

Lecture 7: Solving $Ax = b$ and linear independence (Section 2.2-2.3)

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1/24/2018

A basis of a vector space

- **Definition.** A set of vectors $\{\mathbf{v}_1, \dots, \mathbf{v}_m\}$ in V is a **basis** of V if
- $V = \text{span}\{\mathbf{v}_1, \dots, \mathbf{v}_m\}$, and
 - the vectors $\mathbf{v}_1, \dots, \mathbf{v}_m$ are linearly independent.

Theorem. Suppose that V has dimension d .

- A set of d vectors in V are a basis if they span V .
- A set of d vectors in V are a basis if they are linearly independent.

A basis of a vector space

► **Example.** Let \mathcal{P}_2 be the space of polynomials of degree at most 2.

- a) What is the dimension of \mathcal{P}_2 ?
- b) Is $\{t, 1 - t, 1 + t - t^2\}$ a basis of \mathcal{P}_2 ?

Shrinking and expanding sets of vectors

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► **Example.** Produce a basis of \mathbb{R}^2 from the vectors

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} -2 \\ -4 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

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► **Example.** Find a basis and the dimension of

$$W = \left\{ \begin{bmatrix} a + b + 2c \\ 2a + 2b + 4c + d \\ b + c + d \\ 3a + 3c + d \end{bmatrix} : a, b, c, d \in \mathbb{R} \right\}.$$

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► **Example.** Consider

$$H = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}.$$

- What is the dimension of this subspace of \mathbb{R}^3 ?

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$$H = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}.$$

- What is the dimension of this subspace of \mathbb{R}^3 ?
- Extend it to a basis of \mathbb{R}^3 .

Bases for null spaces

To find a basis for $N(A)$:

Bases for null spaces

To find a basis for $N(A)$:

- find the parametric form of the solutions to $A\mathbf{x} = 0$,
- express solutions \mathbf{x} as a linear combination of vectors with the free variables as coefficients,
- these vectors form a basis of $N(A)$.

Bases for null spaces

► **Example.** Find a basis for $N(A)$ with

$$A = \begin{bmatrix} 3 & 6 & 6 & 3 & 9 \\ 6 & 12 & 13 & 0 & 3 \end{bmatrix}.$$

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► **Solution.** First solve $Ax = 0$.

$$\left[\begin{array}{ccccc|c} 3 & 6 & 6 & 3 & 9 & 0 \\ 6 & 12 & 13 & 0 & 3 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccccc|c} \boxed{1} & 2 & 0 & 13 & 33 & 0 \\ 0 & 0 & \boxed{1} & -6 & -15 & 0 \end{array} \right].$$

The solutions of $Ax = \mathbf{0}$ is of the form

$$\begin{bmatrix} -2x_2 - 13x_4 - 33x_5 \\ x_2 \\ 6x_4 + 15x_5 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -13 \\ 0 \\ 6 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -33 \\ 0 \\ 15 \\ 0 \\ 1 \end{bmatrix}.$$

Bases for null spaces

$$N(A) = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -13 \\ 0 \\ 6 \\ 1 \end{bmatrix}, \begin{bmatrix} -33 \\ 0 \\ 15 \\ 1 \end{bmatrix} \right\}.$$

These above three vectors form a basis of $N(A)$. (Why?)

Bases for column spaces

Recall that the columns of A are independent

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$\Leftrightarrow A$ has no free variables.

A basis for $C(A)$ is given by the pivot columns of A .

Bases for column spaces

► **Example.** Find a basis for $C(A)$ with

$$A = \begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & -1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix}.$$

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► **Example.** Find a basis for $C(A)$ with

$$A = \begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & -1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix}.$$

► **Solution.** Find row reduction form of A

$$\begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & -1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & 4 \\ 0 & 0 & -1 & -5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Hence, $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 2 \\ 0 \end{bmatrix} \right\}$ form a basis for $C(A)$.

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- ▶ **Remark.** Row operations do not preserve *the column space*.
- ▶ **Remark.** Row operations do not preserve *the null space*.

Dimension of $C(A)$ and $N(A)$

Theorem. Let A be an $m \times n$ matrix. Then

- $\dim C(A)$ is the number of pivots of A .
- $\dim N(A)$ is the number of free variables of A .
- $\dim C(A) + \dim N(A) =$

► Proof.???

Dimension of $C(A)$ and $N(A)$

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- $\dim C(A) + \dim N(A) = n$

► Proof.???

Dimension of $C(A)$ and $N(A)$

► **Example.** Suppose $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 4 & 7 & 8 \end{bmatrix}$. Find the dimension of $C(A)$ and $N(A)$.

The four fundamental subspaces

► **Definition.** The **row space** of A is the column space of A^T .

The four fundamental subspaces

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- Why "left"? \mathbf{y} is in $N(A^T)$ if and only if $\mathbf{y}^T A = 0$.

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Why "left"? \mathbf{y} is in $N(A^T)$ if and only if $\mathbf{y}^T A = 0$.

► **Definition.** The **rank** of a matrix A is the number of its pivots.

The four fundamental subspaces

► **Example.** Find a basis for $C(A)$ and $C(A^T)$ where

$$A = \begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & -1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix}.$$

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► **Solution.** To find $C(A)$, we can just use the echelon form of A . Likewise, we can also obtain $C(A^T)$ for an echelon form of A^T . But, it's not necessary!

$$\begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & -1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & 4 \\ 0 & 0 & -1 & -5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = B.$$

The rank of A is 2. And $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 2 \\ 0 \end{bmatrix} \right\}$ form a basis for $C(A)$.

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Recall that $C(A) \neq C(B)$. (We performed row operations).
However, $C(A^T) = C(B^T)$.

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Row space is preserved by elementary row operations.

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Recall that $C(A) \neq C(B)$. (We performed row operations).

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Hence, $\left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -1 \\ -5 \end{bmatrix} \right\}$ form a basis for $C(A)$.

The four fundamental subspaces

Theorem. (Fundamental Theorem of Linear Algebra, Part I)

Let A be an $m \times n$ matrix of rank r .

- $\dim C(A) = r$
- $\dim C(A^T) = r$
- $\dim N(A) = n - r$
- $\dim N(A^T) = m - r$