

LOST IN TRANSLATION











OVERVIEW

- Define the goal
- Understand the virtual table
- Go over (some of) the alternatives
- Benchmark!
- Draw conclusions

THE GOAL

• Understand what happens behind the scenes - use it to improve performance

• Identify the type of our object, and "do something" accordingly

• To implement a "Derived is a Base" relation

MPROVE (RUNTIME) PERFORMANCE

- Optimize hot path (80%) most probable case first, pass by ref, etc.
- Decrease:
 - Dynamic allocation
 - System calls
 - Runtime decision making -> Branching
 - Function calls (*Use inline)
 - Code size → Cache-miss

```
class Base {
public:
     Base() {
          cout << "Base Ctor" << endl;
     ~ Base() {
          cout << "Base Dtor" << endl;</pre>
     void printMe() {
          cout << "Hi, Base" << endl;</pre>
viotion()Base *b)
     Denovind Mi;e();
     func(&d);
```

Hi, Base

```
class Base {
public:
     Base() {
          cout << "Base Ctor" << endl;</pre>
     ~ Base() {
          cout << "Base Dtor" << endl;</pre>
     void printMe() {
          cout << "Hi, Base" << endl;</pre>
};
int main()
     Base *d = new Derived;
     func(&d);
     delete d;
```

```
class Derived : public Base {
public:
      Derived() {
          cout << "Derived Ctor" << endl;</pre>
     ~ Derived() {
          cout << "Derived Dtor" << endl;</pre>
     void printMe() {
          cout << "Hi, Derived" << endl;</pre>
};
```

Base Ctor Derived Ctor Hi, Base Base Dtor

```
class Base {
                                           public:
                                                                                        Base() {
                                                                                                                                   cout << "Base Ctor" << endl;</pre>
                                                                                        VBase(nin(tMe() {
                                                                                                                                   cout << "Blase as to real could to the country of t
                                            protexctiedprintMe() {
                                                                                        ~Baseout << "Hi, Base" << endl;
                                                                                                                                   cout << "Base Dtor" << endl;</pre>
                                        int main()
Derived Pase *b = new Derived;
                                                                                     delete b;
```

```
class Derived : public Base {
public:
        Derived() {
            cout << "Derived Ctor" << endl;
        }
        ~ Derived() {
            cout << "Derived Dtor" << endl;
        }
        void printMe() {
            cout << "Hi, Derived" << endl;
        }
};</pre>
```

Base Ctor
Derived Ctor
Derived Dtor
Base Dtor

```
class Base {
public:
     Base() {
          cout << "Base Ctor" << endl;</pre>
    virtual ~Base() {
          cout << "Base Dtor" << endl;
    virtual void printMe() {
          cout << "Hi, Base" << endl;
};
int main()
     Derived d;
    func(&d);
```

```
class Derived : public Base {
public:
        Derived() {
            cout << "Derived Ctor" << endl;
        }
        ~ Derived() {
            cout << "Derived Dtor" << endl;
        }
        void printMe() {
            cout << "Hi, Derived" << endl;
        }
};</pre>
```

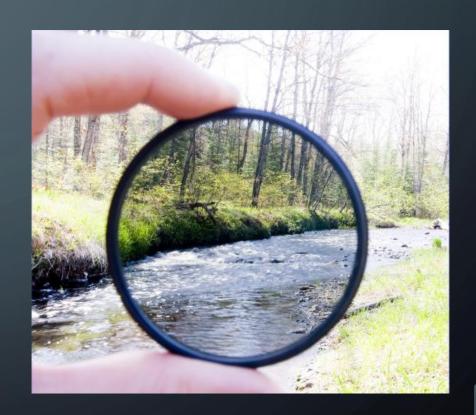
Base Ctor
Derived Ctor
Hi, Derived
Derived Dtor
Base Dtor

DYNAMIC BINDING

- Implementation details are not covered by the standard
- Common implementation: vtable

> THE EXAMPLE

- A Picture of: $10^8 = 10000 \times 10000$ pixels
- X86 Linux Debian machine
- Apply filters:
 - Filter is operating on one pixel
 - Dispatch "Activate" function



> TOOLS

- godbolt.org
- cppinsights.io
- Quick-bench.com
- google/benchmark
- clock_t()

> VTABLE - INTRODUCTION

```
class BaseFilter
public:
     virtual void Activate(PIXEL *pixel) const {
          cout << "BaseFilter" <<endl;</pre>
     virtual ~BaseFilter();
     char val;
class FilterBright : public BaseFilter
public:
     void Activate(PIXEL *pixel) const override {
          *pixel += val;
     ~ FilterBright();
};
```

```
0xAF12

ptr_Dtor
ptr_Activate

0xAF18

ptr_Dtor
ptr_Activate

...
```

class BaseFilter

Class BaseFilter

OxAF12

OxAF12

val

...



VTABLE - STRUCTURE

```
class BaseFilter
public:
    virtual void Activate(PIXEL *pixel) const {
         cout << "BaseFilter" <<endl;</pre>
    virtual ~BaseFilter();
    char val;
class FilterBright : public BaseFilter
                             RTTI
public:
    void Activate
         *pixel +=
                       dynamic_cast
                    Type information
      FilterBright()
```

```
vtable for FilterBright:
     .quad 0
     .quad typeinfo for FilterBright
            FilterBright::~FilterBright() [Complete Dtor]
     .quad FilterBright::~FilterBright() [Deleting Dtor]
     .quad FilterBright::Activate(unsigned char*)
table for BaseFilter:
     .quad 0
     .quad typeinfo for BaseFilter
     .quad BaseFilter::~BaseFilter() [Complete Dtor]
     .quad BaseFilter::~BaseFilter() [Deleting Dtor]
     .quad BaseFilter::Activate(unsigned char*)
typeinfo for FilterBright:
     .quad vtable for __cxxabiv1::__si_class_type_info+16
     .quad typeinfo name for FilterBright
     .quad typeinfo for BaseFilter
typeinfo namefor Filter Bright:
     .string "12FilterBright"
typeinfo for BaseFilter:
     .quad vtable for __cxxabiv1::__class_type_info+16
     .quad typeinfo name for BaseFilter
typeinfo name for BaseFilter:
    .string "10BaseFilter"
```

VTABLE - IMPLEMENTED CODE

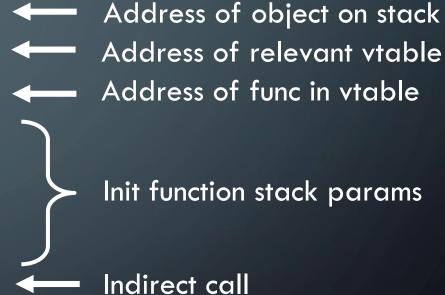
```
ind son Bians() Filter
pub icilterBright f1;
     virtual void Activate(PIXEL *pixel) const
     // f1coBaseFilteseH@&r" <<endl;
     §1.vtable = &BaseFilter_vtable_instance;
     virtual ~BaseFilter();
     /// f1-> FilterBright CTOR:
     Chartalalle = & FilterBright vtable instance
class//FiltheBrighftorpAdtilivaBeaseFilter
    (f1.vtable->Activate)(&f1, p1);
public:
     (Main table at E(Pter Brighte Dtor) (8.61) grride
     (f1.vťapikel>+BakelFilter Dtor)(&f1);
     ~ FilterBright();
```

```
struct FilterBright vtable
     void (*Dtor)(FilterBright *_this);
     void (*Activate)(FilterBright *_this, int *pixel);
struct FilterBright
     const FilterBright_vtable *vtable;
};
void FilterBright_Dtor(FilterBright *_this) {}
void FilterBright_Activate(FilterBright *_this, int *pixel)
     *p1+=1;
static const FilterBright_vtable FilterBright_vtable_instance =
     &FilterBright_Dtor,
     &FilterBright Activate
```

> VTABLE - RUN TIME

The call for "Activate" function

```
QWORD PTR [rbp-24], rbx
mov
      rax, QWORD PTR [rbp-24]
mov
      rax, QWORD PTR [rax]
mov
      rdx, QWORD PTR [rax]
mov
      rax, QWORD PTR [rbp-24]
mov
      esi, 4
mov
      rdi, rdx
mov
call
      BaseFilter<FilterDerived>::Activate(int*)
```



> VTABLE - OVERHEAD

- Retrieve and calculate the relative location of the function.
- Dereference the pointer(s) to the virtual table(s).
- Execute Indirect call (jmp / call).
- (optional) Adjust the value of this pointer.

Solutions:

Minimize the overhead of VT by increasing localization, decreasing dereferences, etc.

- VT alternative implementations
- Dyno by Louis Dionne

Minimize the use of VT by implementing polymorphism with alternative mechanisms.

- Template meta-programming
- Compile time decision making

> VTABLE - FEATURES

- Don't Repeat Yourself
- PRUNTime Binding RTB
- Allows Override Functions in the Derived



- Add External Derived
- AED
- Multiple inheritance

•

> VTABLE - THE ALTERNATIVES

- Solutions should provide a structure, with as little overhead as possible.
- Trade flexibility with performance from **Runtime** to **Compile time**.
- Some of the solutions are only possible if we have all the types known.

THE ALTERNATIVES - SUBCLASSING

Non virtual inheritance

```
class Base
public:
    Base()
         cout<< "Base Ctor" <<endl;
    void printMe()
         cout<< "Hi, Base" <<endl;</pre>
protected:
    ~Base()
         cout<< "Base Dtor" <<endl;
```

```
class Derived : public Base
public:
    Derived()
         cout<< "Derived Ctor" <<endl;
    void printMe()
         cout<< "Hi, Derived" <<endl;</pre>
     Derived()
         cout<< "Derived Ctor" <<endl;</pre>
```

```
int main ()
{
         Derived d;
         d.printMe();
}
```

Base Ctor
Derived Ctor
Hi, Derived
Derived Dtor
Base Dtor

THE ALTERNATIVES - SUBCLASSING

```
class Base
public:
     Base(int a = 1, int b = 1): A(a), B(b) {}
     void Print()
          cout << "getA: " << getA() << endl;</pre>
          cout << "getB: " << getB() << endl;</pre>
     int getA()
                          return A;
     int getB()
                          return B;
     int A;
     int B;
};
```

```
class Derived : public Base
{
  public:
     void PrintCaller ()
     {
          Print();
     }
     int getA() { return A*5; }
     int getB() { return B*5; }
};
```

getA: 1 getB: 1

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THE ALTERNATIVES - CRTP

```
template <typename D>
class BaseFilter
public:
    void Activate()
          D& derived = static_cast<D&>(*this);
         derived.derivedActivate();
int main()
    BaseFilter<FilterBright> f1;
    f1.Activate();
    BaseFilter<FilterDark> f2;
    f2.Activate();
```

Activate Bright **Activate Dark**

```
class FilterBright : public BaseFilter <FilterBright>
public:
     void derivedActivate()
          cout << "Activate Bright" << endl;</pre>
class FilterDark : public BaseFilter <FilterDark>
public:
     void derivedActivate()
          cout << "Activate Dark" << endl;</pre>
};
```

> THE ALTERNATIVES - CRTP

```
class BaseSubclass {
public:
     BaseSubclass(int a = 1, int b = 1): A{a}, B{b} {}
     void Print() {
           cout << "getA: " << getA() << endl;
           cout << "getB: " << getB() << endl;</pre>
     int getA() {
                    return A;
     int getB() {
                    return B;
     int A:
     int B;
class DerivedSubclass : public BaseSubclass {
public:
     void PrintCaller () { Print();
                     return A*5;
     int getA() {
     int getB() {
                     return B*5;
int main()
                                       getA: 1
     DerivedSubclass d;
                                       getB: 1
     d.PrintCaller();
CPPCON2019 | VIRTUAL TABLES AND ITS ALTERNATIVES | INBAL LEVI
```

```
template <typename D> class BaseCRTP {
public:
     BaseCRTP (int a = 1, int b = 1): A\{a\}, B\{b\}\{\}
     void Print() {
          cout << "getA: " << static cast<D&>(*this).getA() << endl;
          cout << "getB: " << static cast<D&>(*this).getB() << endl;
     int getA() {
                   return A;
     int getB() {
                  return B:
     int A;
     int B;
class DerivedCRTP : public BaseCRTP<DerivedCRTP> {
public:
     void PrintCaller () { Print();
     int getA() {
                    return A*5;
     int getB() {
                    return B*5;
int main()
                                  getA: 5
     DerivedCRTP d;
                                  getB: 5
     d.PrintCaller();
```

THE ALTERNATIVES - CRTP

```
template <typename D>
class BaseFilter {
public:
      void Activate()
           static_cast<D&>(*this) .Activate();
 protected:
      ~BaseFilter() = default;
class FilterDerived : public MiddleFilter<FilterDerived> {
public:
     void Activate() {
          cout << "Derived Activate" << endl;</pre>
```

```
template <typename D = void>
class MiddleFilter : public BaseFilter<MiddleFilter<D>> {
public:
     void Activate()
          Activate impl (std::is_same<D, void>{});
private:
     void Activate impl (std::true_type) {
          cout << "Middle Activate" << endl;</pre>
     void Activate_impl (std::false_type) {
          static cast<D&>(*this).Activate();
};
```

THE ALTERNATIVES - CRTP

```
template <typename D>
class BaseFilter {
 public:
      void Activate() {
           static cast<D&>(*this) .Activate();
 protected:
      ~BaseFilter() = default;
class FilterDerived : public MiddleFilter<FilterDerived> {
public:
     void Activate() {
          cout << "Derived Activate" << endl;</pre>
};
int main()
                                     Middle
     MiddleFilter<> f;
                                    Activate
     f.Activate();
```

```
template <typename D = void>
class MiddleFilter : public BaseFilter<MiddleFilter<D>> {
public:
     void Activate() {
          Activate impl (std::is same<D, void>{});
private:
     void Activate_impl (std::true_type) {
          cout << "Middle Activate" << endl;</pre>
     void Activate_impl (std::false_type) {
          static cast<D&>(*this).Activate();
```

```
int main()
{
    FilterDerived f;
    f.Activate();
}
```

Derived Activate

> THE ALTERNATIVES - CRTP - CONCLUSION

```
template <class FilterCRTP>
class BaseFilterCRTP
public:
    void Activate(int *pixel)
         static_cast <FilterCRTP&>(*this).ImplementActivate(pixel);
class FilterCRTP : public BaseFilterCRTP<FilterCRTP>
public:
    void ImplementActivate(int *pixel) {
         *pixel -=1;
};
```

```
int main()
{
    FilterCRTP fc;
    FilterCRTP *p_fc = &fc;
    p_fc ->Activate(&pixel);
}
```

THE ALTERNATIVES - CRTP

Subclassing

Not trivial for use

CRTP

Easy to read, understand & implement

Inheritance of more than one descendant is easy and clear

Derived can only HIDE Base member functions.

Inheritance of more than one descendant is hard

Derived can OVERRIDE Base member functions.

NOTICE: Both only allow to make decisions on Compile Time.

std::variant

template <class... Types>
class variant;

std::visit

template <class Visitor, class... Variants>
constexpr auto visit(Visitor&& vis, Variants&&... vars);

Lambda

[captures]<tparams> (params) -> ret { body }

```
struct FilterBright { };
struct FilterDark { };

struct VisitActivate
{
    void operator()(FilterBright& filter) { cout << "Filter Bright"; }</pre>
```

void operator()(FilterDark& filter) { cout << "Filter Dark"; }</pre>

```
int main()
{
    std::variant <FilterBright, FilterDark> MyFilter { FilterBright() };
    std::visit (VisitActivate(), MyFilter);
}
```



```
template<typename V, typename... Variants>
                                                                            variadic template
constexpr decltype(auto) visit(V&& visitor, Variants&&... variants)
    if ((variants . valueless_by_exception() | | ...))
                                                                         // error handling
         throw bad_variant_access("Unexpected index");
    using resultType = decltype (std::forward<V>(visitor)
                                                                         // recursive variant extraction
    (std::get<0>(std::forward<Variants>(variants))...));
    constexpr auto& variantVtable = detail::variant::gen_vtable
                                                                         // creation of vtable
         <resultType, V&&, Variants&& . . . >::S vtable;
    auto funcPtr = variantVtable.M_access(variants.index()...);
                                                                         // retrieve funPtr from index
    return (*funcPtr)(std::forward<V>(visitor), std::forward<Variants>(variants)...);
```

Anonymous

```
template<class... Ts> struct overload : Ts... { using Ts::operator()...; };
template<class... Ts> overload(Ts...) -> overload<Ts...>;
int main()
    std::variant<FilterBright, FilterDark, . . . > Filter{FilterDark()};
    std::visit (overload){
        [](FilterBright&) { cout << "Filter Bright"; },
        [](FilterDark&) { cout << "Filter Dark"; },</pre>
  }, Filter);
```



Multi variant

```
std::variant<FilterBright, FilterDark> MyFilter1 {FilterDark()};
std::variant<FilterBright, FilterDark> MyFilter2 {FilterBright()};
std::visit(overload{
    [](FilterBright&, FilterBright&) { cout << "FilterBright & FilterBright"; },
    [](FilterBright&, FilterDark&) { cout << "FilterBright & FilterDark"; }
},MyFilter1, MyFilter2);</pre>
```



```
std::variant<FilterBright, FilterDark> MyFilter1 {FilterDark()};
std::variant<FilterBright, FilterDark> MyFilter2 {FilterBright()};
std::visit(overload{
    [](FilterBright&, Pixel& pixel) { cout << "FilterBright"; pixel += 1; },
    [](FilterDark&, Pixel& pixel) { cout << "FilterDark"; pixel -= 1; }
}, FilterBright, Pixel&);</pre>
```

DRY RTB OFD MI AZÓ

Before: 5 After: 6

THE ALTERNATIVES - COMPILE TIME VISITOR

```
std::variant<FilterBright, FilterDark>
Filter{FilterDark()};
std::variant<Pixel> pixel = 5;
for(int i = 0; I < 1000; ++i)
    std::visit (VisitActivate(), Filter, pixel);
   std::variant<int> var{i};
   std::visit (CTAVisitActivate(), Filter, var);
   photoPixelAfter[i] = (var);
```



THE ALTERNATIVES - CONSTEXPR ?

A constexpr function must satisfy the following requirements:

- It must not be **virtual**. (until C++20)
- Its return type must be a LiteralType.
- Each of its parameters must be a LiteralType.
- The function body must not contain:
 - A definition of a variable of non-literal type.

A constexpr constructor must satisfy the following requirements:

- Each of its parameters must be a LiteralType.
- The class must have no virtual base classes.



BENCHMARKING

Pay attention:

- Platform
- Optimization level
- Compiler instructions: Inlining, constexpr, etc.
- Compiler version

THE CODE

```
class BaseFilterVirtual
public:
     virtual inline void Activate(int *pixel) const
          cout << "BaseFilterVirtual Activate" <<endl;</pre>
class FilterVirtual : public BaseFilterVirtual
public:
     virtual inline void Activate(int *pixel) const override
           *pixel -=1;
};
FilterVirtual fv;
BaseFilterVirtual *p_fv = &fv;
p_fv->Activate(&pixel);
```

```
template <class FilterCRTP> class BaseFilterCRTP
public:
     constexpr auto Activate(int *pixel) const noexcept
          static cast <const FilterCRTP *>(this)->
          ImplementActivate(pixel);
class FilterCRTP : public BaseFilterCRTP<FilterCRTP>
public:
     constexpr auto ImplementActivate(int *pixel)
     const noexcept
          *pixel -=1;
};
FilterCRTP fc;
FilterCRTP * p_fc = &fc;
```

p fc ->Activate(&pixel);

THE CODE

```
struct FilterBright {};
struct FilterBright { };
                                                                     struct FilterDark {};
struct FilterDark { };
                                                                     constexpr std::variant<Pixel> filter pixel(Pixel &val)
struct VisitActivate
                                                                           std::variant<FilterBright, FilterDark> Filter{FilterDark()};
     constexpr void operator()(FilterBright& filter, Pixel& pixel)
                                                                           std::variant<Pixel> pixel = 1;
     { pixel+=1; }
     constexpr void operator()(FilterDark&, Pixel& pixel)
                                                                           std::visit (VisitActivate(), Filter, pixel);
     { pixel-=1; }
};
                                                                           return pixel;
int main()
                                                                     int main()
     std::variant<int> photoS[PHOTO SIZE][PHOTO SIZE];
                                                                          std::variant<int> photoPixelAfter[PHOTO SIZE] = {0};
     std::variant<FilterBright, FilterDark> MyFilter {
     FilterBright() };
                                                                          constexpr auto pixel = filter_pixel(i);
     std::visit(VisitActivate(), MyFilter, photoS[Si][Sj]);
```

OPTIMIZATIONS

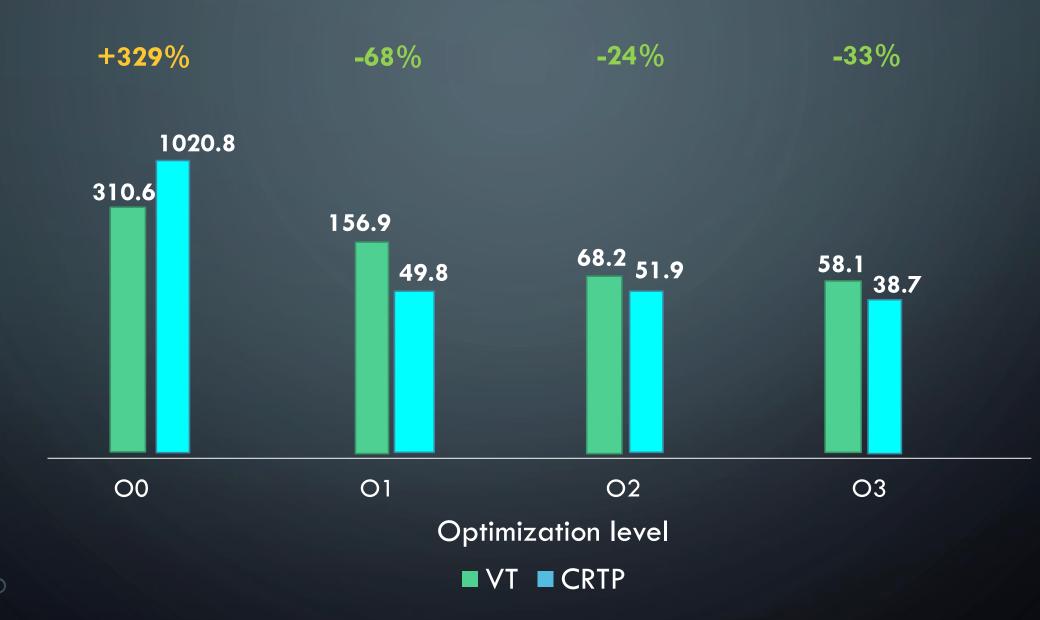
-00 / -01

Reduce code size and execution time, without optimizations that take a great deal of compilation time.

- -O2
 Reduce code size and execution time,increasing compile time. Adds loop unrolling.
- -O3
 All optimizations are on, including inline.
- -Os Reduce size.

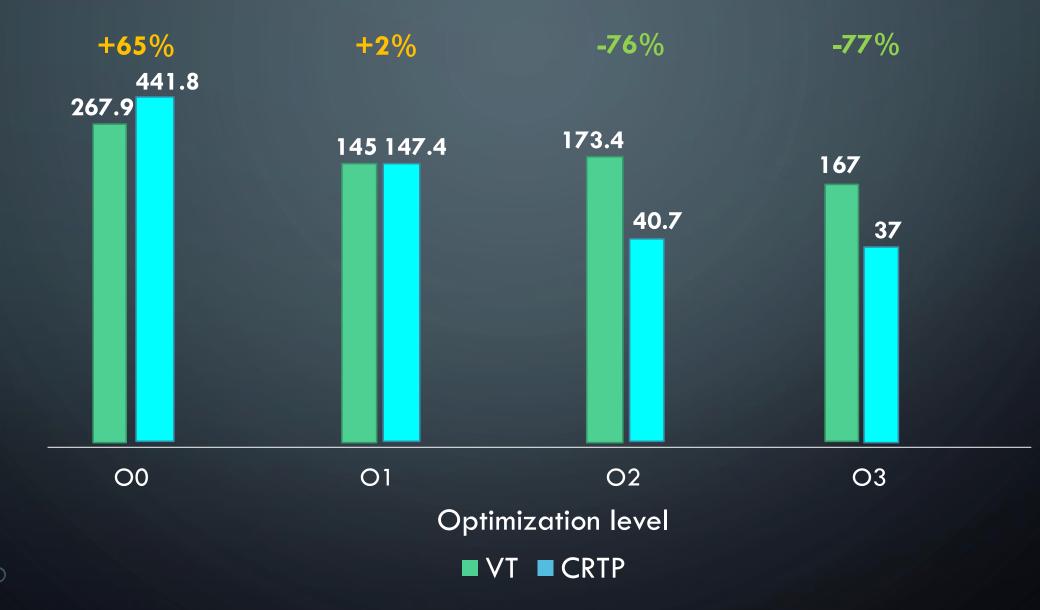
RESULTS - GCC

×1000

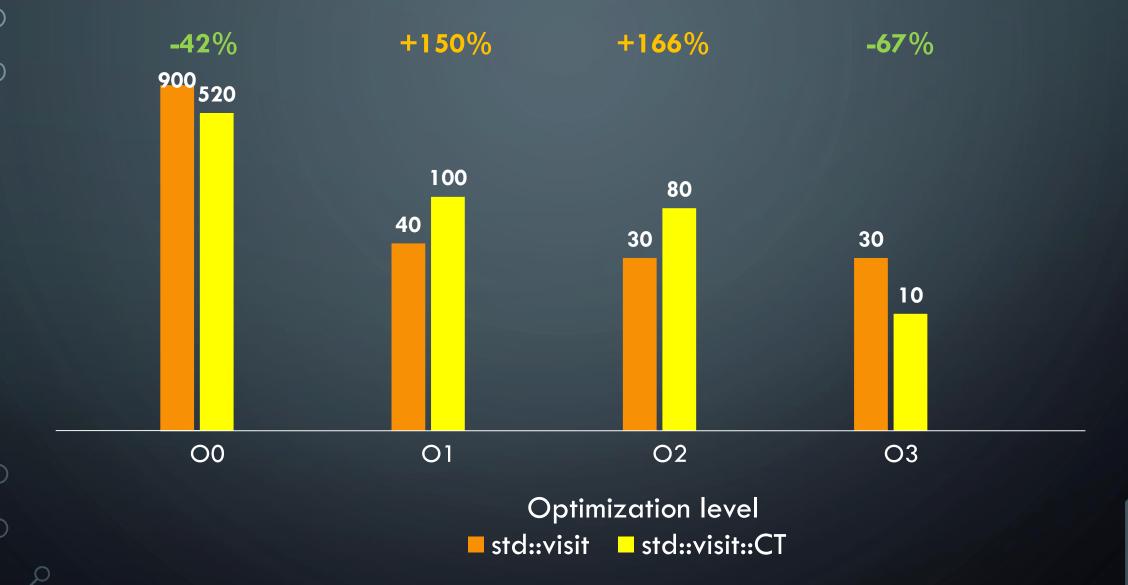


RESULTS - CLANG

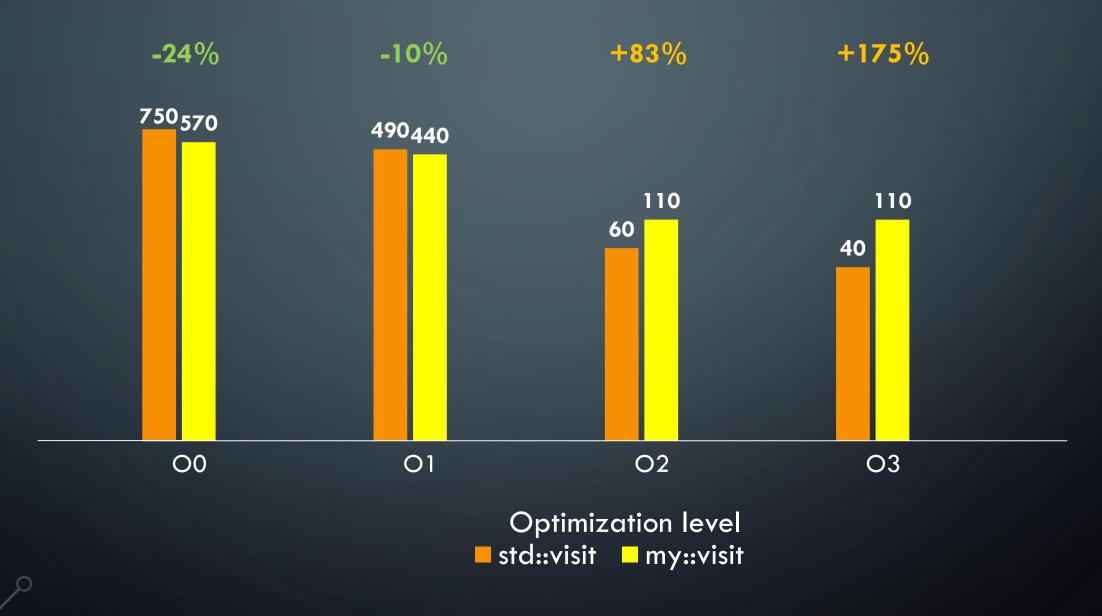
×1000



RESULTS - GCC



RESULTS - CLANG



CONCLUSION

• Overhead:

- Memory vs. Run time
- Design

• Structure:

- Static dispatch
- Dynamic dispatch

| | VT | CRTP | Visitor | CTVisitor |
|-----|--------------|--------------|--------------|--------------|
| DRY | \checkmark | \checkmark | \checkmark | \checkmark |
| RTB | \checkmark | | \checkmark | * |
| OFD | \checkmark | \checkmark | \checkmark | \checkmark |
| MLI | \checkmark | \checkmark | | |
| AED | \checkmark | \checkmark | × | |
| | Slow | | | |

THE FUTURE...

- Expand compile time programming
 - C++20's major features include:
 - Broad use of "normal" C++ for direct compile-time programming,
 without using template metaprogramming (the guys in the next room...)
- constexpr, consteval
- virtual constexpr? /something else?
 - 2019: P1717 Compile-time Metaprogramming in C++
 - 2018: P1064 Allowing Virtual Function Calls in Constant Expressions
- WIP ISO C++20

VIRTUAL DISPATCH AND ITS ALTERNATIVES

Thank you!

- Bryce lelbach
- Louis Dionne
- Jason turner
- Compiler Explorer (godbolt.org)

(the guy in the next room...)

The internet!

Stay In Touch!
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