ECE385 Spring 2023 – Lab 4 Report

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Introduction

The multiplier in this lab takes two 8-bit 2's-complement signed integers and outputs the 16-bit product. It performs in-place operations with an FSM to control the "shift," "add," and "subtract" actions. The product has its higher 8 bits masked out if reused as operand.

Reworked Example

State	Х	Α	В	М
MASK	0	0000 0000	00000111	1
ADD1	1	1100 0101	00000111	1
SHIFT1	1	1110 0010	1 0000011	1
ADD2	1	1010 0111	1 0000011	1
SHIFT2	1	1101 0011	11 000001	1
ADD3	1	1001 1000	11 000001	1
SHIFT3	0	1100 1100	011 00000	0
SHIFT4	0	1110 0110	0011 0000	0
SHIFT5	0	1111 0011	00011 000	0
SHIFT6	0	1111 1001	100011 00	0
SHIFT7	0	1111 1100	1100011 0	0
SHIFT8	0	1111 1110	01100011	1

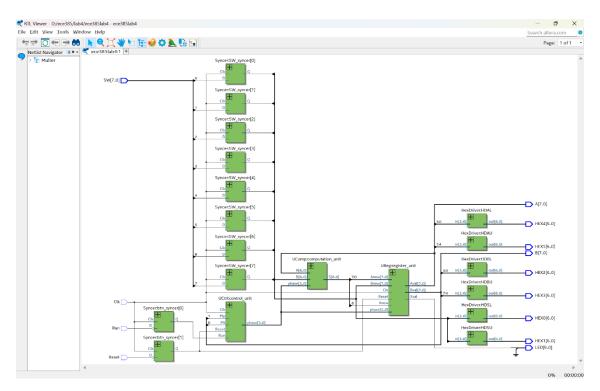
Operating the Multiplier

There are two buttons on the FPGA board, namely Reset and Run. The user first flips the SWitches to the desired B value and presses Reset, at which signal the multiplier (1) clears register A, (2) loads SW into B, and (3) resets the FSM to STOP state. The user then sets SW to the desired A and presses Run, where the multiplier (1) initiates the operation, (2) performs $10\sim17$ state transitions depending on the M value after each register shift, and (3) pauses at DONE state until the user releases Run. Reset overrides Run when both buttons are pressed.

In order to save memory, the multiplier adopts a modified version of the Grade School Multiplication algorithm that adds and shifts the registers in place.

- Shifts: All shifts are arithmetic where XAB is viewed as a 17-bit number that is, XAB <- SEXT(XAB[16:1]). The least significant bit of B is simply dropped.
- Arithmetic operations: A and (synchronized) SW are sign-extended before entering the 9-bit adder, whose output routes to {X, A} and the carry bit is discarded.
- State transitions: If M (a.k.a. B[0]) is 1 by the end of SHIFTi, the FSM moves into ADDi (0 < i < 7) or SUB (i = 7). This indicates that a shifted addend is "written" on the imaginary "paper." Otherwise, the next state will be SHIFT(i+1).

Two FSM states deserve additional explanations. SUB is in the position of a non-existent "ADD8" since the operands are signed integers and the result should be subtracted in case the highest bit of B is 1, indicating a negative number. MASK takes over the action of "clearing register A" from DONE since the machine stays in DONE most of the time and displays the 16-bit product, whose higher bits should not be masked. Instead, the machine forcefully clears A each time it initiates a new operation cycle of multiplication.



Top-level block diagram, generated by the RTL Viewer of Quartus Prime 18.1 Lite

SystemVerilog Modules (Array sizes are abbreviated. E.g., [7:0] is written as [8])

FullAdder Inputs: A B Ci

Outputs: S Co

Description: Standard 1-bit full adder.

Outputs: Xval Aval[8] Bval[8]

Description: At posedge of Clk, {Xval, Aval, Bval} are updated into

• (if Reset) {0, 8'h0, Bnew} ("Clear-and-Load")

• (if Mask) {0, 8'h0, Bval} (only B retains)

• (if Shift) {X, {X, A[7:1]}, {A[0], B[7:1]}}

• (if Add or Sub) {Xnew, Anew, Bval}

Mask, Shift, Add, Sub are encoded in the 4 bits of phase.

These control signals are programmed to be one-hot.

Purpose: Register unit that manages the operands and results.

uComp Inputs: A[9] B[9] phase[4]

Outputs: S[9]

Description: Performs parallel addition and outputs the result. Has built-

in XOR gates that reverse B if phase = Sub. The Sub bit is

also inputted into Ci to perform subtraction when requested.

Purpose: Computation unit that provides updated values for X and A.

uCtrl Inputs: Mp Mt Run Reset Clk

Outputs: phase[4]

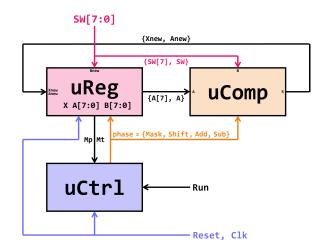
Description: Implements the FSM that gives the proper phase signals at

the right time. Accepts two Ms (Mp = B[1], Mt = B[0]) to

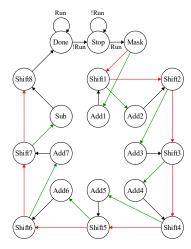
account for the actual shift that occurs at the end of a SHIFT

state, where M is not updated until the next state.

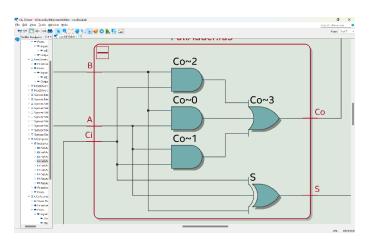
Purpose: Control unit that orchestrates the computation cycle.



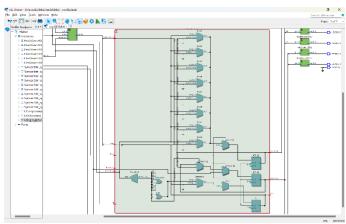
Top-level block diagram of interconnected SystemVerilog modules, simplified and labeled with signals



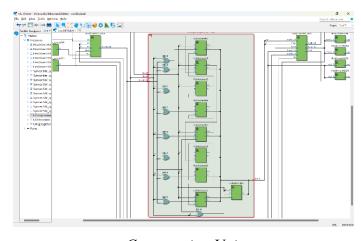
State diagram for the control unit (Green = if M, Red = if !M, unlabeled Black = always)



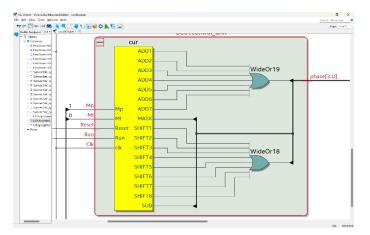
Full Adder



Register Unit

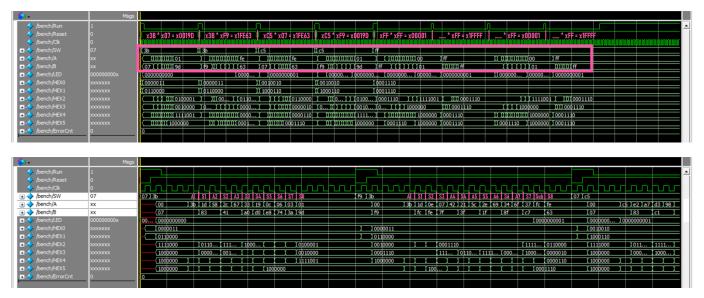


Computation Unit



Control Unit

Expanded RTL diagrams of individual modules (Clear images are in our <u>GitHub repository</u>)



Annotated ModelSim waveforms showing step-by-step operations of $0x3B \times 0x07 = 0x0019D$, $0x3B \times 0xF9 = 0x1FE63$

Post-Lab Problems

Design Resources and Statistics

lultiplier
617
0
733
3,456
89.02
89.95
1.48
100.41

To increase the maximum operating frequency, we can substitute the current CRA for a more time-efficient CSA or CLA at the cost of extra space. To decrease the total register or gate count, we can encode phase from the FSM with only two bits instead of four one-hot bits. Everything else seems to be optimal, especially the seemingly redundant MASK state – merging the operation of masking A into STOP causes the higher two HEX digits to always be 0.

• The purpose of the X register

The 8-bit operands are sign-extended to 9-bit, and X holds the most significant bit of the result. When performing a register shift, its value will be copied to the most significant bit of the 8-bit register A. Since adding produces a carry-out bit, the adder should also be sign-extended to 9 bits, and we need an additional register X to hold the out-of-range bit. X gets set when the 9-bit adder generates a new value and is cleared when Reset is pressed.

• What if we update X with the carry-out of an 8-bit adder?

The result will be incorrect when performing both ADD and SUB operations since 2's complement values are involved. Take 1111111 + 00000011 as an example. If we update X with the carry-out bit of the 8-bit adder, overflowing will negate the result (100000010). In contrast, a sign-extended 9-bit adder yields a positive number (000000010).

• Limitations of continuous multiplications

If we continuously multiply a number whose absolute value exceeds 1, B (holding the result) eventually overflows and yields incorrect values since it only has 16 bits. Valid results should be within the range of [-32768, 32767].

• (Dis)advantages over the Grade School Multiplication algorithm

The pencil-and-paper method needs more memory to hold the intermediate values from each step of multiplication, which is redundant since they are merely shifted versions of the operand. On the contrary, this *in-place* algorithm makes full use of the registers by shifting.

Conclusion

In this lab, we designed a multiplier that consists of 3 parts: a register unit of grouped X, A, and B, a 9-bit adder that adds the sign-extended A and S and loads the result to A and X (that temporarily holds the most significant bit), and a finite state machine that provides control logic to the circuit like the Mask (a.k.a. CLR, Clear-Load-Reset), Shift, Add, and Sub signals. We attempted to use the carry bit of the 8-bit adder to update the register X, and, as we later analyzed, it fails at the final subtraction step.