

UNIT-I

WIRELESS CHANNELS

LARGE SCALE PATH LOSS:

- Paths can vary from simple line-of-sight to ones that are severely obstructed by buildings, mountains, and foliage.
- Radio channels are extremely random and difficult to analyze.
- Two basic goals of propagation modeling:
- Predict magnitude and rate (speed) of received signal strength fluctuations over short distances/time durations
- Predict **average** received signal strength for given Tx/Rx separation
- characterize received signal strength over distances from 20 m to 20 km
- *Large-scale radio wave propagation model* models
- needed to estimate coverage area of base station
- in general, large scale path loss decays *gradually* with distance from the transmitter
- will also be affected by geographical features like hills and buildings

Free-Space Signal Propagation

- Clear, unobstructed line-of-sight path → satellite and fixed microwave
- Friis transmission formula → Rx power (P_r) vs. T-R separation (d)

$$P_r(d) = \frac{P_t G_t G_r \lambda^2}{(4\pi)^2 d^2 L}$$

where

- P_t = Tx power (W) , G = Tx or Rx antenna gain (unitless)
 - relative to isotropic source (ideal antenna which radiates power uniformly in all directions)

Effective Isotropic Radiated Power (EIRP)

$$EIRP = P_t G_t$$

Represents the max. radiated power available from a Tx in the direction of max. antenna gain, as compare to an isotropic radiator.

- L = system losses (antennas, transmission lines between equipment and antennas, atmosphere, etc.)
 - unitless
 - $L = 1$ for zero loss

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- $L > 1$ in general

λ = wavelength = c/f (m).

d = T-R separation distance (m)

Path Loss (PL) in dB:

$$\begin{aligned} PL_{dB} &= 10 \log \left(\frac{P_t}{P_r} \right) = -10 \log \left(\frac{G_t G_r \lambda^2}{(4\pi)^2 d^2 L} \right) \\ &= -10 \log \left(\frac{G_t G_r \lambda^2}{(4\pi)^2 L} \right) + 10 \log(d^2) \\ &= -10 \log \left(\frac{G_t G_r \lambda^2}{(4\pi)^2 L} \right) + 20 \log(d) \end{aligned}$$

- $d^2 \rightarrow$ power law relationship

- P_r decreases at rate of proportional to d^2
- P_r decreases at rate of 20 dB/decade (for line-of-sight, even worse for other cases)
- For example, path loses 20 dB from 100 m to 1 km
- Comes from the d^2 relationship for surface area.

- Close in reference point (d_o) is used in large-scale models

$$P_r(d) = P_r(d_o) \left(\frac{d_o}{d} \right)^2 \quad \text{for } d > d_o > d_f$$

- d_o : known received power reference point - typically 100 m or 1 km for outdoor systems and 1 m for indoor systems
- d_f : far-field distance of antenna, we will always work problems in the far-field

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D: the largest physical linear dimension of antenna

TWO RAY MODEL:

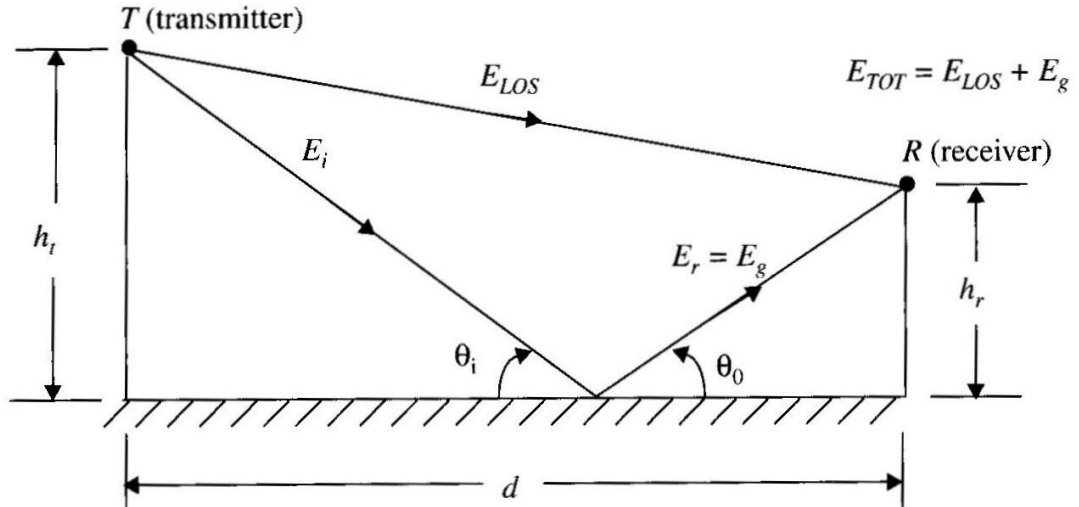


Figure 4.7 Two-ray ground reflection model.

E_{TOT} is the electric field that results from a combination of a direct line-of-sight path and a ground reflected path.

$$\vec{E}_{TOT} = \vec{E}_{LOS} + \vec{E}_g$$

let E_0 be $|\vec{E}|$ at reference point d_0 then

$$\vec{E}(d, t) = \left(\frac{E_0 d_0}{d} \right) \cos \left(\omega_c \left(t - \frac{d}{c} \right) \right) \quad d > d_0$$

□ For the direct path let $d = d'$; for the reflected path

$d = d''$ then

$$\vec{E}_{TOT}(d, t) = \left(\frac{E_0 d_0}{d'} \right) \cos \left(\omega_c \left(t - \frac{d'}{c} \right) \right) + \Gamma \left(\frac{E_0 d_0}{d''} \right) \cos \left(\omega_c \left(t - \frac{d''}{c} \right) \right)$$

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- for large T-R separation : θ_i goes to 0 (angle of incidence to the ground of the reflected wave) and

$$\Gamma = -1$$

- Phase difference can occur depending on the phase difference between direct and reflected E fields

The phase difference is θ_Δ due to Path difference , $\Delta = d'' - d'$, between \bar{E}_{LOS} and \bar{E}_g .

$$\text{Equation (4.40): } \Delta = d'' - d' = \sqrt{(h_t + h_r)^2 + d^2} - \sqrt{(h_t - h_r)^2 + d^2}$$

- From two triangles with sides d and $(h_t + h_r)$ or $(h_t - h_r)$

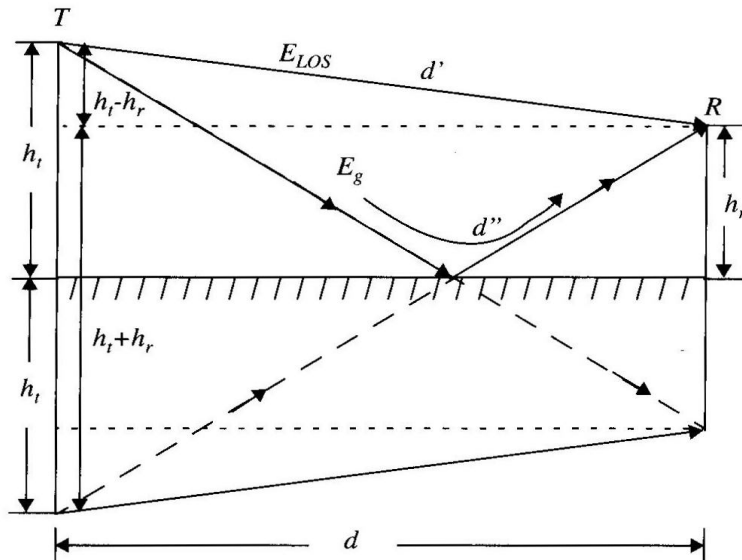


Figure 4.8 The method of images is used to find the path difference between the line-of-sight and the ground reflected paths.

- for large distances $d \gg \sqrt{h_t h_r}$ it can be shown that

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$$\bar{E}_{TOT}(d) \approx \frac{4\pi E_0 d_0 h_t h_r}{\lambda d^2}$$

$$P_r \approx \frac{P_t G_t G_r h_t^2 h_r^2}{d^4}$$

Two-ray path loss model:

$$PL \text{ (dB)} = 40 \log d - [10 \log G_t + 10 \log G_r + 20 \log h_t + 20 \log h_r]$$

Now d^4 instead of d^2 for free space

- $P_r \propto \frac{1}{d^4} P_r$

- $P_r(d) = P_r(d_0) \left(\frac{d_0}{d} \right)^4$

Predictable Link Budget Design using Path Loss Models

Most RF propagation models are derived from combined

- (i) analytical studies
- (ii) experimental methods

Empirical Approach – measured data is fitted to a curve or an analytical expression

- uses field measurements

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- implicitly accounts for all factors (known and unknown)
- model generally not valid for all frequencies or environments
- Classical Models have evolved to predict large scale path loss
- used to estimate receive signal strength as a function of distance
- used along with noise analysis techniques used to predict SNR

for RF mobile systems

3.9.1 Log Distance Path Loss Model

- average received power decreases logarithmically with distance
- theory & measurements indicate validity for indoors & outdoors

(1) Average Large Scale Path Loss Model

- **distance dependent** mean path loss - over significant distances

$$\overline{PL}(d) = \frac{P_r(d)}{P_t(d)} \propto \left(\frac{d}{d_0} \right)^n \quad (3.67)$$

$$\overline{PL}(dB) = \overline{PL}(d_0) + 10n \log \left(\frac{d}{d_0} \right) \quad (3.68)$$

d_0 = close in reference distance, often determined empirically

d = transmitter - receiver separation

n = path loss exponent - indicates rate of path loss increase with d_0

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3.9.2 Log Normal Shadowing

- **surrounding clutter** isn't considered by **log distance model**
- averaged received power (eqn 3.68) is inconsistent with measured data
- measured $PL(d)$ at any location is random, with **log normal** distribution about $\overline{PL}(d)$ (normal distribution of $\log_{10}(\bullet)$)

$$PL(d) = \overline{PL}(d) + X_{\sigma} \quad (3.69a)$$

$$PL(d) \text{ (dB)} = \overline{PL}(d_0) + 10n \log \left(\frac{d}{d_0} \right) + X_{\sigma}$$

$$P_r(d) \text{ (dB)} = P_t(d) \text{ (dB)} - PL(d) \text{ (dB)} \quad (3.69b)$$

- antenna gains included in $PL(d)$
- X_{σ} = zero-mean Gaussian distributed random variable (*in dB*)
- σ = standard deviation of X

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Log Normal Distribution - describes random shadowing effects

- for specific Tx-Rx, measured signal levels have normal distribution about distance dependent mean (in dB)
- occurs over many measurements with same Tx-Rx & different clutter standard deviation, σ (also measured in dB)

Lognormal Model For Local Shadowing

- typically, σ_{dB} ranges from 5-12
- let u = **median path loss** (dB) at distance d from transmitter
→ distribution x_{dB} of observed path loss has pdf given by:

$$\Pr[x_{dB} = x] = f(x_{dB}) = \frac{1}{\sqrt{2\pi}\sigma_{dB}} \exp\left(-\frac{(x_{dB} - u)^2}{2\sigma_{dB}^2}\right)$$

it follows that $\Pr(x_{dB} > x) = \int_x^{\infty} f(x_{dB}) dx_{dB}$

$$= \int_x^{\infty} \frac{1}{\sqrt{2\pi}\sigma_{dB}} \exp\left(-\frac{(x_{dB} - u)^2}{2\sigma_{dB}^2}\right) dx_{dB}$$

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3.9.3 Determination of % Coverage Area

- in a given coverage area, let γ = desired receive signal level – could be determined by receiver sensitivity (or visa versa)
- random shadowing effects cause some locations at d to have received power, $P_r(d) < \gamma$

Determine boundary coverage vs % area covered within a boundary, assuming

- a circular coverage area with radius R from base station
- likelihood of coverage at cell boundary is known (given)
- $d = r$ represents radial distance from transmitter

useful service area (coverage area): $U(\gamma) = \% \text{ area with } P_r(d) > \gamma$

$$U(\gamma) = \frac{1}{2\pi R^2} \int \Pr[P_r(r) > \gamma] dA$$
$$U(\gamma) = \frac{1}{2\pi R^2} \int_0^{2\pi} \int_0^R \Pr[P_r(r) > \gamma] r \, dr \, d\theta$$
(3.73)

SMALL SCALE FADING:

Multi-Path in the radio channel creates small-scale fading. The three most important effects are:

- Rapid changes in signal strength over a small travel distance or time interval
- Random frequency modulation due to varying Doppler shifts on different multi-path signals
- Time dispersion (echoes) caused by multi-path propagation delays

PARAMETERS OF MOBILE MULTIPATH CHANNELS:

- Time dispersion parameters
 - Mean excess delay
 - Rms delay spread
 - Excess delay spread (X dB)
- Coherence bandwidth

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- Doppler spread and coherence time



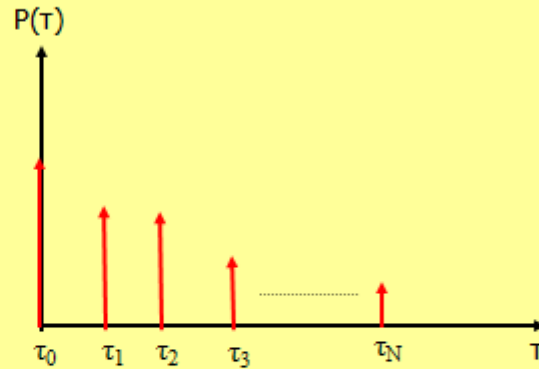
Time Dispersion Parameters

Mean Excess Delay

$$\bar{\tau} = \frac{\sum_k P(\tau_k) \tau_k}{\sum_k P(\tau_k)}$$

RMS Delay Spread

$$\sigma_\tau = \sqrt{\overline{\tau^2} - (\bar{\tau})^2}$$
$$\overline{\tau^2} = \frac{\sum_k P(\tau_k) \tau_k^2}{\sum_k P(\tau_k)}$$



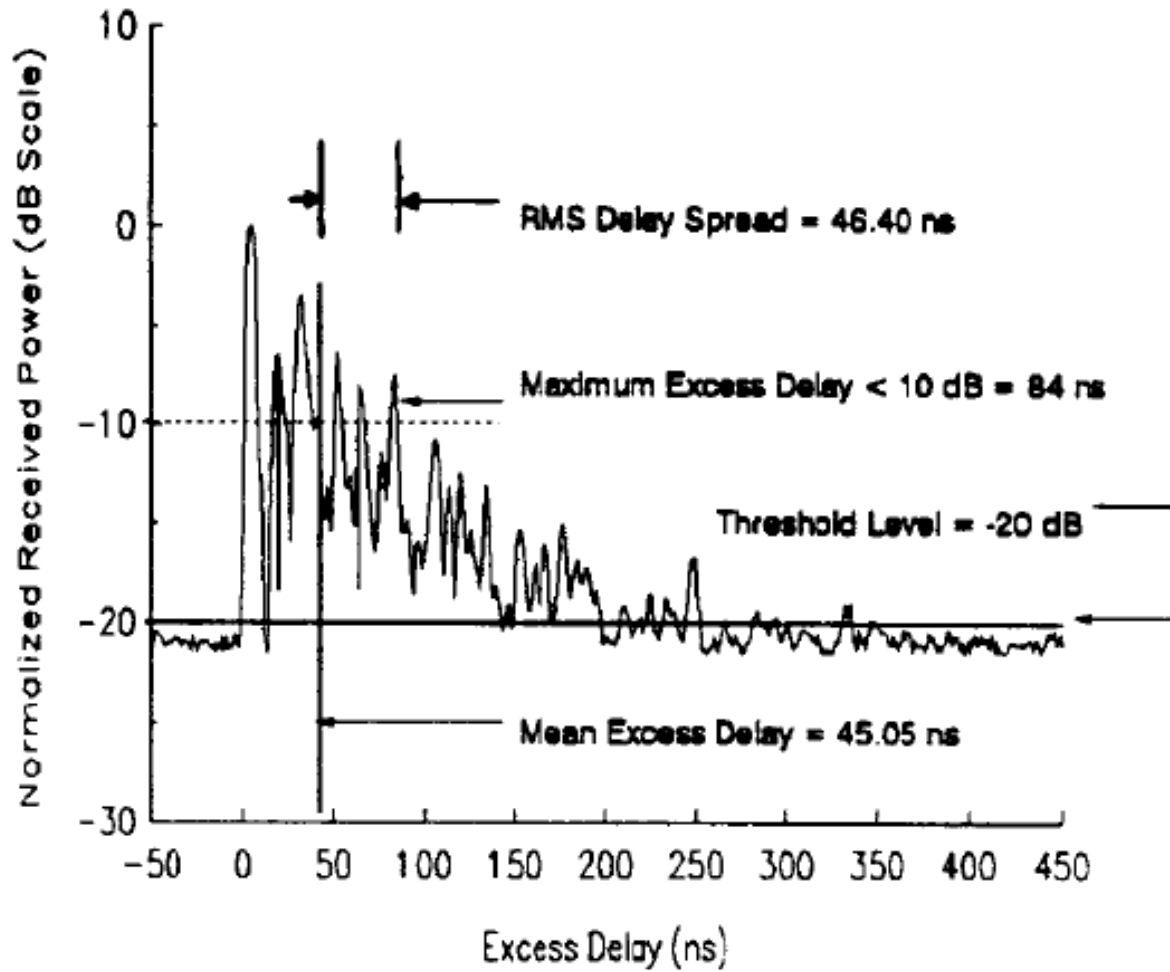
Power Delay Profile

Note: These delays are measured relative to the first detectable signal (multi-path component) arriving at the receiver at $\tau_0=0$

Maximum Excess Delay (XdB) or Excess Delay Spread (XdB):

Time delay during which multi-path energy falls to X dB below the maximum (Note that the strongest component does not necessarily arrive at τ_0)

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Coherence Bandwidth

A statistical measure of the range of frequencies over which the channel is can be considered to be “flat” (i.e., a channel which passes all spectral components with approximately equal gain and linear phase)

Coherence Bandwidth over which the frequency correlation function is 0.9

$$B_c = \frac{1}{50\sigma_\tau}$$

Coherence Bandwidth over which the frequency correlation function is 0.5

$$B_c = \frac{1}{5\sigma_\tau}$$

Doppler Shift

The difference in path lengths traveled by the wave from source S to the mobile at X and Y is Δl

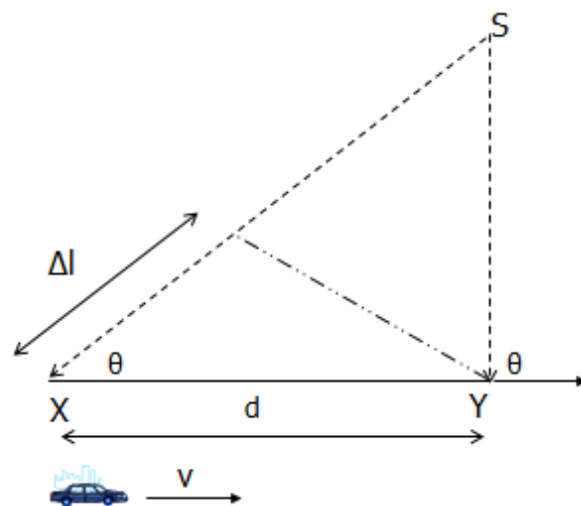
Note: Assume $SX, SY \gg d$ such that angle of arrival is nearly equal at X and Y

$$\Delta l = d \cos \theta = v \Delta t \cos \theta$$

Phase Difference due to variation in path lengths

$$\Delta \phi = \frac{2\pi v \Delta t}{\lambda} = \frac{2\pi v \Delta t}{\lambda} \cos \theta$$

Doppler Shift is Given by



$$f_d = \frac{1}{2\pi} \frac{\Delta \phi}{\Delta t} = \frac{v}{\lambda} \cos \theta$$

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Doppler Spread and Coherence Time

- Doppler spread and coherence time are parameters which describe the time varying nature of the channel
- Doppler spread B_D is a measure of spectral broadening due to the Doppler shift associated with mobile motion
- Coherence time is a statistical measure of the time duration over which the channel impulse response is essentially invariant

Coherence Time is inversely proportional to Doppler spread

$$T_c \approx \frac{1}{f_m}$$

Coherence Time over which the time correlation function is 0.5

$$T_c \approx \frac{9}{16\pi f_m}$$

where f_m is the maximum Doppler shift given by $f_m = v/\lambda$

A Common Rule:

$$T_c = \sqrt{\frac{9}{16\pi f_m} \frac{1}{f_m}} = \frac{0.423}{f_m}$$

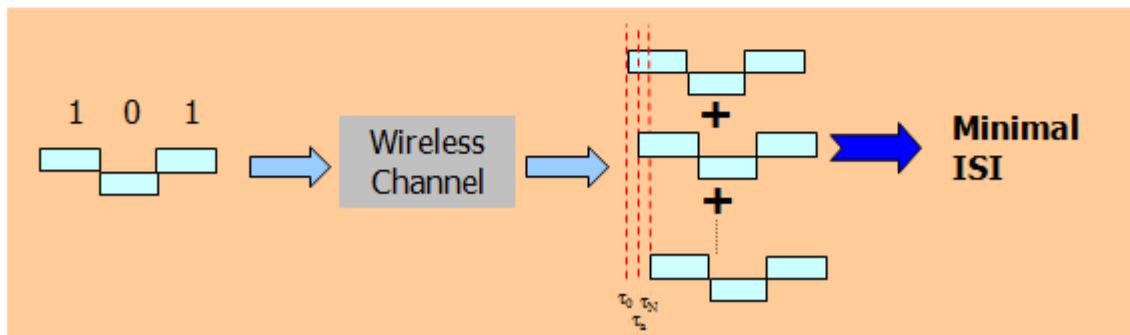
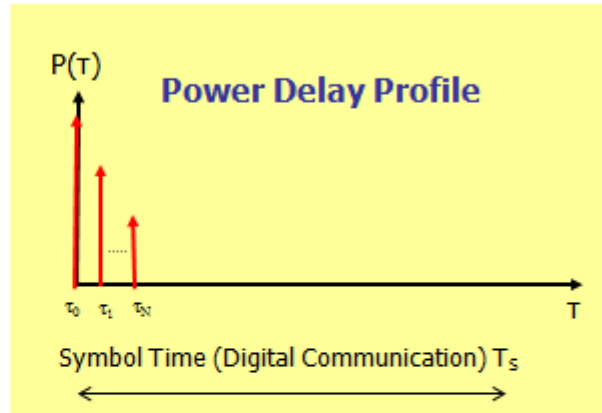


Flat Fading Vs Frequency Selective Fading

Flat Fading

$$B_s \ll B_c \quad T_s \gg \sigma_\tau$$

A Common Rule of Thumb:
 $T_s > 10\sigma_\tau \rightarrow$ Flat fading



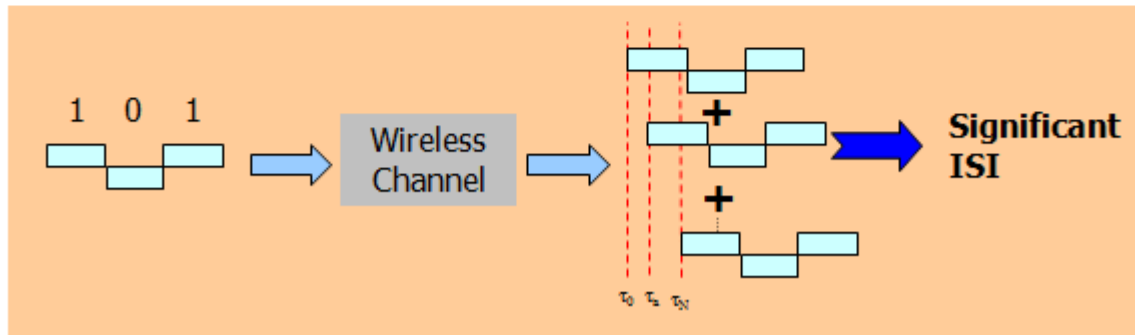
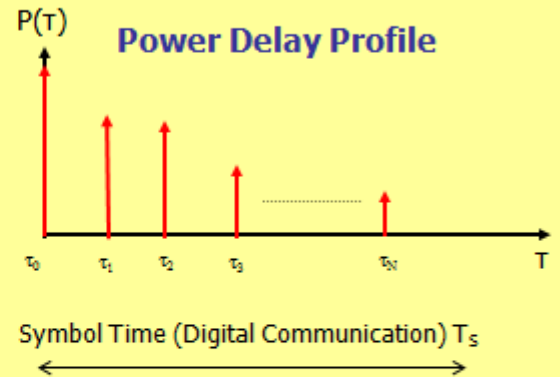


Flat Fading Vs Frequency Selective Fading

Frequency Selective Fading

$$B_s > B_c \quad T_s < \sigma_\tau$$

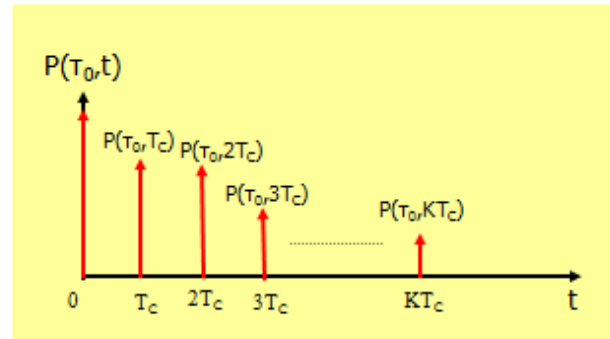
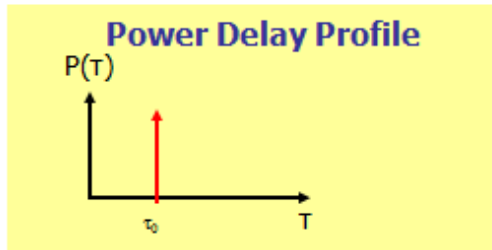
A Common Rule of Thumb:
 $T_s < 10\sigma_\tau \rightarrow$ Frequency Selective Fading



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Slow Fading Vs Fast Fading



- Consider a wireless channel comprised of a single path component.
- The power delay profile reflects average measurements
- $P(\tau_0)$ shall vary as the mobile moves

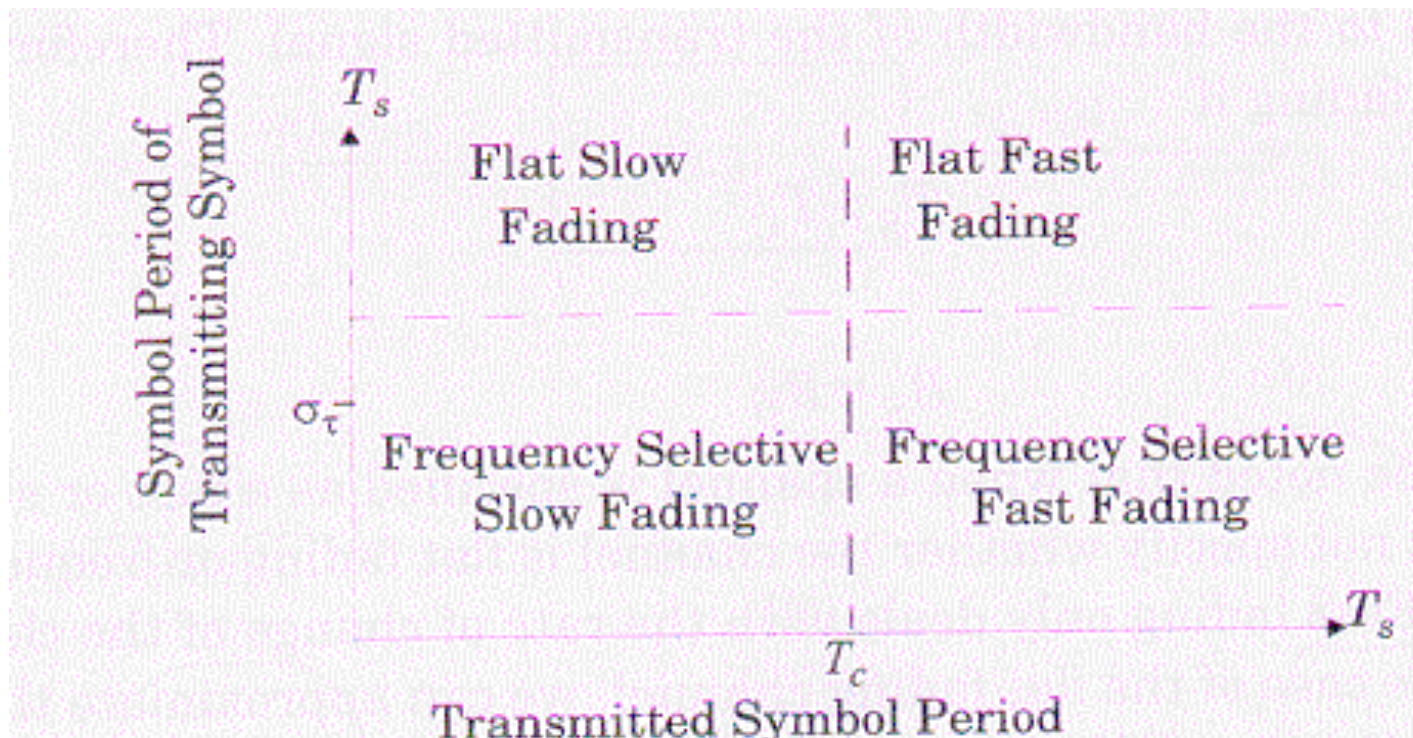
Fast Fading

$$T_s > T_c \quad B_s < B_D$$

Frequency dispersion
(time selective fading)

Slow Fading

$$T_s \ll T_c \quad B_s \gg B_D$$



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