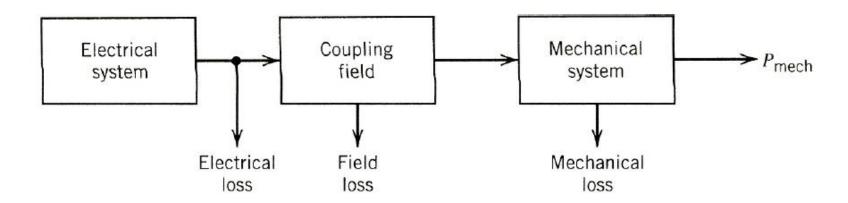
Chapter 2 Electromechanical Energy Conversions

Learning Objectives

- Analyze electromechanical energy conversion based on concepts of energy and coenergy
- Understand operating principles of rotating and cylindrical machines



2.1 Fundamentals

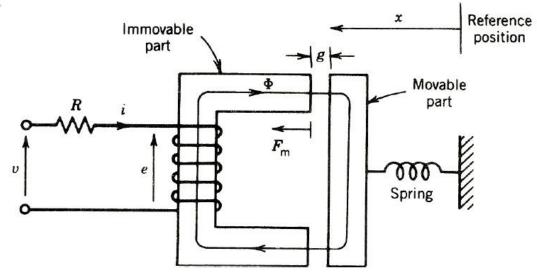


- Based on the principle of conservation of energy, energy can neither be created nor destroyed but changed from one form to another
- Consider a differential time interval

$$dW_e = dW_m + dW_f$$



2.1 Fundamentals



 Consider if the movable part is held stationary at some air gap with current is increased from zero to a value i

$$dW_e = dW_f$$

If core loss is neglected, all incremental electrical energy input is stored as field energy

$$dW_e = eidt dW_f = id\lambda$$



2.1 Fundamentals

Energy stored in the field

$$W_f = \int_0^{\lambda} id\lambda$$

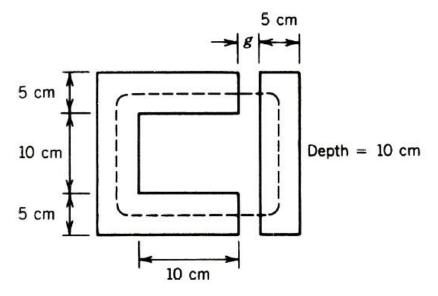
$$= \int \frac{H_c l_c + H_g l_g}{N} NAdB$$

$$= \int \left(H_c dBA l_c + \frac{B}{\mu_0} dB l_g A \right)$$

$$= W_{fc} \times V_c + W_{fg} \times V_g$$

$$= W_{fc} + W_{fg}$$





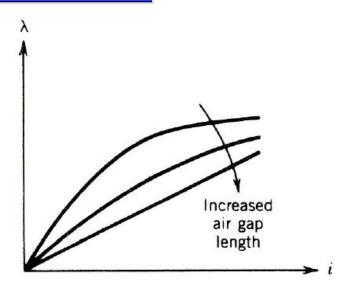
Consider a actuator system as shown above. It consists of coil of 250 turns and coil resistance of 5 Ω . For a fixed air gap length of 5 mm, a dc source is connected to the coil to produce a flux density of 1.0 T in the air gap. Assume the magnetic field intensity of core is a cast steel with flux density of 1.0 T is 670 At/m.

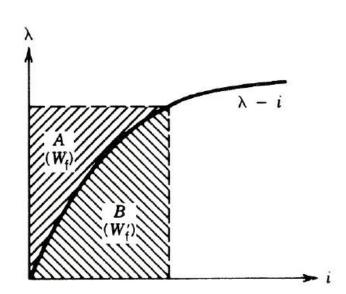
- (a) Find the voltage of the dc source (Ans: 167.2 V)
- (b) Find the stored field energy (Ans: 20.9 J)











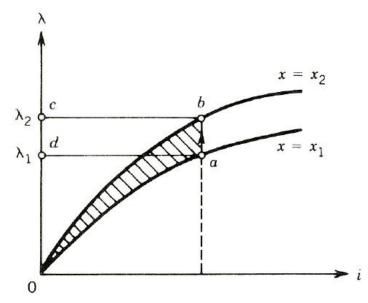
- For larger air gap length, the λi characteristic will become more linear
- The area B is known as coenergy

$$W_f' = \int_0^{\lambda} i d\lambda$$

If it is linear

$$W_f' = W_f = \lambda i$$





If the movable part has moved slowly with current remained constant, the operating point will move upward from point a to b

$$dW_e = \int eidt = \int_{\lambda_1}^{\lambda_2} id\lambda = area \ abcd$$

$$dW_f = area\ 0bc - 0ad$$

$$dW_m = dW_c - dW_f = area\ 0ab$$

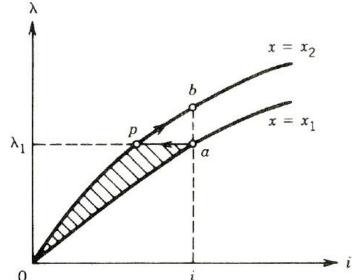


If the motion is under constant-current conditions, the mechanical work done is the incremental part in the coenergy and the mechanical force is

$$f_m dx = dW_m = W_f'$$

$$f_m = \frac{\partial W_f'(i, x)}{\partial x} \Big|_{i=constant}$$





- If the movement is very quick and it can be assumed the flux linkage is constant
- The mechanical work done is shown in area 0ap, which is decreased part in field energy

$$f_m dx = dW_m = W_f$$

$$f_m = \frac{\partial W_f(\lambda, x)}{\partial x}$$

If the displacement is small, areas 0ab of both cases are equal so as the force



The $\lambda - i$ relationship of an electromagnetic system is given as

$$i = \left(\frac{\lambda g}{0.09}\right)^2$$

Given that it is valid for the limits 0 < i < 4 A and 3 < g < 10 cm. For current i = 3 A and air gap length g = 5 cm. Find the mechanical force on the moving part, by using energy and coenergy of the field (Ans: - 124.7 Nm; - 124.7 Nm)







In the reluctance of the magnetic core path is negligible as compared to that of the air gap path, the λ – i relation becomes linear

$$\lambda = L(x)i$$

$$W_f = \int_0^{\lambda} \frac{\lambda}{L(x)} d\lambda$$

$$= \frac{1}{2} L(x)i^2$$

$$f_m = -\frac{\partial}{\partial x} \left(\frac{\lambda^2}{2L(x)} \right) \Big|_{\lambda = constan}$$

$$= \frac{1}{2} i^2 \frac{dL(x)}{dx}$$



For linear system

$$W_f = W_f' = \frac{1}{2}L(x)i^2$$

$$f_m = \frac{\eth}{\partial x} \left(\frac{1}{2}L(x)i^2 \right) \Big|_{i=constan}$$

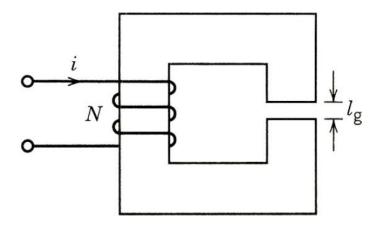
$$= \frac{1}{2}i^2 \frac{dL(x)}{dx}$$

If the reluctance of the magnetic core path is negligible

$$Ni = H_g 2g = \frac{B_g}{\mu_0} 2g$$

$$f_m = \frac{B_g^2}{2\mu_0} \left(2A_g \right)$$





Consider a magnetic system as shown above. It consists of coil of 500 turns, current of 2 A, width of air gap of 2.0 cm, depth of air gap of 2.0 cm and length of air gap of 1 mm. Neglect the reluctance of the core, leakage flux and fringing flux.

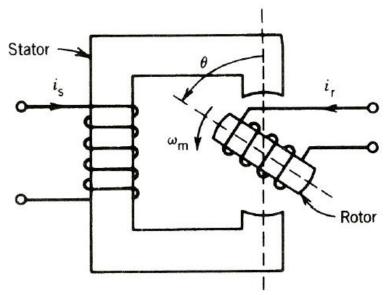
- (a) Find the force of attraction between both sides of the air gap (Ans: 251.3 N)
- (b) Find the energy stored in the air gap (Ans: 0.251 J)







2.3 Rotating Machine



- Consider a rotating electromagnetic system that consists of both stator and rotor with winding carrying currents
- Assume the stored field energy is kept as static, i.e., no mechanical output

$$dW_f = e_S i_S dt + e_r i_r dt$$
$$= i_S d\lambda_S + i_r d\lambda_r$$



2.3 Rotating Machine

For a linear magnetic system

$$\lambda_{S} = L_{SS}i_{S} + L_{Sr}i_{r}$$

$$\lambda_r = L_{rs}i_s + L_{rr}i_r$$

As a matrix form

$$\begin{vmatrix} \lambda_s \\ \lambda_r \end{vmatrix} = \begin{vmatrix} L_{ss} & L_{sr} \\ L_{sr} & L_{rr} \end{vmatrix} \quad \begin{vmatrix} i_s \\ i_r \end{vmatrix}$$

Hence

$$dW_r = i_S d(L_{SS}i_S + L_{Sr}i_r) + i_r d(L_{Sr}i_S + L_{rr}i_r)$$
$$= L_{SS}i_S di_S + L_{rr}i_r di_r + L_{Sr}d(i_Si_r)$$



2.3 Rotating Machine

The field energy

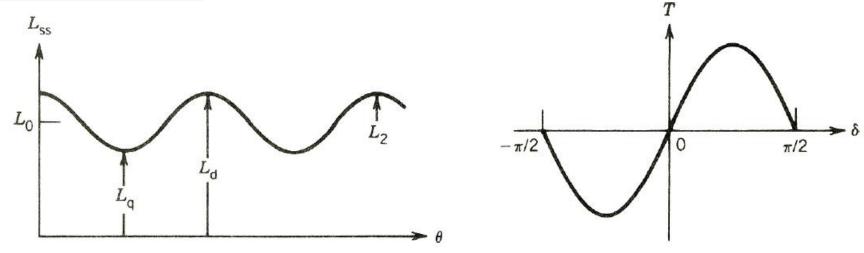
$$W_f = L_{SS} \int_0^{i_S} i_S \, di_S + L_{rr} \int_0^{i_r} i_r \, di_r + L_{Sr} \int_0^{i_S, i_r} d \, (i_S i_r)$$

$$= \frac{1}{2} L_{SS} i_S^2 + \frac{1}{2} L_{rr} i_r^2 + L_{Sr} i_S i_r$$

In a linear magnetic system, energy and coenergy are the same

$$T = \frac{\partial W_f'(i,\theta)}{\partial \theta} \bigg|_{i=constant}$$
$$= \frac{1}{2} i_s^2 \frac{dL_{ss}}{d\theta} + \frac{1}{2} i_r^2 \frac{dL_{rr}}{d\theta} + i_s i_r \frac{dL_{sr}}{d\theta}$$





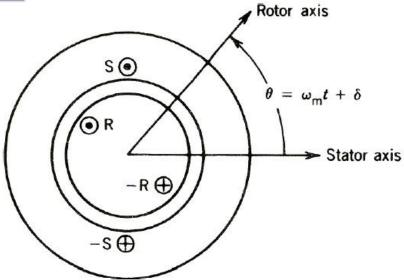
Consider an electromagnetic system whose rotor consists of no winding, i.e., it is a reluctance motor. Its stator current is $i_s = I_{sm} \sin \omega t$ with stator inductance is as a function of the rotor position as $L_{ss} = L_0 + L_2 \cos 2\theta$, as shown above.

- (a) Find an expression for the torque acting on the rotor (Ans: $T = -I_{sm}^2 L_2 \sin 2\theta \sin^2 \omega t$)
- (b) Let $\theta = \omega_m t + \delta$, find the condition for nonzero average torque and also an expression for the torque (Ans: 0; $T_{ava} = -1/4 I_{sm}^2 (L_d L_a) \sin 2\delta$; $\pm \omega$; $T_{ava} = 1/8 I_{sm}^2 (L_d L_a) \sin 2\delta$)









- If the effects of the slots are neglected, the reluctance of the magnetic path is independent of the position of the rotor
- Self-inductances are constant and no reluctance torque is produced
- The mutual inductance varies with position, and the produced torque becomes

$$T = i_S i_r \frac{dL_{ST}}{d\theta}$$



Assume

$$L_{sr} = Mcos\theta$$
 $i_r = I_{rm}cos(\omega_r t + \alpha)$ $i_s = I_{sm}cos\omega_s t$ $\theta = \omega_m t + \delta$

Torque becomes

$$T = -I_{sm}I_{rm}\cos(\omega_{s}t)\cos(\omega_{r}t + \alpha)\sin(\omega_{m}t + \delta)$$

$$= -\frac{I_{sm}I_{rm}M}{4}\left[\sin\{(\omega_{m} + (\omega_{s} + \omega_{r}))t + \alpha + \delta\}\right]$$

$$+\sin\{(\omega_{m} - (\omega_{s} + \omega_{r}))t - \alpha + \delta\}$$

$$+\sin\{(\omega_{m} + (\omega_{s} - \omega_{r}))t - \alpha + \delta\}$$

$$+\sin\{(\omega_{m} - (\omega_{s} - \omega_{r}))t + \alpha + \delta\}$$



Average torque becomes nonzero when

$$\omega_m = \pm (\omega_s \pm \omega_r)$$

• Consider when $\omega_r = 0$, $\alpha = 0$, $\omega_m = \omega_s$

$$T = -\frac{I_{sm}I_{R}M}{2}\{\sin(2\omega_{s}t + \delta) + \sin\delta\}$$

$$T_{avg} = -\frac{I_{sm}I_{R}M}{2}sin\delta$$

- When the machine is operated under synchronous speed, it can develop an average unidirectional torque
- Even it can develop an average torque, it produce a pulsating value



Consider when $\omega_m = \omega_s - \omega_r$, the machine is operated at an asynchronous speed

$$T = -\frac{I_{sm}I_{rm}M}{4}\sin(2\omega_s t + \alpha + \delta) + \sin(-2\omega_r t - \alpha + \delta)$$
$$+[\sin(2\omega_s t - 2\omega_r t - \alpha + \delta) + \sin(\alpha + \delta)]$$
$$T_{avg} = -\frac{I_{sm}I_{rm}M}{4}\sin(\alpha + \delta)$$

- This is the fundamental operation of an induction machine
- No average torque is produced at $\omega_m = 0$
- It can produce average torque when speed is brought up to $\omega_m = \omega_s \omega_r$