

BAYESIAN LEARNING - LECTURE 1

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COURSE OVERVIEW

- ▶ Four **modules** with:
 - ▶ Lectures
 - ▶ Exercises
 - ▶ Labs
- ▶ Modules:
 - ▶ The basics, single- and multiparameter models
 - ▶ Regression models
 - ▶ Tackling more advanced models with MCMC
 - ▶ Model Inference
- ▶ **Examination**
 - ▶ Lab reports, 2 credits
 - ▶ Bayesian project report, 4 credits
 - ▶ Oral exam (for some students)
- ▶ **Bayesian project report**
 - ▶ Individual
 - ▶ Perform a Bayesian analysis on real data.
 - ▶ **Deadline December 21, 2014.**

LECTURE OVERVIEW

- ▶ The likelihood function
- ▶ Bayesian inference
- ▶ The Bernoulli model

THE LIKELIHOOD FUNCTION

- ▶ Bernoulli trials:

$$x_1, \dots, x_n | \theta \stackrel{iid}{\sim} \text{Bern}(\theta).$$

- ▶ Likelihood:

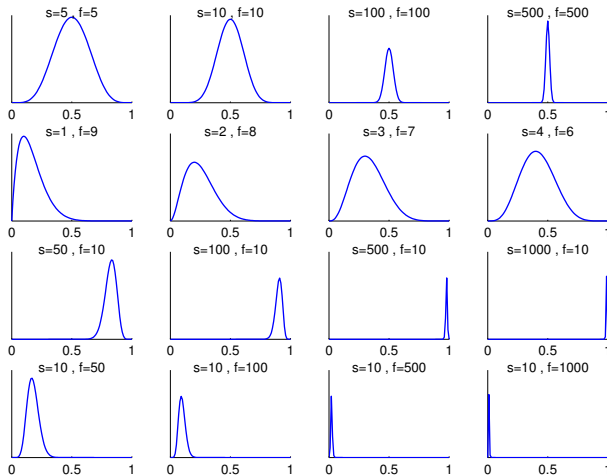
$$\begin{aligned} p(x_1, \dots, x_n | \theta) &= p(x_1 | \theta) \cdots p(x_n | \theta) \\ &= \theta^s (1 - \theta)^f, \end{aligned}$$

where $s = \sum_{i=1}^n x_i$ is the number of successes in the Bernoulli trials and $f = n - s$ is the number of failures.

- ▶ Given the data x_1, \dots, x_n , we may plot $p(x_1, \dots, x_n | \theta)$ as a function of θ .
- ▶ Two different roles played by $p(x_1, \dots, x_n | \theta)$:
 - ▶ **a function of the data**, x_1, \dots, x_n , for a *fixed* θ , it is a **probability distribution** for the data. Here the *data are random* and θ is fixed.
 - ▶ **a deterministic function of** θ for a **fixed data** sample. The **likelihood function**.

THE LIKELIHOOD FUNCTION FROM BERNOULLI TRIALS

Likelihood function of the Bernoulli model for different data



LIKELIHOOD

- ▶ Two different roles played by $p(x_1, \dots, x_n | \theta)$:
 - ▶ **a function of the data**, x_1, \dots, x_n , for a *fixed* θ , it is a **probability distribution** for the data. Here the *data are random* and θ is fixed.
 - ▶ **a deterministic function of θ** for a **fixed data** sample. The **likelihood function**.
- ▶ The **likelihood principle**: Two experiments E_1 and E_2 that give rise to proportional likelihoods, i.e. $L_1(\theta) = c \cdot L_2(\theta)$ for all θ and some constant $c > 0$, should provide the same information about θ .
- ▶ Many frequentist methods violate the likelihood principle.

OBSERVED INFORMATION

- ▶ The curvature of the likelihood is a measure of the informativeness (precision) of the data.
- ▶ The **observed information**

$$J_{\theta, \mathbf{x}} = - \frac{\partial^2 \ln L(\theta; \mathbf{x})}{\partial \theta^2}$$

- ▶ Asymptotic approximation of the likelihood function

$$N \left(\hat{\theta}, J_{\hat{\theta}, \mathbf{x}}^{-1} \right),$$

where $\hat{\theta}$ is the Maximum Likelihood Estimate (MLE) of θ .

- ▶ The normality can be proved heuristically by a second order Taylor expansion of the log-likelihood function.
- ▶ Example: Bernoulli data

$$J_{\hat{\theta}, \mathbf{x}} = - \left. \frac{\partial^2 \ln L(\theta; \mathbf{x})}{\partial \theta^2} \right|_{\theta=\hat{\theta}} = \frac{s}{\hat{\theta}^2} + \frac{f}{(1 - \hat{\theta})^2} = \frac{n}{\hat{\theta}(1 - \hat{\theta})}.$$

FISHER INFORMATION

- **Fisher information**

$$I_{\theta} = E_{\mathbf{x}|\theta} (J_{\theta, \mathbf{x}}) ,$$

where the expectation is with respect to the data distribution.

- The Fisher information is the information that can be **expected** before the data is observed.
- The **asymptotic distribution of the MLE**

$$\hat{\theta}|\theta \overset{approx}{\sim} N \left(\theta, \frac{1}{I_{\theta}} \right) .$$

- Example: Bernoulli data

$$I_{\theta} = \frac{E(s)}{\theta^2} + \frac{E(f)}{(1-\theta)^2} = \frac{n}{\theta(1-\theta)} .$$

UNCERTAINTY AND SUBJECTIVE PROBABILITY

- ▶ The likelihood function does **not** tell us the probability of different values of θ .
- ▶ In order to talk about θ in probabilistic terms we clearly must regard θ as random. But θ may be something that we know is non-random, e.g. a fixed natural constant.
- ▶ **Bayesian: doesn't matter if θ is fixed or random.** What matters is whether or not You know the value of θ . If θ is uncertainty to You, then You can assign a probability distribution to θ which reflects Your knowledge about θ . **Subjective probability.**
- ▶ Different types of prior information
 - ▶ Real **expert information**. Combo of previous studies and experience.
 - ▶ Vague prior information, or even **noninformative priors**.
 - ▶ **Reporting priors**
 - ▶ **Smoothness priors**. Regularization. Shrinkage. Big thing in modern statistics/machine learning.

LEARNING FROM DATA - BAYES' THEOREM

- ▶ Given a distribution for θ , $p(\theta)$, how can we learn from data?
- ▶ How do we make the transition from $p(\theta) \rightarrow p(\theta|Data)$?
- ▶ One form of **Bayes' theorem** reads (A and B are events)

$$p(A|B) = \frac{p(B|A)p(A)}{p(B)}.$$

So that Bayes' theorem 'reverses the conditioning', i.e. takes us from $p(B|A)$ to $p(A|B)$.

- ▶ Let $A = \theta$ and $B = Data$

$$p(\theta|Data) = \frac{p(Data|\theta)p(\theta)}{p(Data)}.$$

- ▶ Interpreting the likelihood function as a probability density for θ is just as wrong as ignoring the factor $p(A)/p(B)$ in Bayes' theorem.

BAYES' THEOREM - MEDICAL DIAGNOSIS

- ▶ $A = \{\text{Horrible and very rare disease}\}$, $B = \{\text{Positive medical test}\}$.
- ▶ $p(B|A) = 0.9$
- ▶ $p(B|A^c) = 0.05$
- ▶ $p(A) = 0.0001$
- ▶ Probability of being sick given a positive test:

$$\begin{aligned} p(A|B) &= \frac{p(B|A)p(A)}{p(B)} = \frac{p(B|A)p(A)}{p(B|A)p(A) + p(B|A^c)p(A^c)} \\ &= \frac{0.9 \cdot 0.0001}{0.9 \cdot 0.0001 + 0.05 \cdot (1 - 0.0001)} \approx 0.001797. \end{aligned}$$

- ▶ Very improbable that you are sick, but nearly 18 times more probable than before taking the test.
- ▶ Morale of the story: If you want $p(A|B)$ then $p(B|A)$ does not tell the whole story. The prior probability $p(A)$ is also very important.

GENERALIZED BAYES' THEOREM

- ▶ From your basic statistics textbook:

$$p(A_i|B) = \frac{p(B|A_i)p(A_i)}{p(B)} = \frac{p(B|A_i)p(A_i)}{\sum_{i=1}^k p(B|A_i)p(A_i)}.$$

- ▶ Let $\theta_1, \dots, \theta_k$ be k different values on a parameter θ . Bayes' Theorem:

$$p(\theta_i|Data) = \frac{p(Data|\theta_i)p(\theta_i)}{p(Data)} = \frac{p(Data|\theta_i)p(\theta_i)}{\sum_{i=1}^k p(Data|\theta_i)p(\theta_i)}.$$

- ▶ If θ takes on a continuum of values

$$p(\theta|Data) = \frac{p(Data|\theta)p(\theta)}{\int_{\theta} p(Data|\theta)p(\theta)d\theta}.$$

THE NORMALIZING CONSTANT IS NOT IMPORTANT

- ▶ $p(Data)$ in Bayes' theorem is just a constant that makes $p(\theta|Data)$ integrate to one. Example: $x \sim N(\mu, \sigma^2)$

$$p(x) = (2\pi\sigma^2)^{-1/2} \exp \left[-\frac{1}{2\sigma^2} (x - \mu)^2 \right].$$

- ▶ We may write

$$p(x) \propto \exp \left[-\frac{1}{2\sigma^2} (x - \mu)^2 \right].$$

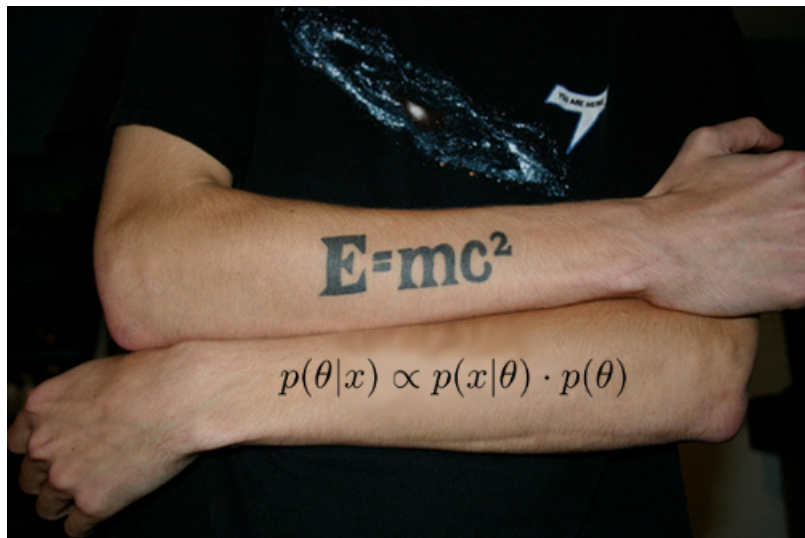
- ▶ Short form of Bayes' theorem

$$p(\theta|Data) \propto p(Data|\theta)p(\theta)$$

or

$$\text{Posterior} \propto \text{Likelihood} \cdot \text{Prior}$$

A GREAT THEORY MAKES A GREAT TATTOO



BAYESIAN LEARNING

- ▶ Suppose: you already have x_1, x_2, \dots, x_n data points, and the corresponding posterior $p(\theta|x_1, \dots, x_n)$
- ▶ Now, a fresh additional data point x_{n+1} arrives.
- ▶ The posterior based on all available data is

$$p(\theta|x_1, \dots, x_{n+1}) \propto p(x_{n+1}|\theta, x_1, \dots, x_n)p(\theta|x_1, \dots, x_n).$$

- ▶ The following are therefore equivalent:
 - ▶ Analyzing the likelihood of all data x_1, \dots, x_{n+1} with the prior based on no data $p(\theta)$
 - ▶ Analyzing the likelihood of the fresh data point x_{n+1} with the 'prior' equal to the posterior based on the old data $p(\theta|x_1, \dots, x_n)$.
- ▶ **Yesterday's posterior is today's prior.**

BERNOULLI TRIALS - BETA PRIOR

► Model

$$x_1, \dots, x_n | \theta \stackrel{iid}{\sim} \text{Bern}(\theta)$$

► Prior

$$\theta \sim \text{Beta}(\alpha, \beta)$$

$$p(y) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} y^{\alpha-1} (1-y)^{\beta-1} \quad \text{for } 0 \leq y \leq 1.$$

► Posterior

$$\begin{aligned} p(\theta | x_1, \dots, x_n) &\propto p(x_1, \dots, x_n | \theta) p(\theta) \\ &\propto \theta^s (1-\theta)^f \theta^{\alpha-1} (1-\theta)^{\beta-1} \\ &= \theta^{s+\alpha-1} (1-\theta)^{f+\beta-1}. \end{aligned}$$

- But this is recognized as proportional to the $\text{Beta}(\alpha + s, \beta + f)$ density. That is, the **prior-to-posterior** mapping reads

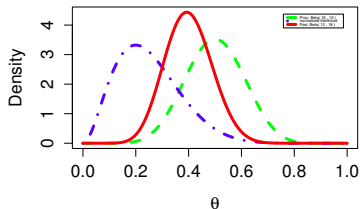
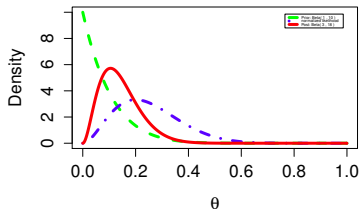
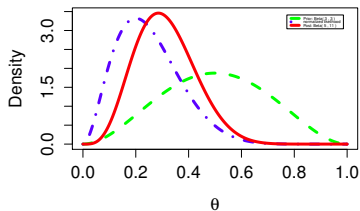
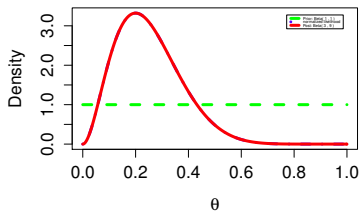
$$\theta \sim \text{Beta}(\alpha, \beta) \xrightarrow{x_1, \dots, x_n} \theta | x_1, \dots, x_n \sim \text{Beta}(\alpha + s, \beta + f).$$

BERNOULLI EXAMPLE: SPAM EMAILS

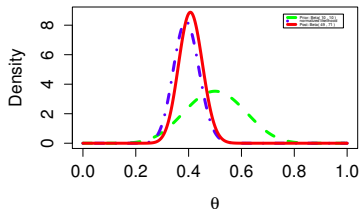
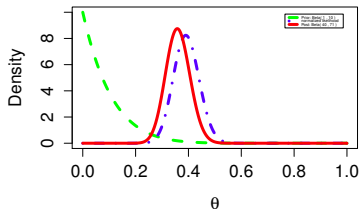
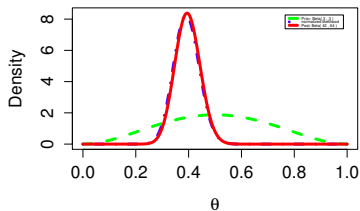
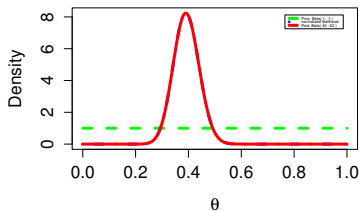
- ▶ George has gone through his collection of 4601 e-mails. He classified 1813 of them to be spam.
- ▶ Let $x_i = 1$ if i :th email is spam. Assume $x_i|\theta \stackrel{iid}{\sim} \text{Bernoulli}(\theta)$ and $\theta \sim \text{Beta}(\alpha, \beta)$.
- ▶ Posterior

$$\theta|x \sim \text{Beta}(\alpha + 1813, \beta + 2788)$$

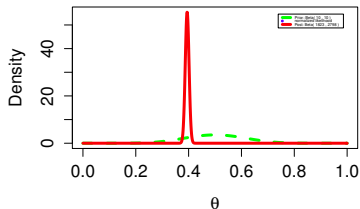
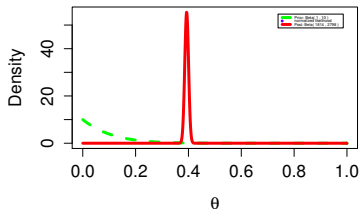
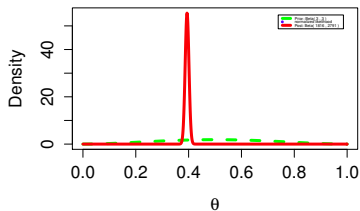
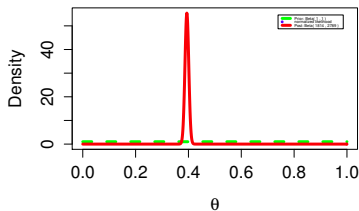
SPAM DATA (N=10): PRIOR SENSITIVITY



SPAM DATA (N=100): PRIOR SENSITIVITY



SPAM DATA (N=4601): PRIOR SENSITIVITY



SPAM DATA: POSTERIOR CONVERGENCE

