

Optimisation

ACTL3143 & ACTL5111 Deep Learning for Actuaries
Patrick Laub



Lecture Outline

- **Dense Layers in Matrices**
- Optimisation
- Loss and derivatives



Logistic regression

Observations: $\mathbf{x}_{i,\bullet} \in \mathbb{R}^2$.

Target: $y_i \in \{0, 1\}$.

Predict: $\hat{y}_i = \mathbb{P}(Y_i = 1)$.

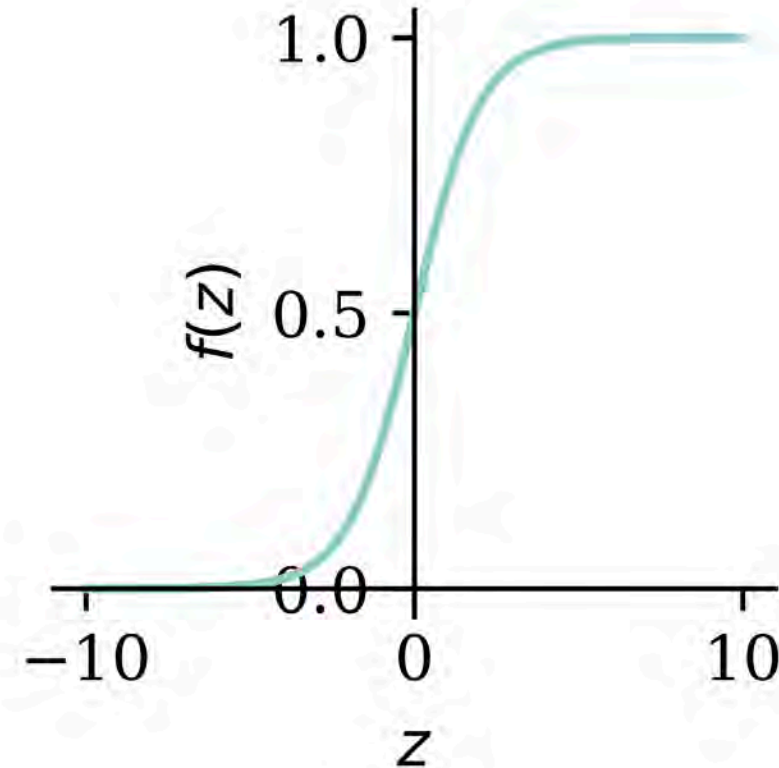
The model

For $\mathbf{x}_{i,\bullet} = (x_{i,1}, x_{i,2})$:

$$z_i = x_{i,1}w_1 + x_{i,2}w_2 + b$$

$$\hat{y}_i = \sigma(z_i) = \frac{1}{1 + e^{-z_i}}.$$

```
1 import sympy
2 sympy.plot("1/(1 + exp(-z))");
```



Multiple observations

```
1 data = pd.DataFrame({"x_1": [1, 3, 5], "x_2": [2, 4, 6], "y": [0, 1, 1]})
2 data
```

	x_1	x_2	y
0	1	2	0
1	3	4	1
2	5	6	1

Let $w_1 = 1$, $w_2 = 2$ and $b = -10$.

```
1 w_1 = 1; w_2 = 2; b = -10
2 data["x_1"] * w_1 + data["x_2"] * w_2 + b
```

```
0    -5
1     1
2     7
dtype: int64
```



Matrix notation

Have $\mathbf{X} \in \mathbb{R}^{3 \times 2}$.

```
1 X_df = data[["x_1", "x_2"]]
2 X = X_df.to_numpy()
3 X
```

```
array([[1, 2],
       [3, 4],
       [5, 6]])
```

Let $\mathbf{w} = (w_1, w_2)^\top \in \mathbb{R}^{2 \times 1}$.

```
1 w = np.array([[1], [2]])
2 w
```

```
array([[1],
       [2]])
```

$$\mathbf{z} = \mathbf{X}\mathbf{w} + b, \quad \mathbf{a} = \sigma(\mathbf{z})$$

```
1 z = X.dot(w) + b
2 z
```

```
array([[ -5],
       [  1],
       [  7]])
```

```
1 1 / (1 + np.exp(-z))
```

```
array([[0.01],
       [0.73],
       [1.   ]])
```



Using a softmax output

Observations: $\mathbf{x}_{i,\bullet} \in \mathbb{R}^2$. Predict: Target: $\mathbf{y}_{i,\bullet} \in \{(1, 0), (0, 1)\}$.
 $\hat{y}_{i,j} = \mathbb{P}(Y_i = j)$.

The model: For $\mathbf{x}_{i,\bullet} = (x_{i,1}, x_{i,2})$

$$z_{i,1} = x_{i,1}w_{1,1} + x_{i,2}w_{2,1} + b_1,$$

$$z_{i,2} = x_{i,1}w_{1,2} + x_{i,2}w_{2,2} + b_2.$$

$$\hat{y}_{i,1} = \text{Softmax}_1(\mathbf{z}_i) = \frac{e^{z_{i,1}}}{e^{z_{i,1}} + e^{z_{i,2}}},$$

$$\hat{y}_{i,2} = \text{Softmax}_2(\mathbf{z}_i) = \frac{e^{z_{i,2}}}{e^{z_{i,1}} + e^{z_{i,2}}}.$$



Multiple observations

1 data

	x_1	x_2	y_1	y_2
0	1	2	1	0
1	3	4	0	1
2	5	6	0	1

Choose:

$$w_{1,1} = 1, w_{2,1} = 2,$$

$$w_{1,2} = 3, w_{2,2} = 4, \text{ and}$$

$$b_1 = -10, b_2 = -20.$$

```
1 w_11 = 1; w_21 = 2; b_1 = -10
2 w_12 = 3; w_22 = 4; b_2 = -20
3 data["x_1"] * w_11 + data["x_2"] * w_21 + b_1
```

```
0    -5
1     1
2     7
dtype: int64
```



Matrix notation

Have $\mathbf{X} \in \mathbb{R}^{3 \times 2}$.

```
1 X
```

```
array([[1, 2],
       [3, 4],
       [5, 6]])
```

$\mathbf{W} \in \mathbb{R}^{2 \times 2}$, $\mathbf{b} \in \mathbb{R}^2$

```
1 W = np.array([[1, 3], [2, 4]])
2 b = np.array([-10, -20])
3 display(W); b
```

```
array([[1, 3],
       [2, 4]])
```

```
array([-10, -20])
```

$$\mathbf{Z} = \mathbf{XW} + \mathbf{b}, \quad \mathbf{A} = \text{Softmax}(\mathbf{Z}).$$

```
1 Z = X @ W + b
2 Z
```

```
array([[ -5,  -9],
       [  1,   5],
       [  7,  19]])
```

```
1 np.exp(Z) / np.sum(np.exp(Z),
2   axis=1, keepdims=True)
```

```
array([[9.82e-01, 1.80e-02],
       [1.80e-02, 9.82e-01],
       [6.14e-06, 1.00e+00]])
```



Lecture Outline

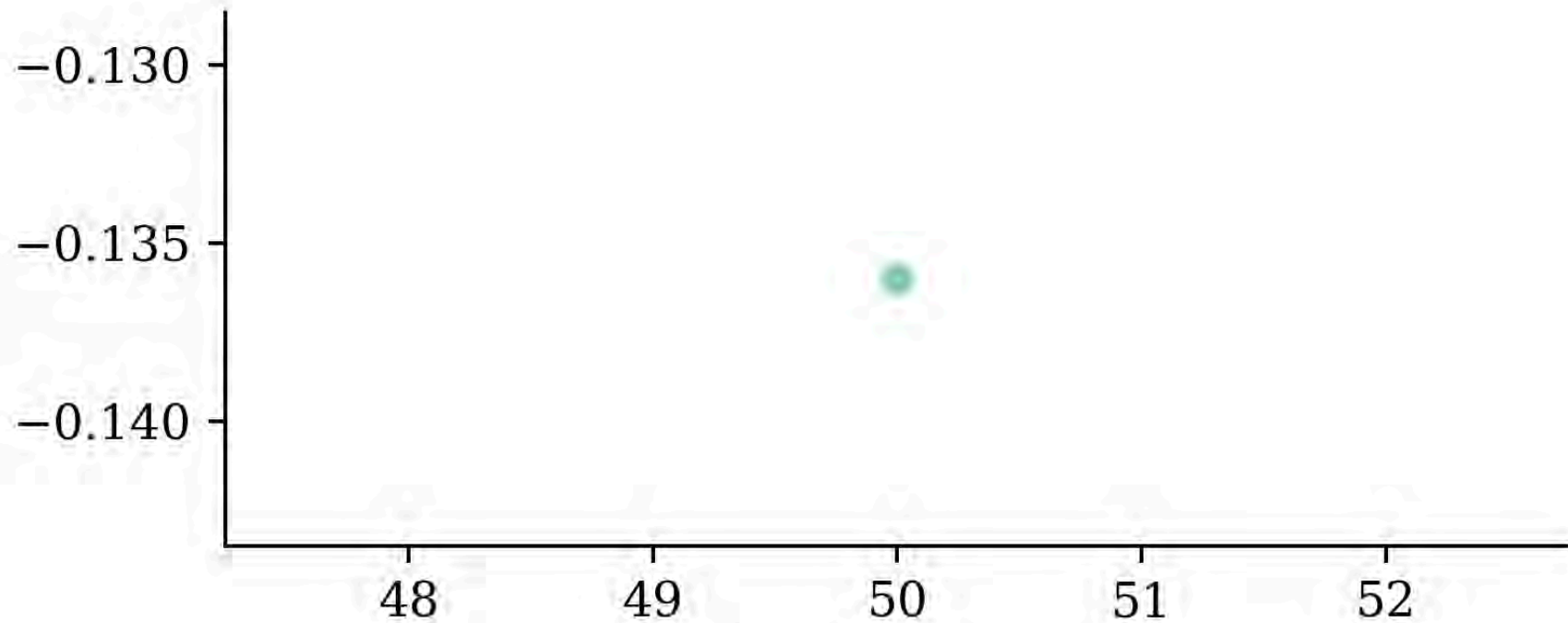
- Dense Layers in Matrices
- **Optimisation**
- Loss and derivatives



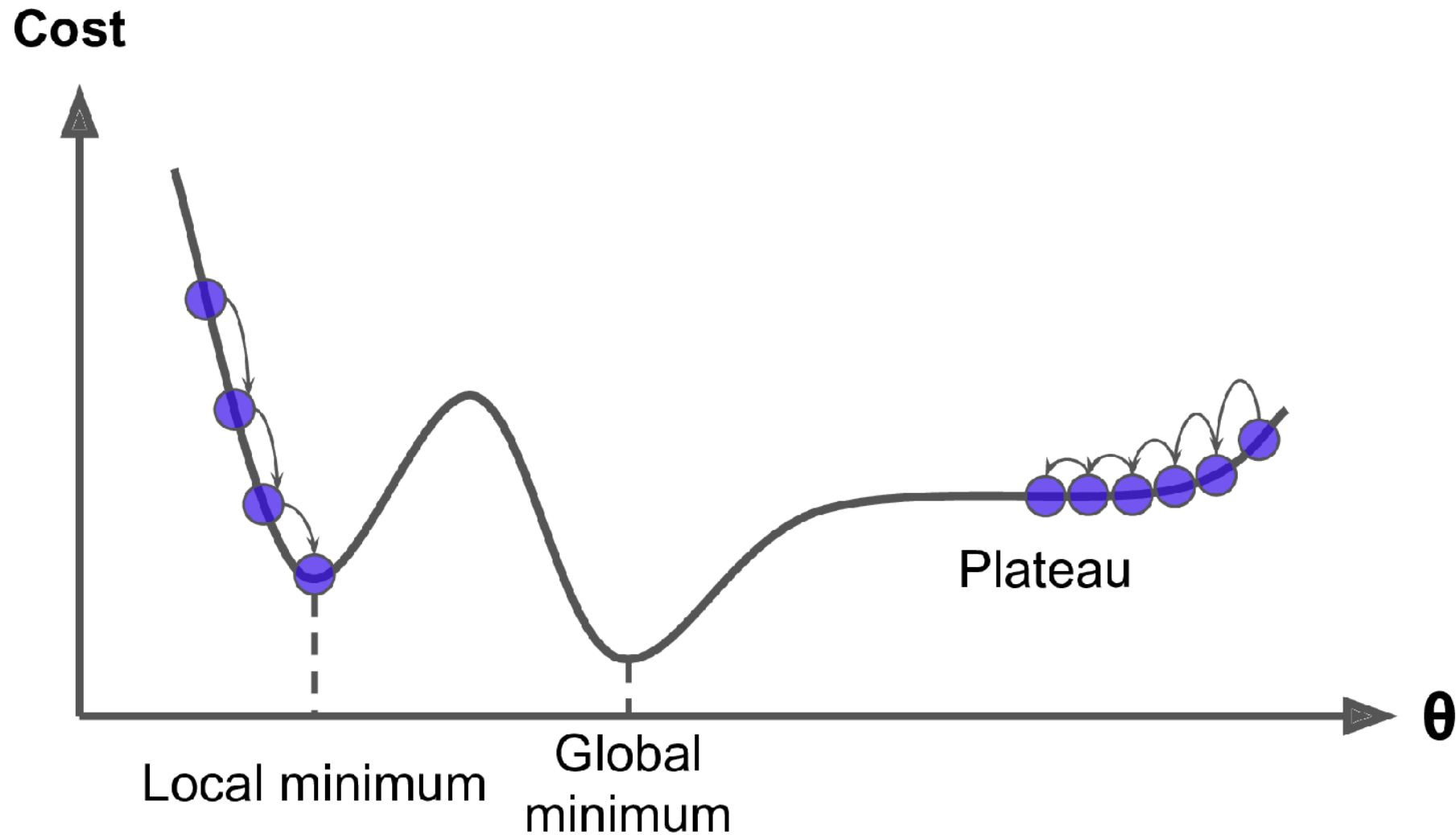
Gradient-based learning

Make a guess:  50

Show derivatives: ☐ Reveal function: ☐



Gradient descent pitfalls



Potential problems with gradient descent.

Source: Aurélien Géron (2019), *Hands-On Machine Learning with Scikit-Learn, Keras, and TensorFlow*, 2nd Edition, Figure 4-6.



Go over all the training data

Called *batch gradient descent*.

```
1 for i in range(num_epochs):  
2     gradient = evaluate_gradient(loss_function, data, weights)  
3     weights = weights - learning_rate * gradient
```



Pick a random training example

Called *stochastic gradient descent*.

```
1 for i in range(num_epochs):  
2     rnd.shuffle(data)  
3     for example in data:  
4         gradient = evaluate_gradient(loss_function, example, weights)  
5         weights = weights - learning_rate * gradient
```



Take a group of training examples

Called *mini-batch gradient descent*.

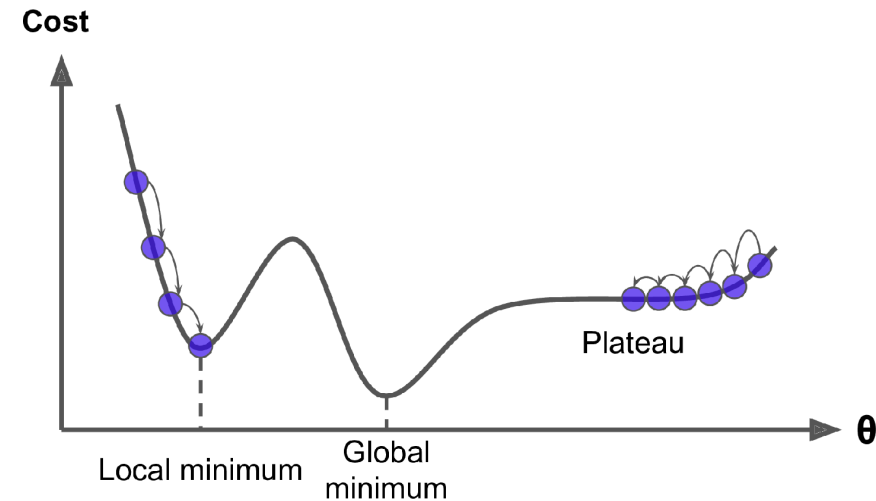
```
1 for i in range(num_epochs):  
2     rnd.shuffle(data)  
3     for b in range(num_batches):  
4         batch = data[b * batch_size : (b + 1) * batch_size]  
5         gradient = evaluate_gradient(loss_function, batch, weights)  
6         weights = weights - learning_rate * gradient
```



Mini-batch gradient descent

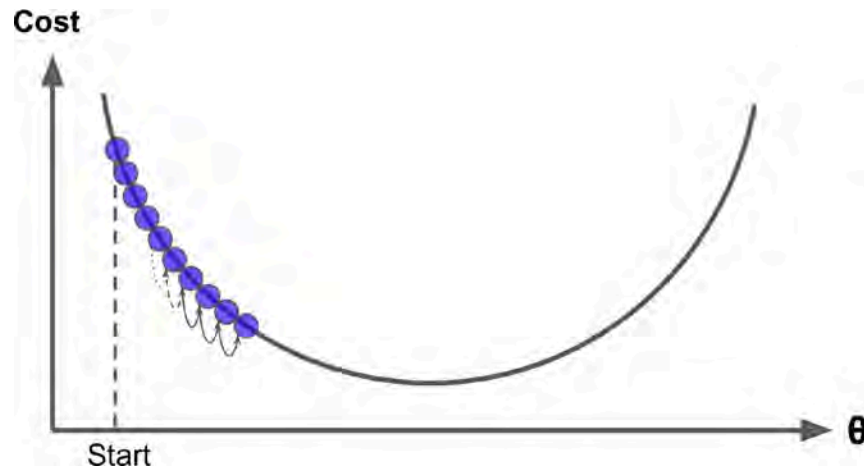
Why?

1. Because we have to (data is too big)
2. Because it is faster (lots of quick noisy steps > a few slow super accurate steps)
3. The noise helps us jump out of local minima

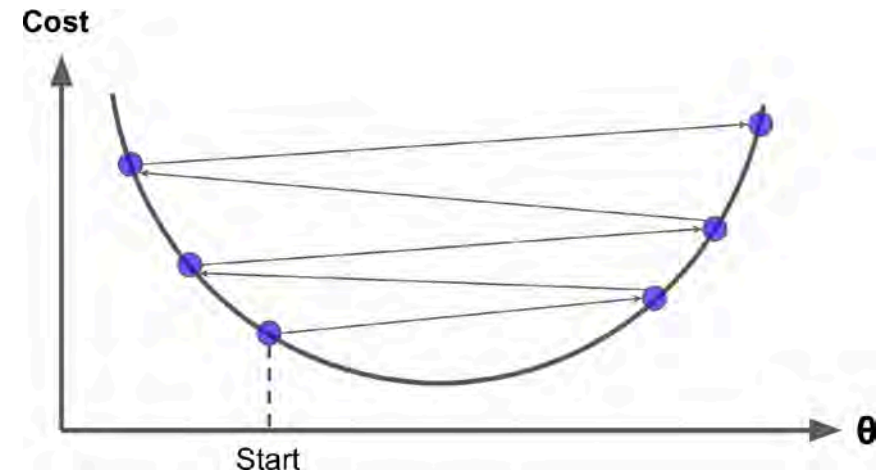


Example of jumping from local minima.

Learning rates



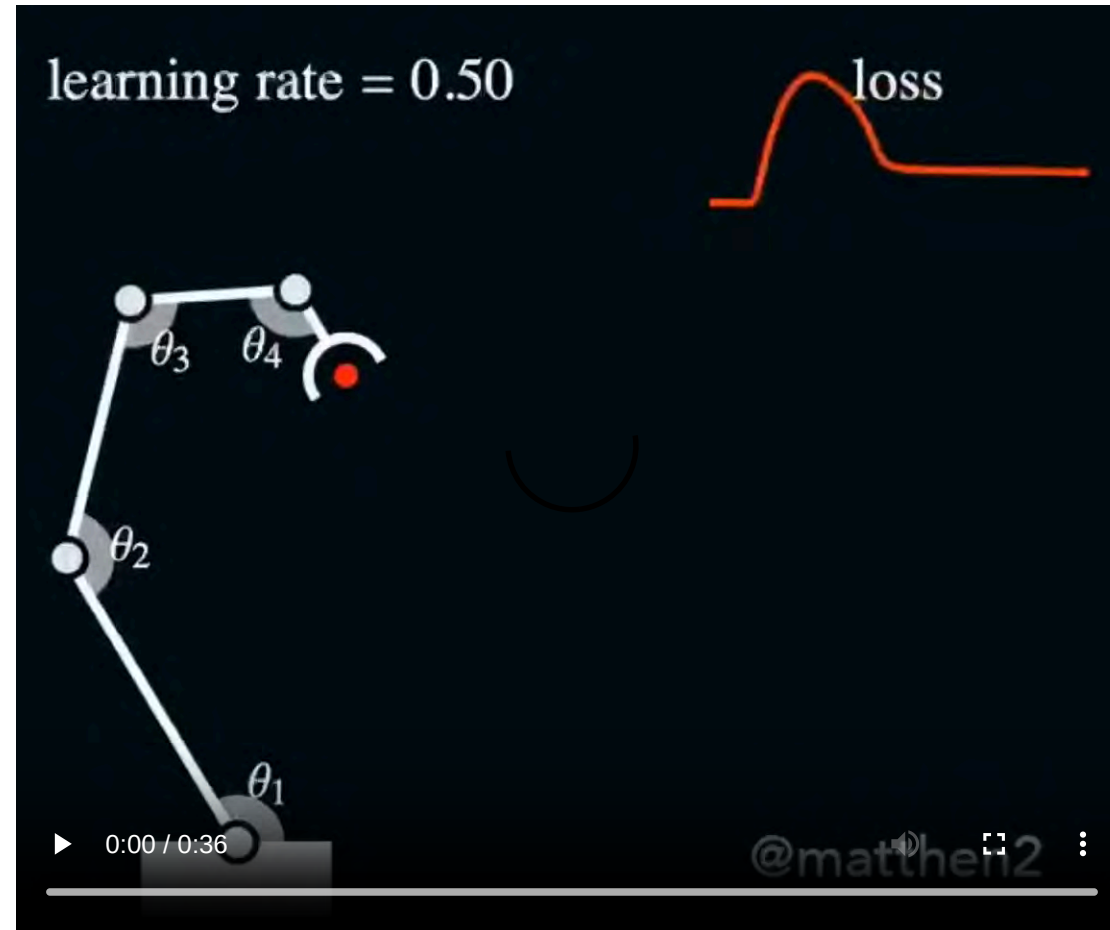
The learning rate is too small



The learning rate is too large



Learning rates #2

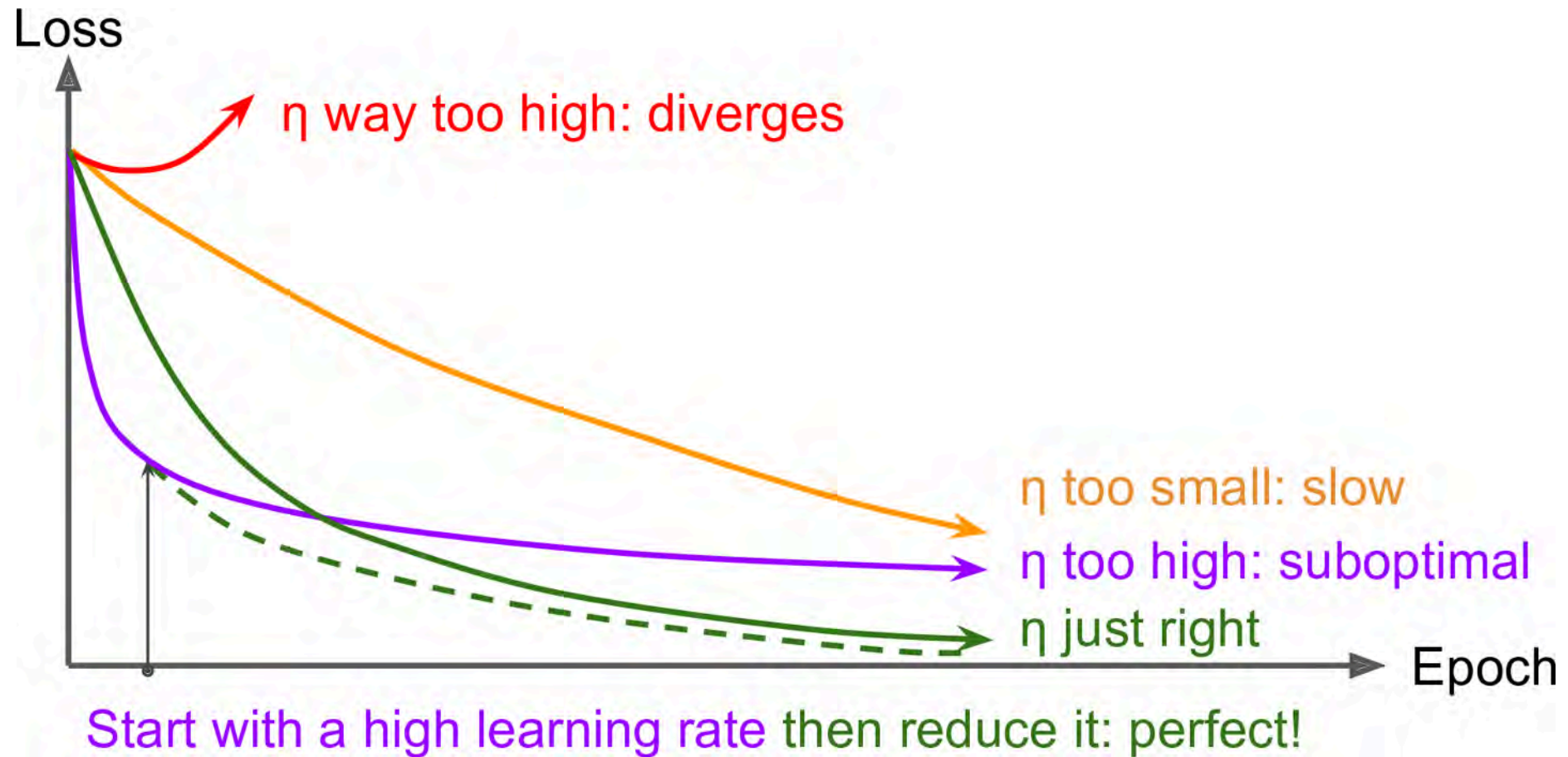


Changing the learning rates for a robot arm.

Source: Matt Henderson (2021), [Twitter post](#)



Learning rate schedule



Learning curves for various learning rates η

In training the learning rate may be tweaked manually.

We need non-zero derivatives

This is why can't use accuracy as the loss function for classification.

Also why we can have the *dead ReLU* problem.

Neural Networks Part 5: ArgMax and SoftMax



Lecture Outline

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- **Loss and derivatives**



Example: linear regression

$$\hat{y}(x) = wx + b$$

For some observation $\{x_i, y_i\}$, the (MSE) loss is

$$\text{Loss}_i = (\hat{y}(x_i) - y_i)^2$$

For a batch of the first n observations the loss is

$$\text{Loss}_{1:n} = \frac{1}{n} \sum_{i=1}^n (\hat{y}(x_i) - y_i)^2$$



Derivatives

Since $\hat{y}(x) = wx + b$,

$$\frac{\partial \hat{y}(x)}{\partial w} = x \text{ and } \frac{\partial \hat{y}(x)}{\partial b} = 1.$$

As $\text{Loss}_i = (\hat{y}(x_i) - y_i)^2$, we know

$$\frac{\partial \text{Loss}_i}{\partial \hat{y}(x_i)} = 2(\hat{y}(x_i) - y_i).$$



Chain rule

$$\frac{\partial \text{Loss}_i}{\partial \hat{y}(x_i)} = 2(\hat{y}(x_i) - y_i), \quad \frac{\partial \hat{y}(x)}{\partial w} = x, \quad \text{and} \quad \frac{\partial \hat{y}(x)}{\partial b} = 1.$$

Putting this together, we have

$$\frac{\partial \text{Loss}_i}{\partial w} = \frac{\partial \text{Loss}_i}{\partial \hat{y}(x_i)} \times \frac{\partial \hat{y}(x_i)}{\partial w} = 2(\hat{y}(x_i) - y_i) x_i$$

and

$$\frac{\partial \text{Loss}_i}{\partial b} = \frac{\partial \text{Loss}_i}{\partial \hat{y}(x_i)} \times \frac{\partial \hat{y}(x_i)}{\partial b} = 2(\hat{y}(x_i) - y_i).$$



Stochastic gradient descent (SGD)

Start with $\boldsymbol{\theta}_0 = (w, b)^\top = (0, 0)^\top$.

Randomly pick $i = 5$, say $x_i = 5$ and $y_i = 5$.



SGD, first iteration

Start with $\boldsymbol{\theta}_0 = (w, b)^\top = (0, 0)^\top$.

Randomly pick $i = 5$, say $x_i = 5$ and $y_i = 5$.

The gradient is $\nabla \text{Loss}_i = (-50, -10)^\top$.

Use learning rate $\eta = 0.01$ to update

$$\begin{aligned}\boldsymbol{\theta}_1 &= \boldsymbol{\theta}_0 - \eta \nabla \text{Loss}_i \\ &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} - 0.01 \begin{pmatrix} -50 \\ -10 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0.5 \\ 0.1 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0.1 \end{pmatrix}.\end{aligned}$$



SGD, second iteration

Start with $\theta_1 = (w, b)^\top = (0.5, 0.1)^\top$.

Randomly pick $i = 9$, say $x_i = 9$ and $y_i = 17$.

The gradient is $\nabla \text{Loss}_i = (-223.2, -24.8)^\top$.

Use learning rate $\eta = 0.01$ to update

$$\begin{aligned}\theta_2 &= \theta_1 - \eta \nabla \text{Loss}_i \\ &= \begin{pmatrix} 0.5 \\ 0.1 \end{pmatrix} - 0.01 \begin{pmatrix} -223.2 \\ -24.8 \end{pmatrix} \\ &= \begin{pmatrix} 0.5 \\ 0.1 \end{pmatrix} + \begin{pmatrix} 2.232 \\ 0.248 \end{pmatrix} = \begin{pmatrix} 2.732 \\ 0.348 \end{pmatrix}.\end{aligned}$$



Batch gradient descent (BGD)

For the first n observations $\text{Loss}_{1:n} = \frac{1}{n} \sum_{i=1}^n \text{Loss}_i$ so

$$\begin{aligned}\frac{\partial \text{Loss}_{1:n}}{\partial w} &= \frac{1}{n} \sum_{i=1}^n \frac{\partial \text{Loss}_i}{\partial w} = \frac{1}{n} \sum_{i=1}^n \frac{\partial \text{Loss}_i}{\hat{y}(x_i)} \frac{\partial \hat{y}(x_i)}{\partial w} \\ &= \frac{1}{n} \sum_{i=1}^n 2(\hat{y}(x_i) - y_i) x_i.\end{aligned}$$

$$\begin{aligned}\frac{\partial \text{Loss}_{1:n}}{\partial b} &= \frac{1}{n} \sum_{i=1}^n \frac{\partial \text{Loss}_i}{\partial b} = \frac{1}{n} \sum_{i=1}^n \frac{\partial \text{Loss}_i}{\hat{y}(x_i)} \frac{\partial \hat{y}(x_i)}{\partial b} \\ &= \frac{1}{n} \sum_{i=1}^n 2(\hat{y}(x_i) - y_i).\end{aligned}$$



BGD, first iteration ($\theta_0 = \mathbf{0}$)

	x	y	y_hat	loss	dL/dw	dL/db
0	1	0.99	0	0.98	-1.98	-1.98
1	2	3.00	0	9.02	-12.02	-6.01
2	3	5.01	0	25.15	-30.09	-10.03

So $\nabla \text{Loss}_{1:3}$ is

```
1 nabra = np.array([df["dL/dw"].mean(), df["dL/db"].mean()])
2 nabra
```

```
array([-14.69, -6.  ])
```

so with $\eta = 0.1$ then θ_1 becomes

```
1 theta_1 = theta_0 - 0.1 * nabra
2 theta_1
```

```
array([1.47, 0.6 ])
```



BGD, second iteration

	x	y	y_hat	loss	dL/dw	dL/db
0	1	0.99	2.07	1.17	2.16	2.16
1	2	3.00	3.54	0.29	2.14	1.07
2	3	5.01	5.01	0.00	-0.04	-0.01

So $\nabla \text{Loss}_{1:3}$ is

```
1 nabla = np.array([df["dL/dw"].mean(), df["dL/db"].mean()])
2 nabla
```

```
array([1.42, 1.07])
```

so with $\eta = 0.1$ then θ_2 becomes

```
1 theta_2 = theta_1 - 0.1 * nabla
2 theta_2
```

```
array([1.33, 0.49])
```



Glossary

- batches, batch size
- gradient-based learning, hill-climbing
- metrics
- stochastic (mini-batch) gradient descent

