

$$p(\Theta|D) = \frac{p(D|\Theta)p(\Theta)}{p(D|\Theta)p(\Theta) + p(D|\neg\Theta)p(\neg\Theta)}$$

## Bayesian Learning 732A46: Lecture 3

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April 2016

- ▶ Multiparameter models - direct simulation and marginalization.
- ▶ Normal model with unknown variance
- ▶ Multinomial model
- ▶ Multivariate normal with known covariance matrix

- ▶ Once  $p(\theta|y)$  is derived we use it for **posterior analysis**.
- ▶ **Direct**: *known distribution* - **Example**: Normal, Beta, Gamma.
- ▶ **Examples** [ $\theta \sim p(\theta|y)$  continuous. Replace  $\int$  by  $\sum$  for discrete  $\theta$ ]

**Expectation**:  $E(\theta) = \int \theta p(\theta|y) d\theta$

**Variance**:  $V(\theta) = \int (\theta - E(\theta))^2 p(\theta|y) d\theta$

**Probabilities**:  $\Pr(\theta \in A) = \int_A p(\theta|y) d\theta$ .

E.g. if  $A = \{\theta; \theta \in [0, \infty)\}$  then  $\Pr(\theta \leq 2) = \int_0^2 p(\theta|y) d\theta$ .

- ▶ **Note**: the function of interest is **averaged over the posterior uncertainty** of the parameters.

# Direct simulation, cont.

- Nothing but expectations of a function  $h(\theta)$ , i.e.

$$E[h(\theta)] = \int h(\theta)p(\theta|y)d\theta.$$

- **Expectation**:  $E(\theta) = \int \theta p(\theta|y)d\theta$ .  $h(\theta) = \theta$ .

**Variance** :  $V(\theta) = \int (\theta - E(\theta))^2 p(\theta|y)d\theta$ .  $h(\theta) = (\theta - E(\theta))^2$ .

**Probabilities**:  $\Pr(\theta \in A) = \int_A p(\theta|y)d\theta = \int \mathbb{1}_A(\theta)p(\theta|y)d\theta$ .  $h(\theta) = \mathbb{1}_A(\theta)$ ,

$$\mathbb{1}_A(\theta) = \begin{cases} 1, & \text{if } \theta \in A, \\ 0, & \text{if } \theta \notin A, \end{cases}$$

- For **complicated**  $h(\theta)$  analytical integration is hard/**impossible**.
- By **simulation** using  $N$  draws  $\theta^{(i)}$ :

$$E[h(\theta)] \approx \frac{1}{N} \sum_{i=1}^N h(\theta^{(i)}) \quad \text{with} \quad \theta^{(i)} \sim p(\theta|y)$$

# Direct simulation, cont.

- ▶ **Expectation**:  $E(\theta) \approx \frac{1}{N} \sum_{i=1}^N \theta^{(i)}$ .
- ▶ **Variance** :  $V(\theta) \approx \frac{1}{N} \sum_{i=1}^N (\theta^{(i)} - \bar{\theta})^2$ .
- ▶ **Probabilities**:  $\Pr(\theta \in A) \approx \frac{\{\#\theta^{(i)} \in A\}}{N}$
- ▶ Want the **posterior distribution** of  $\phi = h(\theta)$ , i.e.  $p(\phi|y)$ ?
- ▶ **Histogram** (or **Kernel density estimate**) of  $h(\theta^{(i)})$  is an approximation.
- ▶ Posterior analysis by *direct simulation* is **easy**...
- ▶ ... the **difficult** part is to make *direct simulation* **possible**.
- ▶ **Note**: *Direct simulation* **requires** that you can **analytically derive** what you "directly simulate"!

# Multiparameter models

## ► Examples

1. Normal model with **both**  $\mu$  and  $\sigma^2$  unknown.
2. Multiple regression models  $(\beta_1, \dots, \beta_p)$ .

## ► Five **invaluable techniques** when working with multiparameters. Generalize easily to $p > 2$ parameters (**try it at home!**)

### ► **Invaluable technique #1:** Simulation in multiparameter models

- $p(\theta_1, \theta_2 | y)$  - **impossible** with direct simulation
- $p(\theta_1, \theta_2 | y) = p(\theta_1 | \theta_2, y) p(\theta_2 | y)$  - Each piece **possible** with direct simulation

### ► **Invaluable technique #2:** How to derive $p(\theta_1 | \theta_2, y)$ analytically?

- Note that  $\theta_2$  is **treated as a constant** here!

$$p(\theta_1 | \theta_2, y) = \frac{p(\theta_1, \theta_2 | y)}{p(\theta_2 | y)} \propto p(\theta_1, \theta_2 | y) \propto p(y | \theta_1, \theta_2) p(\theta_1, \theta_2).$$

- The joy of **ignoring a normalizing constant** applies also for  $\theta_2$ .

- ▶ **Invaluable technique** #3: How to derive  $p(\theta_2|y)$  analytically?
  - ▶  $p(\theta_2|y) = \int p(\theta_1, \theta_2|y) d\theta_1$  - **can make you cry**
  - ▶ **Much** easier to use

$$p(\theta_2|y) = \frac{p(\theta_1, \theta_2|y)}{p(\theta_1|\theta_2, y)} \propto \frac{p(y|\theta_1, \theta_2)p(\theta_1, \theta_2)}{p(\theta_1|\theta_2, y)} \quad (1)$$

**Standard trick:**

**LHS** of (1) **does not depend** on  $\theta_1$  ( $\implies$  must cancel on **RHS**). Insert a  $\theta_1$  that simplifies (1).

- ▶ Note: Analytical derivations are **not always** possible!

## Multiparameter models, cont.

- ▶ **Invaluable technique** #4: Are some of your parameters **nuisance** (not of direct interest)? **Example:** I only care about  $\theta_1$  ( $\theta_2$  nuisance).

- ▶ Computing

$$p(\theta_1|y) = \int p(\theta_1, \theta_2|y) d\theta_2 = \int p(\theta_1|\theta_2, y) p(\theta_2|y) d\theta_2$$

**analytically can make you cry...**

- ▶ ... but computing it by simulation can **can make you smile**

$$\begin{aligned}\theta_2^{(i)} &\sim p(\theta_2|y) \\ \theta_1^{(i)}|\theta_2^{(i)} &\sim p(\theta_1|\theta_2^{(i)}, y)\end{aligned}$$

- ▶ **Histogram** (or **Kernel density estimate**) of  $\theta_1^{(i)}$  is an approximation of  $p(\theta_1|y)$ .
  - ▶ This is **marginalization by simulation**.
- ▶ **Invaluable technique** #5: Interested in **nasty integrals**, e.g.

$$\Pr(\theta_1 > \theta_2|y) = \int \int_{\theta_1 > \theta_2} p(\theta_1, \theta_2|y) d\theta_1 d\theta_2?$$

Remember **the joy** of simulating!



# Normal model with unknown variance - Uniform prior

- ▶ **Model**

$$y_1, \dots, y_n \stackrel{iid}{\sim} N(\theta, \sigma^2)$$

- ▶ **'Non-informative' Prior**

$$p(\theta, \sigma^2) \propto (\sigma^2)^{-1} \quad [\text{uniform in } p(\theta, \log(\sigma^2)) \propto c]$$

- ▶ **Posterior.** Decompose using technique #1,

$$\theta | \sigma^2, y \sim N\left(\bar{y}, \frac{\sigma^2}{n}\right) \tag{2}$$

$$\sigma^2 | y \sim \text{Inv-}\chi^2(\nu_n, s_n^2) \quad , \tag{3}$$

where

$$\nu_n = n - 1 \quad \text{and} \quad s_n^2 = \frac{\sum_{i=1}^n (y_i - \bar{y})^2}{n - 1}$$

is the usual sample variance.

- ▶ (2) - derived in **Lecture 1**. Uses technique #2.

- ▶ (3) - **White board**. Uses technique #3.

# Normal model with unknown variance - Uniform prior, cont.

- ▶  $\sigma_n^2 \sim \text{Inv-}\chi^2(\nu_n, s_n^2)$  if

$$p(\sigma^2) \propto \sigma^{-2(\nu_n/2+1)} \exp\left(-\frac{\nu_n s_n^2}{2\sigma^2}\right).$$

- ▶ By technique #3

$$p(\sigma^2|y) \propto \frac{p(y|\theta, \sigma^2)p(\theta, \sigma^2)}{p(\theta|\sigma^2, y)} = \frac{p(y|\theta, \sigma^2)(\sigma^2)^{-1}}{\mathcal{N}(\theta|\bar{y}, \sigma^2/n)}$$

- ▶ **Important:** As a function of  $\sigma^2$  [at  $\theta = \bar{y}$ ]

1.  $\mathcal{N}(\theta|\bar{y}, \sigma^2/n) \propto (\sigma^{-2})^{-1/2}$

2.  $p(y|\theta, \sigma^2)(\sigma^2)^{-1} \propto (\sigma^{-2})^{n/2+1} \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \bar{y})^2\right)$

- ▶ 1./2. gives

$$\sigma^{-2(\frac{n-1}{2}+1)} \exp\left(-\frac{\overbrace{n-1}^{\nu_n}}{2\sigma^2} \overbrace{\frac{1}{n-1} \sum_{i=1}^n (y_i - \bar{y})^2}^{s_n^2}\right).$$

# Normal model with unknown variance - Uniform prior, cont.

- ▶ **Simulating** the posterior. Uses technique #1.
  1. Draw  $X \sim \chi^2(n-1)$
  2. Compute  $\sigma^2 = \frac{(n-1)s^2}{X}$  [this a draw from  $\text{Inv-}\chi^2(n-1, s^2)$ ]
  3. Draw a  $\theta$  from  $N(\bar{y}, \frac{\sigma^2}{n})$  conditional on the previous draw  $\sigma^2$
  4. Repeat step 1-3 many times.
- ▶ The sampling is implemented in the R program `NormalNonInfoPrior.R`
- ▶ We may derive the **marginal posterior** analytically as

$$\theta|y \sim t_{n-1}\left(\bar{y}, \frac{s^2}{n}\right),$$

or plot the histogram of only  $\theta$  [technique #4] from the simulation above.

- ▶ **Homework** (if you want): follow the techniques to derive the posterior when

$$\begin{aligned} p(\mu|\sigma^2) &= \mathcal{N}(\mu_0, \sigma^2/\kappa_0) \\ p(\sigma^2) &= 1/\sigma^2. \end{aligned}$$

# Multinomial model with Dirichlet prior

- ▶ **Easier** - can simulate from  $p(\theta_1, \dots, \theta_K | y)$  directly. No decomposition needed.
- ▶ **Data**:  $y = (y_1, \dots, y_K)$ , where  $y_k$  counts the number of observations in the  $k$ th category.  $\sum_{k=1}^K y_k = n$ .
- ▶ **Example (brand choices)**: iPhone, Android, Blackberry, other ( $K = 4$ )
- ▶ **Multinomial model**:

$$p(y|\theta) \propto \prod_{k=1}^K \theta_k^{y_k}, \text{ where } \sum_{k=1}^K \theta_k = 1.$$

- ▶ **Conjugate prior**:  $\text{Dirichlet}(\alpha_1, \dots, \alpha_K)$

$$p(\theta) \propto \prod_{k=1}^K \theta_k^{\alpha_k - 1}.$$

# Multinomial model with Dirichlet prior

- ▶ Moments of  $\theta = (\theta_1, \dots, \theta_K)' \sim \text{Dirichlet}(\alpha_1, \dots, \alpha_K)$

$$E(\theta_k) = \frac{\alpha_k}{\sum_{j=1}^K \alpha_j} \quad \text{and} \quad V(\theta_k) = \frac{E(\theta_k) [1 - E(\theta_k)]}{1 + \sum_{j=1}^K \alpha_j}.$$

- ▶ Note that  $\sum_{j=1}^K \alpha_j$  is a **precision** parameter.
- ▶ '**Non-informative**':  $\alpha_1 = \dots = \alpha_K = 1$  (uniform and proper).
- ▶ **Simulating** from the Dirichlet distribution:
  1. Generate  $x_1 \sim \text{Gamma}(\alpha_1, 1), \dots, x_K \sim \text{Gamma}(\alpha_K, 1)$ .
  2. Compute  $y_k = x_k / (\sum_{j=1}^K x_j)$ .
  3.  $y = (y_1, \dots, y_K)$  is a draw from the  $\text{Dirichlet}(\alpha_1, \dots, \alpha_K)$  distribution.
- ▶ **Prior-to-Posterior updating**:

Model	Prior		Posterior
Mult	$\theta \sim \text{Dirichlet}(\alpha_1, \dots, \alpha_K)$	$\rightarrow$	$\theta y \sim \text{Dirichlet}(\alpha_1 + y_1, \dots, \alpha_K + y_K)$

## ► Model

$$y_1, \dots, y_n \stackrel{iid}{\sim} \mathcal{N}_p(\mu, \Sigma)$$

where  $\Sigma$  is a **known** covariance matrix.

## ► Density

$$p(y|\mu, \Sigma) = |\Sigma|^{-1/2} \exp \left( -\frac{1}{2} (y - \mu)' \Sigma^{-1} (y - \mu) \right).$$

## ► Likelihood

$$\begin{aligned} p(y_1, \dots, y_n|\mu, \Sigma) &\propto |\Sigma|^{-n/2} \exp \left( -\frac{1}{2} \sum_{i=1}^n (y_i - \mu)' \Sigma^{-1} (y_i - \mu) \right) \\ &= |\Sigma|^{-n/2} \exp \left( -\frac{1}{2} \text{tr} (\Sigma^{-1} S_\mu) \right), \end{aligned}$$

where  $S_\mu = \sum_{i=1}^n (y_i - \mu)(y_i - \mu)'$ .

► **Prior**

$$\mu \sim \mathcal{N}_p(\mu_0, \Lambda_0).$$

► **Posterior**

$$\mu|y \sim \mathcal{N}_p(\mu_n, \Lambda_n),$$

where

$$\begin{aligned}\Lambda_n^{-1} &= \Lambda_0^{-1} + n\Sigma^{-1} \\ \mu_n &= (\Lambda_0^{-1} + n\Sigma^{-1})^{-1}(\Lambda_0^{-1}\mu_0 + n\Sigma^{-1}\bar{y}).\end{aligned}$$

- **Prior precision:**  $\Lambda_0^{-1}$ . **Data precision:**  $n\Sigma^{-1}$ .
- **Note:** the posterior mean is a (matrix) **weighted average** of prior and data information.
- **Noninformative prior:** let the precision go to zero:  $\Lambda_0^{-1} \rightarrow 0$ .