



# General Physics 1

Istanbul Medipol University  
Fall 2020

Instructor: Asst. Prof. Merve Yüstra Doğan

## Welcome and Introduction

- Course Webpage
  - MS Teams
  - Google classroom, class code: 72jbrpy
  - Use Medipol email**
- Syllabus

## Syllabus

- **Instructor:** Asst. Prof. Merve Yüstra Doğan, mydogan@medipol.edu.tr
- **Office Hours:** Monday, 13:00 - 14:00, Teams
- **Textbook:** Young & Freedman, University Physics with Modern Physics, 13th Edition
- **Lecture:** Monday 14:30 - 17:15
- **Recitation:** TBA
- **Laboratory:** on MS Teams, a different class.

## Syllabus - Teaching Assistants

**TA** **email**

Ömer Kartlı okartli@st.medipol.edu.tr  
Hakan Yücelten hyucelten@st.medipol.edu.tr  
Mehmet Emin Bayrak mebayrak@st.medipol.edu.tr  
Hilal Bulut hbulut@st.medipol.edu.tr

## Syllabus - Calendar

| Tentative Calendar |     |         |  |
|--------------------|-----|---------|--|
| Month              | Day | Chapter | Subject                                  |
| October            | 5   |         | Cancelled                                |
|                    | 12  | 1       | Units, Physical Quantities and Vectors   |
|                    | 19  | 2       | Motion along a straight line             |
|                    | 26  | 3       | Motion in two or three dimensions        |
| November           | 2   | 4       | Newton's Laws of Motion                  |
|                    | 9   | 5       | Applying Newton's Laws                   |
|                    | 16  | 6       | Work and Kinetic Energy                  |
|                    | 23  | 7       | Potential Energy and Energy Conservation |
|                    | 30  |         | Midterm Week                             |
| December           | 7   | 8       | Momentum, Impulse and Collisions         |
|                    | 14  | 9       | Rotation of Rigid Bodies                 |
|                    | 21  | 10      | Dynamics of Rotational Motion            |
|                    | 28  | 11      | Equilibrium and Elasticity               |
| January            | 4   | 14      | Periodic Motion                          |
|                    | 11  | 12      | Fluid Mechanics                          |
|                    | 18  | 13      | Gravitation                              |
|                    | 25  | 15      | Mechanical Waves                         |
| February           | 1   |         | Finals Week                              |

## Syllabus - Grading

- Quiz 30 %
- Midterm 30 %
- Final 40 %

## Syllabus - Exams

### Exams

- You will need to upload files for quiz and exams.
- Please do have an easy access method to scan and upload a pdf file. The easiest method is to have a scanning app on your smartphone.
- We may ask you to turn on your camera during any exam.
- We may have Zoom meetings for exams

### Quiz

- Quizzes will be held during class.
- The quiz platform will vary as QuizEvolved / MS Teams / Google Classroom to be announced during lecture.
- Quiz weights may vary according to content.
- **If we suspect any wrong-doing during any quiz/exam, we will give you an oral exam to replace the respective exam.**

### Midterm and Final

- The midterm day and final day will be set during midterm/finals week.
- Final will cover the entire course material.

## Syllabus – Online Quiz

- <http://quizevolved.com>
- Join this class: ACCESS CODE: 11649953
- **Write your name as it appears on your records when you sign up**
- During lecture, I will give you an access code for the week's quiz

Let's get started!  
Registration is fast and simple.

I am a...

Username

First Name

Last Name

Student ID

Email

Password

Confirm password

Confirm Security Code

## Syllabus - Homework

- Several problems will be assigned
- Homework will not be collected
- It is good practice to work on these problems to fully comprehend the subject matter.

## Syllabus - Written Homework Format

- Guidelines to keep your work neat
- Important to develop good problem solving skills
- Organize your thoughts
- Representative sketches
- Correct formulas
- Thought process

## Syllabus - Recitation

- Problem solving sessions
- Recitations are biweekly. Time TBA
- Recitation weeks are highlighted in green in the calendar.
- Although recitations are not mandatory, it will be wise to attend them

## Syllabus - Laboratory Information

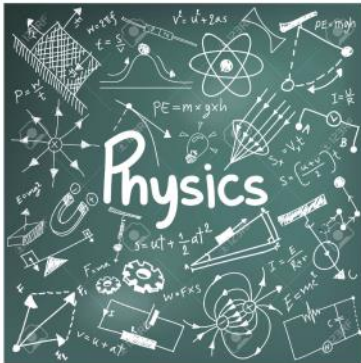
- Labs will be online – virtual labs
- You will be assigned a lab section/time.
- You must attend the section you are assigned.
- You cannot miss an experiment and make up in another section.
- Any excuses need written approval.
- Your TAs are in full charge of the laboratory session
- You need to have a copy of the Lab Manual
- Bring the manual with you to every lab.
- I will post your section assignment on Google classroom/MS Teams

## Syllabus - Laboratory Information

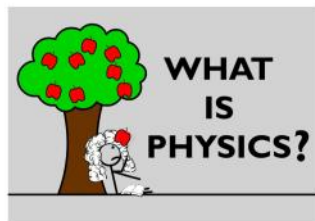
- Lab Manual: Webpage
- Lab Orientation: In the lab, at the beginning of your first lab
- 6 Experiments, days and times TBA

| Experiments                     |
|---------------------------------|
| 1. Motion Along a Straight Line |
| 2. Projectile Motion            |
| 3. Hooke's Law                  |
| 4. Conservation of Momentum     |
| 5. Rotational Motion            |
| 6. Simple Pendulum              |

- Add class on Google Classroom
- Sign up on QuizEvolved.com
- Get a copy of the Laboratory Manual

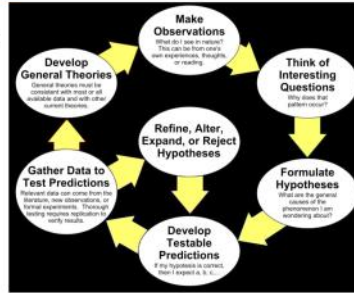


- An experimental science
- Aims to understand the complex universe based on simple ideas
- Finds patterns that relate the phenomena of nature.
- Definition:  
The science that deals with **matter, energy, motion, and force**



## The scientific method

- Finds patterns that relate the phenomena of nature.
- All sciences use the scientific method
  - Observation
  - Question
  - Hypothesis
  - Prediction
  - Test --> experiments
  - Iterate
  - Formulate a general rule



## Physical laws

- The general rules or patterns arrived at are called  
*physical theories*
- A very well established or widely used theory is called  
*a physical law or principle.*

## Fundamental quantities of physics

- Some physical quantities are so fundamental that we can define them only by describing how to measure them.

| Fundamental Quantities    | Units       | Some Derived Quantities                  | Units                 |
|---------------------------|-------------|--|-----------------------|
| Length                    | meter m     | Speed                                    | m/s                   |
| Mass                      | kilogram kg | (ratio of a length by a time)            |                       |
| Time                      | second s    | Acceleration                             | m/s <sup>2</sup>      |
| Electric current          | ampere A    | (ratio of a speed by a time)             |                       |
| Thermodynamic temperature | Kelvin K    | Force                                    | kg · m/s <sup>2</sup> |
| Amount of substance       | mole mol    | (multiplication of acceleration by mass) |                       |
| Luminous intensity        | candela Cd  |  |                       |

## SI Units: International System of Units (*Système International d'Unités*)

- Reference standard
- Such a standard defines a unit of the quantity
- A physical quantity is described by a number and a unit
- The 'INTERNATIONAL SYSTEM OF UNITS', abbreviated SI, defines the seven quantities and a physical standard for each (\*UNIT\*)
- Quantities of the same type can be compared against the same unit

## Some SI derived quantities and units

| Quantity               | Units     | Quantity                  | Units     |                              |
|------------------------|-----------|---------------------------|-----------|------------------------------|
| • area                 | $m^2$     | • frequency               | Hertz H   | 1/s                          |
| • volume               | $m^3$     | • force                   | Newton N  | $kg \cdot m/s^2$             |
| • mass density         | $kg/m^3$  | • pressure                | Pascal Pa | $kg / (m \cdot s^2)$         |
| • speed, velocity      | m/s       | • work, energy            | Joule J   | $kg \cdot m^2/s^2$           |
| • angular velocity     | rad/s     | • power                   | Watt W    | $kg \cdot m^2/s^3$           |
| • acceleration         | $m/s^2$   | • quantity of electricity | Coulomb C | A · s                        |
| • angular acceleration | $rad/s^2$ | • potential difference    | Volt V    | $kg \cdot m^2/(A \cdot s^2)$ |
| • kinematic viscosity  | $m^2/s$   |                           |           |                              |

## The British System of Units

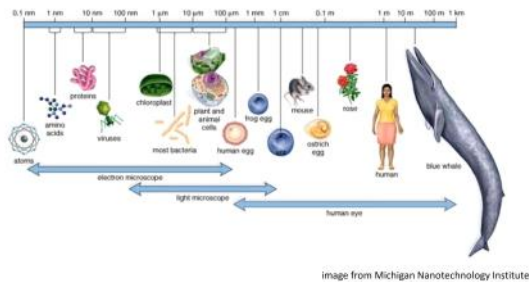
| English Unit | SI Unit    | Conversion        |
|--------------|------------|-------------------|
| Mile         | Kilometer  | 1 mile = 1.609 km |
| Foot         | Meter      | 1 ft = 0.305 m    |
| Inch         | Centimeter | 1 in = 2.54 cm    |
| Pound        | Grams      | 1 lb = 453.59 g   |
| Ounce        | Grams      | 1 oz = 28.35 g    |
| Gallon       | Liter      | 1 gallon = 3.79 l |
| Celsius      | Kelvin     | 0° C = 273.15 K   |



## Unit prefixes

| Number                | Multiplication Factor | Prefix | Prefix Symbol |
|-----------------------|-----------------------|--------|---------------|
| 1 000 000 000 000 000 | $10^{15}$             | peta   | P             |
| 1 000 000 000 000     | $10^{12}$             | tera   | T             |
| 1 000 000 000         | $10^9$                | giga   | G             |
| 1 000 000             | $10^6$                | mega   | M             |
| 1 000                 | $10^3$                | kilo   | k             |
| 100                   | $10^2$                | hecto  | h             |
| 10                    | $10^1$                | deka   | da            |
| 0.1                   | $10^{-1}$             | deci   | d             |
| 0.01                  | $10^{-2}$             | centi  | c             |
| 0.001                 | $10^{-3}$             | milli  | m             |
| 0.000 001             | $10^{-6}$             | micro  | $\mu$         |
| 0.000 000 001         | $10^{-9}$             | nano   | n             |
| 0.000 000 000 001     | $10^{-12}$            | pico   | p             |
| 0.000 000 000 000 001 | $10^{-15}$            | femto  | f             |

## Some size scales



## Unit consistency and calculating with units

- Physical quantities are represented by both a number and a unit
- Example: d represent a distance of 100 meters, d = 100 m
- An equation must always be dimensionally consistent.**
- Example: How many minutes does it take to travel 50 km in a car traveling with constant speed at 100 km/hr ?

$$\text{duration} = (50 \text{ km}) \left( \frac{\text{hr}}{100 \text{ km}} \right) \left( \frac{60 \text{ min}}{\text{hr}} \right)$$

$$\text{duration} = 30 \text{ min}$$

## Unit consistency and calculating with units

- *Example: Speed limit on the highway is 65 mph. What is this in meters per second?*

$$65 \text{ mph} = \left( \frac{65 \text{ miles}}{\text{hour}} \right) \left( \frac{1.609 \text{ km}}{\text{miles}} \right) \left( \frac{1000 \text{ m}}{\text{km}} \right) \left( \frac{\text{hour}}{60 \text{ min}} \right) \left( \frac{\text{min}}{60 \text{ s}} \right)$$

$$65 \text{ mph} = 29.05 \text{ m/s}$$


- *Don't write:*  $65 \text{ mph} = \frac{65 \times 1.609 \times 1000}{60 \times 60} \text{ m/s}$

- **Always include unit conversions in your calculations**

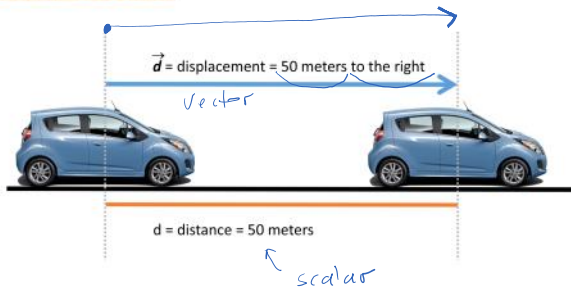
## Scientific notation and significant figures

- In scientific notation, the number is represented with a single digit before decimals, multiplied by a power of 10.
- Example:
  - $572000000 = 5.72 \times 10^8$
  - $0.0000408 = 4.08 \times 10^{-5}$   
(digit term) (exponential term)
- Significant figures of a number are digits that carry meaning contributing to its measurement resolution:
  - 0.00045 (two significant figures) becomes  $4.5 \times 10^{-4}$
  - 0.00452500 (six significant figures) becomes  $4.52500 \times 10^{-3}$
  - 1300 to four significant figures is written as  $1.300 \times 10^3$
  - 1300 to two significant figures is written as  $1.3 \times 10^3$

## Scalars and vectors

- A **scalar quantity** can be described by a **single number (magnitude)**.
- A **vector quantity** has both a **magnitude** and a **direction** in space.
- A vector quantity is represented with an arrow over it:  $\vec{A}$ . 
- The magnitude of  $\vec{A}$  is written as  $A$  or  $|\vec{A}|$ .

## Scalar vs vector

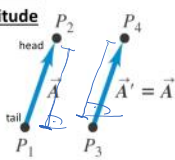


## Vectors

- head, tail, magnitude, direction

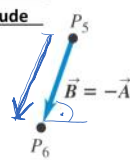
### same direction

#### same magnitude



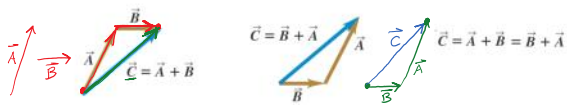
### opposite direction

#### same magnitude

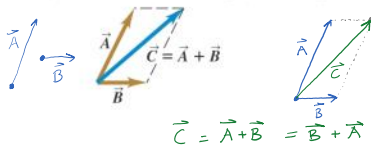


## Vector addition: two vectors

- Option 1: Add by placing them head to tail



- Option 2: Add by drawing a parallelogram

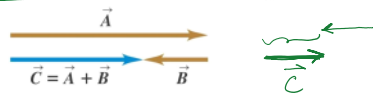


## Vector addition

- Adding two parallel vectors



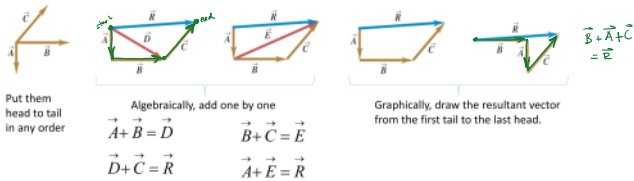
- Adding two antiparallel vectors



## Vector addition: multiple vectors

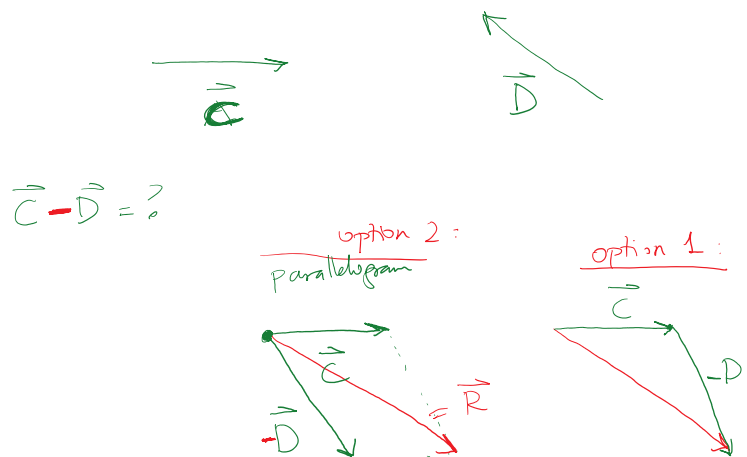
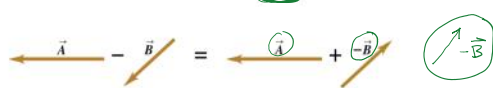
- Add with head-to-tail method in any order

- Finding  $\vec{C} + \vec{A} + \vec{B}$



## Vector subtraction

$$\vec{A} - \vec{B} = \vec{A} + (-\vec{B})$$



## Multiplying a vector by a scalar

- When a vector  $\vec{A}$  is multiplied by a scalar  $c$ , the product  $c\vec{A}$  has magnitude  $|c|A$ .

- If  $c$  is positive, only the magnitude of  $\vec{A}$  changes.



- If  $c$  is negative, the magnitude changes, and the direction of  $\vec{A}$  is reversed



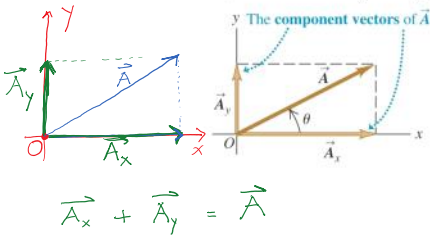
$\vec{A}$  vector  $c$  scalar

$$\rightarrow = 2\vec{A}$$

$$\rightarrow (-3)$$

## Vector components

- Consider a two-dimensional coordinate system and the vector  $\vec{A}$  placed with its tail at the origin
- Projecting  $\vec{A}$  onto the axes gives its component vectors
- $\vec{A}$  is the sum of its component vectors  $\vec{A}_x$  and  $\vec{A}_y$



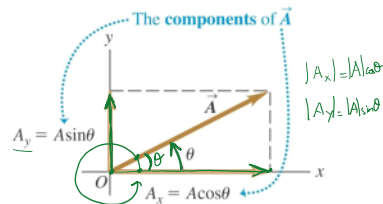
## Vector components

- Components are found using trigonometry

$$A_x = A \cos \theta$$

$$A_y = A \sin \theta$$

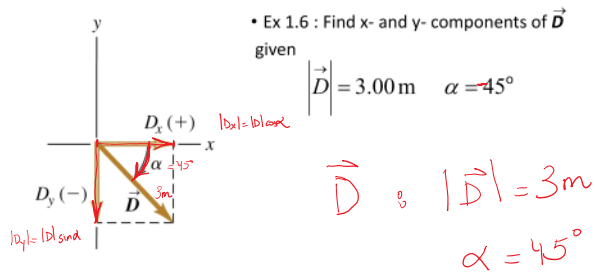
$\theta$  is measured from the +x-axis toward the +y-axis.



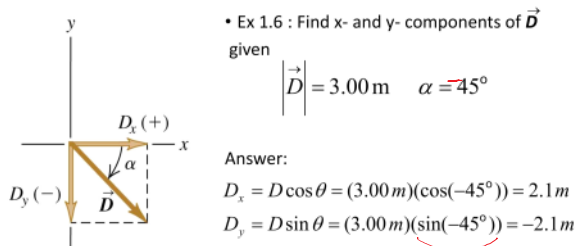
$$\vec{A} = \vec{A}_x + \vec{A}_y$$

$$|A_x|\hat{x} + |A_y|\hat{y} =$$

## Finding vector components



## Finding vector components

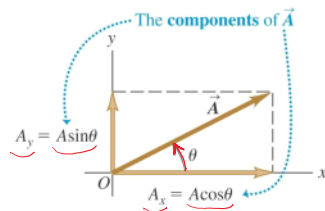


## Vector components

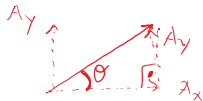
- Similarly, we can find the magnitude and direction of a vector from its components

$$A = \sqrt{A_x^2 + A_y^2}$$

$$\tan \theta = \frac{A_y}{A_x}$$



$$\frac{|A_y|}{|A_x|} = \tan \theta$$



$$|\vec{A}| = \sqrt{|A_x|^2 + |A_y|^2}$$

## Calculating with components

- The sum of two or more vectors can be calculated using components

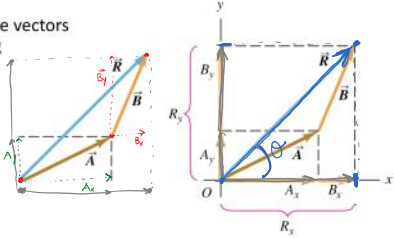
$$R_x = A_x + B_x$$

$$R_y = A_y + B_y$$

- more generally,

$$R_x = A_x + B_x + C_x + D_x + \dots$$

$$R_y = A_y + B_y + C_y + D_y + \dots$$

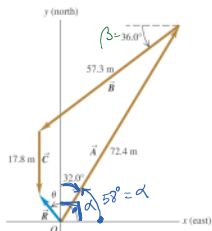


$$\begin{aligned}\vec{A} &= A_x \hat{x} + A_y \hat{y} \\ \vec{B} &= B_x \hat{x} + B_y \hat{y} \\ + \\ \vec{R} &= (A_x + B_x) \hat{x} + (A_y + B_y) \hat{y} \\ \vec{R} &= R_x \hat{x} + R_y \hat{y} \\ |\vec{R}| &= \sqrt{R_x^2 + R_y^2} \\ \tan \theta &= \frac{R_y}{R_x}, \quad \theta = \arctan \frac{R_y}{R_x}\end{aligned}$$

$$\begin{aligned}\vec{A} &= A_x \hat{x} + A_y \hat{y} \\ \vec{B} &= B_x \hat{x} + B_y \hat{y} \\ \vec{C} &= C_x \hat{x} + C_y \hat{y} \\ \vec{D} &= D_x \hat{x} + D_y \hat{y} \\ + \\ \vec{R} &= (A_x + B_x + C_x + D_x) \hat{x} + (A_y + B_y + C_y + D_y) \hat{y} \\ &= R_x \hat{x} + R_y \hat{y}\end{aligned}$$

## Calculating with components

- Ex 1.7: Find R and  $\theta$  for the given configuration



$$\vec{A} + \vec{B} + \vec{C} = \vec{R}$$

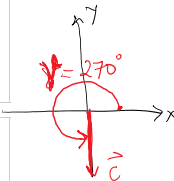
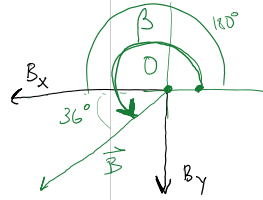
$$\begin{cases} \vec{A}: |\vec{A}| = 72.4 \text{ m} \quad \alpha = 58^\circ \\ A_x = (72.4) \cos 58^\circ \\ A_y = (72.4) \sin 58^\circ \end{cases}$$

$$\begin{cases} \vec{B}: |\vec{B}| = 57.3 \text{ m} \quad \beta = 36^\circ + 180^\circ = 216^\circ \\ B_x = (57.3) \cos 216^\circ \\ B_y = (57.3) \sin 216^\circ \end{cases}$$

$$\vec{C}: |\vec{C}| = 17.8 \text{ m} \\ \gamma = 270^\circ$$

$$C_x = 0 = 17.8 \cos 270^\circ$$

$$C_y = -17.8 = 17.8 \sin 270^\circ$$



$$\vec{R} = R_x \hat{x} + R_y \hat{y}$$

$$R_x = A_x + B_x + C_x$$

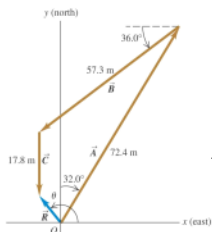
$$R_y = A_y + B_y + C_y$$

$$|\vec{R}| = \sqrt{R_x^2 + R_y^2}$$

$$\theta = \arctan \frac{R_y}{R_x}$$

## Calculating with components

- Ex 1.7: Find R and  $\theta$  for the given configuration



$$R_x = A_x + B_x + C_x$$

$$R_y = A_y + B_y + C_y$$

$$R = \sqrt{R_x^2 + R_y^2}$$

$$\theta = \arctan \frac{R_y}{R_x}$$

$$A_x = (72.4 \text{ m})(\cos 58^\circ) = 38.37 \text{ m}$$

$$B_x = (57.3 \text{ m})(\cos 216^\circ) = -46.36 \text{ m}$$

$$C_x = (17.8 \text{ m})(\cos 270^\circ) = 0$$

$$R_x = -7.99 \text{ m}$$

$$A_y = (72.4 \text{ m})(\sin 58^\circ) = 61.4 \text{ m}$$

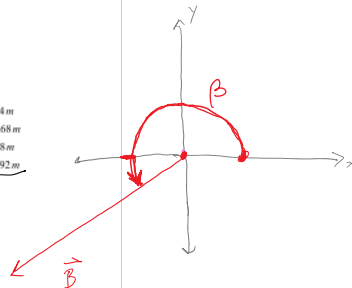
$$B_y = (57.3 \text{ m})(\sin 216^\circ) = -33.68 \text{ m}$$

$$C_y = (17.8 \text{ m})(\sin 270^\circ) = -17.8 \text{ m}$$

$$R_y = -9.92 \text{ m}$$

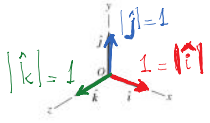
$$R = \sqrt{(-7.99 \text{ m})^2 + (-9.92 \text{ m})^2} = 12.7 \text{ m}$$

$$\theta = \arctan \frac{-9.92 \text{ m}}{-7.99 \text{ m}} = -51^\circ$$

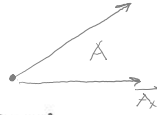


## Unit vectors

- A unit vector has a magnitude of 1 with no units.



- $\hat{i}$  points in the +x-direction
- $\hat{j}$  points in the +y-direction
- $\hat{k}$  points in the +z-direction



Any vector can be expressed in terms of its components as  $\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$   
 such as displacement,  $\vec{D} = (20\hat{i} - 40\hat{j} + 60\hat{k}) \text{ m}$

## Products of vectors

- Two types of products of vectors:

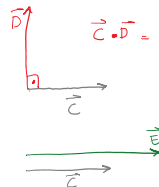
- Dot product
- Cross product

## The dot product (scalar product)



$$\vec{A} \cdot \vec{B} = A(B \cos \phi) = B(A \cos \phi) = \vec{B} \cdot \vec{A}$$

- For perpendicular vectors,  $\phi = 90^\circ$ ,  $\cos \phi = 0$ ;  $\vec{A} \cdot \vec{B} = 0$
- For parallel vectors,  $\phi = 0^\circ$ ,  $\cos \phi = 1$ ;  $\vec{A} \cdot \vec{B} = (A)(B)$



$$\vec{C} \cdot \vec{D} = CD \cos \phi = CD \cos 90^\circ = 0$$

$$\vec{C} \cdot \vec{E} = CE \cos \phi = CE \cos 0^\circ = CE$$

## The dot product in components

$$\vec{A} \cdot \vec{B} = (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k})$$

$$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = (1)(1) \cos 0^\circ = 1$$

$$\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = (1)(1) \cos 90^\circ = 0$$

$$\vec{A} \cdot \vec{B} = (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k})$$

$$= (A_x \hat{i} \cdot B_x \hat{i} + A_x \hat{i} \cdot B_y \hat{j} + A_x \hat{i} \cdot B_z \hat{k}) + (A_y \hat{j} \cdot B_x \hat{i} + A_y \hat{j} \cdot B_y \hat{j} + A_y \hat{j} \cdot B_z \hat{k}) + (A_z \hat{k} \cdot B_x \hat{i} + A_z \hat{k} \cdot B_y \hat{j} + A_z \hat{k} \cdot B_z \hat{k})$$



$$\vec{A} \cdot \vec{B} = (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k})$$

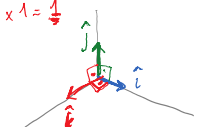
$$\begin{aligned} \hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} &= (1)(1) \cos 0^\circ = 1 \leftarrow \\ \hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} &= (1)(1) \cos 90^\circ = 0 \leftarrow \end{aligned}$$

$$\vec{A} \cdot \vec{B} = A_x B_x \hat{i} \cdot \hat{i} + A_y B_y \hat{j} \cdot \hat{j} + A_z B_z \hat{k} \cdot \hat{k} + A_x B_y \hat{i} \cdot \hat{j} + A_y B_x \hat{j} \cdot \hat{i} + \dots$$

$$\vec{A} \cdot \vec{B} = A_x B_x (1) + A_y B_y (1) + A_z B_z (1) + A_x B_y (0) + A_y B_x (0) + \dots$$

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

$$\begin{aligned} \begin{pmatrix} A_x \hat{i} \\ A_y \hat{j} \\ A_z \hat{k} \end{pmatrix} \cdot \begin{pmatrix} B_x \hat{i} \\ B_y \hat{j} \\ B_z \hat{k} \end{pmatrix} &= A_x B_x + A_y B_y + A_z B_z \\ \text{example: } \begin{pmatrix} 3 \hat{i} \\ -4 \hat{j} \\ 5 \hat{k} \end{pmatrix} \cdot \begin{pmatrix} 5 \hat{i} \\ 6 \hat{j} \\ -4 \hat{k} \end{pmatrix} &= (3)(5) + (-4)(6) + (5)(-4) = 15 - 24 - 20 = -29 \leftarrow \text{scalar} \end{aligned}$$

$$\begin{aligned} (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) \\ (A_x \hat{i} \cdot B_x \hat{i} + A_y \hat{j} \cdot B_y \hat{j} + A_z \hat{k} \cdot B_z \hat{k}) + (A_x \hat{i} \cdot B_y \hat{j} + A_y \hat{j} \cdot B_x \hat{i} + \dots) \\ A_x B_x \quad (\hat{i} \cdot \hat{i}) = |\hat{i}| |\hat{i}| \cos 0 = 1 \times 1 \times 1 = 1 \\ \hat{i} \cdot \hat{j} = 0 \quad \text{normal vectors} \\ \hat{i} \cdot \hat{k} = 0 \quad \text{normal} \\ \hat{j} \cdot \hat{j} = 1 \\ \hat{j} \cdot \hat{k} = 0 \\ \hat{k} \cdot \hat{k} = 1 \end{aligned}$$


## The dot product in components

• Ex 1.11: Find the angle between the vectors

$$\vec{A} = (2.00\hat{i} + 3.00\hat{j} + 1.00\hat{k}) \quad \text{and} \quad \vec{B} = (-4.00\hat{i} + 2.00\hat{j} - 1.00\hat{k})$$

$$\begin{aligned} \vec{A} \cdot \vec{B} &= AB \cos \theta \\ \vec{A} \cdot \vec{B} &= A_x B_x + A_y B_y + A_z B_z \end{aligned} \quad \left. \vphantom{\vec{A} \cdot \vec{B}} \right\} =$$

$$\begin{aligned} AB \cos \theta &= A_x B_x + A_y B_y + A_z B_z \\ AB \cos \theta &= [(2)(-4) + (3)(2) + (1)(-1)] = -3 \end{aligned}$$

$$\cos \theta = \frac{-3}{|\vec{A}| |\vec{B}|} = \frac{-3}{\sqrt{14} \sqrt{21}} \Rightarrow \theta = \arccos \frac{-3}{\sqrt{14} \sqrt{21}}$$

$$|\vec{A}| = \sqrt{2^2 + 3^2 + 1^2} = \sqrt{14}, \quad |\vec{B}| = \sqrt{(-4)^2 + 2^2 + (-1)^2} = \sqrt{21}$$

## The dot product in components

• Ex 1.11: Find the angle between the vectors

$$\vec{A} = (2.00\hat{i} + 3.00\hat{j} + 1.00\hat{k}) \quad \text{and} \quad \vec{B} = (-4.00\hat{i} + 2.00\hat{j} - 1.00\hat{k})$$

$$\vec{A} \cdot \vec{B} = A(B \cos \phi) \Rightarrow \phi = \arccos \frac{\vec{A} \cdot \vec{B}}{AB} = \arccos \frac{-3}{\sqrt{14} \sqrt{21}} = 100^\circ$$

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z = (2)(-4) + (3)(2) + (1)(-1) = -3$$

$$A = \sqrt{A_x^2 + A_y^2 + A_z^2} = \sqrt{2^2 + 3^2 + 1^2} = \sqrt{14}$$

$$B = \sqrt{B_x^2 + B_y^2 + B_z^2} = \sqrt{(-4)^2 + 2^2 + (-1)^2} = \sqrt{21}$$

### The cross product (vector product)

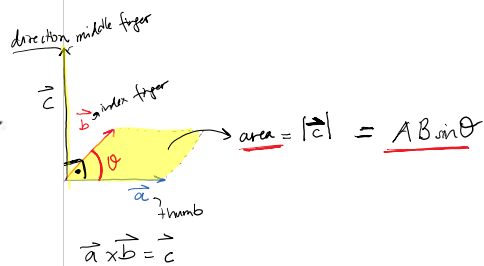
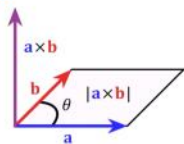
$$\vec{C} = \vec{A} \times \vec{B}$$

$$|\vec{C}| = |\vec{A} \times \vec{B}| = AB \sin \phi$$

→ •  $\vec{C}$  always perpendicular to the plane

→ • Direction of  $\vec{C}$  is determined by the right hand rule

→ • Magnitude of  $\vec{C}$  corresponds to the area of the parallelogram



### Properties of the cross product

$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

• For perpendicular vectors,  $\theta = 90^\circ$ ,  $\sin \theta = 1$ ;  $\vec{A} \times \vec{B} = AB$

• For parallel vectors,  $\theta = 0^\circ$ ,  $\sin \theta = 0$ ;  $\vec{A} \times \vec{B} = 0$

$$(\vec{A} + \vec{B}) \times \vec{C} = (\vec{A} \times \vec{C}) + (\vec{B} \times \vec{C})$$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

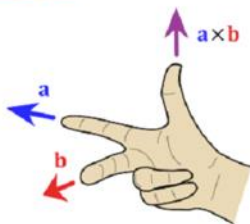
## Properties of the cross product

- Calculating the determinant  $\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix} = \hat{i} \begin{vmatrix} a_y & a_z \\ b_y & b_z \end{vmatrix} - \hat{j} \begin{vmatrix} a_x & a_z \\ b_x & b_z \end{vmatrix} + \hat{k} \begin{vmatrix} a_x & a_y \\ b_x & b_y \end{vmatrix}$$

$$\vec{a} \times \vec{b} = (a_y b_z - a_z b_y) \hat{i} + (a_z b_x - a_x b_z) \hat{j} + (a_x b_y - a_y b_x) \hat{k}$$

## The right hand rule



## The cross product

- Ex 1.12: Magnitudes of  $\vec{A}$  and  $\vec{B}$  shown in figure are 6 and 4 units respectively. Find their cross product  $\vec{C}$ .

- Magnitude :

$$|\vec{C}| = |\vec{A} \times \vec{B}| = AB \sin \phi = (6)(4) \sin 30^\circ = 12$$

- Direction: using right hand rule,  
 $\hat{k}$

