# **Lecture 5: Vector spaces and subspaces**

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In other words, a vector space is a collection of vectors which can be added and scaled; subject to the usual rules you would hope for, namely associativity, commutativity, distributivity.

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No! For example, take  $f(x) = x^3 + x$  and  $g(x) = -x^3 + 5x^2 + 2$ . Both f and g are in V, but their sum  $f(x) + g(x) = 5x^2 + x + 2$  is not in V.

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How to check if a subset W is a subspace?

- W contains the zero vector 0.
- W is closed under addition, i.e. if  $u, v \in W$ , then  $u + v \in W$ .
- W is closed under scaling, i.e. if  $u \in W$  and  $c \in \mathbb{R}$ , then  $cu \in W$ .

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Theorem. If  $v_1, v_2, ..., v_m$  are in a vector space V, then span $\{v_1, v_2, ..., v_m\}$  is a subspace.

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▶ Exercise. Are the following vector spaces?

• 
$$W_1 = \left\{ \begin{bmatrix} a \\ b \\ c \end{bmatrix} : a + 3b = 0, 2a - c = 1 \right\}.$$

• 
$$W_2 = \left\{ \begin{bmatrix} a+c\\ -2b\\ b+3c\\ c \end{bmatrix} : a,b,c \in \mathbb{R} \right\}.$$

• 
$$W_1 = \left\{ \begin{bmatrix} a \\ b \end{bmatrix} : ab \ge 0 \right\}.$$

▶ Definition. The **null space** of a matrix *A* is

$$N(A) = \{ \mathbf{v} : A\mathbf{v} = 0 \}.$$

In other words, if A is  $m \times n$ , then its null space consists of those vectors  $\mathbf{v} \in \mathbb{R}^n$  which solve the *homogeneous* equation  $A\mathbf{x} = 0$ .

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▶ Proof.

 $\blacktriangleright$  Example. Find an explicit description of N(A) where

$$A = \begin{bmatrix} 3 & 6 & 6 & 3 & 9 \\ 6 & 12 & 13 & 0 & 3 \end{bmatrix}.$$

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$$\left[\begin{array}{ccc|c} 3 & 6 & 6 & 3 & 9 & 0 \\ 6 & 12 & 13 & 0 & 3 & 0 \end{array}\right] \rightarrow \left[\begin{array}{ccc|c} \boxed{1} & 2 & 0 & 13 & 33 & 0 \\ 0 & 0 & \boxed{1} & -6 & -15 & 0 \end{array}\right].$$

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The solutions of Ax = 0 is of the form

$$\begin{bmatrix} -2u - 13v - 33w \\ u \\ 6v + 15w \\ v \\ w \end{bmatrix} = u \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + v \begin{bmatrix} -13 \\ 0 \\ 6 \\ 1 \\ 0 \end{bmatrix} + w \begin{bmatrix} -33 \\ 0 \\ 15 \\ 0 \\ 1 \end{bmatrix}.$$

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$$N(A) = \operatorname{span} \left\{ \begin{bmatrix} -2\\1\\0\\0\\0 \end{bmatrix}, \begin{bmatrix} -13\\0\\6\\1\\0 \end{bmatrix}, \begin{bmatrix} -33\\0\\15\\0\\1 \end{bmatrix} \right\}.$$

▶ Definition. The **column space**, C(A), of A is the span of the vector columns of A, i.e., if  $A = [a_1 \ldots a_n]$ , then  $C(A) = \text{span}\{a_1, \ldots, a_n\}$ .

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  - $\boldsymbol{b}$  is in C(A) if and only if  $A\boldsymbol{x} = \boldsymbol{b}$  has a solution. (Why?)

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  - **b** is in C(A) if and only if Ax = b has a solution. (Why?)
  - If *A* is  $m \times n$ , then C(A) is a subspace of  $\mathbb{R}^m$ . (Why?).

**Example.** Find a matrix A such that W = C(A) where

$$W = \left\{ \begin{bmatrix} 2x - y \\ 3y \\ 7x + y \end{bmatrix} : x, y \in \mathbb{R} \right\}.$$

#### C(A) and solutions to Ax = b

Theorem. Let  $x_p$  be a solution of the equation Ax = b. Then every solution to Ax = b is of the form  $x = x_p + x_n$ , where  $x_n$  is a solution to the homogeneous equation Ax = 0.

#### C(A) and solutions to Ax = b

▶ Example. Find a parametric description of the solutions to

$$\begin{bmatrix} 1 & 3 & 3 & 2 \\ 2 & 6 & 9 & 7 \\ -1 & -3 & 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \\ 5 \end{bmatrix}.$$