**Module Design Document**

**For**

**WhlImbRejctn**

**Version: 7**

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**Prepared For:**

**Software Engineering**

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# Introduction

## Purpose

## Scope

# WhlImbRejctn High-Level Description

Refer to FDD

# Design details of software module

## Graphical representation of WhlImbRejctn

## Data Flow Diagram

Refer FDD

### Component level DFD

### Function level DFD

# Constant Data Dictionary

## Program (fixed) Constants

### Embedded Constants

|  |  |  |  |
| --- | --- | --- | --- |
| Constant Name | Resolution | Units | Value |
| MAXMGNMASK\_CNT\_U08 | 1 | Cnt | 1 |
| QUALMASK\_CNT\_U08 | 1 | Cnt | 2 |
| DCTRENDMASK\_CNT\_U08 | 1 | Cnt | 4 |
| FREQDIAGCMASK\_CNT\_U08 | 1 | Cnt | 8 |
| WHLSPDCORRLNMASK\_CNT\_U08 | 1 | Cnt | 16 |
| MINSTOMILLISEC\_ULS\_F32 | 1 | Cnt | 60000 |

For other constants, refer .m file.

#### Local Constants

# Software Component Implementation

## Sub-Module Functions

## Init: WhlImbRejctnInit1

## Design Rationale

Refer FDD

## Module Outputs

Refer FDD

## Per: WhlImbRejctnPer1

## Design Rationale

Refer FDD

## Store Module Inputs to Local copies

*Refer FDD*

## (Processing of function)………

*Refer FDD*

## Store Local copy of outputs into Module Outputs

*Refer FDD*

## Per: WhlImbRejctnPer2

## Design Rationale

Refer FDD

## Store Module Inputs to Local copies

*Refer FDD*

## (Processing of function)………

*Refer FDD*

## Store Local copy of outputs into Module Outputs

*Refer FDD*

## Server Runables

*None*

## Interrupt Functions

*None*

## Module Internal (Local) Functions

## Local Function #1

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | UGRFilOutp | Type | Min | | Max |
| **Arguments Passed** | Y\_Hz\_T\_f32 | float32 | -8.8 | 376.991118 | |
|  | FreqEst\_Hz\_T\_f32 | float32 | 0.005 | 60 | |
|  | PoleMag\_Uls\_T\_f32 | float32 | 0 | 1 | |
|  | \* Ugr1\_MotRadPerSec\_T\_f32 | float32 | 0 | 256 | |
|  | \* Ugr2\_MotRadPerSec\_T\_f32 | float32 | 0 | 256 | |
| **Return Value** | YFild\_Hz\_T\_f32 | float32 | 0 | 127 | |

## Description

‘UGR’ filter implementation. ‘Ugr1\_MotRadPerSec\_T\_f32’ and ‘Ugr2\_MotRadPerSec\_T\_f32’ corresponds to PIMs used in internal calculations.

## Local Function #2

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | DtrmnEnadAmnt | Type | Min | | Max |
| **Arguments Passed** | FreqEstAvg\_Hz\_T\_f32 | float32 | 0.005 | 60 | |
|  | WhlSpdLFilt\_MotRadPerSec\_T\_f32 | float32 | -100 | 100 | |
|  | WhlSpdRFilt\_MotRadPerSec\_T\_f32 | float32 | -100 | 100 | |
|  | VehSpd\_Kph\_T\_f32 | float32 | 0 | 511 | |
|  | VehSpdVld\_Cnt\_T\_logl | boolean | FALSE | TRUE | |
|  | WhlImbRejctnCustEna\_Cnt\_T\_logl | boolean | FALSE | TRUE | |
|  | WhlImbRejctnDi\_Cnt\_T\_logl | boolean | FALSE | TRUE | |
|  | SysSt\_Cnt\_T\_enum | SysSt1 | SYSST\_DI | SYSST\_WRMININ | |
|  | \*Enable\_Uls\_T\_f32 | float32 | 0 | 1 | |
| **Return Value** | WhlImbRejctnActv\_Cnt\_T\_logl | boolean | FALSE | TRUE | |

## Description

"Determine Enabled Amt" block implementation. In determination of ‘DistbnMagEnadPrev’, ‘ScaleL’ and ‘ScaleR’ values, some if-else loops were combined in software for optimization.

\*Enable\_Uls\_T\_f32 is an output of this function.

## Local Function #3

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | EnaRamp | Type | Min | | Max |
| **Arguments Passed** | EnableFac\_Uls\_T\_f32 | float32 | 0 | 1 | |
|  | SysSt\_Cnt\_T\_enum | SysSt1 | SYSST\_DI | SYSST\_WRMININ | |
| **Return Value** | RampEna\_Uls\_T\_f32 | float32 | 0 | 1 | |

## Description

"Enable Ramp" block implementation.

## Local Function #4

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | DistMag | Type | Min | | Max |
| **Arguments Passed** | WhlSpd\_MotRadPerSec\_T\_f32 | float32 | -100 | 100 | |
|  | Freq\_Hz\_T\_f32 | float32 | 0.005 | 60 | |
|  | \* PeakPrev\_Uls\_T\_f32 | float32 | 0 | 127 | |
|  | \* CurrMag\_Uls\_T\_f32 | float32 | 0 | 127 | |
|  | \*LpFilOut\_Cnt\_T\_FilLpRec1 | FilLpRec1 |  |  | |
| **Return Value** | DistMag\_Uls\_T\_f32 | float32 | 0 | 127 | |

## Description

"DistMagL/DistMagR" block implementation. ‘PeakPrev\_Uls\_T\_f32’ is a PIM used in the internal implementation.

‘LePeakPrev’ is output of this function.

## Local Function #5

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | ActvRejctnCmd | Type | Min | | Max |
| **Arguments Passed** | HwTq\_HwNwtMtr\_T\_f32 | float32 | -10 | 10 | |
|  | Enable\_Uls\_T\_f32 | float32 | 0 | 1 | |
|  | FreqEst\_Hz\_T\_f32 | float32 | 0.005 | 60 | |
|  | \* WhlImbRejctnAmp\_MtrNm\_T\_f32 | float32 | 0 | 8.8 | |
| **Return Value** | WhlImbRejctnCmd\_MotNwtMtr\_T\_f32 | float32 | -8.8 | 8.8 | |

## Description

"Active Rejection Command " block implementation. “WhlImbRejctnAmp\_MtrNm\_T\_f32” is the output of this function.

PIMs ‘StordValLe’ and ‘StordValRi’ directly used in the software for signals ‘FiltWhlSpdLScld’ and ‘FiltWhlSpdRScld’ in the FDD.

## Local Function #6

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | AdjSigFil | Type | Min | | Max |
| **Arguments Passed** | In1\_MotNwtMtr\_T\_f32 | float32 | -127 | 127 | |
|  | Zm\_Uls\_T\_f32 | float32 | 0.244742 | 1.0 | |
|  | Pk\_Uls\_T\_f32 | float32 | 0.244742 | 1.0 | |
|  | B0\_Uls\_T\_f32 | float32 | 0.249683 | 4.005074 | |
|  | MagAtFreq\_Uls\_T\_f32 | float32 | 0.414213562 | 2.414213562 | |
|  | \* Coeff1\_Uls\_T\_f32 | float32 | 0 | 127 | |
|  | \* Coeff1\_Uls\_T\_f32 | float32 | 0 | 127 | |
| **Return Value** | Out\_MotNwtMtr\_T\_f32 | float32 | -127 | 127 | |

## Description

"Filter1 / Filter2 " block implementation.

## Local Function #7

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | SetNTCBlk | Type | Min | | Max |
| **Arguments Passed** |  |  |  |  | |
|  |  |  |  |  | |
| **Return Value** | None |  |  |  | |

## Description

'Set NTC Block' implementation.

## Local Function #8

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | MaxMagDiag | Type | Min | | Max |
| **Arguments Passed** | CmdAmp\_MotNwtMtr\_T\_f32 | float32 | -8.8 | 8.8 | |
| **Return Value** | FltStat\_Cnt\_T\_lgc | boolean | FALSE | TRUE | |

## Description

"MaxMagDiag" block implementation.

## Local Function #9

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | DcTrendDiag | Type | Min | | Max |
| **Arguments Passed** | WIRCmd\_MtrNwtMtr\_T\_f32 | float32 | -8.8 | 8.8 | |
| **Return Value** | FltStat\_Cnt\_T\_lgc | boolean | FALSE | TRUE | |

## Description

" DcTrendDiag" block implementation.

## Local Function #10

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | FrequencyDiag | Type | Min | | Max |
| **Arguments Passed** | WIRCmd\_MtrNwtMtr\_T\_f32 | float32 | -8.8 | 8.8 | |
|  | FreqEst\_Hz\_T\_f32 | float32 | 0.005 | 60 | |
|  | Enable\_Uls\_T\_f32 | float32 | 0 | 1 | |
|  | CmdAmp\_MotNwtMtr\_T\_f32 | float32 | -8.8 | 8.8 | |
| **Return Value** | FltStat\_Cnt\_T\_lgc | boolean | FALSE | TRUE | |

## Description

' FrequencyDiag ' block implementation.

## Local Function #11

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | WhlSpdCorrDiag | Type | Min | | Max |
| **Arguments Passed** | WhlRiFrq\_Hz\_T\_f32 | float32 | 0.01 | 60 | |
|  | WhlLeFrq\_Hz\_T\_f32 | float32 | 0.01 | 60 | |
| **Return Value** | FltStat\_Cnt\_T\_lgc | boolean | FALSE | TRUE | |

## Description

" WhlSpdCorrDiag" block implementation.

## Local Function #12

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | ElpdTi | Type | Min | | Max |
| **Arguments Passed** | FltStsTrue\_Cnt\_T\_lgc | boolean | FALSE | TRUE | |
|  | PrevFltStsTrue\_Cnt\_T\_lgc | boolean | FALSE | TRUE | |
|  | RefTi\_Sec\_T\_u32 | uint32 | Full range | Full range | |
| **Return Value** | ElpdTi\_MilliSec\_T\_f32 | float32 | Full range | Full range | |

## Description

"Elapsed Timer" block implementation.

FltStsTrue\_Cnt\_T\_lgc - Fault condition current status

PrevFltStsTrue\_Cnt\_T\_lgc - Fault condition previous status (PIM)

RefTi\_Sec\_T\_u32 - Reference Timer (PIM)

## Local Function #13

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | FltRcvry | Type | Min | | Max |
| **Arguments Passed** | ElpdTi\_Sec\_T\_f32 | float32 | Full range | Full range | |
|  | FltRecDly\_Mins\_T\_f32 | float32 | 0 | 255 | |
|  | \* FltRec\_Uls\_T\_str | PassFailCntrDiagcRec1 | Structure members –full range | Structure members –full range | |
| **Return Value** | None |  |  |  | |

## Description

"Flt Recovery" block implementation. Elapsed time is passed as argument

## Local Function #14

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Function Name** | ChkCompPersc | Type | Min | | Max |
| **Arguments Passed** | ActiveBand1Inp\_Cnt\_T\_u32 | uint32 | 0 | 4.294967294e+09 | |
|  | ActiveBand2Inp\_Cnt\_T\_u32 | uint32 | 0 | 4.294967294e+09 | |
|  | ActiveBand3Inp\_Cnt\_T\_u32 | uint32 | 0 | 4.294967294e+09 | |
| **Return Value** | Flt\_Cnt\_T\_lgc | boolean | FALSE | TRUE | |

## Description

“CheckCompPersistence” block implementation.

## GLOBAL Function/Macro Definitions

None

# Known Limitations with Design

1. The Inter runnable variable 'IniCmpFlt' is written in Init1 and read in Per1. The DD dictionary has a discrepancy where it mentions written in Per2 and read in Per1. The implementation/code has already been updated to the current read write combination. The design needs to be updated for the same. Refer to CR EA4#7979.

2. Constant DURATIONDISABLE\_CNT\_U16 value needs to be changed to a value less than max of the data type.  Implementation is using 18500 to match the EA3 component based on agreement with FDD Owner. Refer to CR EA4#7979

3. The Inter runnable Variable ‘MaxMgnFlt’ is written in Per2 and Read in Per1. The DataDict.m has a discrepancy where it mentions written in Init1 and read in Per1. The implementation/code has already been updated to the current read write combination. The design needs to be updated for the same. Refer to CR EA4#7979.

# UNIT TEST CONSIDERATION

None

Abbreviations and Acronyms

| **Abbreviation or Acronym** | **Description** |
| --- | --- |
|  |  |
|  |  |

Glossary

**Note**: Terms and definitions from the source “Nexteer Automotive” take precedence over all other definitions of the same term. Terms and definitions from the source “Nexteer Automotive” are formulated from multiple sources, including the following:

* ISO 9000
* ISO/IEC 12207
* ISO/IEC 15504
* Automotive SPICE® Process Reference Model (PRM)
* Automotive SPICE® Process Assessment Model (PAM)
* ISO/IEC 15288
* ISO 26262
* IEEE Standards
* SWEBOK
* PMBOK
* Existing Nexteer Automotive documentation

| **Term** | **Definition** | **Source** |
| --- | --- | --- |
| MDD | Module Design Document |  |
| DFD | Data Flow Diagram |  |

References

| **Ref. #** | **Title** | **Version** |
| --- | --- | --- |
| 1 | AUTOSAR Specification of Memory Mapping (Link:[AUTOSAR\_SWS\_MemoryMapping.pdf](http://www.autosar.org/download/R4.0/AUTOSAR_SWS_MemoryMapping.pdf)) | v1.3.0 R4.0 Rev 2 |
| 2 | MDD Guideline | EA4 01.00.01 |
| 3 | [Software Naming Conventions.doc](http://misagweb01.nexteer.com/eRoomReq/Files/erooms8/NextGeneration/0_fc55f/Software%20Naming%20Conventions%2003x(In%20Work).doc) | 2.0 |
| 4 | [Software Design and Coding Standards.doc](http://eroom1.nexteer.com/eRoomReq/Files/erooms8/NextGeneration/0_1a67a9/Software%20Design%20and%20Coding%20Standards.doc) | 2.1 |
| 5 | FDD : SF015A\_WhlImbRejctn\_Design | See Synergy sub project version |