

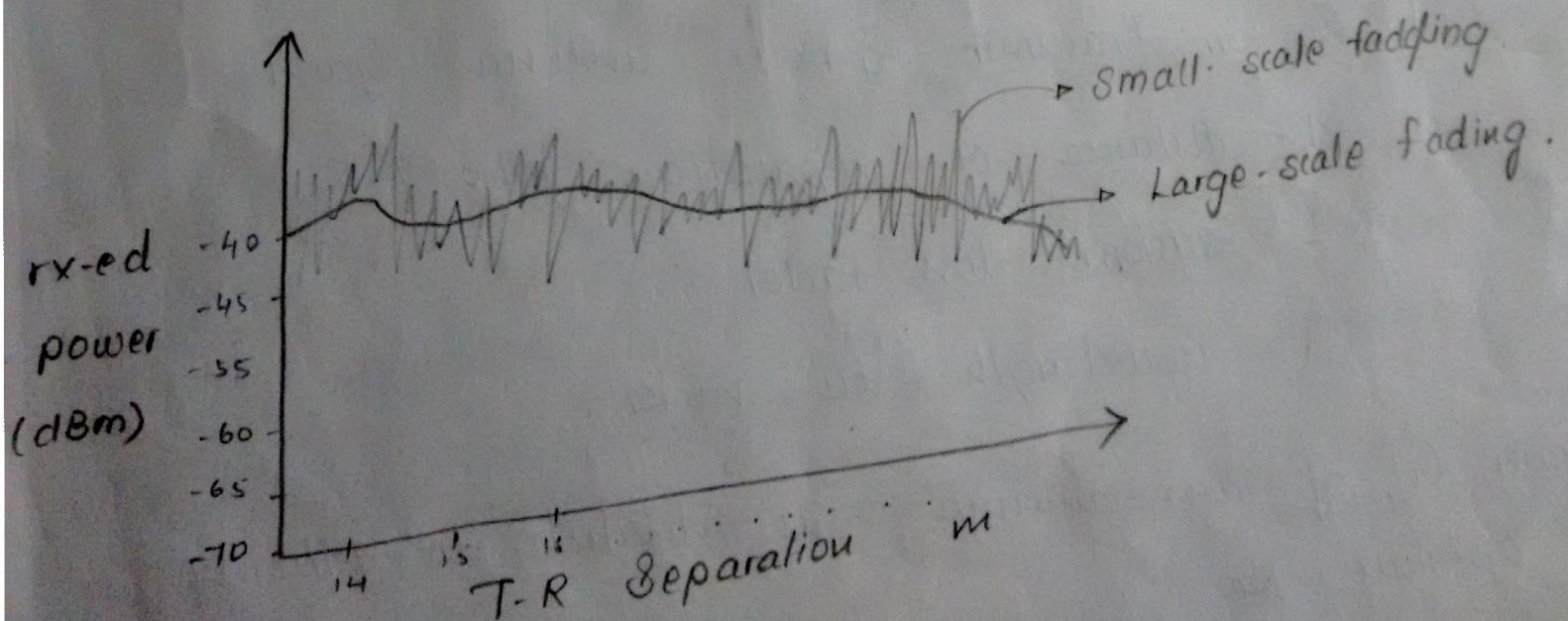
Radio Wave Propagation:

radio channels are extremely random and cannot be easily analysed.

∴ Modeling a radio channel is difficult compared to wired channel.

Propagation models that predict the mean signal strength for an arbitrary transmitter-receiver separated by a large distance (ie) several hundreds & thousands of meters are called large scale PROPAGATION MODEL.

Propagation models that characterize the rapid fluctuations of a received signal strength over a short distance (ie) a few wavelength (or) short duration are called small scale PROPAGATION MODEL.



FREE SPACE PROPAGATION MODEL:

- Satellite communication systems & microwave line of sight radio undergo free space propagation.
- free space propagation model is used to predict the received power signal strength when transmitter & receiver has clear line of sight.

In large scale radio wave propagation model

received power follows as a fn of T-R separation distance raised to power 2.

$$P_r \propto \frac{1}{d^2}$$

According to FRIIS SPACE EQUATION

$$P_r(d) = \frac{P_t \cdot G_t \cdot G_r \cdot \lambda^2}{(4\pi)^2 d^2 L} \quad \text{--- ①}$$

where P_t - transmitted power

$P_r(d)$ - rx-ed power as a fn of T-R separation

G_t, G_r , transmit & rx-er antenna gain

d - distance of separation b/w T-R

L - system loss factor

λ - wavelength in meters.

Gain G_t of an antenna is related to effective aperture A_e .

$$G_t = \frac{4\pi A_e}{\lambda^2}$$

where A_e is related to antenna size &

$$\lambda = \frac{c}{f} = \frac{2\pi c}{w_c}$$

where f - carrier freq (Hz)

w_c - carrier freq (radians/second)

Here P_t & P_r must be expressed in same units &

$G_{t,f}$ & $G_{r,f}$ - dimensionless quantities.

$L=1$ indicates no loss in system hardware.

from eq ① - rxed power decays with distance at a rate of 20 dB/decade.

An isotropic antenna radiates power with unit gain uniformly in all directions.

Effective isotropic radiated power.

$$\boxed{EIRP = P_t G_{t,f}}$$

Generally ERP is used instead of EIRP.

where ERP will be 2.15 dB smaller than EIRP.

Path Loss: represents the signal attenuation and is defined as the difference b/w effective transmit power and received power.

$$PL (\text{dB}) = 10 \log \frac{P_r}{P_t} = -10 \log \left[\frac{G_{t,f} \cdot G_{r,f} \cdot \lambda^2}{(4\pi)^2 d^2} \right]$$

when unity gain is assumed.

$$PL(dB) = 10 \log \frac{P_t}{P_r} = -10 \log \left[\frac{\lambda^2}{(4\pi)^2 d^2} \right]$$

Friis free space model is valid only for value of d which are in far-field region.

far field, Fraunhofer region is defined as region beyond d_f .

$$d_f = \frac{2D^2}{\lambda}$$

D - largest physical dimension of antenna

$$d_f \gg D$$

$$d_f \gg \lambda$$

Large scale propagation at a distance d_0 ; $d > d_0$

also $d_0 \geq d_f$

$$Pr(d) = Pr(d_0) \cdot \left[\frac{d_0}{d} \right]^2 \quad d \geq d_0 \geq d_f$$

P) find the far-field distance for an antenna with maximum dimension of 1m and operating freq of 900 MHz.

Largest dimension of antenna, $D = 1m$

$$f = 900 \text{ MHz}, \lambda = c/f = \frac{3 \times 10^8 \text{ m/s}}{900 \times 10^6 \text{ Hz}} = 0.33 \text{ m}$$

$$d_f = \frac{2D^2}{\lambda} = \frac{2(1)}{0.33} = 6 \text{ m}$$

Q) If a transmitter produces 50W of power, express the transmit power in units of a) dBm and b) dBW.
 If 50W is applied to a unity gain antenna with 900 MHz carrier frequency, find the received power in dBm at a free space distance of 100m from the antenna. What is $P_r(10\text{km})$? Assume unity gain for receiver antenna.

Transmit power, $P_t = 50 \text{ W}$

Carrier frequency, $f_c = 900 \text{ MHz}$

a) Transmitter power

$$P_t(\text{dBm}) = 10 \log [P_t(\text{mW}) / (1\text{mW})]$$

$$= 10 \log [50 / 1 \times 10^{-3}]$$

$$= 10 \log [50 \times 10^3] = 47 \text{ dBm}$$

b) Transmit power.

$$P_t(\text{dBW}) = 10 \log [P_t(\text{W}) / (1\text{W})]$$

$$= 10 \log 50 = 17 \text{ dBW}$$

c) Received power $\lambda = \frac{c}{f} = \frac{3 \times 10^8}{900 \times 10^6} = 1/3$

$$P_r = \frac{P_t \cdot G_t \cdot G_r \cdot \lambda^2}{(4\pi)^2 \times d^2 \times L}$$

$$= \frac{50 \cdot (1) \cdot (1) \cdot [1/3]^2}{(4\pi)^2 \times 100^2 \times (1)} = (3.5 \times 10^{-6}) \text{ W}$$

$$= 3.5 \times 10^{-3} \text{ mW}$$

$$\begin{aligned}
 \Pr(dBm) &= 10 \log [P_r(mw)/1mw] \\
 &= 10 \log \left[3.5 \times 10^{-3} \times (1mw) \over 1mw \right] \\
 &= 10 \log [3.5 \times 10^{-3}] \\
 &= -24.5 dBm
 \end{aligned}$$

d) rx-ed power at 10km can be expressed in it in terms of dBm.

$$\text{where } d_0 = 100m$$

$$d = 10 \text{ km}$$

$$\Pr(d) = \Pr(d_0) \left[\frac{d_0}{d} \right]^2$$

taking log.

$$\begin{aligned}
 \Pr(\overset{10}{d})_{dBm} &= \Pr(100) + 20 \log \left[\frac{d_0}{d} \right] \\
 &= -24.5 dBm + 20 \log \left[\frac{100}{10000} \right] \\
 &= -24.5 dBm - 40 dB \\
 &= -64.5 dBm
 \end{aligned}$$

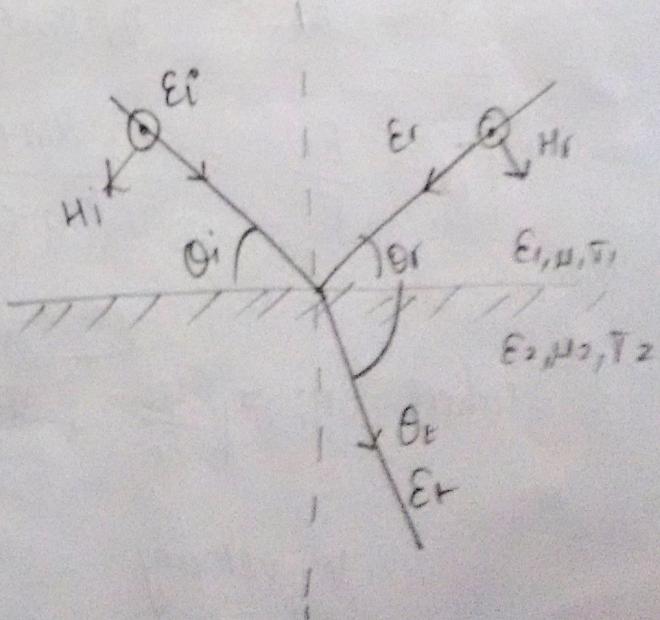
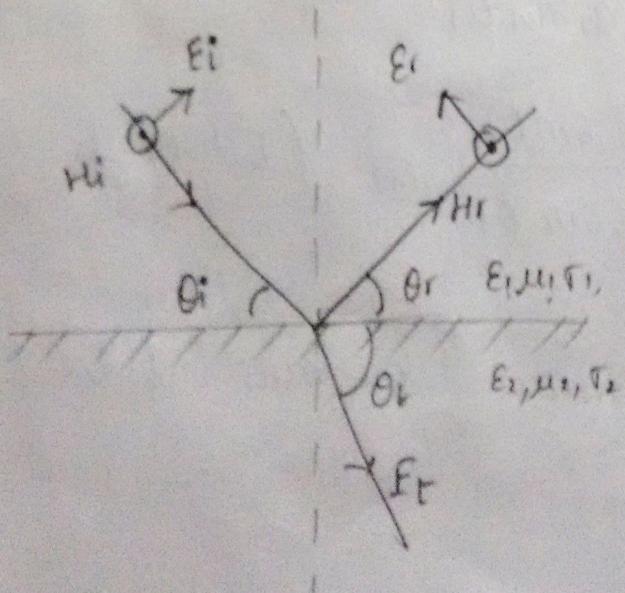
Three Basic Propagation mechanisms:

- Reflection
- Diffraction
- Scattering

Reflection:

- Reflection occurs when an electromagnetic wave impinges on an object having very large dimensions compared to the wavelength of propagating wave.
- When a radio wave impinges on a medium with different electrical properties, the wave is partially reflected & partially transmitted.
- Fresnel reflection co-efficient:
The electric field intensity of the reflected & transmitted wave are related to the incident wave in the medium of origin by fresnel reflection co-eff.

(a) Efield - Udg. to P01



- Fig shows an EM wave with an incident angle θ_i , reflected angle θ_r & part of energy transmitted in second medium θ_t .
- Plane of incidence: is the plane containing the incident, reflected & transmitted rays.
- In the figure,
 - i, r, t refers to incident, reflected and transmitted fields
 - ϵ_i, μ_i, τ & $\epsilon_2, \mu_2, \tau_2$ represents the permittivity, permeability & conductance of the 2 media.
- In fig (a), the E field polarization is || to plane of incidence & H field is \perp to plane of incidence.
- In fig (b), the E-field polarization is \perp to the plane of incidence & H field is || to plane of incidence.
- The reflection coeff's for 2 cases of || & \perp E-field polarization is given as

$$\Gamma_{11} = \frac{E_r}{E_i} = \frac{n_2 \sin \theta_t - n_1 \sin \theta_i}{n_2 \sin \theta_t + n_1 \sin \theta_i} \quad (E \text{ field } \parallel \text{ to POI}) \quad (1)$$

$$\Gamma_{12} = \frac{E_r}{E_i} = \frac{n_2 \sin \theta_i - n_1 \sin \theta_t}{n_1 \sin \theta_i + n_2 \sin \theta_t} \quad (E \text{ field } \perp \text{ to POI}) \quad (2)$$

where $n_i = \sqrt{\frac{\mu_i}{\epsilon_i}}$ (3), n_i - intrinsic impedance. $i=1,2$

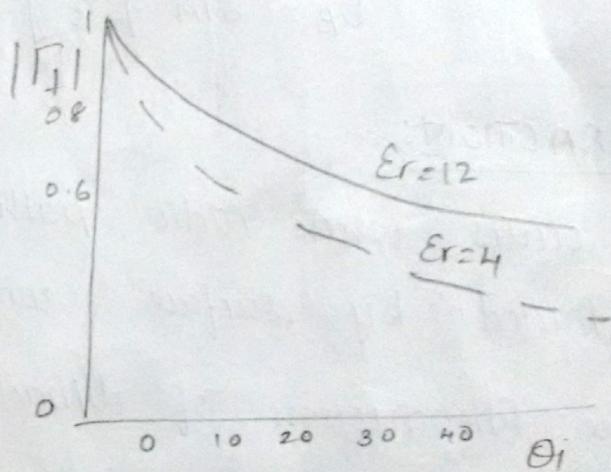
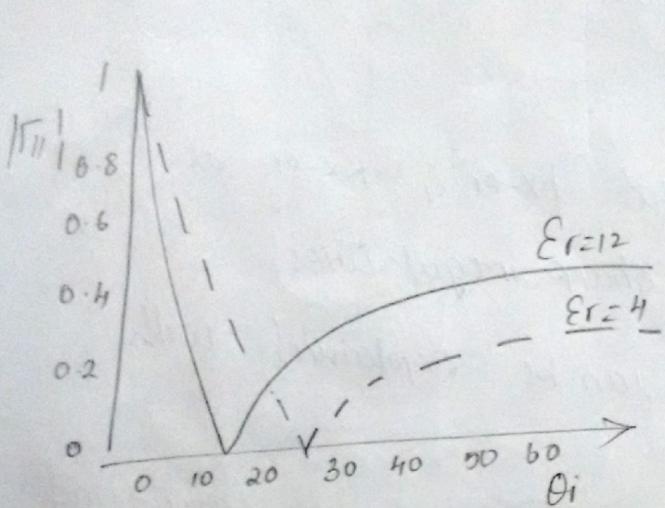
$$V, \text{ velocity} = \frac{1}{\sqrt{\mu \epsilon}}$$

Substituting ② & ③ in ① after simplification

vertical & horizontal polarization becomes.

$$\Gamma_{II} = \frac{-\epsilon_r \sin \theta_i + \sqrt{\epsilon_r - \cos^2 \theta_i}}{\epsilon_r \sin \theta_i + \sqrt{\epsilon_r - \cos^2 \theta_i}}$$

$$\Gamma_I = \frac{\sin \theta_i + \sqrt{\epsilon_r - \cos^2 \theta_i}}{\sin \theta_i + \sqrt{\epsilon_r - \cos^2 \theta_i}}$$



magnitude of reflection co-eff's as a fn of angle of incidence, when it propagates in free space.

Brewster Angle:

- It is the angle at which no reflection occurs in the medium of origin.
- It occurs when the incident angle θ_B is such that the reflection co-eff $\Gamma_{II} = 0$

$$\sin \theta_B = \sqrt{\frac{\epsilon_1}{\epsilon_1 + \epsilon_2}}$$

Brewster Generalized expression

$$\sin \theta_B = \frac{\sqrt{\epsilon_r - 1}}{\sqrt{\epsilon_r^2 - 1}}$$

- P) calculate the Brewster angle for a wave impinging on ground having a permittivity of $\epsilon_r = 4$

$$\sin \theta_B = \frac{\sqrt{4-1}}{\sqrt{4^2-1}} = \sqrt{\frac{1}{5}}$$

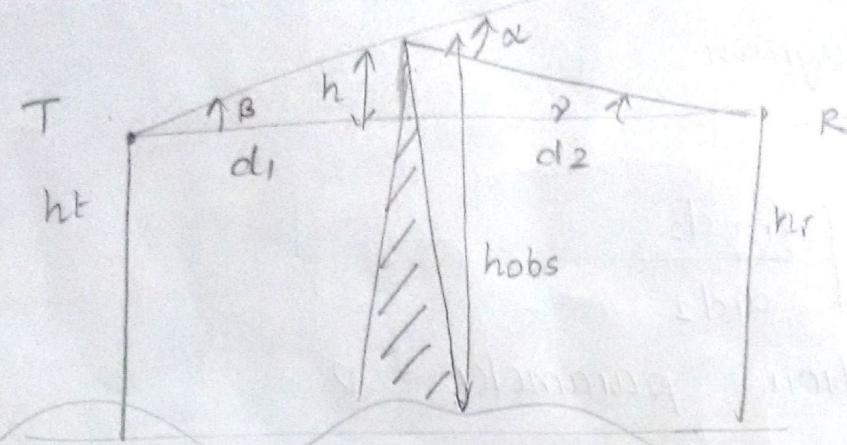
$$\theta_B = \sin^{-1} \left[\frac{1}{\sqrt{5}} \right] = 26.56^\circ$$

DIFFRACTION:

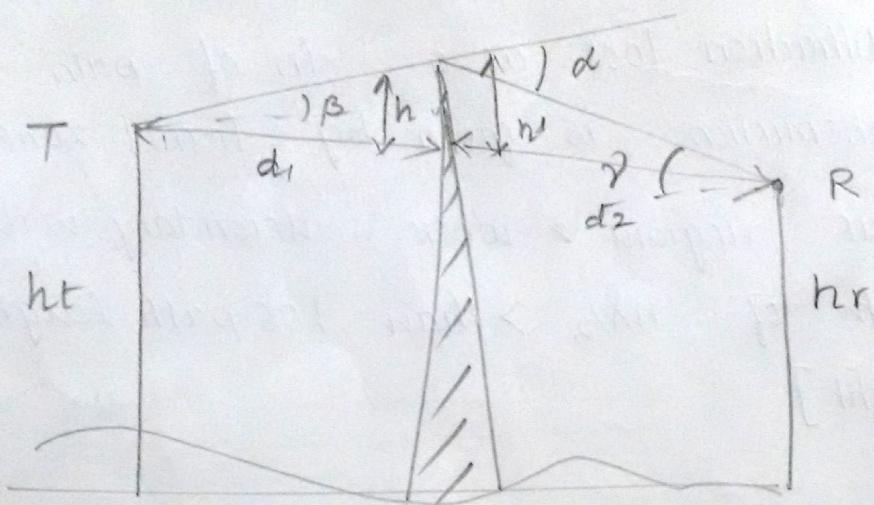
- It occurs when radio path b/w Tx-er & Rx-er is obstructed by surface with sharp irregularities.
- The phenomenon of diffraction can be explained with Huygen's principle.
"all pts. on a wavefront is considered as point source for production of secondary wavelets & these wavelets combine to produce new wavefronts. in the propagating direction"
- Diffraction is caused by propagation of secondary wavelet into a shadowed region.

Fresnel Zone Geometry

- Consider a Tx-er & Rx-er separated in free space.
- An obstruction screen is placed between them with height h & width infinity & at a distance of d_1 from Tx & d_2 from Rx.



It is clear that wave propagating from Tx to Rx via top of screen travels longer than direct line of sight.



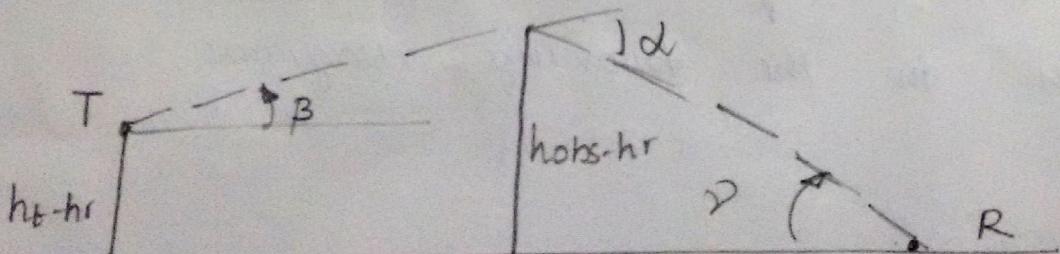
Assuming $h \ll d_1, d_2$ & $h \gg \lambda$, the diff b/w direct path & diffracted path called excess path length(s)

$$\Delta = \frac{h^2}{2} \frac{(d_1 + d_2)}{d_1 d_2}$$

corresponding phase diff.

$$\phi = \frac{2\pi\Delta}{\lambda} = \frac{2\pi}{\lambda} \cdot \frac{h^2}{2} \frac{(d_1 + d_2)}{d_1 d_2}$$

In practical use, it is better to reduce all heights to constant so that the geometry is simplified.



from the diagram

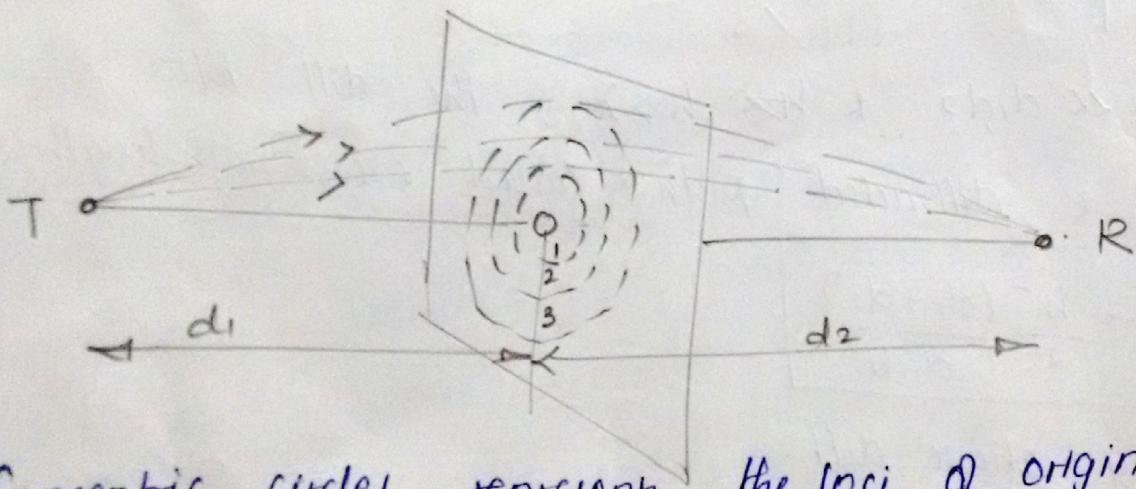
$$\alpha = \beta + \nu$$

$$\alpha = h \left[\frac{d_1 + d_2}{d_1 d_2} \right]$$

Fresnel diffraction parameter ν

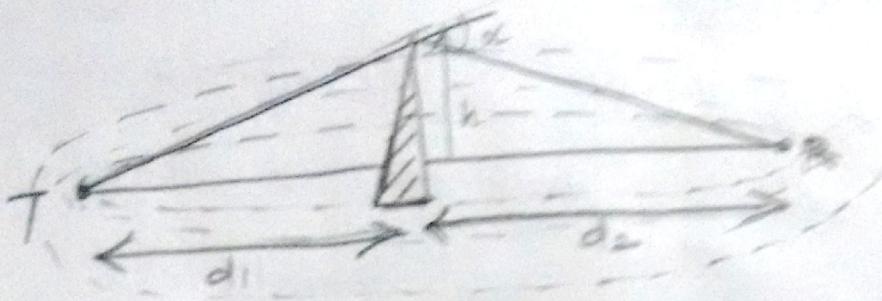
$$\nu = h \sqrt{\frac{2(d_1 + d_2)}{\lambda d_1 d_2}} = \alpha \sqrt{\frac{2d_1 d_2}{\lambda(d_1 + d_2)}}$$

- Concept of diffraction loss as a fn of path difference around an obstruction is given by fresnel zones.
- Fresnel zones are regions where secondary waves have a path length of $n\lambda/2 >$ than LOS path length [Line of sight]

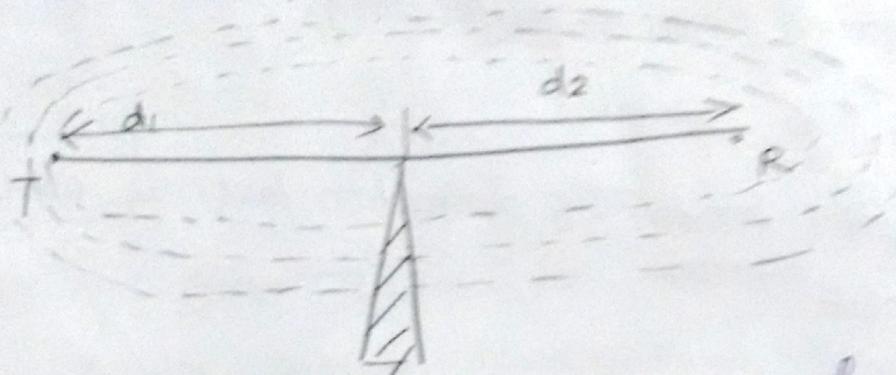


- Concentric circles represent the loci of origin of sec. waves.
- These circles are fresnel zones.
- The successive fresnel zone alter b/w constructive & destructive interference.

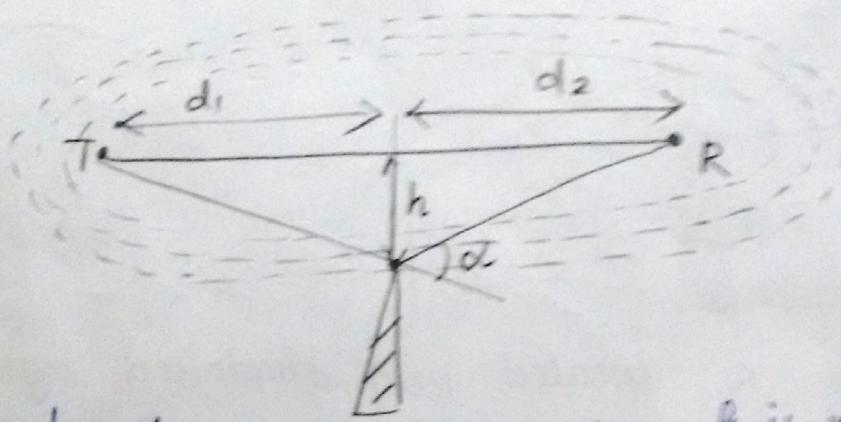
Different ~~to~~ knife edge diffraction scenarios are shown in the following diagrams.



α and ν are positive since h is positive



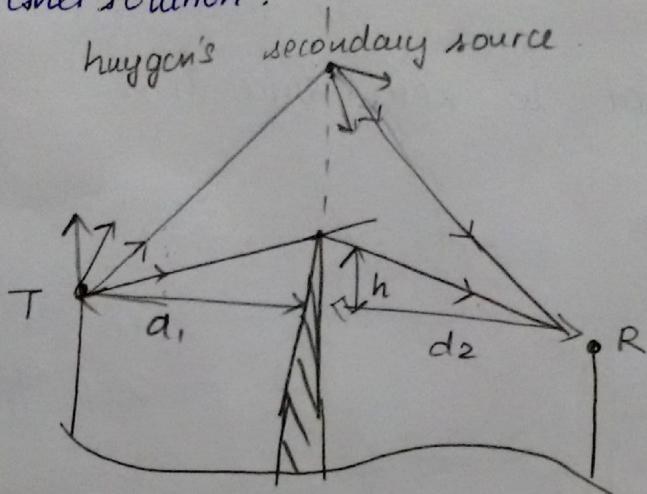
α and ν are equal to zero since $h=0$



α and ν are negative, since h is negative

- We conclude that if the obstruction does not block the volume contained in the first Fresnel zone, the diffraction loss will be minimum.
- Generally Line of sight microwave link is designed in such a way that 55% of Fresnel zone is clear (e.g) without obstruction.

- Knife Edge Diffraction model:
- Estimating the signal attenuation caused by diffraction of radio waves over hills & buildings is difficult.
- When shadowing is caused by single object (hill), it can be considered as a diffracting knife edge & attenuation can be estimated.
- It is the simplest model & diffraction loss is estimated using fresnel solution.



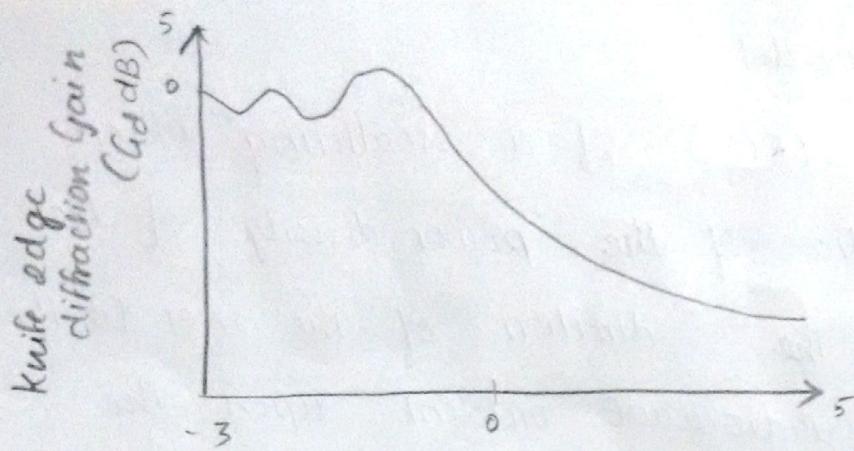
- Consider a receiver R located in a shadowed region
- field strength at pt. R is vector sum of fields due to secondary Huygen's source in the plane above knife edge

$$\frac{E_d}{E_0} = F(v) = \frac{1+j}{2} \int_{\pi v}^{\infty} \exp(-j\pi t^2) / 2 dt$$

E_0 is the free space field strength
 $F(v)$ is the complex fresnel integral

\therefore Diffraction gain

$$G_d (\text{dB}) = 20 \log |F(v)|$$



fresnel diffraction parameter \approx

SCATTERING

- Scattering occurs when the medium through which the wave travels consists of objects with dimensions smaller than the wavelength & the no. of obstacles per unit volume is large.
- When a radio wave impinges on a rough surface the reflected wave is spread in all directions due to scattering thereby providing additional radio energy at the rxer.
- Surface roughness is tested using Rayleigh criteria which defines critical height h_c of surface protuberances for an angle of incidence θ_i .

$$h_c = \frac{\lambda}{8 \sin \theta_i}$$

- A surface is smooth, if its min to max protuberance h is less than h_c .
- It is considered rough, if its min to max protuberance is greater than h_c .

Radar Cross Section model

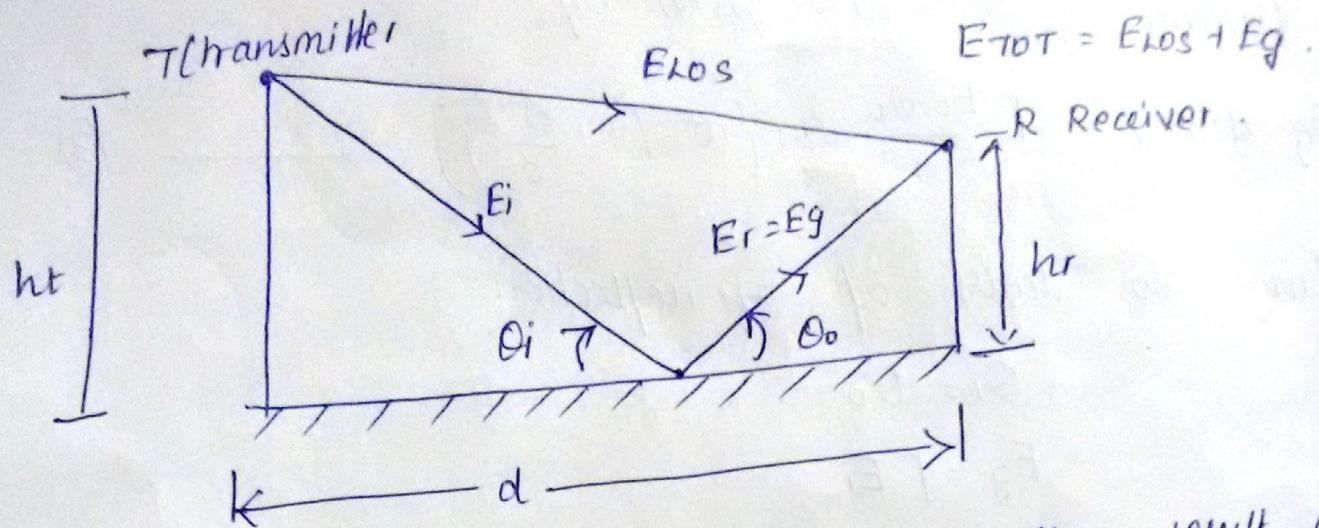
- The radar cross section (RCS) of a scattering object is defined as the ratio of the power density of the signal scattered in the direction of the receiver to the power density of the radio wave incident upon the scattering object.
- for urban mobile radio systems , received power is given by.

$$P_R \text{ (dBm)} = P_T \text{ (dBm)} + G_T \text{ (dBi)} + 20 \log(\lambda) + \text{RCS} [\text{dBm}^2] \\ - 30 \log(4\pi) - 20 \log d_T - 20 \log d_R$$

- where d_T & d_R - distance from the scattering object to the tx-er and rx-er.
- The variable RCS is given in units of dB.m^2

GROUND REFLECTION MODEL: [Two-RAY MODEL]

- Two ray ground reflection model considers both direct path & ground reflected propagation path between tx-er & rx-er.



- The total received E-field E_{TOT} is the result of direct line-of-sight component (E_{LOS}) and ground reflected component E_g .
- In the above figure, ht is the height of tx'er.
 hr - height of the receiver.
- E_0 is the free space E-field at a distance d_0 , ($d > d_0$)
 E_{field} given by,

$$E(d,t) = \frac{E_0 d_0}{d} \cos \left[\omega_c \left(t - \frac{d}{c} \right) \right] \quad (d > d_0) \quad ①$$

where $|E(d,t)| = \frac{E_0 d_0}{d}$, is the envelop of E-field.

E field due to LOS component which travels a distance is given by.

$$E_{LOS}(d',t) = \frac{E_0 d_0}{d'} \cos \left[\omega_c \left(t - \frac{d'}{c} \right) \right] \quad ②$$

E-field due to ground reflected wave which travels a distance of d'' is given by.

$$E_g(d'', t) = \Gamma \frac{E_0 \cdot d_0}{d''} \cos\left(\omega_c(t - \frac{d''}{c})\right) \quad \text{--- (3)}$$

According to laws of reflection

$$\theta_i = \theta_o$$

$$E_g = \Gamma E_i$$

$$E_t = (1 + \Gamma) E_i$$

Γ - reflection co-eff.

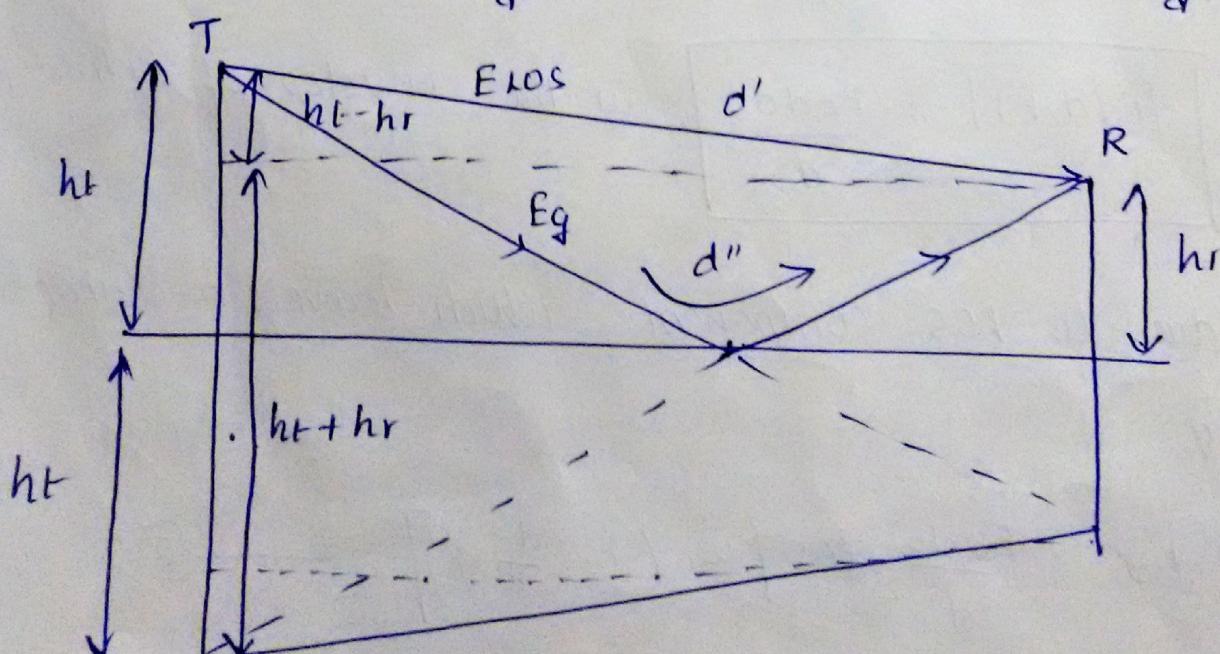
Assuming E-field to be horizontally polarized.

$$\Gamma_t = -1, E_t = 0$$

$$|E_{TOT}| = |E_{LOS} + E_g| \quad \text{--- (4)}$$

(i.e) E_{TOT} is sum of (2) & (3)

$$E_{TOT}(d, t) = \frac{E_0 \cdot d_0}{d'} \cos\left[\omega_c(t - \frac{d'}{c})\right] + (-1) \frac{E_0 \cdot d_0}{d''} \cos\left[\omega_c(t - \frac{d''}{c})\right] \quad \text{--- (5)}$$



Method
of
Imager.

using method of images, path difference Δ , between LOS & ground reflected path.

$$\Delta = d'' - d'$$

$$= \sqrt{(h_t + h_r)^2 + d^2} - \sqrt{(h_t - h_r)^2 + d^2} \quad \text{--- (6)}$$

when d is very large compared to $(h_t + h_r)$

$$\Delta = d'' - d' \approx \frac{2h_t h_r}{d} \quad \text{--- (7)}$$

Phase difference Θ_Δ & time delay is given by

$$\Theta_\Delta = \frac{2\pi\Delta}{\lambda} = \frac{\Delta w_c}{c} \quad \text{--- (8)}$$

$$T_d = \frac{\Delta}{c} = \frac{\Theta_\Delta}{2\pi f_c} \quad \text{--- (9)}$$

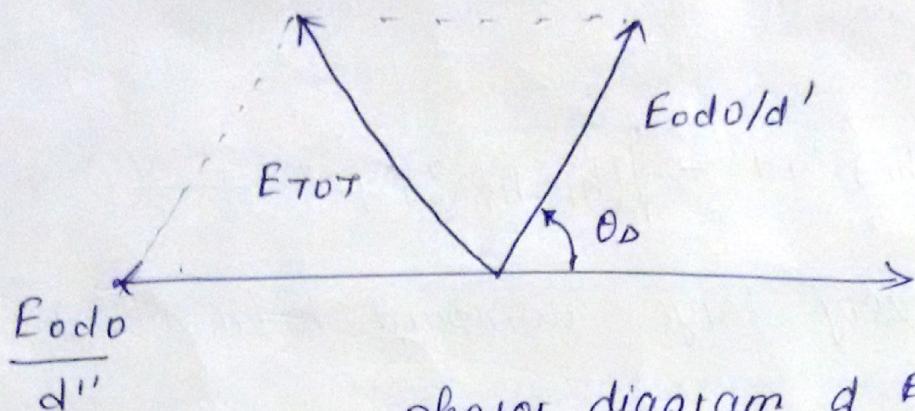
When d is large d' & d'' are almost equal.

$$\therefore \left| \frac{E_{odo}}{d} \right| \approx \left| \frac{E_{odo}}{d'} \right| \approx \left| \frac{E_{odo}}{d''} \right| \quad \text{--- (10)}$$

Received E-field at time $t = \frac{d''}{c}$ can be written from eq. (5). as

$$\begin{aligned} E_{TOT} \left(d, t = \frac{d''}{c} \right) &= \frac{E_{odo}}{d'} \cos \left(w_c \left[\frac{2\pi d'' - d'}{c} \right] \right) - \frac{E_{odo} \cos \Theta_\Delta}{d''} \\ &= \frac{E_{odo}}{d'} \angle \Theta_\Delta - \frac{E_{odo}}{d''} \end{aligned} \quad \text{--- (11)}$$

$$= \frac{E_{odo}}{d} [\angle \theta_D - 1]$$



phasor diagram of E field component.
from the phasor diagram E field at distance d
is given by.

$$|E_{TOT}(d)| = \sqrt{\left(\frac{E_{odo}}{d}\right)^2 (\cos \theta_D - 1)^2 + \left(\frac{E_{odo}}{d}\right)^2 \sin^2 \theta_D}$$

(12)

Using trigonometric identities it is simplified as

$$|E_{TOT}(d)| = 2 \frac{E_{odo}}{d} \sin \left[\frac{\theta_D}{2} \right] \quad (13)$$

where $\left[\sin \left(\frac{\theta_D}{2} \right) \approx \frac{\theta_D}{2} \right]$

using (7) & (8).

$$\frac{\theta_D}{2} \approx \frac{2\pi h \text{thr}}{\lambda d}$$

∴ Eq. (13) becomes.

$$E_{TOT}(d) = \frac{2E_{odo}}{d} \cdot \frac{2\pi h \text{thr}}{\lambda d} \quad (14)$$

∴ Received power at a distance d is given by

$$P_r = P_t \cdot G_t \cdot G_r \frac{h_t^2 h_r^2}{d^4}$$

(15)

(i.e) received power falls at a rate of 40dB/decade.

$$PL(dB) = 40 \log d - [10 \log G_t + 10 \log G_r + 20 \log h_t + 20 \log h_r]$$

L (16)

* Practical Link Budget Design using

Path Loss Models.

- radio propagation models can be derived using analytical & empirical methods.
- Empirical methods are based on curve fitting.
- It takes into account all propagation factors.
- Disadv: it is not valid, when environment changes.
- Path Loss model can be used to estimate the fixed power as a function of distance.

Log-distance path loss model:

Logarithmically
signal power decreases log with distance

- Avg fixed signal power decreases log with distance
- Avg large scale path loss for a TR separation is expressed as a fn of distance using path loss exponent, n .

$$\overline{PL}(d) \propto \left[\frac{d}{d_0} \right]^n$$

$$\overline{PL}(dB) = \overline{PL}(d_0) + 10n \log \left[\frac{d}{d_0} \right]$$

n is the path loss exponent

d_0 - reference distance

d - TR separation distance.

Log-normal shadowing:

disadv in log-distance path loss model:

- It does not consider the fact the environment is different for two diff locations having same T-R separation.
- ∵ many times measured signal is different from the average value.

so we go for log-normal shadowing; which considers the fact that path loss at a particular location is random & log-normally distributed. (i.e)

$$PL(d) [dB] = \overline{PL}(d) + X_r = \overline{PL}(d_0) + 10 \log \frac{d}{d_0}$$

$$+ X_r$$

$$P_r(d) [dBm] = P_t [dBm] - PL(d) [dB]$$

- Where X_r is a zero-mean Gaussian distributed random variable.
- Log normal distribution describes the random shadowing effect which occurs over a large no. of measurement locations for the same TR separation distance but in diff environment.

This is called Log normal shadowing.

Outdoor Propagation model:

- Radio wave transmission takes place over a irregular terrain.
- ∵ Terrain profile has to be considered in order to estimate the path loss.
- A no. of models are available to predict path loss over irregular terrain.

(i) OKUMURA MODEL:

- This model is widely used for signal prediction in urban areas.
- It is used for Base Station antenna height of 30m - 1000m.
- Okumura developed a set of curves which gives median attenuation A_{mu} relative to free space in urban area over quasi smooth terrain with antenna height of 200m (h_{te}) and 3m (h_{re})

h_{te} - transmitter (BS) antenna height

h_{re} - receiver (MS) antenna height

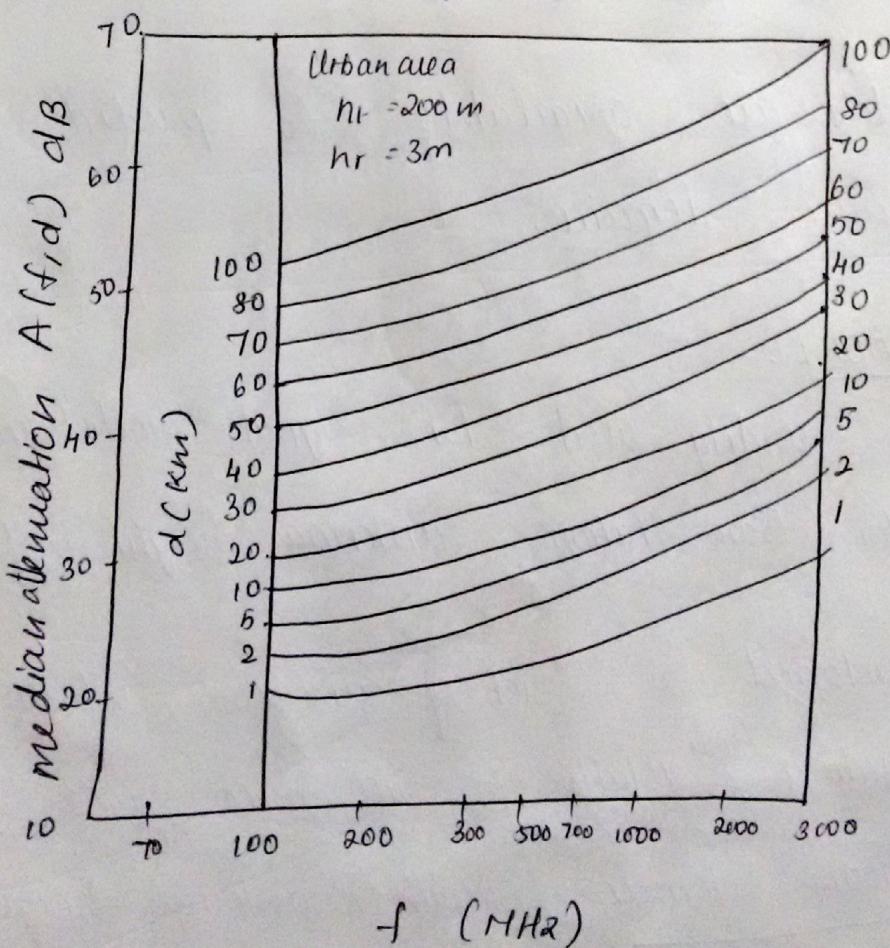
- curves are plotted as a fn of frequency range ~~100~~ 100 MHz to 1920 MHz also as a fn of distance from BS in the range 1km to 100km.
- Path loss (50^{th} percentile) $L_{50}(\text{dB})$

$$L_{50}(\text{dB}) = L_f + A_{\text{mu}}(f, d) - G_t(h_{te}) - G_r(h_{re}) - G_{\text{AREA}}$$

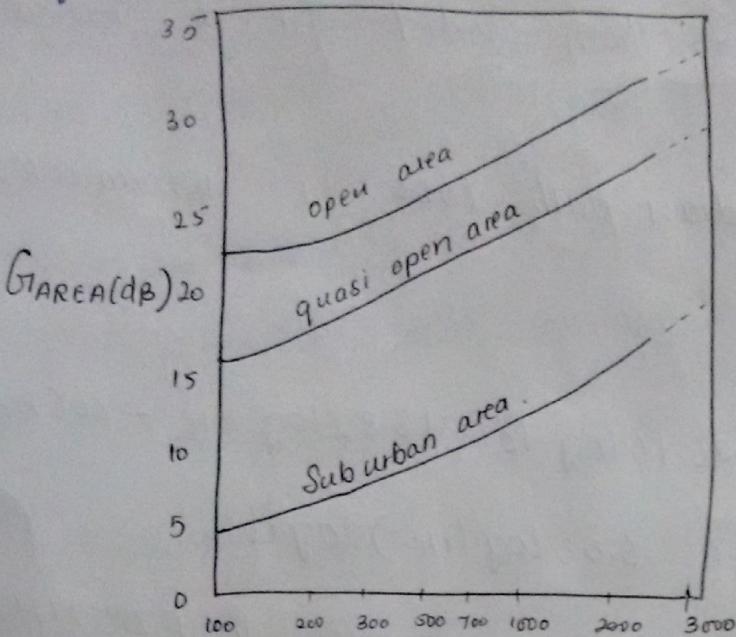
A_{mu} - gain due to environment.

$G_t(h_{te})$ - BS antenna height gain factor

$G_r(h_{re})$ - MS antenna height gain factor.



• Plot of $G_{AREA}(f, d)$ and G_{AREA} for diff freq



$$G(h_{re}) = 20 \log \left[\frac{h_{re}}{200} \right] \quad 1000m > h_{re} > 30m$$

$$G(h_{re}) = 10 \log \left[\frac{h_{re}}{3} \right] \quad h_{re} \leq 3m$$

$$G(h_{re}) = 20 \log \left[\frac{h_{re}}{3} \right] \quad 10m > h_{re} > 3m$$

Okumura found that,

- $G(h_{re})$ varies at a rate of 20dB/ decade &
- $G(h_{re})$ varies at a rate of 10dB/ decade less than 3m

adv:

- It is simplest & accurate method.

disadv:

- Slow response to rapid changes in terrain
- It is good in urban & suburban areas but not good in ~~rural~~ rural areas.

HATA MODEL

- HATA model is empirical method valid for a range from 150 MHz to 1500 MHz.
- Standard formula for median path loss in urban area is given by.

$$L_{50}(\text{urban})(\text{dB}) = 69.55 + 26.16 \log f_c - 13.82 \log h_{te} - a(hre) \\ + (44.9 - 6.55 \log h_{te}) \log d$$

f_c is the frequency from 150 MHz to 1500 MHz.

h_{te} - effective transmitter antenna height (30m - 200m)

h_{re} - effective receiver antenna height (1m to 10m)

d - T-R separation distance

$a(hre)$ - correction factor as a fn. of antenna height.

where the correction factor for small to medium city.

$$a(hre) = (1.1 \log f_c - 0.7) h_{re} - (1.56 \log f_c - 0.8) \text{ dB}$$

for large city it is given by .

$$a(hre) = 8.29 (\log 1.54 h_{re})^2 - 1.01 \text{ dB} \quad \text{for } f_c \leq 300 \text{ MHz}$$

$$a(hre) = 3.2 (\log 11.75 h_{re})^2 - 4.97 \text{ dB} \quad \text{for } f_c > 300 \text{ MHz}$$

Prediction of Hata model compare very closely with original Okumura model as long as d exceeds 1km.

- Indoor Propogation model varies from outdoor propogation model in 2 aspects
 - distance covered are much smaller
 - variability of environment much greater for a much smaller range of TR separation distance.
- Propogation within buildings is influenced by layout of the building, construction materials, building type.

Partition losses : (same floor)

- partitions that are formed as part of building structure - hard partition.
- partitions that ~~can~~ can be moved and that do not span to the ceiling are called soft partitions.
- partitions vary widely in physical & electrical char.
- materials In indoor propagation models, each material have different loss at diff frequencies.

Partition losses between floors:

- losses b/w floors is determined by external dimensions, materials of the building etc.
- Floor Attenuation factor increases with increase in no. of floors.

- Log-distance Path loss model :

distance power law is given by

$$PL(dB) = PL(d_0) + 10n \log \left[\frac{d}{d_0} \right] + X_r$$

where n depends on surrounding building.

X_r - normal random variable.

SMALL SCALE FADING

Small scale fading describes rapid fluctuations of amp, phases & multipath delay of radio signal over a short period of time.

fading:

If is caused by interference between two or more versions of fixed signal that arrive a user with slightly diff time.

multipath signals in radio channel creates small-scale fading effects.

FACTORS INFLUENCING SMALL SCALE FADING:

- Multipath Propagation:

→ The reflecting objects & the scatterers in the environment causes signal energy in amplitude, phase & time to vary.

- This effects causes multiple versions of fixed signal to arrive at the receiver.
- where these multiple version signals vary in time & space (with respect) w.r.t to one another.
- This random phase & amplitude causes fluctuations in signal strength, inducing small-scale fading.

Speed of the mobile:

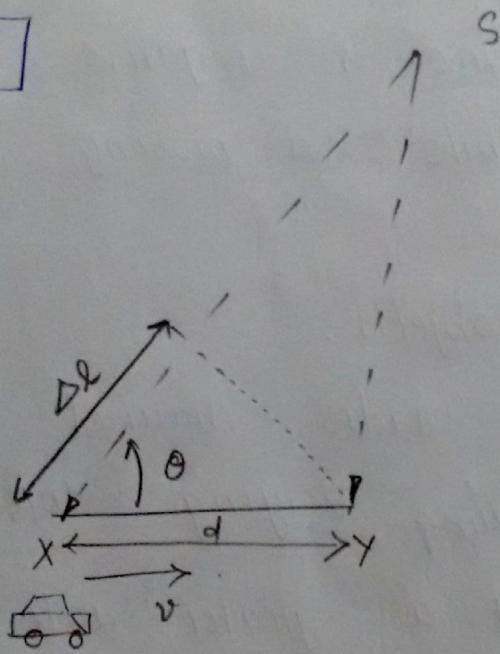
- relative motion between the B.S and the mobile results in different Doppler shift on the each multipath component.
- Doppler shift is positive or negative depending on whether mobile is moving towards or away from B.S.

Speed of surrounding objects:

- when objects in a radio channel are in motion, they induce time varying doppler shift.
- If objects move at a greater rate than the mobile then this effect dominates small scale fading else it can be neglected.
- 'Coherence time' defines the 'stationarity of the channel'

- Transmission bandwidth of the signal :-
- When transmitted radio signal B.W is greater than B.W of multipath channel, the received signal is distorted.
- B.W of the channel is quantified by coherence bandwidth.
- Coherence bandwidth is a measure of maximum frequency difference for which signals are still strongly uncorrelated in amplitude.

DOPPLER SHIFT



- consider a mobile moving at a constant velocity v , along a path segment of length d between pts $X \& Y$.
- Source S.
- Difference in path length (Δl) travelled by the wave from source S to mobile at pts $X \& Y$

is given by

16

$$\Delta l = d \cos \theta = v \Delta t \cos \theta$$

Δt time required for MS to travel from X to Y.

Phase change in received signal,

$$\boxed{\Delta \phi = \frac{2\pi \Delta l}{\lambda} = \frac{2\pi v \Delta t}{\lambda} \cos \theta}$$

Apparent change in freq, Doppler shift.

$$\boxed{f_d = \frac{1}{2\pi} \cdot \frac{\Delta \phi}{\Delta t} = \frac{v}{\lambda} \cdot \cos \theta.}$$

① SMALL-SCALE FADING

(Based on multipath time delay spread)

↓
FLAT FADING

↓
FREQUENCY SELECTIVE
FADING

1. B.W of Signal < B.W of channel

1. B.W of Signal > B.W of channel

2. Delay Spread < Symbol Period

2. Delay Spread > Symbol period

② SMALL-SCALE FADING

(Based on Doppler spread)

↓
FAST FADING

↓
SLOW FADING

1. High Doppler spread

1. Low Doppler spread

2. Coherence time < symbol period

2. Coherence time > symbol period

3. Channel variations faster than
baseband signal variation.

3. Channel variations slower
than baseband signal variations.

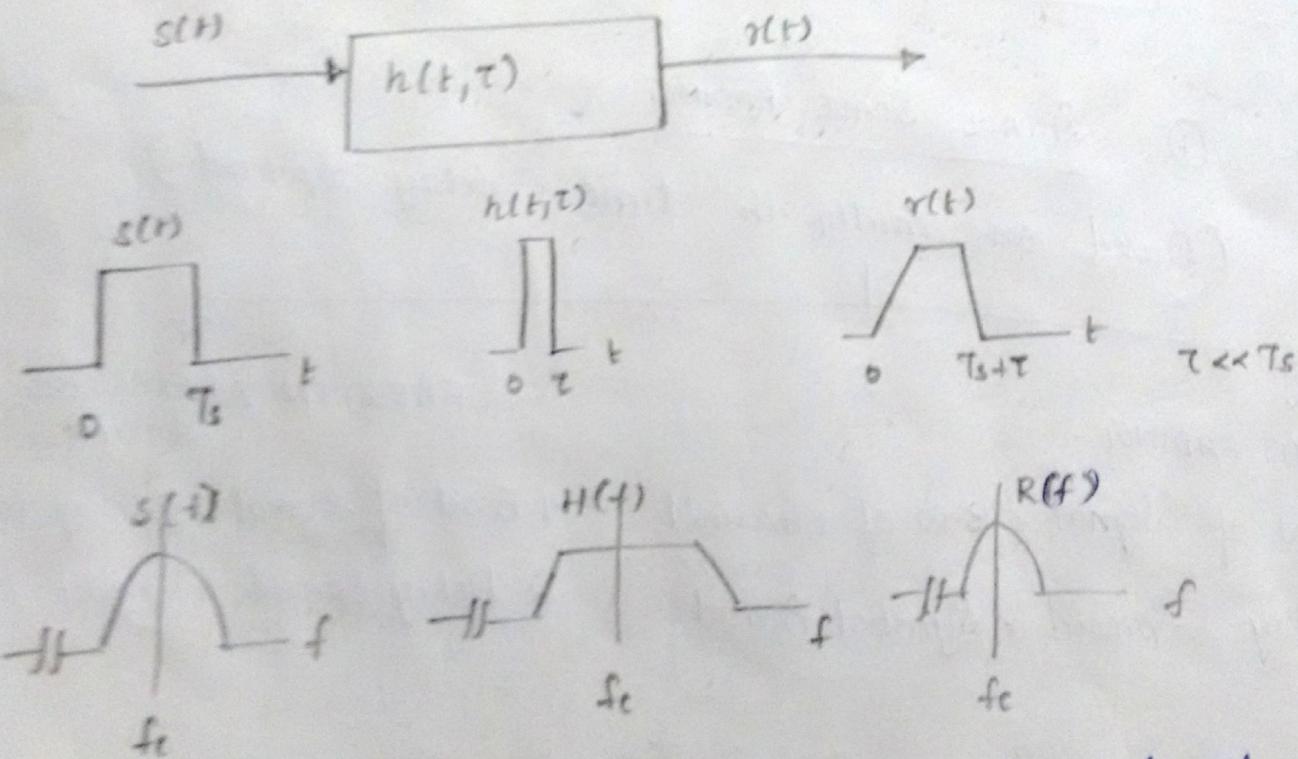
Types of Small Scale fading

fading effects due to multipath Time delay spread

Time dispersion due to multipath causes the transmitted signal to undergo either flat or frequency selective fading.

flat fading:

when a mobile radio channel has constant gain and linear phase response over a B.W greater than B.W of the transmitted signal , then the rx-ed signal undergoes flat fading.



- flat fading is also referred as narrowband channels since B.W of applied signal is narrow compared to channel B.W .

- Signal undergoes flat fading if

$$B_S \ll B_C$$

$$T_S \gg \tau$$

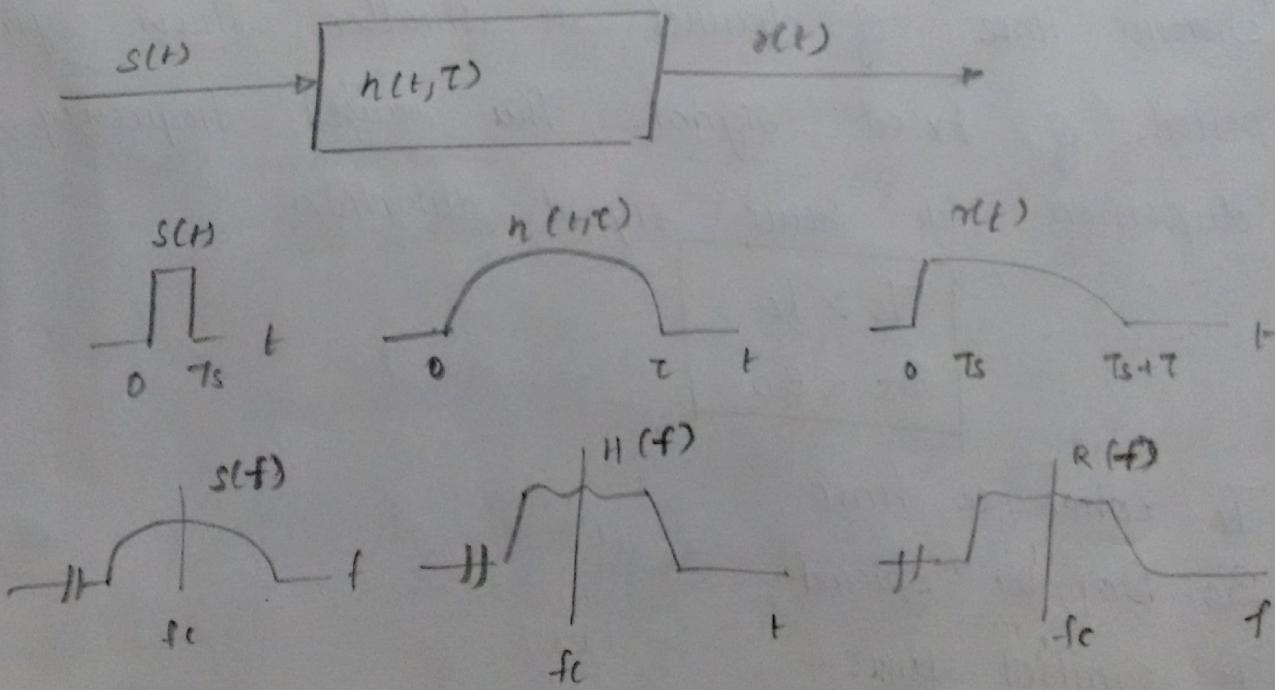
where T_s is the reciprocal of bandwidth B_s .

τ_i is the rms delay spread

B_c is the coherence bandwidth.

(iii) Frequency Selective fading:

- When a mobile radio channel has constant gain and linear phase response over a B.W that is smaller than B.W of the transmitted signal, then the received signal undergoes frequency selective fading.
- Frequency selective fading is due to time dispersion of the transmitted symbols within the channel.
- Thus channel induces ISI



- Frequency selective fading is caused by multipath delay with which exceed the symbol period of the transmitted symbol.
- It is also known as wideband channels since bandwidth of the signal $s(t)$ is wider than the bandwidth of the channel.

Signal undergoes frequency selective fading

$$\left. \begin{array}{l} B_s > B_D \\ T_s < T_c \end{array} \right\}$$

- Fading Effects due to Doppler Spread:

- (i) fast fading:

Based on how rapidly the transmitted signal changes compared to the rate of change of channel channel is classified into fast & slow fading channel.

- fast fading: channel impulse response changes rapidly within the symbol duration.
- coherence time of channel is smaller than symbol period of fixed signal, this causes frequency dispersion & hence signal distortion.

$$\left. \begin{array}{l} T_s > T_c \\ B_s < B_D \end{array} \right\}$$

T_c - coherence time.

B_D - Doppler Spread

T_s - symbol time

B_s - Bandwidth of the fixed signal

- (ii) slow fading:

- channel impulse response changes at a rate much slower than the transmitted baseband signal $s(t)$

- In frequency domain, Doppler spread of the channel is much smaller than bandwidth of the baseband signal.

∴ Signal undergoes slow fading if

$$T_s \ll T_c$$

$$B_s > B_p$$

- MATRIX illustrating type of fading experienced by a signal as a fn of symbol period

Symbol Period of Transmitting Symbol T_s	Transmitted Symbol Period T_c	
	flat slow fading	flat fast fading
freq selective slow fading		freq selective fast fading

$\rightarrow T_s$

- matrix illustrating type of fading experienced by signal as a fn of baseband signal B.W

Baseband Signal B.W B_c	Transmitted Baseband Signal B.W B_s	
	flat fast fading	flat slow fading
freq selective fast fading		freq selective slow fading

$\rightarrow B_s$

Rayleigh fading Distribution:

Rayleigh distribution has a probability fn given by

$$p(r) = \begin{cases} \frac{r}{\sigma^2} \exp\left[-\frac{r^2}{2\sigma^2}\right] & (0 \leq r \leq \infty) \\ 0 & (\text{else}) \end{cases}$$

σ is the rms value of the received voltage
 σ^2 is the time-average power of the rx-ed signal

Cumulative distribution fn.

$$P(R) = 1 - \exp\left[-\frac{R^2}{2\sigma^2}\right]$$

mean value r_{mean} of Rayleigh distribution

$$r_{\text{mean}} = E[r] = \int_0^\infty r p(r) dr = 1.2533 \sigma$$

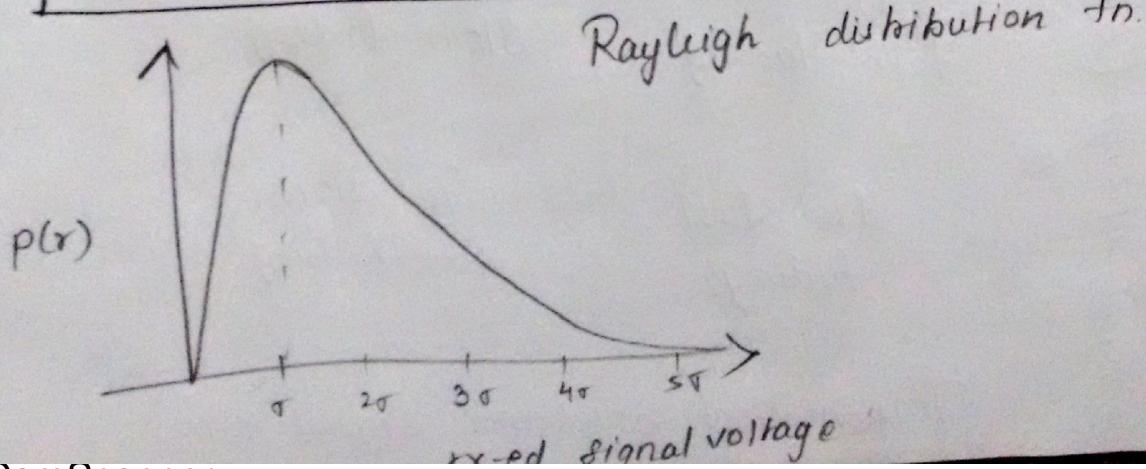
Variance of rayleigh distribution

$$\sigma_r^2 = 0.42 \sigma^2$$

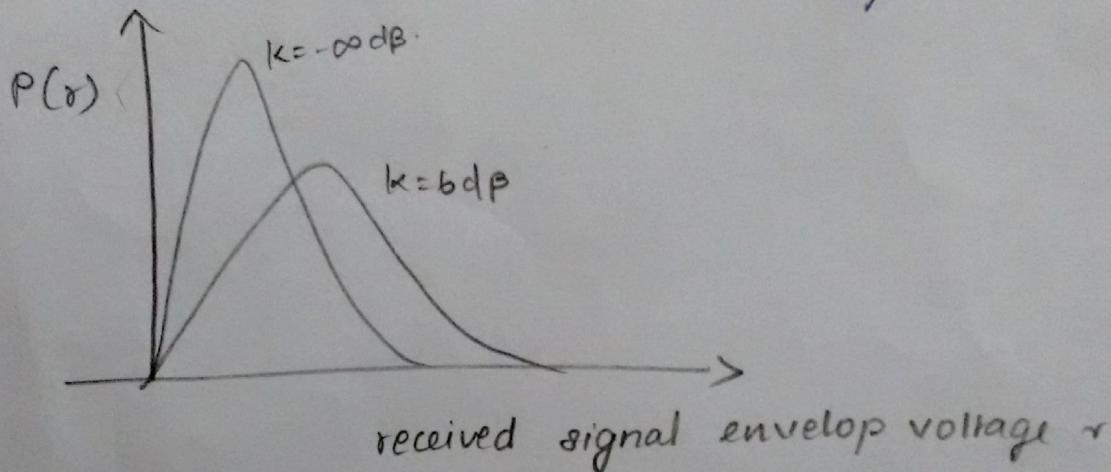
σ is the standard deviation of original signal

median value of r , r_{median}

$$r_{\text{median}} = 1.177 \sigma$$



- Ricean fading Distribution:
- when there is a dominant stationary signal component present, such as a LOS propagation path, small scale fading envelop distribution is Ricean.
- As dominant signal becomes weaker, composite signal resembles a noise signal - which has an envelop of Rayleigh.
- (i.e) Ricean distribution degenerates to Rayleigh distribution when dominant component fades away.



Probability density fn of Ricean distribution : $K = -\infty \text{ dB}$
 (Rayleigh)
 and $K = 6 \text{ dB}$.

Ricean distribution.

$$P(r) = \begin{cases} \frac{\gamma}{\sigma^2} e^{-\frac{(r^2 + A^2)}{2\sigma^2}} I_0 \left[\frac{Ar}{\sigma^2} \right] & \text{for } (A \geq 0, r \geq 0) \\ 0 & \text{for } (r < 0) \end{cases}$$

- A denotes the peak amplitude
- $I_0(\cdot)$ is the modified Bessel fn.

Ricean distribution described using parameter k

$$k = \frac{A^2}{2\sigma^2} \quad \begin{matrix} [\text{deterministic signal}] \\ \text{Variance.} \end{matrix}$$

where k is the Ricean factor.

as $A \rightarrow 0$, $k \rightarrow \infty \text{ dB}$ (ie) Ricean becomes Rayleigh distribution.