

---

# **open source watch Documentation**

***Release 1.0.0***

**jj**

**Dec 25, 2019**



# CONTENTS

<b>1</b>	<b>author:</b>	<b>3</b>
<b>2</b>	<b>LICENSE:</b>	<b>5</b>
<b>3</b>	<b>Zephyr for the pinetime smartwatch</b>	<b>7</b>
<b>4</b>	<b>Install zephyr</b>	<b>9</b>
<b>5</b>	<b>zephyr on the pinetime smartwatch</b>	<b>11</b>
5.1	Blinky example . . . . .	11
<b>6</b>	<b>Reading out the button on the watch</b>	<b>13</b>
6.1	Building and Running . . . . .	13
<b>7</b>	<b>bluetooth (BLE) example</b>	<b>15</b>
7.1	Eddy Stone . . . . .	15
7.2	Ble Peripheral . . . . .	15
7.3	using Python to read out bluetoothservices . . . . .	16
<b>8</b>	<b>st7789 display</b>	<b>17</b>
8.1	Display example . . . . .	17
<b>9</b>	<b>LittlevGL Basic Sample</b>	<b>19</b>
9.1	Overview . . . . .	19
9.2	Requirements . . . . .	19
9.3	Building and Running . . . . .	19
9.4	Todo . . . . .	19
9.5	References . . . . .	20
<b>10</b>	<b>LittlevGL Clock Sample</b>	<b>21</b>
10.1	Overview . . . . .	21
10.2	Requirements . . . . .	21
10.3	Building and Running . . . . .	21
10.4	Todo . . . . .	22
10.5	References . . . . .	22
<b>11</b>	<b>placing a button on the screen</b>	<b>23</b>
11.1	Building and Running . . . . .	23
<b>12</b>	<b>Real Time Clock</b>	<b>25</b>
12.1	Overview . . . . .	25
12.2	Requirements . . . . .	25

12.3	Building and Running	25
12.4	Todo	25
12.5	References	25
<b>13</b>	<b>Serial Nor Flash</b>	<b>27</b>
13.1	Overview	27
13.2	Requirements	27
13.3	Building and Running	28
13.4	Todo	28
13.5	References	28
<b>14</b>	<b>sensors on the I2C bus</b>	<b>29</b>
<b>15</b>	<b>configuring I2C</b>	<b>31</b>
15.1	board level definitions	31
15.2	development trajectory	31
15.3	defining an I2C sensor	31
15.4	compiling the sample	32
<b>16</b>	<b>Bosch BMA280</b>	<b>33</b>
16.1	Overview	33
16.2	Requirements	33
16.3	Building and Running	33
16.4	Todo	33
16.5	References	34
<b>17</b>	<b>Bosch BMA421</b>	<b>35</b>
17.1	Overview	35
17.2	Requirements	35
17.3	Building and Running	36
17.4	Todo	36
17.5	References	36
<b>18</b>	<b>Touchscreen Hynitron</b>	<b>37</b>
18.1	Overview	37
18.2	Requirements	37
18.3	Building and Running	37
18.4	Todo	37
18.5	References	37
<b>19</b>	<b>Menuconfig</b>	<b>39</b>
19.1	Zephyr is like linux	39
<b>20</b>	<b>hacking the pinetime smartwatch</b>	<b>41</b>
<b>21</b>	<b>debugging the pinetime smartwatch</b>	<b>43</b>
<b>22</b>	<b>scanning the I2C_1 port</b>	<b>45</b>
22.1	Building and Running	45
<b>23</b>	<b>howto flash your zephyr image</b>	<b>47</b>
<b>24</b>	<b>howto generate pdf documents</b>	<b>49</b>
<b>25</b>	<b>About</b>	<b>51</b>
25.1	Todo	51

25.2 Fast track . . . . .	51
---------------------------	----





**Note : You may at any time read the book, store it in your ereaders**

The book itself is subject to copyright.

You cannot use the book, or parts of the book into your own publications, without the permission of the author.





---

CHAPTER

ONE

---

**AUTHOR:**

Jan Jansen [najnesnaj@yahoo.com](mailto:najnesnaj@yahoo.com)



**LICENSE:**

All the software is subject to the Apache 2.0 license (same as zephyr), which is very liberal.



## ZEPHYR FOR THE PINTIME SMARTWATCH

this document describes the installation of zephyr RTOS on the PineTime smartwatch.

<https://wiki.pine64.org/index.php/PineTime>

It should be applicable on other nordic nrf52832 based watches (Desay D6....).

the approach **in** this manual **is** to get quick results :

- minimal effort install
- **try** out the samples
- inspire you to modify **and** enhance

**suggestion :**

- install zephyr, <https://docs.zephyrproject.org>
- copy the board definition
- try some examples
- try out bluetooth
- try out the display





## INSTALL ZEPHYR

[https://docs.zephyrproject.org/latest/getting\\_started/index.html](https://docs.zephyrproject.org/latest/getting_started/index.html)

the documentation describes an installation process under Ubuntu/macOS/Windows

I picked Debian (which is not listed) . . . and soon afterwards ran into trouble

*this behaviour is known as : stubborn or stupid, but I remain convinced it could work*

But even after following the rules, I got a problem with the `dtc` (device tree compiler)

- I solved this by creating a link from the development-tools to `/usr/bin/dtc` (here you need to make sure you got a very recent one)

```
cd /root/zephyr-sdk-0.10.3/sysroots/x86_64-pokysdk-linux/usr/bin/  
mv dtc dtc-orig  
ln -s /usr/bin/dtc dtc
```

**Note :** in order to get the display `st7789` Picture-Perfect, you might need a zephyr patch

have a look at : <https://github.com/zephyrproject-rtos/zephyr/pull/20570/files> You will find them in this repo under `patches-zephyr`.





## ZEPHYR ON THE PINETIME SMARTWATCH

### 5.1 Blinky example

**Note:** I think you need to connect the 5V, just connecting the SWD cable (3.3V) is likely not enough to light up the leds

The watch does **not** contain a led **as** such, but it has background leds **for** the LCD.  
Once lit, you can barely see it, cause the screen **is** black.

```
copy the board definition for the pinetime to the zephyrproject directory
$ cp (this repo)pinetime ~/zephyrproject/zephyr/boards/arm/pinetime

replace the blinky sample with the one in this repo
$ cp (this repo)blinky ~/zephyrproject/zephyr/samples/basic
```

have a look at the pinetime.dts file, here you see the definition of the background leds.

```
gpios = <&gpio0 14 GPIO_INT_ACTIVE_LOW>;
gpios = <&gpio0 22 GPIO_INT_ACTIVE_LOW>;
gpios = <&gpio0 23 GPIO_INT_ACTIVE_LOW>;
```

*building an image, which can be found under the build directory*

```
$ west build -p -b pinetime samples/basic/blinky
```

once the compilation is completed you can upload the firmware ~/zephyrproject/zephyr/build/zephyr/zephyr.bin



## READING OUT THE BUTTON ON THE WATCH

The pinetime does have a button.  
I do **not** have a segger debugging probe.  
A way around this, it to put a value **in** memory at a fixed location.  
With openocd you can peek at this memory location.

### 6.1 Building and Running

In this repo under samples you will find an adapted basic/button program. (copy this to the samples/basic directory)

```
west build -p -b pinetime samples/basic/button
```

---

**Note:** #define MY\_REGISTER (\*(volatile uint8\_t\*)0x2000F000)

in the program you can set values: MY\_REGISTER=(read button value);

this way you know till whether the code executes

---

a way to set port 15 high (hard-coded of course :))

```
gpio_pin_configure(gpiob, 15, GPIO_DIR_OUT); //push button out  
gpio_pin_write(gpiob, 15, &button_out); //set port high
```

```
#telnet 127.0.0.1 4444
```

#### Peeking

```
once your telnet sessions started:  
Trying 127.0.0.1...  
Connected to 127.0.0.1.  
Escape character is '^]'.  
Open On-Chip Debugger  
>mdw 0x2000F000 0x1  
0x2000f000: 00000100 (switch pushed)
```

*Note::*

*The watch has a button out port (15) and buttin in port (13). You have to set the out-port high. Took me a while to figure this out...*



## BLUETOOTH (BLE) EXAMPLE

### 7.1 Eddy Stone

**Note:** compile the provided example, so a build directory gets created

```
$ west build -p -b pinetime samples/bluetooth/eddystone
```

this builds an image, which can be found under the build directory

I use linux with a bluetoothadapter 4.0. You need bluez.

```
#bluetoothctl  
[bluetooth]#scan on
```

And your Eddy Stone should be visible.

If you have a smartphone, you can download the nrf utilities app from nordic.

### 7.2 Ble Peripheral

this example is a demo of the services under bluetooth

first build the image

```
$ west build -p -b pinetime samples/bluetooth/peripheral -D CONF_FILE="prj.conf"
```

the image, can be found under the build directory, and has to be flashed to the pinetime

with linux you can have a look using bluetoothctl

```
#bluetoothctl  
[bluetooth]#scan on  
  
[NEW] Device 60:7C:9E:92:50:C1 Zephyr Peripheral Sample Long  
once you see your device  
[blueooth]#connect 60:7C:9E:92:50:C1 (the device mac address as displayed)  
  
then you can already see the services
```

same thing with the app from nordic, you could try to connect and display value of e.g. heart rate

## 7.3 using Python to read out bluetoothservices

In this repo you will find a python script : readbat.py In order to use it you need bluez on linux and the python *bluepy* module.

It can be used in conjunction with the peripheral bluetooth demo. It just reads out the battery level, and prints it.

```
import binascii
from bluepy.btle import UUID, Peripheral

temp_uuid = UUID(0x2A19)

p = Peripheral("60:7C:9E:92:50:C1", "random")

try:
    ch = p.getCharacteristics(uuid=temp_uuid)[0]
    print binascii.b2a_hex(ch.read())
finally:
    p.disconnect()
```

## ST7789 DISPLAY

### 8.1 Display example

**Note:** I think you need to connect the 5V, just connecting the SWD cable (3.3V) is likely not enough to light up the leds While connecting 5V, do not connect 3.3V

The watch has background leds **for** the LCD.

They need to be on (LOW) to visualize the display.

```
replace the display sample with the one in this repo
$ cp (this repo)st7789 ~/zephyrproject/zephyr/samples/display
```

*building an image, which can be found under the build directory*

```
$ west build -p -b pinetime samples/display/st7789v
```

once the compilation is completed you can upload the firmware ~/zephyrproject/zephyr/build/zephyr/zephyr.bin  
if all goes well, you should see some coloured squares on your screen





## LITTLEVGL BASIC SAMPLE

### 9.1 Overview

This sample application displays “Hello World” in the center of the screen and a counter at the bottom which increments every second.

LittlevGL is a free and open-source graphics library providing everything you need to create embedded GUI with easy-to-use graphical elements, beautiful visual effects and low memory footprint.

### 9.2 Requirements

definitions can be found under the boards sub-directory

- pinetime.conf
- pinetime.overlay

The program has been modified to light up the background leds. Might be unnecessary... can be found in this repo

```
Matching labels are necessary!  
pinetime.conf:CONFIG_LVGL_DISPLAY_DEV_NAME="DISPLAY"  
pinetime.overlay:          label = "DISPLAY"; (spi definition)
```

### 9.3 Building and Running

Make sure you copied the board definitions.

```
west build -p -b pinetime samples/gui/lvgl
```

modifying the font size :

west build -t menuconfig goto additional libraries / lvgl gui library (look for fonts, and adapt according to your need)

west build

### 9.4 Todo

- Create a button
- touchscreen activation (problem cause zephyr does not support this yet)

- lvgl supports `lv_canvas_rotate(canvas, &imd_dsc, angle, x, y, pivot_x, pivot_y)` should be cool for a clock, chrono...

## 9.5 References

<https://docs.littlevgl.com/en/html/index.html>

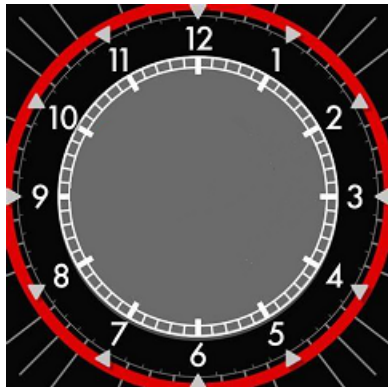
LittlevGL Web Page: <https://littlevgl.com/>

## LITTLEVGL CLOCK SAMPLE

### 10.1 Overview

This sample application displays a “clockbackground” in the center of the screen.

LittlevGL is a free and open-source graphics library providing everything you need to create embedded GUI with easy-to-use graphical elements, beautiful visual effects and low memory footprint.



### 10.2 Requirements

Make sure the prj.conf contains the following :

```
CONFIG_LVGL=y  
CONFIG_LVGL_OBJ_IMAGE=y
```

LittlevGL uses a “c” file to store the image. You need to convert a jpg, or png image to this c file. There is an online tool : <https://littlevgl.com/image-to-c-array>

### 10.3 Building and Running

copy the samples/gui/clock from this repository to the zephyr one.

```
west build -p -b pinetime samples/gui/clock
```

## 10.4 Todo

- create an internal clock (and adjustment mechanism, eg. bluetooth cts)
- lvgl supports `lv_canvas_rotate(canvas, &imd_dsc, angle, x, y, pivot_x, pivot_y)` should be cool for a clock, chrono...

## 10.5 References

<https://docs.littlevgl.com/en/html/index.html>

LittlevGL Web Page: <https://littlevgl.com/>

## PLACING A BUTTON ON THE SCREEN

### 11.1 Building and Running

In this repo under samples you will find an adapted gui/clock program. A button from the LVGL library is placed on the screen.

Later on when the touch-screen driver is ready, we'll be able to manipulate it.

Make sure that `prj.conf` file in `clock` directory contains the following:

---

**Note:** `CONFIG_LVGL_OBJ_CONTAINER=y CONFIG_LVGL_OBJ_BUTTON=y`

---

*problem* the canvas `heigh*width` eats up RAM and exceeds once `> 40`



## REAL TIME CLOCK

### 12.1 Overview

This sample application “clock” uses the RTC0 timer. It uses the counter driver.

### 12.2 Requirements

Make sure the prj.conf contains the following :

```
CONFIG_COUNTER=y
```

You need the Kconfig file, which contains :

```
config COUNTER_RTC0
    bool
    default y if SOC_FAMILY_NRF
```

### 12.3 Building and Running

copy the samples/gui/clock from this repository to the zephyr one.

```
west build -p -b pinetime samples/gui/clock
```

### 12.4 Todo

- time of day clock
- setting the time

### 12.5 References





## SERIAL NOR FLASH

```
west build -p -b pinetime samples/drivers/spi_flash -DCONF=prj.conf
```

### 13.1 Overview

This sample application should unlock the serial nor flash memory. This can be very usefull to store e.g. background for the watch.

compilation problematic ....

/root/zephyrproject/zephyr/samples/drivers/spi\_flash/src/main.c:17:22: error: 'DT\_INST\_0\_JEDEC\_SPI\_NOR\_LABEL' undeclared (first use in this function); did you mean 'DT\_INST\_0\_NORDIC\_NRF\_RTC\_LABEL'?

Turns out this is some problem with the board definition file.

I found it to be very useful to consult the generated dts file. Here you can check if everything is present.

Guess the dts-file has to be well intended.(structured)

```
vi /root/zephyrproject/zephyr/build/zephyr/include/generated/generated_dts_board.conf
```

### 13.2 Requirements

complement the pinetime.dts file with the following (under spi) #define JEDEC\_ID\_MACRONIX\_MX25L640xC22017

```
&spi0 {
    compatible = "nordic,nrf-spi";
    status = "okay";
    sck-pin = <2>;
    mosi-pin = <3>;
    miso-pin = <4>;
    cs-gpios = <&gpio0 27 0>,<&gpio0 5 0>;
    st7789v@0 {
        compatible = "sitronix,st7789v";
        label = "DISPLAY";
        spi-max-frequency = <8000000>;
        reg = <0>;
        cmd-data-gpios = <&gpio0 18 0>;
        reset-gpios = <&gpio0 26 0>;
        width = <240>;
    }
}
```

(continues on next page)

(continued from previous page)

```

height = <240>;
x-offset = <0>;
y-offset = <0>;
vcom = <0x19>;
gctrl = <0x35>;
vrhs = <0x12>;
vdvs = <0x20>;
mdac = <0x00>;
gamma = <0x01>;
colmod = <0x05>;
lcm = <0x2c>;
porch-param = [0c 0c 00 33 33];
cmd2en-param = [5a 69 02 01];
pwctrl1-param = [a4 a1];
pvgam-param = [D0 04 0D 11 13 2B 3F 54 4C 18 0D 0B 1F 23];
nvgam-param = [D0 04 0C 11 13 2C 3F 44 51 2F 1F 1F 20 23];
ram-param = [00 F0];
rgb-param = [CD 08 14];

};

mx25r64: mx25r6435f@1 {
    compatible = "jedec,spi-nor";
    reg = <1>;
    spi-max-frequency = <1000000>;
    label = "MX25R64";
    jedec-id = [0b 40 16];
    size = <67108864>;
    has-be32k;
};

```

## 13.3 Building and Running

```
west build -p -b pinetime samples/drivers/spi_flash
```

## 13.4 Todo

- detect ID memory : it is not the macronix one as suggestion on the pinetime website

I found the following : jedec-id = [0b 40 16]; (OK: can execute sample program)

- create working board definition (OK: see above)

## 13.5 References

<http://files.pine64.org/doc/datasheet/pinetime/MX25L6433F,%203V,%2064Mb,%20v1.6.pdf>

## SENSORS ON THE I2C BUS

0x18: Accelerometer: BMA423-DS000 <https://github.com/BoschSensortec/BMA423-Sensor-API>

0x44: Heart Rate Sensor: HRS3300\_Heart

0x15: Touch Controller: Hynitron CST816S Touch Controller



## CONFIGURING I2C

### 15.1 board level definitions

```
under boards/arm/pinetime are the board definitions
- pinetime.dts
- pinetime_defconfig
```

The sensors **in** the pintime use the I2C bus.

```
&i2c1 {
    compatible = "nordic,nrf-twi";
    status = "okay";
    sda-pin = <6>;
    scl-pin = <7>;

};
```

### 15.2 development trajectory

The final goal is to use the accel-sensor in the watch (BMA423), which does not exist yet. In order to minimize the effort:

- we'll use something that looks like it (ADXL372), because there exists an example.
- next we adapt it to use the existing BMA280 sensor (under drivers/sensor)
- finally we create a driver for the BMA423, based upon the BMA280

### 15.3 defining an I2C sensor

```
under samples/sensor/axl372 we create : "pinetime.overlay"
&i2c1 {
    status = "okay";
    clock-frequency = <I2C_BITRATE_STANDARD>;
    adxl372@18 {
        compatible = "adi,adxl372";
        reg = <0x18>;
        label = "ADXL372";
```

(continues on next page)

(continued from previous page)

```
        int1-gpios = <&gpio0 8 0>;
    };
};
```

**note:** this gets somehow merged with the board definition `pinetime.dts`

In the `"prj.conf"` file we define the sensor

```
CONFIG_STDOUT_CONSOLE=y
CONFIG_LOG=y
CONFIG_I2C=y
CONFIG_SENSOR=y
CONFIG_ADXL372=y
CONFIG_ADXL372_I2C=y
CONFIG_SENSOR_LOG_LEVEL_WRN=y
```

**note:** this gets somehow merged with the board definition `pinetime_defconfig`

## 15.4 compiling the sample

```
west build -p -b pinetime samples/sensor/adxl372 -DCONF=prj.conf
```

## BOSCH BMA280

```
west build -p -b pinetime samples/drivers/bma280
```

### 16.1 Overview

This sample application mimics the presence of a bosch, bma280 accel sensor. For this sensor exists a driver in zephyr, but no sample. Remember, I'm not a zephyr expert and am learning on the way.

### 16.2 Requirements

complement the pinetime.dts file with the following (under samples/sensor/bma280)

```
&i2c1 {
    bma280@18 {
        compatible = "bosch,bma280";
        reg = <0x18>;
        label = "BMA280";
        int1-gpios = <&gpio0 8 0>;
    };
};
```

Create a file: `/dts/bindings/sensor/bosch,bma280-i2c.yaml`. Which contains:

```
compatible: "bosch,bma280"
include: i2c-device.yaml
properties:
    int1-gpios:
        type: phandle-array
        required: false
```

### 16.3 Building and Running

### 16.4 Todo

- since no serial port and no J-LINK, I have to print messages to the screen (see sample gui/lvaccel)
- I adapted the BMA driver so it accepts the CHIP\_ID, further registers are subject to investigation, since no doc

## 16.5 References

BMA421 is not a part number available to the general public, and therefore all the supporting documentation and design resources are neither discussed in public forums, nor disclosed on GitHub.

CHIP\_ID=0X11 (so 423 drivers need to be adapted)



## BOSCH BMA421

this driver does not exist, so it has been created. Still work in progress ....

```
west build -p -b pinetime samples/gui/lvaccel
```

### 17.1 Overview

BMA421 is not a part number available to the general public, and therefore all the supporting documentation and design resources are neither discussed in public forums, nor disclosed on GitHub.

CHIP\_ID=0X11 (so the Bosch BMA423 drivers need to be adapted)

The Bosch documentation on the bma423 seems to apply to the bma421.

### 17.2 Requirements

for this sensor does not exist any driver, so here's what I did to create one under zephyr

#### 17.2.1 adapt CMakeLists.txt

```
~/zephyrproject-2/zephyr/drivers/sensor      add_subdirectory_ifdef(CONFIG_BMA280      bma280)
add_subdirectory_ifdef(CONFIG_BMA421 bma421)
```

#### 17.2.2 add yaml file

```
~/zephyrproject-2/zephyr/dts/bindings/sensor cp bosch,bma280-i2c.yaml bosch,bma421-i2c.yaml
```

#### 17.2.3 edit KConfig

```
source "drivers/sensor/bma280/Kconfig" source "drivers/sensor/bma421/Kconfig"
source "drivers/sensor/bmc150_magn/Kconfig"
source "drivers/sensor/bme280/Kconfig"
```

## 17.2.4 create driver

see under drivers/sensor/bma421

complement the pinetime.dts file with the following (under samples/sensor/bma280)

```
&i2c1 {
    bma421@18 {
        compatible = "bosch,bma421";
        reg = <0x18>;
        label = "BMA421";
        int1-gpios = <&gpio0 8 0>;
    };
};
```

Create a file: `/dts/bindings/sensor/bosch,bma421-i2c.yaml`. Which contains:

```
compatible: "bosch,bma421"
include: i2c-device.yaml
properties:
    int1-gpios:
        type: phandle-array
        required: false
```

## 17.3 Building and Running

## 17.4 Todo

- the driver is interrupt driven as well – need to adapt software
- the sensor has algorithm for steps – read out register
- temperature some attempt has been made, but ...

## 17.5 References

## TOUCHSCREEN HYNITRON

```
git clone https://github.com/lupyuen/hynitron_i2c_cst0xxse
```

### 18.1 Overview

this does not exist yet in zephyr, but there is work in progress <https://github.com/zephyrproject-rtos/zephyr/pull/16119>

### 18.2 Requirements

complement the pinetime.dts file with the following (under samples/sensor/bma280)

```
&i2c1 {  
    touch@18 {  
    };  
};
```

Create a file: */dts/bindings/sensor/touch.yaml*. Which contains:

```
compatible: "touch"  
include: i2c-device.yaml  
properties:  
    int1-gpios:  
        type: phandle-array  
    required: false
```

### 18.3 Building and Running

### 18.4 Todo

-create touchscreen driver -create sample

### 18.5 References



## MENUCONFIG

### 19.1 Zephyr is like linux

**Note:** to get a feel, compile a program, for example

```
west build -p -b pinetime samples/bluetooth/peripheral -D CONF_FILE="prj.conf"
```

the pinetime contains an external 32Kz crystal now you can have a look in the configuration file (and modify if needed)

```
$ west build -t menuconfig
```

```
Modules --->
Board Selection (nRF52832-MDK) --->
Board Options --->
SoC/CPU/Configuration Selection (Nordic Semiconductor nRF52 series MCU) --->
Hardware Configuration --->
ARM Options --->
Architecture (ARM architecture) --->
General Architecture Options --->
[ ] Floating point ----
General Kernel Options --->
Device Drivers ---> *****SELECT THIS ONE*****
C Library --->
Additional libraries --->
[*] Bluetooth --->
[ ] Console subsystem/support routines [EXPERIMENTAL] ----
[ ] C++ support for the application ----
System Monitoring Options --->
Debugging Options --->
[ ] Disk Interface ----
File Systems --->
-- Logging --->
Management --->
Networking --->
```

```
[ ] IEEE 802.15.4 drivers options ----
(UART_0) Device Name of UART Device for UART Console
[*] Console drivers --->
[ ] Net loopback driver ----
[*] Serial Drivers --->
Interrupt Controllers --->
Timer Drivers --->
```

(continues on next page)

(continued from previous page)

[illegible]

```
[*] NRF Clock controller support ---> <<<<<<<<<<<<<<<<<<<SELECT THIS ONE<<<<<<<<<
```

## HACKING THE PINETIME SMARTWATCH

The pinetime **is** preloaded **with** firmware.  
This firmware **is** secured, you cannot peek into it.

**Note:** The pinetime has a swd interface. To be able to write firmware, you need special hardware. I use a stm-link which is very cheap(2\$). You can also use the GPIO header of a raspberry pi. (my repo: <https://github.com/najnesnaj/openocd> is adapted for the orange pi)

To flash the software I use openocd : example for stm-link usb-stick

```
# openocd -s /usr/local/share/openocd/scripts -f interface/stlink.cfg -f target/nrf52.  
↪cfg
```

example for the orange-pi GPIO header (or raspberry)

```
# openocd -f /usr/local/share/openocd/scripts/interface/sysfsgpio-raspberrypi.cfg -c 'transport select swd'  
-f /usr/local/share/openocd/scripts/target/nrf52.cfg -c 'bindto 0.0.0.0'
```

once you started the openocd background server, you can connect to it using:

```
#telnet 127.0.0.1 4444
```

### programming

```
once your telnet sessions started:  
Trying 127.0.0.1...  
Connected to 127.0.0.1.  
Escape character is '^]'.  
Open On-Chip Debugger  
> program zephyr.bin  
  
target halted due to debug-request, current mode: Thread  
xPSR: 0x01000000 pc: 0x00001534 msp: 0x20004a10  
** Programming Started **  
auto erase enabled  
using fast async flash loader. This is currently supported  
only with ST-Link and CMSIS-DAP. If you have issues, add  
"set WORKAREASIZE 0" before sourcing nrf51.cfg/nrf52.cfg to disable it  
target halted due to breakpoint, current mode: Thread  
xPSR: 0x61000000 pc: 0x2000001e msp: 0x20004a10  
wrote 24576 bytes from file zephyr.bin in 1.703540s (14.088 KiB/s)  
** Programming Finished **
```

(continues on next page)

(continued from previous page)

```
And finally execute a reset :  
>reset
```

removing write protection see: *[howto flash your zephyr image](#)*



## DEBUGGING THE PINETIME SMARTWATCH

The pinetime does **not** have a serial port.  
I do **not** have a segger debugging probe.  
A way around this, it to put a value **in** memory at a fixed location.  
With openocd you can peek at this memory location.

---

**Note:** #define MY\_REGISTER (\*(volatile uint8\_t\*)0x2000F000)

in the program you can set values: MY\_REGISTER=1; MY\_REGISTER=8;

this way you know till where the code executes

---

```
#telnet 127.0.0.1 4444
```

programming

```
once your telnet sessions started:  
Trying 127.0.0.1...  
Connected to 127.0.0.1.  
Escape character is '^]'.  
Open On-Chip Debugger  
>mdw 0x2000F000 0x1
```

the last byte shows the value of your program trace value



## SCANNING THE I2C\_1 PORT

```
The pinetime does not have a serial port.  
I do not have a segger debugging probe.  
A way around this, it to put a value in memory at a fixed location.  
With openocd you can peek at this memory location.
```

### 22.1 Building and Running

In this repo under samples you will find an adapted i2c scanner program.

```
west build -p -b pinetime samples/drivers/i2c_scanner
```

---

**Note:** #define MY\_REGISTER (\*(volatile uint8\_t\*)0x2000F000)

in the program you can set values: MY\_REGISTER=1; MY\_REGISTER=8;

this way you know till where the code executes

---

```
#telnet 127.0.0.1 4444
```

#### Peeking

```
once your telnet sessions started:  
Trying 127.0.0.1...  
Connected to 127.0.0.1.  
Escape character is '^]'.  
Open On-Chip Debugger  
>mdw 0x2000F000 0x1  
0x2000f000: 00c24418
```

*Note::*

this corresponds to 0x18, 0x44 and 0xC2 (which is endvalue of scanner, so it does not detect touchscreen, which should be touched first...)



## HOWTO FLASH YOUR ZEPHYR IMAGE

Once you completed your `west build`, your image is located under the build directory

```
$ cd ~/zephyrproject/zephyr/build/zephyr
here you can find zephyr.bin which you can flash
```

I have an orange pi (single board computer) in my network.

I copy the image using `$scp -P 8888 zephyr.bin 192.168.0.77:/usr/src/pinetime` (secure copy using my user defined port 8888 which is normally port 22)

---

**Note:** the PineTime watch is read/write protected executing the following : `nrf52.dap apreg 1 0x0c` shows 0x0

Mind you st-link does not allow you to execute that command, you need J-link. There is a workaround using the GPIO of a raspberry pi or a OrangePi. You have to reconfigure Openocd with the `-enable-cmsis-dap` option.

Unlock the chip by executing the command: `> nrf52.dap apreg 1 0x04 0x01`

---



## HOWTO GENERATE PDF DOCUMENTS

sphinx cannot generate pdf directly, and needs latex

```
apt-get install latexmk
apt-get install texlive-fonts-recommended
apt-get install xzdec
apt-get install cmap
apt-get install texlive-latex-recommended
apt-get install texlive-latex-extra
```





## ABOUT

I got a pinetime development kit very early.

I would like to thank the folks from <https://www.pine64.org/>.

I like to hack stuff, and I like the idea behind Open Source.

The smartwatches I hacked, contained microcontrollers from Nordic Semiconductor.

A lot of resources exist for this breed.

It is an Arm based, 32bit microcontroller with a lot of flash and RAM memory.

In fact it is a small computer on your wrist, with a battery and screen, and capable of bluetooth 4+ wireless communication.

A word of warning: this **is** work **in** progress.  
You're likely to have a better skillset than me.  
You are invited to add the missing pieces **and** to improve what's already there.

## 25.1 Todo

list with suggestions:

- better graphics (lvgl using images and rotating stuff)
- NOR flash (here one can store data)
- watchdog
- DFU (update over bluetooth)
- acceleration sensor
- heart rate sensor
- fun stuff
- useless stuff, but somehow cool
- applications, e.g. calculator, cycle computer, step counter, heart attack predictor ...

## 25.2 Fast track

In this repository you can find modified directories, which you can copy to the zephyrproject directory:

- pinetime (board definition -> boards/arm)

- st7789v (example -> samples/display)
- blinky (example -> samples/basic)