           temp1 = detJacobian*w(ip)*(u_exact(x_global) - ...
18
19
               N*displacements(elementNodes(e,:)))^2;
           L2(e) = L2(e) + temp1;
20
21
           temp2 = detJacobian*w(ip)*(du_exact(x_global) - ...
               B*displacements(elementNodes(e,:)))^2;
22
23
           en(e)=en(e)+temp2;
25 end
26
27 % Data for analysis,
28 h(i) = Le(1); % because of uniform mesh assumption
29 L2_linear(i) = sqrt(sum(L2));
30 en_linear(i) = sqrt(sum(en));
```

WOW!!

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