6.035

Lecture 1: Introduction

Staff

Lecturer

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Rooms

-MWF 32-124 11:00 am

-TH 32-124 12:00 pm

Course Secretary

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Teaching Assistants

- Chengyuan Ma (macy404@mit.edu)
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Reference Textbooks

- Modern Compiler Implementation in Java (Tiger book)
 A.W. Appel
 Cambridge University Press, 1998
 ISBN 0-52158-388-8
- Advanced Compiler Design and Implementation (Whale book)
 Steven Muchnick
 Morgan Kaufman Publishers, 1997
 ISBN 1-55860-320-4
- Compilers: Principles, Techniques and Tools (Dragon book)
 Aho, Lam, Sethi and Ullman
 Addison-Wesley, 2006
 ISBN 0321486811
- Engineering a Compiler (Ark book)
 Keith D. Cooper, Linda Torczon
 Morgan Kaufman Publishers, 2003
 ISBN 1-55860-698-X
- Optimizing Compilers for Modern Architectures Randy Allen and Ken Kennedy Morgan Kaufman Publishers, 2001 ISBN 1-55860-286-0

A textbook tutorial on compiler implementation, including techniques for many language features

Essentially a recipe book of optimizations; very complete and suited for industrial practitioners and researchers.

The classic compilers textbook, although its front-end emphasis reflects its age. New edition has more optimization material.

A modern classroom textbook, with increased emphasis on the back-end and implementation techniques.

A modern textbook that focuses on optimizations including parallelization and memory hierarchy optimization

The Project: The Five Segments

- Lexical and Syntax Analysis
- Semantic Analysis
- © Code Generation
- Dataflow Analysis
- Optimizations

Each Segment...

- Segment Start
 - Project Description
- Lectures
 - 2 to 5 lectures
- Project Time
 - (Design Document)
 - (Project Checkpoint)
- Project Due

Project Groups

- Phase 1 is an individual project
- Phases 2 to 5 are group projects
- Each group consists of 3 to 4 students
- Projects are designed to produce a compiler by the end of class

Grading

- All group members (mostly) get the same grade
- Phase 1: Scanner/Parser
- Phase 2: IR and Semantic Checks
- Phase 3: x86 Code generator
- Phase 4: Dataflow Analysis
- Phase 5: Register Allocation + Optimizations
- 5 turn-ins total

Project Collaboration Policy

- Talk about anything you want with anybody
- Write all the code yourself
- Check with TAs before using specialized libraries designed to support compiler construction

Quizzes

- Two In Class Quizzes
- 50 minutes each
- Book/Open Book Status TBD
- Quiz collaboration policy:
 - Do your quiz by yourself with no input from anyone else during the quiz

Mini Quizzes

- Posted on Gradescope once every week
- Can help you check your understanding of the material
- Collaboration of any kind is OK
- This is in lieu of time consuming problem sets

Grading Breakdown

- Project = 75% of total grade
 - Option A:10% Phase 1/2, 25% Phase 3/4, 40% Phase 5 Final Submission
 - Option B:75% Phase 5 Final Submission
 - We will take the maximum of option A or option B
- Quizzes = 20% total, 10% each
- Miniquizzes/Class participation = 5%

More Course Stuff

- Blank page project all the rope you want!
- Challenging project
- You are on your own!
- Project collaboration policy
 - Talk all you want about project
 - Write all of the your code yourself
- Accepted Languages
 - Java
 - Scala
 - Rust
 - Typescript
 - For other languages: talk to the TAs

Why Study Compilers?

- Compilers enable programming at a high level language instead of machine instructions.
 - Malleability, Portability, Modularity, Simplicity,
 Programmer Productivity
 - Also Efficiency and Performance
- Indispensible programmer productivity tool
- One of most complex software systems to build

Compilers Construction touches many topics in Computer Science

- Theory
 - Finite State Automata, Grammars and Parsing, data-flow
- Algorithms
 - Graph manipulation, dynamic programming
- Data structures
 - Symbol tables, abstract syntax trees
- Systems
 - Allocation and naming, multi-pass systems, compiler construction
- Computer Architecture
 - Memory hierarchy, instruction selection, interlocks and latencies, parallelism
- Security
 - Detection of and Protection against vulnerabilities
- Software Engineering
 - Software development environments, debugging
- Artificial Intelligence
 - Heuristic based search for best optimizations

What a Compiler Does

- Input: High-level programming language
- Output: Low-level assembly instructions
- Compiler does the translation:
 - Read and understand the program
 - Precisely determine what actions it requires
 - Figure-out how to faithfully carry out those actions
 - Instruct the computer to carry out those actions

Input to the Compiler

- Standard imperative language (Java, C, C++)
 - State
 - Variables,
 - Structures,
 - Arrays
 - Computation
 - Expressions (arithmetic, logical, etc.)
 - Assignment statements
 - Control flow (conditionals, loops)
 - Procedures

Output of the Compiler

- State
 - Registers
 - Memory with Flat Address Space
- Machine code load/store architecture
 - Load, store instructions
 - Arithmetic, logical operations on registers
 - Branch instructions

Example (input program)

```
int sumcalc(int a, int b, int N)
{
    int i, x, y;
    x = 0;
    y = 0;
    for(i = 0; i <= N; i++) {
        x = x + (4*a/b)*i + (i+1)*(i+1);
        x = x + b*y;
    }
    return x;
}</pre>
```

Example (Output assembly code)

```
sumcalc:
        pushq
                 %rbp
                 %rsp, %rbp
        mova
                %edi, -4(%rbp)
        movl
                %esi, -8(%rbp)
        movl
                %edx, -12(%rbp)
        movl
                $0, -20(%rbp)
        movl
                $0, -24(%rbp)
        movl
                $0, -16(%rbp)
        movl
.L2:
                -16(%rbp), %eax
        movl
        cmpl
                -12(%rbp), %eax
                 .L3
                -4(%rbp), %eax
        movl
        leal
                0(,%rax,4), %edx
                -8(%rbp), %rax
        leaq
                %rax, -40(%rbp)
        movq
        movl
                %edx, %eax
                 -40(%rbp), %rcx
        mova
        cltd
        idivl
                 (%rcx)
        movl
                %eax, -28(%rbp)
        movl
                -28(%rbp), %edx
                -16(%rbp), %edx
        imull
                -16(%rbp), %eax
        movl
        incl
                 %eax
        imull
                %eax, %eax
        addl
                %eax, %edx
        leaσ
                -20(%rbp), %rax
                %edx, (%rax)
        addl
        movl
                -8(%rbp), %eax
        movl
                %eax, %edx
                -24(%rbp), %edx
        imull
                -20(%rbp), %rax
        leag
        addl
                %edx, (%rax)
                -16(%rbp), %rax
        leaq
        incl
                 (%rax)
        jmp
                 .L2
                 -20(%rbp), %eax
.L3:
        movl
        leave
        ret
```

```
sumcalc, .-sumcalc
 .size
         .section
.Lframe1:
                   .LECIE1-.LSCIE1
         .long
.LSCIE1:.long
                   0 \times 0
         .byte
                   0 \times 1
         .string
         .uleb128 0x1
         .sleb128 -8
         .byte
                   0 \times 10
         .byte
                   0xc
         .uleb128 0x7
         .uleb128 0x8
                   0 \times 90
         .bvte
         .uleb128 0x1
         .aliqn
.LECIE1:.long
                   .LEFDE1-.LASFDE1
         .long
                   .LASFDE1-.Lframe1
                   . LFB2
         .quad
                   .LFE2-.LFB2
         .quad
         .byte
                   0 \times 4
                    .LCFI0-.LFB2
         .long
         .bvte
                   0xe
         .uleb128 0x10
         .bvt.e
                   0x86
         .uleb128 0x2
         .bvte
                   0x4
         .long
                    .LCFI1-.LCFI0
         .bvte
                   0xd
         .uleb128 0x6
         .align
```

Optimization Example

```
int sumcalc(int a, int b, int N)
{
    int i;
    int x, y;
    \mathbf{x} = 0;
    y = 0;
    for(i = 0; i \le N; i++) {
       x = x + (4*a/b)*i + (i+1)*(i+1);
        x = x + b*y;
    return x;
```

```
pushq
                %rbp
                %rsp, %rbp
        movq
                %edi, -4(%rbp)
        movl
                %esi, -8(%rbp)
        movl
        movl
                %edx, -12(%rbp)
        movl
                $0, -20(%rbp)
                $0, -24(%rbp)
        movl
        movl
                $0, -16(%rbp)
.L2:
        movl
                -16(%rbp), %eax
        cmpl
                -12(%rbp), %eax
                .L3
        jg
        movl
                -4 (%rbp), %eax
                0(,%rax,4), %edx
        leal
                -8(%rbp), %rax
        leaq
        movq
                %rax, -40(%rbp)
                %edx, %eax
        movl
                -40(%rbp), %rcx
        movq
        cltd
        idivl
                (%rcx)
                %eax, -28(%rbp)
        movl
        movl
                -28(%rbp), %edx
        imull
                -16(%rbp), %edx
        movl
                -16(%rbp), %eax
        incl
                %eax
        imull
                %eax, %eax
        addl
                %eax, %edx
        leaq
                -20(%rbp), %rax
        addl
                %edx, (%rax)
        movl
                -8(%rbp), %eax
        movl
                %eax, %edx
        imull
                -24(%rbp), %edx
                -20(%rbp), %rax
        leaq
        addl
                %edx, (%rax)
        leaq
                -16(%rbp), %rax
        incl
                (%rax)
                .L2
        qmį
.L3:
                -20(%rbp), %eax
        movl
        leave
        ret
```

Lets Optimize...

```
int sumcalc(int a, int b, int N)
{
    int i, x, y;
    x = 0;
    y = 0;
    for(i = 0; i <= N; i++) {
        x = x + (4*a/b)*i + (i+1)*(i+1);
        x = x + b*y;
    }
    return x;
}</pre>
```

Constant Propagation

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
    x = x + (4*a/b)*i + (i+1)*(i+1);
    x = x + b*y;
}
return x;</pre>
```

Constant Propagation

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
    x = x + (4*a/b)*i + (i+1)*(i+1);
    x = x + b*y;
}
return x;</pre>
```

Constant Propagation

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
    x = x + (4*a/b)*i + (i+1)*(i+1);
    x = x + b*0;
}
return x;</pre>
```

Algebraic Simplification

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
   x = x + (4*a/b)*i + (i+1)*(i+1);
   x = x + b*0;
}
return x;</pre>
```

Algebraic Simplification

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
   x = x + (4*a/b)*i + (i+1)*(i+1);
   x = x + b*0;
}
return x;</pre>
```

Algebraic Simplification

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
   x = x + (4*a/b)*i + (i+1)*(i+1);
   x = x;
}
return x;</pre>
```

Copy Propagation

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
    x = x + (4*a/b)*i + (i+1)*(i+1);
    x = x;
}
return x;</pre>
```

Copy Propagation

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
   x = x + (4*a/b)*i + (i+1)*(i+1);
   x = x;
}
return x;</pre>
```

Copy Propagation

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
   x = x + (4*a/b)*i + (i+1)*(i+1);
}
return x;</pre>
```

Common Subexpression Elimination

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
    x = x + (4*a/b)*i + (i+1)*(i+1);
}
return x;</pre>
```

Common Subexpression Elimination

```
int i, x, y;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
    x = x + (4*a/b)*i + (i+1)*(i+1);
}
return x;</pre>
```

Common Subexpression Elimination

```
int i, x, y, t;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
   t = i+1;
   x = x + (4*a/b)*i + t*t;
}
return x;</pre>
```

Dead Code Elimination

```
int i, x, y, t;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
   t = i+1;
   x = x + (4*a/b)*i + t*t;
}
return x;</pre>
```

Dead Code Elimination

```
int i, x, y, t;
x = 0;
y = 0;
for(i = 0; i <= N; i++) {
   t = i+1;
   x = x + (4*a/b)*i + t*t;
}
return x;</pre>
```

Dead Code Elimination

```
int i, x, t;
x = 0;

for(i = 0; i <= N; i++) {
   t = i+1;
   x = x + (4*a/b)*i + t*t;
}
return x;</pre>
```

Loop Invariant Code Removal

```
int i, x, t;
x = 0;

for(i = 0; i <= N; i++) {
   t = i+1;
   x = x + (4*a/b)*i + t*t;
}
return x;</pre>
```

Loop Invariant Code Removal

```
int i, x, t;
x = 0;

for(i = 0; i <= N; i++) {
   t = i+1;
   x = x + (4*a/b)*i + t*t;
}
return x;</pre>
```

Loop Invariant Code Removal

```
int i, x, t, u;
x = 0;
u = (4*a/b);
for(i = 0; i <= N; i++) {
    t = i+1;
    x = x + u*i + t*t;
}
return x;</pre>
```

Strength Reduction

```
int i, x, t, u;
x = 0;
u = (4*a/b);
for(i = 0; i <= N; i++) {
   t = i+1;
   x = x + u*i + t*t;
return x;
```

Strength Reduction

```
int i, x, t, u;
x = 0;
u = (4*a/b);
for(i = 0; i <= N; i++) {
   t = i+1;
   x = x + u*i + t*t;
return x;
```

Strength Reduction

```
int i, x, t, u, v;
x = 0;
u = ((a << 2)/b);
\mathbf{v} = 0;
for(i = 0; i <= N; i++) {
   t = i+1;
   x = x + v + t*t;
   v = v + u;
return x;
```

Register Allocation

fp

Local variable X
Local variable Y
Local variable I

Register Allocation

```
Local variable X

Local variable Y

Local variable I
```

```
$r8d = X
$r9d = t
$r10d = u
$ebx = v
$ecx = i
```

Optimized Example

```
int sumcalc(int a, int b, int N)
{
    int i, x, t, u, v;
    x = 0;
    u = ((a << 2)/b);
    v = 0;
    for(i = 0; i <= N; i++) {
       t = i+1;
       x = x + v + t*t;
        v = v + u;
    return x;
```

Unoptimized Code

```
pushq
                 %rsp, %rbp
                 %edi, -4(%rbp)
                 %esi, -8(%rbp)
                 %edx, -12(%rbp)
                 $0, -20(%rbp)
                 $0, -24(%rbp)
                 $0, -16(%rbp)
                 -12(%rbp), %eax
                 -4(%rbp), %eax
        leal
                 0(, %rax, 4), %edx
                 -8(%rbp), %rax
        leaq
                 %rax, -40(%rbp)
                 %edx, %eax
                 -40(%rbp), %rcx
        cltd
        idivl
                 (%rcx)
                 %eax, -28(%rbp)
                 -28(%rbp), %edx
        imull
                -16(%rbp), %edx
                 -16(%rbp), %eax
        imull
                 %eax, %eax
        addl
                 %eax, %edx
        leaq
                 -20(%rbp), %rax
        addl
                 %edx, (%rax)
                 -8(%rbp), %eax
                 %eax, %edx
        imull
                 -24(%rbp), %edx
        leaq
                 -20(%rbp), %rax
        addl
                 %edx, (%rax)
        leaq
                 -16(%rbp), %rax
                 (%rax)
                 .L2
.L3:
                 -20(%rbp), %eax
        leave
```

Inner Loop:

10*mov + 5*lea + 5*add/inc + 4*div/mul + 5*cmp/br/jmp = 29 instructions Execution time = 43 sec

Optimized Code

```
%r8d, %r8d
xorl
xorl
movl
        %edx, %r9d
        %edx, %r8d
cmpl
        .L7
        $2, %edi
        %edi, %eax
cltd
        %esi
leal
        1(%rcx), %edx
        %eax, %r10d
imull
        %ecx, %r10d
        %edx, %ecx
imull
        %edx, %ecx
         (%r10,%rcx), %eax
leal
        %edx, %ecx
addl
        %eax, %r8d
cmpl
        %r9d, %edx
        %r8d, %eax
```

```
4*mov + 2*lea + 1*add/inc+

3*div/mul + 2*cmp/br/jmp

= 12 instructions

Execution time = 17 sec
```

Compilers Optimize Programs for...

- Performance/Speed
- Code Size
- Power Consumption
- Fast/Efficient Compilation
- Security/Reliability
- Debugging