PROBLEM STATEMENT:

IOT BASED-REAL TIME RIVER WATER OUALITY MONITORING AND CONTROL SYSTEM

DOMAIN:

INTERNET OF THINGS

ASSIGNMENT 4:

DISTANCE DETECTION USING ULTRASOINC SENSOR

\mathbf{BY}

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Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cm send "alert" to IBM cloud and display in device recent events.

WOWKI LINK:

https://wokwi.com/projects/347013247322292820

Solution:

```
#include <WiFi.h>
 #include < PubSubClient.h >
WiFiClientwifiClient;
String data3;
#define ORG "1qt6jn"
#define DEVICE TYPE "Assignment-4"
#define DEVICE ID "banu"
#define TOKEN "12345678"
#define speed 0.034
#define led 14
Char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
Char publishTopic[] = "iot-2/evt/manimd/fmt/json";
Char topic[] = "iot-2/cmd/led/fmt/String";
Char authMethod[] = "use-token-auth";
Char token[] = TOKEN;
Char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
Const int trigpin=5;
```

```
Const int echopin=18;
String command;
String data=" ";
Long duration;
Float dist;
Void setup()
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
}
void loop() {
 bool isNearby = dist< 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
if (!client.loop()) {
 mqttConnect();
```

```
}
void wifiConnect() {
Serial.print("Connecting to "); Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
 delay(500);
Serial.print(".");
}
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
If (!client.connected()) {
 Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  While (!client.connect(clientId, authMethod, token)) {
  Serial.print(".");
   delay(500);
}
 initManagedDevice();
 Serial.println();
void initManagedDevice() {
 if (client.subscribe(topic)) {
 // Serial.println(client.subscribe(topic));
```

```
Serial.println("IBM subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
Void publishData()
{
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
 String payload = "{\"Alert Distance\":";
 Payload += dist;
 Payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 If (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
}else {
Serial.println("Publish FAILED");
}
```

Output:



