Notes on implementing b-splines

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This is an attempt to clean-up the notation in Carl de Boor's b-spline notes, The m-th B-spline of order $K = 1$ is defined as,

$$X_m^1(t) \equiv \begin{cases} 1 & \text{if } \tau_m \leq t < \tau_{m+1}, \\ 0 & \text{otherwise.} \end{cases} \tag{1}$$

All higher order B-splines are defined by recursion,

$$X_m^K(t) \equiv \frac{t - t_m}{t_{m+K-1} - t_m} X_m^{K-1}(t) + \frac{t_{m+K} - t}{t_{m+K} - t_{m+1}} X_{m+1}^{K-1}(t). \tag{2}$$

and a path is represented as $x(t) \equiv X_m^K(t)\xi^m$ where ξ^m are the coefficients.

The j-th derivative of this path is,

$$\left(\frac{d}{dt}\right)^j \left(X_m^K(t)\xi^m\right) = \xi_{j+1}^m X_m^{K-j}(t) \tag{3}$$

where

$$\xi_{j+1}^m \equiv \begin{cases} \xi^m & \text{for } j = 0, \\ \frac{\xi_j^m - \xi_j^{m-1}}{(t_{m+K-j} - t_m)/(K-j)} & \text{otherwise.} \end{cases} \tag{4}$$

So you compute the coefficients of the higher order derivatives, by differencing the coefficients.

So, de Boor's algorithm is the following sum over $K-j$ non-zero splines for position t,

$$
\begin{aligned}
x^{(j)}(t) &= \sum_{m=1}^{K-j} \xi_{j+1}^{m} X_m^{K-j}(t) && (5)\\
&= \sum_{m=1}^{K-j} \xi_{j+1}^{m} \left[\frac{t-t_m}{t_{m+K-1}-t_m} X_m^{K-j-1}(t) + \frac{t_{m+K}-t}{t_{m+K}-t_{m+1}} X_{m+1}^{K-j-1}(t) \right] && (6)\\
&= \sum_{m=1}^{K-j} \xi_{j+1}^{m} \left[\frac{t-t_m}{t_{m+K-1}-t_m} X_m^{K-j-1}(t) \right] + \sum_{m=0}^{K-j-1} \xi_{j+1}^{m-1} \left[\frac{t_{m+K-1}-t}{t_{m+K-1}-t_m} X_m^{K-j-1}(t) \right] && (7)
\end{aligned}
$$