ST.JOSEPH'S COLLEGE OF ENGINEERING

ST.JOSEPH'S INSTITUTE OF TECHNOLOGY CS6401-OPERATING SYSTEM

Assignment – 2

Part - A

- 1. Define process state?
- 2. Define IPC?
- 3. What are the Scheduling Criteria?
- 4. Differences between a Process and Thread
- 5. Define deadlock
- 6. Difference between pre-emptive and non pre-emptive scheduling? (Nov/Dec 2014)
- 7. What resources are needed when a thread created? (Nov/Dec 2014)
- 8. Give the structure of semaphore while implementing mutual-exclusion?

Part – B

- 1 .i) Draw the state diagram of a process from its creation to termination, including ALL transitions, and briefly elaborate every state and every transitions. (Nov/Dec 2014)
- 2. i) Explain in detail about the different multi threading models with neat diagram. (Nov/Dec 2014) Multithreading Models
 - ii) What is a Deadlock? How does a deadlock occur? How can a system recover from deadlock?
- 3. Consider the following set of processes, with the length of the CPU-burst time given in milliseconds: Process Burst Time Priority

P1	10	3
<i>P</i> 2	1	1
<i>P</i> 3	2	3
<i>P</i> 4	1	4
P5	5	2

The processes are assumed to have arrived in the order P1, P2, P3, P4, P5, all at time 0.

- a. Draw four Gantt charts illustrating the execution of these processes using FCFS, SJF, a non preemptive priority (a smaller priority number implies a higher priority), and RR (quantum = 1) scheduling.
- b. What is the turnaround time of each process for each of the scheduling algorithms in part a?
- c. What is the waiting time of each process for each of the scheduling algorithms in part a?
- d. Which of the schedules in part a results in the minimal average waiting time (over all processes)?
- 4. i) What is the need for process synchronization? Explain critical section problem with a two process.
- ii) Demonstrate that monitors and semaphores are equivalent in so far as they can be used to implement the same types of synchronization problems.