

## **PROBLEM STATEMENT :**

IoT based Smart crop protection system

## **DOMAIN :**

Internet of Things

## **ASSIGNMENT 1:**

Smart home with at least two sensors and led, buzzer in TinkerCad

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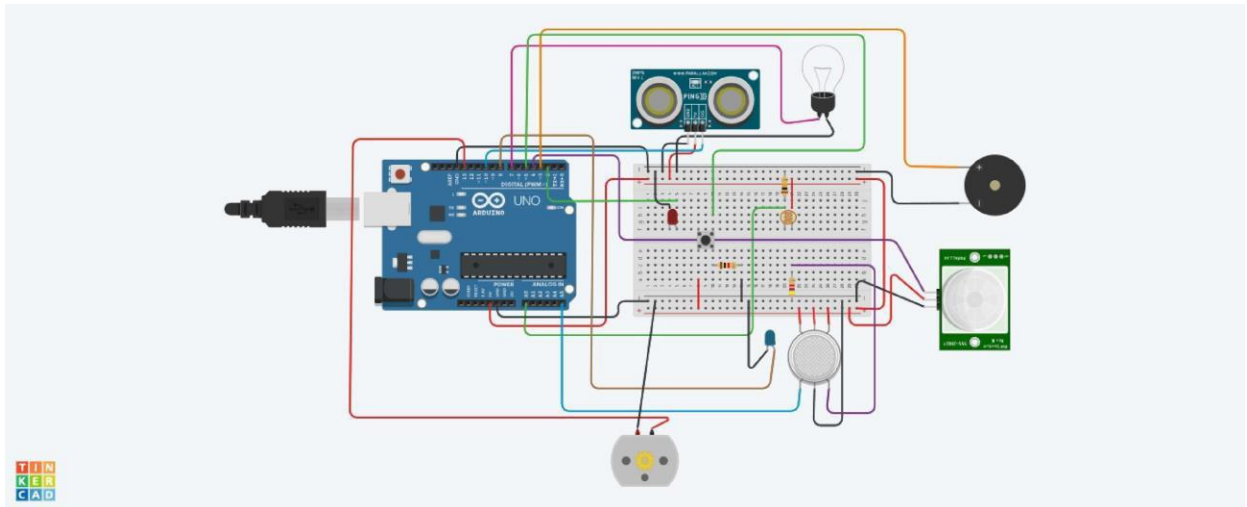
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Link: [https://www.tinkercad.com/things/39SEf7Fqr4h-terrific-luulia-amur/editel?sharecode=FKQR\\_ZuHMPvx0HiLnrJ0Iagb3g2hb1sZ9oTxZPFFAo](https://www.tinkercad.com/things/39SEf7Fqr4h-terrific-luulia-amur/editel?sharecode=FKQR_ZuHMPvx0HiLnrJ0Iagb3g2hb1sZ9oTxZPFFAo)

## CIRCUIT DIAGRAM :



## ARDUINO UNO CODE:

```
const int pingPin = 10;
```

```
const int IedUS = 2;
```

```
const int light = 7;
```

```
const int pir = 4;
```

```
#define photosensor A0
```

```
#define buzzer 3
```

```
intconst PINO SGAS = A5;
```

```
int const IedGas = 8;
```

```
int const button = 5;
```

```
int const motor = 13;
```

```
void setup()
```

```
pinMode(IedUS, OUTPUT);
```

```
pinMode(light, OUTPUT);
```

```
pinMode(buzzer, OUTPUT);
```

```
pinMode(IedGas, OUTPUT);
```

```
pinMode(motor, OUTPUT);
```

```
pinMode(pir, INPUT);
```

```
pinMode(button, INPUT);
```

```
pinMode(photoSensor, INPUT);
```

```
Serial.begin(9600);
```

```
void loop()
```

```
    long duration, cm;
```

```
    int valLight = analogRead(photoSensor);
```

```
    int vaPIR= digitalRead(pir);
```

```
    intvaIGAS =analogRead(PIN0 SGAS);
```

```
    vaIGAS = map(vaIGAS, 300, 750, 0, 100);
```

```
    int valBt = digitalRead(button);
```

```
    pinMode(pingPin, OUTPUT);
```

```
    digitalWrite(pingPin, LOW);
```

```
    delayMicroseconds(2);
```

```
    digitalWrite(pingPin, HIGH);
```

```
    delayMicroseconds(5);
```

```
    digitalWrite(pingPin, LOW);
```

```
    pinMode(pingPin, INPUT);
```

```
    duration = pulseIn(pingPin, HIGH);
```

```
    cm = microsecondsToCentimeters(duration);
```

```
    if(cm < 336)(
```

```
        digitalWrite(IedUS, HIGH);
```

```
    )else(
```

```
        digitalWrite(IedUS, LOW);
```

```
    if(valLight < 890)(
```

```
        digitalWrite(light, HIGH);
```

```
}else(  
    digitalWrite(light, LOW);
```

```
if(vaPIR == 1)(  
    digitalWrite(buzzer, HIGH);  
}else(  
    digitalWrite(buzzer, LOW);
```

```
if(vaIBt == 1)(  
    digitalWrite(motor, HIGH);  
}else(  
    digitalWrite(motor, LOW);
```

```
if(vaIGAS > 20)(  
    digitalWrite(IedGas, HIGH);  
}else(  
    digitalWrite(IedGas, LOW);
```

```
Serial.print(vaPIR);  
Serial.println();
```

```
long microsecondsToCentimeters(long microseconds) { return  
    microseconds / 29 / 2;
```