

COMPUTER ORGANIZATION AND DESIGN



The Hardware/Software Interface

Chapter 3

Arithmetic for Computers

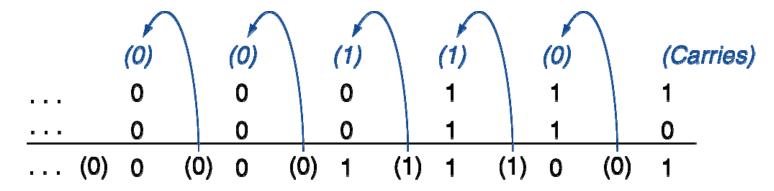
Arithmetic for Computers

- Operations on integers
 - Addition and subtraction
 - Multiplication and division
 - Dealing with overflow
- Floating-point real numbers
 - Representation and operations



Integer Addition

Example: 7 + 6



- Overflow if result out of range
 - Adding +ve and –ve operands, no overflow
 - Adding two +ve operands
 - Overflow if result sign is 1
 - Adding two –ve operands
 - Overflow if result sign is 0



Integer Subtraction

- Add negation of second operand
- Example: 7 6 = 7 + (-6)
 - +7: 0000 0000 ... 0000 0111
 - **–**6: 1111 1111 ... 1111 1010
 - +1: 0000 0000 ... 0000 0001
- Overflow if result out of range
 - Subtracting two +ve or two –ve operands, no overflow
 - Subtracting +ve from –ve operand
 - Overflow if result sign is 0
 - Subtracting –ve from +ve operand
 - Overflow if result sign is 1



Dealing with Overflow

- Some languages (e.g., C) ignore overflow
 - Use MIPS addu, addui, subu instructions
- Other languages (e.g., Ada, Fortran) require raising an exception
 - Use MIPS add, addi, sub instructions
 - On overflow, invoke exception handler
 - Save PC in exception program counter (EPC) register
 - Jump to predefined handler address
 - mfc0 (move from coprocessor reg) instruction can retrieve EPC value, to return after corrective action



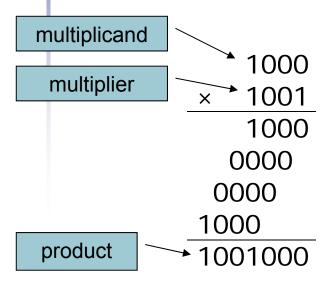
Arithmetic for Multimedia

- Graphics and media processing operates on vectors of 8-bit and 16-bit data
 - Use 64-bit adder, with partitioned carry chain
 - Operate on 8×8-bit, 4×16-bit, or 2×32-bit vectors
 - SIMD (single-instruction, multiple-data)
- Saturating operations
 - On overflow, result is largest representable value
 - c.f. 2s-complement modulo arithmetic
 - E.g., clipping in audio, saturation in video

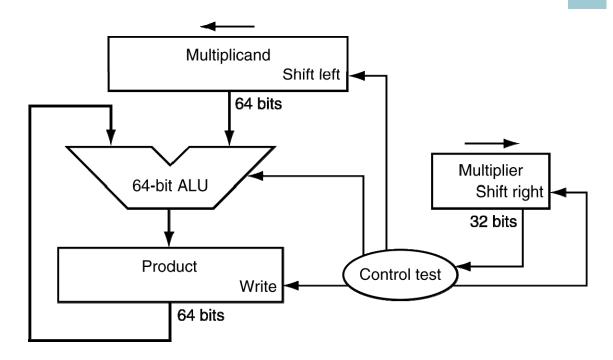


Multiplication

Start with long-multiplication approach

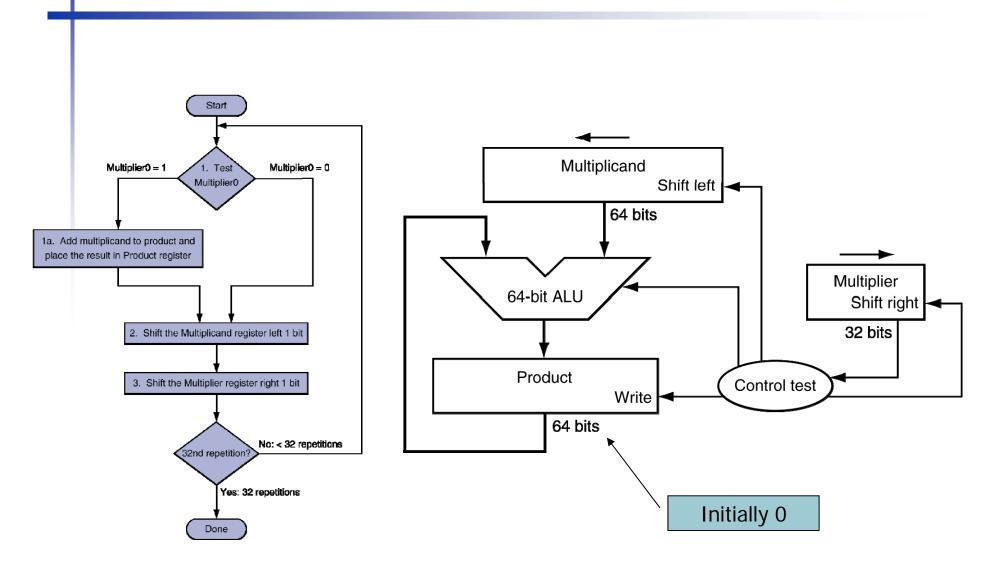


Length of product is the sum of operand lengths





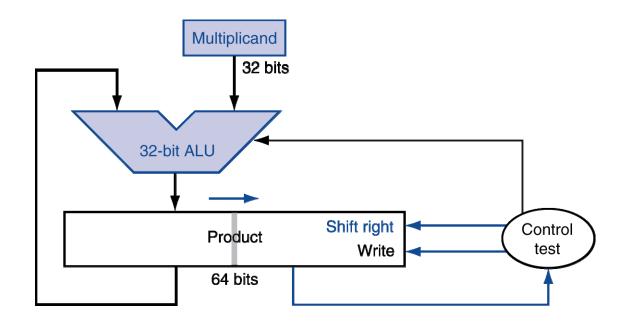
Multiplication Hardware





Optimized Multiplier

Perform steps in parallel: add/shift

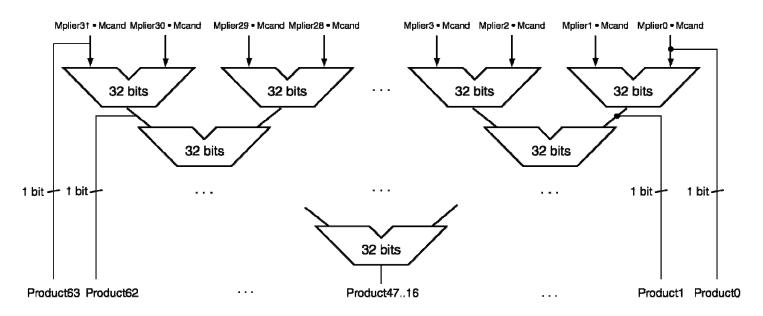


- One cycle per partial-product addition
 - That's ok, if frequency of multiplications is low



Faster Multiplier

- Uses multiple adders
 - Cost/performance tradeoff



- Can be pipelined
 - Several multiplication performed in parallel

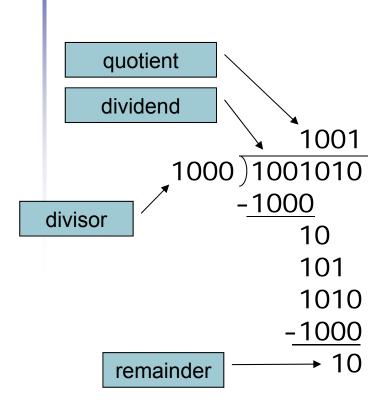


MIPS Multiplication

- Two 32-bit registers for product
 - HI: most-significant 32 bits
 - LO: least-significant 32-bits
- Instructions
 - mult rs, rt / multu rs, rt
 - 64-bit product in HI/LO
 - mfhi rd / mflo rd
 - Move from HI/LO to rd
 - Can test HI value to see if product overflows 32 bits
 - mul rd, rs, rt
 - Least-significant 32 bits of product —> rd



Division

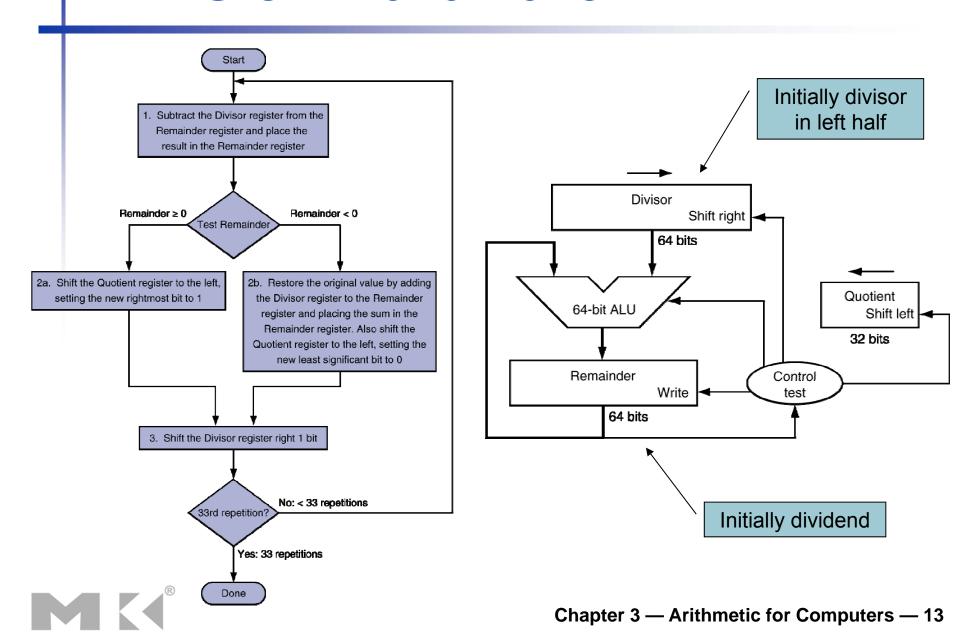


n-bit operands yield *n*-bit quotient and remainder

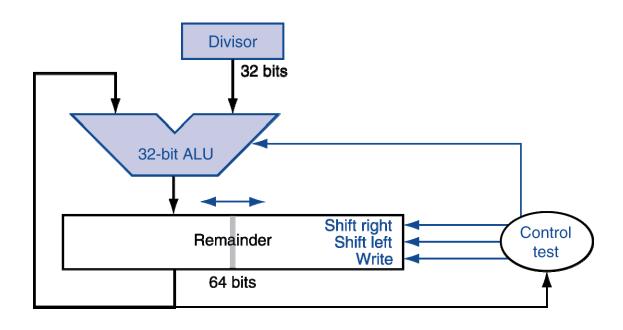
- Check for 0 divisor
- Long division approach
 - If divisor ≤ dividend bits
 - 1 bit in quotient, subtract
 - Otherwise
 - 0 bit in quotient, bring down next dividend bit
- Restoring division
 - Do the subtract, and if remainder goes < 0, add divisor back
- Signed division
 - Divide using absolute values
 - Adjust sign of quotient and remainder as required



Division Hardware



Optimized Divider



- One cycle per partial-remainder subtraction
- Looks a lot like a multiplier!
 - Same hardware can be used for both



Faster Division

- Can't use parallel hardware as in multiplier
 - Subtraction is conditional on sign of remainder
- Faster dividers (e.g. SRT devision)
 generate multiple quotient bits per step
 - Still require multiple steps



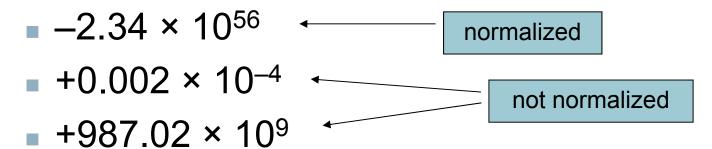
MIPS Division

- Use HI/LO registers for result
 - HI: 32-bit remainder
 - LO: 32-bit quotient
- Instructions
 - div rs, rt / divu rs, rt
 - No overflow or divide-by-0 checking
 - Software must perform checks if required
 - Use mfhi, mfl o to access result



Floating Point

- Representation for non-integral numbers
 - Including very small and very large numbers
- Like scientific notation



- In binary
 - $= \pm 1.xxxxxxx_2 \times 2^{yyyy}$
- Types fl oat and doubl e in C



Floating Point Standard

- Defined by IEEE Std 754-1985
- Developed in response to divergence of representations
 - Portability issues for scientific code
- Now almost universally adopted
- Two representations
 - Single precision (32-bit)
 - Double precision (64-bit)



IEEE Floating-Point Format

single: 8 bits single: 23 bits double: 11 bits double: 52 bits

S Exponent Fraction

$$x = (-1)^{S} \times (1 + Fraction) \times 2^{(Exponent-Bias)}$$

- S: sign bit $(0 \Rightarrow \text{non-negative}, 1 \Rightarrow \text{negative})$
- Normalize significand: 1.0 ≤ |significand| < 2.0</p>
 - Always has a leading pre-binary-point 1 bit, so no need to represent it explicitly (hidden bit)
 - Significand is Fraction with the "1." restored
- Exponent: excess representation: actual exponent + Bias
 - Ensures exponent is unsigned
 - Single: Bias = 127; Double: Bias = 1203



Single-Precision Range

- Exponents 00000000 and 11111111 reserved
- Smallest value
 - Exponent: 00000001⇒ actual exponent = 1 - 127 = -126
 - Fraction: $000...00 \Rightarrow \text{significand} = 1.0$
 - $±1.0 × 2^{-126} ≈ ±1.2 × 10^{-38}$
- Largest value
 - exponent: 11111110⇒ actual exponent = 254 127 = +127
 - Fraction: 111...11 ⇒ significand ≈ 2.0
 - $\pm 2.0 \times 2^{+127} \approx \pm 3.4 \times 10^{+38}$



Double-Precision Range

- Exponents 0000...00 and 1111...11 reserved
- Smallest value
 - Exponent: 0000000001⇒ actual exponent = 1 - 1023 = -1022
 - Fraction: $000...00 \Rightarrow \text{significand} = 1.0$
 - $\pm 1.0 \times 2^{-1022} \approx \pm 2.2 \times 10^{-308}$
- Largest value
 - Exponent: 11111111110⇒ actual exponent = 2046 1023 = +1023
 - Fraction: 111...11 ⇒ significand ≈ 2.0
 - $\pm 2.0 \times 2^{+1023} \approx \pm 1.8 \times 10^{+308}$



Floating-Point Precision

- Relative precision
 - all fraction bits are significant
 - Single: approx 2⁻²³
 - Equivalent to 23 × log₁₀2 ≈ 23 × 0.3 ≈ 6 decimal digits of precision
 - Double: approx 2⁻⁵²
 - Equivalent to 52 × log₁₀2 ≈ 52 × 0.3 ≈ 16 decimal digits of precision



Floating-Point Example

- Represent –0.75
 - $-0.75 = (-1)^1 \times 1.1_2 \times 2^{-1}$
 - S = 1
 - Fraction = $1000...00_2$
 - Exponent = -1 + Bias
 - Single: $-1 + 127 = 126 = 011111110_2$
 - Double: $-1 + 1023 = 1022 = 0111111111110_2$
- Single: 1011111101000...00
- Double: 10111111111101000...00



Floating-Point Example

 What number is represented by the singleprecision float

11000000101000...00

- S = 1
- Fraction = $01000...00_2$
- Fxponent = $10000001_2 = 129$

$$x = (-1)^{1} \times (1 + 01_{2}) \times 2^{(129 - 127)}$$

$$= (-1) \times 1.25 \times 2^{2}$$

$$= -5.0$$



Denormal Numbers

Exponent = $000...0 \Rightarrow$ hidden bit is 0

$$x = (-1)^{S} \times (0 + Fraction) \times 2^{-Bias}$$

- Smaller than normal numbers
 - allow for gradual underflow, with diminishing precision
- Denormal with fraction = 000...0

$$x = (-1)^{S} \times (0+0) \times 2^{-Bias} = \pm 0.0$$

Two representations of 0.0!



Infinities and NaNs

- Exponent = 111...1, Fraction = 000...0
 - ±Infinity
 - Can be used in subsequent calculations, avoiding need for overflow check
- Exponent = 111...1, Fraction ≠ 000...0
 - Not-a-Number (NaN)
 - Indicates illegal or undefined result
 - e.g., 0.0 / 0.0
 - Can be used in subsequent calculations



Floating-Point Addition

- Consider a 4-digit decimal example
 - $-9.999 \times 10^{1} + 1.610 \times 10^{-1}$
- 1. Align decimal points
 - Shift number with smaller exponent
 - \bullet 9.999 × 10¹ + 0.016 × 10¹
- 2. Add significands
 - \bullet 9.999 × 10¹ + 0.016 × 10¹ = 10.015 × 10¹
- 3. Normalize result & check for over/underflow
 - 1.0015 × 10²
- 4. Round and renormalize if necessary
 - -1.002×10^2



Floating-Point Addition

- Now consider a 4-digit binary example
 - $-1.000_2 \times 2^{-1} + -1.110_2 \times 2^{-2} (0.5 + -0.4375)$
- 1. Align binary points
 - Shift number with smaller exponent
 - $-1.000_2 \times 2^{-1} + -0.111_2 \times 2^{-1}$
- 2. Add significands
 - $-1.000_2 \times 2^{-1} + -0.111_2 \times 2^{-1} = 0.001_2 \times 2^{-1}$
- 3. Normalize result & check for over/underflow
 - $1.000_2 \times 2^{-4}$, with no over/underflow
- 4. Round and renormalize if necessary
 - $-1.000_2 \times 2^{-4}$ (no change) = 0.0625

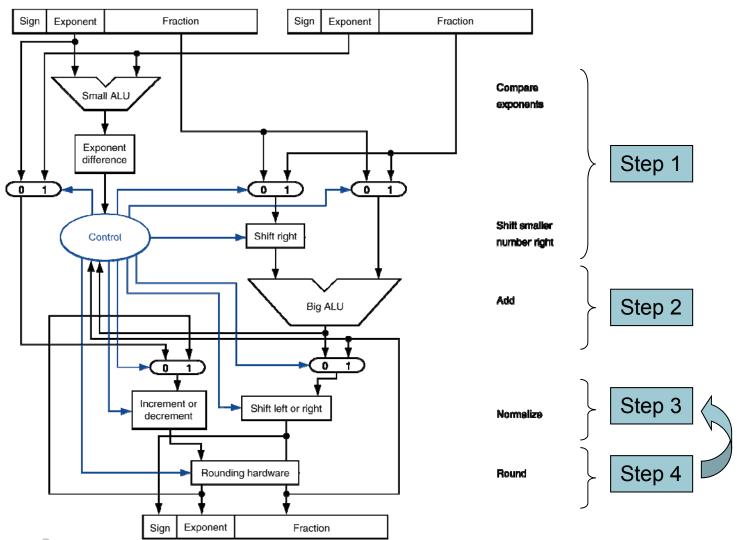


FP Adder Hardware

- Much more complex than integer adder
- Doing it in one clock cycle would take too long
 - Much longer than integer operations
 - Slower clock would penalize all instructions
- FP adder usually takes several cycles
 - Can be pipelined



FP Adder Hardware





Floating-Point Multiplication

- Consider a 4-digit decimal example
 - $-1.110 \times 10^{10} \times 9.200 \times 10^{-5}$
- 1. Add exponents
 - For biased exponents, subtract bias from sum
 - New exponent = 10 + -5 = 5
- 2. Multiply significands
 - $1.110 \times 9.200 = 10.212 \Rightarrow 10.212 \times 10^{5}$
- 3. Normalize result & check for over/underflow
 - 1.0212 × 10⁶
- 4. Round and renormalize if necessary
 - 1.021 × 10⁶
- 5. Determine sign of result from signs of operands
 - +1.021 × 10⁶



Floating-Point Multiplication

- Now consider a 4-digit binary example
 - $1.000_2 \times 2^{-1} \times -1.110_2 \times 2^{-2} (0.5 \times -0.4375)$
- 1. Add exponents
 - Unbiased: -1 + -2 = -3
 - Biased: (-1 + 127) + (-2 + 127) = -3 + 254 127 = -3 + 127
- 2. Multiply significands
 - $1.000_2 \times 1.110_2 = 1.1102 \implies 1.110_2 \times 2^{-3}$
- 3. Normalize result & check for over/underflow
 - $1.110_2 \times 2^{-3}$ (no change) with no over/underflow
- 4. Round and renormalize if necessary
 - $1.110_2 \times 2^{-3}$ (no change)
- 5. Determine sign: +ve × −ve ⇒ −ve
 - $-1.110_2 \times 2^{-3} = -0.21875$



FP Arithmetic Hardware

- FP multiplier is of similar complexity to FP adder
 - But uses a multiplier for significands instead of an adder
- FP arithmetic hardware usually does
 - Addition, subtraction, multiplication, division, reciprocal, square-root
 - FP ↔ integer conversion
- Operations usually takes several cycles
 - Can be pipelined



FP Instructions in MIPS

- FP hardware is coprocessor 1
 - Adjunct processor that extends the ISA
- Separate FP registers
 - 32 single-precision: \$f0, \$f1, ... \$f31
 - Paired for double-precision: \$f0/\$f1, \$f2/\$f3, ...
 - Release 2 of MIPs ISA supports 32 × 64-bit FP reg's
- FP instructions operate only on FP registers
 - Programs generally don't do integer ops on FP data, or vice versa
 - More registers with minimal code-size impact
- FP load and store instructions
 - I wc1, I dc1, swc1, sdc1
 - e.g., I dc1 \$f8, 32(\$sp)



FP Instructions in MIPS

- Single-precision arithmetic
 - add. s, sub. s, mul. s, div.s
 - e.g., add. s \$f0, \$f1, \$f6
- Double-precision arithmetic
 - add. d, sub. d, mul. d, di v. d
 - e.g., mul. d \$f4, \$f4, \$f6
- Single- and double-precision comparison
 - c. xx. s, c. xx. d (xx is eq, I t, I e, ...)
 - Sets or clears FP condition-code bit
 - e.g. c. I t. s \$f3, \$f4
- Branch on FP condition code true or false
 - bc1t, bc1f
 - e.g., bc1t TargetLabel



FP Example: °F to °C

C code:

```
float f2c (float fahr) {
  return ((5.0/9.0)*(fahr - 32.0));
}
```

- fahr in \$f12, result in \$f0, literals in global memory space
- Compiled MIPS code:



FP Example: Array Multiplication

- $X = X + Y \times Z$
 - All 32 × 32 matrices, 64-bit double-precision elements
- C code:

Addresses of x, y, z in \$a0, \$a1, \$a2, and i, j, k in \$s0, \$s1, \$s2



FP Example: Array Multiplication

MIPS code:

```
$t1, 32  # $t1 = 32 (row size/loop end)
   li $s0, 0 # i = 0; initialize 1st for loop
L1: Ii \$s1, 0 # j = 0; restart 2nd for loop
L2: Ii \$s2, 0 # k = 0; restart 3rd for loop
   sll $t2, $s0, 5 # $t2 = i * 32 (size of row of x)
   addu $t2, $t2, $s1 # $t2 = i * size(row) + j
   sll $t2, $t2, 3 # $t2 = byte offset of [i][j]
   addu t2, a0, t2 \# t2 = byte address of <math>x[i][j]
   I.d f4, 0(t2) # f4 = 8 bytes of x[i][j]
L3: sll $t0, $s2, 5 # <math>$t0 = k * 32 (size of row of z)
   addu $t0, $t0, $s1 # $t0 = k * size(row) + j
   sll $t0, $t0, 3 # $t0 = byte offset of [k][j]
   addu t0, a2, t0 # t0 = byte address of z[k][j]
   I.d f16, 0(f0) # f16 = 8 bytes of z[k][j]
```



FP Example: Array Multiplication

\$11 \$t0, \$s0, 5 # \$t0 = i*32 (size of row of y)addu \$t0, \$t0, \$s2 # \$t0 = i*size(row) + ksll \$t0, \$t0, 3 # \$t0 = byte offset of [i][k] addu t0, a1, t0 # t0 = byte address of y[i][k]I.d f18, 0(f0) # f18 = 8 bytes of f[i][k]mul.d f16, f18, f16 # f16 = y[i][k] * z[k][j]add. d f4, f4, f4 f4=x[i][j] + y[i][k]*z[k][j]addi u \$s2, \$s2, 1 # \$k k + 1 bne \$s2, \$t1, L3 # if (k!= 32) go to L3 s.d f4, O(t2) # x[i][j] = f4addiu \$\$1, \$\$1, 1 # \$j = j + 1 bne \$s1, \$t1, L2 # if (j != 32) go to L2 addi u \$\$0, \$\$0, 1 # \$i = i + 1bne \$s0, \$t1, L1 # if (i != 32) go to L1



Accurate Arithmetic

- IEEE Std 754 specifies additional rounding control
 - Extra bits of precision (guard, round, sticky)
 - Choice of rounding modes
 - Allows programmer to fine-tune numerical behavior of a computation
- Not all FP units implement all options
 - Most programming languages and FP libraries just use defaults
- Trade-off between hardware complexity, performance, and market requirements



Interpretation of Data

The BIG Picture

- Bits have no inherent meaning
 - Interpretation depends on the instructions applied
- Computer representations of numbers
 - Finite range and precision
 - Need to account for this in programs



Associativity

- Parallel programs may interleave operations in unexpected orders
 - Assumptions of associativity may fail

		(x+y)+z	x+(y+z)
X	-1.50E+38		-1.50E+38
у	1.50E+38	0.00E+00	
Z	1.0	1.0	1.50E+38
		1.00E+00	0.00E+00

 Need to validate parallel programs under varying degrees of parallelism



x86 FP Architecture

- Originally based on 8087 FP coprocessor
 - 8 × 80-bit extended-precision registers
 - Used as a push-down stack
 - Registers indexed from TOS: ST(0), ST(1), ...
- FP values are 32-bit or 64 in memory
 - Converted on load/store of memory operand
 - Integer operands can also be converted on load/store
- Very difficult to generate and optimize code
 - Result: poor FP performance



x86 FP Instructions

Data transfer	Arithmetic	Compare	Transcendental
FILD mem/ST(i) FISTP mem/ST(i) FLDPI FLD1 FLDZ	FIADDP mem/ST(i) FISUBRP mem/ST(i) FIMULP mem/ST(i) FIDIVRP mem/ST(i) FSQRT FABS FRNDINT	FICOMP FIUCOMP FSTSW AX/mem	FPATAN F2XMI FCOS FPTAN FPREM FPSIN FYL2X

Optional variations

- I: integer operand
- P: pop operand from stack
- R: reverse operand order
- But not all combinations allowed



Streaming SIMD Extension 2 (SSE2)

- Adds 4 × 128-bit registers
 - Extended to 8 registers in AMD64/EM64T
- Can be used for multiple FP operands
 - 2 × 64-bit double precision
 - 4 × 32-bit double precision
 - Instructions operate on them simultaneously
 - Single-Instruction Multiple-Data



Right Shift and Division

- Left shift by i places multiplies an integer by 2ⁱ
- Right shift divides by 2ⁱ?
 - Only for unsigned integers
- For signed integers
 - Arithmetic right shift: replicate the sign bit
 - e.g., -5 / 4
 - 11111011₂ >> 2 = 11111110₂ = -2
 - Rounds toward -∞
 - c.f. $11111011_2 >>> 2 = 001111110_2 = +62$



Who Cares About FP Accuracy?

- Important for scientific code
 - But for everyday consumer use?
 - "My bank balance is out by 0.0002¢!" ⊗
- The Intel Pentium FDIV bug
 - The market expects accuracy
 - See Colwell, The Pentium Chronicles



Concluding Remarks

- ISAs support arithmetic
 - Signed and unsigned integers
 - Floating-point approximation to reals
- Bounded range and precision
 - Operations can overflow and underflow
- MIPS ISA
 - Core instructions: 54 most frequently used
 - 100% of SPECINT, 97% of SPECFP
 - Other instructions: less frequent

