

1.)

Claim:

For any integer $k \geq 1$,

$\sum_{i=1}^n i^k \cdot \log i = O(n^{k+1} \cdot \log n)$

Proof (by integral approximation):

Let $S(n) = \sum_{i=1}^n i^k \cdot \log i$

Use integral approximation:

$S(n) \leq \int_1^n x^k \log x \, dx + n^k \log n$

Now compute the integral:

Let $u = \log x$, $dv = x^k \, dx$

Then:

$du = 1/x \, dx$, $v = x^{k+1}/(k+1)$

So:

$\int x^k \log x \, dx = (x^{k+1}/(k+1)) \cdot \log x - \int x^k \, dx / (k+1)$

$= (x^{k+1}/(k+1)) \cdot \log x - (1/(k+1)^2) \cdot x^{k+1}$

Evaluating from 1 to n:

$\int_1^n x^k \log x \, dx = (n^{k+1}/(k+1)) \cdot \log n - (n^{k+1}/(k+1)^2) + \text{constants}$

$\Rightarrow \Theta(n^{k+1} \log n)$

Thus:

$S(n) = \sum_{i=1}^n i^k \log i = O(n^{k+1} \log n)$ \square

3. Given n arrays, each array contain n positive integers. Write an $O(n^2 \log n)$ algorithm to find the smallest n sums out of n possible sums that can be obtained by picking one positive integer from each of n arrays. For example, given three arrays as follows: [5, 1, 8], [5, 2, 9], and [6, 7, 10]. The smallest n sums of the given array is [9, 10, 12].

```
SmallestNSums(Arrays):
    Let n = length(Arrays)
    For each array A in Arrays:
        Sort A in ascending order
    Set CurrentSums = Arrays[0]
    For i = 1 to n - 1:
        CurrentSums = MergeTwoArrays(CurrentSums, Arrays[i], n)
    Return CurrentSums

MergeTwoArrays(A, B, n):
    Initialize MinHeap H
    Initialize VisitedPairs as an empty set
    Initialize Result as an empty list
    Push (A[0] + B[0], 0, 0) into H
    Add (0, 0) to VisitedPairs
    While length(Result) < n:
        Pop the smallest element (sum_val, i, j) from H
        Append sum_val to Result
        If i + 1 < n and (i + 1, j) not in VisitedPairs:
            Push (A[i + 1] + B[j], i + 1, j) into H
            Add (i + 1, j) to VisitedPairs
        If j + 1 < n and (i, j + 1) not in VisitedPairs:
            Push (A[i] + B[j + 1], i, j + 1) into H
            Add (i, j + 1) to VisitedPairs
    Return Result
```

2a(n): $s := 0$

for $i := 0$ to n do

for $j := 1$ to i do

for $k := j$ to $i + j$ do

$s := s + 1$

Analysis:

Innermost loop runs from $k = j$ to $k = i + j$, hence it iterates $i + 1$ times. For each fixed i , the middle loop runs i times.

Thus, Total iterations = $\sum_{i=0}^n (i+1) \cdot i = \sum_{i=0}^n (i^2 + i) = O(n^3)$.

2b(n):

$i := 0$

$j := n$

$s := 0$

while $i < j$ do:

$i := i + 2$

$j := j - 3$

$s := s + 1$

Analysis:

After t iterations, $i = 2t$, $j = n - 3t$. Loop stops when $i \geq j$.

Solving for t , we get $t \geq n/5$.

Thus, total iterations = $O(n)$.

Time Complexity: $T(n) = O(n)$

Procedure Problem 2c(n):

if $n \leq 0$ then return

for $i := 1$ to n do:

for $j := 1$ to n do:

$s := s + 1$

for $i := 1$ to 4 do:

Problem 2c($n/4$)

$$S = \sum_{k=0}^{\infty} ar^k = \frac{a}{1-r}$$

$$T(n) = n^2 + \frac{4n^2}{16} + \frac{16n^2}{256} + 64T\left(\frac{n}{64}\right)$$

$$T(n) = n^2 + 4T\left(\frac{n}{4}\right)$$

$\Theta(n^2)$ or $O(n^2)$

4. Write an algorithm to sort n integers in the range 0 to $n^3 - 1$ in $O(n)$ time.

```
def counting_sort(arr, n):
    # Step 1: Initialize a count array of size n^3
    # (since values are between 0 and n^3-1)
    count = [0] * (n**3)

    # Step 2: Count the frequency of each integer in arr
    for i in range(n):
        count[arr[i]] += 1

    # Step 3: Reconstruct the sorted array
    index = 0
    for value in range(n**3):
        while count[value] > 0:
            arr[index] = value
            index += 1
            count[value] -= 1

    return arr
```

5. Assuming that there are no duplicate keys in a binary search tree, develop an algorithm to determine the pre-order traversal of the tree based on their in-order and post-order traversal. For example,

In-order traversal: 3 1 4 0 2 5

Post-order traversal: 3 4 1 5 2 0

Output: 0 1 3 4 2 5

```
def PreOrderFromInPost(inorder, postorder):
    if not inorder:
        return []

    # Root is the last element of postorder
    root = postorder[-1]
    root_index = inorder.index(root)

    # Left and right inorder and postorder arrays
    left_inorder = inorder[:root_index]
    right_inorder = inorder[root_index + 1:]
    left_postorder = postorder[:len(left_inorder)]
    right_postorder = postorder[len(left_inorder):-1]

    # Recursively find the pre-order traversal
    left_preorder = PreOrderFromInPost(left_inorder, left_postorder)
    right_preorder = PreOrderFromInPost(right_inorder, right_postorder)

    # Return root followed by left and right pre-orders
    return [root] + left_preorder + right_preorder

# Example usage
inorder = [3, 1, 4, 0, 2, 5]
postorder = [3, 4, 1, 5, 2, 0]
preorder = PreOrderFromInPost(inorder, postorder)
print(preorder) # Output: [0, 1, 3, 4, 2, 5]
```

6. Write the algorithm Tree-Delete(T, z) to delete a node z from a Binary Search Tree. When z has two children, use its Predecessor (maximum in the left subtree) to replace it instead of the Successor.

```
class Node:
    def __init__(self, key):
        self.key = key
        self.left = None
        self.right = None
        self.parent = None

def tree_delete(T, z):
    if z.left is None and z.right is None:
        if z.parent is None:
            T.root = None
        else:
            if z.parent.left == z:
                z.parent.left = None
            else:
                z.parent.right = None
    elif z.left is None or z.right is None:
        if z.left is not None:
            child = z.left
        else:
            child = z.right

        if z.parent is None:
            T.root = child
        else:
            if z.parent.left == z:
                z.parent.left = child
            else:
                z.parent.right = child
            child.parent = z.parent
    else:
        y = tree_predecessor(z)
        if y.parent != z:
            if y.left is not None:
                y.parent.right = y.left
                y.left.parent = y.parent
            else:
                y.parent.right = None
        if z.parent is None:
            T.root = y
        else:
            if z.parent.left == z:
                z.parent.left = y
            else:
                z.parent.right = y
            y.left = z.left
            if y.left is not None:
                y.left.parent = y
            y.right = z.right
            if y.right is not None:
                y.right.parent = y
            y.parent = z.parent

def tree_predecessor(z):
    if z.left is not None:
        return tree_maximum(z.left)
    else:
        return None

def tree_maximum(x):
    while x.right is not None:
        x = x.right
    return x
```

(7) The d -ary heap, also known as the d -heap, is a type of priority queue data structure. It extends the concept of the binary heap by allowing nodes to have d children instead of just 2.

- Describe how to represent a d -ary heap in an array.
- Give an efficient implementation of EXTRACTMIN in a d -ary min-heap. Analyze its running time in terms of d and n .
- Give an efficient implementation of DECREASEKEY in a d -ary min-heap. Analyze its running time in terms of d and n .
- Give an efficient implementation of INSERT in a d -ary min-heap. Analyze its running time in terms of d and n .

a). A d -ary heap is stored in an array, just like a binary heap, but each node has up to d children.

For a node at index i (0-based indexing):

- Its parent is at index $\lfloor (i - 1) / d \rfloor$
- Its children are at indices $d \cdot i + 1$ to $d \cdot i + d$

This lets us efficiently store and access the heap without using pointers.

```
def decrease_key(self, i, new_value):
    if new_value > self.heap[i]:
        return
    self.heap[i] = new_value
    while i > 0 and self.heap[(i - 1) // self.d] > self.heap[i]:
        parent_index = (i - 1) // self.d
        self.heap[i], self.heap[parent_index] = self.heap[parent_index], self.heap[i]
        i = parent_index

def insert(self, value):
    self.heap.append(value)
    i = len(self.heap) - 1
    self.decrease_key(i, value)

# Example Usage:
heap = DaryHeap(d=3) # 3-ary heap
heap.insert(10)
heap.insert(20)
heap.insert(5)
print(heap.extract_min()) # Output: 5
heap.decrease_key(1, 3)
print(heap.extract_min()) # Output: 3
```

```
class DaryHeap:
    def __init__(self, d):
        self.d = d
        self.heap = []

    def extract_min(self):
        if len(self.heap) == 0:
            return None
        self.heap[0], self.heap[-1] = self.heap[-1], self.heap[0]
        min_element = self.heap.pop()
        self._heapify_down(0)
        return min_element

    def _heapify_down(self, i):
        size = len(self.heap)
        min_index = i
        for j in range(1, self.d + 1):
            child_index = self.d * i + j
            if child_index < size and self.heap[child_index] < self.heap[min_index]:
                min_index = child_index
        if min_index != i:
            self.heap[i], self.heap[min_index] = self.heap[min_index], self.heap[i]
            self._heapify_down(min_index)
```