This is a companion notebook for the book <u>Deep Learning with Python, Second Edition</u>. For readability, it only contains runnable code blocks and section titles, and omits everything else in the book: text paragraphs, figures, and pseudocode.

If you want to be able to follow what's going on, I recommend reading the notebook side by side with your copy of the book.

This notebook was generated for TensorFlow 2.6.

Introduction to deep learning for computer vision

Introduction to convnets

Instantiating a small convnet

```
from tensorflow import keras
from tensorflow.keras import layers
inputs = keras.Input(shape=(28, 28, 1))
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu")(inputs)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=64, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.Flatten()(x)
outputs = layers.Dense(10, activation="softmax")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
```

Displaying the model's summary

```
model.summary()
```

Model: "model"

Layer (type)	Output Shape	Param #
input_1 (InputLayer)	[(None, 28, 28, 1)]	0
conv2d (Conv2D)	(None, 26, 26, 32)	320
<pre>max_pooling2d (MaxPooling2D)</pre>	(None, 13, 13, 32)	0
conv2d_1 (Conv2D)	(None, 11, 11, 64)	18496
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	(None, 5, 5, 64)	0

Training the convnet on MNIST images

Evaluating the convnet

▼ The convolution operation

Understanding border effects and padding

Understanding convolution strides

▼ The max-pooling operation

An incorrectly structured convnet missing its max-pooling layers

```
inputs = keras.Input(shape=(28, 28, 1))
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu")(inputs)
x = layers.Conv2D(filters=64, kernel_size=3, activation="relu")(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.Flatten()(x)
outputs = layers.Dense(10, activation="softmax")(x)
model_no_max_pool = keras.Model(inputs=inputs, outputs=outputs)
```

model_no_max_pool.summary()

Model: "model 1"

Layer (type)	Output Shape	Param #
input_2 (InputLayer)	[(None, 28, 28, 1)]	0
conv2d_3 (Conv2D)	(None, 26, 26, 32)	320
conv2d_4 (Conv2D)	(None, 24, 24, 64)	18496
conv2d_5 (Conv2D)	(None, 22, 22, 128)	73856
flatten_1 (Flatten)	(None, 61952)	0
dense_1 (Dense)	(None, 10)	619530

Trainable params: 712,202 Non-trainable params: 0

▼ Training a convnet from scratch on a small dataset

The relevance of deep learning for small-data problems

Downloading the data

```
from google.colab import files
files.upload()
     Choose files kaggle.json
    • kaggle.json(application/json) - 64 bytes, last modified: 05/11/2022 - 100% done
    Saving kaggle.json to kaggle.json
    { 'kaggle.json':
    b'{"username":"ribakhan"."kev":"2cb4a7bc3a38aecc4d227f3f9ae26a8b"}'}
!mkdir ~/.kaggle
!cp kaggle.json ~/.kaggle/
!chmod 600 ~/.kaggle/kaggle.json
!kaggle competitions download -c dogs-vs-cats
    Downloading dogs-vs-cats.zip to /content
    100% 811M/812M [00:20<00:00, 42.2MB/s]
    100% 812M/812M [00:20<00:00, 40.9MB/s]
!unzip -qq dogs-vs-cats.zip
!unzip -qq train.zip
```

→ Question-1

Consider the Cats & Dogs example. Start initially with a training sample of 1000, a validation sample of 500, and a test sample of 500 (like in the text). Use any technique to reduce overfitting and improve performance in developing a network that you train from scratch. What performance did you achieve?

Creating a convolutional network. Here we are diving the data into test, train and validation as mentioned in the question.

```
import os, shutil, pathlib
original dir = pathlib.Path("train")
new_base_dir = pathlib.Path("cats_vs_dogs_small")
def make_subset(subset_name, start_index, end_index):
    for category in ("cat", "dog"):
        dir = new base dir / subset name / category
        os.makedirs(dir)
        fnames = [f"{category}.{i}.jpg" for i in range(start index, end index)]
        for fname in fnames:
            shutil.copyfile(src=original_dir / fname,
                            dst=dir / fname)
make_subset("test", start_index=0, end_index=500)
```

```
make_subset("validation", start_index=500, end_index=1000)
make_subset("train", start_index=1000, end_index=2000)
```

▼ Building the model

Instantiating a small convnet for dogs vs. cats classification

```
from tensorflow import keras
from tensorflow.keras import layers
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
```

model.summary()

Model: "model 3"

-		
Layer (type)	Output Shape	Param #
input_4 (InputLayer)	[(None, 180, 180, 3)]	0
rescaling_1 (Rescaling)	(None, 180, 180, 3)	0
conv2d_11 (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d_6 (MaxPooling 2D)</pre>	(None, 89, 89, 32)	0
conv2d_12 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_7 (MaxPooling 2D)</pre>	(None, 43, 43, 64)	0
conv2d_13 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_8 (MaxPooling 2D)</pre>	(None, 20, 20, 128)	0
conv2d_14 (Conv2D)	(None, 18, 18, 256)	295168

```
max_pooling2d_9 (MaxPooling (None, 9, 9, 256) 0
2D)

conv2d_15 (Conv2D) (None, 7, 7, 256) 590080

flatten_3 (Flatten) (None, 12544) 0

dense_3 (Dense) (None, 1) 12545

Total params: 991,041
Trainable params: 991,041
Non-trainable params: 0
```

Total parameteres turned out to be 991,041. Parameters in general are weights that are learnt during training.

Configuring the model for training

Data preprocessing

Using image_dataset_from_directory to read images

Modifying the images to tensors.

```
from tensorflow.keras.utils import image dataset from directory
train dataset = image dataset from directory(
    new base dir / "train",
    image size=(180, 180),
   batch size=32)
validation dataset = image dataset from directory(
    new_base_dir / "validation",
    image_size=(180, 180),
   batch_size=32)
test dataset = image dataset from directory(
   new base dir / "test",
   image_size=(180, 180),
   batch size=32)
    Found 2000 files belonging to 2 classes.
    Found 1000 files belonging to 2 classes.
    Found 1000 files belonging to 2 classes.
```

```
import numpy as np
import tensorflow as tf
random numbers = np.random.normal(size=(1000, 16))
dataset = tf.data.Dataset.from tensor slices(random numbers)
for i, element in enumerate(dataset):
   print(element.shape)
    if i >= 2:
       break
    (16,)
    (16,)
    (16,)
batched dataset = dataset.batch(32)
for i, element in enumerate(batched dataset):
   print(element.shape)
   if i >= 2:
       break
    (32, 16)
    (32, 16)
    (32, 16)
reshaped_dataset = dataset.map(lambda x: tf.reshape(x, (4, 4)))
for i, element in enumerate(reshaped dataset):
    print(element.shape)
   if i >= 2:
       break
    (4, 4)
    (4, 4)
```

Displaying the shapes of the data and labels yielded by the Dataset

```
for data_batch, labels_batch in train_dataset:
    print("data batch shape:", data_batch.shape)
    print("labels batch shape:", labels_batch.shape)
    break

data batch shape: (32, 180, 180, 3)
    labels batch shape: (32,)
```

Fitting the model using a Dataset

(4, 4)

The reason we are using "callbacks" here is beacuse Callbacks can help prevent overfitting, visualize training progress and create a TensorBoard, etc. In order to avoid having to retrain the

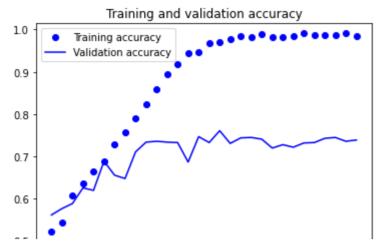
```
callbacks = [
 keras.callbacks.ModelCheckpoint(
   filepath="convnet from scratch.keras",
   save best only=True,
   monitor="val loss")
history = model.fit(
 train dataset,
 epochs=30,
 validation data=validation dataset,
 callbacks=callbacks)
 110011 2/JU
 63/63 [============] - 5s 72ms/step - loss: 0.6967 - accurac
 Epoch 3/30
 63/63 [============== ] - 5s 71ms/step - loss: 0.6758 - accurac
 Epoch 4/30
 Epoch 5/30
 Epoch 6/30
 Epoch 7/30
 63/63 [============== ] - 5s 71ms/step - loss: 0.5405 - accurac
 Epoch 8/30
 Epoch 9/30
 Epoch 10/30
 Epoch 11/30
 Epoch 12/30
 Epoch 13/30
 Epoch 14/30
 Epoch 15/30
 Epoch 16/30
 63/63 [============] - 5s 71ms/step - loss: 0.0906 - accurac
 Epoch 17/30
 Epoch 18/30
 63/63 [============== ] - 5s 71ms/step - loss: 0.0687 - accurac
 Epoch 19/30
 Epoch 20/30
 Epoch 21/30
 Epoch 22/30
 63/63 [============== ] - 6s 86ms/step - loss: 0.0486 - accurac
```

```
Epoch 23/30
63/63 [============= ] - 5s 71ms/step - loss: 0.0557 - accurac
Epoch 24/30
63/63 [============== ] - 5s 72ms/step - loss: 0.0490 - accurac
Epoch 25/30
Epoch 26/30
Epoch 27/30
Epoch 28/30
Epoch 29/30
Epoch 30/30
63/63 [============== ] - 5s 73ms/step - loss: 0.0496 - accurac
```

Validation accuracy 73%.

Displaying curves of loss and accuracy during training

```
import matplotlib.pyplot as plt
accuracy = history.history["accuracy"]
val accuracy = history.history["val accuracy"]
loss = history.history["loss"]
val loss = history.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, "bo", label="Training accuracy")
plt.plot(epochs, val accuracy, "b", label="Validation accuracy")
plt.title("Training and validation accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, "bo", label="Training loss")
plt.plot(epochs, val_loss, "b", label="Validation loss")
plt.title("Training and validation loss")
plt.legend()
plt.show()
```



Evaluating the model on the test set

The accuracy turns out to be 74% which is not fairly very high. Next I will perform additional steps to improve model performance.

```
0 5 10 15 20 25 20
```

Now, in order to improve model performance I will use the dropout method. Using a dropout layer of 0.5

Including dropout in a new convent

```
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=64, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
```

Compiling model

Now training the convent

Here, i am using only 50 epochs due to time constraint.

```
callbacks = [
   keras.callbacks.ModelCheckpoint(
      filepath="convnet from scratch with dropout.keras",
      save best only=True,
      monitor="val loss")
 history = model.fit(
   train dataset,
   epochs=50,
   validation data=validation dataset,
   callbacks=callbacks)
    Epoch 22/50
    63/63 [============== ] - 5s 73ms/step - loss: 0.0831 - accurac
    Epoch 23/50
    Epoch 24/50
    Epoch 25/50
    Epoch 26/50
    63/63 [============== ] - 5s 73ms/step - loss: 0.0357 - accurac
    Epoch 27/50
    Epoch 28/50
    Epoch 29/50
    Epoch 30/50
    63/63 [============] - 5s 72ms/step - loss: 0.0688 - accurac
    Epoch 31/50
    63/63 [============= ] - 5s 72ms/step - loss: 0.0555 - accurac
    Epoch 32/50
    Epoch 33/50
    Epoch 34/50
    63/63 [============= ] - 5s 74ms/step - loss: 0.0785 - accurac
    Epoch 35/50
    63/63 [===============] - 5s 73ms/step - loss: 0.0208 - accurac
    Epoch 36/50
    Epoch 37/50
    63/63 [============== ] - 5s 73ms/step - loss: 0.0443 - accurac
    Epoch 38/50
    https://colab.research.google.com/drive/1Vep_Jr0dAjw4m2lqbvr7xuagVhdWOAdz#scrollTo=4CU6DImAM25i&printMode=true
                                             11/28
```

```
Epoch 39/50
63/63 [============= ] - 6s 89ms/step - loss: 0.0517 - accurac
Epoch 40/50
Epoch 41/50
63/63 [============= ] - 5s 72ms/step - loss: 0.0363 - accurac
Epoch 42/50
Epoch 43/50
63/63 [============== ] - 5s 74ms/step - loss: 0.0420 - accurac
Epoch 44/50
63/63 [============ ] - 6s 87ms/step - loss: 0.0445 - accurac
Epoch 45/50
63/63 [============= ] - 5s 73ms/step - loss: 0.0542 - accurac
Epoch 46/50
63/63 [============= ] - 5s 72ms/step - loss: 0.0492 - accurac
Epoch 47/50
Epoch 48/50
63/63 [============== ] - 5s 73ms/step - loss: 0.0242 - accurac
Epoch 49/50
63/63 [============== ] - 5s 73ms/step - loss: 0.0794 - accurac
Epoch 50/50
63/63 [============= ] - 5s 72ms/step - loss: 0.0274 - accurac
```

Validation accuracy turns out to be 73%

The second method i will be using to improve the model performance is using data augmentaion technique combining with dropout function

including image augmentation and dropout

```
inputs = keras.Input(shape=(180, 180, 3))
x = data_augmentation(inputs)
x = layers.Rescaling(1./255)(x)
```

```
x = layers.Conv2D(filters=32, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.compile(loss="binary crossentropy",
              optimizer="rmsprop",
              metrics=["accuracy"])
```

training the model

I am using only 50 epochs here.

```
callbacks = [
   keras.callbacks.ModelCheckpoint(
      filepath="convnet from scratch with augmentation dropout.keras",
      save best only=True,
      monitor="val loss")
]
history = model.fit(
   train dataset,
   epochs=50,
   validation data=validation dataset,
   callbacks=callbacks)
   Epoch 1/50
   63/63 [============== ] - 8s 99ms/step - loss: 0.8148 - accurac
   Epoch 2/50
   63/63 [============== ] - 6s 95ms/step - loss: 0.6953 - accurac
   Epoch 3/50
   63/63 [============== ] - 6s 97ms/step - loss: 0.6917 - accurac
   Epoch 4/50
   63/63 [============== ] - 7s 108ms/step - loss: 0.6759 - accura
   Epoch 5/50
   63/63 [============== ] - 6s 97ms/step - loss: 0.6769 - accurac
   Epoch 6/50
   63/63 [============== ] - 6s 96ms/step - loss: 0.6278 - accurac
   Epoch 7/50
   63/63 [============= ] - 6s 96ms/step - loss: 0.6102 - accurac
   Epoch 8/50
   63/63 [============== ] - 6s 96ms/step - loss: 0.6065 - accurac
   Epoch 9/50
   Epoch 10/50
```

```
63/63 [============] - 6s 94ms/step - loss: 0.5857 - accurac
Epoch 11/50
Epoch 12/50
Epoch 13/50
Epoch 14/50
63/63 [============= ] - 6s 95ms/step - loss: 0.5160 - accurac
Epoch 15/50
Epoch 16/50
Epoch 17/50
Epoch 18/50
Epoch 19/50
Epoch 20/50
63/63 [============== ] - 7s 104ms/step - loss: 0.4664 - accura
Epoch 21/50
Epoch 22/50
63/63 [============ ] - 6s 95ms/step - loss: 0.4640 - accurac
Epoch 23/50
Epoch 24/50
63/63 [============= ] - 7s 106ms/step - loss: 0.4400 - accura
Epoch 25/50
63/63 [============== ] - 6s 93ms/step - loss: 0.4389 - accurac
Epoch 26/50
63/63 [============= ] - 6s 93ms/step - loss: 0.4089 - accurac
Epoch 27/50
Epoch 28/50
63/63 [============= ] - 6s 94ms/step - loss: 0.4067 - accurac
Epoch 29/50
```

Validation accuracy turns out to be 81% which is improved by 8% than before.

Question 2

Increase your training sample size. You may pick any amount. Keep the validation and test samples the same as above. Optimize your network (again training from scratch). What performance did you achieve?

```
make_subset("train3", start_index=1000, end_index=6000)

train_dataset_3 = image_dataset_from_directory(
    new_base_dir / "train3",
    image_size=(180, 180),
    batch_size=32)
```

Found 10000 files belonging to 2 classes.

I have increased the training sample size to 5000.

```
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.compile(loss="binary crossentropy",
              optimizer="rmsprop",
              metrics=["accuracy"])
```

Training the regularized convent. I am using 60 epochs here.

```
callbacks = [
 keras.callbacks.ModelCheckpoint(
  filepath="convnet from scratch.keras",
  save best only=True,
  monitor="val loss")
1
history = model.fit(
 train dataset 3,
 epochs=70,
 validation data=validation dataset,
 callbacks=callbacks)
 Epoch 42//0
 Epoch 43/70
 Epoch 44/70
 Epoch 45/70
 Epoch 46/70
 Epoch 47/70
 Epoch 48/70
 Epoch 49/70
 15/28
```

```
JIJ/JIJ [-----
      - 225 /IMS/SCCP - IOSS. V.IJIJ - acct
Epoch 50/70
Epoch 51/70
Epoch 52/70
Epoch 53/70
Epoch 54/70
Epoch 55/70
Epoch 56/70
Epoch 57/70
Epoch 58/70
Epoch 59/70
Epoch 60/70
Epoch 61/70
Epoch 62/70
Epoch 63/70
Epoch 64/70
Epoch 65/70
Epoch 66/70
Epoch 67/70
Epoch 68/70
Epoch 69/70
Epoch 70/70
```

Validation accuracy turns out to be 88%

Checking the model accuracy

```
test_model = keras.models.load_model(
    "convnet_from_scratch3.keras")
test_loss, test_acc = test_model.evaluate(test_dataset)
print(f"Test accuracy: {test_acc:.3f}")
```

Question 3: Now change your training sample so that you achieve better performance than those from Steps 1 and 2. This sample size may be larger, or smaller than those in the previous steps. The objective is to find the ideal training sample size to get best prediction results.

```
#import shutil
#shutil.rmtree('/content/cats_vs_dogs_small/train2')

make_subset("train2", start_index=1000, end_index=11000)

train_dataset2 = image_dataset_from_directory(
    new_base_dir / "train2",
    image_size=(180, 180),
    batch_size=32)
```

Found 20000 files belonging to 2 classes.

```
from tensorflow import keras
from tensorflow.keras import layers
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
\#x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.compile(loss="binary crossentropy",
              optimizer="rmsprop",
              metrics=["accuracy"])
```

```
callbacks = [
    keras.callbacks.ModelCheckpoint(
        filepath="convnet_from_scratch_test3.keras",
        save_best_only=True,
        monitor="val_loss")
]
history = model.fit(
    train_dataset_3,
    epochs=50,
```

validation_data=validation_dataset, callbacks=callbacks)

```
Epoch 22/50
Epoch 23/50
Epoch 24/50
Epoch 25/50
Epoch 26/50
Epoch 27/50
Epoch 28/50
Epoch 29/50
Epoch 30/50
Epoch 31/50
Epoch 32/50
Epoch 33/50
Epoch 34/50
Epoch 35/50
Epoch 36/50
Epoch 37/50
Epoch 38/50
Epoch 39/50
Epoch 40/50
Epoch 41/50
Epoch 42/50
Epoch 43/50
Epoch 44/50
Epoch 45/50
Epoch 46/50
Epoch 47/50
Epoch 48/50
Epoch 49/50
Epoch 50/50
212/212 r---
      21c 65mc/c+on
        1000 1 0000
```

Check model accuracy

313/313 1-----

```
test model = keras.models.load model(
    "convnet from scratch test3.keras")
test loss, test acc = test model.evaluate(test dataset)
print(f"Test accuracy: {test acc:.3f}")
    32/32 [============= ] - 2s 37ms/step - loss: 0.4147 - accurac
    Test accuracy: 0.834
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.compile(loss="binary_crossentropy",
             optimizer="rmsprop",
             metrics=["accuracy"])
```

Training regularized convent

```
023/023 [------
         - JTB JTMB/BUCP - 1088. 0.3323 - accu
Epoch 4/30
Epoch 5/30
Epoch 6/30
Epoch 7/30
Epoch 8/30
Epoch 9/30
625/625 [=============] - 34s 54ms/step - loss: 0.1672 - accu
Epoch 10/30
Epoch 11/30
Epoch 12/30
625/625 [=============] - 34s 54ms/step - loss: 0.1540 - accu
Epoch 13/30
Epoch 14/30
Epoch 15/30
Epoch 16/30
Epoch 17/30
Epoch 18/30
Epoch 19/30
625/625 [===========] - 34s 54ms/step - loss: 0.1679 - accu
Epoch 20/30
Epoch 21/30
Epoch 22/30
Epoch 23/30
Epoch 24/30
Epoch 25/30
Epoch 26/30
Epoch 27/30
Epoch 28/30
Epoch 29/30
Epoch 30/30
```

Now evelauting the test data

```
test_model = keras.models.load_model(
    "convnet_from_scratch2.keras")
test_loss, test_acc = test_model.evaluate(test_dataset)
print(f"Test accuracy: {test_acc:.3f}")
```

Question 4: Repeat Steps 1-3, but now using a pretrained network. The sample sizes you use in Steps 2 and 3 for the pretrained network may be the same or different from those using the network where you trained from scratch. Again, use any and all optimization techniques to get best performance.

Using pre trained model. Using the VGG16 convolution base. Here using 1000 samples.

```
conv_base = keras.applications.vgg16.VGG16(
    weights="imagenet",
    include_top=False,
    input_shape=(180, 180, 3))
```

```
conv_base.summary()
```

Model: "vgg16"

Layer (type)	Output Shape	 Param #
		========
<pre>input_11 (InputLayer)</pre>	[(None, 180, 180, 3)]	0
block1_conv1 (Conv2D)	(None, 180, 180, 64)	1792
block1_conv2 (Conv2D)	(None, 180, 180, 64)	36928
block1_pool (MaxPooling2D)	(None, 90, 90, 64)	0
block2_conv1 (Conv2D)	(None, 90, 90, 128)	73856
block2_conv2 (Conv2D)	(None, 90, 90, 128)	147584
<pre>block2_pool (MaxPooling2D)</pre>	(None, 45, 45, 128)	0
block3_conv1 (Conv2D)	(None, 45, 45, 256)	295168
block3_conv2 (Conv2D)	(None, 45, 45, 256)	590080
block3_conv3 (Conv2D)	(None, 45, 45, 256)	590080
<pre>block3_pool (MaxPooling2D)</pre>	(None, 22, 22, 256)	0
block4_conv1 (Conv2D)	(None, 22, 22, 512)	1180160

2359808

(None, 22, 22, 512)

block4 conv2 (Conv2D)

```
(None, 22, 22, 512) 2359808
     block4 conv3 (Conv2D)
     block4 pool (MaxPooling2D) (None, 11, 11, 512)
     block5 conv1 (Conv2D)
                                 (None, 11, 11, 512)
                                                          2359808
     block5 conv2 (Conv2D)
                                (None, 11, 11, 512)
                                                           2359808
     block5 conv3 (Conv2D)
                                (None, 11, 11, 512)
                                                           2359808
     block5 pool (MaxPooling2D) (None, 5, 5, 512)
    Total params: 14,714,688
    Trainable params: 14,714,688
    Non-trainable params: 0
conv base = keras.applications.vgg16.VGG16(
   weights="imagenet",
    include top=False)
conv base.trainable = True
for layer in conv base.layers[:-4]:
   layer.trainable = False
data augmentation = keras.Sequential(
        layers.RandomFlip("horizontal"),
        layers.RandomRotation(0.1),
        layers.RandomZoom(0.2),
    ]
)
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation(inputs)
x = keras.applications.vgg16.preprocess input(x)
x = conv base(x)
x = layers.Flatten()(x)
x = layers.Dense(256)(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs, outputs)
model.compile(loss="binary crossentropy",
             optimizer=keras.optimizers.RMSprop(learning rate=1e-5),
             metrics=["accuracy"])
callbacks = [
   keras.callbacks.ModelCheckpoint(
        filepath="fine tuning.keras",
        save best only=True,
```

```
monitor="val loss")
1
history = model.fit(
 train dataset,
 epochs=20,
 validation data=validation dataset,
 callbacks=callbacks)
  Epoch 1/20
  Epoch 2/20
  Epoch 3/20
  Epoch 4/20
  63/63 [============== ] - 14s 217ms/step - loss: 0.3889 - accur
  Epoch 5/20
  Epoch 6/20
  Epoch 7/20
  Epoch 8/20
  63/63 [============== ] - 14s 218ms/step - loss: 0.1453 - accur
  Epoch 9/20
  63/63 [=============] - 14s 225ms/step - loss: 0.1602 - accur
  Epoch 10/20
  Epoch 11/20
  63/63 [============== ] - 14s 222ms/step - loss: 0.1016 - accur
  Epoch 12/20
  63/63 [============== ] - 14s 214ms/step - loss: 0.0856 - accur
  Epoch 13/20
  Epoch 14/20
  63/63 [==============] - 14s 220ms/step - loss: 0.0932 - accur
  Epoch 15/20
  Epoch 16/20
  Epoch 17/20
  Epoch 18/20
  63/63 [============== ] - 15s 227ms/step - loss: 0.0384 - accur
  Epoch 19/20
  63/63 [=============== ] - 14s 213ms/step - loss: 0.0426 - accur
  Epoch 20/20
  model = keras.models.load_model("fine_tuning.keras")
```

```
model = keras.models.load_model("fine_tuning.keras")
test_loss, test_acc = model.evaluate(test_dataset)
print(f"Test accuracy: {test_acc:.3f}")
```

```
32/32 [============== ] - 4s 105ms/step - loss: 0.1480 - accurates accuracy: 0.977
```

Pre trained model - 10000 samples

```
conv_base = keras.applications.vgg16.VGG16(
    weights="imagenet",
    include_top=False,
    input_shape=(180, 180, 3))
```

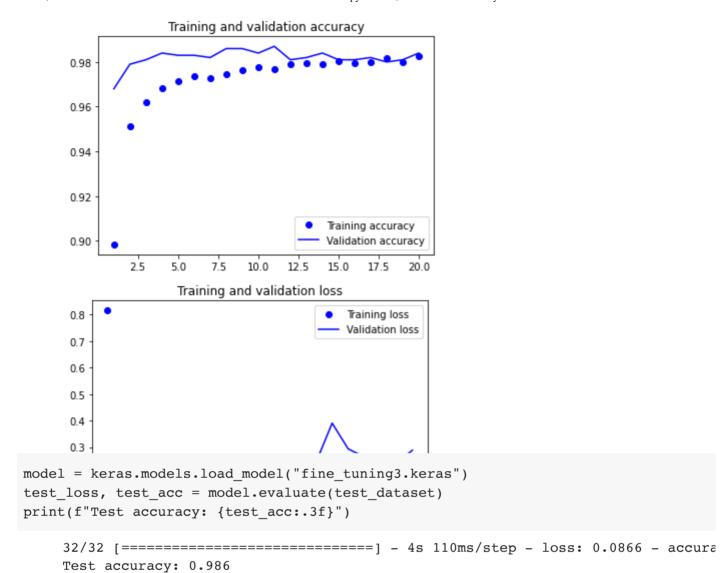
```
conv_base = keras.applications.vgg16.VGG16(
    weights="imagenet",
    include_top=False)

conv_base.trainable = True
for layer in conv_base.layers[:-4]:
    layer.trainable = False
```

```
data augmentation = keras.Sequential(
        layers.RandomFlip("horizontal"),
        layers.RandomRotation(0.1),
        layers.RandomZoom(0.2),
    ]
)
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation(inputs)
x = keras.applications.vgg16.preprocess input(x)
x = conv base(x)
x = layers.Flatten()(x)
x = layers.Dense(256)(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs, outputs)
model.compile(loss="binary_crossentropy",
              optimizer=keras.optimizers.RMSprop(learning rate=1e-5),
              metrics=["accuracy"])
callbacks = [
    keras.callbacks.ModelCheckpoint(
        filepath="fine tuning3.keras",
        save best only=True,
        monitor="val loss")
]
history = model.fit(
   train dataset2,
   epochs=20,
   validation data=validation dataset,
   callbacks=callbacks)
```

```
och 4/20
och 5/20
och 6/20
och 7/20
och 8/20
5/625 [===========] - 104s 165ms/step - loss: 0.0747 - accur
och 9/20
5/625 [============] - 105s 168ms/step - loss: 0.0788 - accur
10/20
och 11/20
och 12/20
och 13/20
och 14/20
15/20
och 16/20
5/625 [============== ] - 103s 165ms/step - loss: 0.0798 - accur
och 17/20
och 18/20
och 19/20
och 20/20
5/625 [=============] - 104s 166ms/step - loss: 0.0734 - accur
```

```
import matplotlib.pyplot as plt
accuracy = history.history["accuracy"]
val accuracy = history.history["val accuracy"]
loss = history.history["loss"]
val loss = history.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, "bo", label="Training accuracy")
plt.plot(epochs, val accuracy, "b", label="Validation accuracy")
plt.title("Training and validation accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, "bo", label="Training loss")
plt.plot(epochs, val_loss, "b", label="Validation loss")
plt.title("Training and validation loss")
plt.legend()
plt.show()
```



→ SUMMARY

Q1) In question 1 the above plots clearly show that the model is facing the overfitting issue. Training accuracy increases gradually until it reaches the highest point. While validation accuracy reaches only 72-76%.

To avoid overfitting, a few techniques can be implemented.

I used the following two techniques to improve the model performance:

- 1) Using a dropout layer of 0.5
- 2) Combining data augmentation technique with dropout

Techniques used	Test Accuracy	Validation Accuracy
Unregularized Model	74%	73%
Model with Dropout Layer	74%	73%
Model with Data	81%	81%
augmentation and dropout		
layer		

Observations from the above table

We can clearly see that test and validation accuracy doesn't show any difference when we used unregularized model and a model with a dropout layer of 0.5. However, the model performance improved by 7% when we used data augmentation with dropout function.

Q2)

In this question, I have increased the training sample to 5000 and a regularized model is used.

Results:

Test loss: 17%

Test accuracy: 87%

Validation accuracy: 88%

In comparison with the unregularized model, the regularized model with the training size of 5000 performs better with higher accuracy.

Q4)

Using a pre-trained model with VGG16 convolution base. Using 1000 samples

Test accuracy: 99%

Validation accuracy: 97%

Using a pre-trained model with 10000 samples

Validation accuracy: 98%

Test accuracy: 98%

Final Conclusion and Recommendations

- Convolutional network-based machine learning models are the best for computer vision.
- Overfitting is the main issue with a tiny dataset. Data augmentation can be a powerful
 tool for preventing overfitting when working with image data. Model performance
 improves when the training sample amount is increased.
- We can use "callbacks" because it prevents overfitting, visualise training progress and create a Tesnorboard. In order to avoid having to retain the model. We employ "callbacks" which will automatically save a file with the weights produced from the best epoch.

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