

Lecture 15: QR decomposition and Fourier Series (Section 3.4)

Thang Huynh, UC San Diego

2/14/2018

Gram-Schmidt

► Gram-Schmidt orthonormalization:

- Input: basis $\mathbf{a}_1, \dots, \mathbf{a}_n$ for V
- Output: orthonormal basis $\mathbf{q}_1, \dots, \mathbf{q}_n$ for V .

$$\mathbf{b}_1 = \mathbf{a}_1, \quad \mathbf{q}_1 = \frac{\mathbf{b}_1}{\|\mathbf{b}_1\|}$$

$$\mathbf{b}_2 = \mathbf{a}_2 - \langle \mathbf{a}_2, \mathbf{q}_1 \rangle \mathbf{q}_1, \quad \mathbf{q}_2 = \frac{\mathbf{b}_2}{\|\mathbf{b}_2\|}$$

$$\mathbf{b}_3 = \mathbf{a}_3 - \langle \mathbf{a}_3, \mathbf{q}_1 \rangle \mathbf{q}_1 - \langle \mathbf{a}_3, \mathbf{q}_2 \rangle \mathbf{q}_2, \quad \mathbf{q}_3 = \frac{\mathbf{b}_3}{\|\mathbf{b}_3\|}$$

\vdots

The QR decomposition

Let A be an $m \times n$ matrix of rank n . Then we have the **QR decomposition** $A = QR$,

- where Q is $m \times n$ and has orthonormal columns, and
- R is upper triangular, $n \times n$ and invertible.

The QR decomposition

Let A be an $m \times n$ matrix of rank n . Then we have the **QR decomposition** $A = QR$,

- where Q is $m \times n$ and has orthonormal columns, and
- R is upper triangular, $n \times n$ and invertible.

► **Example.** Find the QR decomposition of $A = \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 5 \\ 0 & 3 & 6 \end{bmatrix}$.

The QR decomposition

- We apply Gram-Schmidt to the columns of A :

$$\mathbf{b}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \mathbf{q}_1,$$

$$\mathbf{b}_2 = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix} - \left\langle \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix}, \mathbf{q}_1 \right\rangle \mathbf{q}_1 = \mathbf{q}_1 \Rightarrow \mathbf{q}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\mathbf{b}_3 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} - \left\langle \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \mathbf{q}_1 \right\rangle \mathbf{q}_1 - \left\langle \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \mathbf{q}_2 \right\rangle \mathbf{q}_2 \Rightarrow \mathbf{b}_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

The QR decomposition

- We apply Gram-Schmidt to the columns of A :

$$\mathbf{b}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \mathbf{q}_1,$$

$$\mathbf{b}_2 = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix} - \left\langle \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix}, \mathbf{q}_1 \right\rangle \mathbf{q}_1 = \mathbf{q}_1 \Rightarrow \mathbf{q}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\mathbf{b}_3 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} - \left\langle \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \mathbf{q}_1 \right\rangle \mathbf{q}_1 - \left\langle \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \mathbf{q}_2 \right\rangle \mathbf{q}_2 \Rightarrow \mathbf{b}_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

$$Q = [\mathbf{q}_1 \mathbf{q}_2 \mathbf{q}_3] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

The QR decomposition

To find R in $A = QR$, note that $Q^T A = Q^T QR = R$.

The QR decomposition

To find R in $A = QR$, note that $Q^T A = Q^T QR = R$.

$$R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 5 \\ 0 & 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix}.$$

The QR decomposition

To find R in $A = QR$, note that $Q^T A = Q^T QR = R$.

$$R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 5 \\ 0 & 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix}.$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 5 \\ 0 & 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix}.$$

The QR decomposition

To find R in $A = QR$, note that $Q^T A = Q^T QR = R$.

$$R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 5 \\ 0 & 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix}.$$
$$\Rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 5 \\ 0 & 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix}.$$

In general, to obtain $A = QR$.

- Gram-Schmidt on (columns of) A , to get Q .
- Then $R = Q^T A$.

The QR decomposition

To find R in $A = QR$, note that $Q^T A = Q^T QR = R$.

$$R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 5 \\ 0 & 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix}.$$
$$\Rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 5 \\ 0 & 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix}.$$

In general, to obtain $A = QR$.

- Gram-Schmidt on (columns of) A , to get Q .
- Then $R = Q^T A$.

Why does this process ensure R is an upper triangular matrix?

Practice Problems

► **Example.** Complete $\frac{1}{3} \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \frac{1}{3} \begin{bmatrix} -2 \\ -1 \\ 2 \end{bmatrix}$ to an orthonormal basis of \mathbb{R}^3 .

- a) by using the FTLA to determine the orthogonal complement of the span you already have
- b) by using Gram-Schmidt after throwing in an independent vector such as $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

► **Example.** Find the QR decomposition of $A = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$.

The QR decomposition

► **Example.** The QR decomposition is very useful for solving least squares problems:

$$\begin{aligned}A^T A \hat{\mathbf{x}} &= A^T \mathbf{b} \iff (QR)^T QR \hat{\mathbf{x}} = (QR)^T \mathbf{b} \\ &\iff R^T R \hat{\mathbf{x}} = R^T Q^T \mathbf{b} \\ R \hat{\mathbf{x}} &= Q^T \mathbf{b}\end{aligned}$$

The QR decomposition

► **Example.** The QR decomposition is very useful for solving least squares problems:

$$\begin{aligned}A^T A \hat{\mathbf{x}} &= A^T \mathbf{b} \iff (QR)^T QR \hat{\mathbf{x}} = (QR)^T \mathbf{b} \\ &\iff R^T R \hat{\mathbf{x}} = R^T Q^T \mathbf{b} \\ R \hat{\mathbf{x}} &= Q^T \mathbf{b}\end{aligned}$$

The last system is triangular and is solved by back substitution.

The QR decomposition

► **Example.** The QR decomposition is very useful for solving least squares problems:

$$\begin{aligned}A^T A \hat{\mathbf{x}} &= A^T \mathbf{b} \iff (QR)^T QR \hat{\mathbf{x}} = (QR)^T \mathbf{b} \\&\iff R^T R \hat{\mathbf{x}} = R^T Q^T \mathbf{b} \\R \hat{\mathbf{x}} &= Q^T \mathbf{b}\end{aligned}$$

The last system is triangular and is solved by back substitution.

$\hat{\mathbf{x}}$ is a least squares solution of $A\mathbf{x} = \mathbf{b}$ if and only if $R\hat{\mathbf{x}} = Q^T \mathbf{b}$, where $A = QR$.

Application: Fourier series

Given an orthogonal basis $\mathbf{v}_1, \mathbf{v}_2, \dots$, we express a vector \mathbf{x} as

$$\mathbf{x} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots, \text{ where } c_i \mathbf{v}_i = \frac{\langle \mathbf{x}, \mathbf{v}_i \rangle}{\langle \mathbf{v}_i, \mathbf{v}_i \rangle} \mathbf{v}_i.$$

Application: Fourier series

Given an orthogonal basis $\mathbf{v}_1, \mathbf{v}_2, \dots$, we express a vector \mathbf{x} as

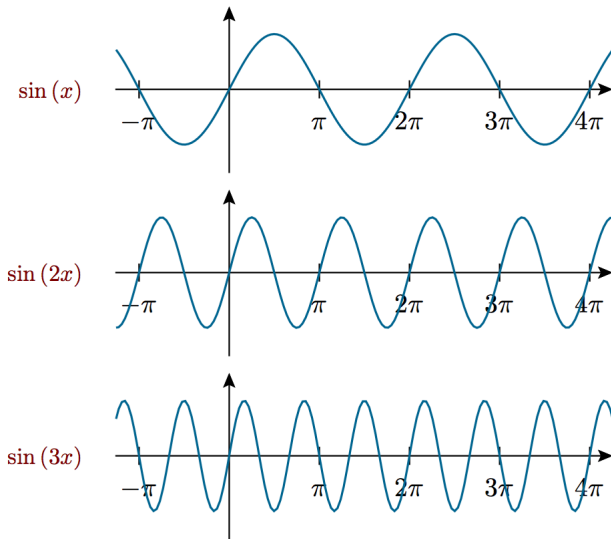
$$\mathbf{x} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots, \text{ where } c_i \mathbf{v}_i = \frac{\langle \mathbf{x}, \mathbf{v}_i \rangle}{\langle \mathbf{v}_i, \mathbf{v}_i \rangle} \mathbf{v}_i.$$

A **Fourier series** of a function $f(x)$ is an infinite expansion:

$$f(x) = a_0 + a_1 \cos(x) + b_1 \sin(x) + a_2 \cos(2x) + b_2 \sin(2x) + \dots$$

Application: Fourier series

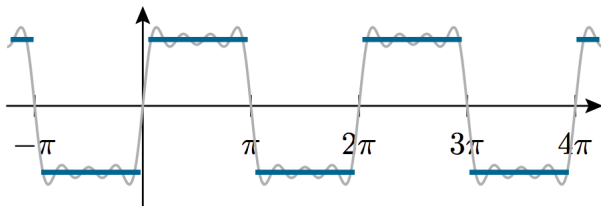
► Example.



Application: Fourier series

► Example.

$$\text{blue function} = \frac{4}{\pi} \left(\sin(x) + \frac{1}{3}\sin(3x) + \frac{1}{5}\sin(5x) + \frac{1}{7}\sin(7x) + \dots \right)$$



Application: Fourier series

- ▶ We are working in the **vector space of functions** $\mathbb{R} \rightarrow \mathbb{R}$.
 - More precisely, “nice” (e.g., piecewise continuous) functions that have period 2π .
 - There are **infinite dimensional vector spaces**.

Application: Fourier series

- ▶ We are working in the **vector space of functions** $\mathbb{R} \rightarrow \mathbb{R}$.
 - More precisely, “nice” (e.g., piecewise continuous) functions that have period 2π .
 - There are **infinite dimensional vector spaces**.
- ▶ The functions

$$1, \cos(x), \sin(x), \cos(2x), \sin(2x), \dots$$

are a basis of this space.

Application: Fourier series

- ▶ We are working in the **vector space of functions** $\mathbb{R} \rightarrow \mathbb{R}$.
 - More precisely, “nice” (e.g., piecewise continuous) functions that have period 2π .
 - There are **infinite dimensional vector spaces**.
- ▶ The functions

$$1, \cos(x), \sin(x), \cos(2x), \sin(2x), \dots$$

are a basis of this space. In fact, an **orthogonal basis**!

Application: Fourier series

- ▶ We are working in the **vector space of functions** $\mathbb{R} \rightarrow \mathbb{R}$.
 - More precisely, “nice” (e.g., piecewise continuous) functions that have period 2π .
 - There are **infinite dimensional vector spaces**.
- ▶ The functions

$$1, \cos(x), \sin(x), \cos(2x), \sin(2x), \dots$$

are a basis of this space. In fact, an **orthogonal basis**!

Application: Fourier series

But what is the inner product on the space of functions?

Application: Fourier series

But what is the inner product on the space of functions?

► Recall that for vectors in \mathbb{R}^n : $\langle \mathbf{v}, \mathbf{w} \rangle = v_1 w_1 + \dots + v_n w_n$.

Application: Fourier series

But what is the inner product on the space of functions?

- Recall that for vectors in \mathbb{R}^n : $\langle \mathbf{v}, \mathbf{w} \rangle = v_1 w_1 + \dots + v_n w_n$.
- Functions: $\langle f, g \rangle = \int_0^{2\pi} f(x)g(x) dx$.

Application: Fourier series

But what is the inner product on the space of functions?

- ▶ Recall that for vectors in \mathbb{R}^n : $\langle \mathbf{v}, \mathbf{w} \rangle = v_1 w_1 + \dots + v_n w_n$.
- ▶ Functions: $\langle f, g \rangle = \int_0^{2\pi} f(x)g(x) dx$.
- ▶ **Example.** Show that $\cos(x)$ and $\sin(x)$ are orthogonal.

Application: Fourier series

But what is the inner product on the space of functions?

- ▶ Recall that for vectors in \mathbb{R}^n : $\langle \mathbf{v}, \mathbf{w} \rangle = v_1 w_1 + \dots + v_n w_n$.
- ▶ Functions: $\langle f, g \rangle = \int_0^{2\pi} f(x)g(x) dx$.
- ▶ **Example.** Show that $\cos(x)$ and $\sin(x)$ are orthogonal.
- ▶ **Example.** What is the norm of $\cos(x)$?

Application: Fourier series

Fourier series of $f(x)$:

$$f(x) = a_0 + a_1 \cos(x) + b_1 \sin(x) + a_2 \cos(2x) + b_2 \sin(2x) + \dots$$

Application: Fourier series

Fourier series of $f(x)$:

$$f(x) = a_0 + a_1 \cos(x) + b_1 \sin(x) + a_2 \cos(2x) + b_2 \sin(2x) + \dots$$

How can we find a_k and b_k ?

$$a_0 = \frac{\langle f(x), 1 \rangle}{\langle 1, 1 \rangle} = \frac{1}{\pi} \int_0^{2\pi} f(x) dx,$$

$$a_k = \frac{\langle f(x), \cos(kx) \rangle}{\langle \cos(kx), \cos(kx) \rangle} = \frac{1}{\pi} \int_0^{2\pi} f(x) \cos(kx) dx,$$

$$b_k = \frac{\langle f(x), \sin(kx) \rangle}{\langle \sin(kx), \sin(kx) \rangle} = \frac{1}{\pi} \int_0^{2\pi} f(x) \sin(kx) dx,$$

Application: Fourier series

Fourier series of $f(x)$:

$$f(x) = a_0 + a_1 \cos(x) + b_1 \sin(x) + a_2 \cos(2x) + b_2 \sin(2x) + \dots$$

How can we find a_k and b_k ?

$$a_0 = \frac{\langle f(x), 1 \rangle}{\langle 1, 1 \rangle} = \frac{1}{\pi} \int_0^{2\pi} f(x) dx,$$

$$a_k = \frac{\langle f(x), \cos(kx) \rangle}{\langle \cos(kx), \cos(kx) \rangle} = \frac{1}{\pi} \int_0^{2\pi} f(x) \cos(kx) dx,$$

$$b_k = \frac{\langle f(x), \sin(kx) \rangle}{\langle \sin(kx), \sin(kx) \rangle} = \frac{1}{\pi} \int_0^{2\pi} f(x) \sin(kx) dx,$$

► **Example.** Find the Fourier series of the 2π -periodic function $f(x)$ defined by

$$f(x) = \begin{cases} 1, & \text{for } x \in (0, \pi), \\ -1, & \text{for } x \in (\pi, 2\pi). \end{cases}$$