This notebook is an exercise in the Computer Vision course. You can reference the tutorial at this link.

Introduction

In these exercises, you'll explore what effect various random transformations have on an image, consider what kind of augmentation might be appropriate on a given dataset, and then use data augmentation with the *Car or Truck* dataset to train a custom network.

Run the cell below to set everything up!

```
In [1]:
         # Setup feedback system
         from learntools.core import binder
         binder.bind(globals())
         from learntools.computer_vision.ex6 import *
         from tensorflow import keras
         from tensorflow.keras import layers
         from tensorflow.keras.layers.experimental import preprocessing
         # Imports
         import os, warnings
         import matplotlib.pyplot as plt
         from matplotlib import gridspec
         import numpy as np
         import tensorflow as tf
         from tensorflow.keras.preprocessing import image dataset from directory
         # Reproducability
         def set seed(seed=31415):
             np.random.seed(seed)
             tf.random.set seed(seed)
             os.environ['PYTHONHASHSEED'] = str(seed)
             os.environ['TF_DETERMINISTIC_OPS'] = '1'
         set seed()
         # Set Matplotlib defaults
         plt.rc('figure', autolayout=True)
         plt.rc('axes', labelweight='bold', labelsize='large',
                titleweight='bold', titlesize=18, titlepad=10)
         plt.rc('image', cmap='magma')
         warnings.filterwarnings("ignore") # to clean up output cells
         # Load training and validation sets
         ds_train_ = image_dataset_from_directory(
             '../input/car-or-truck/train',
             labels='inferred',
             label mode='binary',
             image size=[128, 128],
             interpolation='nearest',
             batch_size=64,
             shuffle=True,
```

```
ds valid = image dataset from directory(
     '../input/car-or-truck/valid',
     labels='inferred',
     label mode='binary'
     image_size=[128, 128],
     interpolation='nearest',
     batch size=64,
     shuffle=False,
 )
# Data Pipeline
def convert to float(image, label):
     image = tf.image.convert_image_dtype(image, dtype=tf.float32)
     return image, label
AUTOTUNE = tf.data.experimental.AUTOTUNE
 ds train = (
     ds train
     .map(convert to float)
     .cache()
     .prefetch(buffer size=AUTOTUNE)
 )
ds valid = (
     ds valid
     .map(convert_to_float)
     .cache()
     .prefetch(buffer size=AUTOTUNE)
 )
Found 5117 files belonging to 2 classes.
2022-12-19 13:55:39.601696: I tensorflow/stream executor/cuda/cuda gpu executor.cc:937]
successful NUMA node read from SysFS had negative value (-1), but there must be at least
one NUMA node, so returning NUMA node zero
2022-12-19 13:55:39.713726: I tensorflow/stream executor/cuda/cuda gpu executor.cc:937]
```

successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero 2022-12-19 13:55:39.714643: I tensorflow/stream executor/cuda/cuda gpu executor.cc:937] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero 2022-12-19 13:55:39.722794: I tensorflow/core/platform/cpu feature guard.cc:142] This Te nsorFlow binary is optimized with oneAPI Deep Neural Network Library (oneDNN) to use the following CPU instructions in performance-critical operations: AVX2 AVX512F FMA To enable them in other operations, rebuild TensorFlow with the appropriate compiler fla gs. 2022-12-19 13:55:39.723116: I tensorflow/stream executor/cuda/cuda gpu executor.cc:937] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero 2022-12-19 13:55:39.724067: I tensorflow/stream executor/cuda/cuda gpu executor.cc:937] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero 2022-12-19 13:55:39.724956: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:937] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero 2022-12-19 13:55:41.807768: I tensorflow/stream executor/cuda/cuda gpu executor.cc:937] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero 2022-12-19 13:55:41.808655: I tensorflow/stream executor/cuda/cuda gpu executor.cc:937] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

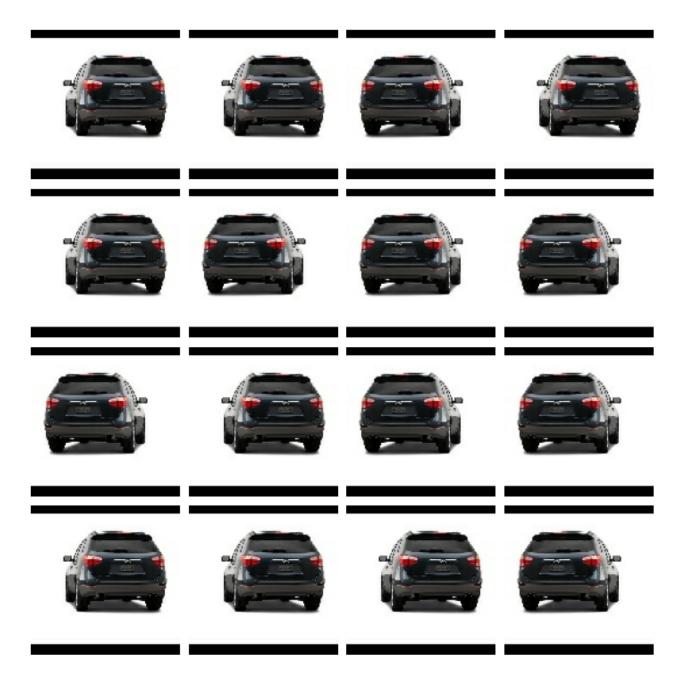
```
2022-12-19 13:55:41.809381: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:937] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero 2022-12-19 13:55:41.810010: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1510] Cre ated device /job:localhost/replica:0/task:0/device:GPU:0 with 15401 MB memory: -> device: 0, name: Tesla P100-PCIE-16GB, pci bus id: 0000:00:04.0, compute capability: 6.0 Found 5051 files belonging to 2 classes.
```

(Optional) Explore Augmentation

Uncomment a transformation and run the cell to see what it does. You can experiment with the parameter values too, if you like. (The factor parameters should be greater than 0 and, generally, less than 1.) Run the cell again if you'd like to get a new random image.

```
In [2]:
         # all of the "factor" parameters indicate a percent-change
         augment = keras.Sequential([
             # preprocessing.RandomContrast(factor=0.5),
             preprocessing.RandomFlip(mode='horizontal'), # meaning, Left-to-right
             # preprocessing.RandomFlip(mode='vertical'), # meaning, top-to-bottom
             # preprocessing.RandomWidth(factor=0.15), # horizontal stretch
             # preprocessing.RandomRotation(factor=0.20),
             # preprocessing.RandomTranslation(height factor=0.1, width factor=0.1),
         ])
         ex = next(iter(ds_train.unbatch().map(lambda x, y: x).batch(1)))
         plt.figure(figsize=(10,10))
         for i in range(16):
             image = augment(ex, training=True)
             plt.subplot(4, 4, i+1)
             plt.imshow(tf.squeeze(image))
             plt.axis('off')
         plt.show()
```

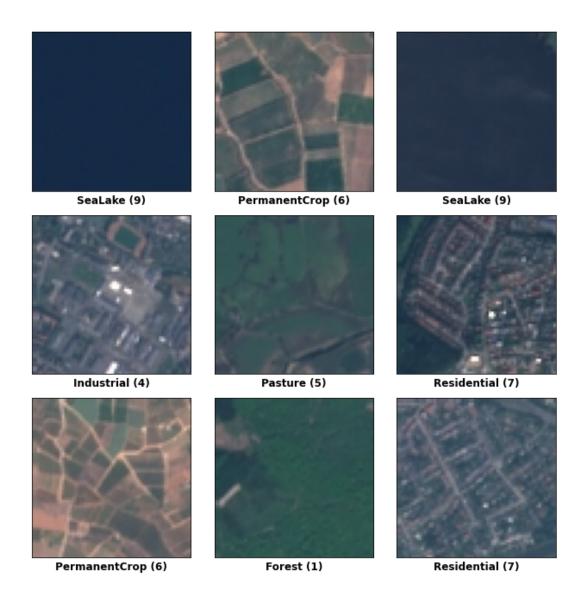
2022-12-19 13:55:48.176031: I tensorflow/compiler/mlir_graph_optimization_pass.cc:1 85] None of the MLIR Optimization Passes are enabled (registered 2) 2022-12-19 13:55:50.043178: W tensorflow/core/kernels/data/cache_dataset_ops.cc:768] The calling iterator did not fully read the dataset being cached. In order to avoid unexpect ed truncation of the dataset, the partially cached contents of the dataset will be disc arded. This can happen if you have an input pipeline similar to `dataset.cache().take (k).repeat()` . You should use `dataset.take(k).cache().repeat()` instead.



Do the transformations you chose seem reasonable for the Car or Truck dataset?

In this exercise, we'll look at a few datasets and think about what kind of augmentation might be appropriate. Your reasoning might be different that what we discuss in the solution. That's okay. The point of these problems is just to think about how a transformation might interact with a classification problem -- for better or worse.

The EuroSAT dataset consists of satellite images of the Earth classified by geographic feature. Below are a number of images from this dataset.



1) EuroSAT

What kinds of transformations might be appropriate for this dataset?

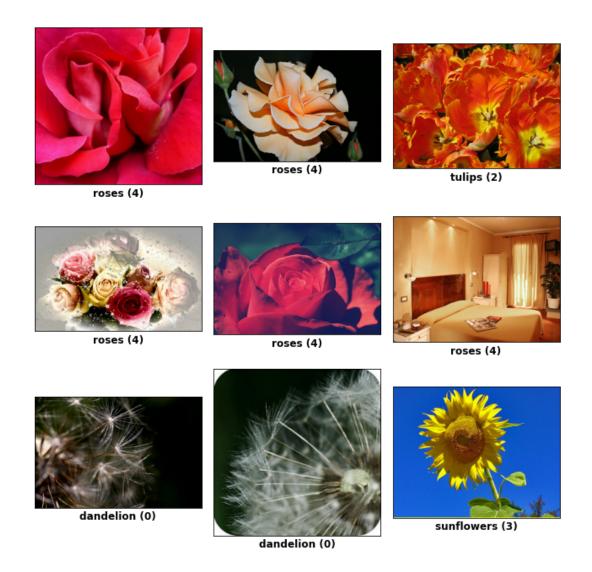
```
In [3]:
# View the solution (Run this code cell to receive credit!)
q_1.check()
```

Correct:

It seems to this author that flips and rotations would be worth trying first since there's no concept of orientation for pictures taken straight overhead. None of the transformations seem likely to confuse classes, however.

```
In [4]:
# Lines below will give you a hint
#q_1.solution()
```

The TensorFlow Flowers dataset consists of photographs of flowers of several species. Below is a sample.



2) TensorFlow Flowers

What kinds of transformations might be appropriate for the TensorFlow Flowers dataset?

In [5]:

View the solution (Run this code cell to receive credit!)
q_2.check()

Correct:

It seems to this author that horizontal flips and moderate rotations would be worth trying first. Some augmentation libraries include transformations of hue (like red to blue). Since the color of a flower seems distinctive of its class, a change of hue might be less successful. On the other hand, there is suprising variety in cultivated flowers like roses, so, depending on the dataset, this might be an improvement after all!

In [6]:

Lines below will give you a hint
#q_2.solution()

Now you'll use data augmentation with a custom convnet similar to the one you built in Exercise 5. Since data augmentation effectively increases the size of the dataset, we can increase the capacity of the model in turn without as much risk of overfitting.

3) Add Preprocessing Layers

Add these preprocessing layers to the given model.

```
preprocessing.RandomContrast(factor=0.10),
preprocessing.RandomFlip(mode='horizontal'),
preprocessing.RandomRotation(factor=0.10),
```

```
In [7]:
         from tensorflow import keras
         from tensorflow.keras import layers
         model = keras.Sequential([
             layers.InputLayer(input_shape=[128, 128, 3]),
             # Data Augmentation
             preprocessing.RandomContrast(factor=0.10),
             preprocessing.RandomFlip(mode='horizontal'),
             preprocessing.RandomRotation(factor=0.10),
             # Block One
             layers.BatchNormalization(renorm=True),
             layers.Conv2D(filters=64, kernel_size=3, activation='relu', padding='same'),
             layers.MaxPool2D(),
             # Block Two
             layers.BatchNormalization(renorm=True),
             layers.Conv2D(filters=128, kernel_size=3, activation='relu', padding='same'),
             layers.MaxPool2D(),
             # Block Three
             layers.BatchNormalization(renorm=True),
             layers.Conv2D(filters=256, kernel_size=3, activation='relu', padding='same'),
             layers.Conv2D(filters=256, kernel_size=3, activation='relu', padding='same'),
             layers.MaxPool2D(),
             layers.BatchNormalization(renorm=True),
             layers.Flatten(),
             layers.Dense(8, activation='relu'),
             layers.Dense(1, activation='sigmoid'),
         ])
         # Check your answer
         q 3.check()
```

Correct

```
In [8]: # Lines below will give you a hint or solution code
#q_3.hint()
```

```
#q 3.solution()
```

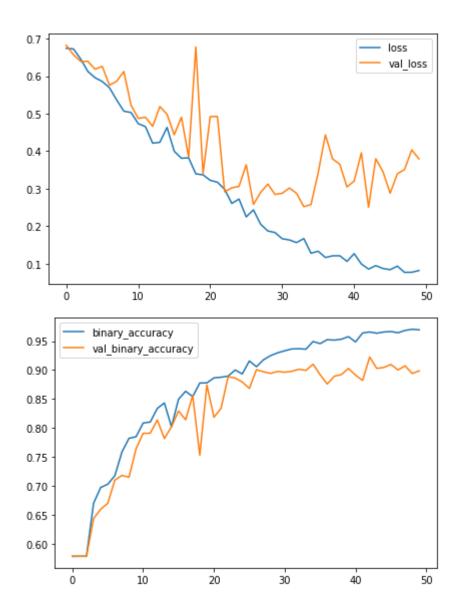
Now we'll train the model. Run the next cell to compile it with a loss and accuracy metric and fit it to the training set.

```
In [9]:
        optimizer = tf.keras.optimizers.Adam(epsilon=0.01)
        model.compile(
            optimizer=optimizer,
            loss='binary crossentropy',
            metrics=['binary_accuracy'],
        history = model.fit(
            ds train,
            validation_data=ds_valid,
            epochs=50,
        # Plot learning curves
        import pandas as pd
        history_frame = pd.DataFrame(history.history)
        history frame.loc[:, ['loss', 'val loss']].plot()
        history_frame.loc[:, ['binary_accuracy', 'val_binary_accuracy']].plot();
        Epoch 1/50
        2022-12-19 13:55:54.915690: I tensorflow/stream_executor/cuda/cuda_dnn.cc:369] Loaded cu
       DNN version 8005
        80/80 [============ - - 42s 409ms/step - loss: 0.6742 - binary accurac
        y: 0.5781 - val_loss: 0.6822 - val_binary_accuracy: 0.5785
        Epoch 2/50
        80/80 [===============] - 8s 102ms/step - loss: 0.6724 - binary_accuracy:
       0.5783 - val_loss: 0.6570 - val_binary_accuracy: 0.5785
        Epoch 3/50
        80/80 [============= ] - 8s 103ms/step - loss: 0.6455 - binary accuracy:
       0.5785 - val loss: 0.6391 - val_binary_accuracy: 0.5781
        80/80 [============= ] - 8s 103ms/step - loss: 0.6125 - binary accuracy:
        0.6699 - val_loss: 0.6394 - val_binary_accuracy: 0.6434
        Epoch 5/50
        80/80 [============== ] - 8s 102ms/step - loss: 0.5957 - binary_accuracy:
       0.6971 - val loss: 0.6185 - val binary accuracy: 0.6595
        Epoch 6/50
        80/80 [================ ] - 8s 102ms/step - loss: 0.5858 - binary_accuracy:
       0.7028 - val_loss: 0.6259 - val_binary_accuracy: 0.6698
        Epoch 7/50
        80/80 [============= ] - 8s 102ms/step - loss: 0.5691 - binary accuracy:
       0.7174 - val loss: 0.5758 - val binary accuracy: 0.7098
        Epoch 8/50
        80/80 [============] - 8s 103ms/step - loss: 0.5366 - binary_accuracy:
       0.7583 - val loss: 0.5863 - val binary accuracy: 0.7181
       Epoch 9/50
        80/80 [================= ] - 8s 102ms/step - loss: 0.5066 - binary_accuracy:
       0.7821 - val_loss: 0.6122 - val_binary_accuracy: 0.7149
        Epoch 10/50
       80/80 [=========== ] - 8s 102ms/step - loss: 0.5030 - binary accuracy:
       0.7848 - val_loss: 0.5223 - val_binary_accuracy: 0.7640
        Epoch 11/50
```

80/80 [===============] - 8s 103ms/step - loss: 0.4734 - binary_accuracy:

```
0.8085 - val loss: 0.4873 - val binary accuracy: 0.7907
Epoch 12/50
80/80 [=========== ] - 8s 102ms/step - loss: 0.4655 - binary accuracy:
0.8102 - val_loss: 0.4905 - val_binary_accuracy: 0.7909
Epoch 13/50
80/80 [===========] - 8s 102ms/step - loss: 0.4214 - binary_accuracy:
0.8337 - val loss: 0.4661 - val binary accuracy: 0.8139
Epoch 14/50
80/80 [=============== ] - 8s 103ms/step - loss: 0.4236 - binary_accuracy:
0.8433 - val loss: 0.5189 - val binary accuracy: 0.7816
Epoch 15/50
80/80 [================= ] - 8s 102ms/step - loss: 0.4634 - binary_accuracy:
0.8020 - val_loss: 0.4984 - val_binary_accuracy: 0.8020
Epoch 16/50
80/80 [============= ] - 8s 102ms/step - loss: 0.3999 - binary accuracy:
0.8497 - val_loss: 0.4437 - val_binary_accuracy: 0.8293
Epoch 17/50
80/80 [===============] - 8s 102ms/step - loss: 0.3812 - binary_accuracy:
0.8634 - val loss: 0.4906 - val binary accuracy: 0.8141
Epoch 18/50
80/80 [=========== ] - 8s 103ms/step - loss: 0.3825 - binary accuracy:
0.8542 - val_loss: 0.3841 - val_binary_accuracy: 0.8561
Epoch 19/50
80/80 [=========== ] - 8s 102ms/step - loss: 0.3397 - binary accuracy:
0.8777 - val loss: 0.6777 - val binary accuracy: 0.7529
Epoch 20/50
80/80 [=============== ] - 8s 103ms/step - loss: 0.3371 - binary_accuracy:
0.8779 - val loss: 0.3402 - val binary accuracy: 0.8743
Epoch 21/50
80/80 [============= ] - 8s 103ms/step - loss: 0.3225 - binary accuracy:
0.8865 - val_loss: 0.4921 - val_binary_accuracy: 0.8185
Epoch 22/50
0.8876 - val_loss: 0.4926 - val_binary_accuracy: 0.8339
Epoch 23/50
80/80 [===========] - 8s 102ms/step - loss: 0.2986 - binary_accuracy:
0.8896 - val_loss: 0.2915 - val_binary_accuracy: 0.8885
Epoch 24/50
80/80 [=========== ] - 8s 102ms/step - loss: 0.2609 - binary accuracy:
0.9001 - val_loss: 0.3026 - val_binary_accuracy: 0.8862
80/80 [=========== ] - 8s 103ms/step - loss: 0.2726 - binary accuracy:
0.8933 - val_loss: 0.3063 - val_binary_accuracy: 0.8794
Epoch 26/50
80/80 [============] - 8s 102ms/step - loss: 0.2250 - binary_accuracy:
0.9158 - val_loss: 0.3639 - val_binary_accuracy: 0.8683
Epoch 27/50
80/80 [============] - 8s 102ms/step - loss: 0.2438 - binary_accuracy:
0.9058 - val loss: 0.2582 - val binary accuracy: 0.9006
Epoch 28/50
80/80 [=============] - 8s 103ms/step - loss: 0.2055 - binary_accuracy:
0.9177 - val loss: 0.2901 - val binary accuracy: 0.8971
Epoch 29/50
80/80 [============= ] - 8s 102ms/step - loss: 0.1875 - binary accuracy:
0.9250 - val_loss: 0.3125 - val_binary_accuracy: 0.8943
Epoch 30/50
80/80 [=============] - 8s 102ms/step - loss: 0.1833 - binary_accuracy:
0.9298 - val_loss: 0.2848 - val_binary_accuracy: 0.8976
Epoch 31/50
80/80 [============= ] - 8s 103ms/step - loss: 0.1669 - binary accuracy:
```

```
0.9334 - val loss: 0.2879 - val binary accuracy: 0.8963
Epoch 32/50
80/80 [=========== ] - 8s 102ms/step - loss: 0.1635 - binary accuracy:
0.9365 - val_loss: 0.3020 - val_binary_accuracy: 0.8978
Epoch 33/50
80/80 [============ ] - 8s 102ms/step - loss: 0.1565 - binary accuracy:
0.9369 - val loss: 0.2877 - val binary accuracy: 0.9014
Epoch 34/50
80/80 [=============== ] - 8s 102ms/step - loss: 0.1673 - binary_accuracy:
0.9361 - val loss: 0.2523 - val binary accuracy: 0.8994
Epoch 35/50
80/80 [================= ] - 8s 103ms/step - loss: 0.1282 - binary_accuracy:
0.9494 - val_loss: 0.2578 - val_binary_accuracy: 0.9101
Epoch 36/50
80/80 [============= ] - 8s 102ms/step - loss: 0.1335 - binary accuracy:
0.9457 - val_loss: 0.3427 - val_binary_accuracy: 0.8919
Epoch 37/50
80/80 [=============== ] - 8s 102ms/step - loss: 0.1167 - binary_accuracy:
0.9525 - val loss: 0.4436 - val binary accuracy: 0.8759
Epoch 38/50
80/80 [============ ] - 8s 103ms/step - loss: 0.1213 - binary accuracy:
0.9517 - val_loss: 0.3794 - val_binary_accuracy: 0.8893
Epoch 39/50
80/80 [=========== ] - 8s 102ms/step - loss: 0.1214 - binary accuracy:
0.9533 - val_loss: 0.3652 - val_binary_accuracy: 0.8923
Epoch 40/50
80/80 [===============] - 8s 102ms/step - loss: 0.1066 - binary_accuracy:
0.9578 - val loss: 0.3048 - val binary accuracy: 0.9028
Epoch 41/50
80/80 [============ ] - 8s 103ms/step - loss: 0.1270 - binary accuracy:
0.9486 - val_loss: 0.3206 - val_binary_accuracy: 0.8913
Epoch 42/50
80/80 [============ ] - 8s 102ms/step - loss: 0.0995 - binary accuracy:
0.9640 - val_loss: 0.3957 - val_binary_accuracy: 0.8820
Epoch 43/50
80/80 [=========== ] - 8s 102ms/step - loss: 0.0859 - binary accuracy:
0.9658 - val_loss: 0.2507 - val_binary_accuracy: 0.9226
Epoch 44/50
80/80 [=========== ] - 8s 102ms/step - loss: 0.0951 - binary accuracy:
0.9637 - val_loss: 0.3799 - val_binary_accuracy: 0.9028
80/80 [=========== ] - 8s 103ms/step - loss: 0.0875 - binary accuracy:
0.9658 - val_loss: 0.3453 - val_binary_accuracy: 0.9046
Epoch 46/50
80/80 [============] - 8s 102ms/step - loss: 0.0843 - binary_accuracy:
0.9666 - val_loss: 0.2881 - val_binary_accuracy: 0.9097
Epoch 47/50
80/80 [===========] - 8s 102ms/step - loss: 0.0938 - binary_accuracy:
0.9644 - val_loss: 0.3398 - val_binary_accuracy: 0.9002
Epoch 48/50
80/80 [============= ] - 8s 103ms/step - loss: 0.0771 - binary accuracy:
0.9685 - val loss: 0.3514 - val binary accuracy: 0.9073
Epoch 49/50
80/80 [============= ] - 8s 102ms/step - loss: 0.0774 - binary accuracy:
0.9705 - val_loss: 0.4036 - val_binary_accuracy: 0.8941
Epoch 50/50
80/80 [============= ] - 8s 102ms/step - loss: 0.0821 - binary accuracy:
0.9695 - val_loss: 0.3795 - val_binary_accuracy: 0.8986
```



4) Train Model

Examine the training curves. What there any sign of overfitting? How does the performance of this model compare to other models you've trained in this course?

```
In [10]: # View the solution (Run this code cell to receive credit!)
q_4.solution()
```

Solution: The learning curves in this model stayed close together for much longer than in previous models. This suggests that the augmentation helped prevent overfitting, allowing the model to continue improving.

And notice that this model achieved the highest accuracy of all the models in the course! This won't always be the case, but it shows that a well-designed custom convnet can sometimes perform as well or better than a much larger pretrained model. Depending on your application, having a smaller model (which requires fewer resources) could be a big advantage.

Conclusion

Data augmentation is a powerful and commonly-used tool to improve model training, not only for convolutional networks, but for many other kinds of neural network models as well. Whatever your problem, the principle remains the same: you can make up for an inadequacy in your data by adding in "fake" data to cover it over. Experimenting with augmentations is a great way to find out just how far your data can go!

The End

That's all for **Computer Vision** on Kaggle Learn! Are you ready to apply your knowledge? Check out our two bonus lessons! They'll walk you through preparing a submission for a competition while you learn how to train neural nets with TPUs, Kaggle's most advanced accelerator. At the end, you'll have a complete notebook ready to extend with ideas of your own.

- Create Your First Submission Prepare a submission for our *Petals to the Metal* Getting Started competition. You'll train a neural net to recognize over 100 species of flowers.
- Cassava Leaf Disease Rather compete for money and medals? Train a neural net to diagnose common diseases in the cassava plant, a staple security crop in Africa.

Have fun learning!

Have questions or comments? Visit the course discussion forum to chat with other learners.