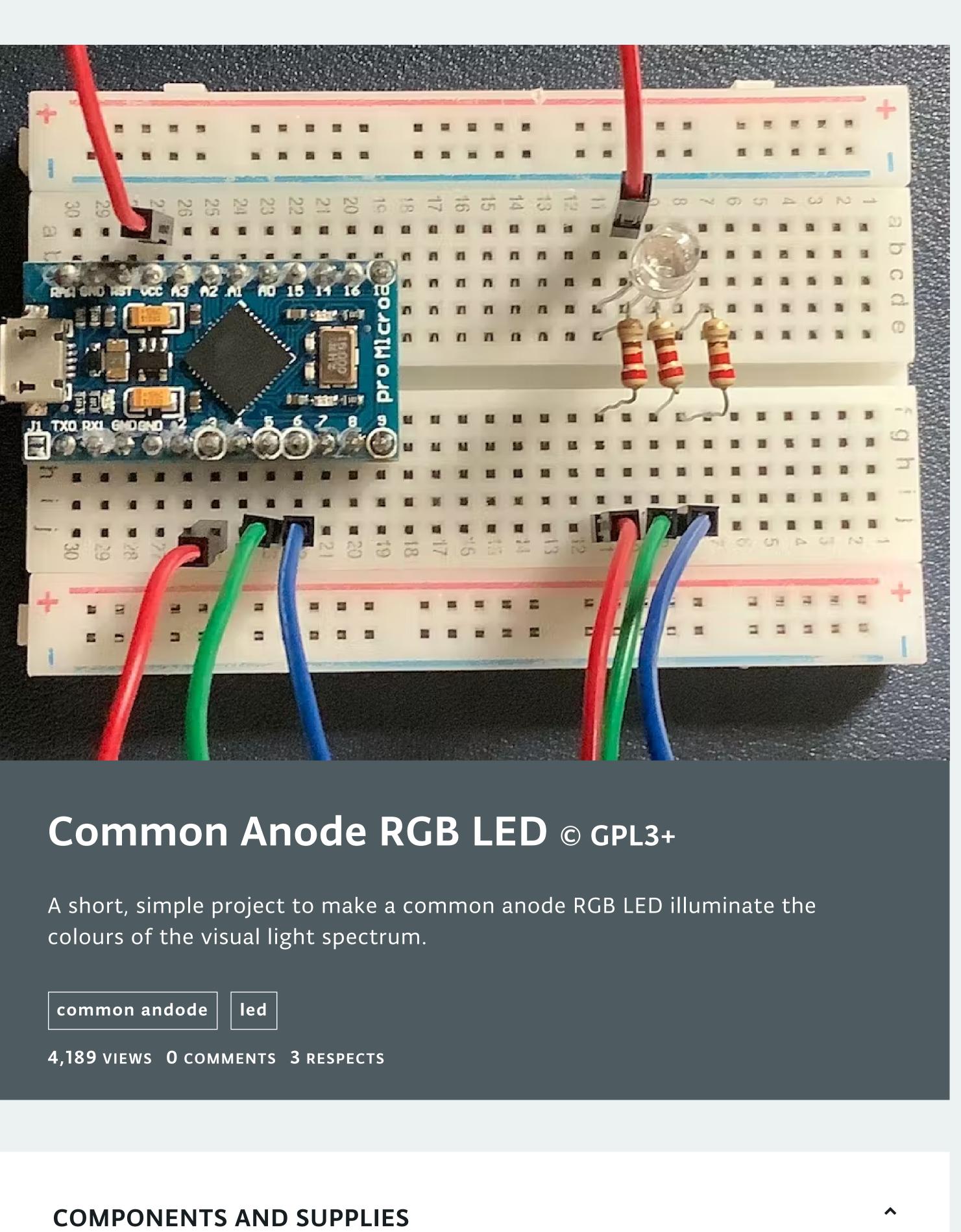
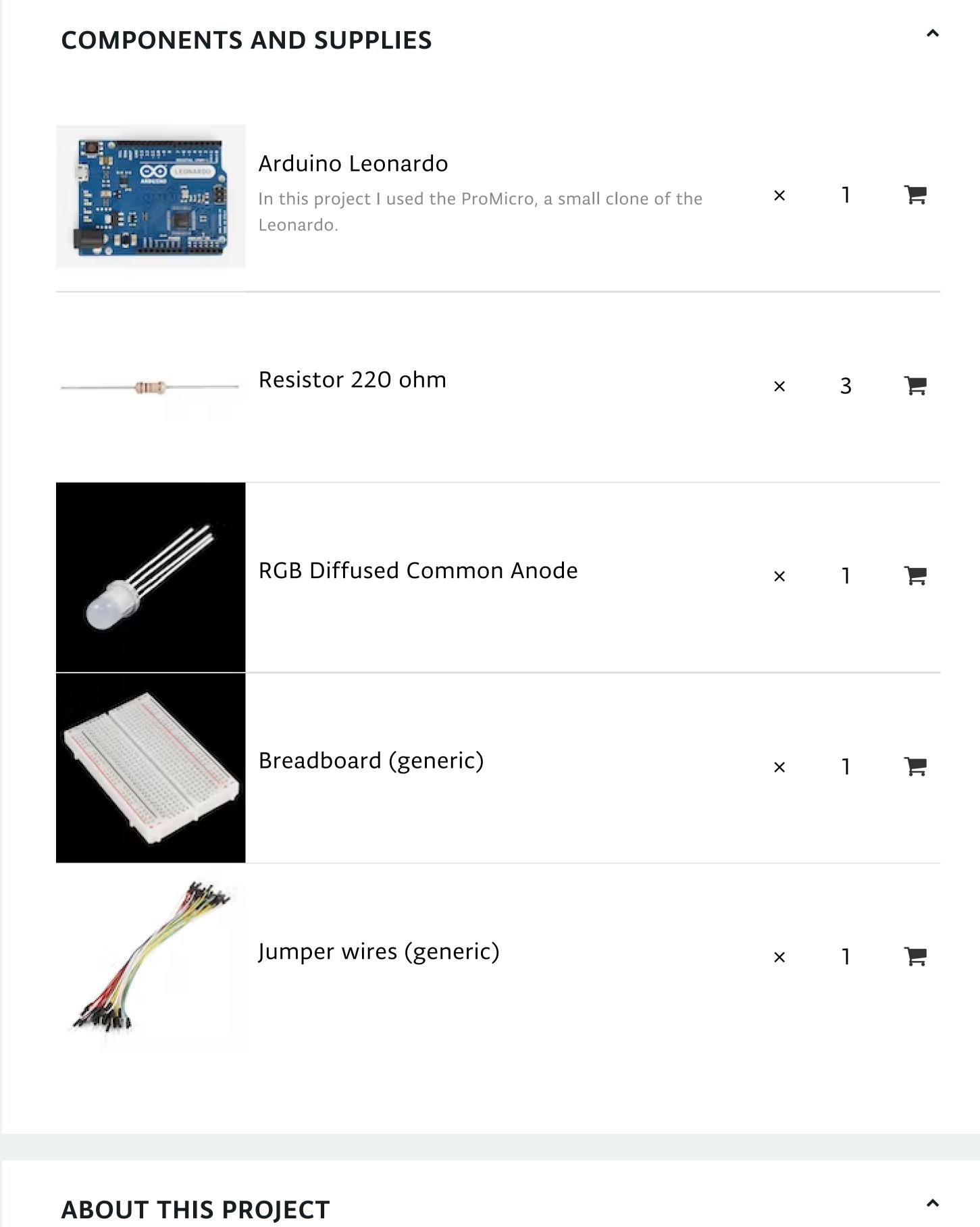
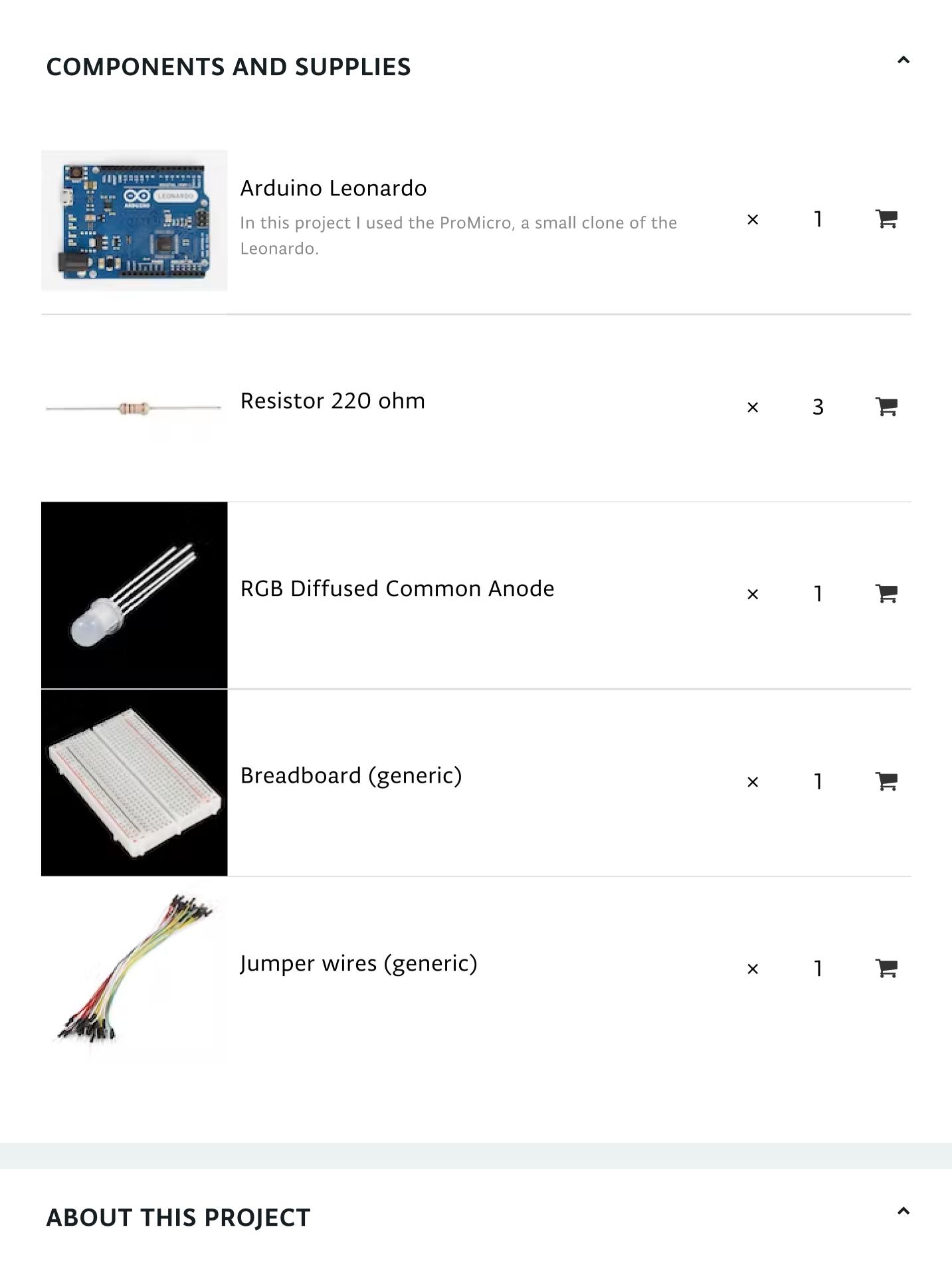
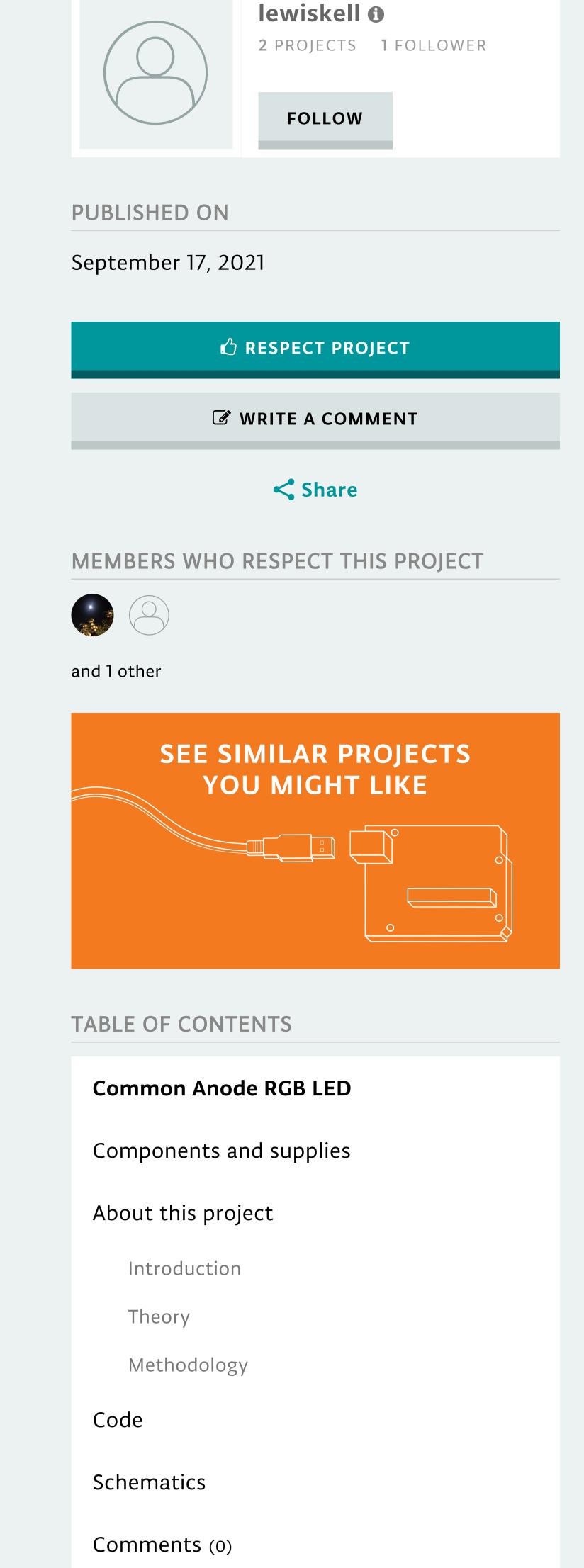
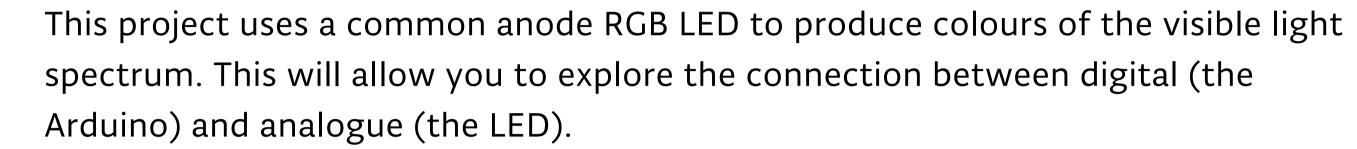
AUTHOR











Introduction

Theory

Pulse Width Modulation (PWM) is a method of reducing the average power of an electrical signal. The *duty cycle* is the proportion of time the signal is on. A duty cycle of 100% describes a full power signal. A duty cycle of 50% describes a signal that is on half the time and off the other half, which corresponds to half power.

Therefore, each colour of LED can be varied in brightness by using the PWM pins

An RGB LED is comprised of 3 individual LEDs on a single package; a red LED, a

varying combinations to produce a wide array of colours.

green LED, and a blue LED. These three primary colours can be added together in

of the Arduino to achieve various colour combinations. analogueWrite() is used to vary the duty cycle of the PWM pins. With an 8-bit PWM output, this gives 2^8 = 256 possible values to vary the duty cycle. This is how different colours are produced. As this project utilises a common anode LED, the ON state of the LED is active low meaning that for the LED to illuminate, the signal must be LOW. This is opposite to a common cathode LED. As a result, for a common anode LED to be ON a 0% PWM cycle is required using analogueWrite(0) and for a LED to be OFF, a 100% PWM cycle is required using analogueWrite(255).

PWM pins are shown by Figure 1. Pins 3, 5, and 6 are used for the red, green, and blue LEDs respectively. For other microcontrollers, refer to the respective board

pin diagram.

using other microcontrollers.

Methodology

This project uses an Arduino Leonardo clone (ProMicro), however can be recreated

Pulse Width Modulation (PWM) is used to control the brightness of the LEDs. The

Power LED-**GND**

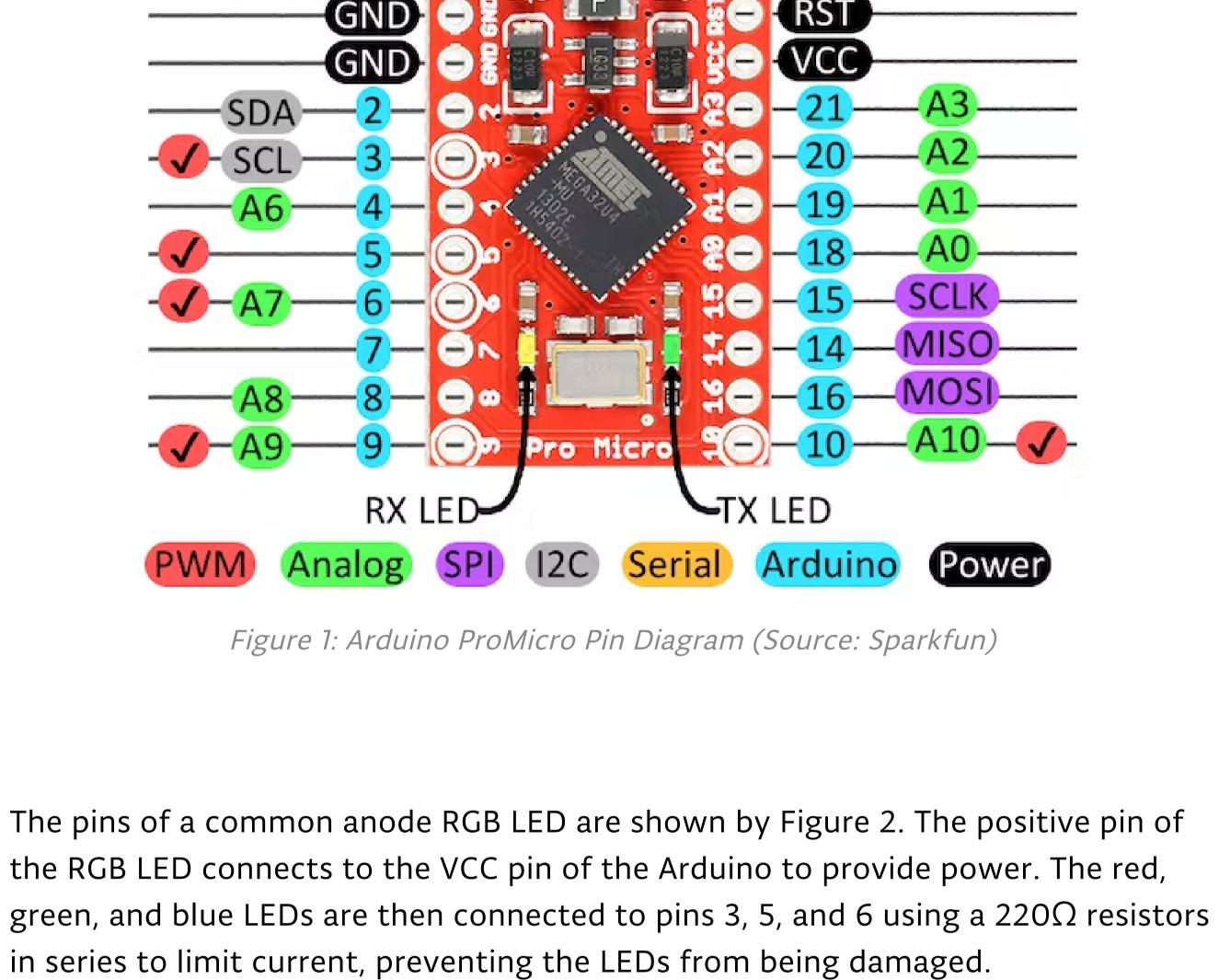
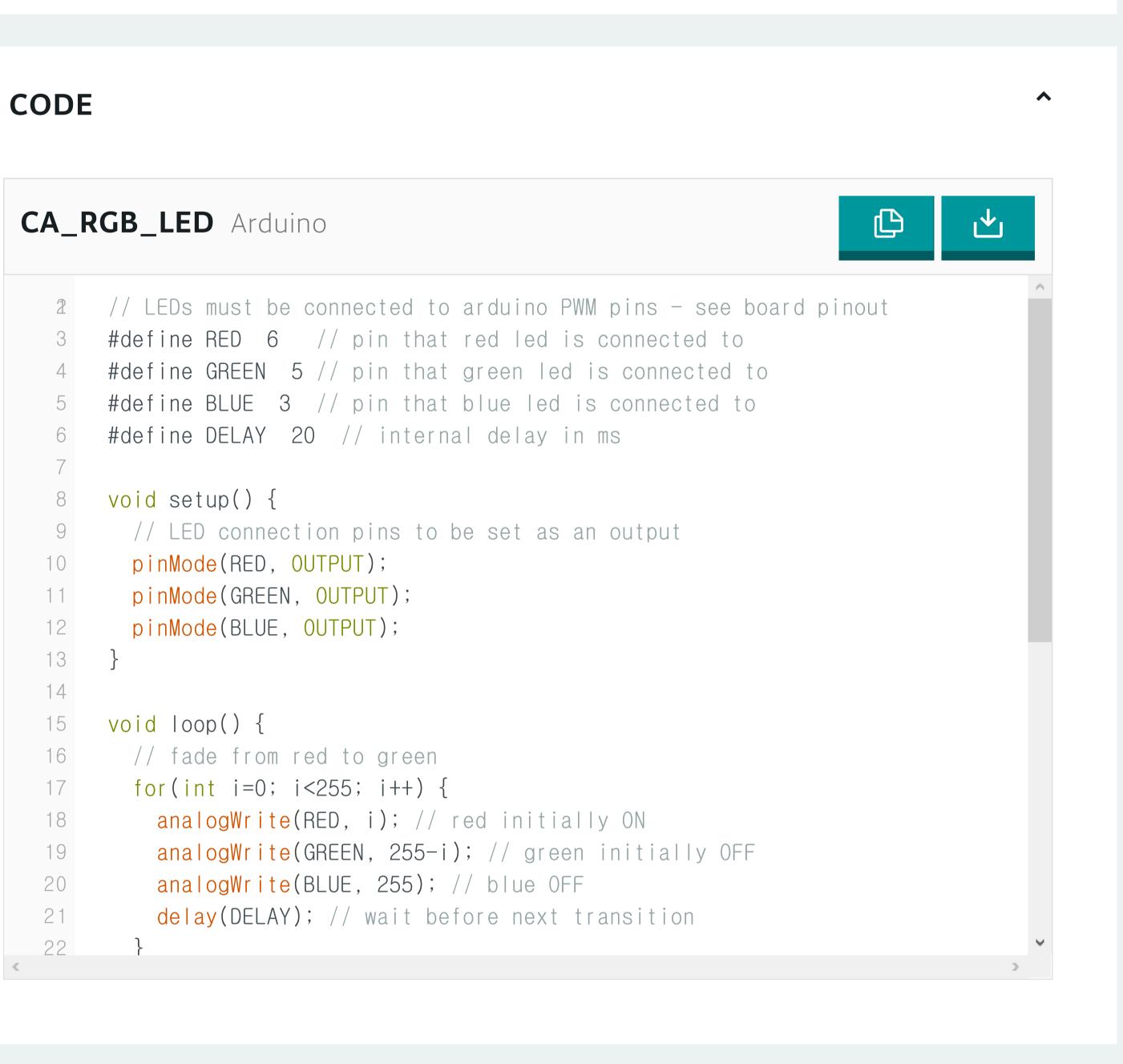
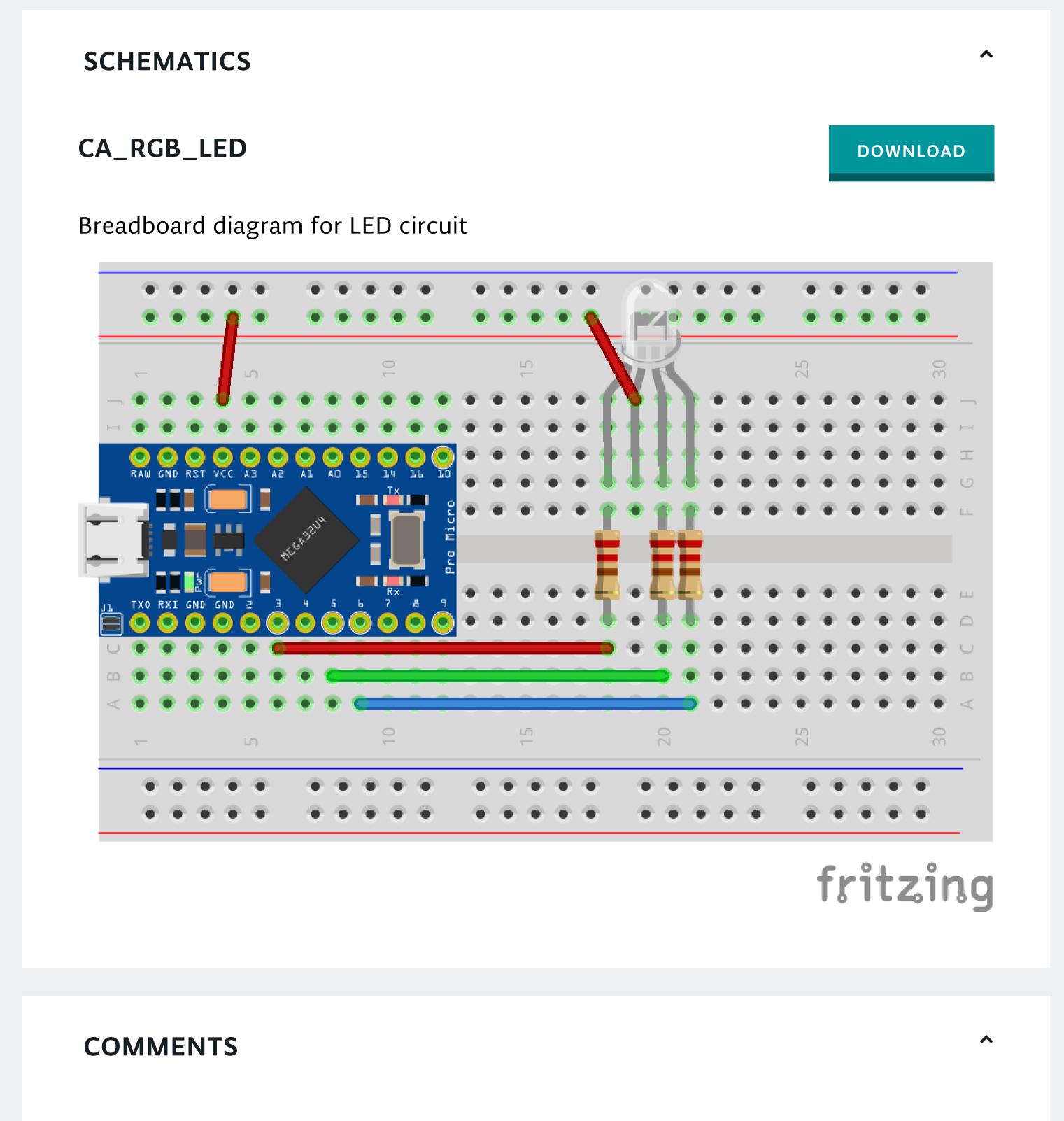


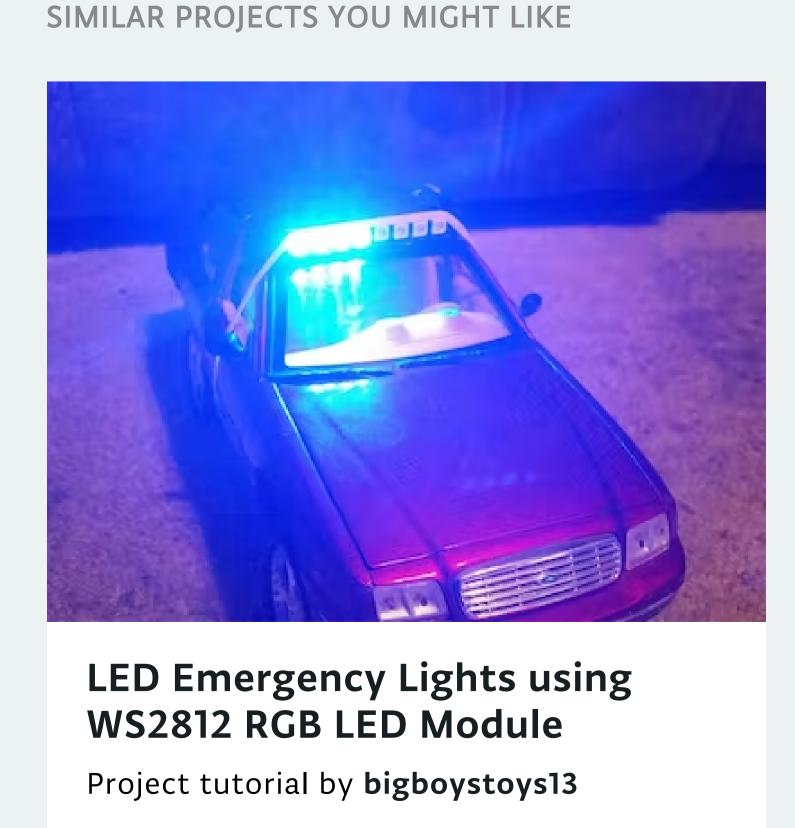
Figure 2: Common Anode RGB LED diagram (Source: CircuitBread)

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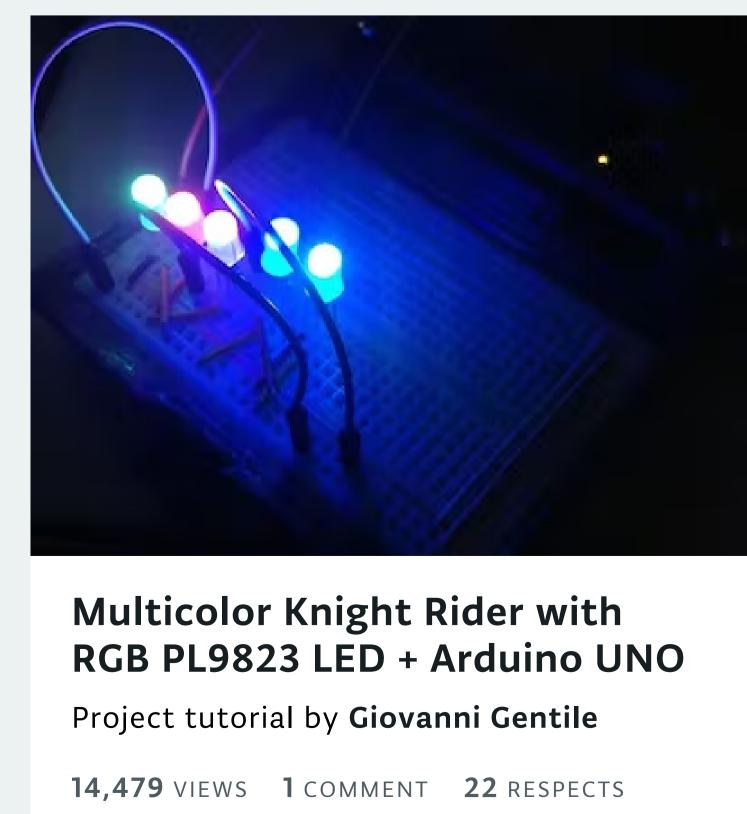


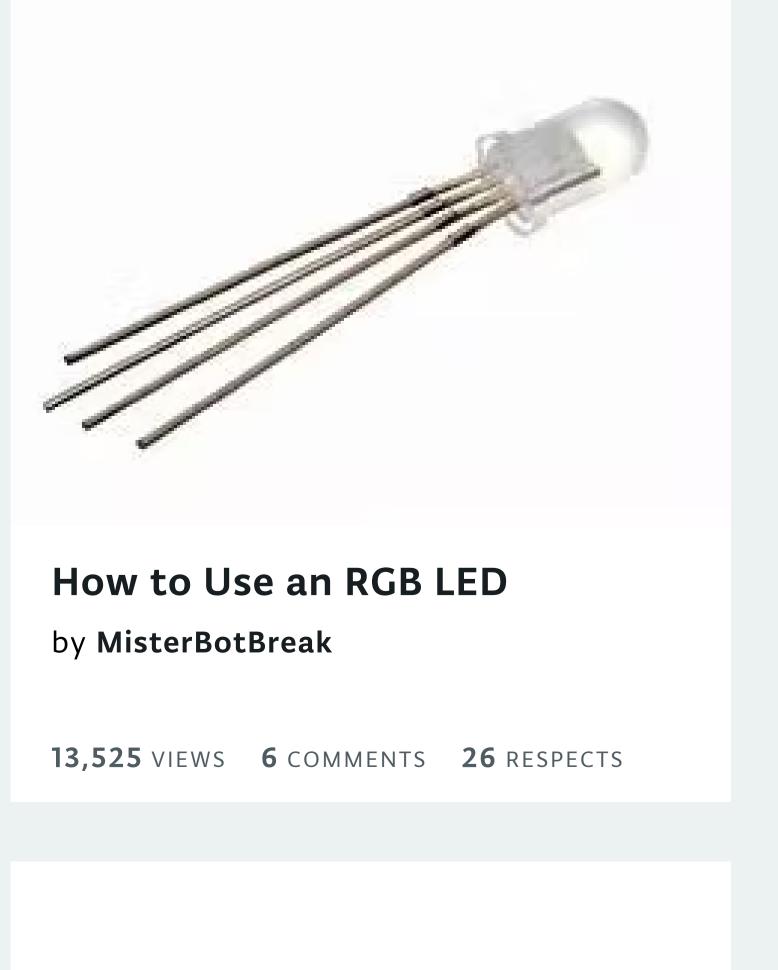


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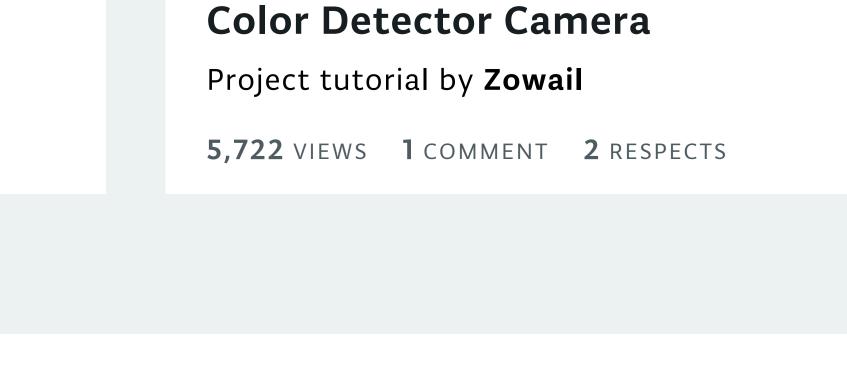
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Controlling an RGB LED with

